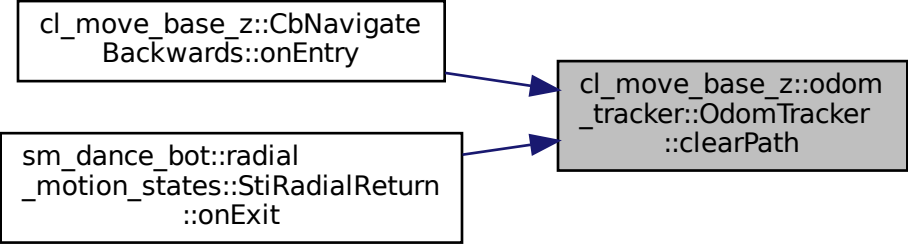


cl_move_base_z::CbNavigate
Backwards::onEntry

sm_dance_bot::radial
_motion_states::StiRadialReturn
::onExit

cl_move_base_z::odom
_tracker::OdomTracker
::clearPath



```
graph LR; A[cl_move_base_z::CbNavigateBackwards::onEntry] --> C[cl_move_base_z::odom_tracker::OdomTracker::clearPath]; B[sm_dance_bot::radial_motion_states::StiRadialReturn::onExit] --> C;
```

The diagram illustrates a state transition or action sequence. Two source boxes on the left point via blue arrows to a single target box on the right. The top source box contains the text 'cl_move_base_z::CbNavigateBackwards::onEntry'. The bottom source box contains the text 'sm_dance_bot::radial_motion_states::StiRadialReturn::onExit'. The target box, which has a gray background, contains the text 'cl_move_base_z::odom_tracker::OdomTracker::clearPath'.