# Building Energy Management Internet of Things

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Monday, November 5, 2018





- Introduction
- 2 Background Study
  - Literature
  - Prior Work
  - Challenges
- 3 Subsystem Level Functional Requirements
  - Block Diagram
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  - Design
  - Experimental Activities





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### Introduction

- Building Energy Management Open Source Software (BEMOSS) is an open source Internet of Thing (IoT) software developed under the Department of Energy
- We are tasked with creating a new device that can be controlled through this software over the internet
- We are creating an interface to control a DC motor through BEMOSS
  - Control curtains to regulate interior temperatures
  - Close/ open barriers
- We will also create a machine learning algorithm that can be supported within BEMOSS to reduce power consumption

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# Background Study Literature

- The previous literature that has been released on BEMOSS has been describing what it can do instead of how to do it
- Currently BEMOSS is being used by Virginia Tech and McNeese University to monitor a microgrid

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# Background Study

Prior Work

 The BEMOSS team has thus far successfully incorporated control of the following devices into BEMOSS:

Device Model	Vendor	Protocol
HVAC controller		
CT30 w/ Wi-Fi USNAP module	Radio Thermostat	Wi-Fi
CT50 w/ Wi-Fi USNAP module	Radio Thermostat	Wi-Fi
PL-M1000RTU/M2000RTU	Prolon	Modbus RTU
VC1000/VC2000	Prolon	Modbus RTU
Lighting load controller		
WeMo light switch	Belkin	Wi-Fi
Philips Hue	Philips	Wi-Fi/Ethernet
LMRC-212-U	Wattstopper	BACnet MS/TP
Plug load controller		
WeMo switch	Belkin	Wi-Fi
WeMo insight switch	Belkin	Wi-Fi
LMPL-201	Wattstopper	BACnet MS/TP
Sensor		
LMLS-400	Wattstopper	BACnet MS/TP

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# Background Study Challenges

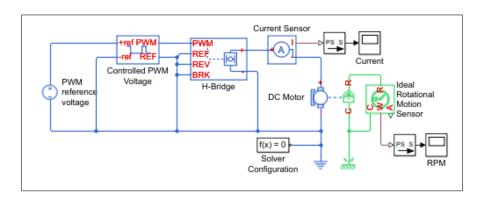
- Create a new BEMOSS supported device
- Implement BEMOSS on a new device, such as a raspberry pi
- Develop and implement an algorithm for BEMOSS to use to efficiently utilize power consumption in a HVAC system

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# Subsystem Level Functional Requirements

Block Diagram



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# Subsystem Level Functional Requirements Specifications

### Motor Requirements

- The simulation must be modeled based on the real system in the lab
- The model must be run by a PWM signal and H-bridge to allow for feedback control later
- The model must produce a power calculation to be used later for the machine learning algorithm

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#### Simulation

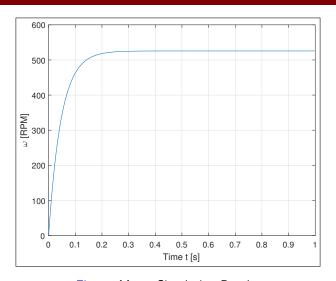


Figure: Motor Simulation Results

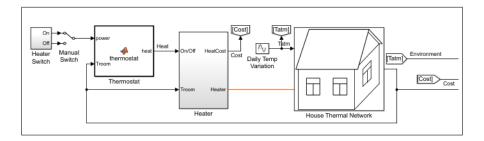


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# Subsystem Level Functional Requirements

Block Diagram



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# Subsystem Level Functional Requirements

#### Specifications

### House Requirements

- The model must give a realistic thermal behavior of a room
- Modeled after work done by a previous work, the system is modeled after the system of equations:

$$\begin{split} \frac{\mathrm{d}\mathbf{T}^{e}}{\mathrm{d}t} &= \begin{bmatrix} \dot{T}_{1}^{e} \\ \dot{T}_{2}^{e} \end{bmatrix} = \begin{bmatrix} -\frac{u_{cc}A_{cc}}{M_{cc}C_{v}} & \frac{Q_{w}\rho_{w}C_{\rho_{w}}}{M_{cc}C_{v}} \\ 0 & -\frac{Q_{w}\rho_{w}C_{pw}+U_{t}A_{t}}{V_{t}\rho_{w}C_{pw}} \end{bmatrix} \begin{bmatrix} T_{1}^{e} \\ T_{2}^{e} \end{bmatrix} + \\ \begin{bmatrix} \frac{U_{cc}A_{cc}}{M_{cc}C_{v}}T_{amb} - \frac{Q_{w}\rho_{w}C_{pw}}{M_{cc}C_{v}}T_{wo} \\ \frac{U_{t}A_{t}}{V_{t}\rho_{w}C_{pw}}T_{amb} + \frac{Q_{w}\rho_{w}C_{pw}}{V_{t}\rho_{w}C_{pw}}T_{wo} \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{15000}{V_{t}\rho_{w}C_{pw}} \end{bmatrix} \chi + \begin{bmatrix} (\frac{\rho_{a}C_{pa}}{M_{cc}C_{v}}Q_{a1} - \frac{U_{cc}A_{cc}}{M_{cc}C_{v}}) \\ 0 \end{bmatrix} \end{split}$$

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Simulation

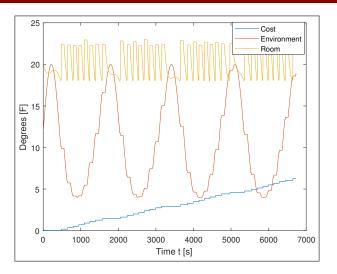


Figure: House Simulation Results using on/off control



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#### Design

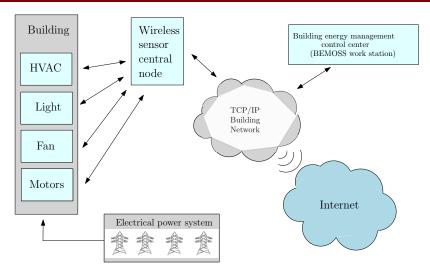


Figure: BEMOSS Network

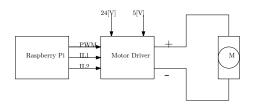


Design

Hardware video demonstration



### Design



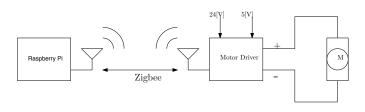


Figure: Raspberry Pi Motor Driver Interface



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#### **Experimental Activities**

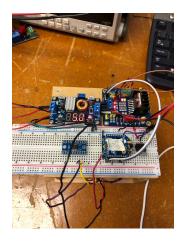


Figure: Remote Circuit 10/27/18

BRADLE?

#### Experimental Activities

- XBee S2C radio module
  - Receive motor direction commands
  - Toggle H-Bridge pins
  - Relay encoder positional data to central node
- L298 H-bridge
  - Supply motor power
  - control motor rotation direction
- Pittman 24v DC motor
  - Close/ open curtains
- Optical encoder
  - Measure and relay positional data
- Buck/Boost Converter
  - Allow for a single power source to remote node
  - Bucks incoming 20V line down to 5V for motor driver, XBee module, and encoder logic

#### **Experimental Activities**

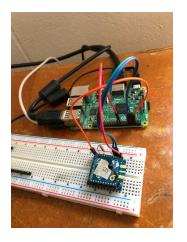


Figure: Raspberry Pi Central Node

#### Experimental Activities

- Raspberry Pi Model 3B
  - Connect to BEMOSS
  - TX pin to transmit commands
  - RX pin to recieve encoder data
- Python Script:
  - Transmit remote AT commands to XBee Module
  - Process encoder data and send stop start command
- XBee S2C radio module
  - Coordinator XBee



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Design

BEMOSS video presentation



#### Experimental Activities

- Future work includes:
  - Utilize logic converters to allow data exchange between the 5V logic H-bridge and encoder to the 3.3v logic XBee module (Pictured in "Remote Circuit 10/27/18)
  - Employ I2C protocol in place of XBee radio communication between nodes (cheaper communication method)
  - Implement feedback control using the motor encoder to control the position and speed of the motor
  - Further energy efficiency by only powering the encoder during times of motor rotation (through use of relays)

### Parts List

Part	Price	Quantity
XBee Interface Board	\$5.31	1
8 Channel Logic Converter	\$5.99	1
3.3 [V] Relay Board	\$11.90	1
Buck/ Boost Converter	\$9.99	1
WeMo Smart Plug	\$ 27.90	2

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### **Deliverables**

#### Division of Labor

- Jordan
  - Develop accurate models using Simscape
  - Algorithm for BEMOSS
  - Machine learning research and implementation
- Reece
  - Interfacing a new device
  - Motor driver configuration
- Robert
  - BEMOSS
  - Implement Reece and Jordan's work



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### **Deliverables**

#### Schedule for Completion

#### Fall Semester 2018

- Working BEMOSS September 2018
- Transmit AT command via XCTU October 2018
- Transmit AT command via python November 2018
- Adaptive HVAC Control Algorithm December 2018

### **Deliverables**

#### Schedule for Completion

### Spring Semester 2019

- Interface new device March 2019
- Implement Machine learning April 2019
- Have device supported by BEMOSS April 2019

# Summary

- Introduce a new supported device within BEMOSS
- Configure BEMOSS to work on a single board computer like raspberry pi
- Develop an algorithm for BEMOSS to determine energy consumption and energy saved

# Discussion

Questions?



# For Further Reading I



#### P. M. Ferreira

Neural networks based predictive control for thermal comfort and energy savings in public buildings/  $\,$ 

Energy and Buildings, 2012



#### 🚺 V. Reppa

A Distributed Architecture for HVAC Sensor Fault Detection and Isolation.

IEEE Transactions on Control Systems Technology, 2015.



### X. Zhang

Deploying IoT devices to make buildings smart: Performance evaluation and deployment experience.

2016 IEEE 3rd World Forum on Internet of Things (WF-IoT)