```
move_group_interface
                                             _client::CbDetachObject
                                                     ::onEntry
                                             sm_moveit_4::cl_gripper
                                             ::CbOpenGripper::onEntry
                                             sm_moveit::cl_gripper
                                             ::CbOpenGripper::onEntry
                                             sm_moveit_2::cl_gripper
                                             ::CbOpenGripper::onEntry
                                             sm_moveit_3::cl_gripper
                                             ::CbOpenGripper::onEntry
                                         cl_ros_timer::CbTimerCountdown
                                                  Once::onEntry
                                            sm_moveit_2::cl_gripper
                                             ::CbCloseGripper::onEntry
                                            sm moveit 3::cl gripper
                                             ::CbCloseGripper::onEntry
                                            sm_moveit_4::cl_gripper
                                             ::CbCloseGripper::onEntry
                                            sm_moveit::cl_gripper
                                            ::CbCloseGripper::onEntry
                                        cl_ros_timer::CbTimerCountdown
                                                  Loop::onEntry
                                             move_group_interface
                                             _client::CbAttachObject
                                                     ::onEntry
                                             sm_dance_bot_2::cl
                                              led::CbLEDOn::onEntry
                                              sm dance bot::cl led
                                               ::CbLEDOff::onEntry
                                             sm dance bot 2::cl
                                              led::CbLEDOff::onEntry
                                             sm_dance_bot_strikes
_back::cl_led::CbLEDOff
                                                     ::onEntry
                                              sm_dance_bot::cl_led
                                                ::CbLEDOn::onEntry
                                             sm_dance_bot_strikes
                                              _back::cl_led::CbLEDOn
                                                     ::onEntry
smacc::ISmaccClientBehavior
                                         cl keyboard::CbDefaultKeyboard
       ::requiresClient
                                                Behavior::onEntry
                                           cl_move_base_z::CbNavigate
                                              NextWaypoint::onEntry
                                           sm_dance_bot_strikes
                                            back::cl_string_publisher
                                           ::CbStringPublisher::onEntry
                                            move_group_interface
                                            _client::CbMoveEndEffector
                                                     ::onEntry
                                           sm_dance_bot::cl_string
                                           _publisher::CbStringPublisher
                                                     ::onEntry
                                            sm_dance_bot_2::cl
                                            _string_publisher::CbString
                                                Publisher::onEntry
                                          cl_move_base_z::CbUndoPath
                                               Backwards::onEntry
                                              move_group_interface
                                              _client::CbMoveJoints
                                                     ::onEntry
                                        move_group_interface
                                        client::CbMoveEndEffectorRelative
                                                     ::onEntry
                                           move_group_interface
                                           client::CbMoveNamedTarget
                                                     ::onEntry
                                        move_group_interface
                                         _client::CbMoveCartesianRelative
                                                     ::onEntry
                                            cl_move_base_z::CbRotate
                                                     ::onEntry
                                            cl_ros_publisher::CbPublish
                                                  Once::onEntry
                                           cl_move_base_z::CbAbsolute
                                                 Rotate::onEntry
                                           cl move base z::CbNavigate
                                               Backwards::onEntry
                                           cl_move_base_z::CbNavigate
GlobalPosition::onEntry
                                           cl ros publisher::CbDefault
                                               PublishLoop::onEntry
                                           cl_move_base_z::CbNavigate
                                                 Forward::onEntry
                                         cl multirole sensor
                                         :: CbDefault MultiRole Sensor
                                         Behavior < sm_dance_bot_strikes
                                         back::cl lidar::ClLidarSensor
                                                    >::onEntry
```

cl_move_base_z::CbUndoPath Backwards::onExit

cl_ros_timer::CbTimer ::onEntry