

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
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::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

A diagram showing a call to the `findInitialCarrotGoal` method from the `BackwardLocalPlanner` class, which is part of the `cl_move_base_z::backward` process. The call is represented by a blue arrow pointing from the left box to the right box.

```
cl_move_base_z::backward  
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```