

### PHY 300 HW 3, Carl Liu

#### 4-16

A) Through Kirchhoff's junction rule, we have that the current into a junction is equal to that out of the junction. So we have  $I_0 \cos(\omega t) = I_1 + I_2 + I_3$ . But  $I_1 = V_R/R$ . We also have  $C * V_C = q$ . Since  $V_C$  is dependent on the current, which is dependent on time, we have  $C * dV_C/dt = I_2$ . Finally  $V_L = LdI_3/dt$ . Thus

$$\frac{1}{L} \int V_L dt = \int dI_3 = I_3$$

So

$$I_0 \cos(\omega t) = \frac{V_R}{R} + C \frac{dV_C}{dt} + \frac{1}{L} \int V_L dt$$

But because  $V_C = V_L = V_R$  due to the components being in parallel and  $V_L = LdI_3/dt$ , we can thus conclude that

$$I_0 \cos(\omega t) = CL \frac{d^2 I_3}{dt^2} + \frac{L}{R} \frac{dI_3}{dt} + I_3$$

So

$$\frac{I_0}{LC} \cos(\omega t) = \frac{d^2 I_3}{dt^2} + \frac{1}{RC} \frac{dI_3}{dt} + \frac{1}{LC} I_3$$

This is the same form as a damped driven harmonic oscillator and so we have

$$\omega_0^2 = \frac{1}{LC} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$

and

$$B) \quad \gamma = \frac{1}{RC}$$

C) Since the resistor is the only draining power source we have  $\langle P \rangle = \langle V^2/R \rangle = V_0^2/2R$

Since  $V_0 = I_0 R$  at resonance, we have  $\langle V^2/R \rangle = I_0^2 R/2$

#### 5-2

Lets consider the right pendulum clamped. We then have

$$m \frac{d^2 x}{dt^2} = -m \frac{g}{l} x - kx$$

$$\frac{d^2x}{dt^2} + \left(\frac{g}{l} + \frac{k}{m}\right)x = 0$$

for the left pendulum since the right pendulum causes no displacement to the spring. But that means  $\omega_0^2 = \frac{g}{l} + \frac{k}{m}$  and so  $\omega_0 = \sqrt{\frac{g}{l} + \frac{k}{m}}$ . We know that  $T = 1.25s$ . So  $\omega_0 = 2\pi/T = 5.027rad/s$ . Then  $5.027rad/s = \sqrt{\frac{g}{l} + \frac{k}{m}}$  meaning  $0.770729s^{-2} = \frac{k}{m}$

A) The forces on the pendulums allowed to swing freely is governed by the differential equations

$$m \frac{d^2x_1}{dt^2} = -\frac{mg}{l}x_1 - k(x_1 - x_2)$$

$$m \frac{d^2x_2}{dt^2} = -\frac{mg}{l}x_2 - k(x_2 - x_1)$$

Thus

$$\frac{d^2x_1}{dt^2} + \left(\frac{g}{l} + \frac{k}{m}\right)x_1 - \frac{k}{m}x_2 = 0$$

$$\frac{d^2x_2}{dt^2} + \left(\frac{g}{l} + \frac{k}{m}\right)x_2 - \frac{k}{m}x_1 = 0$$

We then have

$$\frac{d^2(x_1 - x_2)}{dt^2} + \left(\frac{g}{l} + 2\frac{k}{m}\right)(x_1 - x_2) = 0$$

$$\frac{d^2(x_1 + x_2)}{dt^2} + \left(\frac{g}{l}\right)(x_1 + x_2) = 0$$

Letting  $y = x_1 - x_2$  and  $z = x_1 + x_2$ , we then have solutions of

$$y = C \cos \left( \sqrt{\frac{g}{l} + 2\frac{k}{m}}t \right)$$

$$z = D \cos \left( \sqrt{\frac{g}{l}}t \right)$$

So for the two normal modes, we have

$$\omega_1 = \sqrt{\frac{g}{l} + 2\frac{k}{m}} = 5.1031rad/s$$

$$\omega_2 = \sqrt{\frac{g}{l}} = 4.95 \text{ rad/s}$$

and thus their periods are

$$T_1 = \frac{2\pi}{\omega_1} 1.23 \text{ s}$$

$$T_2 = \frac{2\pi}{\omega_2} = 1.27 \text{ s}$$

B) We have

$$x_1(t) = \frac{y+z}{2} = C \cos \left( \sqrt{\frac{g}{l} + 2\frac{k}{m}} t \right) + D \cos \left( \sqrt{\frac{g}{l}} t \right)$$

$$x_2(t) = \frac{z-y}{2} = D \cos \left( \sqrt{\frac{g}{l}} t \right) - C \cos \left( \sqrt{\frac{g}{l} + 2\frac{k}{m}} t \right)$$

These can be considered beats and we thus have successive maximums with a period of  $2\pi/(5.1031 - 4.95) = 41.04 \text{ s}$

#### 5-4

The differential equation governing this system is

$$m \frac{d^2 x_A}{dt^2} = -k_A x_A - k_C (x_A - x_B)$$

$$m \frac{d^2 x_B}{dt^2} = -k_B x_B - k_C (x_B - x_A)$$

Then

$$\frac{d^2 x_A}{dt^2} + \frac{k_A + k_C}{m} x_A - \frac{k_C}{m} x_B = 0$$

$$\frac{d^2 x_B}{dt^2} + \frac{k_B + k_C}{m} x_B - \frac{k_C}{m} x_A = 0$$

Using the eigenvalue method we have

$$e^{\alpha t} \mathbf{c} = \mathbf{x} \quad \text{Let } \alpha^2 = \lambda = -\omega^2 \quad \text{Thus } \alpha = \pm i\omega$$

$$\lambda \mathbf{c} = \begin{bmatrix} -\frac{k_A + k_C}{m} & \frac{k_C}{m} \\ \frac{k_C}{m} & -\frac{k_B + k_C}{m} \end{bmatrix} \mathbf{c}$$

$$0 = \begin{bmatrix} -\frac{k_A+k_C}{m} - \lambda & \frac{k_C}{m} \\ \frac{k_C}{m} & -\frac{k_B+k_C}{m} - \lambda \end{bmatrix} \mathbf{c}$$

So

$$\begin{aligned} & \left( -\frac{k_A+k_C}{m} - \lambda \right) \left( -\frac{k_B+k_C}{m} - \lambda \right) - \frac{k_C^2}{m^2} = \\ \lambda^2 + \lambda \left( \frac{k_A+k_C}{m} + \frac{k_B+k_C}{m} \right) + \left( \frac{k_A+k_C}{m} \right) \left( \frac{k_B+k_C}{m} \right) - \frac{k_C^2}{m^2} = \\ \lambda^2 + \lambda \left( \frac{k_A+2k_C+k_B}{m} \right) + \left( \frac{k_Ak_B+k_C(k_A+k_B)}{m^2} \right) &= 0 \end{aligned}$$

Meaning

$$\begin{aligned} \lambda = - \left( \frac{k_A+2k_C+k_B}{2m} \right) \pm \frac{1}{2} \sqrt{\left( \frac{k_A+2k_C+k_B}{m} \right)^2 - 4 \left( \frac{k_Ak_B+k_C(k_A+k_B)}{m^2} \right)} = \\ - \left( \frac{k_A+2k_C+k_B}{2m} \right) \pm \frac{1}{2} \sqrt{\frac{k_A^2 - 2k_Bk_A + 4k_C^2 + k_B^2}{m^2}} \end{aligned}$$

But we have  $k_C^2 = k_Ak_B$  and so

$$\begin{aligned} \lambda = - \left( \frac{k_A+2k_C+k_B}{2m} \right) \pm \frac{1}{2m} \sqrt{k_A^2 + 2k_Bk_A + k_B^2} = \\ - \left( \frac{k_A+2k_C+k_B}{2m} \right) \pm \frac{1}{2m} \sqrt{(k_A+k_B)^2} = \\ - \left( \frac{k_A+2k_C+k_B}{2m} \right) \pm \frac{1}{2m} (k_A+k_B) \end{aligned}$$

So we have

$$\lambda = -\frac{k_C}{m}$$

or

$$\lambda = -\frac{k_A+k_C+k_B}{m}$$

From the earlier definition of  $\alpha$ , we have

$$\alpha = \pm i \sqrt{\frac{k_C}{m}}$$

or

$$\alpha = \pm i \sqrt{\frac{k_A + k_C + k_B}{m}}$$

This means we have linearly independent solutions of

$$\exp\left(\pm i \sqrt{\frac{k_C}{m}} t\right)$$

$$\exp\left(\pm i \sqrt{\frac{k_A + k_C + k_B}{m}} t\right)$$

Thus we have

$$\omega' = \sqrt{\frac{k_C}{m}}$$

and

$$\omega'' = \sqrt{\frac{k_A + k_C + k_B}{m}}$$

## 5-9

A) We have the differential equations below describing the molecules motion

$$m_1 \frac{d^2 x_1}{dt^2} = -k(x_1 - x_2)$$

$$m_2 \frac{d^2 x_2}{dt^2} = -k(x_2 - x_3) - k(x_2 - x_1) = -k(2x_2 - x_1 - x_3)$$

$$m_3 \frac{d^2 x_3}{dt^2} = -k(x_3 - x_2)$$

So

$$\frac{d^2 x_1}{dt^2} = -\frac{k}{m_1}(x_1 - x_2)$$

$$\frac{d^2 x_2}{dt^2} = -\frac{k}{m_2}(2x_2 - x_1 - x_3)$$

$$\frac{d^2 x_3}{dt^2} = -\frac{k}{m_3}(x_3 - x_2)$$

We will solve for the normal modes by using the eigenvalue method

$$e^{\alpha t} \mathbf{c} = \mathbf{x} \quad \text{Let } \alpha^2 = \lambda = -\omega^2 \quad \text{Thus } \alpha = \pm i\omega$$

$$\lambda \mathbf{c} = \begin{bmatrix} -\frac{k}{m_1} & \frac{k}{m_1} & 0 \\ \frac{k}{m_2} & -2\frac{k}{m_2} & \frac{k}{m_2} \\ 0 & \frac{k}{m_3} & -\frac{k}{m_3} \end{bmatrix} \mathbf{c}$$

$$0 = \begin{bmatrix} -\frac{k}{m_1} - \lambda & \frac{k}{m_1} & 0 \\ \frac{k}{m_2} & -2\frac{k}{m_2} - \lambda & \frac{k}{m_2} \\ 0 & \frac{k}{m_3} & -\frac{k}{m_3} - \lambda \end{bmatrix} \mathbf{c}$$

So

$$\begin{aligned} 0 &= \left( \frac{-k}{m_1} - \lambda \right) \left( \left( \frac{-2k}{m_2} - \lambda \right) \left( \frac{-k}{m_3} - \lambda \right) - \frac{k^2}{m_2 m_3} \right) - \frac{k^2}{m_1 m_2} \left( \frac{-k}{m_3} - \lambda \right) = \\ &= \frac{-k}{m_1} \left( \frac{-2k}{m_2} - \lambda \right) \left( \frac{-k}{m_3} - \lambda \right) + \frac{k^3}{m_1 m_2 m_3} - \lambda \left( \frac{-2k}{m_2} - \lambda \right) \left( \frac{-k}{m_3} - \lambda \right) + \\ &= \frac{k^2 \lambda}{m_2 m_3} + \frac{k^3}{m_1 m_2 m_3} + \frac{k^2 \lambda}{m_1 m_2} = \\ &= \frac{-2k^3}{m_1 m_2 m_3} - \frac{k^2 \lambda}{m_1 m_3} - \frac{2k^2 \lambda}{m_1 m_2} - \frac{\lambda^2 k}{m_1} + \frac{k^3}{m_1 m_2 m_3} - \frac{2k^2 \lambda}{m_2 m_3} - \frac{k \lambda^2}{m_3} - \frac{2k \lambda^2}{m_2} - \lambda^3 + \\ &= \frac{k^2 \lambda}{m_2 m_3} + \frac{k^3}{m_1 m_2 m_3} + \frac{k^2 \lambda}{m_1 m_2} = \\ &= -\frac{k^2 \lambda}{m_1 m_3} - \frac{k^2 \lambda}{m_1 m_2} - \frac{\lambda^2 k}{m_1} - \frac{k^2 \lambda}{m_2 m_3} - \frac{k \lambda^2}{m_3} - \frac{2k \lambda^2}{m_2} - \lambda^3 = \\ &= -\lambda \left( \frac{k^2}{m_1 m_3} + \frac{k^2}{m_1 m_2} + \frac{\lambda k}{m_1} + \frac{k^2}{m_2 m_3} + \frac{k \lambda}{m_3} + \frac{2k \lambda}{m_2} + \lambda^2 \right) = \\ &= -\lambda \left( \lambda^2 + \left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right) \lambda + \left( \frac{k^2}{m_1 m_3} + \frac{k^2}{m_1 m_2} + \frac{k^2}{m_2 m_3} \right) \right) = 0 \end{aligned}$$

So we have  $\lambda = 0$  as a solution and so  $\alpha = 0$  thus  $0 = \omega_0$  as a normal mode.

We also have

$$\lambda = -\frac{1}{2} \left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right) \pm \frac{1}{2} \sqrt{\left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right)^2 - 4 \left( \frac{k^2}{m_1 m_3} + \frac{k^2}{m_1 m_2} + \frac{k^2}{m_2 m_3} \right)} =$$

$$\begin{aligned}
& -\frac{1}{2} \left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right) \pm \\
& \frac{1}{2} \sqrt{\frac{k^2}{m_1^2} + \frac{k^2}{m_3 m_1} + \frac{2k^2}{m_2 m_1} + \frac{k^2}{m_1 m_3} + \frac{k^2}{m_3^2} + \frac{2k^2}{m_3 m_2} + \frac{2k^2}{m_1 m_2} +} \\
& \frac{2k^2}{m_3 m_2} + \frac{4k^2}{m_2^2} - 4 \left( \frac{k^2}{m_1 m_3} + \frac{k^2}{m_1 m_2} + \frac{k^2}{m_2 m_3} \right) = \\
& -\frac{1}{2} \left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right) \pm \\
& \frac{1}{2} \sqrt{\frac{k^2}{m_1^2} + \frac{2k^2}{m_3 m_1} + \frac{4k^2}{m_2 m_1} + \frac{k^2}{m_3^2} + \frac{4k^2}{m_3 m_2} +} \\
& \frac{4k^2}{m_2^2} - 4 \left( \frac{k^2}{m_1 m_3} + \frac{k^2}{m_1 m_2} + \frac{k^2}{m_2 m_3} \right) = \\
& -\frac{1}{2} \left( \frac{k}{m_1} + \frac{k}{m_3} + \frac{2k}{m_2} \right) \pm \frac{1}{2} \sqrt{\frac{k^2}{m_1^2} - \frac{2k^2}{m_3 m_1} + \frac{k^2}{m_3^2} + \frac{4k^2}{m_2^2}}
\end{aligned}$$

But  $m_1 = m_3$  and so we have

$$\begin{aligned}
\lambda &= -\frac{1}{2} \left( \frac{k}{m_1} + \frac{k}{m_1} + \frac{2k}{m_2} \right) \pm \frac{1}{2} \sqrt{\frac{k^2}{m_1^2} - \frac{2k^2}{m_1^2} + \frac{k^2}{m_1^2} + \frac{4k^2}{m_2^2}} = \\
& -\frac{1}{2} \left( \frac{2k}{m_1} + \frac{2k}{m_2} \right) \pm \frac{1}{2} \frac{2k}{m_2}
\end{aligned}$$

So we have

$$\lambda = -\frac{k}{m_1}$$

or

$$\lambda = -\frac{k}{m_1} - \frac{2k}{m_2}$$

From the earlier definitions for  $\alpha$ , we have  $\alpha = \pm i \sqrt{\frac{k}{m_1}}$  or  $\alpha = \pm i \sqrt{\frac{k}{m_1} + \frac{2k}{m_2}}$

Thus we have

$$\exp \left( \pm i \sqrt{\frac{k}{m_1}} t \right)$$

$$\exp\left(\pm i\sqrt{\frac{k}{m_1} + \frac{2k}{m_2}}t\right)$$

as linearly independent solutions. Thus we have

$$\omega' = \sqrt{\frac{k}{m_1}}, \quad \omega'' = \sqrt{\frac{k}{m_1} + \frac{2k}{m_2}}, \text{ and } \omega_0 = 0$$

as normal modes ( $\omega_0$  was shown earlier). If  $m_3 \neq m_1$ , we could have taken the square root of the  $\lambda$ 's before substituting  $m_3 = m_1$  and arrived at the normal modes through the same continuing process.

B) By having  $m_1 = m_3 = 16$  and  $m_2 = 12$  and taking a ratio

$$\frac{\omega'}{\omega''} = \frac{\sqrt{\frac{k}{m_1}}}{\sqrt{\frac{k}{m_1} + \frac{2k}{m_2}}} = \sqrt{\frac{1}{m_1\left(\frac{1}{m_1} + \frac{2}{m_2}\right)}} = \sqrt{\frac{1}{1 + \frac{2m_1}{m_2}}} = \sqrt{\frac{1}{1 + \frac{32}{12}}} =$$

0.5222

Taking the ratio the other way we arrive at

$$\frac{\omega''}{\omega'} = \left(\frac{\omega'}{\omega''}\right)^{-1} = 1.915$$

as the ratio

## 5-10

Not taking into account the gravitational force, we have

$$m \frac{d^2 x_1}{dt} = -kx_1 - k(x_1 - x_2)$$

$$m \frac{d^2 x_2}{dt} = -k(x_2 - x_1)$$

So

$$\frac{d^2 x_1}{dt} + 2\frac{k}{m}x_1 - \frac{k}{m}x_2 = 0$$

$$\frac{d^2 x_2}{dt} + \frac{k}{m}(x_2 - x_1) = 0$$



We shall use the eigenvalue method

$$e^{\alpha t} \mathbf{c} = \mathbf{x} \quad \text{Let } \alpha^2 = \lambda = -\omega^2 \quad \text{Thus } \alpha = \pm i\omega$$

$$\lambda \mathbf{c} = \begin{bmatrix} -2\frac{k}{m} & \frac{k}{m} \\ \frac{k}{m} & -\frac{k}{m} \end{bmatrix} \mathbf{c}$$

$$0 = \begin{bmatrix} -2\frac{k}{m} - \lambda & \frac{k}{m} \\ \frac{k}{m} & -\frac{k}{m} - \lambda \end{bmatrix} \mathbf{c}$$

So

$$0 = \left(-2\frac{k}{m} - \lambda\right) \left(-\frac{k}{m} - \lambda\right) - \frac{k^2}{m^2} = 2\frac{k^2}{m^2} + \frac{k\lambda}{m} + 2\frac{k\lambda}{m} + \lambda^2 - \frac{k^2}{m^2} =$$

$$\lambda^2 + 3\lambda\frac{k}{m} + \frac{k^2}{m^2}$$

Thus

$$\lambda = -\frac{3k}{m} \pm \frac{1}{2}\sqrt{9\frac{k^2}{m^2} - 4\frac{k^2}{m^2}} = -3\frac{k}{2m} \pm \frac{1}{2}\sqrt{5\frac{k^2}{m^2}} = (-3 \pm \sqrt{5})\frac{k}{2m}$$

Therefore we have linearly independent solutions of

$$\exp(\pm i\sqrt{(3 \pm \sqrt{5})\frac{k}{2m}}t)$$

So

$$\omega = \sqrt{(3 \pm \sqrt{5})\frac{k}{2m}}$$

for the normal modes meaning

$$\omega^2 = (3 \pm \sqrt{5})\frac{k}{2m}$$

as required. The ratio is thus

$$\frac{\omega_+}{\omega_-} = \sqrt{\frac{(3 + \sqrt{5})\frac{k}{2m}}{(3 - \sqrt{5})\frac{k}{2m}}} = \sqrt{\frac{3 + \sqrt{5}}{3 - \sqrt{5}}} = \frac{\sqrt{4}}{3 - \sqrt{5}} = \sqrt{\frac{3 + \sqrt{5}}{3 - \sqrt{5}}}$$

$$= \frac{2 + 2\sqrt{5}}{3 - \sqrt{5} + 3\sqrt{5} - 5} = \frac{2 + 2\sqrt{5}}{-2 + 2\sqrt{5}} = \frac{\sqrt{5} + 1}{\sqrt{5} - 1}$$

as required. Since the solutions have the same frequencies when in normal modes, we have  $x_1 = A \cos(\omega t)$  and  $x_3 = B \cos(\omega t)$ . Consider the first normal mode  $\omega_+$ , we have from the differential equations

$$\begin{aligned} -A\omega_+^2 + A2\frac{k}{m} &= B\frac{k}{m} \\ -A(3 + \sqrt{5})\frac{k}{2m} + A2\frac{k}{m} &= B\frac{k}{m} \\ \frac{B}{A} &= 2 - \frac{1}{2}(3 + \sqrt{5}) = -0.618 \end{aligned}$$

Consider the second normal mode  $\omega_-$ , we have from the differential equations

$$\begin{aligned} -A\omega_-^2 + A2\frac{k}{m} &= B\frac{k}{m} \\ -A(3 - \sqrt{5})\frac{k}{2m} + A2\frac{k}{m} &= B\frac{k}{m} \\ \frac{B}{A} &= 2 - \frac{1}{2}(3 - \sqrt{5}) = 1.618 \end{aligned}$$