```
smacc::ISmaccClientBehavior
- stateMachine
currentState
- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- onOrthogonalAllocation()
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
              Δ
                       multirole sensor
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                       Behavior < ClientType >
                     + deferedEventPropagation
                     + CbDefaultMultiRoleSensor
                     Behavior()
                     + onOrthogonalAllocation()
                     + propagateEvent()
                     + propagateEvent2()
                     + onEntry()
                     + onExit()
                     + onMessageCallback()
                     + getEventLabel()
                           < ClLidarSensor >
 cl_multirole_sensor
::CbDefaultMultiRoleSensor
  Behavior < ClLidarSensor >
 + sensor

    + deferedEventPropagation

  + CbDefaultMultiRoleSensor
 Behavior()
 + onOrthogonalAllocation()
 + propagateEvent()
 + propagateEvent2()
 + onEntry()
 + onExit()
 + onMessageCallback()
 + getEventLabel()
               Д
    sm_ridgeback_floor
    _coverage_static_1::
cl_lidar::CbLidarSensor
    + CbLidarSensor()
    + onEntry()
    + onMessageCallback()
```