

```
mecanum_drive_controller  
::MecanumDriveController::init
```



```
graph LR; A[mecanum_drive_controller  
::MecanumDriveController::init] --> B[mecanum_drive_controller  
::MecanumDriveController  
::setWheelParamsFromUrdf];
```

A diagram showing a function call. A white box on the left contains the text 'mecanum_drive_controller' followed by '::MecanumDriveController::init'. A blue arrow points from this box to a gray box on the right. The gray box contains the text 'mecanum_drive_controller' followed by '::MecanumDriveController' and '::setWheelParamsFromUrdf' on separate lines.

```
mecanum_drive_controller  
::MecanumDriveController  
::setWheelParamsFromUrdf
```