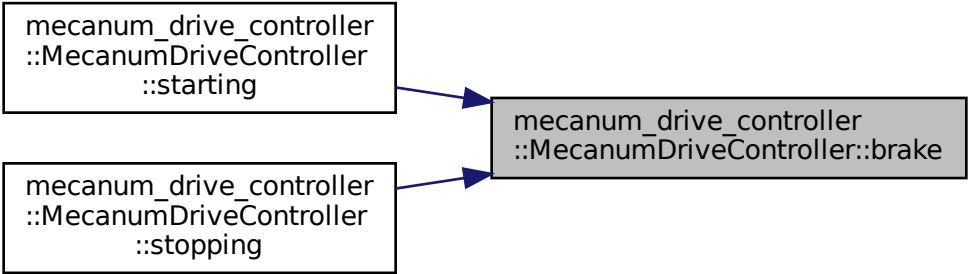


mecanum_drive_controller
::MecanumDriveController
::starting

mecanum_drive_controller
::MecanumDriveController
::stopping

mecanum_drive_controller
::MecanumDriveController::brake



```
graph LR; A[mecanum_drive_controller ::MecanumDriveController ::starting] --> C[mecanum_drive_controller ::MecanumDriveController::brake]; B[mecanum_drive_controller ::MecanumDriveController ::stopping] --> C;
```