**Project 1: Finding Lane Lines on the Road**

**Finding Lane Lines on the Road**

The goals / steps of this project are the following:

* Make a pipeline that finds lane lines on the road on an image and a video file

**Reflection**

1. **Describe your pipeline. As part of the description, explain how you modified the draw\_lines() function.**

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**2. Identify potential shortcomings with your current pipeline**

- It’s a tedious process to tweak Canny edge detector and Hough algorithm’s parameter to find the right tradeoffs and get the right output

- The parameters are hard coded and will have to modified for different images

**3. Suggest possible improvements to your pipeline**

**-** A possible improvement would be to make the code more versatile so that it works with most of the images reasonably well