

sm\_dance\_bot::cl\_service3  
::CbService3::onEntry

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graph LR; A[sm_dance_bot::cl_service3::CbService3::onEntry] --> B[smacc::client_bases::SmaccServiceClient::call]; A --> C[smacc::ISmaccClientBehavior::requiresClient];
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smacc::client\_bases  
::SmaccServiceClient::call

smacc::ISmaccClientBehavior  
::requiresClient