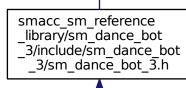
smacc_sm_reference _library/sm_dance_bot _3/include/sm_dance_bot _3/orthogonals/or_obstacle _perception.h



smacc_sm_reference _library/sm_dance_bot 3/src/sm_dance_bot

_3/src/sm_dance_bot_3.cpp