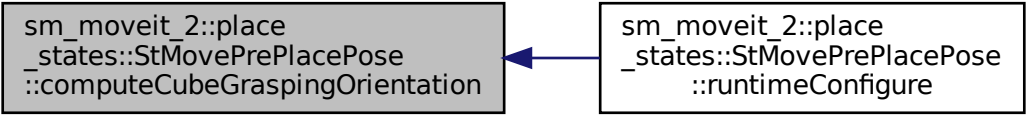


```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::computeCubeGraspingOrientation
```



A diagram showing a call from the `runtimeConfigure` function to the `computeCubeGraspingOrientation` function. The `runtimeConfigure` function is in a white box on the right, and the `computeCubeGraspingOrientation` function is in a gray box on the left. A blue arrow points from the `runtimeConfigure` box to the `computeCubeGraspingOrientation` box.

```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::runtimeConfigure
```