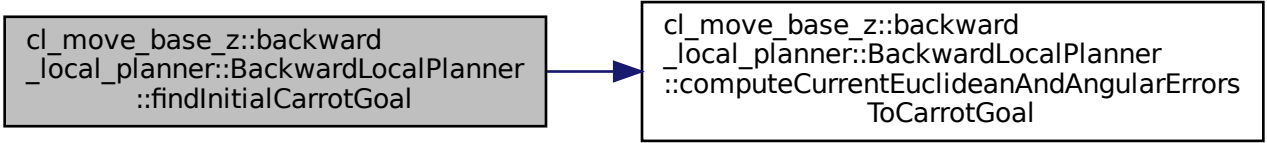
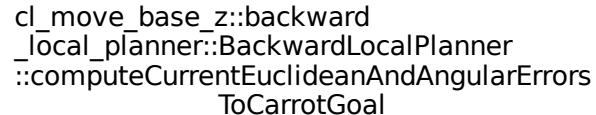


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```

A rectangular box with a black border and a light gray fill. It contains three lines of C++ code. The first line is 'cl\_move\_base\_z::backward', the second is '\_local\_planner::BackwardLocalPlanner', and the third is '::findInitialCarrotGoal'. A blue arrow points from the right side of this box to the left side of the box on the right.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```

A rectangular box with a black border and a white fill. It contains four lines of C++ code. The first line is 'cl\_move\_base\_z::backward', the second is '\_local\_planner::BackwardLocalPlanner', the third is '::computeCurrentEuclideanAndAngularErrors', and the fourth is 'ToCarrotGoal'. A blue arrow points from the right side of the box on the left to the left side of this box.