The Generalised Linear Model; Bootstrapping and Permutations

Philip Leifeld

GV903: Advanced Research Methods, Week 17



1. The Generalised Linear Model

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Many of the distributions we have dealt with can be reformulated mathematically to conform to the exponential family form.

Some of the distributions we have dealt with can only be pressed into an extended version of the exponential family that has an additional *dispersion* parameter ϕ :

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Think of dispersion as the variance and location as the mean.

The Bernoulli Model as an Exponential Family

Ward and Ahlquist (2019)

Last week, we formulated the Bernoulli model for binary outcome data:

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We can show that this is an exponential-family model with $\phi = 1$:

$$f_B(x;\theta) = \theta^x (1-\theta)^{1-x}$$

$$= \exp\left[\log(\theta^x (1-\theta)^{1-x})\right]$$

$$= \exp\left[x\log\theta + (1-x)\log(1-\theta)\right]$$

$$= \exp\left[x\log\frac{\theta}{1-\theta} + \log(1-\theta)\right]$$

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Similar transformations can be applied to the normal distribution (for the linear model), the Poisson distribution for counts etc.

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Fox(2015): Applied Regression Analysis and Generalized Linear Models

Remember the normal distribution from Week 3:

$$p(y) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left[\frac{(y-\mu)^2}{2\sigma^2}\right]$$

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$$p(y; \theta, \phi) = \exp\left\{\frac{y\theta - \theta^2/2}{\phi} - \frac{1}{2}\left[\frac{y^2}{\phi} + \log_e(2\pi\phi)\right]\right\}$$

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This is now in the form of the two-parameter exponential family.

Overview of Different Distributions

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Table 15.9 Functions $a(\cdot)$, $b(\cdot)$, and $c(\cdot)$ for Constructing the Exponential Families

Family	$a(\phi)$	$b(\theta)$	$c(y, \phi)$
Gaussian	φ	$\theta^2/2$	$-\frac{1}{2}\left[y^2/\phi + \log_e(2\pi\phi)\right]$
Binomial	1/n	$\log_{\mathrm{e}}(1+\mathrm{e}^{\theta})$	$\log_{\mathbf{e}}\binom{n}{ny}$
Poisson	1	e^{θ}	$-\log_e y!$
Gamma	ϕ	$-\log_e(-\theta)$	$\phi^{-2}\log_{e}(y/\phi) - \log_{e}y - \log_{e}\Gamma(\phi^{-1})$
Inverse-Gaussian	ϕ	$-\sqrt{-2\theta}$	$-\frac{1}{2}\left[\log_e(\pi\phi y^3) + 1/(\phi y)\right]$

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The *systematic component* is the (additive) linear model part (called the *linear predictor*).

Components of the GLM

Fox(2015): Applied Regression Analysis and Generalized Linear Models

A generalized linear model (or GLM) consists of three components:

- 1. A random component, specifying the conditional distribution of the response variable, Y_i (for the ith of n independently sampled observations), given the values of the explanatory variables in the model. In the initial formulation of GLMs, the distribution of Y_i was a member of an exponential family, such as the Gaussian, binomial, Poisson, gamma, or inverse-Gaussian families of distributions.
- 2. A linear predictor—that is a linear function of regressors,

$$\eta_i = \alpha + \beta_1 X_{i1} + \beta_2 X_{i2} + \cdots + \beta_k X_{ik}$$

3. A smooth and invertible linearizing link function $g(\cdot)$, which transforms the expectation of the response variable, $\mu_i = E(Y_i)$, to the linear predictor:

$$g(\mu_i) = \eta_i = \alpha + \beta_1 X_{i1} + \beta_2 X_{i2} + \dots + \beta_k X_{ik}$$

Link Functions

Fox(2015): Applied Regression Analysis and Generalized Linear Models

Table 15.1 Some Common Link Functions and Their Inverses

Link	$ \eta_i = g(\mu_i) $	$\mu_i = g^{-1}(\eta_i)$
Identity	μ_i	η_i
Log	$\log_e \mu_i$	$e^{\eta_{ar{l}}}$
Inverse	μ_i^{-1}	$\eta_i^{-1} \\ \eta_i^{-1/2}$
Inverse-square	μ_i^{-2}	$\eta_i^{-1/2}$
Square-root	$\sqrt{\mu_i}$	η_i^2
Logit	$\log_{\mathrm{e}} \frac{\mu_i}{1 - \mu_i}$	$\frac{1}{1+e^{-\eta_i}}$
Probit	$\Phi^{-1}(\mu_i)$	$\Phi(\eta_i)$
Log-log	$-\log_{e}[-\log_{e}(\mu_{i})]$	$\exp[-\exp(-\eta_i)]$
Complementary log-log	$\log_{\mathrm{e}}[-\log_{\mathrm{e}}(1-\mu_{i})]$	$1-\exp[-\exp(\eta_i)]$

NOTE: μ_i is the expected value of the response; η_i is the linear predictor; and $\Phi(\cdot)$ is the cumulative distribution function of the standard-normal distribution.

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In R, many of them are conveniently implemented in a single function, glm, with argument family. For example, family = binomial(link = "logit").

2. Bootstrapping

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- ► The *bootstrapping* metaphor goes back to the 19th century saying "to pull oneself over a fence by one's bootstraps", which is of course an impossible task.

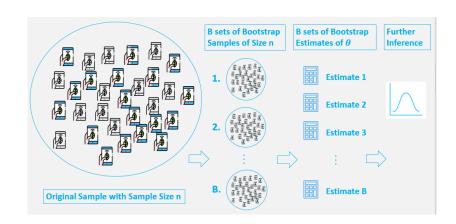
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- ► The *bootstrapping* metaphor goes back to the 19th century saying "to pull oneself over a fence by one's bootstraps", which is of course an impossible task.
- ► Applied to statistics: We sample with replacement from the sample itself.

Bootstrapping: Algorithm Overview

https://towardsdatascience.com/

 $\verb|an-introduction-to-the-bootstrap-method-58bcb51b4d60|$



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- Note how some values appear multiple times while other don't appear in a specific bootstrapping sample due to the replacement.
- These bootstrapping samples form a set of samples $B = \{b_1, b_2, \dots, b_K\}.$

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- Or use the 2.5 per cent and 97.5 quantiles of the distribution of B as the confidence interval if the distribution is not normal.

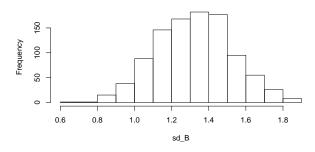
We will try this with n=20 for illustration. With larger samples, it will be asymptotically unbiased.

```
set.seed(123) # set a random seed for reproducibility
n < -20
S <- rnorm(n = n, mean = 5.5, sd = 1.4) # generate some values
S
## [1] 4.715334 5.177752 7.682192 5.598712 5.681003 7.901091
## [7] 6.145283 3.728914 4.538406 4.876073 7.213715 6.003739
## [13] 6.061080 5.654956 4.721822 8.001678 6.196991 2.746736
## [19] 6.481898 4.838092
sd(S) # the empirical SD is slightly off due to small n
## [1] 1.361731
B \leftarrow matrix(0, nrow = 1000, ncol = n)
for (i in 1:1000) { # resample 1000 times
  B[i, ] <- sample(S, size = n, replace = TRUE)</pre>
```

```
B[1:2, ] # let's look at some of the resampled values
          [,1] [,2] [,3] [,4] [,5] [,6]
##
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## [1,] 4.538406 4.721822
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sd_B <- apply(B, 1, sd) # compute SD for each row
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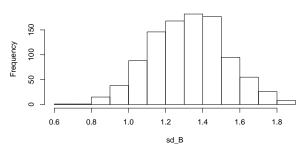
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sd_hat <- mean(sd_B) # compute mean SD across samples
sd_hat # again, slightly off due to small n
## [1] 1.320427
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Histogram of sd_B



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Here's the black magic: We have a sampling distribution of the SD and can now compute SE, CI etc.

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```
SE <- sd(sd_B)
SE
## [1] 0.2022155

CI_lower <- sd_hat - qnorm(1 - (0.05 / 2)) * SE
CI_upper <- sd_hat + qnorm(1 - (0.05 / 2)) * SE
cat(sd_hat, " [", CI_lower, "; ", CI_upper, "]", sep = "")
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Or, if we cannot assume a normal distribution, we can just use the quantiles from the empirical sampling distribution:

```
quantile(sd_B, 0.025)
## 2.5%
## 0.9413218

quantile(sd_B, 0.975)
## 97.5%
## 1.722768
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# lower CI bound, based on initial sample
sd(S) - qnorm(1 - (0.05 / 2)) * (sd(S) / sqrt(n))
## [1] 0.7649373

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Sometimes, the population distribution is unknown. Example: if you do content analysis and count the number of occurrences of some word per speech, to compare two politicians' speech patterns. You want to report the counts along with confidence intervals. You can bootstrap the CIs without having to assume that the counts are generated by a Poisson process and looking up the variance of the Poisson distribution. Cool.

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- ► A simpler estimation strategy, MPLE, is known to be fast but produces biased SEs.
- Bootstrapping across time steps and recomputing the SEs has been shown to be unbiased.

- ► The temporal exponential random graph model (TERGM) is a model for panel network data.
- ► For example, how do the friendships between students in a school class evolve over the weeks of the semester and why?
- ► Estimation: MCMC-MLE. Computationally *very* expensive.
- ► With many observations (e.g., international conflict), the MLE cannot be computed in a hundred human lifetimes.
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Leifeld, Philip, Skyler J. Cranmer and Bruce A. Desmarais (2018): Temporal Exponential Random Graph Models with btergm: Estimation and Bootstrap Confidence Intervals. *Journal of Statistical Software* 83(6): 1–36.

3. Other Resampling Approaches

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- Bootstrap is newer and more flexible.

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- Corrects for overfitting of the model to the data.

Illustration of k-fold Cross-Validation

http://www.ebc.cat/2017/01/31/cross-validation-strategies/



Performance can be assessed using AUC or mean squared prediction error.

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- ▶ H_0 : There is no difference. H_1 : Positive effect on grades.
- ▶ I can now do a two-sample *t*-test or regression with a group dummy to check if there are any differences.
- ▶ OR I can do a permutation test without any distributional assumptions!

Student name	Group	Mark
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Student B	Control	48
Student C	Treatment	97
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- 5. We check if our observed difference is in the tails of that distribution to check for significance.

Let's first create some data for this experiment:

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```
set.seed(123)
dat <- data.frame(group = c(rep("t", 10),</pre>
                          rep("c", 10)),
                mark = c(rnorm(10, 69, 10),
                         rnorm(10, 57, 10)))
head(dat)
## group
          mark
## 1 t. 63.39524
## 2 t 66.69823
## 3 t 84.58708
## 4 t 69.70508
## 5 t 70.29288
## 6 t 86.15065
```

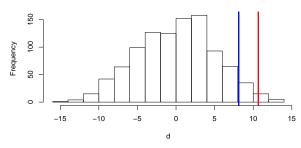
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```
obs <- mean(dat$mark[dat$group == "t"]) -</pre>
    mean(dat$mark[dat$group == "c"])
obs
## [1] 10.66004
t.test(dat$mark[dat$group == "t"], dat$mark[dat$group == "c"])
##
   Welch Two Sample t-test
##
##
## data: dat$mark[dat$group == "t"] and dat$mark[dat$group == "c"]
## t = 2.3913, df = 17.872, p-value = 0.02801
## alternative hypothesis: true difference in means is not equal to 0
## 95 percent confidence interval:
## 1.289512 20.030562
## sample estimates:
## mean of x mean of y
## 69.74626 59.08622
```

```
d <- numeric(1000)
for (i in 1:1000) {
  dat2 <- dat
  dat2$group <- sample(dat2$group, replace = FALSE)
  d[i] <- mean(dat2$mark[dat2$group == "t"]) -
        mean(dat2$mark[dat2$group == "c"])
}
hist(d)
abline(v = quantile(d, 0.95), col = "blue", lwd = 3)
abline(v = obs, col = "red", lwd = 3)</pre>
```

Histogram of d



We can check what the 95 per cent quantile is (as the critical value) and compare the observed difference:

```
obs

## [1] 10.66004

quantile(d, 0.95)

## 95%

## 8.120266
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The observed difference is clearly more extreme than the difference we would have observed if there was no difference in treatment and control group!

We can also compute the *p*-value directly:

```
1 - ecdf(d)(obs) # create a cdf function for empirical values
## [1] 0.013
```

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- ▶ Malang, Thomas, Laurence Brandenberger and Philip Leifeld (2019): Networks and Social Influence in European Legislative Politics. *British Journal of Political Science* 49(4): 1475–1498.
- ▶ But: If parametric (distribution-based) tests are feasible and plausible, they should be preferred!