BaseLocalPlanner
move_base_z_client ::backward_local_planner ::BackwardLocalPlanner
- paramServer
+ BackwardLocalPlanner() + ~BackwardLocalPlanner() + computeVelocityCommands() + isGoalReached() + setPlan() + initialize() + initialize() - reconfigCB() - createCarrotGoal() - pureSpinningCmd() - defaultBackwardCmd() - publishGoalMarker() - generateTrajectory() - computeNewPositions()