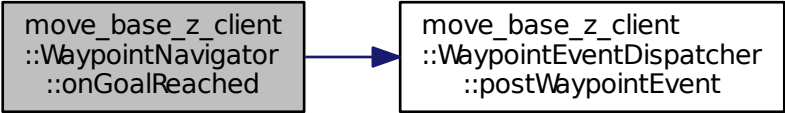


```
move_base_z_client  
::WaypointNavigator  
::onGoalReached
```



```
graph LR; A["move_base_z_client::WaypointNavigator::onGoalReached"] --> B["move_base_z_client::WaypointEventDispatcher::postWaypointEvent"]
```

```
move_base_z_client  
::WaypointEventDispatcher  
::postWaypointEvent
```