

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::updateCarrotGoal"]
```

A diagram showing a call sequence. A white box on the left contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from this box to a gray box on the right. The gray box contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::updateCarrotGoal'.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::updateCarrotGoal
```