```
smacc::SmaccClientBehavior
    - stateMachine
    - currentState
    - currentOrthogonal
    + SmaccClientBehavior()
    + ~SmaccClientBehavior()
    + getStateMachine()
    + getName()
    + runtimeConfigure()
    + onEntry()
    + onExit()
    + postEvent()
    + postEvent()
    + requiresClient()
    + requiresComponent()
    + getCurrentState()
    configureEventSourceTypes()
                   cl multirole sensor
                   :: CbDefault MultiRole Sensor
                       Behavior < ClientType >
                   + sensor
                   + deferedEventPropagation
                   + CbDefaultMultiRoleSensor
                   Behavior()
                   + configureEventSourceTypes()
                   + propagateEvent()
                   + propagateEvent2()
                   + onEntry()
                   + onExit()
                   + onMessageCallback()
                   + getEventLabel()
                         < ClLidarSensor >
cl multirole sensor
::CbDefaultMultiRoleSensor
  Behavior < ClLidarSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
   sm dance bot::cl lidar
       ::CbLidarSensor
   + CbLidarSensor()
   + onEntry()
```

+ onMessageCallback()