

```
redha@juanFlatro: ~/ros2_ws
QImage::pixel: coordinate (503,266) out of range
QImage::pixel: coordinate (502,266) out of range
QImage::pixel: coordinate (501,266) out of range
QImage::pixel: coordinate (500,266) out of range
QImage::pixel: coordinate (500,266) out of range
[INFO] [1678550188.184087377] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550243.314020016] [rclcpp]: signal_handler(signum=2)
redha@juanFlatro: ~/ros2_ws$ ros2 run turtlesim turtlesim_node
[INFO] [1678550244.904025692] [turtlesim]: Starting turtlesim with node name /tu
rlesim
[INFO] [1678550244.91840455] [turtlesim]: Spawning turtle [turtle1] at x=[5.544
445], y=[5.544445], theta=[0.000000]
[INFO] [1678550257.930467330] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550268.650608706] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550283.962406936] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550293.082617369] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550298.650837673] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550306.458584959] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550314.410959838] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550327.098243221] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550333.066195830] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550343.562223911] [turtlesim]: Rotation goal completed successfully
[INFO] [1678550348.778851073] [turtlesim]: Rotation goal completed successfully

redha@juanFlatro: ~/ros2_ws
[INFO] [1678550348.443341600] [turtlesim_controller]: Received feedback
[INFO] [1678550348.458762953] [turtlesim_controller]: Received feedback
[INFO] [1678550348.474778821] [turtlesim_controller]: Received feedback
[INFO] [1678550348.491820713] [turtlesim_controller]: Received feedback
[INFO] [1678550348.508026385] [turtlesim_controller]: Received feedback
[INFO] [1678550348.523340576] [turtlesim_controller]: Received feedback
[INFO] [1678550348.539575957] [turtlesim_controller]: Received feedback
[INFO] [1678550348.555814166] [turtlesim_controller]: Received feedback
[INFO] [1678550348.572091304] [turtlesim_controller]: Received feedback
[INFO] [1678550348.587297388] [turtlesim_controller]: Received feedback
[INFO] [1678550348.603495268] [turtlesim_controller]: Received feedback
[INFO] [1678550348.619964562] [turtlesim_controller]: Received feedback
[INFO] [1678550348.636204116] [turtlesim_controller]: Received feedback
[INFO] [1678550348.652649780] [turtlesim_controller]: Received feedback
[INFO] [1678550348.668805846] [turtlesim_controller]: Received feedback
[INFO] [1678550348.682822782] [turtlesim_controller]: Received feedback
[INFO] [1678550348.698800725] [turtlesim_controller]: Received feedback
[INFO] [1678550348.714844426] [turtlesim_controller]: Received feedback
[INFO] [1678550348.730861592] [turtlesim_controller]: Received feedback
[INFO] [1678550348.747883305] [turtlesim_controller]: Received feedback
[INFO] [1678550348.764859625] [turtlesim_controller]: Received feedback
[INFO] [1678550348.780620698] [turtlesim_controller]: Received feedback
[INFO] [1678550348.784435119] [turtlesim_controller]: Result

> OUTLINE
143
144 # Destroy the node explicitly
```