

submodules/robot_controllers
/robot_controllers/include
/robot_controllers/trajectory.h

```
graph TD; A["submodules/robot_controllers<br>/robot_controllers/include<br>/robot_controllers/trajectory.h"] --> B["ros/ros.h"]; A --> C["angles/angles.h"]; A --> D["trajectory_msgs/JointTrajectory.h"];
```

The diagram illustrates the include relationships for the file `/robot_controllers/trajectory.h`. It is a hierarchical structure where a parent header file includes three other header files. The parent file is located in the `submodules/robot_controllers/include` directory. The three included files are `ros/ros.h`, `angles/angles.h`, and `trajectory_msgs/JointTrajectory.h`.

ros/ros.h

angles/angles.h

trajectory_msgs/JointTrajectory.h