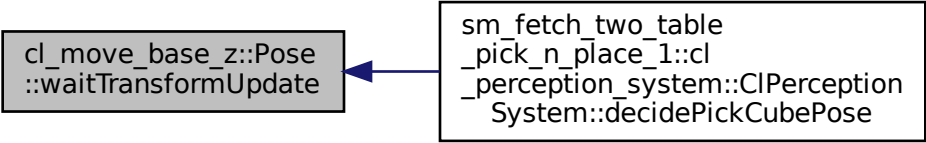


cl_move_base_z::Pose
::waitTransformUpdate



```
graph LR; A["sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::ClPerception  
System::decidePickCubePose"] --> B["cl_move_base_z::Pose  
::waitTransformUpdate"]
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'cl_move_base_z::Pose' followed by '::waitTransformUpdate' on the next line. The box on the right is white with a black border and contains three lines of text: 'sm_fetch_two_table', '_pick_n_place_1::cl', and '_perception_system::ClPerception System::decidePickCubePose'. A blue arrow points from the right box to the left box.

sm_fetch_two_table
_pick_n_place_1::cl
_perception_system::ClPerception
System::decidePickCubePose