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// OregonState EECS
// Microcontroller System Design
// lab1_code.c
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// This program represents S0 button presses as a BCD counter on the
// PORTB LEDs
#include <avr/io.h>
#include <util/delay.h>
//***************
                           inc_as_bcd
// Increment 2 digit BCD counter and return a single integer representing 2 BCD
int8_t inc_as_bcd() {
   // digit one and two for BCD on PORTB LEDs
   static uint8_t dig1 = 0;
   static uint8_t dig2 = 0;
   if (dig1 < 9) { // increment dig1</pre>
       dig1 += 1;
   else if (dig2 < 9) { // rollover dig1 // increment dig2</pre>
       dig1 = 0;
       dig2 += 1;
   else { // rollover both digits
       dig1 = 0;
       dig2 = 0;
   // return single integer representing the counter as BCD
   return (dig2<<4) | dig1;</pre>
                           debounce_switch
// Check pushbutton SO.
// Adapted from Roger's debounce function.
// Shift in a one when the button is depressed else a zero.
// Return a one once per debounced press.
// Expects an active low pushbutton on PORTD bit zero.
// Debounce time is determined by external loop delay times 4.
//**************
int8_t debounce_switch() {
   // button press shift register
   static uint8_t [8] SR = 0;
   uint8_t i = 0;
   for (i=0; i<8; i++) {
       // bit_is_clear() returns a one when button pushed
       SR[i] = (SR[i] << 1) | bit_is_clear(PIND, i);</pre>
   if (SR[i] == 0x0F) { // if shift register = 00001111
       return i;
   return 9;
```

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                           to digs
//
//**************
uint8_t * to_digs(num)
   static uint8_t [4] digs;
   digs[0] = num
   digs[1] = (num/10) % 10;
   digs[2] = (num/100) % 10;
   digs[3] = (num/100);
   return digs;
                            main
// Check switch SO.
// If low for 4 passes of debounc_switch() increment BCD counter in inc_as_bcd()
// The BCD count is then displayed on PORTB's LEDs.
int main(){
   // set all of PORTB to output
   DDRB = 0xFF;
   while(1) { // loop forever
       if (debounce_switch()) { // if switch true for 4 passes, increment PORTB
           PORTB = inc_as_bcd();
       // debounce 8ms
       _delay_ms(2);
```