

mecanum_drive_controller
::MecanumDriveController
::starting

mecanum_drive_controller
::MecanumDriveController
::stopping

mecanum_drive_controller
::MecanumDriveController::brake

```
graph LR; A[mecanum_drive_controller::MecanumDriveController::starting] --> C[mecanum_drive_controller::MecanumDriveController::brake]; B[mecanum_drive_controller::MecanumDriveController::stopping] --> C;
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