```
robot controllers::
           .
Handle
     + Handle()
     + ~Handle()
     + getName()
     Handle()
     - operator=()
robot controllers::
         Controller
- name
+ Controller()
+ ~Controller()
+ init()
+ start()
+ stop()
+ reset()
+ update()
+ getName()
+ getType()
+ getCommandedNames()
+ getClaimedNames()
robot controllers::
  ScaledMimicController
- initialized
joint_to_mimic_joint_to_control_
- scale
+ ScaledMimicController()
+ ~ScaledMimicController()
+ init()
+ start()
+ stop()
+ reset()
+ update()
+ getType()
+ getCommandedNames()
+ getClaimedNames()
```