

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintTableWorkspaces  
::setBigTableCollisionVolume
```



The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains four lines of C++ code. The right box has a white background and contains the same four lines of code, but with an additional line, `::update`, indented under the `Workspaces` line. The arrow is a solid blue line with a triangular head pointing towards the right box.

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintTableWorkspaces  
    ::update
```