

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a function call. A white rectangular box on the left contains the code snippet. A blue arrow points from the right side of this box to a gray rectangular box on the right, which contains the code snippet for the function's implementation.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```