

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



A diagram showing a call to the `findInitialCarrotGoal` method. On the left, a grey box contains the code `cl_move_base_z::backward`, `_local_planner::BackwardLocalPlanner`, and `::findInitialCarrotGoal`. A blue arrow points from this box to a white box on the right. The white box contains the code `cl_move_base_z::backward`, `_local_planner::BackwardLocalPlanner`, and `::computeCurrentEuclideanAndAngularErrorsToCarrotGoal`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```