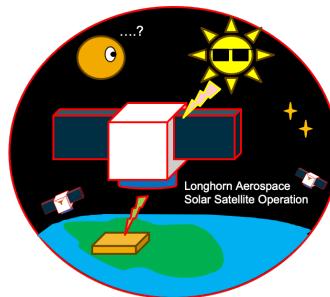


ASE374K

LASSO (Longhorn Aerospace Solar Satellite Operation) Project



4/12/2024

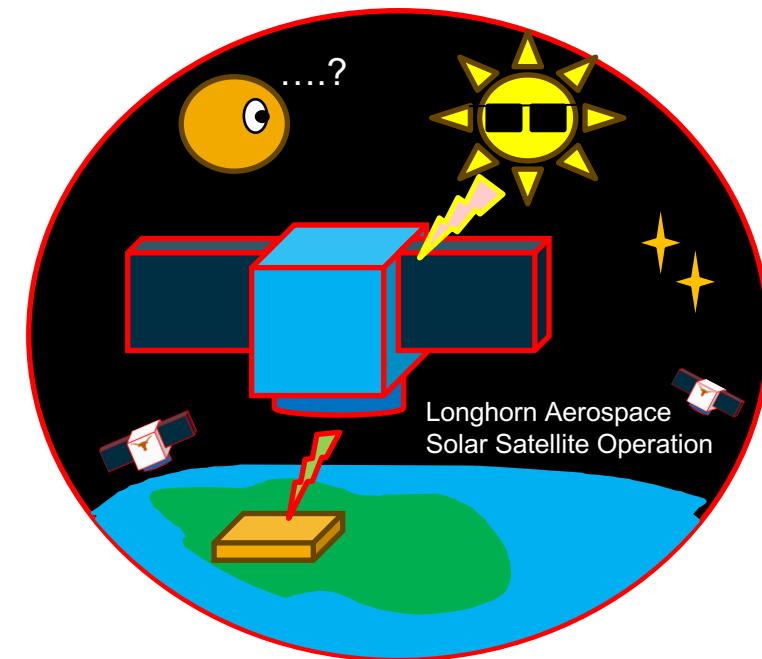
Hongseok Kim

UT Austin Aerospace Engineering

redstone@utexas.edu

Contents

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- II. Mission Statement
- III. Concept of Operation
- IV. System Architecture & Scope of Research
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- VI. Interface Management and Decision Process
- VII. Mission Operation Analysis
 - Case Study 1: Sun Pointing Mode Analysis
 - Case Study 2: Energy Transmission Mode Analysis
 - Case Study 3: Constellation Concept Analysis
- VIII. Conclusion and Future Study Topic



Mission Logo

I. Statement of Purpose

- We design Space Solar Power Satellite Mission and Solar Power Satellite which can charge the solar energy from sun and transmit energy to the ground.
- We are proposing architecture level system design process and end-to-end energy concepts and technology.
- Our project is divided by 4 sub-topics: Orbit Analysis, Energy Transmission Payload Analysis, Solar Energy acquisition (Solar Panel and Battery) and satellite structure analysis, and mission operation concept analysis.
- In mission operation analysis process, the validation of analysis of the other three sub-topics is proposed, including satellite ADCS (Attitude Determination and Control System) demonstration.
- Satellite constellation concept for continuous power transmission on ground and inter-satellite charge is proposed.
- In the future, inter-satellite charging technique and energy transmission cis-lunar regime will be studied.

II. Mission Statement and Objective

Mission Statement:

- Design Low-Earth-Orbit Solar Power Satellite ‘Redstone-1’ operation concept which receives solar power via solar panel and transmit energy to designated ground plant.

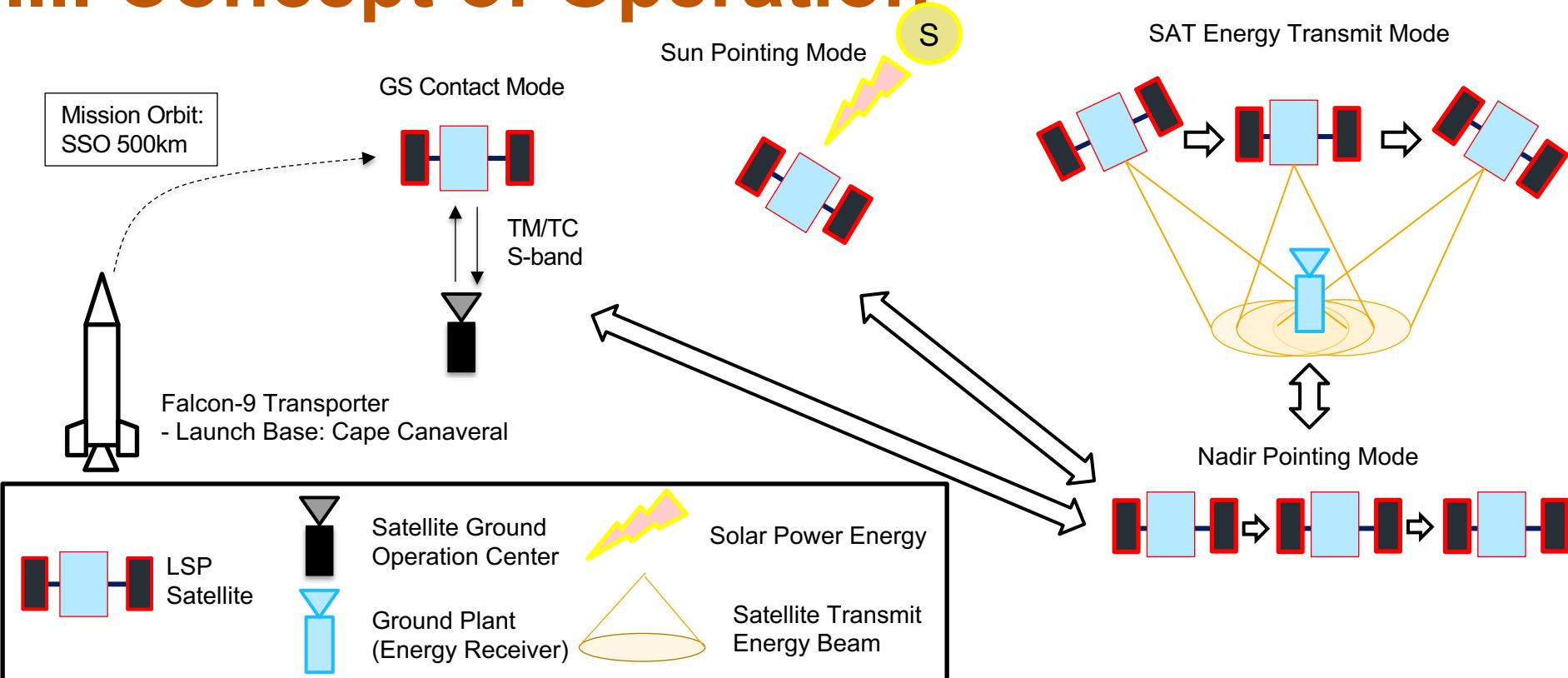
Primary Mission Objectives

- Satellite shall receive solar energy from sun more than [1,TBD] kJ per [1, TBD] orbit .
- Satellite shall transmit stored solar energy to [3, TBD] ground stations [1,TBD]kJ each per [1, TBD]week.

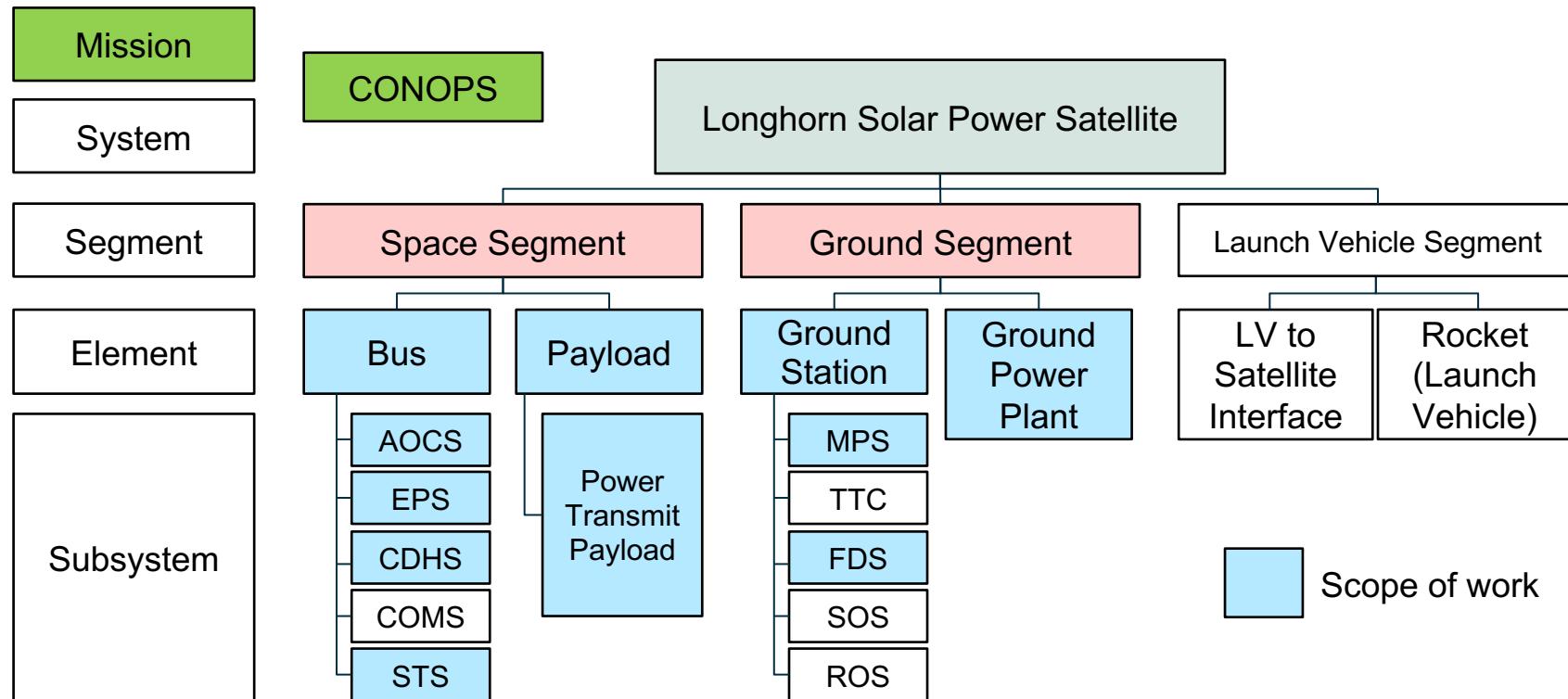
Secondary Mission Objective

- Satellite can transmit stored solar energy to cislunar orbit satellite or other satellites. [Concept Study]
- Propose constellation strategy for continuous solar power reception and transmission. [Concept Study]

III. Concept of Operation



IV. System Architecture, SOW



V. Work Breakdown

Orbit Analysis

Related to:

Mission

CONOPS

Description:

- Design Orbit which complies mission req and CONOPS
- Generate orbit design details (Contact Time, Slant range, Elevation Angle, Beta Angle, Eclipse Time)

Energy Transmission Analysis

Related to:

Power
Transmit
Payload

Ground
Power
Plant

Description

- Design Power transmission Payload and Ground Power Plant to match the mission requirement and given orbit environment
- Generate Energy Requirement

Solar Panel and Battery Analysis

Related to:

EPS

STS

Description

- Design Solar Panel and Battery which complies the Power Budget Requirement from Energy Transmission Payload
- Generate satellite physical characteristics
- Design CAD model

Mission Operation Analysis

Related to:

AOCS

CDHS

MPS

FDS

Description

- Design operation concept from given orbit, payload and solar panel and battery to comply mission and CONOPS
- Validate the operation concept generated
- Proceed Satellite operation simulation

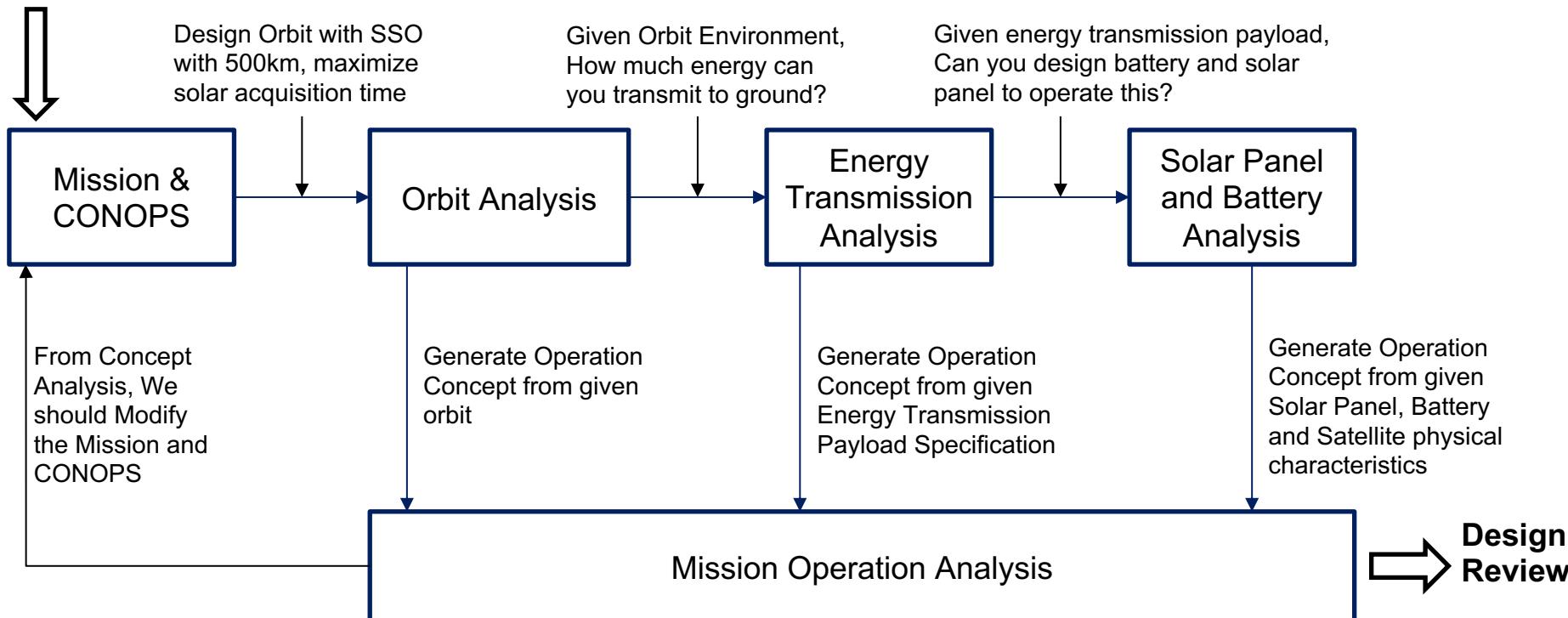
V. Work Flowchart (N-2 Chart)

Mission	Mission Statement Mission Requirement				
* Check CONOPS matches Mission * Design Advanced CONOPS	CONOPS	Orbit Requirement * SSO / 500km * Dawn-Dusk * Contact Time	Power Trans. Req. * Shall transmit meaningful power to ground	EPS Requirement * Shall store enough energy for 3 times contact per day	Mission Operation Requirement
	Orbit Analysis	Contact Time Slant Range Elevation Angle	Beta Angle Eclipse Time	Mission Orbit Epoch Time Duration	
	Request to Change Orbit	Energy Transmission Analysis	Payload Power Requirement * Allocate 300kWh per single charge	Operation Requirement for Energy Transmission	
	Request to Change Orbit	Payload Power Requirement Compliance	Solar Panel & Battery Analysis	Operation Requirement for Solar Power Charging	
	Operation Concept Compliance	Validation & Verification	Validation & Verification	Validation & Verification	Mission Operation Analysis

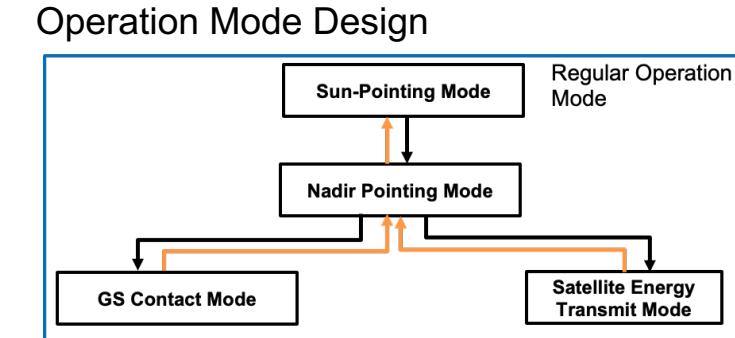
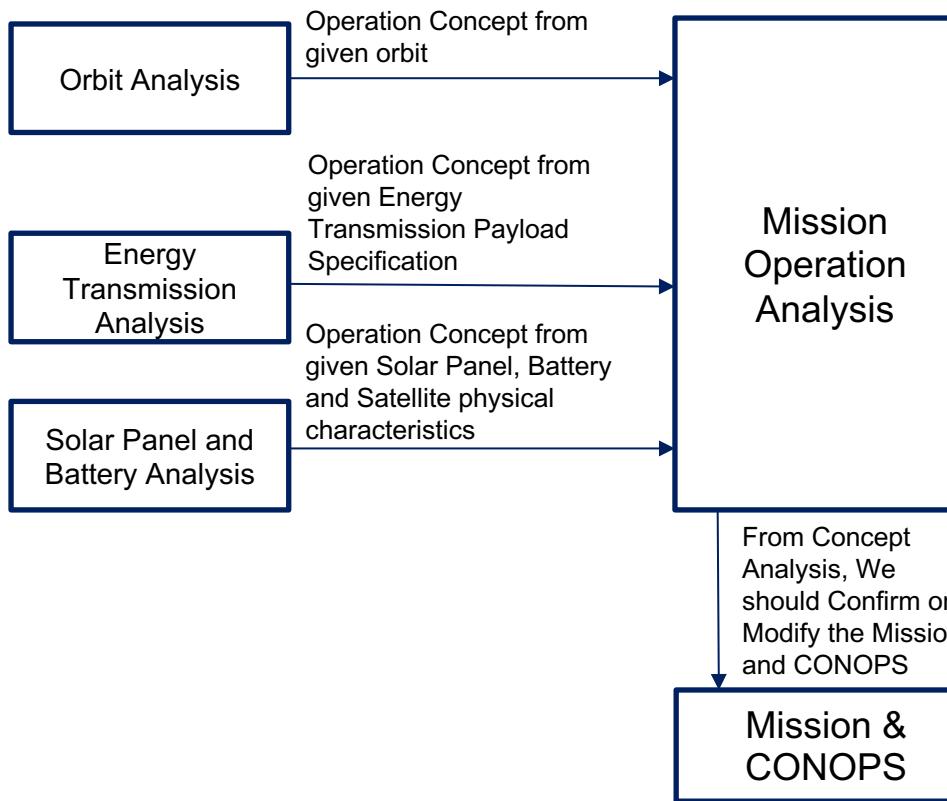
- Mission and CONOPS are mostly related to orbit analysis. Orbit
- Energy Transmission and Solar Panel/Battery Analysis receives orbit environment and generate payload and EPS specification for each
- Mission operation part receives operation requirements and generate simulation results, check whether CONOPS and mission is possible

VI. Interface Management & Decision Process

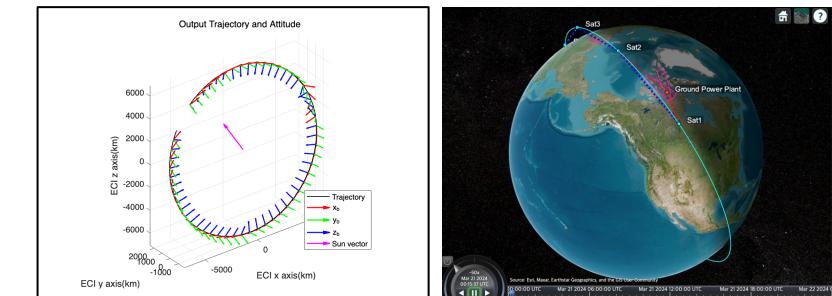
Top Requirements



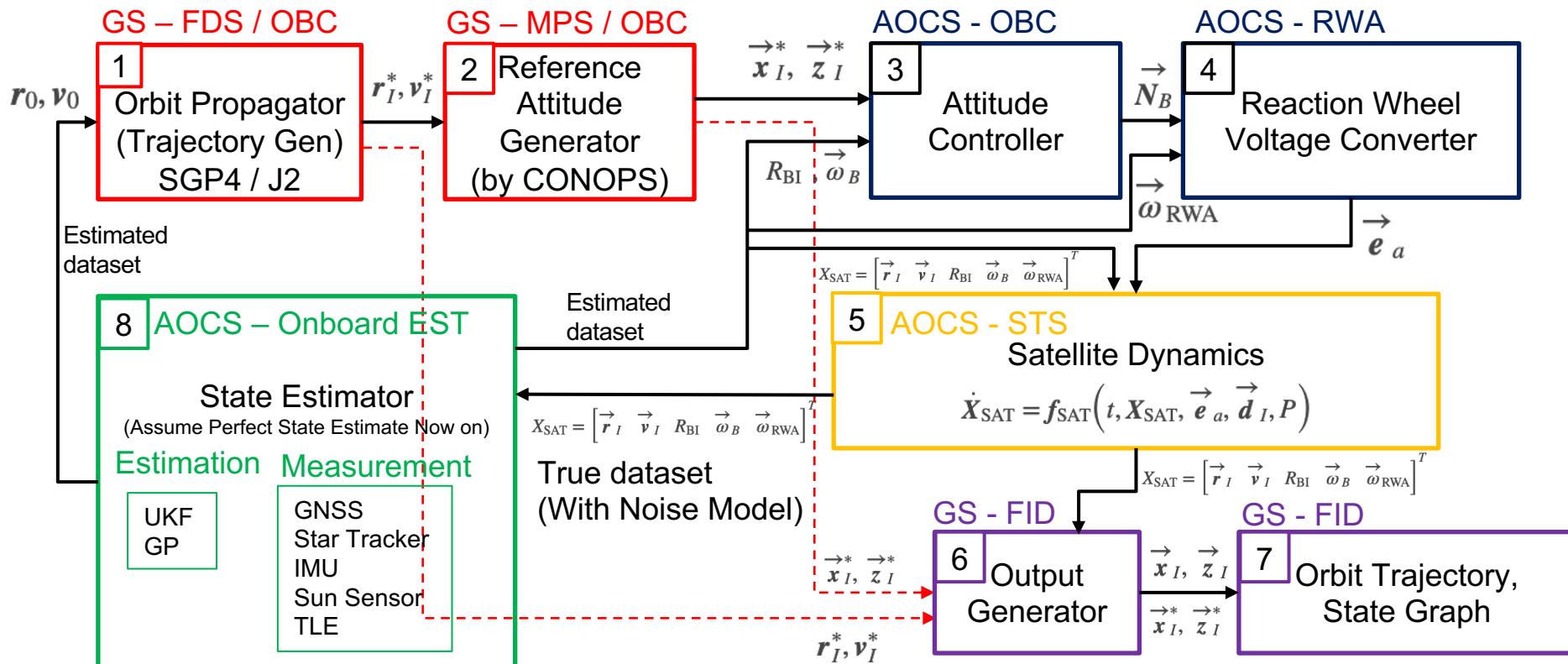
VII. Mission Operation Analysis – Introduction



Data plot by graph and visualization method



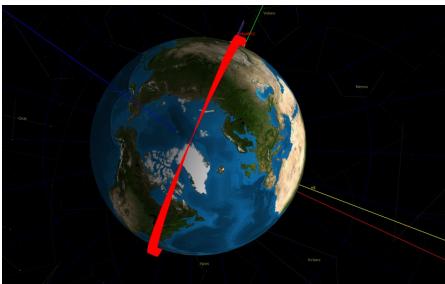
Mission Operation Analysis – SAT Controller



Mission Operation Analysis: from Orbit Analysis

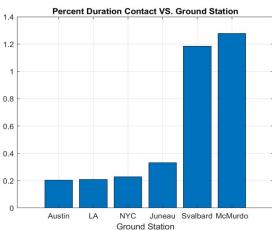
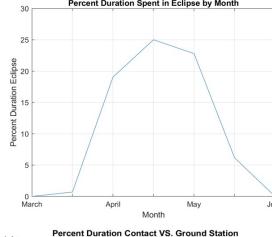
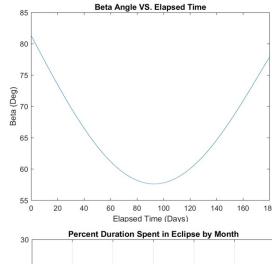
From Orbit Analysis:

Dawn Dusk Orbit has been proposed on 500km orbit



Elements	
SMA	6857 km
ECC	0.0009999
INC	97.319999 deg
RAAN	90 deg
AOP	90.000000 deg
TA	99.887749 deg

Epoch Format	UTC/Greg
Epoch	19 Mar 2024
Coordinate System	Earth/MJ2
State Type	Keplerian



Task Activities for Mission Operation:

TA#1: Beta Angle and Sun Pointing Mode Validation

- Confirm whether Beta Angle for given elapsed days (0, 30, 60, 90): 90 ~ 180 days are symmetric
- Check whether satellite can align -y axis to sun vector in given elapsed days without significant attitude maneuver

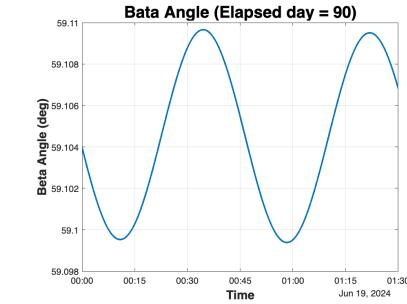
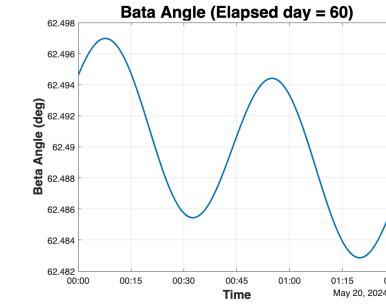
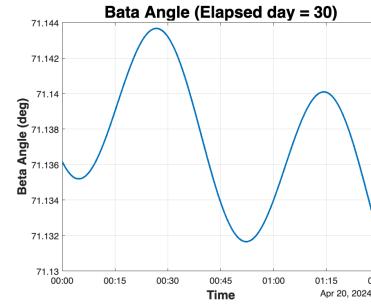
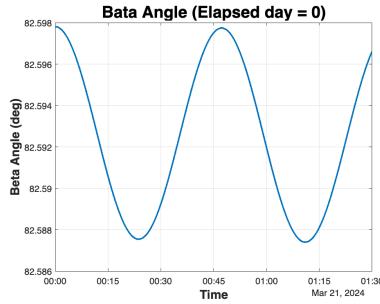
TA#2: Contact and Energy Transmission Mode Validation

- Confirm whether satellite can maneuver adequately to fully utilize 100 ~ 200 seconds contact time.
- Check whether satellite can transit operation mode in 1 orbit, from sun-pointing mode to power transmission mode, and return to sun-pointing mode

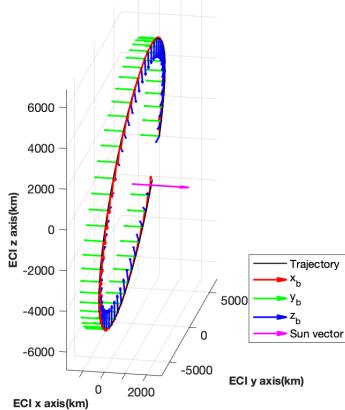
TA#3: Constellation Concept Study

- From Orbit Analysis, we have found Contact time and contact opportunity can be significantly larger for high latitude area such as Svalbard or McMurdo
- We can proceed constellation concept study for these areas for continuous power transmission

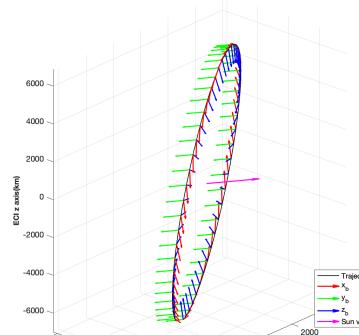
Case Study 1-1 : Dawn-Dusk Orbit & Beta Angle



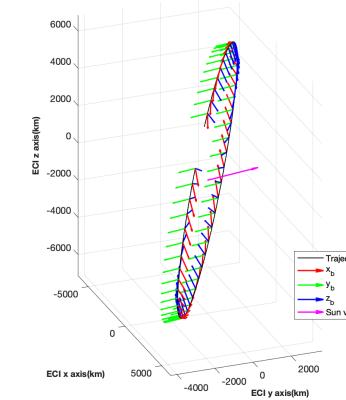
Trajectory and Attitude (Elapsed day = 0)



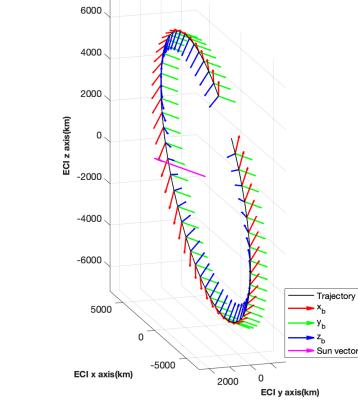
Trajectory and Attitude (Elapsed day = 30)



Trajectory and Attitude (Elapsed day = 60)

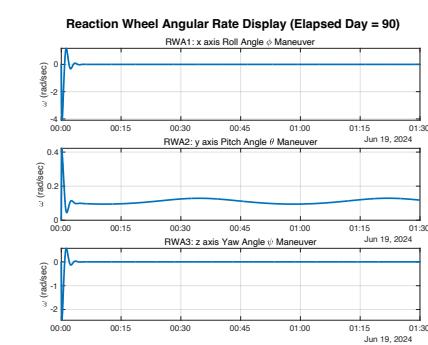
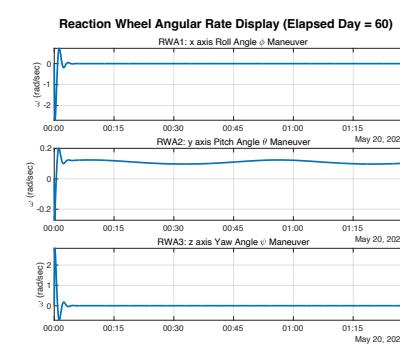
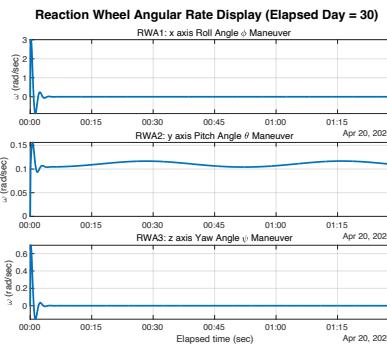
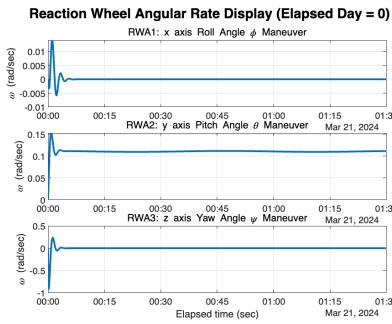
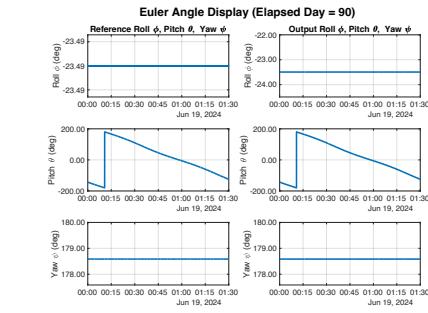
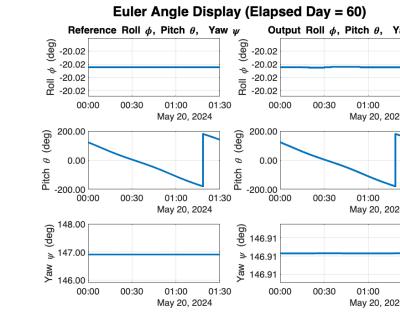
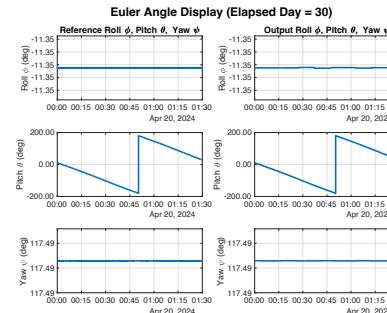
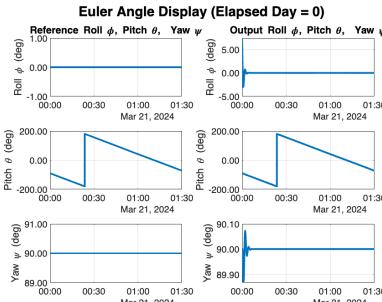


Trajectory and Attitude (Elapsed day = 90)



- Given MATLAB simulation matches the beta angle expressed by GMAT

Case Study 1-2 : Sun Pointing Mode Analysis



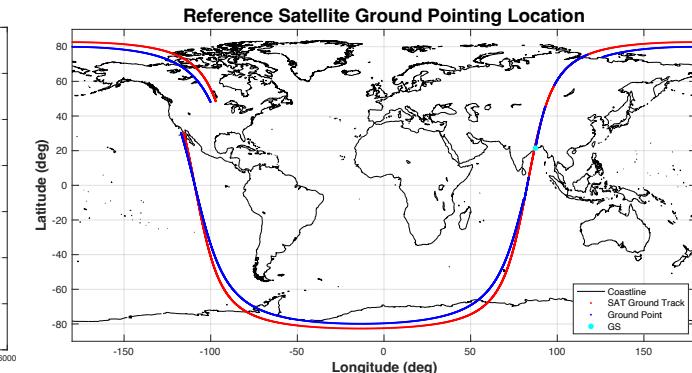
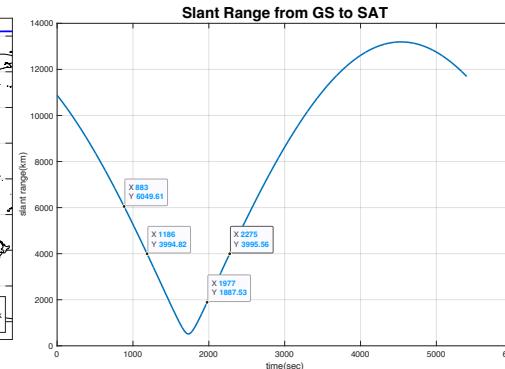
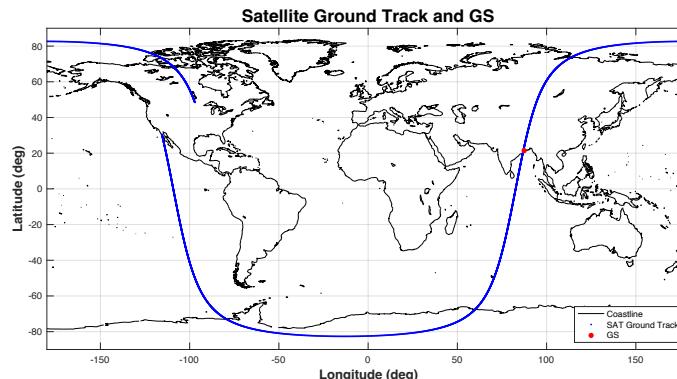
- Initially Nadir Pointing Mode, changed to Sun Pointing Mode
- No gimbal lock (roll = 90 deg), Controllable around one sequence

Case Study 1 : Discussion and Conclusion

- **Dawn Dusk Orbit & Beta Angle Analysis Result**
 - We could show GMAT simulation result is identical to MATLAB simulation result of beta angle.
 - We could visualize sun vector and orbit plane for selected day throughout 90 days.
 - From the visualization, we could see the angle between orbit plane and sun vector changes, but remains close to orbit normal vector.
- **Sun Pointing Mode Analysis Result**
 - Mainly roll angle changes for different elapsed date, which reflects different beta angle for each elapsed date.
 - We need around 100 seconds to transit from nadir mode to sun pointing mode for each elapsed day environment.
 - But for every case, the gimbal lock is not occurred.
 - Tracking capability is good after the satellite transits to the sun pointing mode.
- **Overall Result**
 - We could show sun-pointing mode is valid for given satellite and controller specification in given orbit.

Case Study 2 : Energy Transmission Analysis

Simulation Setup:



Orbit and Ground Environment Specification

- Epoch: 06/19/2024 00:00:00 – Elapsed Day: 60 days
- Dawn Dusk orbit 6PM LTAN started 3/21/2024
- Ground Powerplant Location: [21.4284 N, 87.4145 E]
- Simulation Duration: 7200 Seconds

Proposed Command

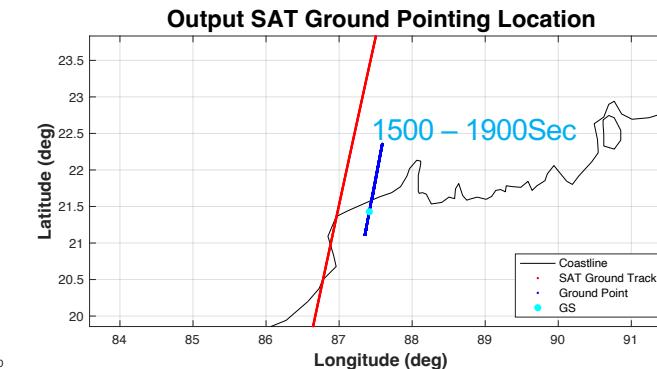
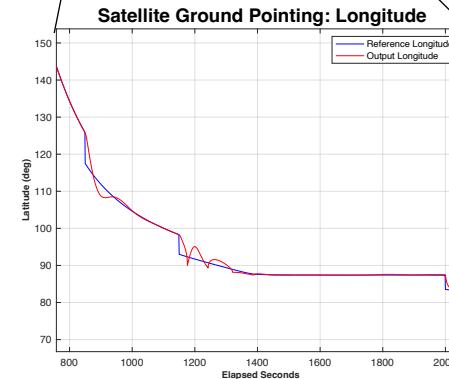
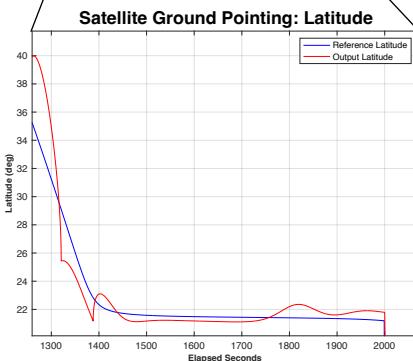
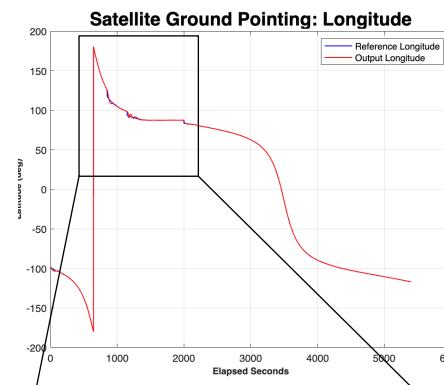
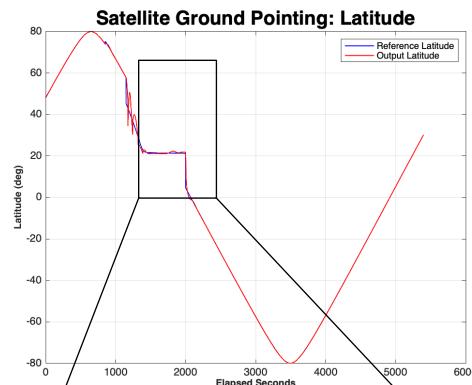
- Start Mode: Nadir Pointing. [1]
- Start – 850 sec: Sun Pointing [3]
- 851 – 1150 sec: Nadir Pointing [1]
- 1151 – 2000 sec: Power Transmission [2]
- 2001 – 2200 sec: Nadir Pointing [1]
- 2201 – end : Sun Pointing [3]

```
% initial operation mode
initial_operation_mode = 1;
% 1: Nadir Pointing Mode
% 2: Energy Transmission Mode
% 3: Sun Pointing Mode
```

```
operation_mode_vec(1:850) = 3;
operation_mode_vec(851:1150) = 1;
operation_mode_vec(1151:2000) = 2;
operation_mode_vec(2001:2200) = 1;
operation_mode_vec(2201:end) = 3;
```

Case Study 2-1 : Pointing Accuracy for Given scenario

Simulation Result 1: Pointing Accuracy

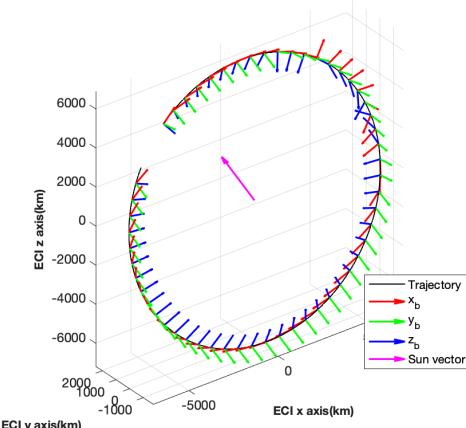


Proposed Command

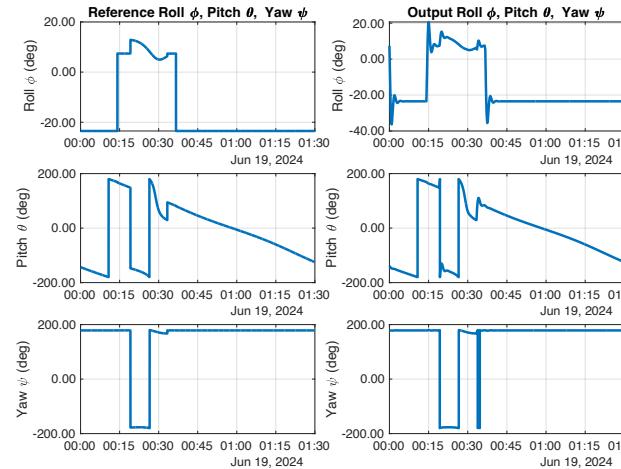
- Start Mode: Nadir Pointing. [1]
- Start – 850 sec: Sun Pointing [3]
- 851 – 1150 sec: Nadir Pointing [1]
- **1151 – 2000 sec: Power Transmission [2]**
- 2001 – 2200 sec: Nadir Pointing [1]
- 2201 – end : Sun Pointing [3]

Case Study 2-2 : Control Capability for Given scenario

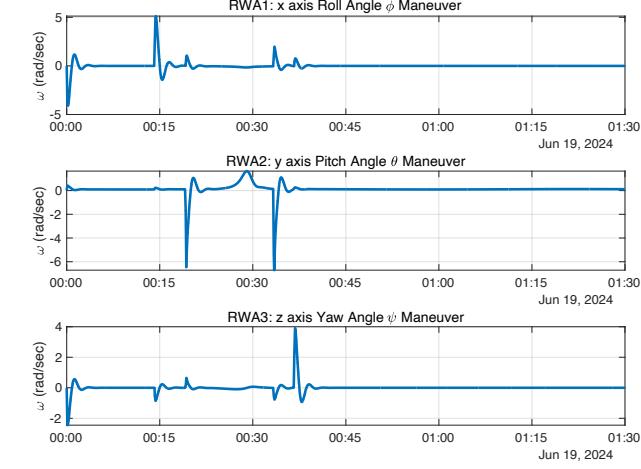
Output Trajectory and Attitude



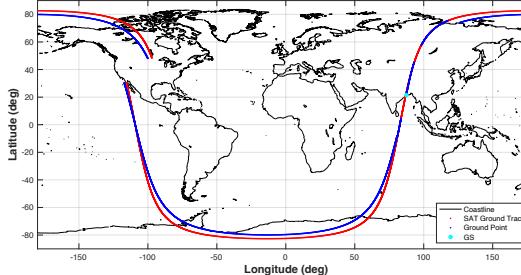
Euler Angle Display



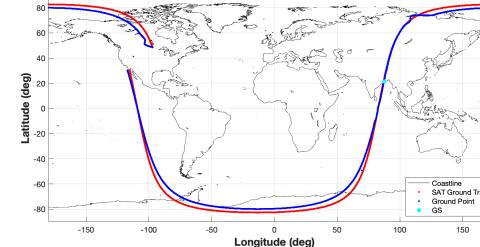
Reaction Wheel Angular Rate Display



Reference Satellite Ground Pointing Location



Output SAT Ground Pointing Location



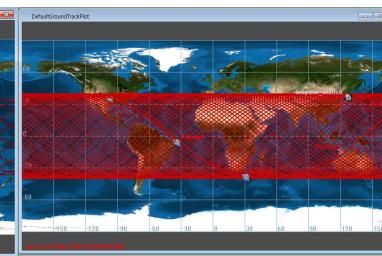
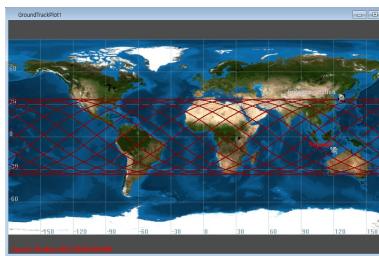
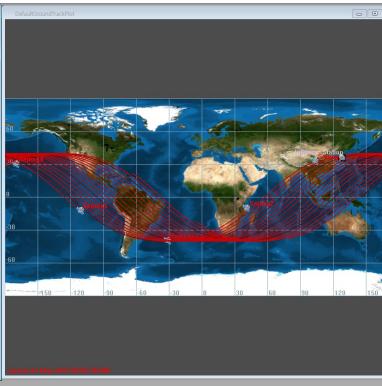
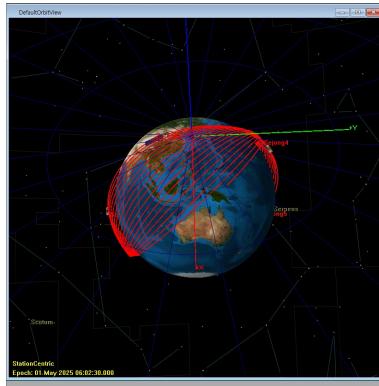
Command

- Start Mode: Nadir Pointing. [1]
- 00:00:00 – 00:14:10 Sun Pointing [3]
- 00:14:11 – 00:19:10 Nadir Pointing [1]
- 00:19:11 – 00:33:20 Power Transmission [2]
- 00:33:21 – 00:36:40 Nadir Pointing [1]
- 00:36:41 – end : Sun Pointing [3]

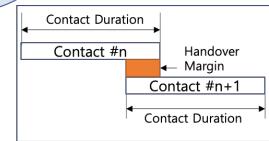
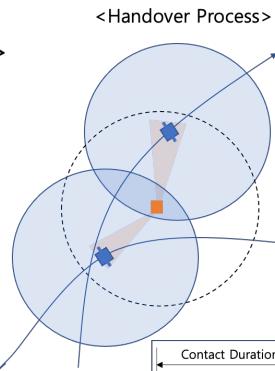
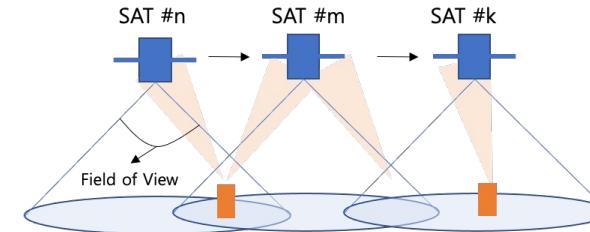
Case Study 2 : Discussion and Conclusion

- **Pointing Accuracy Analysis Result**
 - Achieved +/- 0.5 deg pointing error for given of satellite body and controller specification
 - Remaining pointing error can be compensated by sophisticated beam maneuver process
 - Across track error is significantly lower than along track error. Therefore we should concentrate how to improve accuracy for along track error.
- **Control capability Analysis Result**
 - Achieved <5rad/s rotational rate of reaction wheel for all three axis for given energy transmission scenario. The tracking performance after stabilization of mode is good for all 3 modes.
 - Roll angle remains under +/- 50deg for the given scenario, preventing gimbal lock.
 - But, the overshoot in transferring the control mode is large. We should adjust controller gain for lowering the overshoot.
 - Yaw angle and Roll angle does not have significant change, but pitch angle changes continuously for a 3 modes. We should design pitch angle maneuver and control more carefully.
- **Overall Result**
 - In given physical specification of satellite and operation scenario, satellite could both achieve pointing accuracy and control capability.
 - But this specification will be changed, and we have to test simulations in various scenario.

Case Study 3 : Constellation Concept Analysis



<Satellite Cluster Operation Cluster Operation Concept>



- From GMAT, we can see operating multiple satellite in. single orbit can make higher density of orbit, and may make continuous contact stream for certain period.
- Therefore, we can do continuous energy transmission CONOPS using this methodology

Case Study 3 - 1 : Continuous Contact

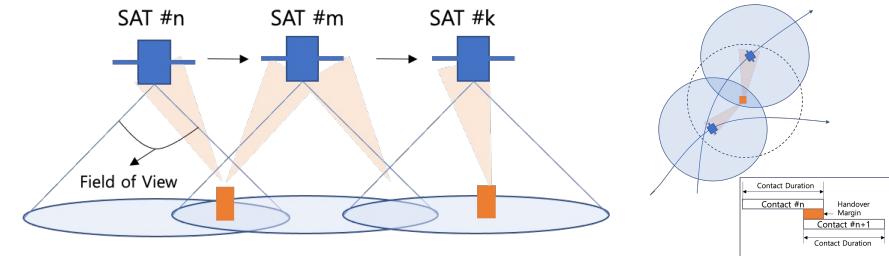
Simulation Parameter Setting

```

startTime = datetime(2024,3,21,0,0,0);
stopTime = startTime + hours(24);
sampleTime = 1; % seconds
sc = satelliteScenario(startTime,stopTime,sampleTime);
% Orbit Settings
semiMajorAxis = 6378000 + 500000; %m
eccentricity = 1e-5;
inclination = 97.4022; %degrees
rightAscensionOfAscendingNode = 90; %degrees
argumentOfPeriapsis = 0; %degrees
trueAnomaly = 75; % Degrees
% Satellite Constellation Settings
sat1 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat1");
trueAnomaly = 60; % Allocate Different True Anomaly
sat2 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat2");
trueAnomaly = 45; % Allocate Different True Anomaly
sat3 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat3");
trueAnomaly = 30; % Allocate Different True Anomaly
sat4 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat4");
trueAnomaly = 15; % Allocate Different True Anomaly
sat5 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat5");
trueAnomaly = 0; % Allocate Different True Anomaly
sat6 = satellite(sc,semiMajorAxis,eccentricity,inclination,rightAscensionOfAscendingNode,... 
    argumentOfPeriapsis,trueAnomaly,"OrbitPropagator","two-body-keplerian","Name","Sat6");

% Ground Power Plant Site
name = "Ground Power Plant";
minElevationAngle = 15; % degrees
geoSite = groundStation(sc, ...
    "Name",name, ...
    "Latitude", 30.2672, ...
    "Longitude", -97.7431, ...
    "Altitude", 0, ...
    "MinElevationAngle",minElevationAngle);
    
```

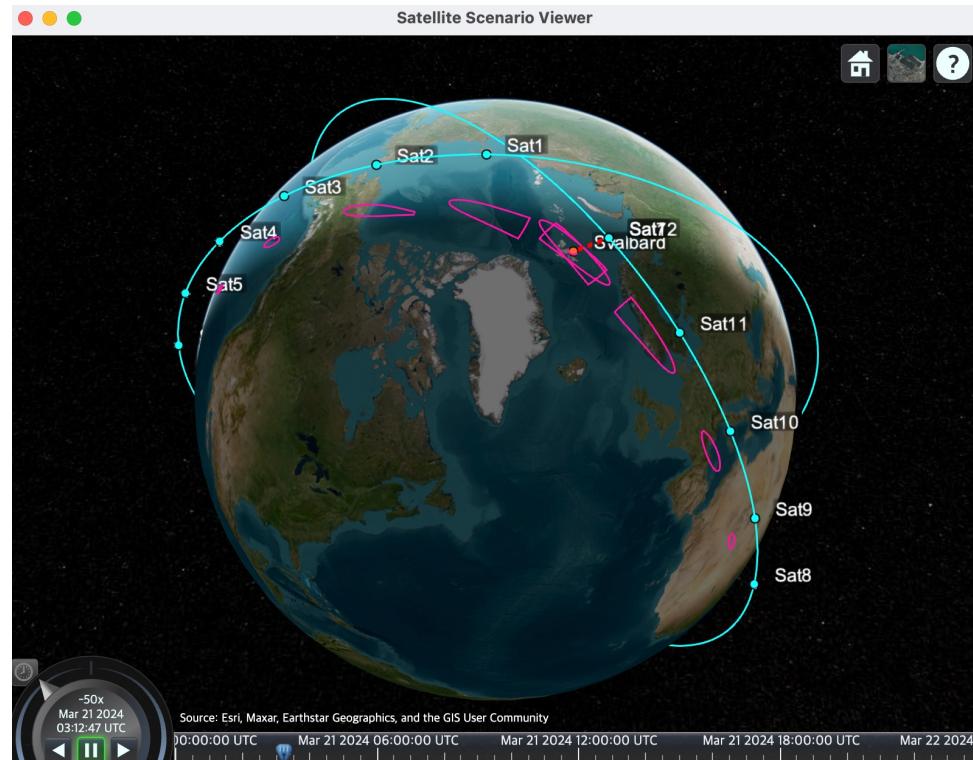
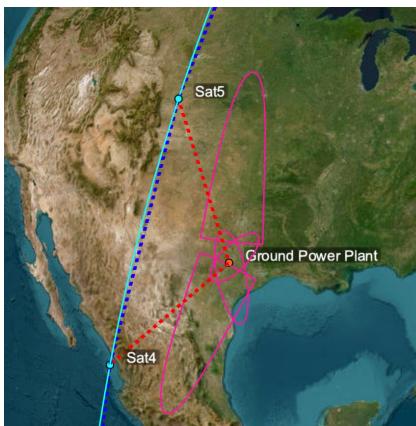
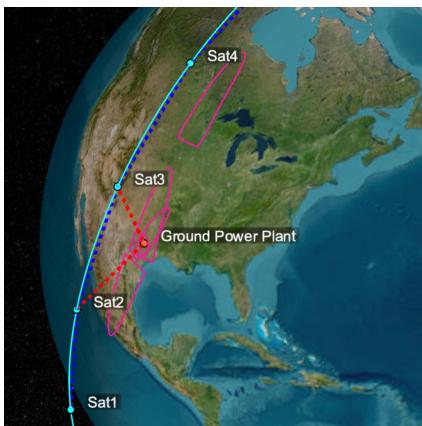
Simulation Result



Source	Target	StartTime	EndTime	Duration	Contact_Margin
SAT 1	AUSTIN	21-Mar-2024 12:53:28	21-Mar-2024 12:59:24	356	
SAT 2	AUSTIN	21-Mar-2024 12:57:24	21-Mar-2024 13:03:16	352	0:02:00
SAT 3	AUSTIN	21-Mar-2024 13:01:20	21-Mar-2024 13:07:07	347	0:01:56
SAT 4	AUSTIN	21-Mar-2024 13:05:17	21-Mar-2024 13:10:56	339	0:01:50
SAT 5	AUSTIN	21-Mar-2024 13:09:16	21-Mar-2024 13:14:45	329	0:01:40
SAT 6	AUSTIN	21-Mar-2024 13:13:15	21-Mar-2024 13:18:32	317	0:01:30

- **Contact Margin = SAT (N) End time = SAT (N+1) Start time**
- We can see continuous contact for certain incidence for 15 degree True Anomaly Difference

Case Study 3 - 2 : Simulation Visualization



Case Study 3 : Conclusion and Discussion

- **Continuous contact analysis**
 - We could generate contact chart for given scenario from each satellite to each ground stations
 - Allocating satellites for 15 degrees step for true anomaly in same orbit can make continuous contact for certain scenario.
 - In minimum elevation 15 degrees, satellite have up to 300 – 350 seconds contact time. And contact margin is around 100 seconds.
 - Ground station in higher latitude can make more contact per day than ground station in lower latitude.
- **Simulation Visualization result**
 - We could visualize the contact sequence for multiple viewpoints.
 - We could visualize the inter-satellite connection availability for given mission.
 - But adding multiple satellite and multiple ground plants will have more calculation cost and processing time.
 - We could visualize satellites operating in multiple orbits with different RAAN. Which turnout to be good approach for continuous contact in high latitude area.
- **Overall Result**
 - We could show both continuous contact simulation and visualization process in this case study.
 - We should simulate in multiple scenario with various environments. Also design more detailed constellation concept.

VIII. Conclusion and Future Study Topic

- The concept studies for operational environments generated from other sub-topic (Orbit, Energy Transmission, Solar Energy Acquisition) is presented.
- For all concept studies, the operation is successful for given satellite specification and orbit.
- For the pointing accuracy and control capability analysis, we can design better satellite design for lowering the overshoot and response time.
- We could model the constellation concept and contact chart for analyze it, so we can proceed detailed research on this concept.
- In the future, we will quantify how much energy is received and how much energy is transmitted from satellite by given mission scenario.
- Also, we will proposed detailed constellation concept, both for continuous energy transmission to inter-satellite charge technique and transmitting energy to cislunar regime.



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