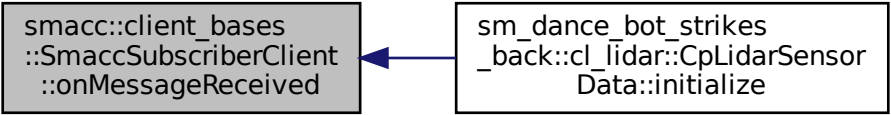


```
smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived
```



```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize"] --> B["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from right to left. The left box has a light gray background and contains the text 'smacc::client_bases', '::SmaccSubscriberClient', and '::onMessageReceived' stacked vertically. The right box has a white background and contains the text 'sm_dance_bot_strikes', '_back::cl_lidar::CpLidarSensor', and 'Data::initialize' stacked vertically. A blue arrow originates from the right side of the right box and points to the right side of the left box.

```
sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize
```