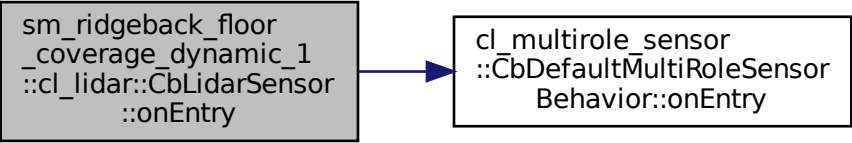


sm\_ridgeback\_floor  
\_coverage\_dynamic\_1  
::cl\_lidar::CbLidarSensor  
::onEntry



```
graph LR; A["sm_ridgeback_floor_coverage_dynamic_1::cl_lidar::CbLidarSensor::onEntry"] --> B["cl_multirole_sensor::CbDefaultMultiRoleSensorBehavior::onEntry"]
```

cl\_multirole\_sensor  
::CbDefaultMultiRoleSensor  
Behavior::onEntry