

submodules/ridgeback  
/ridgeback\_control/src  
/speed\_limiter.cpp

```
graph TD; A["submodules/ridgeback<br/>/ridgeback_control/src<br/>/speed_limiter.cpp"] --> B["algorithm"]; A --> C["mecanum_drive_controller<br/>/speed_limiter.h"]
```

algorithm

mecanum\_drive\_controller  
/speed\_limiter.h