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graph BT; A["smacc_sm_reference_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/sm_dance_bot_2.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/sti_s_pattern_1.h"]; C --> D["smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/sti_spattern_rotate_1.h"];
```

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_run
_mode/s_pattern_states/sti
_spattern_rotate_1.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_run
_mode/s_pattern_states/ss
_s_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2.cpp