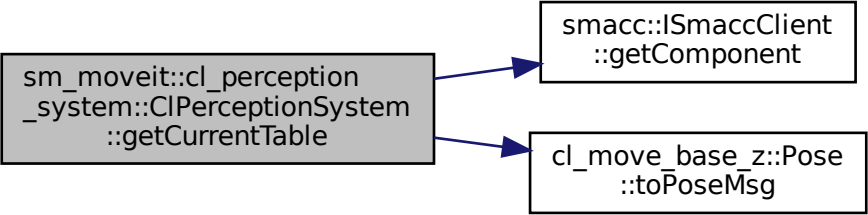


sm\_moveit::cl\_perception  
\_system::ClPerceptionSystem  
::getCurrentTable



```
graph LR; A["sm_moveit::cl_perception_system::ClPerceptionSystem::getCurrentTable"] --> B["smacc::ISmaccClient::getComponent"]; A --> C["cl_move_base_z::Pose::toPoseMsg"]
```

smacc::ISmaccClient  
::getComponent

cl\_move\_base\_z::Pose  
::toPoseMsg