

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A diagram illustrating a function call. A grey rectangular box on the left contains the text 'cl\_move\_base\_z::pure\_spinning\_local\_planner::PureSpinningLocalPlanner::computeVelocityCommands'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'cl\_move\_base\_z::pure\_spinning\_local\_planner::optionalRobotPose'.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```