smacc::ISmaccClient # stateMachine # components + ISmaccClient() + ~ISmaccClient() + initialize() + setStateMachine() + getName() + postEvent() + postEvent() + getComponent() + configureEventSourceTypes() + getType() smacc::client bases ::SmaccSubscriberClient < MessageType > + topicName + queueSize + onFirstMessageReceived_ + onMessageReceived_ + postMessageEvent + postInitialMessageEvent # nh_ - sub firstMessage_ - initialized + SmaccSubscriberClient() + ~SmaccSubscriberClient() + onMessageReceived() + onFirstMessageReceived() + configureEventSourceTypes() + initialize() messageCallback() < sensor_msgs::Temperature > smacc::client_bases ::SmaccSubscriberClient < sensor_msgs::Temperature > multirole sensor client + topicName ::CIMultiroleSensor< Message + queueSize Type > + onFirstMessageReceived_ + onMessageReceived_ + onMessageTimeout + postMessageEvent + postTimeoutMessageEvent + postInitialMessageEvent + timeout # nh timeoutTimer_ initialized_ - sub - firstMessage_ + CIMultiroleSensor() initialized + onMessageTimeout() + SmaccSubscriberClient() + configureEventSourceTypes() + ~SmaccSubscriberClient() + initialize() + onMessageReceived() # resetTimer() + onFirstMessageReceived() - timeoutCallback() + configureEventSourceTypes() + initialize() messageCallback() < sensor_msgs::Temperature > multirole_sensor_client ::CIMultiroleSensor< sensor msgs::Temperature > + onMessageTimeout_ + postTimeoutMessageEvent + timeout - timeoutTimer_ initialized + CIMultiroleSensor() + onMessageTimeout() + configureEventSourceTypes() + initialize() # resetTimer() timeoutCallback() sm_dance_bot::cl_temperature sensor::CITemperatureSensor

+ CITemperatureSensor()