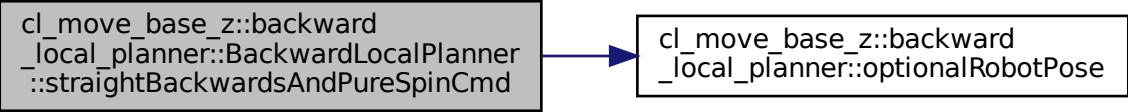


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```



A diagram consisting of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains three lines of C++ code. The right box has a white background and contains two lines of C++ code. The arrow indicates a transformation or conversion from the state in the left box to the state in the right box.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```