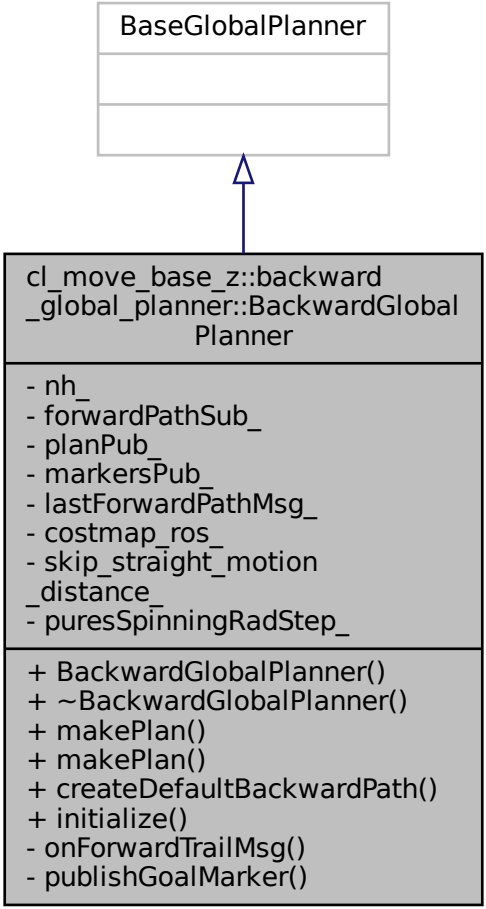
BaseGlobalPlanner
cl_move_base_z::backward_global_planner::BackwardGlobalPlanner
- nh_
- forwardPathSub_
- planPub_
- markersPub_
- lastForwardPathMsg_
- costmap_ros_
- skip_straight_motion_distance_
- puresSpinningRadStep_
+ BackwardGlobalPlanner()
+ ~BackwardGlobalPlanner()
+ makePlan()
+ makePlan()
+ createDefaultBackwardPath()
+ initialize()
- onForwardTrailMsg()
- publishGoalMarker()