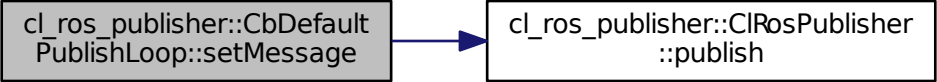


cl\_ros\_publisher::CbDefault  
PublishLoop::setMessage



```
graph LR; A[cl_ros_publisher::CbDefault PublishLoop::setMessage] --> B[cl_ros_publisher::ClRosPublisher::publish]
```

cl\_ros\_publisher::ClRosPublisher  
::publish