

submodules/robot_controllers
/robot_controllers/include
/robot_controllers/trajectory.h

```
graph TD; A["submodules/robot_controllers<br>/robot_controllers/include<br>/robot_controllers/trajectory.h"] --> B["ros/ros.h"]; A --> C["angles/angles.h"]; A --> D["trajectory_msgs/JointTrajectory.h"];
```

The diagram illustrates the include relationships for the file `/robot_controllers/trajectory.h`. It is a hierarchical structure where the top node is the header file itself, and it includes three other files: `ros/ros.h`, `angles/angles.h`, and `trajectory_msgs/JointTrajectory.h`. The top node is highlighted with a gray background, while the included files are in white boxes. Blue arrows point from the top node to each of the three included files.

ros/ros.h

angles/angles.h

trajectory_msgs/JointTrajectory.h