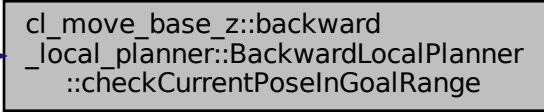


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```

A rectangular box with a black border containing the text for a function call to computeVelocityCommands.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkCurrentPoseInGoalRange
```

A rectangular box with a black border and a light gray fill, containing the text for a function call to checkCurrentPoseInGoalRange.