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# Homework

Stochastic Models and Adaptive Algorithms

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# 1 Linear regression

## 1.1 Function approximation with least squares

### Ordinary least-squares

At first, a noisy sample of  $x \rightarrow y$  is generated. Let  $[\Phi]_{ij} = f_j(x_i)$  be the transformed input vector and  $\mathbf{y}$  the output, where  $f_j$  is a basis function. We have to find the  $\theta$  parameter vector, for which  $\Phi \theta = \mathbf{y}$ . From this the  $\Phi(x)$  matrix can be generated after selecting a suitable  $f$ . A number of these were tried, and the best one seemed to be the polynomial one, that is  $f_i(x) = x^{i-1}$ . As a parameter,  $d = 10$  was used. The  $\Phi$  matrix of the sampled inputs and of the LS estimate are the same, so the function is evaluated at the same  $x$  values.

For the QR decomposition problem, the "economic" mode of scipy's `qr` function is used, then  $\hat{\theta}$  is found with  $\hat{\theta} = \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}$ . Because the pseudoinverse of a matrix is unique, this method gives the same result as the previous one.

The results are shown in figure [1a](#).

### Recursive least-squares

The equation for  $\hat{\theta}$  can be reformulated in the following way:

$$\hat{\theta} = \underbrace{\left[ \sum_{i=1}^n \varphi \varphi^T \right]}_{\Psi_n}^{-1} \underbrace{\sum_{i=1}^n y_i \varphi_i}_{z_n}. \quad (1)$$

Now we have an update rule for both  $\Psi_{n+1} = (\Psi + \varphi_{n+1} \varphi_{n+1}^T)^{-1}$ , and  $z_{n+1} = z_n + \varphi_{n+1} y_{n+1}$ . Both  $\Psi_0$  and  $z_0$  are set to zero. Also, in the code  $\theta_n$  is calculated only when plotted for speed.

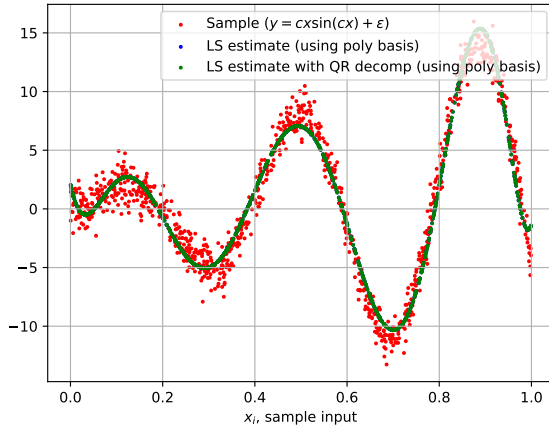
The resulting plots are shown in figure [1c](#)., taken at  $n \in [25, 50, 75, 100]$ .

### Least-norm problem

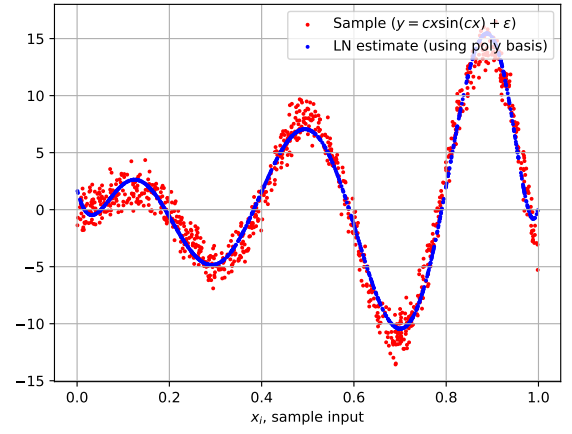
Now let's make  $d > n$ , which makes  $\Phi$  fat, specifically  $n = 100$  and  $d = 200$ . We make the assumption that  $\Phi$  is still full-rank. The solution is the same, except we are going to use singular value decomposition (SVD) for the pseudoinverse of  $\Phi$ .

The SVD is calculated like this:  $\Phi_{d \times n} = \mathbf{U}_{d \times d} \Sigma_{d \times n} \mathbf{V}_{n \times n}^T$ . Let's denote the matrix of column vectors of the normalized eigen-vectors of matrix  $\Phi$  by  $\text{eig}(\Phi)$ . Let's denote the eigenvalues by  $\text{eigval}(\Phi)$ . Then,  $\mathbf{U} = \text{eig}(\Phi \Phi^T)$ ,  $\mathbf{V} = \text{eig}(\Phi^T \Phi)$  and  $\Sigma = \text{diag}(\text{eigval}(\Phi \Phi^T))_{d \times n}$ . Then, the pseudoinverse is  $\Phi^+ = \mathbf{V} \Sigma^+ \mathbf{U}^T$ . For  $\Sigma^+$ , we take the inverse of the non-zero elements of  $\Sigma$ , and add zeros such that it has the shape of  $d \times n$ .

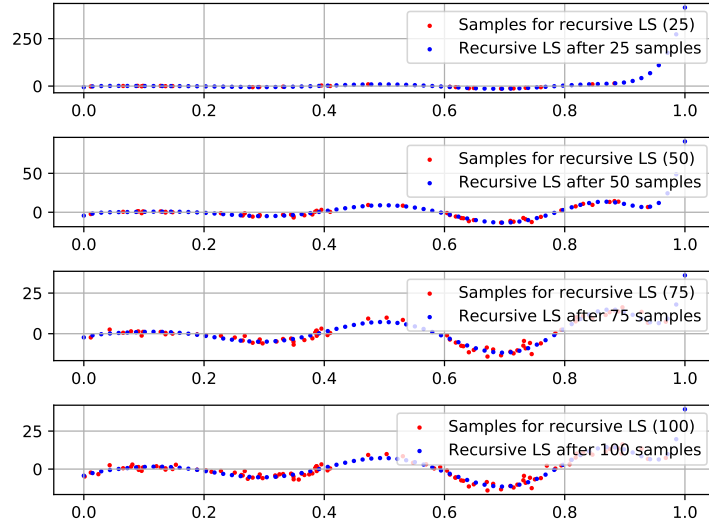
The resulting plots are shown in figure 1b.



(a) Least-squares estimate for thin  $\Phi$



(b) Least-norm estimate for fat  $\Phi$

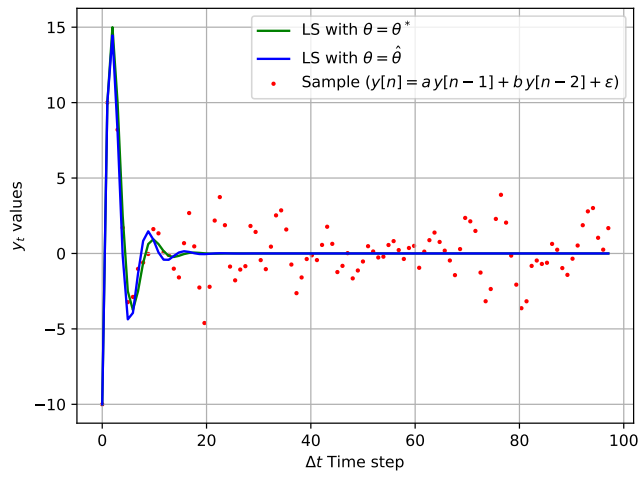


(c) Recursive least-squares

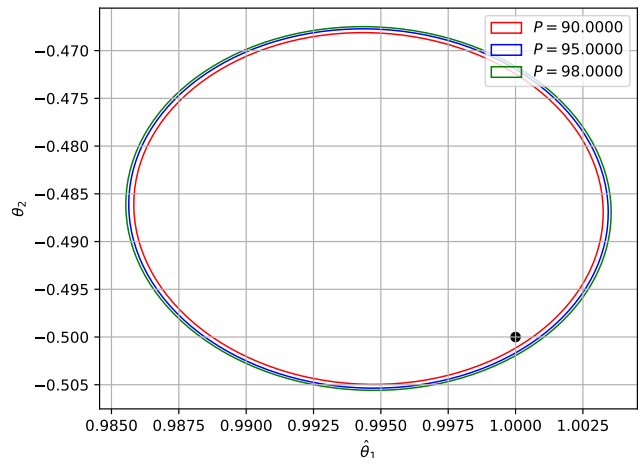
Figure 1: Experiments with ordinary least-squares

## 1.2 Approximating auto-regressive series

A recursive time-series is generated from the give equation:  $y_t = a y_{t-1} + b y_{t-2} + \epsilon_t$ .



(a)



(b)

## 2 Kernel methods

### **3 Reinforcement learning**