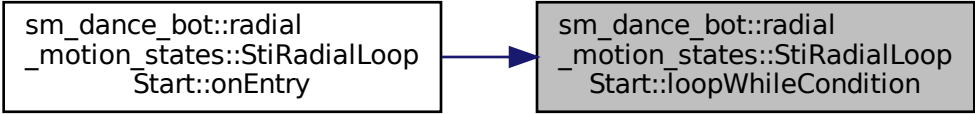


sm\_dance\_bot::radial  
\_motion\_states::StiRadialLoop  
Start::onEntry



```
graph LR; A["sm_dance_bot::radial  
_motion_states::StiRadialLoop  
Start::onEntry"] --> B["sm_dance_bot::radial  
_motion_states::StiRadialLoop  
Start::loopWhileCondition"]
```

sm\_dance\_bot::radial  
\_motion\_states::StiRadialLoop  
Start::loopWhileCondition