

mecanum\_drive\_controller  
::MecanumDriveController  
::starting

mecanum\_drive\_controller  
::MecanumDriveController  
::stopping

mecanum\_drive\_controller  
::MecanumDriveController::brake

```
graph LR; A["mecanum_drive_controller  
::MecanumDriveController  
::starting"] --> C["mecanum_drive_controller  
::MecanumDriveController::brake"]; B["mecanum_drive_controller  
::MecanumDriveController  
::stopping"] --> C;
```

The diagram illustrates two transitions from the MecanumDriveController class. The first transition is from the 'starting' state to the 'brake' state. The second transition is from the 'stopping' state to the 'brake' state. Both transitions are represented by blue arrows pointing from the source state boxes to the target state box.