

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::defaultBackwardCmd'. The right box is white and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::checkGoalReached'. A blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached
```