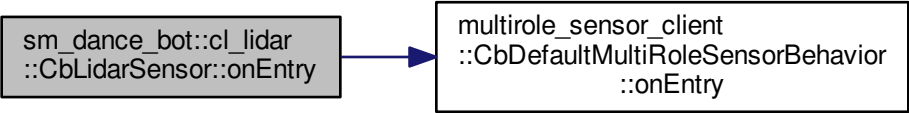


sm\_dance\_bot::cl\_lidar  
::CbLidarSensor::onEntry



```
graph LR; A["sm_dance_bot::cl_lidar  
::CbLidarSensor::onEntry"] --> B["multirole_sensor_client  
::CbDefaultMultiRoleSensorBehavior  
::onEntry"]
```

multirole\_sensor\_client  
::CbDefaultMultiRoleSensorBehavior  
::onEntry