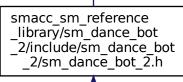
smacc\_sm\_reference \_library/sm\_dance\_bot \_2/include/sm\_dance\_bot \_2/orthogonals/or\_obstacle \_perception.h



smacc\_sm\_reference \_library/sm\_dance\_bot \_2/src/sm\_dance\_bot\_2.cpp