


```
sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::decidePlacePose
```



A diagram showing a call from a function in the sm_moveit_screw_loop namespace to a method in the smacc::ISmaccClient interface. The call is represented by a blue arrow pointing from the left box to the right box.

```
smacc::ISmaccClient  
::getComponent
```