```
smacc::ISmaccComponent

# stateMachine_
# owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
```



+ configureEventSourceTypes()

_lidar::CpLidarSensorData

+ forwardObstacleDistance + SECURITY_DISTANCE

+ postEvent()

+ lastMessage

+ initialize() + MessageCallbackStoreDistance

+ MessageCalibackStoreDistance ToWall()