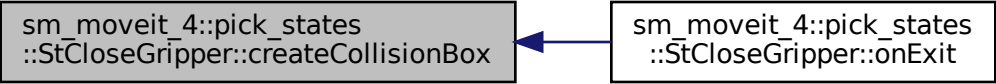


```
sm_moveit_4::pick_states  
::StCloseGripper::createCollisionBox
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'sm_moveit_4::pick_states' followed by '::StCloseGripper::createCollisionBox' on the next line. The box on the right is white and contains the text 'sm_moveit_4::pick_states' followed by '::StCloseGripper::onExit' on the next line. A dark blue arrow points from the right box to the left box, indicating a call or relationship between the two functions.

```
sm_moveit_4::pick_states  
::StCloseGripper::onExit
```