

```
graph BT; A["smacc_sm_reference  
_library/sm_mtc_picknplace  
/include/sm_mtc_picknplace  
/states/ms_pick_object_states  
/st_grasp_pose_IK.h"] <-- B["smacc_sm_reference  
_library/sm_mtc_picknplace  
/include/sm_mtc_picknplace  
/sm_mtc_picknplace.h"]; B <-- C["smacc_sm_reference  
_library/sm_mtc_picknplace  
/src/sm_mtc_picknplace_node.cpp"]
```

smacc_sm_reference
_library/sm_mtc_picknplace
/include/sm_mtc_picknplace
/states/ms_pick_object_states
/st_grasp_pose_IK.h

smacc_sm_reference
_library/sm_mtc_picknplace
/include/sm_mtc_picknplace
/sm_mtc_picknplace.h

smacc_sm_reference
_library/sm_mtc_picknplace
/src/sm_mtc_picknplace_node.cpp