

submodules/robot\_controllers  
/robot\_controllers\_interface  
/include/robot\_controllers\_interface  
/joint\_handle.h

```
graph TD; A["submodules/robot_controllers<br>/robot_controllers_interface<br>/include/robot_controllers_interface<br>/joint_handle.h"] --> B["robot_controllers_interface<br>/handle.h"]; B --> C["string"]; B --> D["boost/shared_ptr.hpp"];
```

robot\_controllers\_interface  
/handle.h

string

boost/shared\_ptr.hpp