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# Homework

Stochastic Models and Adaptive Algorithms

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# 1 Linear regression

## 1.1 Function approximation with least squares

### Ordinary least-squares

At first, a noisy sample of  $x \rightarrow y$  is generated. Let  $[\Phi]_{ij} = f_j(x_i)$  be the transformed input vector and  $\mathbf{y}$  the output, where  $f_j$  is a basis function. We have to find the  $\theta$  parameter vector, for which  $\Phi \theta = \mathbf{y}$ . From this the  $\Phi(x)$  matrix can be generated after selecting a suitable  $f$ . A number of these were tried, and the best one seemed to be the polynomial one, that is  $f_i(x) = x^{i-1}$ . As a parameter,  $d = 10$  was used. The  $\Phi$  matrix of the sampled inputs and of the LS estimate are the same, so the function is evaluated at the same  $x$  values.

For the QR decomposition problem, the "economic" mode of scipy's `qr` function is used, then  $\hat{\theta}$  is found with  $\hat{\theta} = \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}$ . Because the pseudoinverse of a matrix is unique, this method gives the same result as the previous one.

The results are shown in figure [1a](#).

### Recursive least-squares

The equation for  $\hat{\theta}$  can be reformulated in the following way:

$$\hat{\theta} = \underbrace{\left[ \sum_{i=1}^n \varphi \varphi^T \right]^{-1}}_{\Psi_n} \underbrace{\sum_{i=1}^n y_i \varphi_i}_{z_n}. \quad (1)$$

Now we have an update rule for both  $\Psi_{n+1} = (\Psi + \varphi_{n+1} \varphi_{n+1}^T)^{-1}$ , and  $z_{n+1} = z_n + \varphi_{n+1} y_{n+1}$ . Both  $\Psi_0$  and  $z_0$  are set to zero. Also, in the code  $\theta_n$  is calculated only when plotted for speed.

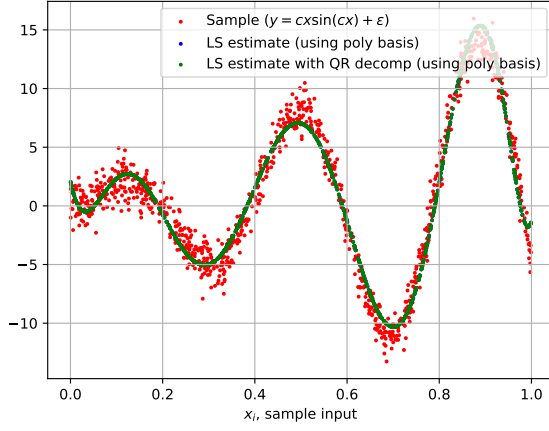
The resulting plots are shown in figure [1c](#)., taken at  $n \in [25, 50, 75, 100]$ .

### Least-norm problem

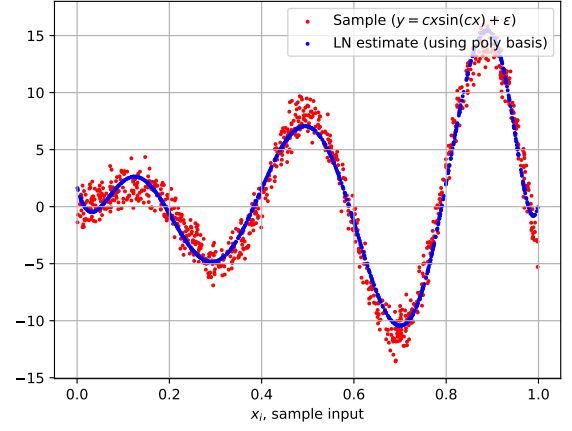
Now let's make  $d > n$ , which makes  $\Phi$  fat, specifically  $n = 100$  and  $d = 200$ . We make the assumption that  $\Phi$  is still full-rank. The solution is the same, except we are going to use singular value decomposition (SVD) for the pseudoinverse of  $\Phi$ .

The SVD is calculated like this:  $\Phi_{d \times n} = \mathbf{U}_{d \times d} \Sigma_{d \times n} \mathbf{V}_{n \times n}^T$ . Let's denote the matrix of column vectors of the normalized eigen-vectors of matrix  $\Phi$  by  $\text{eig}(\Phi)$ . Let's denote the eigenvalues by  $\text{eigval}(\Phi)$ . Then,  $\mathbf{U} = \text{eig}(\Phi \Phi^T)$ ,  $\mathbf{V} = \text{eig}(\Phi^T \Phi)$  and  $\Sigma = \text{diag}(\text{eigval}(\Phi \Phi^T))_{d \times n}$ . Then, the pseudoinverse is  $\Phi^+ = \mathbf{V} \Sigma^+ \mathbf{U}^T$ . For  $\Sigma^+$ , we take the inverse of the non-zero elements of  $\Sigma$ , and add zeros such that it has the shape of  $d \times n$ .

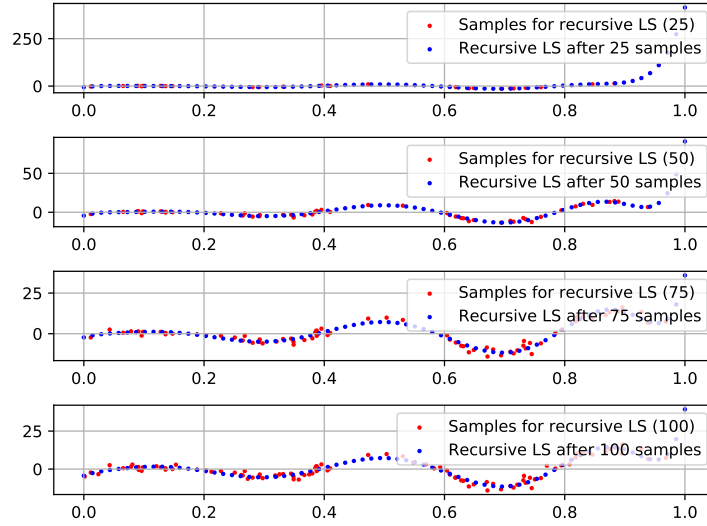
The resulting plots are shown in figure 1b.



(a) Least-squares estimate for thin  $\Phi$



(b) Least-norm estimate for fat  $\Phi$



(c) Recursive least-squares

Figure 1: Experiments with ordinary least-squares

## 1.2 Approximating auto-regressive series

A recursive time-series is generated from the give equation:  $y_t = a y_{t-1} + b y_{t-2} + \epsilon_t$ . Let's calculate the least-squares estimate using  $\Phi_{i=t} = \varphi_t = [y_{t-1}, y_{t-2}]$ , then  $\hat{\theta} = \Phi^+ y$ .

The time plots can be seen on figure 2a.

Now let's calculate the inverse of the covariance matrix:  $\Gamma_n = \frac{1}{n} \Phi^T \Phi$ . Now define  $\Delta\theta := (\theta - \hat{\theta}_n)$ . The confidence ellipsoid is given by

$$\Delta\theta^T \Gamma_n \Delta\theta \leq \frac{q \hat{\sigma}_n^2}{n}, \quad (2)$$

where  $q$  is calculated from the inverse of the cumulative  $\chi^2$  distribution function given the  $p$  probabilities ( $q = F(p)_{\chi^2(d)}^{-1}$ ). This means that if the optimal  $\theta^*$  is at most  $\Delta\theta$  distance from  $\hat{\theta}$  with probability  $p$ .

Now we assume that  $\hat{\sigma}_n = 1$ , and let  $\Gamma_{ij}/n = [\mathbf{\Gamma}_n]_{ij}$ . Then we have an equation that outputs an ellipse for a  $p$  probability. Written out:

$$\Delta\theta_1^2 \Gamma_{11} + 2 \Delta\theta_1 \Delta\theta_2 \Gamma_{12} + \Delta\theta_2^2 \Gamma_{22} = q. \quad (3)$$

For the plotting, this equation is transformed so that the axis distances and the rotation angle is known with the function `ellipse_transform[1]`.

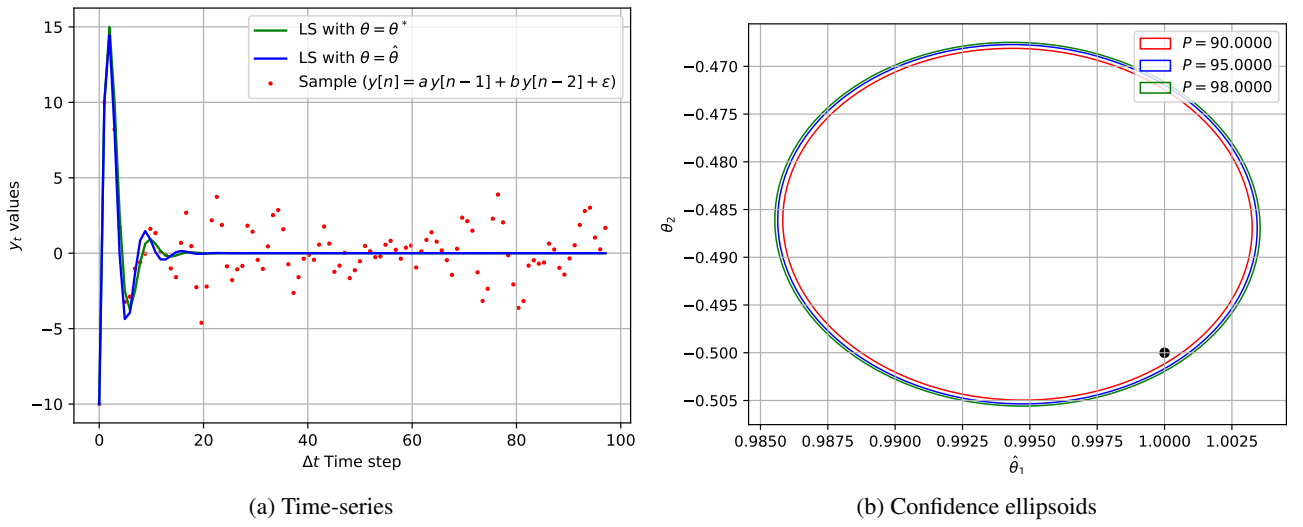


Figure 2: Experiments with auto-regressive series

## 2 Kernel methods

### **3 Reinforcement learning**

## References

- [1] Ellipse equation: [https://www.maa.org/external\\_archive/joma/Volume8/Kalman/General.html#:~:text=Applying%20the%20methods%20of%20%E2%8C%99%BD,rotated%20through%20an%20angle%20%E2%8C%B1%20.&text=which%20is%20in%20the%20form,with%20A%20and%20C%20positive.](https://www.maa.org/external_archive/joma/Volume8/Kalman/General.html#:~:text=Applying%20the%20methods%20of%20%E2%8C%99%BD,rotated%20through%20an%20angle%20%E2%8C%B1%20.&text=which%20is%20in%20the%20form,with%20A%20and%20C%20positive.)