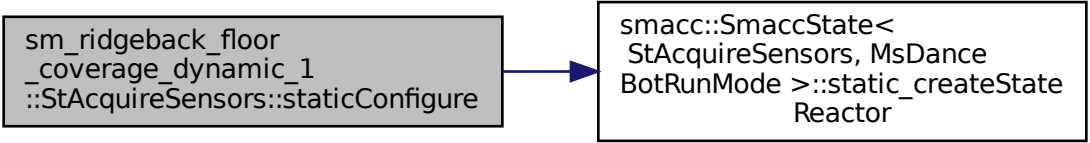


```
sm_ridgeback_floor  
_coverage_dynamic_1  
::StAcquireSensors::staticConfigure
```



```
graph LR; A[sm_ridgeback_floor_coverage_dynamic_1::StAcquireSensors::staticConfigure] --> B[smacc::SmaccState<StAcquireSensors, MsDanceBotRunMode >::static_createStateReactor];
```

```
smacc::SmaccState<  
  StAcquireSensors, MsDance  
  BotRunMode >::static_createState  
  Reactor
```