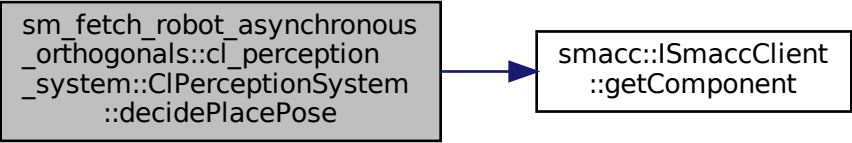```
sm_fetch_robot_asynchronous
_orthogonals::cl_perception
_system::ClPerceptionSystem
::decidePlacePose
```

```
smacc::ISmaccClient
::getComponent
```