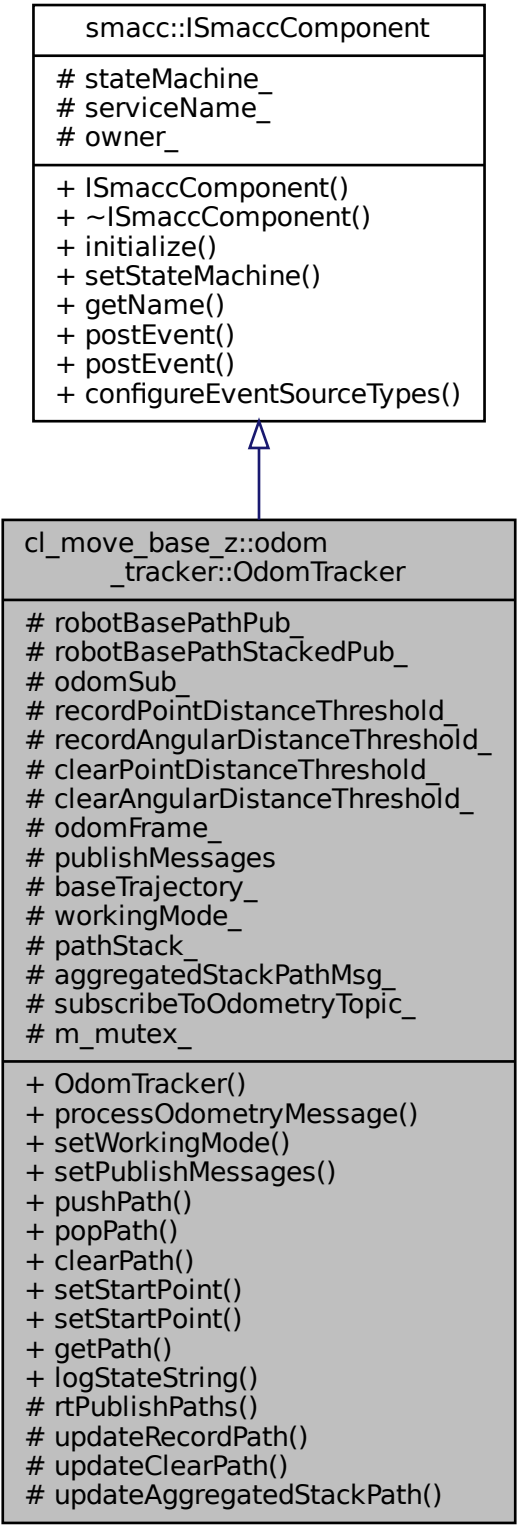
smacc::ISmaccComponent
stateMachine_
serviceName_
owner_
+ ISmaccComponent()
+ ~ISmaccComponent()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
+ configureEventSourceTypes()
cl_move_base_z::odom
_tracker::OdomTracker
robotBasePathPub_
robotBasePathStackedPub_
odomSub_
recordPointDistanceThreshold_
recordAngularDistanceThreshold_
clearPointDistanceThreshold_
clearAngularDistanceThreshold_
odomFrame_
publishMessages
baseTrajectory_
workingMode_
pathStack_
aggregatedStackPathMsg_
subscribeToOdometryTopic_
m_mutex_
+ OdomTracker()
+ processOdometryMessage()
+ setWorkingMode()
+ setPublishMessages()
+ pushPath()
+ popPath()
+ clearPath()
+ setStartPoint()
+ setStartPoint()
+ getPath()
+ logStateString()
# rtPublishPaths()
# updateRecordPath()
# updateClearPath()
# updateAggregatedStackPath()