```
smacc::ISmaccClientBehavior

    stateMachine_

- currentState

    currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
configureEventSourceTypes()
              Δ
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
                   cl_multirole_sensor
                   :: C

b

Default M

ultiRole Sensor
                       Behavior < ClientType >
                   + sensor
                   + deferedEventPropagation
                   + CbDefaultMultiRoleSensor
                   Behavior()
                   + configureEventSourceTypes()
                   + propagateEvent()
                   + propagateEvent2()
                   + onEntry()
                   + onExit()
                   + onMessageCallback()
                   + getEventLabel()
                           < sm_ridgeback_floor
                           coverage_dynamic_1::
                          cl_lidar::ClLidarSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < sm_ridgeback_floor
_coverage_dynamic_1::cl_lidar
       ::ClLidarSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
   sm_ridgeback_floor
    coverage_dynamic
   ::cl lidar::CbLidarSensor
    + CbLidarSensor()
   + onEntry()
    + onMessageCallback()
```