

controller\_interface  
::MultiInterfaceController  
< franka\_hw::FrankaStateInterface >



franka\_control::FrankaState  
Controller

- arm\_id\_
- franka\_state\_interface\_
- franka\_state\_handle\_
- publisher\_transforms\_
- publisher\_franka\_states\_
- publisher\_joint\_states\_
- publisher\_joint\_states\_desired\_
- publisher\_external\_wrench\_
- trigger\_publish\_
- robot\_state\_
- sequence\_number\_
- joint\_names\_

- + FrankaStateController()
- + init()
- + update()
- publishFrankaStates()
- publishJointStates()
- publishTransforms()
- publishExternalWrench()