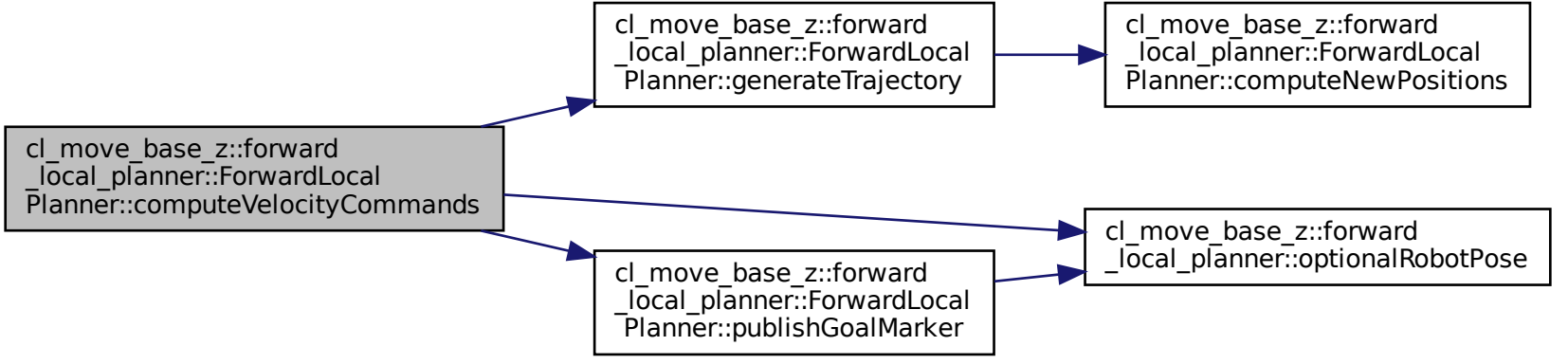
cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::computeVelocityCommands
cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::generateTrajectory
cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::computeNewPositions
cl_move_base_z::forward
_local_planner::optionalRobotPose
cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::publishGoalMarker