

sm\_moveit\_2::SS1::SsPick  
Object::runtimeConfigure

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graph LR; A[sm_moveit_2::SS1::SsPick Object::runtimeConfigure] --> B[moveit_z_client::CIMoveGroup::onMotionExecutionFailed]; A --> C[sm_moveit_2::SS1::SsPick Object::onMoveitError];
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moveit\_z\_client::CIMoveGroup  
::onMotionExecutionFailed

sm\_moveit\_2::SS1::SsPick  
Object::onMoveitError