BaseGlobalPlanner cl move base z::backward global planner::BackwardGlobal Planner - nh - forwardPathSub - planPub markersPub - lastForwardPathMsq - costmap ros - cmd server - skip straight motion distance - puresSpinningRadStep + BackwardGlobalPlanner() + ~BackwardGlobalPlanner() + makePlan() + makePlan() + createDefaultBackwardPath() + createPureSpiningAndStragiht LineBackwardPath() + initialize() onForwardTrailMsq() publishGoalMarker() commandServiceCall()