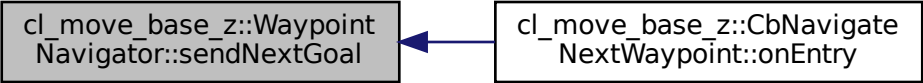


cl_move_base_z::Waypoint
Navigator::sendNextGoal



```
graph LR; A[cl_move_base_z::CbNavigateNextWaypoint::onEntry] --> B[cl_move_base_z::WaypointNavigator::sendNextGoal];
```

cl_move_base_z::CbNavigate
NextWaypoint::onEntry