

```
mecanum_drive_controller  
::MecanumDriveController  
::update
```



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::update] --> B[mecanum_drive_controller::Odometry::update];
```

A diagram showing a call from the `mecanum_drive_controller::MecanumDriveController::update` method to the `mecanum_drive_controller::Odometry::update` method. The source method is in a white box on the left, and the target method is in a gray box on the right, connected by a blue arrow.

```
mecanum_drive_controller  
::Odometry::update
```