

[illegible]

The diagram illustrates a ROS (Robot Operating System) architecture. A central box labeled 'roscore' is connected to several other components. On the left, a dashed box contains three robot nodes: '/robot1', '/robot2', and '/robotN'. On the right, a solid box labeled 'Központi PC' contains three control nodes: '/robot1 vezérlő node-ok', '/robot2 vezérlő node-ok', and '/robotN vezérlő node-ok'. Red arrows point from the robot nodes to 'roscore', and blue arrows point from 'roscore' to the control nodes. Ellipses (...) indicate additional robots and control nodes.