```
robot controllers::
           Handle
      + Handle()
      + ~Handle()
      + getName()
      Handle()
      operator=()
              Λ
 robot controllers::
          Controller
 - name
 + Controller()
 + ~Controller()
 + init()
 + start()
 + stop()
 + reset()
 + update()
 + getName()
 + getType()
 + getCommandedNames()
 + getClaimedNames()
              Λ
robot controllers::
  ParallelGripperController
- initialized
- manager_

    left

right
- goal
- effort
max_position_
- max effort

    server

use_centering_controller
- centering pid
+ ParallelGripperController()
+ ~ParallelGripperController()
+ init()
+ start()
+ stop()
+ reset()
+ update()
+ getType()
+ getCommandedNames()
+ getClaimedNames()
executeCb()
```