

sm_atomic_cb::State2
::runtimeConfigure

sm_atomic_cb::State1
::runtimeConfigure

cl_ros_timer::CbTimerCountdown
Once::onTimerTick

```
graph LR; A["sm_atomic_cb::State2::runtimeConfigure"] --> C["cl_ros_timer::CbTimerCountdownOnce::onTimerTick"]; B["sm_atomic_cb::State1::runtimeConfigure"] --> C;
```

The diagram illustrates a dependency or call relationship. On the left, two white rectangular boxes represent state configuration functions: 'sm_atomic_cb::State2::runtimeConfigure' (top) and 'sm_atomic_cb::State1::runtimeConfigure' (bottom). On the right, a gray rectangular box represents a timer callback function: 'cl_ros_timer::CbTimerCountdownOnce::onTimerTick'. Two blue arrows point from the right side of each white box to the left side of the gray box, indicating that both state configuration functions invoke or depend on the timer callback function.