


```
sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall
```



A blue arrow points from the right box to the left box, indicating a dependency or relationship between the two state machine configurations.

```
sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::onInitialize
```