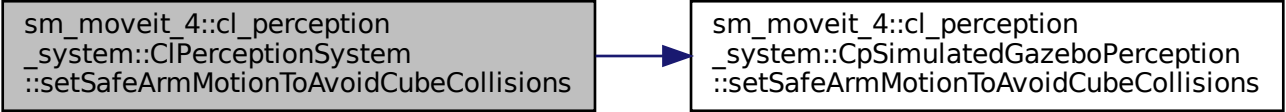


```
sm_moveit_4::cl_perception  
_system::ClPerceptionSystem  
::setSafeArmMotionToAvoidCubeCollisions
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'sm_moveit_4::cl_perception', '_system::ClPerceptionSystem', and '::setSafeArmMotionToAvoidCubeCollisions'. The right box has a white background and contains the text 'sm_moveit_4::cl_perception', '_system::CpSimulatedGazeboPerception', and '::setSafeArmMotionToAvoidCubeCollisions'.

```
sm_moveit_4::cl_perception  
_system::CpSimulatedGazeboPerception  
::setSafeArmMotionToAvoidCubeCollisions
```