

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



A diagram showing a transition between two states. On the left, a gray-shaded box contains the text 'cl_move_base_z::forward', '_local_planner::ForwardLocal', and 'Planner::publishGoalMarker'. A blue arrow points from this box to a white box on the right. The white box contains the text 'cl_move_base_z::forward', '_local_planner::optionalRobotPose', and 'RobotPose'.

```
cl_move_base_z::forward  
_local_planner::optionalRobotPose  
RobotPose
```