

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/ms_dance_bot_run  
_mode/st_acquire_sensors.h"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/states/ms\_dance\_bot\_run  
\_mode/st\_acquire\_sensors.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp