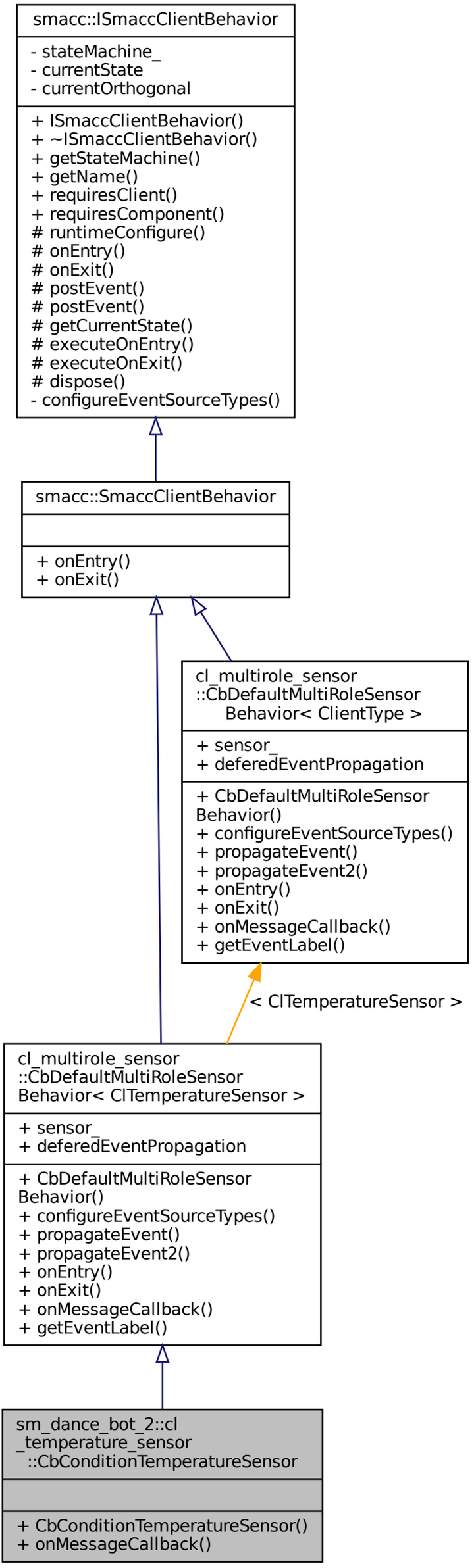
smacc::ISmaccClientBehavior
- stateMachine_
- currentState
- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- configureEventSourceTypes()
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior< ClientType >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
< ClTemperatureSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior< ClTemperatureSensor >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_2::cl
_temperature_sensor
::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()