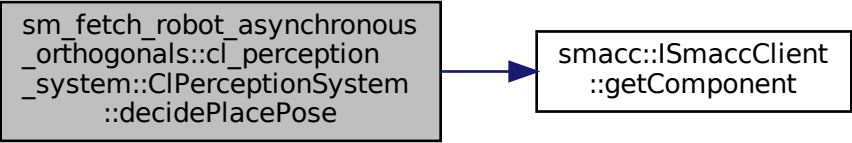


```
sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::ClPerceptionSystem  
::decidePlacePose
```



```
graph LR; A["sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::ClPerceptionSystem  
::decidePlacePose"] --> B["smacc::ISmaccClient  
::GetComponent"]
```

```
smacc::ISmaccClient  
::GetComponent
```