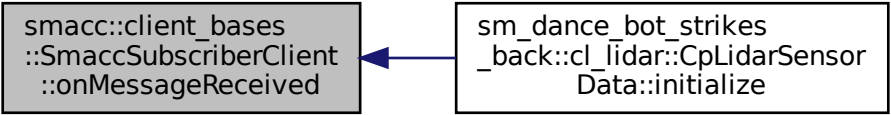


```
smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived
```



```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize"] --> B["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]
```

A diagram showing a call from a function in the `sm_dance_bot_strikes` namespace to a function in the `smacc::client_bases` namespace. The call is represented by a blue arrow pointing from the right box to the left box. The left box has a light gray background, while the right box is white.

```
sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize
```