

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a sequence of function calls. A white box on the left contains the code for `computeVelocityCommands`. A blue arrow points from this box to a gray box on the right, which contains the code for `updateCarrotGoal`. Both boxes represent the same function context: `cl_move_base_z::backward` and `_local_planner::BackwardLocalPlanner`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::updateCarrotGoal
```