## smacc::SmaccClientBehavior

- stateMachine_
- currentState
- currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
- configureEventSourceTypes()

## ros_timer_client::CbTimer CountdownLoop

- tickCounter_
- tickTriggerCount_
- timerClient_
- postCountDownEvent_
- onTimerTick_

+ CbTimerCountdownLoop()
+ onEntry()
+ onExit()
+ configureEventSourceTypes()
+ onTimerTick()
- onClientTimerTickCallback()