

tuck_arm.MoveItThread.
__init__

FollowTeleop::update

HeadTeleop::update

TeleopComponent::start

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graph LR; A[tuck_arm.MoveItThread.__init__] --> D[TeleopComponent::start]; B[FollowTeleop::update] --> D; C[HeadTeleop::update] --> D;
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The diagram illustrates a dependency or call relationship. Three source functions, each in a white box with a black border, are positioned on the left. Blue arrows point from each of these source functions to a single target function, 'TeleopComponent::start', which is in a gray box with a black border on the right. The source functions are 'tuck_arm.MoveItThread.__init__' (top), 'FollowTeleop::update' (middle), and 'HeadTeleop::update' (bottom). The target function is 'TeleopComponent::start'.