```
mecanum_drive_controller
::SpeedLimiter::limit_velocity
```
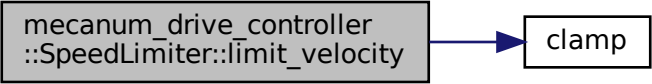→ `clamp`