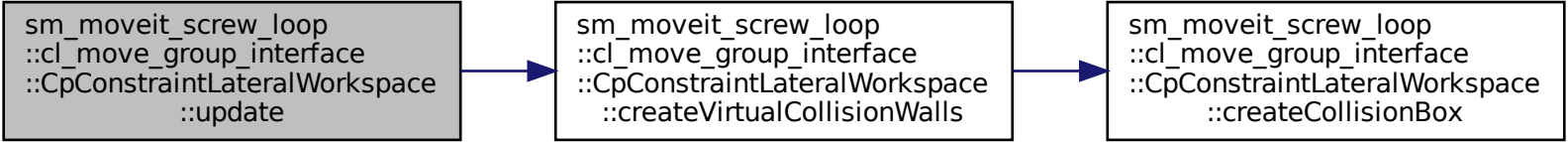


```
sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::update
```



```
graph LR; A["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::update"] --> B["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createVirtualCollisionWalls"]; B --> C["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createCollisionBox"]
```

```
sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createVirtualCollisionWalls
```

```
sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createCollisionBox
```