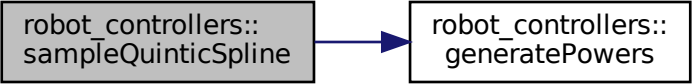


```
robot_controllers::  
sampleQuinticSpline
```



```
graph LR; A[robot_controllers::sampleQuinticSpline] --> B[robot_controllers::generatePowers]
```

A diagram showing a call from the `sampleQuinticSpline` function to the `generatePowers` function. The `sampleQuinticSpline` box is shaded gray, and the `generatePowers` box is white. A blue arrow points from the right side of the gray box to the left side of the white box.

```
robot_controllers::  
generatePowers
```