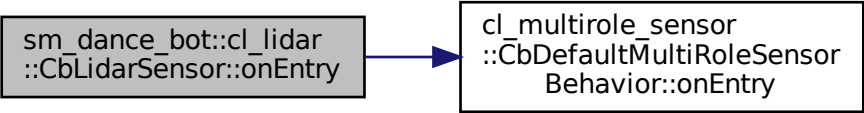


sm_dance_bot::cl_lidar
::CbLidarSensor::onEntry



```
graph LR; A["sm_dance_bot::cl_lidar  
::CbLidarSensor::onEntry"] --> B["cl_multirole_sensor  
::CbDefaultMultiRoleSensor  
Behavior::onEntry"]
```

cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior::onEntry