

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_superstates/ss_f_pattern_1.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_states/f_pattern_states  
_sti_fpattern_forward_1.h"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_states/f\_pattern\_states  
\_sti\_fpattern\_forward\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_superstates/ss\_f\_pattern\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_src/sm\_dance\_bot.cpp