


```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::generateTrajectory
```



```
graph LR; A[cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands] --> B[cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::generateTrajectory];
```

A diagram showing a call from the `computeVelocityCommands` method to the `generateTrajectory` method. The source box on the right is white, and the target box on the left is gray. A blue arrow points from the source to the target.

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