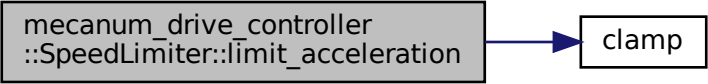


mecanum_drive_controller
::SpeedLimiter::limit_acceleration



```
graph LR; A[mecanum_drive_controller::SpeedLimiter::limit_acceleration] --> B[clamp]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is gray with a black border and contains the text 'mecanum_drive_controller' on the first line and '::SpeedLimiter::limit_acceleration' on the second line. The right box is white with a black border and contains the text 'clamp'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

clamp