

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```

A diagram illustrating a function call. A blue arrow points from the `computeVelocityCommands` method of the `PureSpinningLocalPlanner` class to the `pure` static method of the `cl_move_base_z::pure_spinning_local_planner` namespace. The target box is shaded gray, while the source box is white.

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```