```
smacc::ISmaccState
                                        ::getROSNode
                                sm_dance_bot_strikes
                                 _back::f_pattern_states
                                ::StiFPatternStartLoop
                                < SsFPattern1 >::loopCondition
                                  sm_pr2_plugs::StNavigate
                                      ::runtimeConfigure
                                 sm_pr2_plugs::StGetOutlet
                                 Locations::runtimeConfigure
                                  sm_pr2_plugs::StClearLeft
                                    Arm::runtimeConfigure
                                    sm_pr2_plugs::StPlugIn
                                      ::runtimeConfigure
                                  sm_pr2_plugs::StPullBack
                                  FromWall::runtimeConfigure
                                sm_pr2_plugs::StSucceedTuck
                                      ::runtimeConfigure
                                sm_pr2_plugs::StRecoverStow
                                    Plug::runtimeConfigure
                                 sm_pr2_plugs::StSafetyTuck
                                      ::runtimeConfigure
                                sm_pr2_plugs::StCloseGripper
                                      ::runtimeConfigure
                                  sm_pr2_plugs::StStowLeft
                                    Arm::runtimeConfigure
                                  sm_pr2_plugs::StStowPlug
                                      ::runtimeConfigure
                                sm_pr2_plugs::StSucceedFree
                                   Base::runtimeConfigure
                                   sm_pr2_plugs::StUnplug
                                      ::runtimeConfigure
                                  sm_pr2_plugs::StUntuckAt
                                   Outlet::runtimeConfigure
                                  sm_pr2_plugs::StWiggleOut
                                      ::runtimeConfigure
                                sm_pr2_plugs::StDetectOutlet
                                      ::runtimeConfigure
                                  sm_pr2_plugs::StFailLower
Spine::runtimeConfigure
                                  sm_pr2_plugs::StFetchPlug
                                      ::runtimeConfigure
                                  sm_pr2_plugs::StFailOpen
                                  Gripper::runtimeConfigure
                                  sm_pr2_plugs::StFailUntuck
                                      ::runtimeConfigure
                                   sm_pr2_plugs::StFailTuck
                                   Arms::runtimeConfigure
                                  sm_pr2_plugs::StNavigate
                                  ToOutlet::runtimeConfigure
                                sm_calendar_week::StThursday
smacc::ISmaccState
  ::requiresClient
                                      ::runtimeConfigure
                                sm_calendar_week::StSaturday
                                      ::runtimeConfigure
                                sm_calendar_week::StSunday
                                      ::runtimeConfigure
                               sm_calendar_week::StWednesday
                                      ::runtimeConfigure
                                 sm_calendar_week::StFriday
                                      ::runtimeConfigure
                                   sm_test::State2::runtime
                                          Configure
                                 sm_calendar_week::StMonday
                                      ::runtimeConfigure
                                sm_calendar_week::StTuesday
                                      ::runtimeConfigure
                                     sm update::State2::
                                       runtimeConfigure
                                     sm atomic::State2::
                                       runtimeConfigure
                                  sm_dance_bot_strikes
                                   back::radial motion
                                   states::StiRadialEndPoint
                                      ::runtimeConfigure
                                 sm_pr2_plugs::StFailStill
                                 Unplugged::runtimeConfigure
                                 sm pr2 plugs::StGoallsLocal
                                      ::runtimeConfigure
                                  sm_dance_bot::StNavigate
                                  Forward1::runtimeConfigure
                                   sm_dance_bot_strikes
                                    back::s_pattern_states
                                   ::StiSPatternForward4::
                                       runtimeConfigure
                                   sm_dance_bot_strikes
                                    back::s_pattern_states
                                    ::StiSPatternForward2::
                                       runtimeConfigure
                              sm_pr2_plugs::StProcessRecharge
                                 Command::runtimeConfigure
                                    sm_dance_bot_strikes
                                     back::f_pattern_states
                                    ::StiFPatternForward1::
                                       runtimeConfigure
                                  sm_three_some::StState3
                                      ::runtimeConfigure
                                  sm_three_some::inner
                                   states::StiState2::runtime
                                          Configure
                                  sm_three_some::inner
                                  states::StiState3::runtime
                                          Configure
                                  sm_three_some::StState1
                                      ::runtimeConfigure
                               sm_dance_bot::StNavigate
                                ToWaypointsX::runtimeConfigure
                                sm_dance_bot_strikes
                                 _back::StNavigateToWaypoints
                                     X::runtimeConfigure
                                  sm_three_some::StState2
                                      ::runtimeConfigure
```