

```
graph LR; A["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::update"] --> B["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::createVirtualCollisionWalls"]; B --> C["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::createCollisionBox"]
```

sm\_moveit\_wine\_serve  
::cl\_move\_group\_interface  
::CpConstraintLateralWorkspace  
::update

sm\_moveit\_wine\_serve  
::cl\_move\_group\_interface  
::CpConstraintLateralWorkspace  
::createVirtualCollisionWalls

sm\_moveit\_wine\_serve  
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::CpConstraintLateralWorkspace  
::createCollisionBox