

```
move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::publishGoalMarker
```

```
move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::makePlan
```

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```
graph RL; B[move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::makePlan] --> A[move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::publishGoalMarker]; C[move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::makePlan] --> B;
```