
Homework

Stochastic Models and Adaptive Algorithms

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1 Linear regression

1.1 Function approximation with least squares

Ordinary least-squares

At first, a noisy sample of $x \rightarrow y$ is generated. Let $[\Phi]_{ij} = f_j(x_i)$ be the transformed input vector and \mathbf{y} the output, where f_j is a basis function. We have to find the θ parameter vector, for which $\Phi \theta = \mathbf{y}$. From this the $\Phi(x)$ matrix can be generated after selecting a suitable f . A number of these were tried, and the best one seemed to be the polynomial one, that is $f_i(x) = x^{i-1}$. As a parameter, $d = 10$ was used. The Φ matrix of the sampled inputs and of the LS estimate are the same, so the function is evaluated at the same x values.

For the QR decomposition problem, the "economic" mode of scipy's `qr` function is used, then $\hat{\theta}$ is found with $\hat{\theta} = \mathbf{R}^{-1} \mathbf{Q}^T \mathbf{y}$. Because the pseudoinverse of a matrix is unique, this method gives the same result as the previous one.

The results are shown in figure [1a](#).

Recursive least-squares

The equation for $\hat{\theta}$ can be reformulated in the following way:

$$\hat{\theta} = \underbrace{\left[\sum_{i=1}^n \varphi \varphi^T \right]}_{\Psi_n}^{-1} \underbrace{\sum_{i=1}^n y_i \varphi_i}_{z_n}. \quad (1)$$

Now we have an update rule for both Ψ_n and z_n :

$$\Psi_{n+1} = (\Psi + \varphi_{n+1} \varphi_{n+1}^T)^{-1} \quad (2)$$

$$z_{n+1} = z_n + \varphi_{n+1} y_{n+1} \quad (3)$$

Both Ψ_0 and z_0 are set to zero. Also, in the code θ_n is calculated only when plotted for speed.

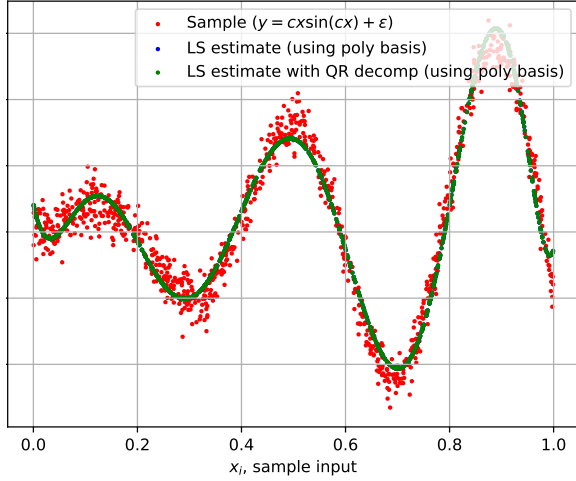
The resulting plots are shown in figure [1b](#)., taken at $n \in [25, 50, 75, 100]$.

Least-norm problem

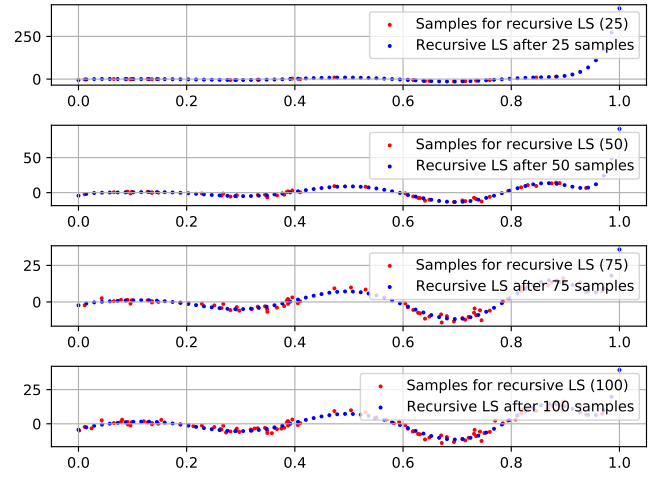
Now let's make $d > n$, which makes Φ fat, specifically $n = 100$ and $d = 200$. We make the assumption that Φ is still full-rank. The solution is the same, except we are going to use singular value decomposition (SVD) for the pseudoinverse of Φ .

The SVD is calculated like this: $\Phi_{d \times n} = \mathbf{U}_{d \times d} \mathbf{\Sigma}_{d \times n} \mathbf{V}_{n \times n}^T$. Let's denote the matrix of column vectors of the normalized eigen-vectors of matrix Φ by $\text{eig}(\Phi)$. Let's denote the eigenvalues by $\text{eigval}(\Phi)$. Then, $\mathbf{U} = \text{eig}(\Phi \Phi^T)$, $\mathbf{V} = \text{eig}(\Phi^T \Phi)$ and $\mathbf{\Sigma} = \text{diag}(\text{eigval}(\Phi \Phi^T))_{d \times n}$. Then, the pseudoinverse is $\Phi^+ = \mathbf{V} \mathbf{\Sigma}^+ \mathbf{U}^T$. For $\mathbf{\Sigma}^+$, we take the inverse of the non-zero elements of $\mathbf{\Sigma}$, and add zeros such that it has the shape of $d \times n$.

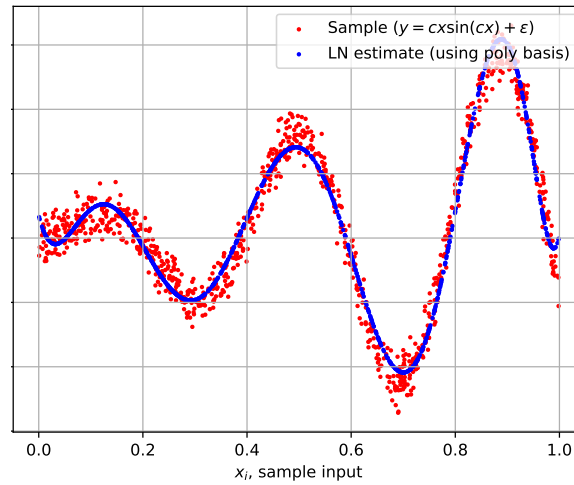
The resulting plots are shown in figure 1c.



(a) Least-squares estimate for thin Φ



(b) Recursive least-squares



(c) Least-norm estimate for fat Φ

Figure 1: Experiments with ordinary least-squares

1.2 Approximating auto-regressive series

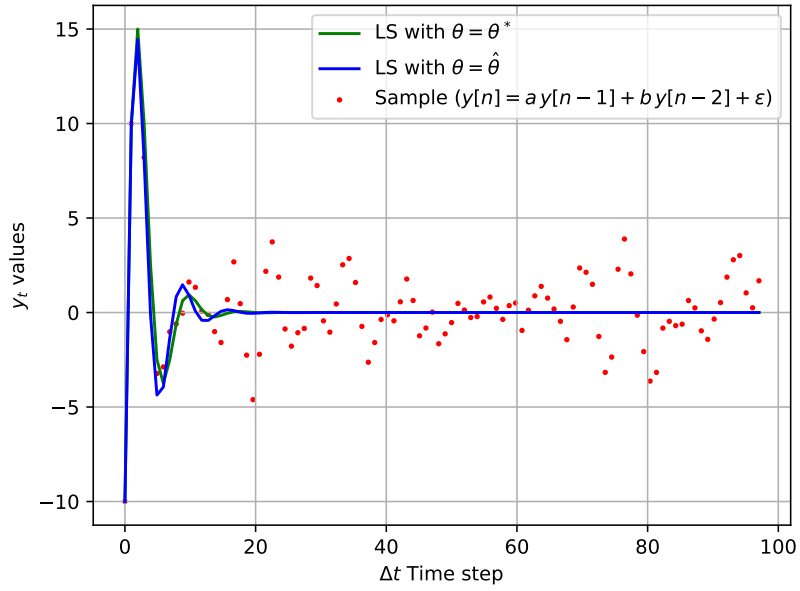


Figure 2

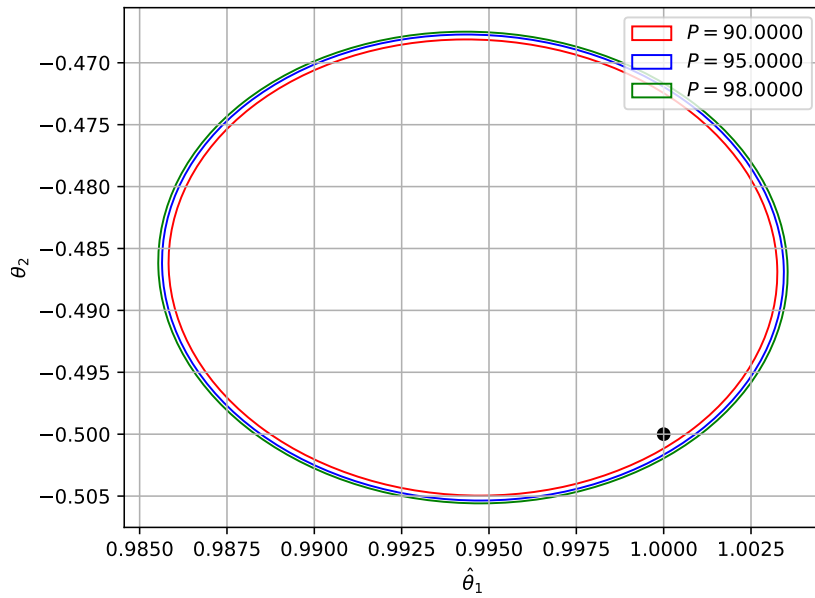


Figure 3

2 Kernel methods

3 Reinforcement learning