

```
anonymous_namespace  
{motion_with_control  
::cpp}::generateTrajectory
```

main



```
graph RL; main --> generateTrajectory
```

A diagram illustrating a function call. A box on the right labeled 'main' has a blue arrow pointing left to a larger box on the left. The larger box contains the text 'anonymous_namespace {motion_with_control ::cpp}::generateTrajectory'.