```
smacc::ISmaccClientBehavior

    stateMachine

    currentState

- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
configureEventSourceTypes()
 smacc::SmaccClientBehavior
 + onEntry()
 + onExit()
                     cl_multirole_sensor
                     :: CbDefault MultiRole Sensor
                         Behavior < ClientType >
                     + sensor
                     + deferedEventPropagation

    + CbDefaultMultiRoleSensor

                     Behavior()
                     + configureEventSourceTypes()
                     + propagateEvent()
                     + propagateEvent2()
                     + onEntry()
                     + onExit()
                     + onMessageCallback()
                     + getEventLabel()
                             < sm dance bot strikes
                             back::cl lidar::ClLidarSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < sm_dance_bot_strikes
 _back::cl_lidar::ClLidarSensor >
+ sensor
+ \ defere\overline{d} Event Propagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
 sm_dance_bot_strikes
_back::cl_lidar::CbLidarSensor
  + CbLidarSensor()
  + onEntry()
  + onMessageCallback()
```