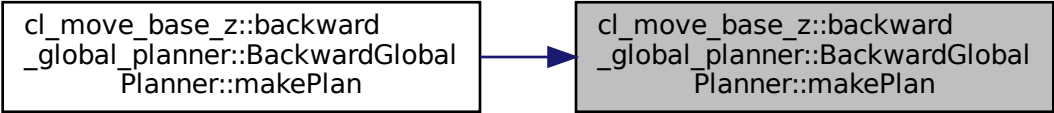


```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::makePlan
```



```
graph LR; A["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::makePlan"] --> B["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::makePlan"]
```

A diagram showing a call to the `makePlan` method of the `BackwardGlobalPlanner` class. The call is shown in a white box on the left, with a blue arrow pointing to a gray box on the right, which contains the same code. The gray box likely represents a target or a state where the plan is executed.

```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::makePlan
```