

Matrice di Inerzia

Definiamo $P :=$ coordinate di un punto generico solidale al copro (\hat{P}):

$$\mathbb{I} = \rho \int_V S^T(P) S(P) \partial V \quad \text{con } V = \int_V \partial V, \rho = \frac{M}{V}$$

Ipotizziamo che il punto $P = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$ abbia x,y,z sui piani di simmetria del corpo. Allora:

$$S^T S = \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix}$$

Se la densità del corpo $\rho = \text{cost}$:

$$\mathbb{I} = \frac{M}{V} \iiint \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix} \partial x \partial y \partial z$$

In alternativa:

$$\mathbb{I} = \iiint \rho(x, y, z) \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix} \partial x \partial y \partial z$$

Parallelepipedo di lati A,B,C senza tappi

$$x \in \left[-\frac{A}{2}, \frac{A}{2} \right], y \in \left[-\frac{B}{2}, \frac{B}{2} \right], z \in \left[-\frac{C}{2}, \frac{C}{2} \right]$$

$$\mathbb{I} = \frac{M}{V} \iiint \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix} \partial x \partial y \partial z$$

$$x^2 \longrightarrow \int_{-\frac{C}{2}}^{\frac{C}{2}} \int_{-\frac{B}{2}}^{\frac{B}{2}} \int_{-\frac{A}{2}}^{\frac{A}{2}} x^2 \partial x \partial y \partial z = \int_{-\frac{C}{2}}^{\frac{C}{2}} \int_{-\frac{B}{2}}^{\frac{B}{2}} \left[\frac{x^3}{3} \right]_{-\frac{A}{2}}^{\frac{A}{2}} = \int_{-\frac{C}{2}}^{\frac{C}{2}} \int_{-\frac{B}{2}}^{\frac{B}{2}} \frac{A^3}{12} \partial y \partial z = \frac{A^3}{12} BC$$

$$\rho x^2 \Rightarrow \frac{M}{ABC} \frac{A^3}{12} BC = \frac{MA^2}{12}$$

$$y^2 \longrightarrow \frac{MB^2}{12}; z^2 \longrightarrow \frac{MC^2}{12}$$

$$xy \longrightarrow \int_{-\frac{C}{2}}^{\frac{C}{2}} \int_{-\frac{B}{2}}^{\frac{B}{2}} \int_{-\frac{A}{2}}^{\frac{A}{2}} xy \partial x \partial y \partial z = \int_{-\frac{C}{2}}^{\frac{C}{2}} \int_{-\frac{B}{2}}^{\frac{B}{2}} \left[\frac{x^2}{2} y \right]_{-\frac{A}{2}}^{\frac{A}{2}} \partial y \partial z = 0$$

$$xz \longrightarrow 0; yz \longrightarrow 0$$

Quindi:

$$\mathbb{I} = \frac{M}{12} \begin{pmatrix} B^2 + C^2 & 0 & 0 \\ 0 & A^2 + C^2 & 0 \\ 0 & 0 & A^2 + B^2 \end{pmatrix}$$

Maxima 5.44.0 <http://maxima.sourceforge.net>

using Lisp SBCL 2.0.0

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Dedicated to the memory of William Schelter.

The function bug_report() provides bug reporting information.

```
(%i1) SSt:matrix([y^2+z^2,-y*x,-x*z],[-y*z,x^2+z^2,-y*z],[-x*z,-y*z,x^2+y^2]);
```

```
(%o1) 
$$\begin{pmatrix} z^2 + y^2 & -xy & -xz \\ -yz & z^2 + x^2 & -yz \\ -xz & -yz & y^2 + x^2 \end{pmatrix}$$

```

```
(%i1) paral(A,B,C,M):=block([x2,y2,z2,xy,xz,yz,rho,I],
    rho:M/(A*B*C),
    x2:integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    y2:integrate(integrate(integrate(y^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    z2:integrate(integrate(integrate(z^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    xy:integrate(integrate(integrate(x*y,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    xz:integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    yz:integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
    2,C/2),
    I:zeromatrix(3,3),
    I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
    I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
    I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
    I:ratsimp(rho*I),
    print("Matrice di Ineriza"),
    print(I)
```

```
);
```

```
(%o2) paral(A,B,C,M):=block([x2,y2,z2,xy,xz,yz,rho,I],rho:M/(A*B*C),x2:
integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),y2:
integrate(integrate(integrate(y^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),z2:
integrate(integrate(integrate(z^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),xy:
integrate(integrate(integrate(x*y,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),xz:
integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),yz:
integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),
I:zeromatrix(3,3),
I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
I:ratsimp(rho*I),
print("Matrice di Ineriza"),
print(I)
```

```

integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),yz:
integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),I: zeromatrix(3,3), (I1)1:
y2 + z2, (I1)2: -xy, (I1)3: -xz, (I2)1: (I1)2, (I2)2: x2 + z2, (I2)3: -yz, (I3)1: (I1)3, (I3)2: (I2)3, (I3)3:
x2 + y2, I: ratsimp(rho*I), print(Matrice di Ineriza ), print(I)

```

```
(%i3) paral(A,B,C,M);
```

Matrice di Ineriza

$$\begin{pmatrix} \frac{(C^2+B^2)M}{12} & 0 & 0 \\ 0 & \frac{(C^2+A^2)M}{12} & 0 \\ 0 & 0 & \frac{(B^2+A^2)M}{12} \end{pmatrix}$$

(%o3)

$$\begin{pmatrix} \frac{(C^2+B^2)M}{12} & 0 & 0 \\ 0 & \frac{(C^2+A^2)M}{12} & 0 \\ 0 & 0 & \frac{(B^2+A^2)M}{12} \end{pmatrix}$$

```
(%i4)
```

Parallelepipedo di lato A,B,C con tappi A',B',C'

```

(%i1) paral(A,B,C,M):=block([x2,y2,z2,xy,xz,yz,rho,I],
    rho:M/(A*B*C),
    x2:integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    y2:integrate(integrate(integrate(y^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    z2:integrate(integrate(integrate(z^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    xy:integrate(integrate(integrate(x*y,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    xz:integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    yz:integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
    I:zeromatrix(3,3),
    I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
    I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
    I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
    I:ratsimp(rho*I),
    print("Matrice di Ineriza"),
    print(I)

```

```
);
```

```

(%o1) paral(A,B,C,M):=block([x2,y2,z2,xy,xz,yz,rho,I],rho:frac{M}{A*B*C},x2:
integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),y2:

```

```

integrate(integrate(integrate( $y^2, x, \frac{-A}{2}, \frac{A}{2}$ ),  $y, \frac{-B}{2}, \frac{B}{2}$ ),  $z, \frac{-C}{2}, \frac{C}{2}$ ),  $z2$ :
integrate(integrate(integrate( $z^2, x, \frac{-A}{2}, \frac{A}{2}$ ),  $y, \frac{-B}{2}, \frac{B}{2}$ ),  $z, \frac{-C}{2}, \frac{C}{2}$ ),  $xy$ :
integrate(integrate(integrate( $xy, x, \frac{-A}{2}, \frac{A}{2}$ ),  $y, \frac{-B}{2}, \frac{B}{2}$ ),  $z, \frac{-C}{2}, \frac{C}{2}$ ),  $xz$ :
integrate(integrate(integrate( $xz, x, \frac{-A}{2}, \frac{A}{2}$ ),  $y, \frac{-B}{2}, \frac{B}{2}$ ),  $z, \frac{-C}{2}, \frac{C}{2}$ ),  $yz$ :
integrate(integrate(integrate( $yz, x, \frac{-A}{2}, \frac{A}{2}$ ),  $y, \frac{-B}{2}, \frac{B}{2}$ ),  $z, \frac{-C}{2}, \frac{C}{2}$ ),  $I$ : zeromatrix(3,3), ( $I_1$ )1:
 $y2 + z2$ , ( $I_1$ )2:  $-xy$ , ( $I_1$ )3:  $-xz$ , ( $I_2$ )1: ( $I_1$ )2, ( $I_2$ )2:  $x2 + z2$ , ( $I_2$ )3:  $-yz$ , ( $I_3$ )1: ( $I_1$ )3, ( $I_3$ )2: ( $I_2$ )3, ( $I_3$ )3:
 $x2 + y2$ ,  $I$ : ratsimp( $\rho I$ ), print(Matrice di Ineriza ), print( $I$ )

```

```

(%i2) paraITappi(A,B,C,A1,B1,C1,M):=block(
  V:A*B*C-A1*B1*C1,
  rho:M/V,
  x2:integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  y2:integrate(integrate(integrate(y^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  z2:integrate(integrate(integrate(z^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  xy:integrate(integrate(integrate(x*y,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  xz:integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  yz:integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/
2,C/2),
  x21:integrate(integrate(integrate(x^2,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  y21:integrate(integrate(integrate(y^2,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  z21:integrate(integrate(integrate(z^2,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  xy1:integrate(integrate(integrate(x*y,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  xz1:integrate(integrate(integrate(x*z,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  yz1:integrate(integrate(integrate(y*z,x,-A1/2,A1/2),y,-B1/2,B1/2),
z,-C1/2,C1/2),
  x2:x2-x21,y2:y2-y21,z2:z2-z21,
  xy:xy-xy1,xz:xz-xz1,yz:yz-yz1,
  I:zeromatrix(3,3),
  I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
  I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
  I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
  I:ratsimp(expand(rho*I)),
  print("Matrice di Ineriza"),
  print(I));

```

```

(%o2) paraITappi(A,B,C,A1,B1,C1,M):=block( V: A B C - A1 B1 C1, rho:  $\frac{M}{V}$ , x2:

```

```

integrate(integrate(integrate(x^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),y2:
integrate(integrate(integrate(y^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),z2:
integrate(integrate(integrate(z^2,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),xy:
integrate(integrate(integrate(x*y,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),xz:
integrate(integrate(integrate(x*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),yz:
integrate(integrate(integrate(y*z,x,-A/2,A/2),y,-B/2,B/2),z,-C/2,C/2),x21:
integrate(integrate(integrate(x^2,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),y21:
integrate(integrate(integrate(y^2,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),z21:
integrate(integrate(integrate(z^2,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),xy1:
integrate(integrate(integrate(x*y,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),xz1:
integrate(integrate(integrate(x*z,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),yz1:
integrate(integrate(integrate(y*z,x,-A1/2,A1/2),y,-B1/2,B1/2),z,-C1/2,C1/2),x2: x2 - x21, y2:
y2 - y21, z2: z2 - z21, xy: xy - xy1, xz: xz - xz1, yz: yz - yz1, I: zeromatrix(3,3), (I1)1: y2 + z2,
(I1)2: -xy, (I1)3: -xz, (I2)1: (I1)2, (I2)2: x2 + z2, (I2)3: -yz, (I3)1: (I1)3, (I3)2: (I2)3, (I3)3: x2 + y2, I:
ratsimp(expand(rho I)), print(Matrice di Ineriza ), print(I)

```

Parallelepipedo con tappi

(%i3) paralTappi(A,B,C,A1,B1,C1,M);

Matrice di Ineriza

```

((A1*B1*C1^3 + A1*B1^3*C1 - A*B*C^3 - A*B^3*C)*M / (12*A1*B1*C1 - 12*A*B*C), 0, 0, 0, (A1*B1*C1^3 + A1^3*B1*C1 - A*B*C^3 - A^3*B*C)*M / (12*A1*B1*C1 - 12*A*B*C), 0, 0, 0,
((A1*B1^3 + A1^3*B1)*C1 + (-A*B^3 - A^3*B)*C)*M / (12*A1*B1*C1 - 12*A*B*C)
(%o3) ((A1*B1*C1^3 + A1*B1^3*C1 - A*B*C^3 - A*B^3*C)*M / (12*A1*B1*C1 - 12*A*B*C), 0, 0, 0, (A1*B1*C1^3 + A1^3*B1*C1 - A*B*C^3 - A^3*B*C)*M / (12*A1*B1*C1 - 12*A*B*C), 0, 0, 0,
0, ((A1*B1^3 + A1^3*B1)*C1 + (-A*B^3 - A^3*B)*C)*M / (12*A1*B1*C1 - 12*A*B*C))

```

Parallelepipedo senza tappi

(%i4) paralTappi(A,B,C,A,B1,C1,M);

Matrice di Ineriza

$$\left(\frac{(B1 C1^3 + B1^3 C1 - B C^3 - B^3 C) M}{12 B1 C1 - 12 B C}, 0, 0, 0, \frac{(B1 C1^3 + A^2 B1 C1 - B C^3 - A^2 B C) M}{12 B1 C1 - 12 B C}, 0, 0, 0, \right. \\ \left. \frac{((B1^3 + A^2 B1) C1 + (-B^3 - A^2 B) C) M}{12 B1 C1 - 12 B C} \right) \\ (%o4) \left(\frac{(B1 C1^3 + B1^3 C1 - B C^3 - B^3 C) M}{12 B1 C1 - 12 B C}, 0, 0, 0, \frac{(B1 C1^3 + A^2 B1 C1 - B C^3 - A^2 B C) M}{12 B1 C1 - 12 B C}, 0, 0, 0, \right. \\ \left. \frac{((B1^3 + A^2 B1) C1 + (-B^3 - A^2 B) C) M}{12 B1 C1 - 12 B C} \right)$$

(%i5)

Cilindro di raggio R ed altezza H

$$\mathbb{I} = \frac{M}{V} \iiint \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix} \partial x \partial y \partial z$$

$$V = A_b H = \pi R^2 H$$

$$\rho = \frac{M}{\pi R^2 H}$$

Al fine di svolgere l'integrale, una delle scelte è quella di ricorrere alle coordinate cilindriche. In particolare:

$$\begin{cases} x = \rho \cos(\theta) \\ y = \rho \sin(\theta) \\ z = z \end{cases} \longrightarrow \theta \in [0, 2\pi], \rho \in [0, R], z \in \left[-\frac{H}{2}, \frac{H}{2} \right]$$

```
(%i23) cilindro(R,H):=block([x,y,z,a,b,c,d],
                             x:rho*cos(theta),
                             y:rho*sin(theta),
                             z:z,
                             V:%pi*R^2*H,
                             d:M/V,
                             x2:integrate(integrate(integrate(rho*x^2,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),
                             y2:integrate(integrate(integrate(rho*y^2,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),
                             z2:integrate(integrate(integrate(rho*z^2,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),
                             xy:integrate(integrate(integrate(rho*x*y,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),
                             xz:integrate(integrate(integrate(rho*x*z,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),
                             yz:integrate(integrate(integrate(rho*y*z,theta,0,2*%pi),rho,0,R),
                             z,-H/2,H/2),

                             I:zeromatrix(3,3),
                             I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
                             I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
                             I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
                             I:ratsimp((d*I)),
                             print("Matrice di Ineriza"),
                             print(I))
```

```
(%o23) cilindro(R, H) := block  $\left( [x, y, z, a, b, c, d], x: \rho \cos(\vartheta), y: \rho \sin(\vartheta), z: z, V: \pi R^2 H, d: \frac{M}{V}, \right.$ 
 $x2: \text{integrate}\left(\text{integrate}(\text{integrate}(\rho x^2, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), y2:$ 
 $\text{integrate}\left(\text{integrate}(\text{integrate}(\rho y^2, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), z2:$ 
 $\text{integrate}\left(\text{integrate}(\text{integrate}(\rho z^2, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), xy:$ 
 $\text{integrate}\left(\text{integrate}(\text{integrate}(\rho x y, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), xz:$ 
 $\text{integrate}\left(\text{integrate}(\text{integrate}(\rho x z, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), yz:$ 
 $\text{integrate}\left(\text{integrate}(\text{integrate}(\rho y z, \vartheta, 0, 2\pi), \rho, 0, R), z, \frac{-H}{2}, \frac{H}{2}\right), I: \text{zeromatrix}(3, 3), (I_1)_1: y2 +$ 
 $z2, (I_1)_2: -xy, (I_1)_3: -xz, (I_2)_1: (I_1)_2, (I_2)_2: x2 + z2, (I_2)_3: -yz, (I_3)_1: (I_1)_3, (I_3)_2: (I_2)_3, (I_3)_3: x2 + y2,$ 
 $I: \text{ratsimp}(d I), \text{print}(\text{Matrice di Ineriza}), \text{print}(I) \left. \right)$ 
```

```
(%i24) cilindro(R,H);
```

Matrice di Ineriza

$$\begin{pmatrix} \frac{3MR^2 + H^2M}{12} & 0 & 0 \\ 0 & \frac{3MR^2 + H^2M}{12} & 0 \\ 0 & 0 & \frac{MR^2}{2} \end{pmatrix}$$

(%o24)

$$\begin{pmatrix} \frac{3MR^2 + H^2M}{12} & 0 & 0 \\ 0 & \frac{3MR^2 + H^2M}{12} & 0 \\ 0 & 0 & \frac{MR^2}{2} \end{pmatrix}$$

(%i25)

Cilindro di raggio R, altezza H cavo con cilindro R',H senza tappi

```
(%i40) cilindro(R,H,R1):=block([x,y,z,a,b,c,d],
                                x:rho*cos(theta),
                                y:rho*sin(theta),
                                z:z,
                                V:%pi*(R)^2*H-%pi*(R1)^2*H,
                                d:M/V,
                                x2:integrate(integrate(integrate(rho*x^2,theta,0,2*%pi),rho,R1,
                                R),z,0,H),
                                y2:integrate(integrate(integrate(rho*y^2,theta,0,2*%pi),rho,R1,
                                R),z,0,H),
                                z2:integrate(integrate(integrate(rho*z^2,theta,0,2*%pi),rho,R1,
                                R),z,0,H),
                                xy:integrate(integrate(integrate(rho*x*y,theta,0,2*%pi),rho,R1,
                                R),z,0,H),
                                xz:integrate(integrate(integrate(rho*x*z,theta,0,2*%pi),rho,R1,
                                R),z,0,H),
                                yz:integrate(integrate(integrate(rho*y*z,theta,0,2*%pi),rho,R1,
                                R),z,0,H),

                                I:zeromatrix(3,3),
                                I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
                                I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
                                I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
                                I:ratsimp(expand(d*I)),
                                print("Matrice di Ineriza"),
                                print(I))
```

```
(%o40) cilindro(R, H, R1) := block ([x, y, z, a, b, c, d], x: rho cos (vartheta), y: rho sin (vartheta), z: z, V: pi R^2 H -
pi R1^2 H, d: M/V, x2: integrate(integrate(integrate(rho x^2, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), y2:
integrate(integrate(integrate(rho y^2, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), z2:
integrate(integrate(integrate(rho z^2, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), xy:
integrate(integrate(integrate(rho x y, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), xz:
integrate(integrate(integrate(rho x z, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), yz:
integrate(integrate(integrate(rho y z, vartheta, 0, 2 pi), rho, R1, R), z, 0, H), I: zeromatrix(3, 3), (I1)1: y2 + z2,
(I1)2: -xy, (I1)3: -xz, (I2)1: (I1)2, (I2)2: x2 + z2, (I2)3: -yz, (I3)1: (I1)3, (I3)2: (I2)3, (I3)3: x2 + y2, I:
ratsimp(expand(d I)), print(Matrice di Ineriza ), print(I))
```

```
(%i41) cilindro(R,H,R[1]);
```


Matrice di Ineriza

$$(\%o41) \begin{pmatrix} \frac{3MR^2 + (4H^2 + 3R_1^2)M}{12} & 0 & 0 \\ 0 & \frac{3MR^2 + (4H^2 + 3R_1^2)M}{12} & 0 \\ 0 & 0 & \frac{MR^2 + R_1^2M}{2} \end{pmatrix}$$

$$\begin{pmatrix} \frac{3MR^2 + (4H^2 + 3R_1^2)M}{12} & 0 & 0 \\ 0 & \frac{3MR^2 + (4H^2 + 3R_1^2)M}{12} & 0 \\ 0 & 0 & \frac{MR^2 + R_1^2M}{2} \end{pmatrix}$$

Cilindro di raggio **R**, altezza **H** cavo con cilindro **R'**, **H'** con tappi

```
(%i52) cilindro(R,H):=block([x,y,z,a,b,c,d],
    x:rho*cos(theta),
    y:rho*sin(theta),
    z:z,

    x2:integrate(integrate(integrate(rho*x^2,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),
    y2:integrate(integrate(integrate(rho*y^2,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),
    z2:integrate(integrate(integrate(rho*z^2,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),
    xy:integrate(integrate(integrate(rho*x*y,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),
    xz:integrate(integrate(integrate(rho*x*z,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),
    yz:integrate(integrate(integrate(rho*y*z,theta,0,2*%pi),rho,0,R),
z,-H/2,H/2),

    I:zeromatrix(3,3),
    I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
    I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
    I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
    I:ratsimp(I)
)
```

```
(%o52) cilindro(R,H):=block([x,y,z,a,b,c,d],x:rho*cos(theta),y:rho*sin(theta),z:z,x2:
integrate(integrate(integrate(rho*x^2,theta,0,2*pi),rho,0,R),z,-H/2,H/2),y2:
integrate(integrate(integrate(rho*y^2,theta,0,2*pi),rho,0,R),z,-H/2,H/2),z2:
integrate(integrate(integrate(rho*z^2,theta,0,2*pi),rho,0,R),z,-H/2,H/2),xy:
integrate(integrate(integrate(rho*x*y,theta,0,2*pi),rho,0,R),z,-H/2,H/2),xz:
integrate(integrate(integrate(rho*x*z,theta,0,2*pi),rho,0,R),z,-H/2,H/2),yz:
integrate(integrate(integrate(rho*y*z,theta,0,2*pi),rho,0,R),z,-H/2,H/2),I:zeromatrix(3,3),I[1][1]:y2+z2,
I[1][2]:-xy,I[1][3]:-xz,I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
I:ratsimp(I))
```

$z^2, (I_1)_2: -xy, (I_1)_3: -xz, (I_2)_1: (I_1)_2, (I_2)_2: x^2 + z^2, (I_2)_3: -yz, (I_3)_1: (I_1)_3, (I_3)_2: (I_2)_3, (I_3)_3: x^2 + y^2,$
 $I: \text{ratsimp}(I) \Big)$

```
(%i53) cilindroSV(R,H,H1,R1):=block([x,y,z,a,b,c,d],
      V:%pi*R^2*H-%pi*R1^2*H1,
      d:M/V,
      I:ratsimp(expand(cilindro(R,H))),
      Icavo:ratsimp(expand(cilindro(R1,H1))),
      print("Matrice di Ineriza"),
      print(ratsimp(d*I)))
```

(%o53) cilindroSV($R, H, H1, R1$) := **block** $\left([x, y, z, a, b, c, d], V: \pi R^2 H - \pi R1^2 H1, d: \frac{M}{V}, I: \right.$
 $\text{ratsimp}(\text{expand}(\text{cilindro}(R, H))), \text{Icavo}: \text{ratsimp}(\text{expand}(\text{cilindro}(R1, H1))), \text{print}(\text{Matrice di Ine-}$
 $\text{riza}), \text{print}(\text{ratsimp}(d I)) \Big)$

```
(%i54) cilindroSV(R,H,H[1],R[1]);
```

Matrice di Ineriza

$$(\%o54) \begin{pmatrix} \frac{(3 H_1 R_1^4 + H_1^3 R_1^2) M}{12 H R^2 - 12 H_1 R_1^2} & 0 & 0 \\ 0 & \frac{(3 H_1 R_1^4 + H_1^3 R_1^2) M}{12 H R^2 - 12 H_1 R_1^2} & 0 \\ 0 & 0 & \frac{H_1 R_1^4 M}{2 H R^2 - 2 H_1 R_1^2} \end{pmatrix}$$

$$\begin{pmatrix} \frac{(3 H_1 R_1^4 + H_1^3 R_1^2) M}{12 H R^2 - 12 H_1 R_1^2} & 0 & 0 \\ 0 & \frac{(3 H_1 R_1^4 + H_1^3 R_1^2) M}{12 H R^2 - 12 H_1 R_1^2} & 0 \\ 0 & 0 & \frac{H_1 R_1^4 M}{2 H R^2 - 2 H_1 R_1^2} \end{pmatrix}$$

```
(%i55)
```

Sfera di raggio R

$$\mathbb{I} = \frac{M}{V} \iiint \begin{pmatrix} y^2 + z^2 & -xy & -xz \\ -xy & x^2 + z^2 & -yz \\ -xz & -yz & x^2 + y^2 \end{pmatrix} \partial x \partial y \partial z$$

$$V = \frac{4}{3} \pi R^3$$

$$\rho = \frac{M}{\frac{4}{3} \pi R^3}$$

Al fine di svolgere l'integrale, una delle scelte è quella di ricorrere alle coordinate sferiche. In particolare:

$$\begin{cases} x = \rho \sin(\phi) \cos(\theta) \\ y = \rho \sin(\phi) \sin(\theta) \\ z = \rho \cos(\phi) \end{cases} \longrightarrow \theta \in [0; 2\pi], \rho \in \left[-\frac{R}{2}, \frac{R}{2} \right], \phi \in [0; 2\pi]$$

```
(%i57) sfera(R):=block([x,y,z,a,b,c,d],
                        x:rho*cos(theta)*sin(phi),
                        y:rho*sin(theta)*sin(phi),
                        z:rho*cos(phi),
                        V:(4/3)*%pi*(R)^3,
                        d:M/V,
                        x2:integrate(integrate(integrate(rho^2*sin(phi)*x^2,theta,0,
2*%pi),rho,0,R),phi,0,%pi),
                        y2:integrate(integrate(integrate(rho^2*sin(phi)*y^2,theta,0,
2*%pi),rho,0,R),phi,0,%pi),
                        z2:integrate(integrate(integrate(rho^2*sin(phi)*z^2,theta,0,
2*%pi),rho,0,R),phi,0,%pi),
                        xy:integrate(integrate(integrate(rho^2*sin(phi)*x*y,theta,0,
2*%pi),rho,0,R),phi,0,%pi),
                        xz:integrate(integrate(integrate(rho^2*sin(phi)*x*z,theta,0,
2*%pi),rho,0,R),phi,0,%pi),
                        yz:integrate(integrate(integrate(rho^2*sin(phi)*y*z,theta,0,
2*%pi),rho,0,R),phi,0,%pi),

                        I:zeromatrix(3,3),
                        I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
                        I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
                        I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
                        I:ratsimp(expand(d*I)),
                        print("Matrice di Ineriza"),
                        print(I))
```

```
(%o57) sfera(R):=block([x,y,z,a,b,c,d],x:rho*cos(theta)*sin(phi),y:rho*sin(theta)*sin(phi),z:rho*cos(phi),V:
4/3*pi*R^3,d:M/V,x2:integrate(integrate(integrate(rho^2*sin(phi)*x^2,theta,0,2*pi),rho,0,R),phi,0,%pi),y2:
integrate(integrate(integrate(rho^2*sin(phi)*y^2,theta,0,2*pi),rho,0,R),phi,0,%pi),z2:
integrate(integrate(integrate(rho^2*sin(phi)*z^2,theta,0,2*pi),rho,0,R),phi,0,%pi),xy:
integrate(integrate(integrate(rho^2*sin(phi)*x*y,theta,0,2*pi),rho,0,R),phi,0,%pi),xz:
integrate(integrate(integrate(rho^2*sin(phi)*x*z,theta,0,2*pi),rho,0,R),phi,0,%pi),yz:
integrate(integrate(integrate(rho^2*sin(phi)*y*z,theta,0,2*pi),rho,0,R),phi,0,%pi),I:zeromatrix(3,3),
(I1)1:y2+z2,(I1)2:-xy,(I1)3:-xz,(I2)1:(I1)2,(I2)2:x2+z2,(I2)3:-yz,(I3)1:(I1)3,(I3)2:(I2)3,(I3)3:
x2+y2,I:ratsimp(expand(d*I)),print(Matrice di Ineriza ),print(I))
```

```
(%i58) sfera(R);
```

Matrice di Ineriza

$$\begin{pmatrix} \frac{2MR^2}{5} & 0 & 0 \\ 0 & \frac{2MR^2}{5} & 0 \\ 0 & 0 & \frac{2MR^2}{5} \end{pmatrix}$$

```
(%o58) \begin{pmatrix} \frac{2MR^2}{5} & 0 & 0 \\ 0 & \frac{2MR^2}{5} & 0 \\ 0 & 0 & \frac{2MR^2}{5} \end{pmatrix}
```

```
(%i59)
```

Sfera cava di raggio R e R'

Maxima 5.44.0 <http://maxima.sourceforge.net>
 using Lisp SBCL 2.0.0
 Distributed under the GNU Public License. See the file COPYING.
 Dedicated to the memory of William Schelter.
 The function bug_report() provides bug reporting information.

```
(%i61) sfera(R,R1):=block([x,y,z,a,b,c,d],
                        x:rho*cos(theta)*sin(phi),
                        y:rho*sin(theta)*sin(phi),
                        z:rho*cos(phi),
                        V:(4/3)*%pi*(R)^3-(4/3)*%pi*(R1)^3,
                        d:M/V,
                        x2:integrate(integrate(integrate(rho^2*sin(phi)*x^2,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),
                        y2:integrate(integrate(integrate(rho^2*sin(phi)*y^2,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),
                        z2:integrate(integrate(integrate(rho^2*sin(phi)*z^2,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),
                        xy:integrate(integrate(integrate(rho^2*sin(phi)*x*y,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),
                        xz:integrate(integrate(integrate(rho^2*sin(phi)*x*z,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),
                        yz:integrate(integrate(integrate(rho^2*sin(phi)*y*z,theta,0,
2*%pi),rho,R1,R),phi,0,%pi),

                        I:zeromatrix(3,3),
                        I[1][1]:y2+z2,I[1][2]:-xy,I[1][3]:-xz,
                        I[2][1]:I[1][2],I[2][2]:x2+z2,I[2][3]:-yz,
                        I[3][1]:I[1][3],I[3][2]:I[2][3],I[3][3]:x2+y2,
                        I:ratsimp(expand(d*I)),
                        print("Matrice di Ineriza"),
                        print(I))
```

```
(%o61) sfera(R,R1):=block([x,y,z,a,b,c,d],x:rho*cos(theta)*sin(phi),y:rho*sin(theta)*sin(phi),z:
rho*cos(phi),V:(4/3)*pi*R^3-(4/3)*pi*R1^3,d:M/V,x2:integrate(integrate(integrate(rho^2*sin(phi)*x^2,theta,0,2*pi),rho,R1,
R),phi,0,pi),y2:integrate(integrate(integrate(rho^2*sin(phi)*y^2,theta,0,2*pi),rho,R1,R),phi,0,pi),z2:
integrate(integrate(integrate(rho^2*sin(phi)*z^2,theta,0,2*pi),rho,R1,R),phi,0,pi),xy:
integrate(integrate(integrate(rho^2*sin(phi)*x*y,theta,0,2*pi),rho,R1,R),phi,0,pi),xz:
integrate(integrate(integrate(rho^2*sin(phi)*x*z,theta,0,2*pi),rho,R1,R),phi,0,pi),yz:
integrate(integrate(integrate(rho^2*sin(phi)*y*z,theta,0,2*pi),rho,R1,R),phi,0,pi),I:zeromatrix(3,3),(I1)1:
y2+z2,(I1)2:-xy,(I1)3:-xz,(I2)1:(I1)2,(I2)2:x2+z2,(I2)3:-yz,(I3)1:(I1)3,(I3)2:(I2)3,(I3)3:
x2+y2,I:ratsimp(expand(d*I)),print(Matrice di Ineriza ),print(I))
```

```
(%i62) sfera(R,R[1])
```

Matrice di Ineriza

$$\begin{pmatrix} \frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2}, 0, 0; 0, \frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2}, \\ 0; 0, 0, \frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2} \end{pmatrix}$$

$$\begin{aligned}
& (\%o62) \left(\frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2}, 0, 0; 0, \right. \\
& \left. \frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2}, 0; 0, 0, \frac{2MR^4 + 2R_1MR^3 + 2R_1^2MR^2 + 2R_1^3MR + 2R_1^4M}{5R^2 + 5R_1R + 5R_1^2} \right)
\end{aligned}$$

(%i63)