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graph LR; A["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::update"] --> B["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::createVirtualCollisionWalls"]; B --> C["sm_moveit_wine_serve<br/>::cl_move_group_interface<br/>::CpConstraintLateralWorkspace<br/>::createCollisionBox"]
```

sm_moveit_wine_serve
::cl_move_group_interface
::CpConstraintLateralWorkspace
::update

sm_moveit_wine_serve
::cl_move_group_interface
::CpConstraintLateralWorkspace
::createVirtualCollisionWalls

sm_moveit_wine_serve
::cl_move_group_interface
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