

# RS-HL-4: Data Transmission by MDP algorithm

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## Scope

Create Data Transmission Dataset from given contact matrix

## I. Load the Data

```
clc; clear;
addpath( '~/Desktop/Redstone_Project/RS_HL/RS_HL_3_Network_Graph_Generation/' )
load( "RS_HL_3_Network_Graph_Generation.mat" )

sat_to_sat_contact_3d_matrix(:, :, 1);
gs_to_sat_contact_3d_matrix(:, :, 1);
```

## II. Specify the start GS and end GS and get the contact schedule

```
start_gs = 26;

end_gs = 3;

start_gs_contact_schedule = zeros(48, 5761);
end_gs_contact_schedule = zeros(48, 5761);

for i = 1:48
    start_gs_contact_schedule(i, :) = gs_to_sat_contact_3d_matrix(start_gs, i, :);
    end_gs_contact_schedule(i, :) = gs_to_sat_contact_3d_matrix(end_gs, i, :);
end

start_gs_contact_schedule;
end_gs_contact_schedule;
```

## III. Contact Availability For GS

```
[row1, col1] = find(start_gs_contact_schedule == 1);
```

```
[row2,col2] = find(end_gs_contact_schedule == 1);
```

```
start_info = [row1,col1]
```

```
start_info = 2063x2
```

```
7 821  
7 822  
7 823  
7 824  
7 825  
6 834  
6 835  
6 836  
6 837  
6 838  
:  
:
```

```
end_info = [row2,col2]
```

```
end_info = 2162x2
```

```
16 179  
16 180  
16 181  
16 182  
16 183  
16 184  
16 185  
15 193  
15 194  
15 195  
:  
:
```

```
end_info = end_info(end_info(:,2) > start_info(1,2),:);
```

```
start_sat = start_info(1,1)
```

```
start_sat = 7
```

```
end_sat = end_info(1,1)
```

```
end_sat = 47
```

```
start_time = start_info(1,2)
```

```
start_time = 821
```

```
end_time = end_info(1,2)
```

```
end_time = 822
```

## IV. MDP formulation

```
A = 1:48;
B = string(A');

MDP = createMDP(48,B);

time_stamp = start_time;

gs_to_sat_matrix = gs_to_sat_contact_3d_matrix(:, :, time_stamp);
sat_to_sat_matrix = sat_to_sat_contact_3d_matrix(:, :, time_stamp);

MDP.TerminalStates = "s" + end_sat;

for i = 1:48
    for j = 1:48
        if sat_to_sat_matrix(i,j) == 1
            MDP.T(i,j,j) = sat_to_sat_matrix(i,j);

            if i < 25
                if j < 25
                    MDP.R(i,j,j) = -1;
                end
                if j > 24
                    MDP.R(i,j,j) = -25;
                end
            end

            if i > 24
                if j > 24
                    MDP.R(i,j,j) = -1;
                end
                if j < 25
                    MDP.R(i,j,j) = -25;
                end
            end

            if j == end_sat
                if j < 25
                    if i > 24
                        MDP.R(i,end_sat,end_sat) = 70;
                    end
                else
                    MDP.R(i,end_sat,end_sat) = 100;
                end
            end
        end
    end
end
```

```

        if j > 24
            if i < 25
                MDP.R(i,end_sat,end_sat) = 70;
            end
            else
                MDP.R(i,end_sat,end_sat) = 100;
            end
        end
    end

    end

    if sat_to_sat_matrix(i,j) == 0
        MDP.T(i,i,j) = 1;
        MDP.R(i,i,j) = -50;
    end
end
end

env = rlMDPEnv(MDP);

env.ResetFcn = @( ) start_sat;

rng(0)

obsInfo = getObservationInfo(env);
actInfo = getActionInfo(env);
qTable = rlTable(obsInfo, actInfo);
qFunction = rlQValueFunction(qTable, obsInfo, actInfo);
qOptions = rlOptimizerOptions(LearnRate=1);

agentOpts = rlQAgentOptions;
agentOpts.DiscountFactor = 1;
agentOpts.EpsilonGreedyExploration.Epsilon = 0.9;
agentOpts.EpsilonGreedyExploration.EpsilonDecay = 0.01;
agentOpts.CriticOptimizerOptions = qOptions;
qAgent = rlQAgent(qFunction,agentOpts); % #ok<NASGU>

trainOpts = rlTrainingOptions;
trainOpts.MaxStepsPerEpisode = 100;
trainOpts.MaxEpisodes = 500;
trainOpts.StopTrainingCriteria = "AverageReward";
trainOpts.StopTrainingValue = 13;
trainOpts.ScoreAveragingWindowLength = 30;

trainingStats = train(qAgent,env,trainOpts);

```

```
Data = sim(qAgent,env);
```

```
reshape(Data.Observation.MDPObservations.Data, [],1)
```

```
ans = 7x1
      7
      6
      5
      4
      3
      2
     47
```

```
size(Data.Observation.MDPObservations.Data)
```

```
ans = 1x3
      1      1      7
```

```
Data.Reward.Data
```

```
ans = 6x1
     -1
     -1
     -1
     -1
     -1
     70
```

```
sum(Data.Reward.Data)
```

```
ans = 65
```