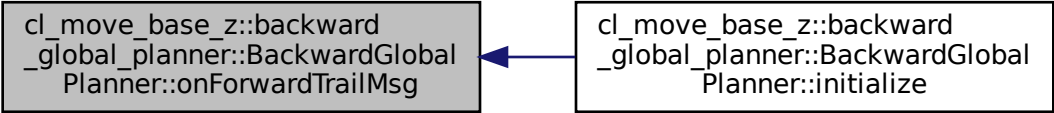


```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::onForwardTrailMsg
```



```
graph LR; A["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::initialize"] --> B["cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::onForwardTrailMsg"]
```

```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::initialize
```