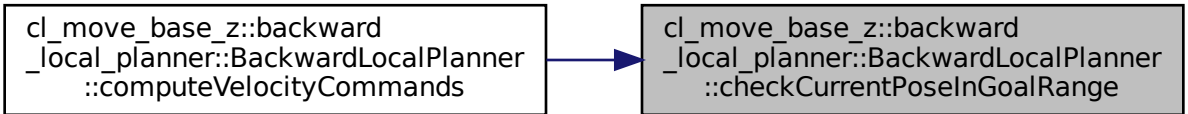
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::computeVelocityCommands
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::checkCurrentPoseInGoalRange