

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the code for the `findInitialCarrotGoal` method. The right box is white with a black border and contains the code for the `computeCurrentEuclideanAndAngularErrorsToCarrotGoal` method. A blue arrow points from the right side of the left box to the left side of the right box, indicating a call or dependency.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```