


$$\dot{X} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} X$$

$$\begin{bmatrix} 0 & 1 \\ -\omega^2 & 0 \end{bmatrix}$$

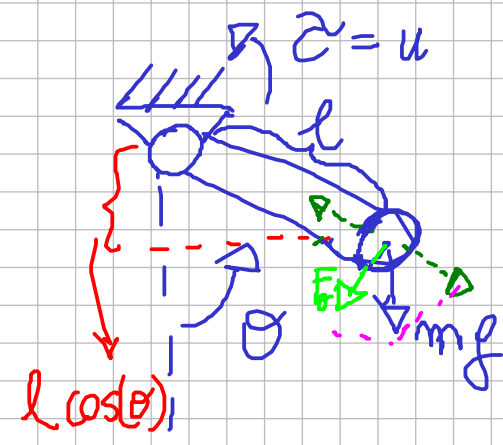
$$P(\lambda) = \lambda^2 + 1 \rightarrow \lambda_{1,2} = \pm j$$

$$\Sigma \begin{cases} \dot{X} = f(X, u), X_0 \\ y = h(X, u) \end{cases}$$


$$(X_e, u_e) \rightarrow \begin{cases} 0 = f(X_e, u_e) \\ y_e = h(X_e, u_e) \end{cases}$$

$$\begin{cases} \tilde{X} = X - X_e \\ \tilde{y} = y - y_e \\ \tilde{u} = u - u_e \end{cases} \rightarrow \begin{cases} \dot{\tilde{X}} = \frac{\partial f(X, u)}{\partial X} \bigg|_{X_e, u_e} \tilde{X} + \frac{\partial f(X, u)}{\partial u} \bigg|_{X_e, u_e} \tilde{u} \\ \tilde{y} = \frac{\partial h(X, u)}{\partial X} \bigg|_{X_e, u_e} \tilde{X} + \frac{\partial h(X, u)}{\partial u} \bigg|_{X_e, u_e} \tilde{u} \end{cases}$$

$$\Sigma \text{ lin in } (X_e, u_e)$$



$$\begin{aligned} \bar{F}_\theta &= mg \sin(\theta) \\ \tau_\theta &= mg \sin(\theta) l \end{aligned}$$

$$I \ddot{\theta} = -mg l \sin(\theta) - c \dot{\theta} + \tau$$

$$x_1 = \theta$$

$$x_2 = \dot{\theta}$$

$$\begin{cases} \dot{x}_1 = x_2 \\ \dot{x}_2 = -\frac{mg l}{I} \sin(x_1) - \frac{c}{I} x_2 + \frac{1}{I} \tau \end{cases} = f_1(x, u)$$

$$\begin{matrix} f_1(x, u) \\ \parallel \\ 1 \\ \parallel \\ 2 \end{matrix} \quad \begin{matrix} \parallel \\ 1 \\ \parallel \\ 2 \end{matrix} \quad \begin{matrix} \parallel \\ 1 \\ \parallel \\ 2 \end{matrix}$$

$$(x_e, u_e) \rightarrow u_e = 0 = \tilde{u}_e$$

↓
?

$$0 = x_{2e}$$

$$0 = -\frac{m l g}{I} \sin(x_{1e}) - \frac{c}{I} x_{2e} + \frac{1}{I} \cdot \tilde{u}_e$$

$$\rightarrow x_e = \begin{bmatrix} K\pi \\ 0 \end{bmatrix}$$

$$K \in \mathbb{Z}$$

$$\tilde{x} = x - x_e$$

$$\dot{\tilde{x}} = \begin{bmatrix} 0 & 1 \\ -\cos(x_{1e}) & -2 \end{bmatrix} \tilde{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \tilde{u}$$

$$x_e = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\dot{\tilde{x}} = \begin{bmatrix} 0 & 1 \\ -1 & -2 \end{bmatrix} \tilde{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \tilde{u}$$

$$A \downarrow$$

$$p_A(\lambda) = \lambda^2 + 2\lambda + 1$$

$$\det(\lambda I - A) = \begin{vmatrix} \lambda & -1 \\ -1 & \lambda + 2 \end{vmatrix} = \lambda(\lambda + 2) - 1$$

$$A \text{ \u00e8 Hurwitz} \Leftrightarrow p_A(\lambda) \text{ \u00e8 Hurwitz} \Leftrightarrow \forall \lambda_i \in \sigma(A), \operatorname{Re}(\lambda_i) < 0$$

Shur

Shur

$$|\lambda_i| < 1$$

$$\sum_{i=1}^n \ln \left(\begin{bmatrix} 0 \\ 0 \end{bmatrix} \right) \text{ \u00e8 A.S.}$$

$$\dot{\tilde{x}} = \begin{bmatrix} 0 & 1 \\ 1 & -2 \end{bmatrix} \tilde{x} + \begin{bmatrix} 0 \\ 1 \end{bmatrix} \tilde{u} \rightarrow \sum_{i=1}^n \ln \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) \text{ \u00e8 (*)}$$

$$\ln x_0 \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\downarrow p_A(\lambda) = \lambda^2 + 2\lambda - 1$$

\u2192 Cortesia $p_A(\lambda)$ non \u00e8 di Hurwitz quindi

A non \u00e8 di Hurwitz quindi (*) \u00e8 INSTABILE

$P(\lambda)$ è di HURWITZ
tutte $\lambda_i \in \mathbb{C}^-$ stretta



(condiz. necessaria)
tutti i coeff. di $P(\lambda)$ hanno
lo stesso segno



$\text{grad}(P(\lambda)) = 2$ (Regola di Routh-Hurwitz)



generare una tabella di
Routh ripulendo con gli
elementi della I colonna
eventi lo stesso segno

$$(\lambda + P_1)(\lambda + P_2) = \lambda^2 + (P_1 + P_2)\lambda + P_1 P_2$$

$\lambda_1 = -P_1, \lambda_2 = -P_2$
 $\text{se } (P_1, P_2) > 0$
 $P_1 < 0, P_2 > 0$

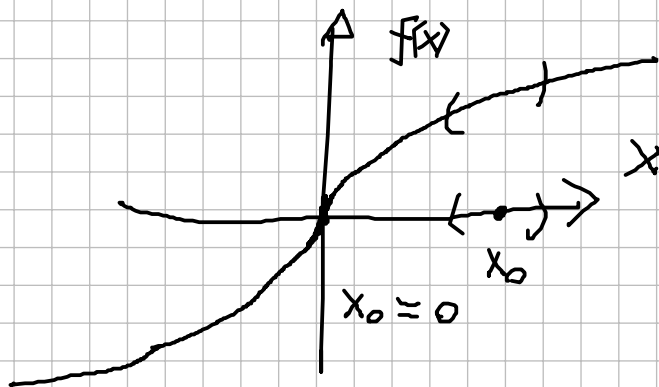
$\lambda^3 + \lambda + 1$ NON è HURWITZ

$\lambda^3 + 4\lambda^2 + 10\lambda + 1$ potrebbe \rightarrow

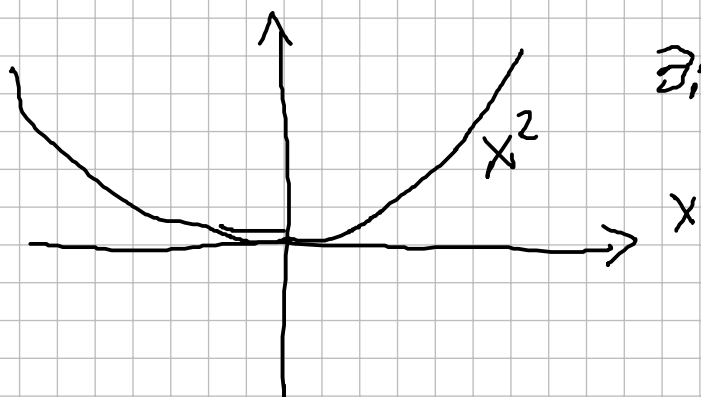
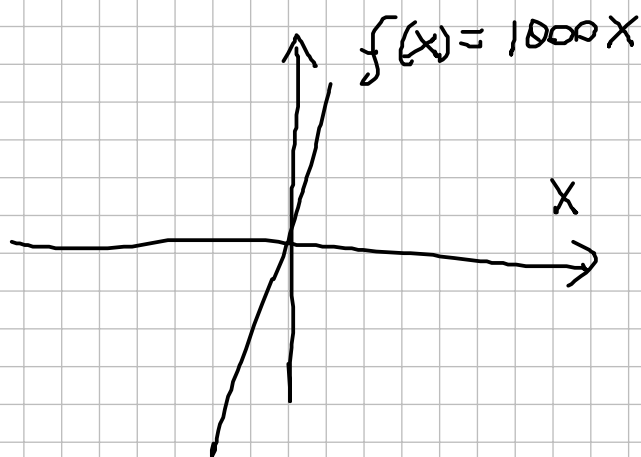
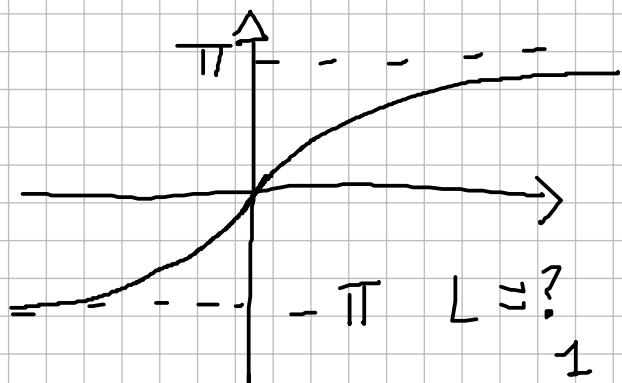
$$(\lambda + 0.5)(\lambda - 0.5) = \lambda^2 + 0\lambda - 0.25$$

No segno coeff
e T.D.

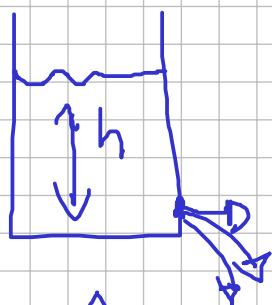
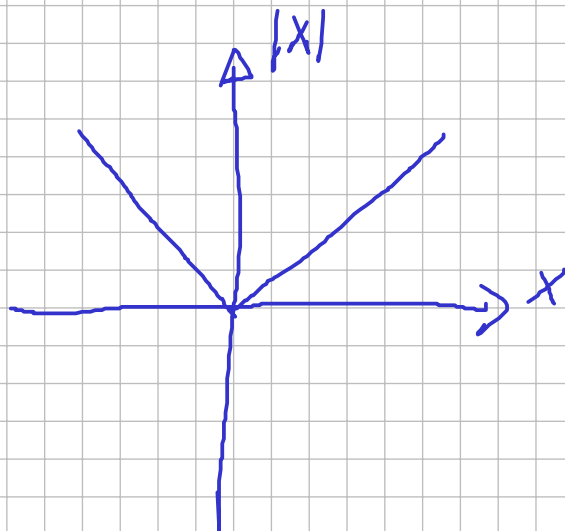
$$f(x) \triangleq \begin{cases} \sqrt{x} & \text{se } x > 0 \\ -\sqrt{-x} & \text{se } x \leq 0 \end{cases}$$



$$L = 1000$$

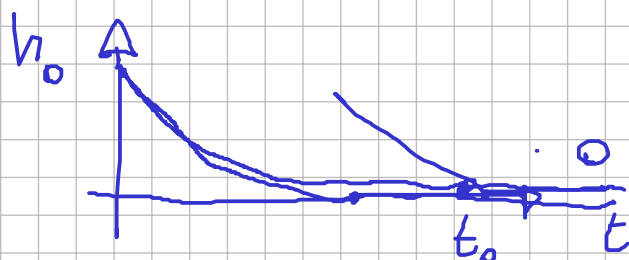
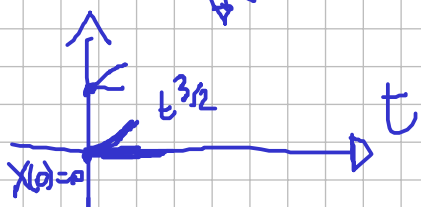


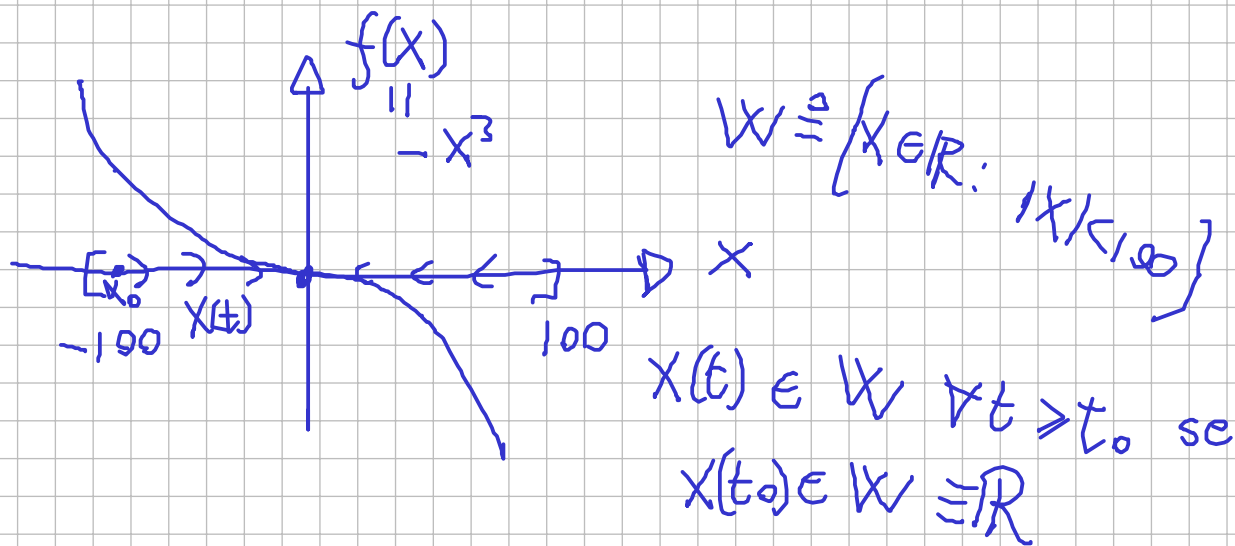
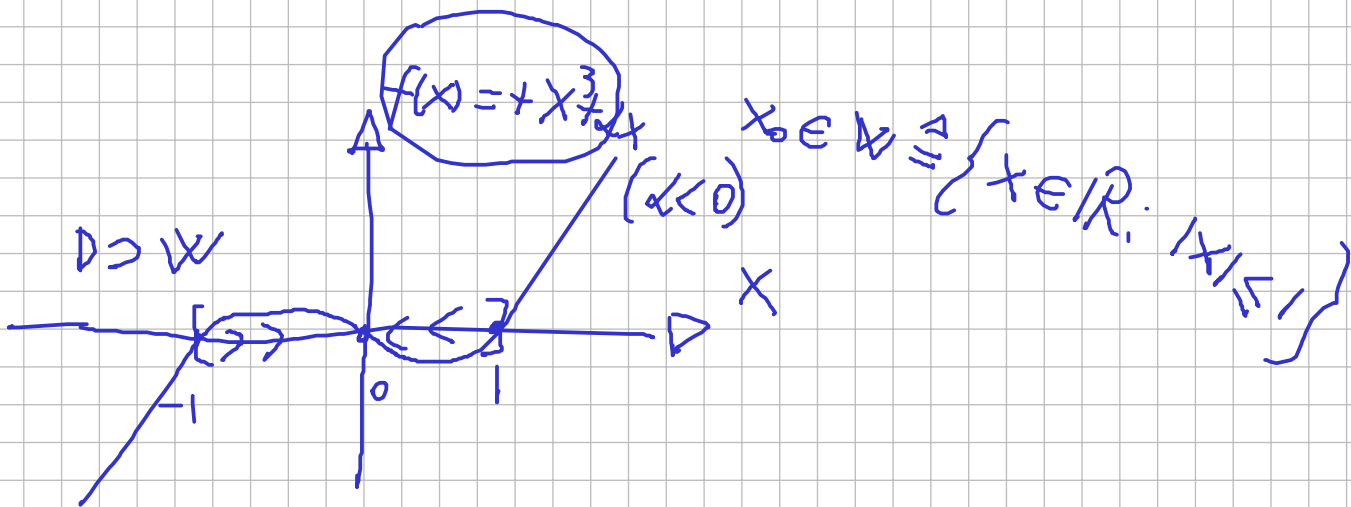
$$\exists! L \forall x_0$$



$$\dot{h} = c\sqrt{h}$$

$$h_0 = h(t_0)$$





$$\dot{x}_e = \boxed{Ax_e}$$

$$Ix_e = Ax_e$$

