

# Zhenggang Tang

[zt15@illinois.edu](mailto:zt15@illinois.edu)

(+1) 217-200-0937

[LinkedIn](#), [Google Scholar](#)

[Personal Website](#)

## RESEARCH INTERESTS

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I'm working on **multimodal foundation models**, including **unified understanding and generation, spatial-temporal understanding and spatial reconstruction**.

I'm also generally interested in **reinforcement learning** and **multi-agent systems**.

## EDUCATION

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**Bachelor of Science, School of EECS, Peking University, China.**

GPA: **3.80**/4 Rank: **5/91**

09/2017 - 06/2021

**Doctor of Philosophy in Computer Science, University of Illinois at Urbana-Champaign, United States.**

Advisor by [Prof. Alexander Schwing](#)

08/2021 - present

## EMPLOYMENT

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### Meta Platform Inc.

- **Research Scientist Intern @ XR Tech Core AI** 05/2025 – present  
*Unified spatial understanding and generation, still in progress.*
- **Research Scientist Intern @ XR Tech Core AI** 05/2024 – 01/2025  
*Single stage efficient scene reconstruction from pose-free RGB only views. Work published in CVPR 2025 as an oral presentation. Github 500+ stars.*

### Snap Inc.

- **Research Scientist Intern @ Creative Vision Group** 01/2024 – 05/2024  
*Pixel Aligned multi-view generation for 3D generation. Work published in CVPR 2025 workshop*

### NVIDIA

- **Research Scientist Intern** 05/2022 – 10/2022  
*RGB-Only SDF Reconstruction of Tabletop Scenes for Collision-Free Manipulator Control. Work published in ICRA 2022.*

### Microsoft Research Asia

- **Research Scientist Intern @ Fintech Group** 10/2020 – 05/2021  
*Learning to negotiate intentions in a diffusion-like way in multi-asset order execution modeled as a multi-agent system. Work published in KDD 2023.*

## PUBLICATIONS

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1. **Zhenggang Tang**, Yuchen Fan, Dilin Wang, Hongyu Xu, Rakesh Ranjan, Alex Schwing, Zhicheng Yan, "[MV-DUS3R+: Single-Stage Scene Reconstruction from Sparse Views In 2 Seconds](#)", **CVPR 2025 (Oral presentation)**, Nashville, USA.
2. **Zhenggang Tang**, Peiye Zhuang, Chaoyang Wang, Aliaksandr Siarohin, Yash Kant, Alex Schwing, Sergey Tulyakov, Hsin-Ying Lee, [Pixel-Aligned Multi-View Generation with Depth Guided Decoder](#), **CVPR 2025 workshop**, Nashville, USA.
3. **Zhenggang Tang**, Zhongzheng Ren, Xiaoming Zhao, Bowen Wen, Jonathan Tremblay, Stan Birchfield, Alexander Schwing, "[NeRFDeformer: NeRF Transformation from a Single View via 3D Scene Flows](#)", **CVPR 2024**, Seattle, USA.
4. **Zhenggang Tang\***, Yuchen Fang\*, Kan Ren, Weiqing Liu, Li Zhao, Jiang Bian, Dongsheng Li, Weinan Zhang, Yong Yu, Tie-Yan Liu, "[Learning Multi-Agent Intention-Aware Communication for Optimal Multi-Order Execution in Finance](#)", **ACM SIGKDD Conference on Knowledge Discovery and Data Mining 2023**, Long Beach, California, United States. (\* contribute equally).
5. **Zhenggang Tang**, Balakumar Sundaralingam, Jonathan Tremblay, Bowen Wen, Ye Yuan, Stephen Tyree, Charles Loop, Alexander Schwing, Stan Birchfield. "[RGB-Only Reconstruction of Tabletop Scenes for Collision-Free Manipulator Control](#)", **IEEE International Conference on Robotics and Automation (ICRA) 2023**, London, UK.

6. **Zhenggang Tang\***, Chao Yu\*, Boyuan Chen, Huazhe Xu, Xiaolong Wang, Fei Fang, Simon Shaolei Du, Yu Wang, Yi Wu, “[Discovering Diverse Multi-Agent Strategic Behavior via Reward Randomization](#)”, Accepted in [International Conference on Learning Representations \(ICLR\)](#), Vienna, Austria (2021) (\* contribute equally)

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## **PREPRINTS**

1. **Zhenggang Tang\***, Yuehao Wang\*, Yuchen Fan, Jun-Kun Chen, Yu-Ying Yeh, Kihyuk Sohn, Zhangyang Wang, Qixing Huang, Rakesh Ranjan, Dilin Wang, Zhicheng Yan, “[Autoregressive Diffusion Modeling for Compositional Text-to-3D Generation](#)”, in submission. (\* contribute equally)
2. Haozhen Zheng, Beitong Tian, Mingyuan Wu, **Zhenggang Tang**, Klara Nahrstedt, Alex Schwing, “[Spatio-Temporal LLM: Reasoning about Environments and Actions](#)”, arXiv preprint: 2507.05258.
3. **Zhenggang Tang\***, Kai Yan\*, Liting Sun, Wei Zhan, Tianhao Wei, Changliu Liu, “[A Microscopic Epidemic Model and Pandemic Prediction of Allegheny County using Multi-Agent Reinforcement Learning](#)”, arXiv preprint: 2108.06589. (\* contribute equally).

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## **PATENTS**

1. Balakumar Sundaralingam, Stanley Birchfield, **Zhenggang Tang**, Jonathan Tremblay, Stephen Tyree, Bowen Wen, Ye Yuan, Charles Loop, "[Techniques for controlling robots within environments modeled based on images](#).", U.S. Patent Application No. 18/168,482.

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## **REVIEWER EXPERIENCE**

IEEE/CVF Conference on Computer Vision and Pattern Recognition ( <b>CVPR</b> )	2024 – present
European Conference on Computer Vision ( <b>ECCV</b> )	2024 – present
Neural Information Processing Systems ( <b>NeurIPS</b> )	2024 – present
International Conference on Learning Representations ( <b>ICLR</b> )	2024 – present
ACM SIGGRAPH Asia	2025 – present
International Conference on 3D Vision ( <b>3DV</b> )	2024 – present

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## **AWARDS AND HONORS**

- Award of Stars of Tomorrow Internship Program in Microsoft Research Asia. 06/2021
- Top 10% thesis reward when graduating from Peking University. 06/2021
- Award of Turing Class in Peking University (Top10 in AI direction) 10/2019
- Silver Medal in 33rd National Olympiad in Informatics 07/2016
- Gold Medal in 10th Asia-Pacific Informatics Olympiad (China District). 05/2016