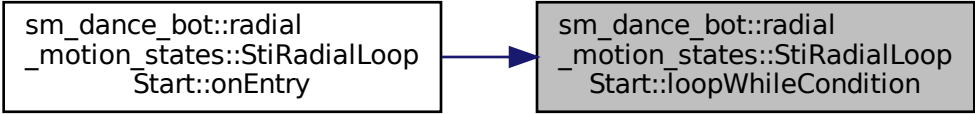


sm_dance_bot::radial
_motion_states::StiRadialLoop
Start::onEntry



```
graph LR; A["sm_dance_bot::radial<br/>_motion_states::StiRadialLoop<br/>Start::onEntry"] --> B["sm_dance_bot::radial<br/>_motion_states::StiRadialLoop<br/>Start::loopWhileCondition"]
```

sm_dance_bot::radial
_motion_states::StiRadialLoop
Start::loopWhileCondition