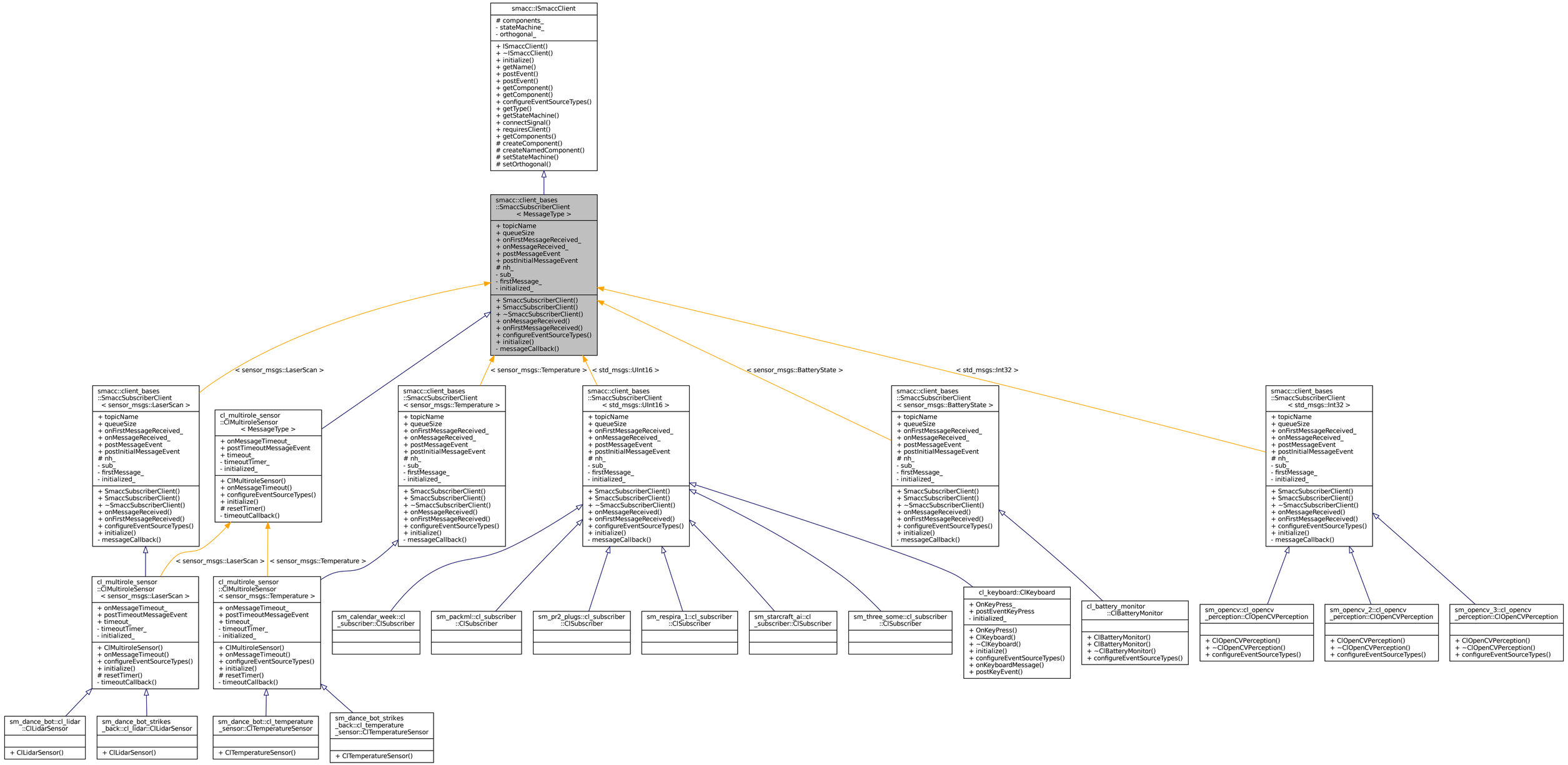
smacc::ISmaccClient
components_
- stateMachine_
- orthogonal_
+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ getComponent()
+ configureEventSourceTypes()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
# createComponent()
# createNamedComponent()
# setStateMachine()
# setOrthogonal()
smacc::client_bases ::SmaccSubscriberClient < MessageType >
+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
# nh_
- sub_
- firstMessage_
- initialized_
+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ configureEventSourceTypes()
+ initialize()
- messageCallback()
< sensor_msgs::LaserScan >
< sensor_msgs::Temperature >
< std_msgs::UInt16 >
< sensor_msgs::BatteryState >
< std_msgs::Int32 >
smacc::client_bases ::SmaccSubscriberClient < sensor_msgs::LaserScan >
cl_multirole_sensor ::ClMultiroleSensor < MessageType >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ configureEventSourceTypes()
+ initialize()
# resetTimer()
- timeoutCallback()
smacc::client_bases ::SmaccSubscriberClient < sensor_msgs::Temperature >
smacc::client_bases ::SmaccSubscriberClient < std_msgs::UInt16 >
smacc::client_bases ::SmaccSubscriberClient < sensor_msgs::BatteryState >
smacc::client_bases ::SmaccSubscriberClient < std_msgs::Int32 >
< sensor_msgs::LaserScan >
< sensor_msgs::Temperature >
cl_multirole_sensor ::ClMultiroleSensor < sensor_msgs::LaserScan >
cl_multirole_sensor ::ClMultiroleSensor < sensor_msgs::Temperature >
sm_calendar_week::cl _subscriber::ClSubscriber
sm_packml::cl_subscriber ::ClSubscriber
sm_pr2_plugs::cl_subscriber ::ClSubscriber
sm_respira_1::cl_subscriber ::ClSubscriber
sm_starcraft_ai::cl _subscriber::ClSubscriber
sm_three_some::cl_subscriber ::ClSubscriber
cl_keyboard::ClKeyboard
+ OnKeyPress_
+ postEventKeyPress
- initialized_
+ OnKeyPress()
+ ClKeyboard()
+ ~ClKeyboard()
+ initialize()
+ configureEventSourceTypes()
+ onKeyboardMessage()
+ postKeyEvent()
cl_battery_monitor ::ClBatteryMonitor
+ ClBatteryMonitor()
+ ClBatteryMonitor()
+ ~ClBatteryMonitor()
+ configureEventSourceTypes()
sm_opencv::cl_opencv _perception::ClOpenCVPerception
+ ClOpenCVPerception()
+ ~ClOpenCVPerception()
+ configureEventSourceTypes()
sm_opencv_2::cl_opencv _perception::ClOpenCVPerception
+ ClOpenCVPerception()
+ ~ClOpenCVPerception()
+ configureEventSourceTypes()
sm_opencv_3::cl_opencv _perception::ClOpenCVPerception
+ ClOpenCVPerception()
+ ~ClOpenCVPerception()
+ configureEventSourceTypes()
sm_dance_bot::cl_lidar ::ClLidarSensor
+ ClLidarSensor()
sm_dance_bot_strikes _back::cl_lidar::ClLidarSensor
+ ClLidarSensor()
sm_dance_bot::cl_temperature _sensor::ClTemperatureSensor
+ ClTemperatureSensor()
sm_dance_bot_strikes _back::cl_temperature _sensor::ClTemperatureSensor
+ ClTemperatureSensor()