```
smacc::SmaccClientBehavior

- stateMachine_
- currentState
- currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntry()
```

+ postEvent() + postEvent()

+ onExit()

- + requiresClient()
- + requiresComponent()
  + getCurrentState()
- configureEventSourceTypes()

ros\_timer\_client::CbTimer

- timerClient\_
- postTimerEvent\_
- c\_
- + onEntry()
  + onExit()
- + configureEventSourceTypes()
- + onClientTimerTickCallback()