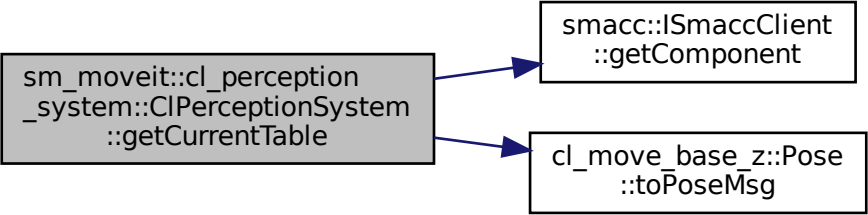


sm\_moveit::cl\_perception  
\_system::ClPerceptionSystem  
::getCurrentTable



```
graph LR; A["sm_moveit::cl_perception  
_system::ClPerceptionSystem  
::getCurrentTable"] --> B["smacc::ISmaccClient  
::GetComponent"]; A --> C["cl_move_base_z::Pose  
::toPoseMsg"]
```

The diagram illustrates a single source box on the left with two arrows pointing to two separate destination boxes on the right. The source box is shaded gray and contains the text 'sm\_moveit::cl\_perception \_system::ClPerceptionSystem ::getCurrentTable'. The top destination box is white and contains 'smacc::ISmaccClient ::GetComponent'. The bottom destination box is white and contains 'cl\_move\_base\_z::Pose ::toPoseMsg'.

smacc::ISmaccClient  
::GetComponent

cl\_move\_base\_z::Pose  
::toPoseMsg