Title: Human-in-the-loop

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Supervised learning

Unsupervised learning

Semi-supervised learning

Self-supervised learning

Reinforcement learning

Meta-learning

Online learning

Batch learning

Curriculum learning

Rule-based learning

Neuro-symbolic Al

Neuromorphic engineering

Quantum machine learning

Classification

Generative modeling

Regression

Clustering

Dimensionality reduction

Density estimation

Anomaly detection

Data cleaning

AutoML

Association rules

Semantic analysis

Structured prediction

Feature engineering

Feature learning

Learning to rank

Grammar induction

Ontology learning

Multimodal learning
Apprenticeship learning
Decision trees
Ensembles Bagging Boosting Random forest
Bagging
Boosting
Random forest
k -NN
Linear regression
Naive Bayes
Artificial neural networks
Logistic regression
Perceptron
Relevance vector machine (RVM)
Support vector machine (SVM)
BIRCH
CURE
Hierarchical
k -means
Fuzzy
Expectation-maximization (EM)
DBSCAN
OPTICS
Mean shift
Factor analysis
CCA
ICA
LDA
NMF
PCA
PGD
t-SNE
SDL
Graphical models Bayes net Conditional random field Hidden Markov
Bayes net
Conditional random field
Hidden Markov
RANSAC

k -NN
Local outlier factor
Isolation forest
Autoencoder
Deep learning
Feedforward neural network
Recurrent neural network LSTM GRU ESN reservoir computing
LSTM
GRU
ESN
reservoir computing
Boltzmann machine Restricted
Restricted
GAN
Diffusion model
SOM
Convolutional neural network U-Net LeNet AlexNet DeepDream
U-Net
LeNet
AlexNet
DeepDream
Neural field Neural radiance field Physics-informed neural networks
Neural radiance field
Physics-informed neural networks
Transformer Vision
Vision
Mamba
Spiking neural network
Memtransistor
Electrochemical RAM (ECRAM)
Q-learning
Policy gradient
SARSA
Temporal difference (TD)
Multi-agent Self-play
Self-play Self-play
Active learning
Crowdsourcing

Human-in-the-loop Mechanistic interpretability **RLHF** Coefficient of determination Confusion matrix Learning curve **ROC** curve Kernel machines Bias-variance tradeoff Computational learning theory Empirical risk minimization Occam learning **PAC** learning Statistical learning VC theory Topological deep learning **AAAI ECML PKDD NeurIPS ICML ICLR IJCAI** ML **JMLR** Glossary of artificial intelligence List of datasets for machine-learning research List of datasets in computer vision and image processing List of datasets in computer vision and image processing Outline of machine learning t Human-in-the-loop (HITL) is used in multiple contexts. It can be defined as a model requiring human interaction. [1][2] HITL is associated with modeling and simulation (M&S;) in the live, virtual, and constructive taxonomy. HITL along with the related human- on -the-loop are also used in relation to lethal autonomous weapons . [3] Further, HITL is used in the context of machine learning . [4] Machine learning In machine learning, HITL is used in the sense of humans aiding the computer in making the correct

decisions in building a model. [4] HITL improves machine learning over random sampling by

selecting the most critical data needed to refine the model. [5]

## Simulation

In simulation, HITL models may conform to human factors requirements as in the case of a mockup . In this type of simulation, a human is always part of the simulation and consequently influences the outcome in such a way that is difficult if not impossible to reproduce exactly. HITL also readily allows for the identification of problems and requirements that may not be easily identified by other means of simulation.

HITL is often referred to as interactive simulation, which is a special kind of physical simulation in which physical simulations include human operators, such as in a flight or a driving simulator.

## **Benefits**

Human-in-the-loop allows the user to change the outcome of an event or process. The immersion effectively contributes to a positive transfer of acquired skills into the real world. This can be demonstrated by trainees utilizing flight simulators in preparation to become pilots.

HITL also allows for the acquisition of knowledge regarding how a new process may affect a particular event. Utilizing HITL allows participants to interact with realistic models and attempt to perform as they would in an actual scenario. HITL simulations bring to the surface issues that would not otherwise be apparent until after a new process has been deployed. A real-world example of HITL simulation as an evaluation tool is its usage by the Federal Aviation Administration (FAA) to allow air traffic controllers to test new automation procedures by directing the activities of simulated air traffic while monitoring the effect of the newly implemented procedures. [6]

As with most processes, there is always the possibility of human error , which can only be reproduced using HITL simulation. Although much can be done to automate systems, humans typically still need to take the information provided by a system to determine the next course of action based on their judgment and experience. Intelligent systems can only go so far in certain circumstances to automate a process; only humans in the simulation can accurately judge the final design. Tabletop simulation may be useful in the very early stages of project development for the purpose of collecting data to set broad parameters, but the important decisions require human-in-the-loop simulation. [7]

Within virtual simulation taxonomy

Virtual simulations inject HITL in a central role by exercising motor control skills (e.g. flying an airplane), decision making skills (e.g. committing fire control resources to action), or communication skills (e.g. as members of a C4I team).

Examples

Flight simulators

**Driving simulators** 

Marine simulators

Video games

Supply chain management simulators [8]

Digital puppetry

Misconceptions

Although human-in-the-loop simulation can include a computer simulation in the form of a synthetic environment, computer simulation is not necessarily a form of human-in-the-loop simulation, and is often considered as human-out-of-the loop simulation. In this particular case, a computer model's behavior is modified according to a set of initial parameters. The results of the model differ from the results stemming from a true human-in-the-loop simulation because the results can easily be replicated time and time again, by simply providing identical parameters.

Weapons

Three classifications of the degree of human control of autonomous weapon systems were laid out by Bonnie Docherty in a 2012 Human Rights Watch report. [3]

human-in-the-loop : a human must instigate the action of the weapon (in other words not fully autonomous)

human-on-the-loop: a human may abort an action human-out-of-the-loop: no human action is involved

See also

Humanistic intelligence , which is intelligence that arises by having the human in the feedback loop of the computational process [ 9 ]

Reinforcement learning from human feedback

MIM-104 Patriot - Examples of a human-on-the-loop lethal autonomous weapon system posing a threat to friendly forces.

References