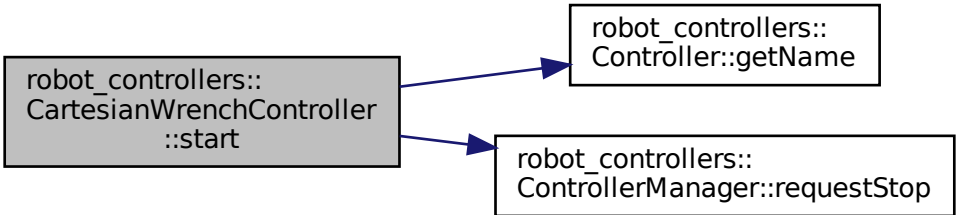
robot_controllers::
CartesianWrenchController
::start
robot_controllers::
Controller::getName
robot_controllers::
ControllerManager::requestStop