

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::pureSpinningCmd
```



A diagram showing a transformation from a specific command to a more general pose. On the left, a gray box contains the command `cl_move_base_z::backward`, `_local_planner::BackwardLocalPlanner`, and `::pureSpinningCmd`. A blue arrow points from this box to a white box on the right. The white box contains `cl_move_base_z::backward` and `_local_planner::optionalRobotPose`, indicating that the specific command is mapped to a general robot pose.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```