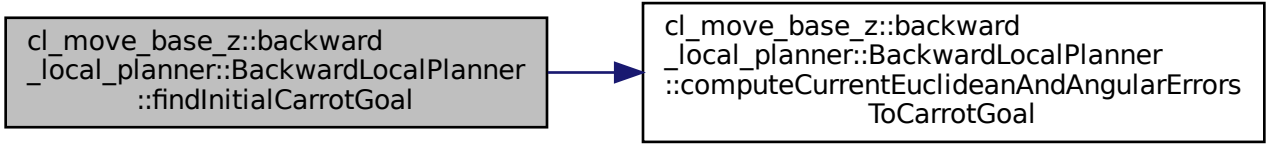
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::findInitialCarrotGoal
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::computeCurrentEuclideanAndAngularErrors
ToCarrotGoal