

```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::onInitialize
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'sm_fetch_screw_loop', '_1::cl_perception_system', '::CpSimulatedGazeboPerception', and '::onInitialize'. The right box has a white background and contains the text 'sm_fetch_screw_loop', '_1::cl_perception_system', '::CpSimulatedGazeboPerception', and '::simulatedLinkStateCallback'.

```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::simulatedLinkStateCallback
```