


```
sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::decidePlacePose
```



A diagram showing a call from a function in the sm_moveit_screw_loop namespace to a component in the smacc namespace. The left box, which is shaded gray, contains the code for the caller: sm_moveit_screw_loop, ::cl_perception_system, and ::ClPerceptionSystem::decidePlacePose. A blue arrow points from the right side of this box to the right box. The right box is white with a black border and contains the code for the callee: smacc::ISmaccClient and ::getComponent.

```
smacc::ISmaccClient  
::getComponent
```