```
smacc::ISmaccClientBehavior
    stateMachine_
    - currentState
    - currentOrthogonal
    + ISmaccClientBehavior()
    + ~ISmaccClientBehavior()
    + getStateMachine()
    + getName()
    + requiresClient()
    + requiresComponent()
    # runtimeConfigure()
    # onEntry()
    # onExit()
    # postEvent()
    # postEvent()
    # getCurrentState()
    # executeOnEntry()
    # executeOnExit()
    # dispose()

    configureEventSourceTypes()

                  Δ
    smacc::SmaccClientBehavior
    + onEntry()
    + onExit()
                       cl_multirole_sensor
                       :: CbDefault MultiRole Sensor
                           Behavior < ClientType >
                       + sensor
                       + deferedEventPropagation

    + CbDefaultMultiRoleSensor

                       Behavior()
                       + configureEventSourceTypes()
                       + propagateEvent()
                       + propagateEvent2()
                       + onEntry()
                       + onExit()
                       + onMessageCallback()
                       + getEventLabel()
                              < ClTemperatureSensor >
  cl_multirole_sensor
   ::CbDefaultMultiRoleSensor
  Behavior < ClTemperatureSensor >
  + sensor
  + deferedEventPropagation
   + CbDefaultMultiRoleSensor
  Behavior()
  + configureEventSourceTypes()
  + propagateEvent()
  + propagateEvent2()
  + onEntry()
  + onExit()
  + onMessageCallback()
  + getEventLabel()
sm_dance_bot::cl_temperature
sensor::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```