```
    stateMachine

    orthogonal

+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ configureEventSourceTypes()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
# createComponent()
# setStateMachine()
# setOrthogonal()
   smacc::client_bases
     ::ISmaccActionClient
   # name_
   + ISmaccActionClient()
   + ~ISmaccActionClient()
   + getNamespace()
   + cancelGoal()
   + getState()
                   smacc::client bases
                   ::SmaccActionClientBase
                           < ActionType >
                   + name
                   + onSucceeded
                    + onAborted
                   + onPreempted
                   + onRejected
                    + postSuccessEvent
                   + postAbortedEvent
                   + postPreemptedEvent
                    + postRejectedEvent
                   + postFeedbackEvent
                   + done cb
                    + active_cb
                   + feedback_cb
                   # client
                   + ACTION_DEFINITION()
                   + SmaccActionClientBase()
                      ~SmaccActionClientBase()
                   + initialize()
                   + postResultEvent()
                    + configureEventSourceTypes()
                   + onSucceeded()
                   + onSucceeded()
                    + onAborted()
                   + onAborted()
                   + onPreempted()
                    + onPreempted()
                   + onRejected()
                   + onRejected()
                    + cancelGoal()
                   + getState()
                   + sendGoal()
                    + getEventLabel()
                   # onFeedback()
                   # onResult()
                            < sm_dance_bot::LEDControl
                                     Action >
 smacc::client bases
 ::SmaccActionClientBase
 < sm_dance_bot::LEDControlAction >
  + name
 + onSucceeded
 + onAborted
 + onPreempted
 + onRejected
 + postSuccessEvent
  + postAbortedEvent
 + postPreemptedEvent
 + postRejectedEvent
 + postFeedbackEvent
 + done_cb
 + active_cb
 + feedback_cb
 # client
 + ACTION_DEFINITION()
 + SmaccActionClientBase()
 + ~SmaccActionClientBase()
 + initialize()
 + postResultEvent()
 + configureEventSourceTypes()
 + onSucceeded()
 + onSucceeded()
 + onAborted()
 + onAborted()
 + onPreempted()
 + onPreempted()
 + onRejected()
 + onRejected()
 + cancelGoal()
 + getState()
```

+ sendGoal()
+ getEventLabel()
onFeedback()
onResult()

sm_dance_bot::cl_led ::ClLED

+ ACTION_DEFINITION()

+ CILED() + getName() + ~CILED()

smacc::ISmaccClient

components