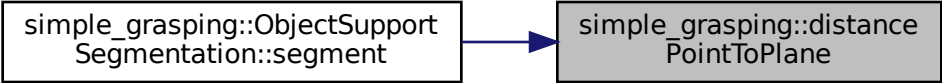


simple_grasping::ObjectSupport
Segmentation::segment



```
graph LR; A[simple_grasping::ObjectSupport Segmentation::segment] --> B[simple_grasping::distance PointToPlane];
```

The diagram illustrates a function call. A white rectangular box on the left contains the text 'simple_grasping::ObjectSupport' and 'Segmentation::segment' on two lines. A dark blue arrow points from the right side of this box to a gray rectangular box on the right. The gray box contains the text 'simple_grasping::distance' and 'PointToPlane' on two lines.

simple_grasping::distance
PointToPlane