```
smacc::SmaccClientBehavior

    stateMachine

- currentState

    currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
configureEventSourceTypes()
 cl ros publisher::CbPublish
    Once < RosMsqType >
 - deferedPublishFn

    client

 + CbPublishOnce()
 + CbPublishOnce()
 + setMessage()
 + onEntry()
 + onExit()
```