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graph BT; A["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/src/sm_ridgeback_floor_coverage_dynamic_1.cpp"] --> B["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/sm_ridgeback_floor_coverage_dynamic_1.h"]; B --> C["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/include/sm_ridgeback_floor_coverage_dynamic_1/orthogonals/or_obstacle_perception.h"]; C --> D["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/include/sm_ridgeback_floor_coverage_dynamic_1/clients/cl_lidar/components/cp_lidar_data.h"];
```

smacc\_sm\_reference  
\_library/sm\_ridgeback  
\_floor\_coverage\_dynamic  
\_1/include/sm\_ridgeback  
\_floor\_coverage\_dynamic\_1  
/clients/cl\_lidar/components  
/cp\_lidar\_data.h

smacc\_sm\_reference  
\_library/sm\_ridgeback  
\_floor\_coverage\_dynamic  
\_1/include/sm\_ridgeback  
\_floor\_coverage\_dynamic\_1  
/orthogonals/or\_obstacle\_perception.h

smacc\_sm\_reference  
\_library/sm\_ridgeback  
\_floor\_coverage\_dynamic  
\_1/include/sm\_ridgeback  
\_floor\_coverage\_dynamic\_1  
/sm\_ridgeback\_floor\_coverage  
\_dynamic\_1.h

smacc\_sm\_reference  
\_library/sm\_ridgeback  
\_floor\_coverage\_dynamic  
\_1/src/sm\_ridgeback\_floor  
\_coverage\_dynamic\_1.cpp