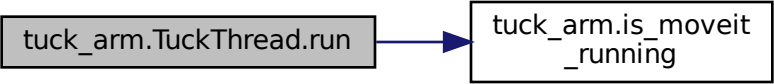


tuck_arm.TuckThread.run



```
graph LR; A[tuck_arm.TuckThread.run] --> B[tuck_arm.is_moveit_running];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'tuck_arm.TuckThread.run'. The right box is white with a black border and contains the text 'tuck_arm.is_moveit_running' on two lines. A dark blue arrow points from the right side of the left box to the left side of the right box.

tuck_arm.is_moveit
_running