

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached"]
```

A diagram showing a call sequence. A grey box on the left contains the code for the default backward command. A blue arrow points from this box to a white box on the right, which contains the code for the check goal reached function. Both boxes have a black border.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached
```