

```
graph BT; A[smacc_sm_reference_library/sm_fetch_screw_loop_1/src/sm_fetch_screw_loop_1_node.cpp] --> B[smacc_sm_reference_library/sm_fetch_screw_loop_1/include/sm_fetch_screw_loop_1/sm_fetch_screw_loop_1.h]; B --> C[smacc_sm_reference_library/sm_fetch_screw_loop_1/include/sm_fetch_screw_loop_1/st_initial_posture.h];
```

smacc_sm_reference
_library/sm_fetch_screw
_loop_1/include/sm_fetch
_screw_loop_1/st_initial
_posture.h

smacc_sm_reference
_library/sm_fetch_screw
_loop_1/include/sm_fetch
_screw_loop_1/sm_fetch_screw
_loop_1.h

smacc_sm_reference
_library/sm_fetch_screw
_loop_1/src/sm_fetch_screw
_loop_1_node.cpp