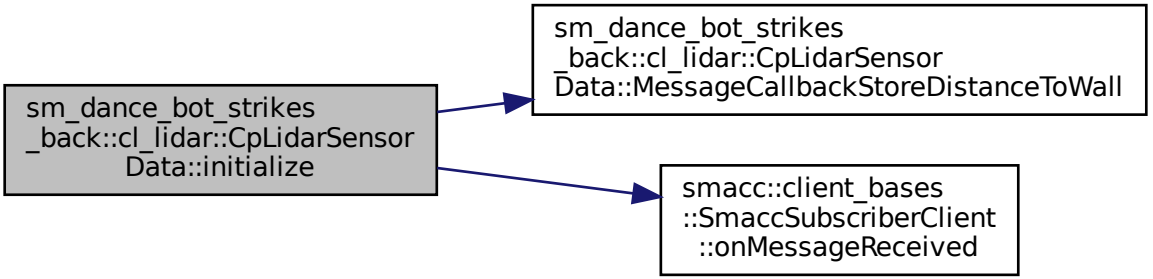
sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::initialize
sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::MessageCallbackStoreDistanceToWall
smacc::client_bases
::SmaccSubscriberClient
::onMessageReceived