

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a light gray background and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::findInitialCarrotGoal'. The right box has a white background and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeCurrentEuclideanAndAngularErrors ToCarrotGoal'. A dark blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```