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HW 2: Proofs Section

- i) Knowing that S follows the form $S^T = -S$, we can conclude that the diagonal entries of S are 0. Thus, S follows the format

$$S = \begin{bmatrix} 0 & s_{12} & \dots & s_{1n} \\ -s_{12} & 0 & & \vdots \\ \vdots & & \ddots & \\ -s_{1n} & \dots & & 0 & s_{(n-1)n} \\ & & & -(s_{(n-1)n}) & 0 \end{bmatrix}.$$

The eigenvalues of S follow the format $S\vec{x} = \lambda\vec{x}$ s.t. eigenvector

$$\vec{x} \in \mathbb{C}^n.$$

Simplify

$$S \vec{x} = \lambda \vec{x}$$

$$\Rightarrow \vec{x}^* S \vec{x} = \vec{x}^* \lambda \vec{x}$$

$$\Rightarrow \vec{x}^* S \vec{x} = \lambda \vec{x}^* \vec{x}$$

$$\Rightarrow \vec{x}^* S \vec{x} = \lambda \|\vec{x}\|_2^2 \quad (\text{by 2-norm definition}).$$

Additionally,

$$S \vec{x} = -S^T \vec{x} = \lambda \vec{x}$$

$$\Rightarrow -\vec{x}^* S^T \vec{x} = \lambda \|\vec{x}\|_2^2$$

Using our definitions,

$$\begin{aligned}\lambda \|\vec{x}\|_2^2 &= \vec{x}^* \lambda \vec{x} \\ &= \vec{x}^* (-S^* \vec{x})\end{aligned}$$

(by equivalence:
skew symmetric
matrix
definition)

$$= -\vec{x}^* S^* \vec{x}$$

$$= -(S \vec{x})^* \vec{x}$$

$$= -(\lambda \vec{x})^* \vec{x}$$

$$= -\vec{x}^* \lambda^* \vec{x}$$

$$= -\overline{\lambda} \vec{x}^* \vec{x}$$

$$= -\overline{\lambda} \|\vec{x}\|_2^2.$$

Thus,

$$\lambda \|\vec{x}\|_2^2 = -\bar{\lambda} \|\vec{x}\|_2^2$$

$$\Rightarrow \lambda = -\bar{\lambda}$$

$$\Rightarrow a+bi = -\overline{(a+bi)}, \quad \text{s.t. } a \in \mathbb{R} ; b \in \mathbb{R}$$

$$\Rightarrow a+bi = -a+bi.$$

This equivalence only holds when
 $a=0$,

\therefore Any non-zero eigenvalue of S
must be purely imaginary.



ii) Assume that S is invertible
and hence has a determinant
of all n values s.t.

$n \in \mathbb{Z}^+$.

We know that by properties
of determinants, $|A| = |A^T|$ for
an arbitrary $A \in \mathbb{R}^{n \times n}$.

Applying this property to S ,

$$|S| = |S^T|,$$

Manipulating the skew-symmetric property,

$$|S| = |-S^T|$$

$$= |S^T|$$

$$= |-S|.$$

However, another property of determinants is that $|c \cdot A| = c^n |A|$ for some arbitrary $c \in \mathbb{R}$; $A \in \mathbb{R}^{n \times n}$.

Back to our case,

$$|-S^T| = |S^T|$$

$$\Rightarrow |-S| = |S|$$

$$\Rightarrow |-1 \cdot S| = |S|$$

$$\Rightarrow (-1)^n |S| = |S|.$$

Observing, in the case that $|S| \neq 0$, which is the invertible condition that we already stated must be true, there exists some contradictions,

When $(-1)^n = 1$, LHS & RHS are equivalent, but not when $(-1)^n = -1$, a contradiction.

∴ The statement that when S is invertible, then n must be even is true. If n is odd, S cannot be invertible.



iii) Given our definition of S in part i, the matrix $I - S$ follows

the format

$$I - S = \begin{bmatrix} 1 & -s_{12} & \dots & \dots & -s_{1n} \\ s_{12} & 1 & & & \\ \vdots & & \ddots & & \vdots \\ s_{in} & \dots & \dots & 1 - s_{(n-1)n} & \\ & & & (s_{nn}) & 1 \end{bmatrix}.$$

Simplifying, $I - S = I + S^T$.

In an attempt to find a nontrivial solution $\vec{x} \in \mathbb{C}^n$ of $(I + S^T)\vec{x} = \vec{0}$ that we guarantee exists,

$$(\mathbf{I} + \mathbf{S}^T) \vec{x} = 0$$

$$\Rightarrow \vec{x} + \mathbf{S}^T \vec{x} = 0$$

$$\Rightarrow \vec{x} = -\mathbf{S}^T \vec{x}$$

$$\Rightarrow \vec{x} = \mathbf{S} \vec{x}$$

$$\Rightarrow \vec{x}^* \vec{x} = \vec{x}^* \mathbf{S} \vec{x}$$

$$\Rightarrow \|\vec{x}\|_2^2 = (\mathbf{S}^* \vec{x})^* \vec{x}$$

$$\Rightarrow \|\vec{x}\|_2^2 = (\mathbf{S}^T \vec{x})^* \vec{x}$$

$$\Rightarrow \|\vec{x}\|_2^2 = (-\mathbf{S} \vec{x})^* \vec{x}$$

$$\Rightarrow \|\vec{x}\|_2^2 = (-\vec{x})^* \vec{x} \quad (\text{by } \mathbf{S} \vec{x} = -\vec{x})$$

$$\Rightarrow \|\vec{x}\|_2^2 = -\vec{x}^* \vec{x}$$

$$\Rightarrow \|\vec{x}\|_2^2 = -\|\vec{x}\|_2^2$$

$$\Rightarrow \|\vec{x}\|_2^2 = 0$$

$$\Rightarrow \vec{x} = \vec{0}, \text{ a contradiction.}$$

No nontrivial solution \vec{x} exists in

$$(\mathbf{I} + \mathbf{S}^T) \vec{x} = \vec{0}, \text{ which implies the}$$

$$\text{same for } (\mathbf{I} - \mathbf{S}) \vec{x} = \vec{0}.$$

$\therefore \mathbf{I} - \mathbf{S}$ is always invertible.



iv.) unitary proof

↳ inverse is equal to conj transpose.

For a real matrix to be unitary, its inverse must equal its conjugate transpose.

Multiplying the Cayley transform by its transpose,

$$\begin{aligned} C^T C &= \left[(I+S)(I-S)^{-1} \right]^T (I+S)(I-S)^{-1} \\ &= (I-S^T)^{-1} (I+S^T)(I+S)(I-S)^{-1} \\ &= (I+S)^{-1} (I-S)(I+S)(I-S)^{-1} \\ &= \left[(I+S)^{-1} (I-S) \right] C. \end{aligned}$$

If $I-S$ is invertible, then

$I+S$ is invertible as well, since

$I-S = I+S^T$, which maintains the same properties as $I+S$ because S^T is a skew-symmetric matrix.

Set $A := (I+S)$, $B := (I-S)^{-1}$.

By definition, $C = AB$.

So,

$$C^{-1} = (AB)^{-1}$$

$$= A^{-1}B^{-1} \left(\begin{array}{c} \text{because } A \text{ \& } B \text{ are both} \\ \text{invertible} \end{array} \right)$$

$$= (I+S)^{-1}(I-S)C.$$

Substituting back into our previous problem,

$$C^T C = [(I+S)^{-1} (I-S)] C$$

$$= C^{-1} C,$$

$$\Rightarrow C^T = C^{-1}.$$

$\therefore C(s)$ is a unitary matrix.



$$v) \quad C = (I + S)(I - S)^{-1}$$

Eigenvalues of S are denoted as

λ_i $\forall_i, i=1, 2, \dots, n$, and they are all imaginary for all non-zero eigenvectors \vec{x} as seen in part i. Finding the eigenvalues of $I + S$,

$$\begin{aligned} (I + S)\vec{x} &= \vec{x} + S\vec{x} \\ &= \vec{x} + \lambda_i \vec{x} \\ &= (1 + \lambda_i) \vec{x}. \end{aligned}$$

So, the eigenvalues of $I + S$ are equivalent to $1 + \lambda_i$ for all i .

Likewise for $I-S$,

$$\begin{aligned}(I-S)\vec{x} &= \vec{x} - S\vec{x} \\ &= \vec{x} - \lambda_i \vec{x} \\ &= (1-\lambda_i)\vec{x}.\end{aligned}$$

So, the eigenvalues of $I-S$ are equivalent to $1-\lambda_i$ for all i .

Moreover,

$$(I-S)\vec{x} = (1-\lambda_i)\vec{x}$$

$$\Rightarrow (I-S)^{-1}(I-S)\vec{x} = (1-\lambda_i)(I-S)^{-1}\vec{x}$$

$$\Rightarrow \left(\frac{1}{1-\lambda_i}\right)\vec{x} = (I-S)^{-1}\vec{x}.$$

So, the eigenvalues of $(I-S)^{-1}$ are

$$\left(\frac{1}{1-\lambda_i}\right).$$

Now addressing the Cayley transform,

let β_i denote its eigenvalues for all i
associated w/ λ_i . That being said,

$$(\mathbf{I} + \mathbf{S})(\mathbf{I} - \mathbf{S})^{-1} \vec{x}_i$$

$$= \frac{1}{1 - \lambda_i} (\mathbf{I} + \mathbf{S}) \vec{x}$$

$$= \frac{1}{1 - \lambda_i} (1 + \lambda_i) \vec{x}$$

$$= \left(\frac{1 + \lambda_i}{1 - \lambda_i} \right) \vec{x}$$

$$= \beta_i \vec{x}.$$

\therefore The eigenvalues of $C(S)$ are

$$\frac{1 + \lambda_i}{1 - \lambda_i} \quad \text{for all } i = 1, 2, \dots, n.$$