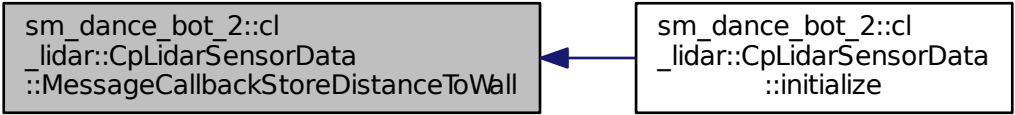


```
sm_dance_bot_2::cl  
_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall
```



A diagram showing a call from an initialize function to a callback store. On the right, a white box contains the text 'sm_dance_bot_2::cl', '_lidar::CpLidarSensorData', and '::initialize'. A blue arrow points from this box to a gray box on the left. The gray box contains the text 'sm_dance_bot_2::cl', '_lidar::CpLidarSensorData', and '::MessageCallbackStoreDistanceToWall'.

```
sm_dance_bot_2::cl  
_lidar::CpLidarSensorData  
::initialize
```