

```
graph BT; A["smaccc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/states/st_acquire_sensors.h"] --> B["smaccc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.h"]; B --> C["smaccc_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance  
_bot_strikes_back.cpp"]
```

smaccc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/states/st_acquire_sensors.h

smaccc_sm_reference
_library/sm_dance_bot
_strikes_back/include
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smaccc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back.cpp