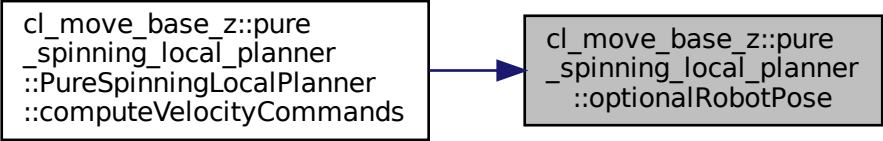


```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A blue arrow points from the right side of the white box to the left side of the gray box.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```