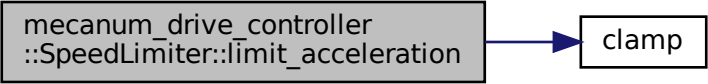


```
mecanum_drive_controller  
::SpeedLimiter::limit_acceleration
```



A diagram illustrating a function call. On the left, a gray rectangular box contains the text 'mecanum_drive_controller' followed by '::SpeedLimiter::limit_acceleration' on the next line. A dark blue arrow points from the right side of this box to a white rectangular box on the right. The white box contains the text 'clamp'.

clamp