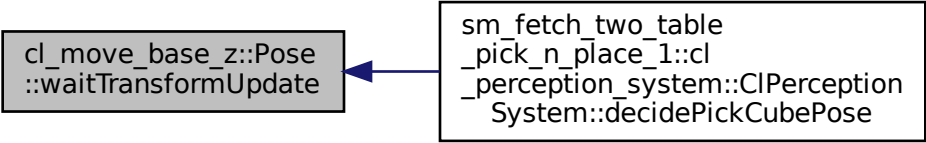


cl\_move\_base\_z::Pose  
::waitTransformUpdate



```
graph LR; A["sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::ClPerception  
System::decidePickCubePose"] --> B["cl_move_base_z::Pose  
::waitTransformUpdate"]
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'cl\_move\_base\_z::Pose' followed by '::waitTransformUpdate' on the next line. The box on the right is white with a black border and contains the text 'sm\_fetch\_two\_table' followed by '\_pick\_n\_place\_1::cl' on the next line, and '\_perception\_system::ClPerception' followed by 'System::decidePickCubePose' on the third line. A blue arrow points from the right side of the white box to the left side of the gray box.

sm\_fetch\_two\_table  
\_pick\_n\_place\_1::cl  
\_perception\_system::ClPerception  
System::decidePickCubePose