

```
graph BT; A["smacc_sm_reference  
_library/sm_moveit_2  
_include/sm_moveit_2  
_states/pick_states/st  
_close_gripper.h"] --> B["smacc_sm_reference  
_library/sm_moveit_2  
_include/sm_moveit_2  
_superstates/ss_pick_object.h"]; B --> C["smacc_sm_reference  
_library/sm_moveit_2  
_include/sm_moveit_2  
_sm_moveit_2.h"]; C --> D["smacc_sm_reference  
_library/sm_moveit_2  
_src/sm_moveit_2_node.cpp"];
```

smacc_sm_reference
_library/sm_moveit_2
_include/sm_moveit_2
_states/pick_states/st
_close_gripper.h

smacc_sm_reference
_library/sm_moveit_2
_include/sm_moveit_2
_superstates/ss_pick_object.h

smacc_sm_reference
_library/sm_moveit_2
_include/sm_moveit_2
_sm_moveit_2.h

smacc_sm_reference
_library/sm_moveit_2
_src/sm_moveit_2_node.cpp