```
smacc::ISmaccClientBehavior

    stateMachine

  currentState
 - currentOrthogonal
 + ISmaccClientBehavior()
     -ISmaccClientBehavior()
 + getStateMachine()
 + getName()
 + requiresClient()
 + requiresComponent()
 # runtimeConfigure()
 # onEntry()
 # onExit()
 # postEvent()
 # postEvent()
 # getCurrentState()
 # executeOnEntry()
 # executeOnExit()
  configureEventSourceTypes()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                     D
                        multirole
                                  sensor
                     :: CbDefault MultiRole Sensor
                         Behavior < ClientType >
                     + sensor
                     + deferedEventPropagation
                     + CbDefaultMultiRoleSensor
                     Behavior()
                     + configureEventSourceTypes()
                     + propagateEvent()
                     + propagateEvent2()
                     + onEntry()
                     + onExit()
                      + onMessageCallback()
                     + getEventLabel()
                            < ClTemperatureSensor >
cl multirole sensor
 :CbDefaultMultiRoleSensor
Behavior < ClTemperatureSensor >
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_strikes
_back::cl_temperature
sensor::CbConditionTemperature
              Sensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```