

fetch_arm::IKFastKinematics
Plugin::getSolution

main

ikfast::IkSolutionList
::GetSolution

```
graph LR; A["fetch_arm::IKFastKinematics  
Plugin::getSolution"] --> C["ikfast::IkSolutionList  
::GetSolution"]; B["main"] --> C;
```

The diagram illustrates a call graph with three nodes. The top-left node, labeled 'fetch_arm::IKFastKinematics Plugin::getSolution', has a blue arrow pointing to the rightmost node. The bottom-left node, labeled 'main', also has a blue arrow pointing to the same rightmost node. The rightmost node is labeled 'ikfast::IkSolutionList ::GetSolution' and is shaded gray, indicating it is the target or a final function in the sequence.