

submodules/robot_controllers
/robot_controllers/include
/robot_controllers/trajectory.h

```
graph TD; A["submodules/robot_controllers<br>/robot_controllers/include<br>/robot_controllers/trajectory.h"] --> B["ros/ros.h"]; A --> C["angles/angles.h"]; A --> D["trajectory_msgs/JointTrajectory.h"];
```

The diagram illustrates the include relationships for the file `/robot_controllers/trajectory.h`. It is a hierarchical structure where a single parent node at the top points to three child nodes below it. The parent node is a gray rectangle containing the file path and its include directives. The child nodes are white rectangles, each representing a file that is included by the parent. Blue arrows indicate the direction of the include relationship from the parent to each child.

ros/ros.h

angles/angles.h

trajectory_msgs/JointTrajectory.h