

```
graph BT; A["smacc_sm_reference_library/sm_dance_bot/include/sm_dance_bot/st_navigate_to_waypoint_1.h"] --> B["smacc_sm_reference_library/sm_dance_bot/include/sm_dance_bot/sm_dance_bot.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot/src/sm_dance_bot.cpp"];
```

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
/states/st_navigate_to
_waypoint_1.h

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
_src/sm_dance_bot.cpp