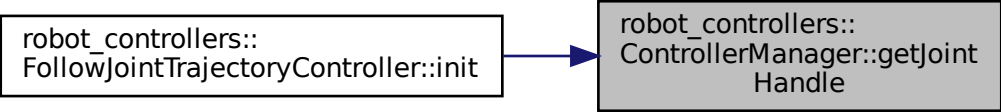


robot_controllers::
FollowJointTrajectoryController::init



```
graph LR; A[robot_controllers::  
FollowJointTrajectoryController::init] --> B[robot_controllers::  
ControllerManager::getJoint  
Handle];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'robot_controllers::' followed by 'FollowJointTrajectoryController::init' on two lines. The right box is gray with a black border and contains the text 'robot_controllers::' followed by 'ControllerManager::getJoint' and 'Handle' on three lines. A blue arrow points from the right side of the left box to the left side of the right box.

robot_controllers::
ControllerManager::getJoint
Handle