

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```

A diagram showing a call to findInitialCarrotGoal from a backward movement function. A grey box on the left contains the code snippet. A blue arrow points from this box to a white box on the right, which contains the code snippet for computeCurrentEuclideanAndAngularErrorsToCarrotGoal.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```