smacc::SmaccClientBehavior stateMachine - currentState - currentOrthogonal + SmaccClientBehavior() + ~SmaccClientBehavior() + getStateMachine() + getName() + runtimeConfigure() + onEntry() + onExit() + postEvent() + postEvent() + requiresClient() + requiresComponent() + getCurrentState() configureEventSourceTypes() multirole sensor client ::CbDefaultMultiRoleSensorBehavior < ClientType > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() < ClTemperatureSensor > < ClLaserSensor > multirole_sensor_client multirole sensor client ::CbDefaultMultiRoleSensorBehavior ::CbDefaultMultiRoleSensorBehavior < ClTemperatureSensor > < ClLaserSensor > + sensor + sensor + deferedEventPropagation + deferedEventPropagation + CbDefaultMultiRoleSensor + CbDefaultMultiRoleSensor Behavior() Behavior() + configureEventSourceTypes() + configureEventSourceTypes() + propagateEvent() + propagateEvent() + propagateEvent2() + propagateEvent2() + onEntry() + onEntry() + onExit() + onExit() + onMessageCallback() + onMessageCallback() + getEventLabel() + getEventLabel() sm dance bot::cl lidar sm_dance_bot::cl_temperature ::CbLidarSensor sensor::CbConditionTemperatureSensor + CbLidarSensor() + CbConditionTemperatureSensor() + onEntry() + onMessageCallback() + onMessageCallback()