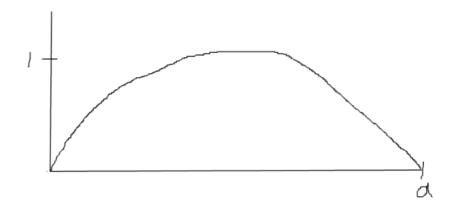
MAT 341 HW8, Carl Liu

1.

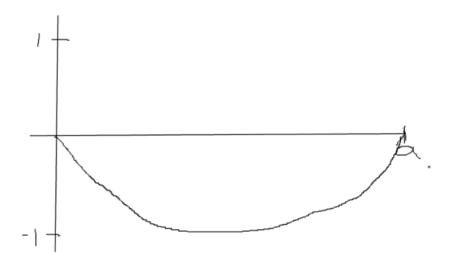
We have $u_1(x,t) = \sin(\lambda_1 x)\cos(\lambda_1 ct) = \sin(\frac{\pi}{a}x)\cos(\frac{\pi}{a}ct)$ and $u_2(x,t) = \sin(\frac{2\pi}{a}x)\cos(\frac{2\pi}{a}ct)$ at t=0 we would have $u_1(x,0) = \sin(\frac{\pi}{a}x)$ and so a graph of the form



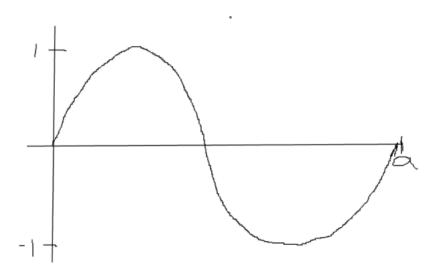
at t = a/2c we would have as our string $u_1(x, a/2c) = \sin(\frac{\pi}{a}x)\cos(\frac{\pi a}{a2c}c) = \sin(\frac{\pi}{a}x)\cos(\frac{\pi}{2}c) = 0$. Resulting in a graph



finally at t = a/c we have $u_1(x, a/c) = \sin(\frac{\pi}{a}x)\cos(\frac{\pi a}{ac}c) = -\sin(\frac{\pi}{a})$ resulting in a graph



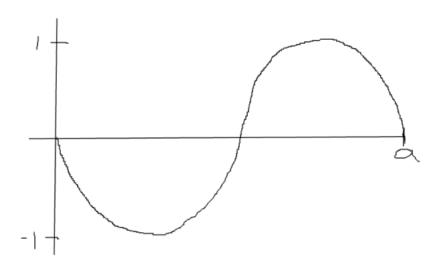
For u_2 at time t=0, we have $u_2(x,0)=\sin(\frac{2\pi}{a}x)$ resulting in a graph



at time t=a/4c we have as our position, $u_2(x,a/4c)=\sin(\frac{2\pi}{a}x)\cos(\frac{2\pi a}{4ac}c)=\sin(\frac{2\pi}{a}x)\cos(\frac{\pi}{a}x)\cos(\frac{\pi}{a}x)$ and so a graph



at time t=a/c we have $u_2(x,a/c)=\sin(\frac{2\pi}{a}x)\cos(\frac{2\pi a}{ac}c)=-\sin(\frac{2\pi}{a}x)$ and so a graph



2.

We have $u(x,0) = f(x) = \sin(\pi x/a)$ and so

$$u(x,0) = \sum_{n=1}^{\infty} a_n \sin\left(\frac{n\pi x}{a}\right) = \sin(\pi x/a)$$

thus resulting in

$$a_n = \frac{1}{a} \int_{-a}^{a} \sin\left(\frac{\pi x}{a}\right) \sin\left(\frac{n\pi x}{a}\right) dx =$$

where we are considering $\sin\left(\frac{\pi x}{a}\right)$ as an odd extension. But we have by orthogonality that $a_n = 0$ for all $n \neq 1$ and so we have $a_1 = a/a = 1$. Since g(x) = 0, we have $b_n = 0$ for all n. Therefore we have

$$u(x,t) = \sin\left(\frac{\pi}{a}x\right)\cos\left(\frac{\pi}{a}ct\right)$$

For the initial condition of f(x) = 0 and g(x) = 1, we have

$$\frac{\partial u}{\partial t}(x,0) = \sum_{n=1}^{\infty} b_n \frac{n\pi}{a} c \sin\left(\frac{n\pi x}{a}\right) = 1$$

This results in

$$b_n = \frac{2}{n\pi c} \int_0^a \sin\left(\frac{n\pi x}{a}\right) dx = -\frac{2a}{n^2 \pi^2 c} \cos(n\pi) + \frac{2a}{n^2 \pi^2 c} = \frac{2a}{n^2 \pi^2 c} (1 - (-1)^n)$$

and since f(x) = 0 we have $a_n = 0$. Thus we have

$$u(x,t) = \sum_{n=1}^{\infty} \frac{2a}{n^2 \pi^2 c} (1 - (-1)^n) \sin\left(\frac{n\pi}{a}x\right) \sin\left(\frac{n\pi}{a}ct\right)$$

3.

We have $u(x,t) = \psi(x+ct) + \phi(x-ct)$ and so

$$\frac{\partial^2 u}{\partial x^2} = \frac{d^2 \psi}{d(x+ct)^2} (x+ct) + \frac{d^2 \phi}{d(x-ct)^2} (x-ct)$$

$$\frac{\partial^2 u}{\partial t^2} = c^2 \frac{d^2 \psi}{d(x+ct)^2} (x+ct) + c^2 \frac{d^2 \phi}{d(x-ct)^2} (x-ct)$$

where the first equality comes from the fact that the derivative of x + ct and x - ct with respect to x is 1 and the second equality due to the derivative of x + ct and x - ct with respect to t being c and -c respectively. Thus we have

$$\frac{\partial^2 u}{\partial x^2} = \frac{d^2 \psi}{d(x+ct)^2} (x+ct) + \frac{d^2 \phi}{d(x-ct)^2} (x-ct) =$$

$$\frac{c^2}{c^2} \frac{d^2 \psi}{d(x+ct)^2} (x+ct) + \frac{c^2}{c^2} \frac{d^2 \phi}{d(x-ct)^2} (x-ct) = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2}$$

and so

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2}$$

as required thereby satisfying the vibrating string equation.

4.

We have

$$u(x,t) = \psi(x+ct) + \phi(x-ct) = \frac{1}{2}(\overline{f}_o(x+ct) + \overline{G}_e(x+ct) + \overline{f}_o(x-ct) - \overline{G}_e(x-ct))$$

but because \overline{G}_e and \overline{f}_o both have their third derivative existing at every point on the real line, we can conclude that ψ and ϕ also have their third derivative existing at every point on the real line. Thus we can conclude through problem 3 that u(x,t) as defined as so satisfies

$$\frac{\partial^2 u}{\partial x^2} = \frac{1}{c^2} \frac{\partial^2 u}{\partial t^2}$$

Now for u(0,t), we have

$$u(0,t) = \frac{1}{2} (\overline{f}_o(ct) + \overline{G}_e(ct) + \overline{f}_o(-ct) - \overline{G}_e(-ct))$$

Since \overline{G}_e is even, we have $\overline{G}_e(ct) = \overline{G}_e(-ct)$. Since \overline{f}_o is odd we have $\overline{f}_o(ct) = -\overline{f}_o(-ct)$. Thus we have

$$u(0,t) = 0$$

as required. Now

$$u(x,0) = \frac{1}{2}(\overline{f}_o(x) + \overline{G}_e(x) + \overline{f}_o(x) - \overline{G}_e(x)) = \overline{f}_o(x)$$

which is just f(x) over 0 < x < a and so we have

$$u(x,0) = f(x)$$

as required. Finally

$$\frac{\partial u}{\partial t}(x,t) = \frac{1}{2} \left(c \frac{d\overline{f}_o}{d(x+ct)}(x+ct) + c \frac{d\overline{G}_e}{d(x+ct)}(x+ct) - c \frac{d\overline{f}_o}{d(x-ct)}(x-ct) + c \frac{d\overline{G}_e}{d(x-ct)}(x-ct) \right)$$

Thus we have

$$\frac{\partial u}{\partial t}(x,0) = \frac{1}{2} \left(c \frac{d\overline{f}_o}{d(x)}(x) + c \frac{d\overline{G}_e}{d(x)}(x) - c \frac{d\overline{f}_o}{d(x)}(x) + c \frac{d\overline{G}_e}{d(x)}(x) \right) = c \frac{d\overline{G}_e}{d(x)}(x)$$

Since it has been established that $\frac{d\overline{G}_e}{d(x)}(x)$ has a derivative that exists for all x, we must have

$$\frac{d\overline{G}_e}{d(x)}(x) = \frac{dG}{d(x)}(x) = \frac{1}{c}\frac{d}{dx}\int_0^x g(y)dy = \frac{1}{c}g(x)$$

for 0 < x < a and thus

$$\frac{\partial u}{\partial t}(x,0) = c \frac{d\overline{G}_e}{d(x)}(x) = \frac{c}{c}g(x) = g(x)$$

as required.