

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a function call. A white box on the left contains the code for the `computeVelocityCommands` function. A blue arrow points from this box to a grey box on the right, which contains the code for the `defaultBackwardCmd` function. Both boxes have a black border.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```