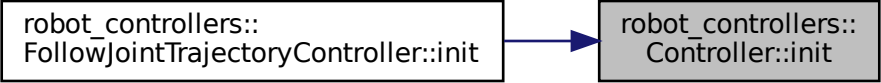


robot\_controllers::  
FollowJointTrajectoryController::init



```
graph LR; A[robot_controllers::FollowJointTrajectoryController::init] --> B[robot_controllers::Controller::init];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'robot\_controllers::FollowJointTrajectoryController::init'. The right box is gray with a black border and contains the text 'robot\_controllers::Controller::init'. The arrow is a solid blue line with a triangular arrowhead pointing towards the right box.

robot\_controllers::  
Controller::init