

sm_dance_bot::cl_lidar
::CbLidarSensor::onEntry

sm_dance_bot_2::cl
_lidar::CbLidarSensor
::onEntry

sm_dance_bot_strikes
_back::cl_lidar::CbLidarSensor
::onEntry

cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior::onEntry

```
graph LR; A[sm_dance_bot::cl_lidar::CbLidarSensor::onEntry] --> D[cl_multirole_sensor::CbDefaultMultiRoleSensorBehavior::onEntry]; B[sm_dance_bot_2::cl_lidar::CbLidarSensor::onEntry] --> D; C[sm_dance_bot_strikes_back::cl_lidar::CbLidarSensor::onEntry] --> D;
```

The diagram illustrates three state machine (sm) entry points on the left, each with a blue arrow pointing to a single, shaded rectangular box on the right. The boxes on the left contain text representing state machine names and sensor entry functions. The box on the right is shaded gray and contains text representing a multirole sensor behavior entry function.