

sm_dance_bot_2::radial
_motion_states::StiRadialEnd
Point::runtimeConfigure

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graph LR; A["sm_dance_bot_2::radial_motion_states::StiRadialEndPoint::runtimeConfigure"] --> B["smacc::ISmaccClient::getComponent"]; A --> C["smacc::ISmaccState::requiresClient"]
```

The diagram illustrates a dependency or call relationship. A central box on the left, representing a state or component, has two arrows pointing to boxes on the right. The top arrow points to an interface method, and the bottom arrow points to another interface method.

smacc::ISmaccClient
::getComponent

smacc::ISmaccState
::requiresClient