


```
sm_moveit_screw_loop  
::cl_perception_system  
::CpSimulatedGazeboPerception  
  ::simulatedLinkStateCallback
```



A blue arrow points from the white box on the right to the gray box on the left, indicating a function call or dependency.

```
sm_moveit_screw_loop  
::cl_perception_system  
::CpSimulatedGazeboPerception  
  ::onInitialize
```