

Probability theory basics

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‘HPC and Uncertainty Treatment – Examples with Open TURNS and Uranie’

EDF – Phimeca – Airbus Group – IMACS – CEA

PRACE Advanced Training Center – May, 17-19 2016



MAISON DE LA SIMULATION

Motivation

☐ Uncertainty is here defined in a broad sense. It is meant to include variability, uncertainty and lack-of-knowledge.

- **Aleatory** uncertainty: intrinsic randomness, variance of a phenomenon
 - Due to lack of control over environmental variability and test settings (temperature, humidity, etc.), and to errors made during testing.
 - Can be better characterized but cannot be reduced by taking more measurements or performing more simulations.
- **Epistemic** uncertainty: lack-of-knowledge, ambiguity, haziness.
 - Due to lack-of-knowledge about materials, loads, initial conditions, etc. and to assumptions made during testing and modeling.
 - Can be reduced by collecting more information and evidence.

These sources of uncertainty are modeled and propagated by means of
probability theory

Note: Other theories have been developed to represent epistemic uncertainty such as Imprecise Theory (IP), Possibility theory, Fuzzy sets and fuzzy logic.

Outline

General definitions

- Random experiment – Event
- Measurable space
- Kolmogorov axioms
- Bayes' theorem

Random variables

- Definitions
- Cumulative distribution function (CDF) and probability density function (PDF)
- Discrete / continuous random variables
- Statistical moments
- Confidence intervals (CI)

Some common continuous distributions

Random vectors

- Definitions
- Moments
- Copulas

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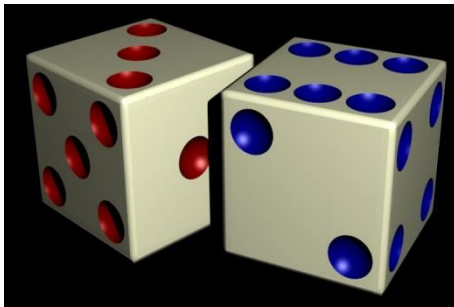
- Definitions
- Moments
- Copulas

Definitions

☐ Random experiment

- A **random experiment** is a repeatable procedure that has more than one possible **outcome**. The result is aleatory.
- A **realization** or an **outcome** is a possible result of an experiment.
- The **sample space** is the set of all possible outcomes of the experiment. It is commonly referred by Ω

Throwing of two six-sided dices



Sample space:

- ✓ The pairs of faces
 $\Omega = \{(1,1), (1,2), (1,3), \dots\}$
- ✓ The sum of the faces
 $\Omega = \{2,3,4,5,6,7,8,9,10,11,12\}$

Definitions

Event

An **event** is a set of outcomes of an experiment (a subset of the sample space Ω).
The set of events is denoted Φ .

Throwing of 2 six-face-dices

A_1 = “Do an even number”

A_2 = “Do more than 2”

Some **particular events**:

Ω Certain event

The sum of the two dices is less than or equal to 12

\emptyset Impossible event

The sum of the two dices is strictly less than to 2

$\{\omega\}$ Simple event

The sum of the two dices is equal to 12

Composed event

Any event whose cardinality is strictly more than 1

Definitions

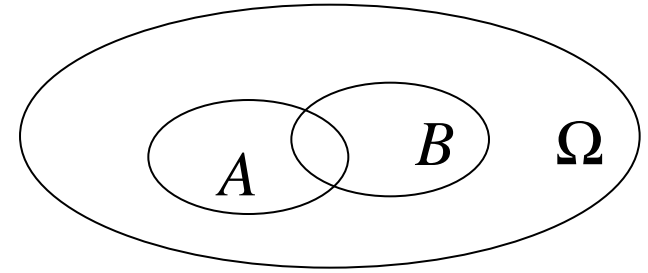
Operations of events

Operators

$A \cup B$: union

$A \cap B$: intersection

\bar{A} : complement



Venn diagram

Properties

- Any finite or countable union or intersection of events is an event.
- If $A \cap B = \emptyset$ then A et B are disjoint
- *Commutativity, associativity, distributivity* of intersection over union and De Morgan's laws:

$$A \cup B = B \cup A \quad \text{et} \quad A \cap B = B \cap A \quad (A \cup B) \cup C = A \cup (B \cup C)$$

$$(A \cup B) \cap C = (A \cap C) \cup (B \cap C) \quad \overline{A \cap B} = \bar{A} \cup \bar{B} \quad \text{et} \quad \overline{A \cup B} = \bar{A} \cap \bar{B}$$

Definitions

Partitions of Ω

- A and B form a *partition* of Ω if and only if they are *mutually exclusive* and *collectively exhaustive*:

$$A \cap B = \emptyset \quad \text{and} \quad A \cup B = \Omega$$

Set of measurable spaces (or σ – algebra)

A set of events \mathcal{F} belonging to the set of parts of Ω is measurable if and only if:

- $\emptyset \in \mathcal{F}$ and $\Omega \in \mathcal{F}$
- If A_i is a sequence in \mathcal{F} then $\bigcup_i A_i \in \mathcal{F}$ and $\bigcap_i A_i \in \mathcal{F}$
- If $A \in \mathcal{F}$ then $\bar{A} \in \mathcal{F}$

If \mathcal{F} is measurable in Ω then (\mathcal{F}, Ω) is a *measurable space*.

Definitions

Kolmogorov axioms

A *probability measure* allows to associate numbers to events, i.e. *their probability of occurrence*.

It is defined as an application $\mathbb{P} : \mathcal{F} \mapsto [0, 1]$ satisfying the *Kolmogorov axioms*:

- $\forall A \in \mathcal{F}, 0 \leq \mathbb{P}(A) \leq 1$
- $\mathbb{P}(\Omega) = 1$
- For any set of finite or countable of disjoints events A_i

$$\mathbb{P}[\cup_i A_i] = \sum_i \mathbb{P}[A_i]$$

The *probability space* thus build is denoted $(\Omega, \mathcal{F}, \mathbb{P})$

Throwing 2 dices

A_1 = « Do an even number »

$$\mathbb{P}[A_1] = \frac{1}{2}$$

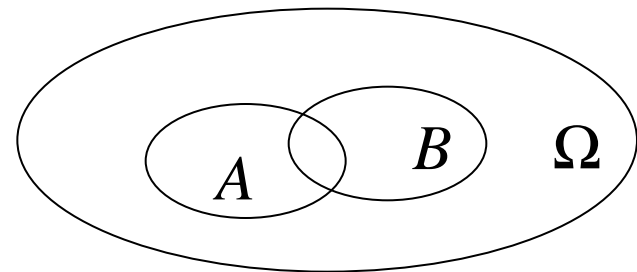
A_2 = « Do more than 2 »

$$\mathbb{P}[A_2] = \frac{35}{36}$$

Definitions

From the Kolmogorov axioms, the elementary results hold:

- $\mathbb{P}[\emptyset] = 0$
- $\mathbb{P}[\omega] = 1$
- $\mathbb{P}[\bar{A}] = 1 - \mathbb{P}[A]$
- $\mathbb{P}[A \setminus B] = \mathbb{P}[A] - \mathbb{P}[A \cap B]$
- $\mathbb{P}[A \cup B] = \mathbb{P}[A] + \mathbb{P}[B] - \mathbb{P}[A \cap B]$
- $A \subseteq B \Rightarrow \mathbb{P}[A] \leq \mathbb{P}[B]$



Definitions

☐ Frequentist interpretation of probabilities

The *probability of an event* is the limit of its *empirical frequency* of occurrence

Throwing 2 dices:

- A random experiment is made N times
- The event A_1 = « Do an even number » is observed
- N_{A_1} is the number of times for which the event A_1 is observed

$$\mathbb{P}[A_1] = \lim_{N \rightarrow \infty} \frac{N_{A_1}}{N}$$

Definitions

Conditional probability

$$\mathbb{P}[A|B] = \frac{\mathbb{P}[A \cap B]}{\mathbb{P}[B]}$$

It reads « probability of A given B »

Independence

- Two events A and B are said independent events when the occurrence of B does not affect the probability of occurrence of A , and vice versa:

$$\mathbb{P}[A|B] = \mathbb{P}[A] \Rightarrow \mathbb{P}[A \cap B] = \mathbb{P}[A]\mathbb{P}[B]$$

Definitons

Bayes' theorem

$$\mathbb{P}[A|B] = \frac{\mathbb{P}[B|A]}{\mathbb{P}[B]} \mathbb{P}[A]$$

Influence of the information
contained in B

Initial probability of A

It is the probability of A that is *updated by the knowledge of the occurrence of B*

- Proof:

$$\mathbb{P}(A|B) = \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(B)} = \frac{\mathbb{P}(B|A)\mathbb{P}(A)}{\mathbb{P}(B)}$$

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Random variables

Definition

A random variable is a *measurable function*:

$$X : \Omega \rightarrow \mathbb{X}$$
$$\omega \mapsto x = X(\omega)$$

A *discrete random variables* can take either a finite or at most a countably infinite set of discrete values

$$\mathbb{X} \subseteq \mathbb{Z}$$

Examples : sum of two dices, rupture cycles number

Continuous random variables take on values that vary continuously within one or more real intervals

$$\mathbb{X} \subseteq \mathbb{R}$$

Examples : Young modulus of a material, value of loading applied on a structure.

Random variables

☐ Cumulative distribution function

It is the function that relates x to the probability that the random variable X takes on a value less than or equal to x

$$F_X(x) = \mathbb{P}[X \leq x]$$

☐ Probability density function

Discrete case: it is the function that relates x to the probability that the random variable X takes on a given value *equal* to x :

$$p_X(x) = \mathbb{P}[X = x]$$

Continuous case: it is the function that relates x to the probability that the random variable X belongs to the infinitesimal interval $[x, x + dx]$.

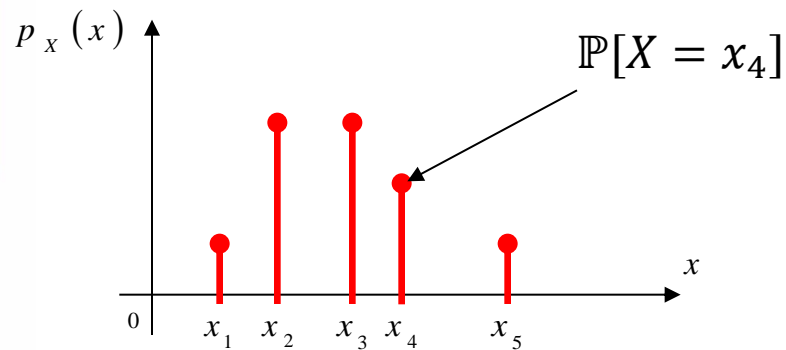
$$f_X(x)dx = \mathbb{P}(x < X \leq x + dx)$$

And $f_X(x)$ is the *derivative of the cumulative distribution function* :

$$f_X(x) = \frac{dF_X(x)}{dx}$$

Random variables

Discrete random variable



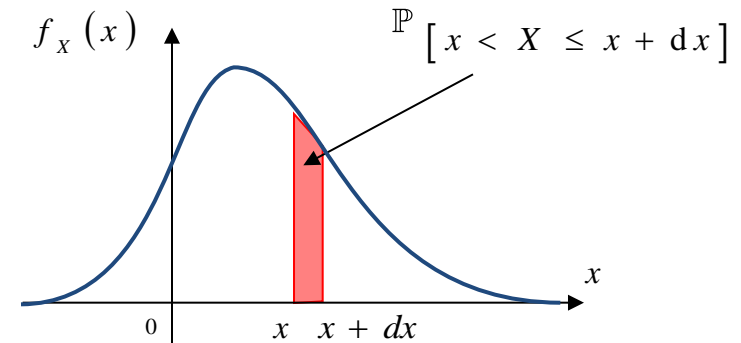
$$p_X(x_i) = \mathbb{P}[X = x_i]$$

p_X = *probability mass function*

$$\forall x_i, 0 \leq p_X(x_i) \leq 1$$

$$\sum_{x_i} p_X(x_i) = 1$$

Continuous random variable



$$f_X(x) dx = \mathbb{P}[x < X \leq x + dx]$$

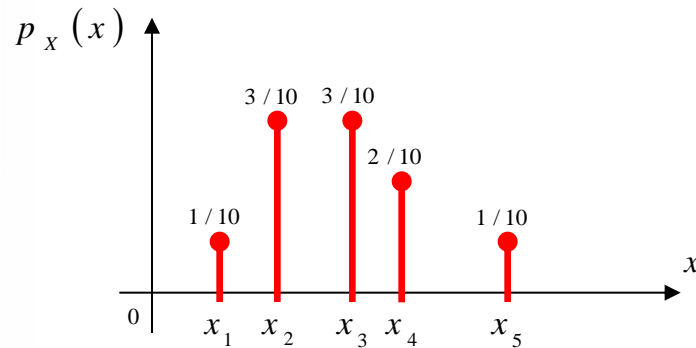
f_X = *probability density function*

$$\forall x, f_X(x) \geq 0$$

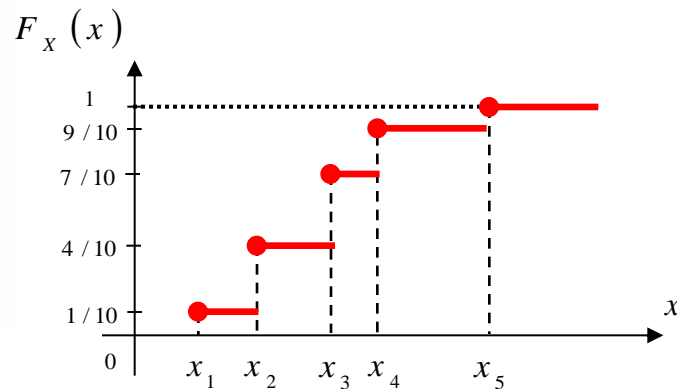
$$\int_{x \in \mathbb{X}} f_X(x) dx = 1$$

Random variables

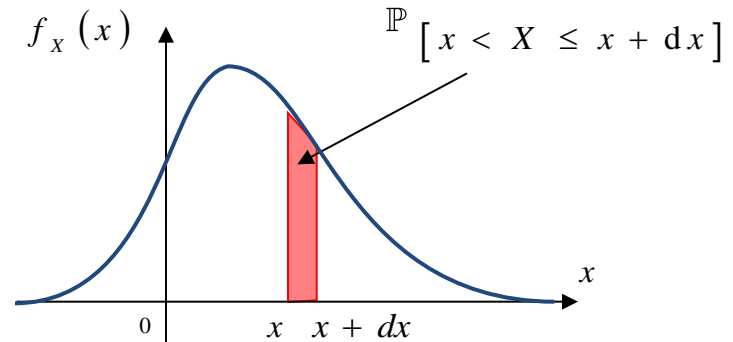
Discrete random variable



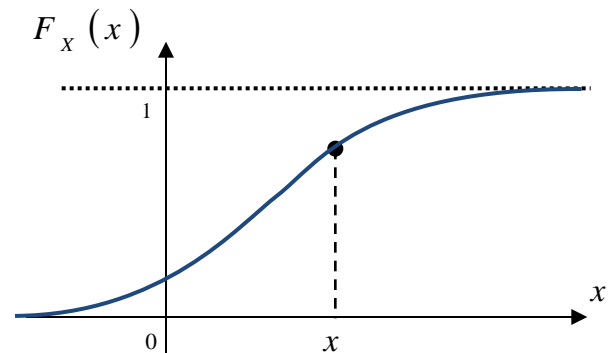
$$F_X(x) = \mathbb{P}[X \leq x] = \sum_{x \leq x_i} p_X(x_i)$$



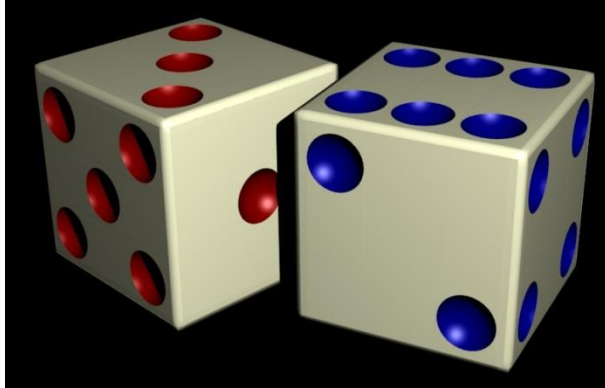
Continuous random variable



$$F_X(x) = \mathbb{P}[X \leq x] = \int_{-\infty}^x f_X(x) dx$$

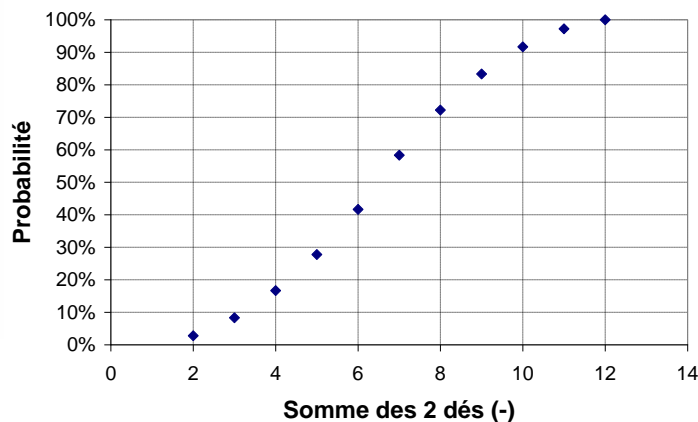


Random variables



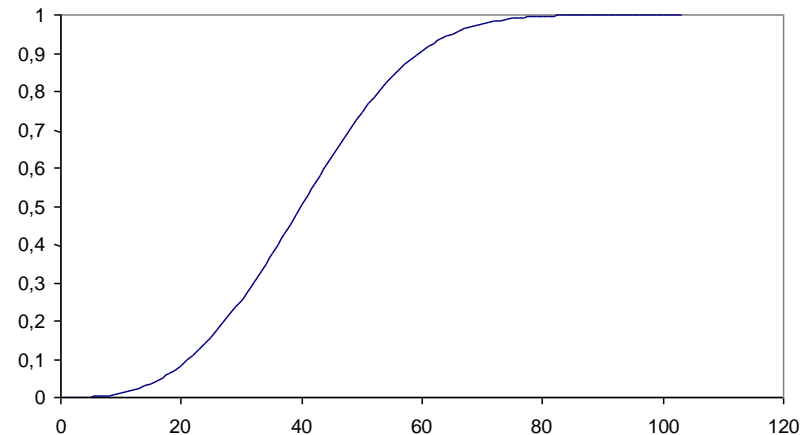
Discrete variable

Sum of 2 dices: $\Omega \rightarrow \{2, \dots, 12\}$



Continuous variable

Wind speed: $\Omega \rightarrow \mathbb{R}^+$



Random variables

☐ Sum of 2 independent random variables

Given two independent continuous random variables X and Y , the sum S of the two variables is:

$$S = X + Y$$

The probability density function of the sum of the random variable S is the **convolution** of the two separate density functions of X and Y .

$$f_S = f_X * f_Y$$

Where the convolution is defined as:

$$f_S(y) = \int f_X(x) f_Y(x - y) dx$$

The convolution is **commutative**:

$$f_X * f_Y = f_Y * f_X$$

Random variables

☐ Theorem of « composition of laws »

Let X be a *continuous random variable* and φ a *continuously differentiable strictly monotonic function*. The random variable $Y = \varphi(X)$ has a probability density function:

$$f_Y(y) = f_X(x) \left| \frac{dx}{dy} \right|$$

• Proof:

Case of strictly increasing function:

From the rules on inequalities: $X \leq x \Rightarrow \varphi(X) \leq \varphi(x) \Rightarrow Y \leq y$

Thus : $\mathbb{P}[Y \leq y] = \mathbb{P}[X \leq x] \Leftrightarrow F_Y(y) = F_X(x)$

By derivating according to y :

$$\frac{dF_Y(y)}{dy} = \frac{dF_X(x)}{dy} \Leftrightarrow f_Y(y) = \frac{dF_X(x)}{dx} \frac{dx}{dy} = f_X(x) \frac{dx}{dy}$$

Case of strictly decreasing function:

From the rules on inequalities: $X > x \Rightarrow \varphi(X) \leq \varphi(x) \Rightarrow Y \leq y$

Thus : $\mathbb{P}[Y \leq y] = \mathbb{P}[X > x] \Leftrightarrow F_Y(y) = 1 - F_X(x)$

By derivating according to y :

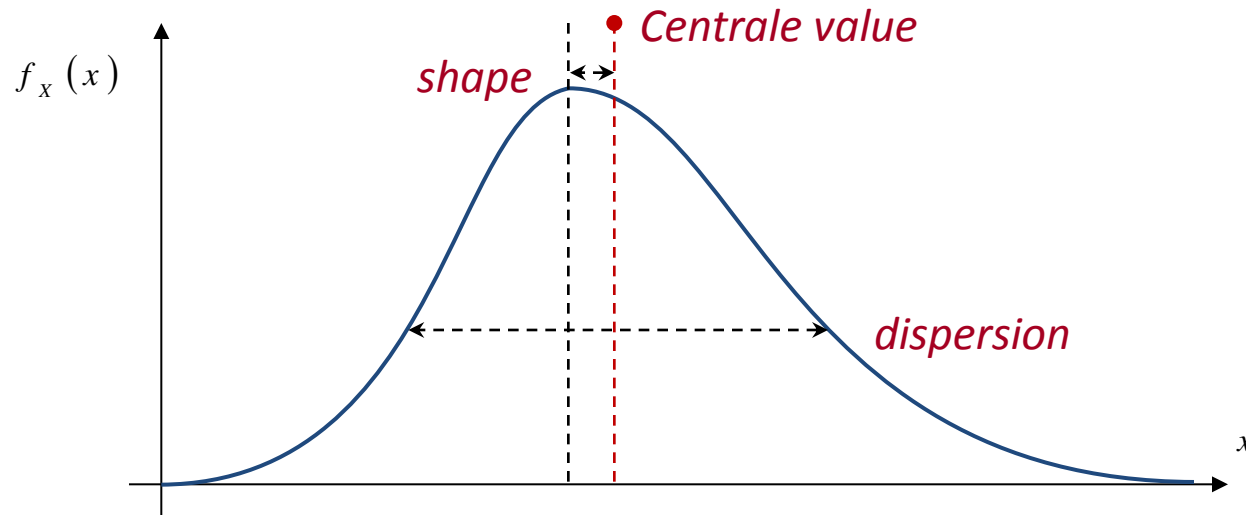
$$\frac{dF_Y(y)}{dy} = - \frac{dF_X(x)}{dy} \Leftrightarrow f_Y(y) = - \frac{dF_X(x)}{dx} \frac{dx}{dy} = - f_X(x) \frac{dx}{dy}$$

Random variables

Characterization of a random variable

A probability distribution is characterized by a number of features:

- Its *central value*
- its *dispersion*
- its *shape* (asymmetry, shift, etc.)



Generally, one will define *statistical moments* to characterize some features related to a random variable's probability distribution.

Random variables

Expected value (definition)

To define the statistical moments, one introduces the « *expectation* » operator denoted \mathbb{E} for a random variable (under some conditions).

Case of *discrete random variables*:

$$\mathbb{E}[X] = \sum_{x_i} x_i p_X(x_i)$$

(if the sum converges)

Case of *continuous random variables*:

$$\mathbb{E}[X] = \int_{x \in \mathbb{X}} x f_X(x) dx$$

(if the integral converges)

Random variables

Expected value (properties)

Given X and Y , two random variables and a and b two reals.

- The expected value operator is *linear*:

$$\mathbb{E}[aX + bY] = a\mathbb{E}[X] + b\mathbb{E}[Y]$$

- Caution, *in the general case*:

$$\mathbb{E}[XY] \neq \mathbb{E}[X]\mathbb{E}[Y]$$

- The equality is true only if X and Y are *independent*.

Statistical moments (centered) (normed) of order $r > 0$

$$\mu_X^r = \mathbb{E}[X^r]$$

$$\mu_{X \text{ centered}}^r = \mathbb{E}[(X - \mu_X)^r]$$

$$\mu_{X \text{ centered normed}}^r = \mathbb{E}\left[\frac{(X - \mu_X)^r}{\sigma_X^r}\right]$$

Random variables

First statistical moment (mean)

The *mean* refers to one measure of the central tendency of a probability distribution. It informs about the *location* of the probability distribution and it is defined as:

$$\mu_X = \mathbb{E}[X^1] = \mathbb{E}[X]$$

Second central moment (variance)

The variance is the second indicator of the central tendency, it sums up the *variability* of the probability distribution, the variance is given by:

$$\sigma_X^2 = \text{Var} [X] = \mathbb{E}[(X - \mu_X)^2] \quad (\text{if it exists})$$

A random variable with a finite variance is a variable of the *second order* (counter-example : The Cauchy distribution).

An other indicator of dispersion is the coefficient of variation :

$$\text{c.o.v.} = \frac{\sigma_X}{|\mu_X|}, \quad \mu_X \neq 0$$

(σ_X is the *standard deviation* , homogeneous to X and μ_X)

Random variables

⌚ Properties of variance

The variance is obviously *non linear* but:

$$\text{Var}[aX + b] = a^2 \text{Var}[X]$$

$$\text{Var}[X + Y] = \text{var}[X] + \text{Var}[Y] + 2\underbrace{\mathbb{E}[(X - \mu_X)(Y - \mu_Y)]}_{\text{Cov}[X, Y]}$$

An other important relation (for hand calculations), is the *König-Huyghens formula* :

$$\begin{aligned}\text{Var}[X] &= \mathbb{E}[X^2] - \mathbb{E}[X]^2 \\ &= \mathbb{E}[X^2] - \mu_X^2\end{aligned}$$

It allows in particular to show that if X and Y are *independents* :

$$\text{Var}[XY] = \text{Var}[X] \text{Var}[Y] + \text{Var}[X] \mathbb{E}[Y]^2 + \text{Var}[Y] \mathbb{E}[X]^2$$

Random variables

☐ The normalized 3rd central moment (skewness)

The *skewness* is a shape indicator, it measures the (a)symmetry of the distribution:

$$\delta_X = \mathbb{E} \left[\frac{(X - \mu_X)^3}{\sigma_X^3} \right]$$

A symmetric distribution has a zero skewness (example: the normal distribution).

☐ The normalized 3rd central moment (kurtosis)

The *kurtosis* is a shape indicator, measuring the flattening of the probability distribution:

$$\kappa_X = \mathbb{E} \left[\frac{(X - \mu_X)^4}{\sigma_X^4} \right]$$

It is generally compared to the kurtosis of the *normal distribution* ($\kappa_X = 3$) to know if the studied distribution is more or less flattened than the normal one.

Random variables

Quantiles

The *quantile at probability level α , denoted x_α* is determined by the inverse reading of the cumulative distribution function (strictly increasing)

$$F_x(x_\alpha) = \alpha \quad \Rightarrow \quad x_\alpha = F_x^{-1}(\alpha), \quad 0 \leq \alpha \leq 1$$

The *quantile function* is defined as *the inverse cumulative distribution function*.

The *median* is the 50% quantile. The *first* (resp. *third*) *quantile* is the 25% quantile (resp. 75%).

Confidence intervals

To sum up the variability of a random variable, one can use a confidence interval.

It is bounded by two quantiles *centered on the median*.

The *confidence interval at the probability level of $1 - \alpha$* is given by:

$$[x_{\alpha/2}; x_{1-\alpha/2}] = [F_x^{-1}(\alpha/2); F_x^{-1}(1-\alpha/2)], \quad 0 \leq \alpha \leq 1$$

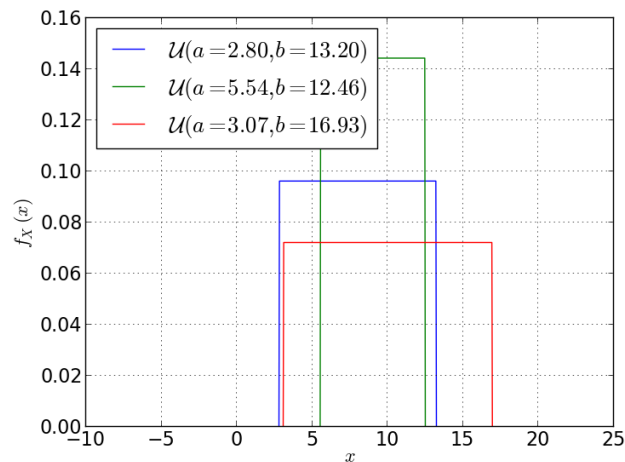
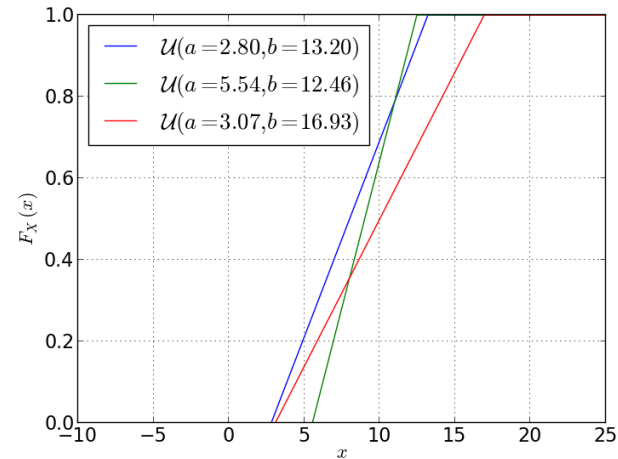
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Common probability distributions

Uniform distribution

$$X \sim \mathcal{U}(a, b) \text{ on } [a; b]$$



Cumulative distribution function

$$F(x) = \frac{x - a}{b - a}$$

Probability density function

$$f(x) = \frac{1}{b - a}$$

Mean

$$\frac{a + b}{2}$$

Variance

$$\frac{(b - a)^2}{12}$$

Skewness

$$0$$

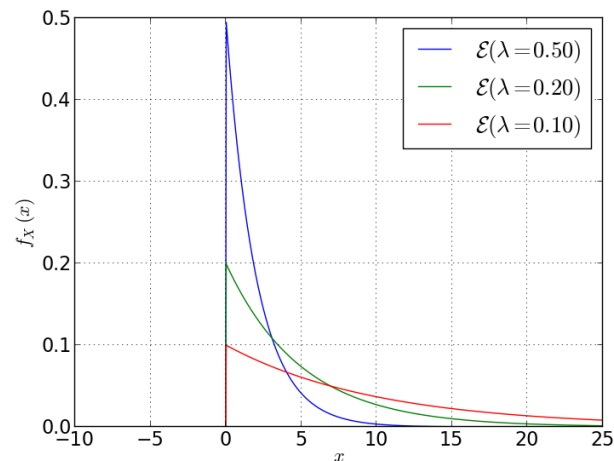
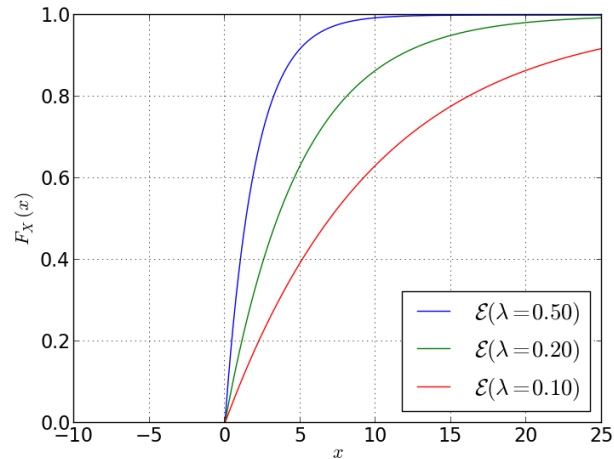
Kurtosis

$$1.8$$

Common probability distributions

Exponential distribution

$$X \sim \mathcal{E}(\lambda, \gamma) \text{ on } [\gamma; +\infty[$$



Cumulative distribution function

$$F(x) = 1 - \exp[-\lambda(x - \gamma)]$$

Probability density function

$$f(x) = \lambda \exp[-\lambda(x - \gamma)]$$

Mean

$$\frac{1}{\lambda} + \gamma$$

Variance

$$\frac{1}{\lambda^2}$$

Skewness

$$2$$

Kurtosis

$$9$$

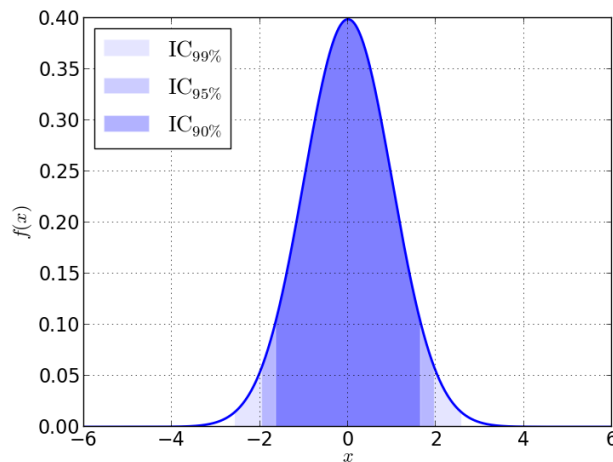
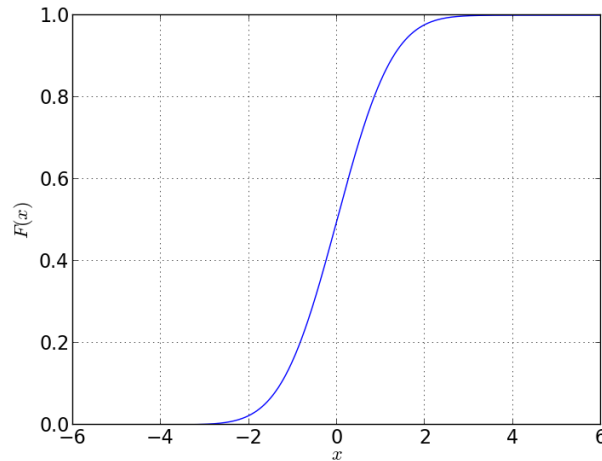
- The exponential distribution is used in reliability to model the lifetime of a phenomenon (*without aging*).
- Memoryless property:*

$$\mathbb{P}[X > a + b \mid X > a] = \mathbb{P}[X > b], \quad \forall a, b \geq \gamma$$

Common probability distributions

Standard normal distribution

$\Xi \sim \mathcal{N}(0,1)$ on \mathbb{R}



Cumulative distribution function

$$F(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{1}{2}s^2} ds = \Phi(x)$$

Probability density function

$$f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2} = \varphi(x)$$

Mean

0

Variance

1

Skewness

0

Kurtosis

3

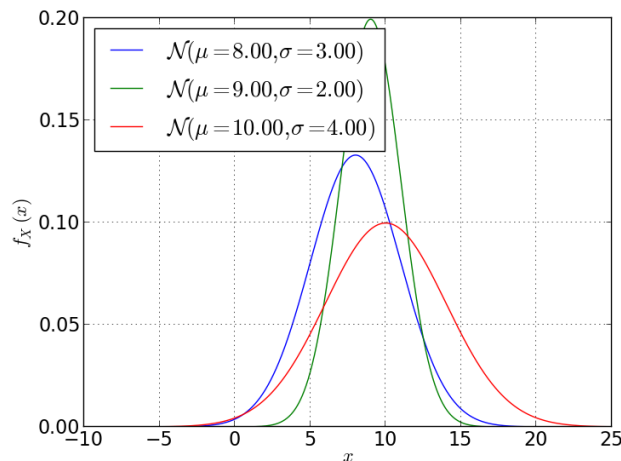
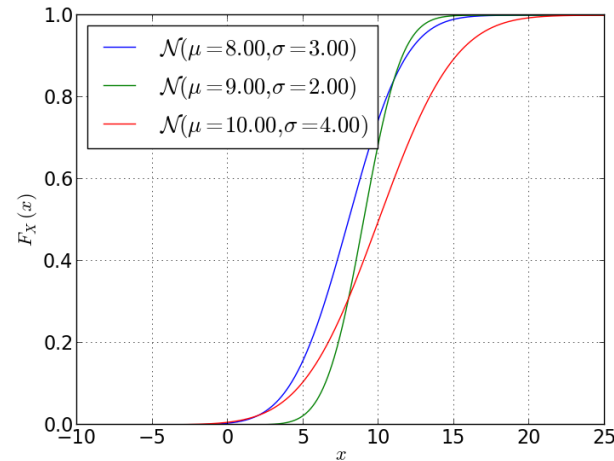
Characteristic values:

- CI 99% = [-2,58 ; 2,58]
- CI 95% = [-1,96 ; 1,96]
- CI 90% = [-1,64 ; 1,64]

Common probability distributions

Normal distribution

$$\Xi \sim \mathcal{N}(\mu, \sigma) \text{ on } \mathbb{R}$$



Cumulative distribution function

$$F(x) = \frac{1}{\sigma \sqrt{2\pi}} \int_{-\infty}^x e^{-\frac{1}{2}\left(\frac{s-\mu}{\sigma}\right)^2} ds = \Phi\left(\frac{x-\mu}{\sigma}\right)$$

Probability density function

$$f(x) = \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2} = \frac{1}{\sigma} \varphi\left(\frac{x-\mu}{\sigma}\right)$$

Mean

$$\mu$$

Variance

$$\sigma^2$$

Skewness

$$0$$

Kurtosis

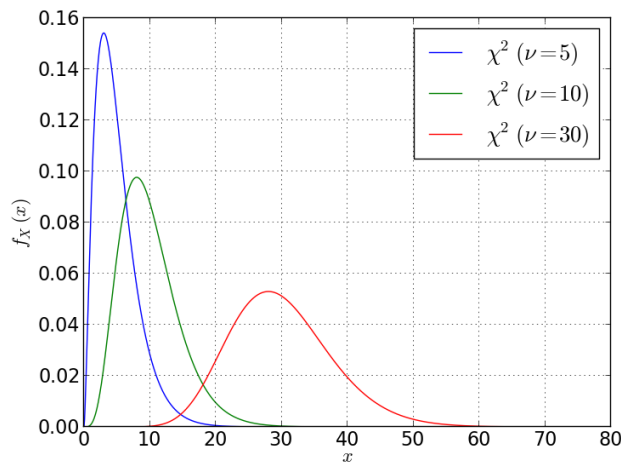
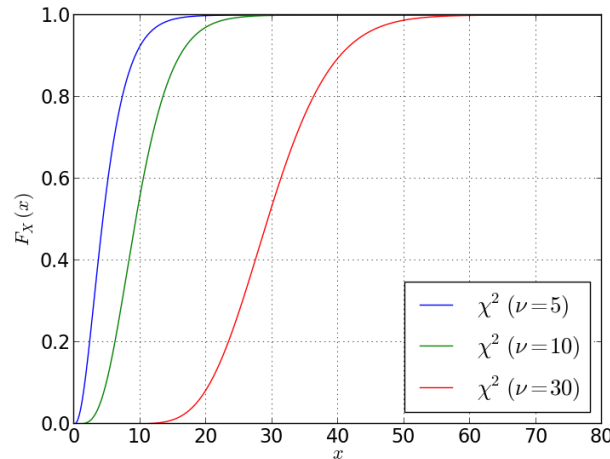
$$3$$

- The **sum** of independent normal variables is **normal**.
- The mode (unique), the median and the mean coincide.

Common probability distributions

Chi-square distribution (χ^2)

$$X \sim \chi^2(\nu) \text{ on } \mathbb{R}^+$$



Cumulative distribution function

$$F(x) = \frac{\gamma(\nu/2, x/2)}{\Gamma(\nu/2)}$$

Probability density function

$$f(x) = \frac{2^{-\nu/2}}{\Gamma(\nu/2)} x^{\nu/2-1} \exp\left(-\frac{x}{2}\right)$$

Mean

$$\nu$$

Variance

$$2\nu$$

Skewness

$$\sqrt{\frac{8}{\nu}}$$

Kurtosis

$$\frac{12}{\nu}$$

where $\Gamma(a) = \int_0^{\infty} t^{a-1} e^{-t} dt$ is the **Gamma function**,

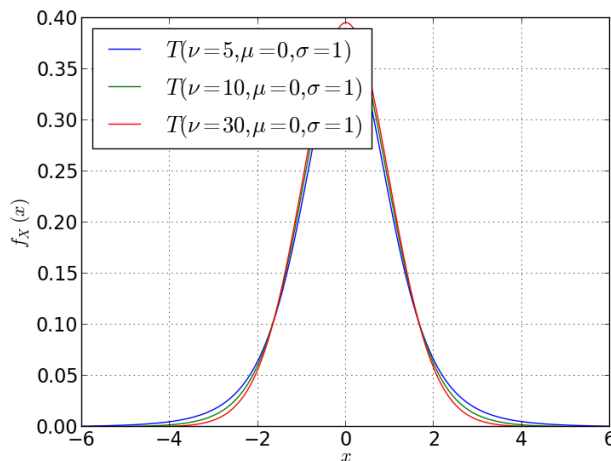
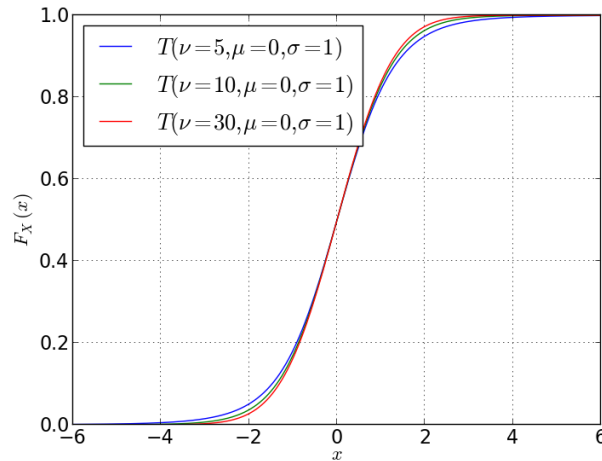
and $\gamma(a, x) = \int_0^x t^{a-1} e^{-t} dt$ is the incomplete **Gamma function**.

- The quadratic sum of ν **independent standard normal variables** follows a Chi-square distribution with ν d.d.f.

Common probability distributions

Student distribution

$$X \sim T(\nu, \mu, \sigma) \text{ on } \mathbb{R}$$



Cumulative distribution function

$$F(x) = F_{\text{Student}}\left(\nu, \frac{x - \mu}{\sigma}\right)$$

Probability density function

$$f(x) = \frac{1}{\sigma \sqrt{\nu \pi}} \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{(x - \mu)^2}{\nu \sigma^2}\right)^{-\frac{\nu+1}{2}}$$

Mean ($1 < \nu$)

$$\mu$$

Variance ($2 < \nu$)

$$\frac{\nu}{\nu - 2} \sigma^2$$

Skewness ($3 < \nu$)

$$0$$

Kurtosis ($4 < \nu$)

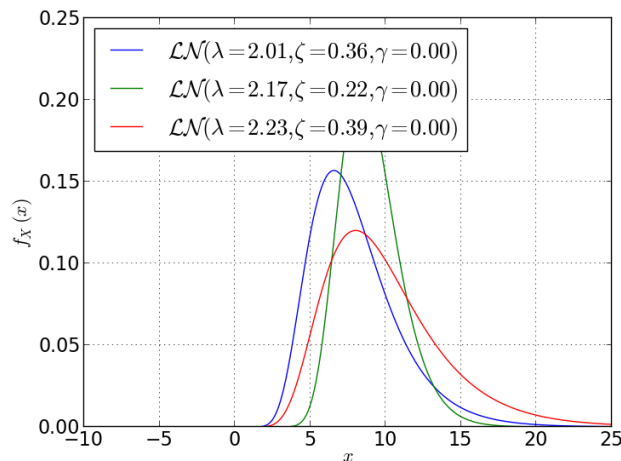
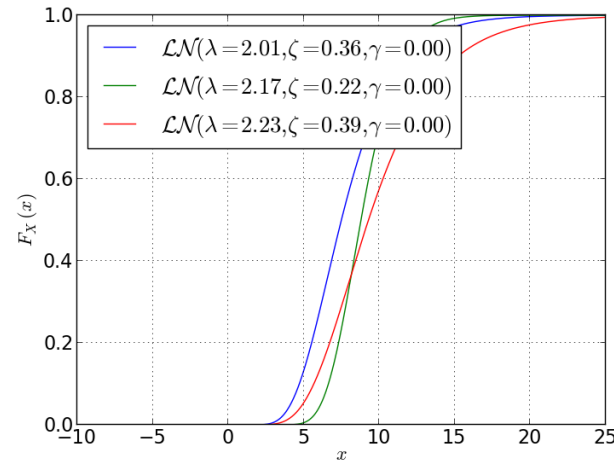
$$\frac{6}{\nu - 4} + 3$$

- By **definition**, if $Z \sim N(\mu, \sigma)$ and $U \sim \chi^2(\nu)$ are independent then $X = Z / \sqrt{U/\nu} \sim T(\nu, \mu, \sigma)$
- The **Student distribution tends to the normal distribution** when ν tends to the infinity (a.s.a. $\nu \geq 30$).
- The mean of a ν -sample **following a normal distribution** follows a Student distribution with ν d.d.f.

Common probability distributions

Lognormal distribution

$$X \sim \mathcal{LN}(\lambda, \zeta, \gamma) \text{ on } [\gamma; +\infty[$$



Cumulative distribution function

$$F(x) = \Phi\left(\frac{\ln(x - \gamma) - \lambda}{\zeta}\right)$$

Probability density function

$$f(x) = \frac{1}{\zeta \sqrt{2\pi} (x - \gamma)} e^{-\frac{1}{2} \left(\frac{\ln(x - \gamma) - \lambda}{\zeta} \right)^2}$$

Mean

$$\exp\left(\lambda + \frac{\zeta^2}{2}\right) + \gamma$$

Variance

$$(\mu - \gamma)^2 (\exp(\zeta^2) - 1)$$

Skewness

$$\sqrt{\exp(\zeta^2) - 1} (\exp(\zeta^2) - 2)$$

Kurtosis

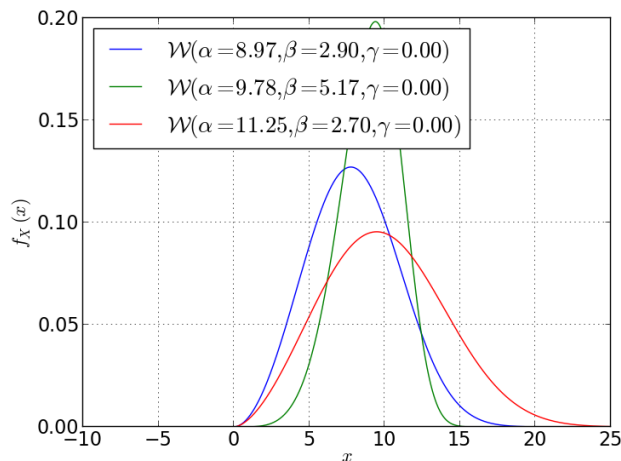
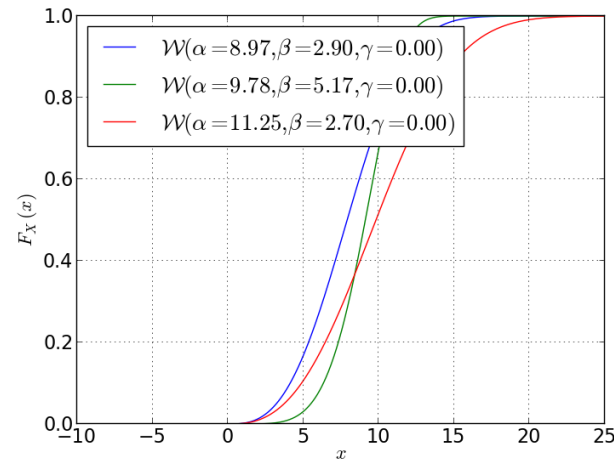
$$\exp(4\zeta^2) + 2\exp(3\zeta^2) + 3\exp(2\zeta^2) - 3$$

- By *definition*, the *logarithm* of a lognormal variable is *normal*.
- The *product* of independent lognormal variables is *lognormal*.
- The *inverse* of a lognormal variable is *lognormal*.

Common probability distributions

Weibull distribution

$$X \sim \mathcal{W}(k, \lambda, \gamma) \text{ sur } [\gamma; +\infty[$$



Cumulative distribution function

$$F(x) = 1 - \exp \left[- \left(\frac{x - \gamma}{\lambda} \right)^k \right]$$

Probability density function

$$f(x) = \left(\frac{k}{\lambda} \right) \left(\frac{x - \gamma}{\lambda} \right)^{k-1} \exp \left[- \left(\frac{x - \gamma}{\lambda} \right)^k \right]$$

Mean

$$\lambda \Gamma \left(1 + \frac{1}{k} \right) + \gamma$$

Variance

$$\lambda^2 \left(\Gamma \left(1 + \frac{2}{k} \right) - \mu^2 \right)$$

Skewness

$$\frac{1}{\sigma^3} \left(\lambda^3 \Gamma \left(1 + \frac{3}{k} \right) - 3 \mu \sigma^2 - \mu^3 \right)$$

Kurtosis

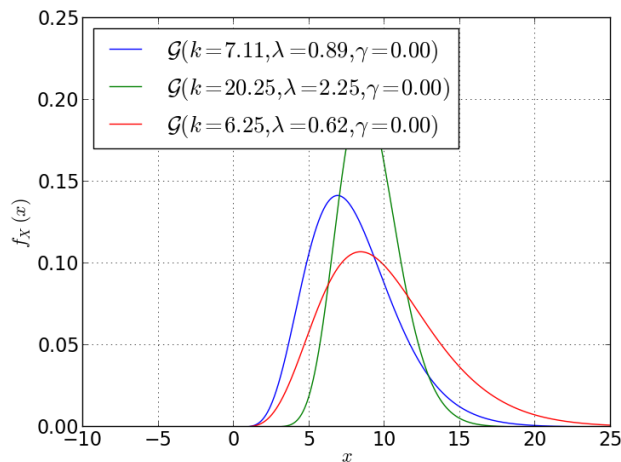
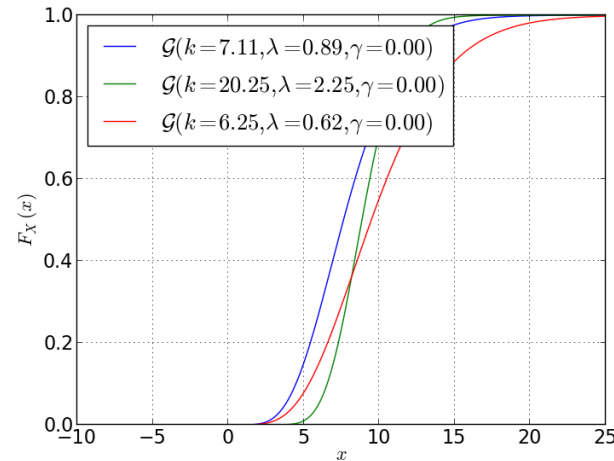
$$\frac{1}{\sigma^4} \left(\lambda^4 \Gamma \left(1 + \frac{4}{k} \right) - 4 \delta \mu \sigma^3 - 6 \mu^2 \sigma^2 - \mu^4 \right)$$

- The Weibull distribution is used in reliability to model the *lifetime of a phenomenon (with aging)* :
 - $k < 1$: « infant mortality »
 - $k = 1$: no aging(exp. distrib.)
 - $k > 1$: « aging process »

Common probability distributions

Gamma distribution

$$X \sim \mathcal{G}(\lambda, k, \gamma) \text{ on } [\gamma; +\infty[$$



Cumulative distribution function

$$F(x) = \frac{\gamma(k, \lambda x)}{\Gamma(k)}$$

Probability density function

$$f(x) = \frac{\lambda}{\Gamma(k)} (\lambda(x - \gamma))^{k-1} \exp[-\lambda(x - \gamma)]$$

Mean

$$\frac{k}{\lambda}$$

Variance

$$\frac{k}{\lambda^2}$$

Skewness

$$\frac{2}{\sqrt{k}}$$

Kurtosis

$$\frac{3(k+2)}{k}$$

Where $\Gamma(a) = \int_0^{\infty} t^{a-1} e^{-t} dt$ is the **Gamma function**,

And $\gamma(a, x) = \int_0^x t^{a-1} e^{-t} dt$ is the **incomplete Gamma**.

Outline

- General definitions
 - Random experiment – Event
 - Measurable space
 - Kolmogorov axioms
 - Bayes' theorem
- Random variables
 - Definitions
 - Cumulative distribution function (CDF) and probability density function (PDF)
 - Discrete / continuous random variables
 - Statistical moments
 - Confidence intervals (CI)
- Some common continuous distributions
- Random vectors
 - Definitions
 - Moments
 - Copulas

Random vectors

Definition

A random vector is a *measurable function*:

$$\begin{aligned} \mathbf{X} : \Omega &\rightarrow \mathbb{X} \subseteq \mathbb{R}^n \\ \omega &\mapsto \mathbf{x} = \mathbf{X}(\omega) = (X_1(\omega), \dots, X_n(\omega))^t \end{aligned}$$

Where the dimension n of the support space \mathbb{X} is larger than 1.

It is a *multi-dimensional random variable*.

It is defined by:

- *Its joint cumulative distribution function:*
- *Its joint probability density function:*

$$F_{\mathbf{X}}(\mathbf{x}) = \mathbb{P} \left[\bigcap_{i=1}^n X_i \leq x_i \right]$$

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{\mathbb{P}[\bigcap_{i=1}^n x_i \leq X_i \leq x_i + dx_i]}{\prod_{i=1}^n dx_i} = \frac{\partial F_{\mathbf{X}}(\mathbf{x})}{\partial x_1 \dots \partial x_n}$$

Random vectors

Complementary definitions

- The *marginal* probability density function is the probability density function of a *sub-vector* of \mathbf{X} .

If $\mathbf{X} = (\mathbf{X}_1, \mathbf{X}_2)^t$, the marginal density of \mathbf{X}_1 (in \mathbf{X}) is given by:

$$f_{\mathbf{X}_1}(\mathbf{x}_1) = \int_{\mathbf{x}_2 \in \mathbb{X}_2} f_{\mathbf{X}}(\mathbf{x}_1, \mathbf{x}_2) d\mathbf{x}_2$$

- The *conditional density function* is the probability density function of the sub-vector of \mathbf{X} given the occurrence value of the *complementary sub-vector*.

If $\mathbf{X} = (\mathbf{X}_1, \mathbf{X}_2)^t$ the conditional probability density function of \mathbf{X}_1 given $\mathbf{x}_2 = \mathbf{a}$ is:

$$f_{\mathbf{X}_1|\mathbf{X}_2}(\mathbf{x}_1 | \mathbf{x}_2 = \mathbf{a}) = \frac{f_{\mathbf{X}}(\mathbf{x}_1, \mathbf{a})}{\int_{\mathbf{x}_1 \in \mathbb{X}_1} f_{\mathbf{X}}(\mathbf{x}_1, \mathbf{a}) d\mathbf{x}_1} = \frac{f_{\mathbf{X}}(\mathbf{x}_1, \mathbf{a})}{f_{\mathbf{X}_2}(\mathbf{a})}$$

According to the *Bayes theorem*.

The associate cumulative distribution functions are obtained thanks to their definition (*i.e.* by integration).

Random vectors

Statistical moments

By definition, the *expected value* of a random vector is the vector of expected values of random variables that compose it :

$$\mathbb{E}[\mathbf{X}] = (\mathbb{E}[X_i], i = 1, \dots, n)^t$$

Its property of *linearity* holds.

The *covariance matrix* is the matrix whose element in the i, j position is:

$$\sigma_{ij} = \text{Cov}[X_i, X_j] = \mathbb{E}[(X_i - \mu_{X_i})(X_j - \mu_{X_j})], \quad i, j = 1, \dots, n$$

Thus the *variance of the components* are found *on the diagonal* ($\sigma_{ii} = \sigma_i^2$).

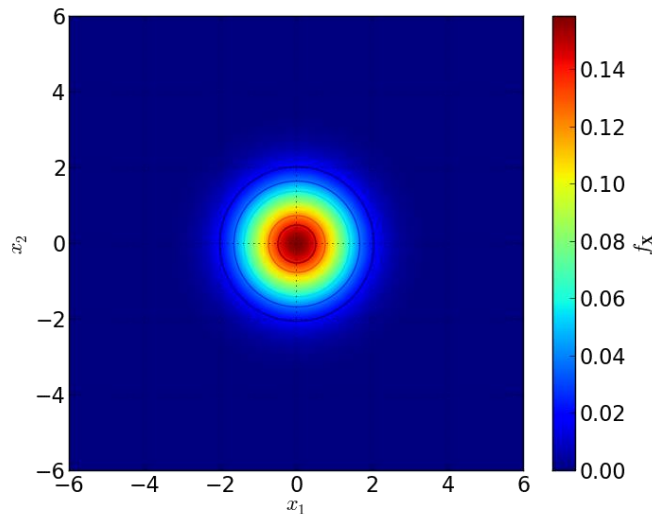
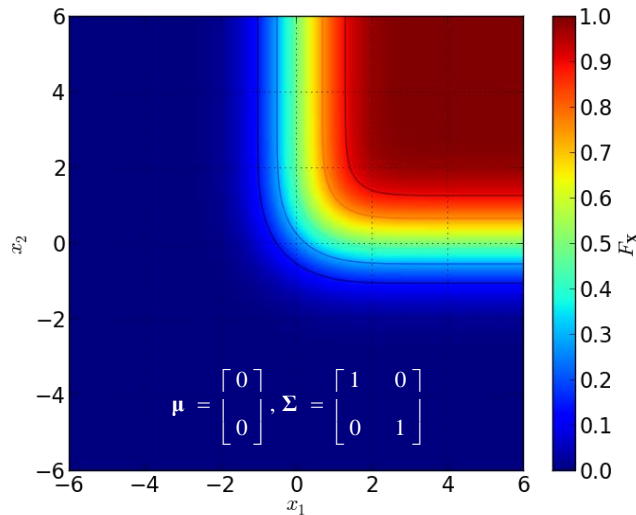
One defines as well the linear *correlation matrix* whose the i - j element is given by:

$$\rho_{ij} = \frac{\text{Cov}[X_i, X_j]}{\sqrt{\text{Var}[X_i] \text{Var}[X_j]}} = \frac{\sigma_{ij}}{\sigma_i \sigma_j}, \quad i, j = 1, \dots, n$$

Random vectors

☐ Multivariate normal distribution

$$\mathbf{X} \sim \mathcal{N}_n(\boldsymbol{\mu}, \boldsymbol{\Sigma}) \text{ on } \mathbb{R}^n$$



CDF

$$\Phi_n(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

PDF

$$\varphi_n(\mathbf{x}; \boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{\exp\left[-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right]}{\det(\boldsymbol{\Sigma})^{1/2} (2\pi)^{n/2}}$$

Mean

$$\boldsymbol{\mu}$$

Covariance

$$\boldsymbol{\Sigma}$$

By definition, if $\boldsymbol{\Xi}$ is a vector of n independent standard normal random, if \mathbf{L} is solution of $\boldsymbol{\Sigma} = \mathbf{L} \mathbf{L}^T$ (symmetric squared matrix of size n) and $\boldsymbol{\mu}$ is a vector of size n , then:

$$\mathbf{X} = \mathbf{L} \boldsymbol{\Xi} + \boldsymbol{\mu} \sim \mathcal{N}_n(\boldsymbol{\mu}, \boldsymbol{\Sigma})$$

Consequently, any linear combination of Gaussian vectors is Gaussian.

Random vectors

☐ Multivariate normal distribution

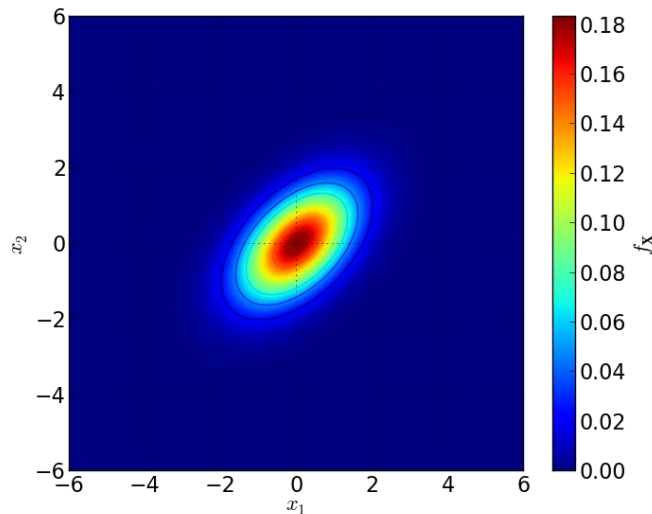
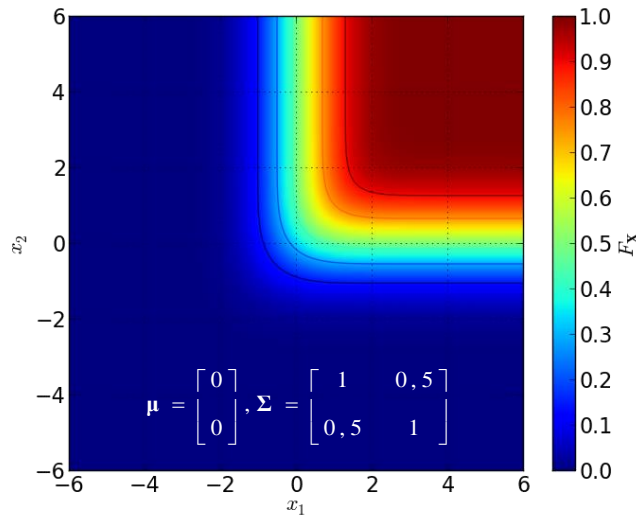
$$\mathbf{X} \sim \mathcal{N}_n(\boldsymbol{\mu}, \boldsymbol{\Sigma}) \text{ on } \mathbb{R}^n$$

Let \mathbf{X} be a Gaussian vector defined as :

$$\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \sim \mathcal{N}_n \left(\begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix}, \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{12}^T & \boldsymbol{\Sigma}_{22} \end{bmatrix} \right)$$

The sub-vector \mathbf{X}_1 (as \mathbf{X}_2) is also Gaussian and it is enough to forget the crossed terms of covariance matrix:

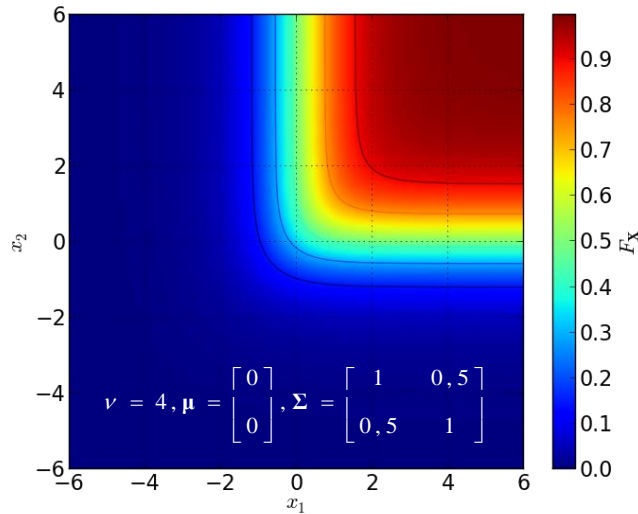
$$\mathbf{X}_1 \sim \mathcal{N}_{n_1}(\boldsymbol{\mu}_1, \boldsymbol{\Sigma}_{11})$$



Random vectors

☐ Multivariate Student distribution

$$\mathbf{X} \sim T_n(\nu, \boldsymbol{\mu}, \boldsymbol{\Sigma}) \text{ on } \mathbb{R}^n$$



CDF

$$F_n(\mathbf{x}; \nu, \boldsymbol{\mu}, \boldsymbol{\Sigma})$$

PDF

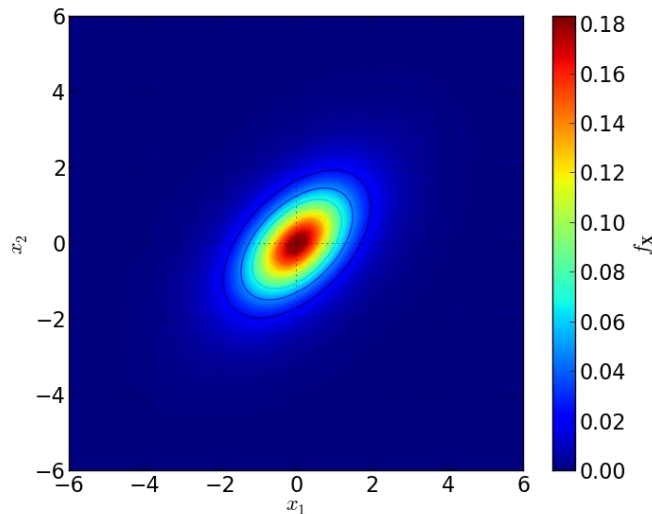
$$\frac{\Gamma\left(\frac{\nu+n}{2}\right)}{\Gamma\left(\frac{\nu}{2}\right)} \frac{\left(1 + \frac{1}{\nu}(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu})\right)^{-\frac{\nu+n}{2}}}{\det(\boldsymbol{\Sigma})^{1/2} (\nu\pi)^{n/2}}$$

Mean($\nu > 1$)

$$\boldsymbol{\mu}$$

Covariance ($\nu > 2$)

$$\frac{\nu}{\nu - 2} \boldsymbol{\Sigma}$$



Random vectors

Copulas

A *copula* (denoted C) is a joint cumulative distribution function defined on the unit cube $[0 ; 1]$ with uniform variables (*marginal*). See Sklar's theorem for more details.

Let \mathbf{X} be a random vector of size n , with multivariate cumulative distribution function $F_{\mathbf{X}}$, and with marginal cumulative distribution functions $(F_{X_i}, i = 1, \dots, n)$.

There is a copula C of size n such that:

$$F_{\mathbf{X}}(\mathbf{x}) = C\left(F_{X_1}(x_1), \dots, F_{X_n}(x_n)\right), \quad \mathbf{x} \in \mathbb{X}$$

If \mathbf{X} is a *continuous random vector*, then the copula is *unique*. If \mathbf{X} is *discrete*, the copula is *defined uniquely on the support* \mathbb{X} .

The *copula* is what is remained of a random vector, once the effects of the marginal distributions are removed.
It is the *stochastic dependence structure*.

Random vectors

Ⓢ Synthesis

- A random vector can be defined directly from its *joint distribution* (e.g. the multivariate normal distribution).
- Or, one can define it from a *collection of marginal distributions* and a *stochastic dependence structure* expressed as a copula.
- The copulas formalism allows also to simply express the joint probability density function from its definition:

$$\begin{aligned} f_{\mathbf{x}}(\mathbf{x}) &= \frac{\partial F_{\mathbf{x}}(\mathbf{x})}{\partial x_1 \cdots \partial x_n} = \frac{\partial C(u_1, \cdots, u_n)}{\partial u_1 \cdots \partial u_n} \bigg|_{u_i = F_{x_i}(x_i)} \prod_{i=1}^n \frac{\partial F_{x_i}(x_i)}{\partial x_i} \\ &= c(F_{x_1}(x_1), \cdots, F_{x_n}(x_n)) \prod_{i=1}^n f_{x_i}(x_i) \end{aligned}$$

Where c is, by definition, the *density function of the copula* C .

Random vectors

Independent copula

$$n \geq 2$$

CDF

$$C(\mathbf{u}) = \prod_{i=1}^n u_i$$

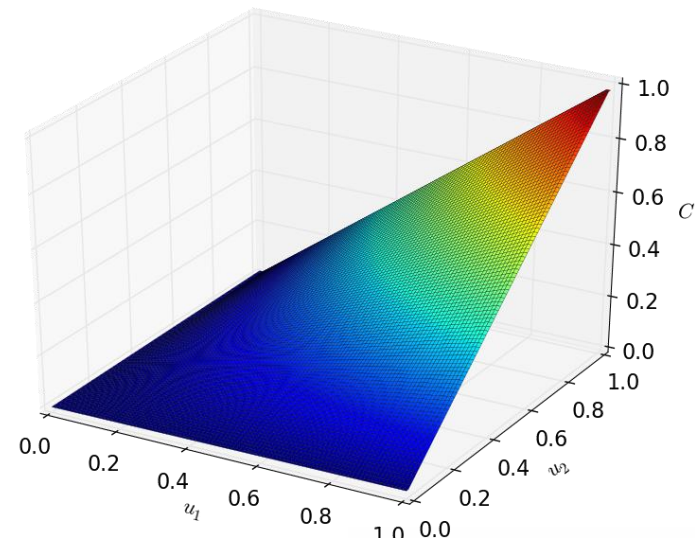
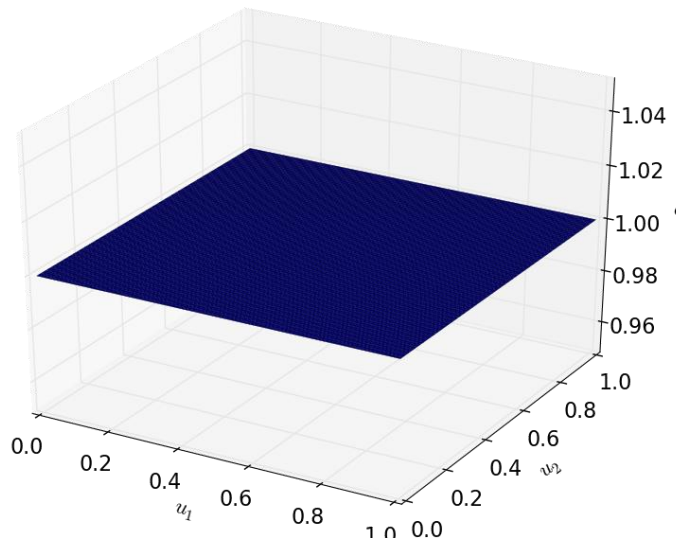
PDF

$$c(\mathbf{u}) = 1, \quad \mathbf{u} \in [0; 1]^n$$

Thus, the joint cumulative distribution function (resp. density) is reduced to the *product* of the marginal cumulative distribution functions (resp. density):

$$F_{\mathbf{x}}(\mathbf{x}) = \prod_{i=1}^n F_{x_i}(x_i)$$

$$f_{\mathbf{x}}(\mathbf{x}) = \prod_{i=1}^n f_{x_i}(x_i)$$



Random vectors

☐ Gaussian copula

$n \geq 2$

Family

Elliptic

CDF

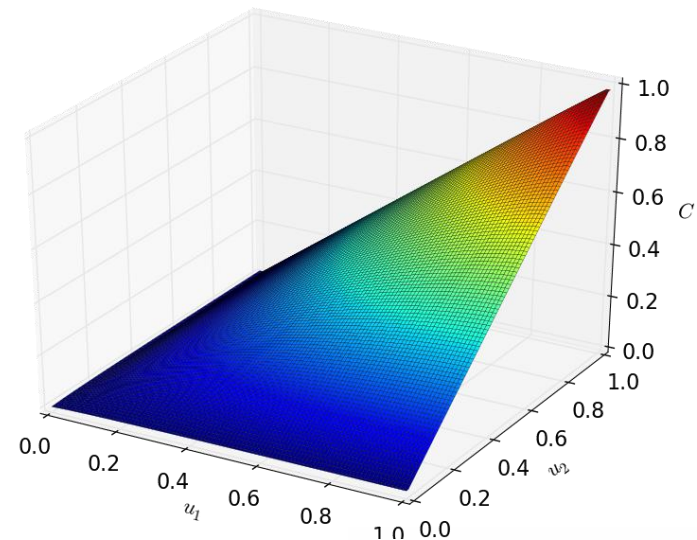
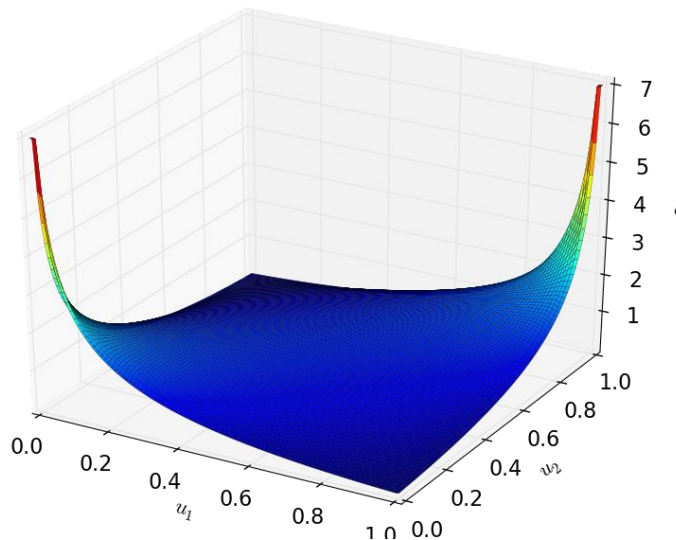
$$C(\mathbf{u}) = \Phi_n(\Phi^{-1}(u_1), \dots, \Phi^{-1}(u_n); \mathbf{R}_0)$$

PDF

$$c(\mathbf{u}) = \frac{\varphi_n(\Phi^{-1}(u_1), \dots, \Phi^{-1}(u_n); \mathbf{R}_0)}{\prod_{i=1}^n \varphi(\Phi^{-1}(u_i))}$$

Example: $\mathbf{R}_0 = \begin{bmatrix} 1 & 0,5 \\ 0,5 & 1 \end{bmatrix}$

\mathbf{R}_0 is not the linear correlation matrix!



Random vectors

Student copula

$$n \geq 2$$

Family

Elliptic

CDF

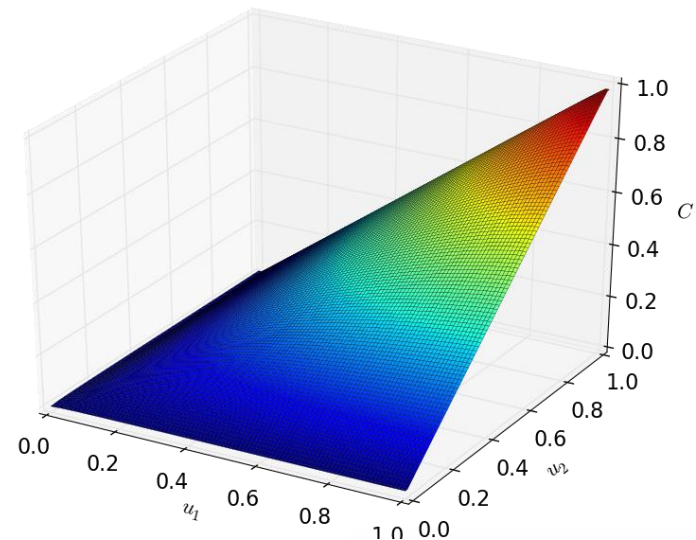
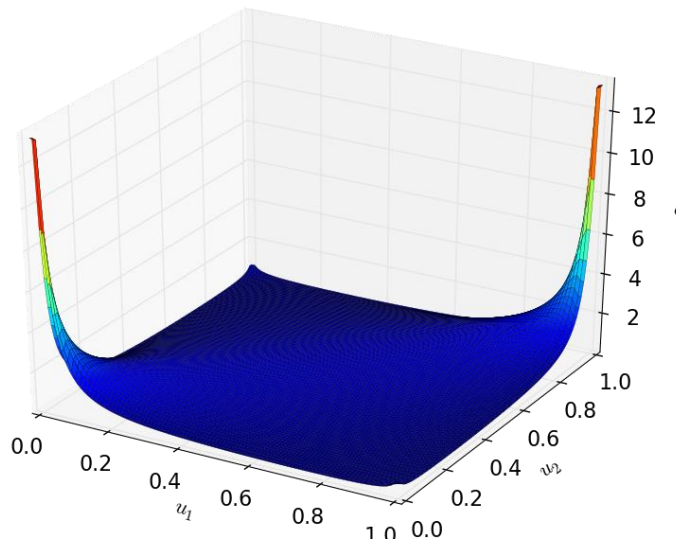
$$C(\mathbf{u}) = F_n(F^{-1}(u_1; \nu), \dots, F^{-1}(u_n; \nu); \mathbf{R}_0, \nu) \quad (\text{via th. Sklar})$$

PDF

$$c(\mathbf{u}) = \frac{f_n(F^{-1}(u_1; \nu), \dots, F^{-1}(u_n; \nu); \mathbf{R}_0, \nu)}{\prod_{i=1}^n f(F^{-1}(u_i; \nu); \nu)} \quad (\text{via th. Sklar})$$

Example: $\mathbf{R}_0 = \begin{bmatrix} 1 & 0,5 \\ 0,5 & 1 \end{bmatrix}, \nu = 4$

\mathbf{R}_0 is not the linear correlation matrix!



Random vectors

Clayton copula

$n = 2$

Family

Archimedean

CDF

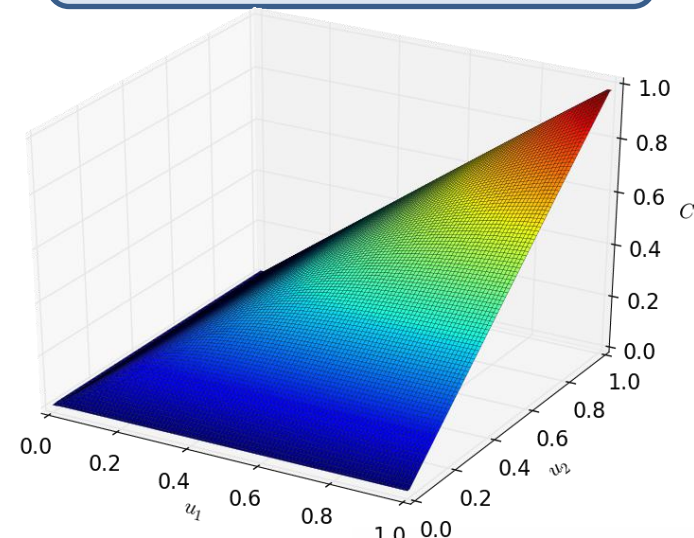
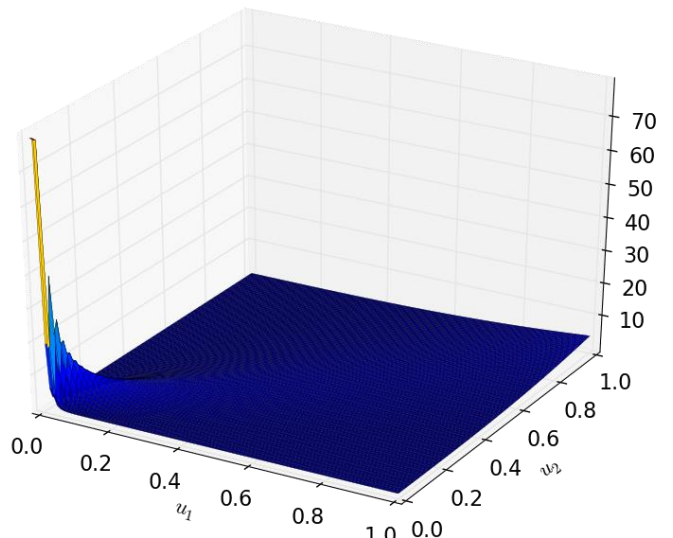
$$C(u_1, u_2) = (u_1^{-\theta} + u_2^{-\theta} - 1)^{-1/\theta}$$

PDF

$$c(u_1, u_2) = (\theta + 1)(u_1 u_2)^{-(\theta+1)} (u_1^{-\theta} + u_2^{-\theta} - 1)^{-1/\theta - 2}$$

Example: $\theta = 3$

Lower tail dependence



Random vectors

Gumbel copula

$n = 2$

Family

Archimedean

CDF

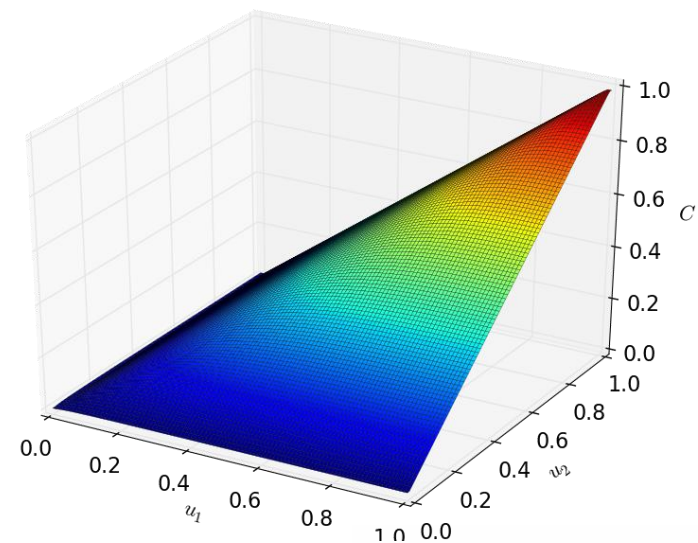
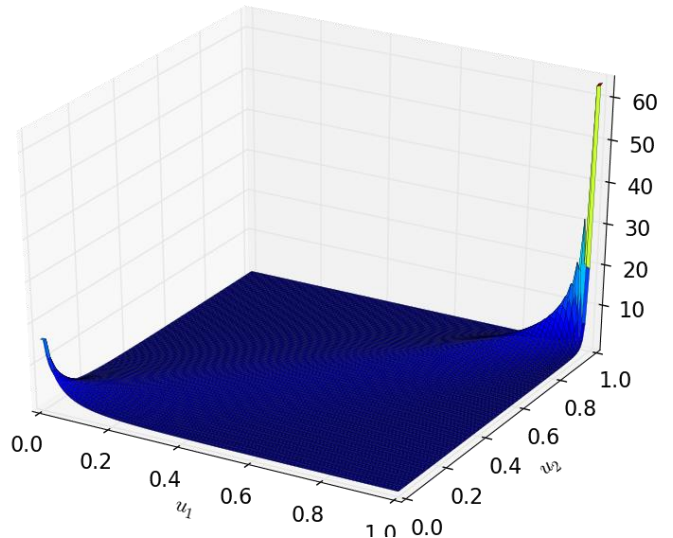
$$C(u_1, u_2) = \exp \left[- \left((-\ln u_1)^\theta + (-\ln u_2)^\theta \right)^{1/\theta} \right]$$

PDF

$$c(u_1, u_2) = C(u_1, u_2) \frac{(-\ln u_1)^{\theta-1} (-\ln u_2)^{\theta-1} \left((-\ln u_1)^\theta + (-\ln u_2)^\theta \right)^{1/\theta-2} (\theta - 1 - \ln C(u_1, u_2))}{u_1 u_2}$$

Example: $\theta = 3$

Upper tail dependence



Random vectors

Frank copula

$n = 2$

Family

Archimedean

CDF

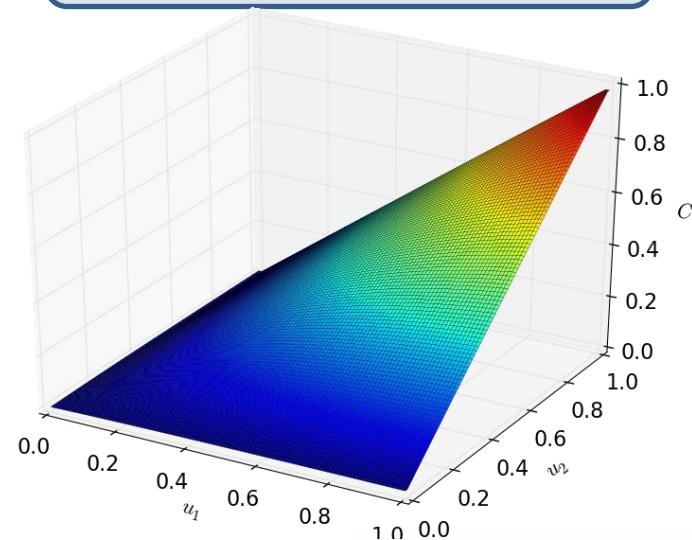
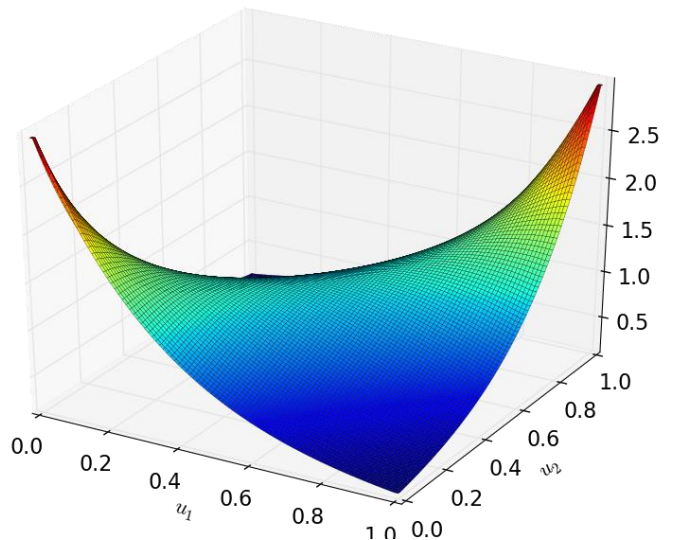
$$C(u_1, u_2) = -\frac{1}{\theta} \ln \left(1 + \frac{(e^{-\theta u_1} - 1)(e^{-\theta u_2} - 1)}{(e^{-\theta} - 1)} \right)$$

PDF

$$c(u_1, u_2) = \frac{\theta (1 - e^{-\theta}) e^{-\theta(u_1 + u_2)}}{\left[(1 - e^{-\theta}) - (e^{-\theta u_1} - 1)(e^{-\theta u_2} - 1) \right]^2}$$

Example: $\theta = 3$

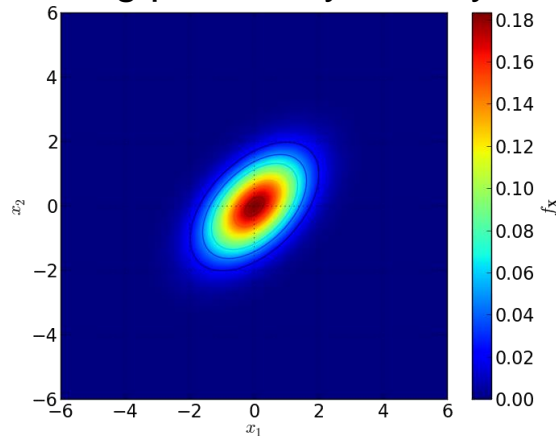
symmetric dependence



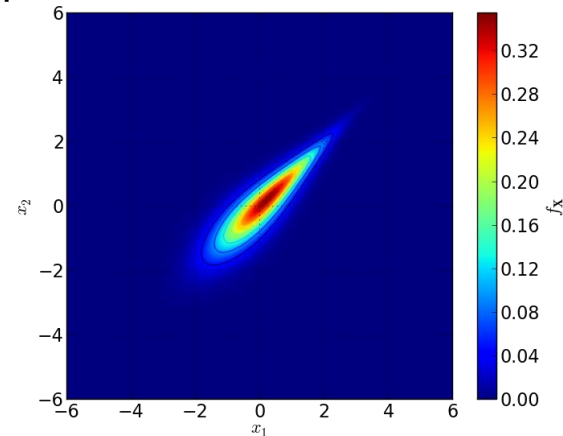
Random vectors

Examples of composed distributions $n = 2$

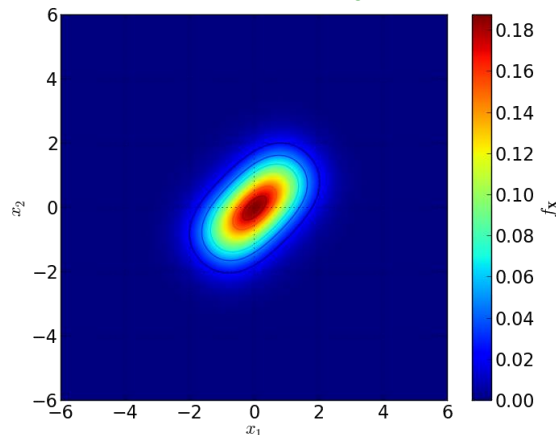
Two normal standard random variables are linked with different copulas and their corresponding probability density functions are plotted.



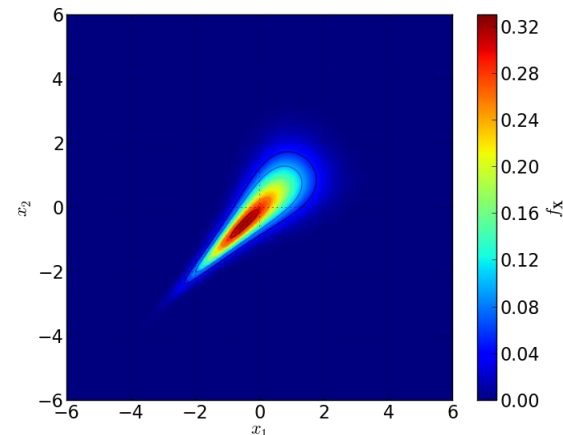
Gaussienne ($\rho_0 = 0,5$)



Gumbel ($\theta = 3$)



Frank ($\theta = 3$)



Clayton ($\theta = 3$)