

sm_moveit_3::cl_perception
_system::ClPerceptionSystem
::decidePlacePose

```
graph LR; A["sm_moveit_3::cl_perception  
_system::ClPerceptionSystem  
::decidePlacePose"] --> B["smacc::ISmaccClient  
::GetComponent"]; A --> C["cl_move_base_z::Pose  
::toPoseMsg"]
```

The diagram consists of a single source box on the left and two target boxes on the right. Two blue arrows originate from the right side of the source box, pointing to the left side of each target box. The source box has a light gray background, while the target boxes have a white background. All boxes have a black border.

smacc::ISmaccClient
::GetComponent

cl_move_base_z::Pose
::toPoseMsg