

nav\_core::BaseLocalPlanner



cl\_move\_base\_z::pure  
\_spinning\_global\_planner  
::PureSpinningGlobalPlanner

- + PureSpinningGlobalPlanner()
- + ~PureSpinningGlobalPlanner()
- + computeVelocityCommands()
- + isGoalReached()
- + setPlan()
- + initialize()
- + initialize()
- + initialize()