

fetch_arm::IKFastKinematics
Plugin::getSolution

main

ikfast::IkSolutionList
::GetSolution

```
graph LR; A["fetch_arm::IKFastKinematics  
Plugin::getSolution"] --> C["ikfast::IkSolutionList  
::GetSolution"]; B["main"] --> C;
```

The diagram illustrates a call graph with three nodes. The node 'fetch_arm::IKFastKinematics Plugin::getSolution' is a white rectangle with a black border. The node 'main' is a smaller white rectangle with a black border. The node 'ikfast::IkSolutionList ::GetSolution' is a gray rectangle with a black border. Two blue arrows point from the first two nodes to the third node, indicating that both functions call 'ikfast::IkSolutionList ::GetSolution'.