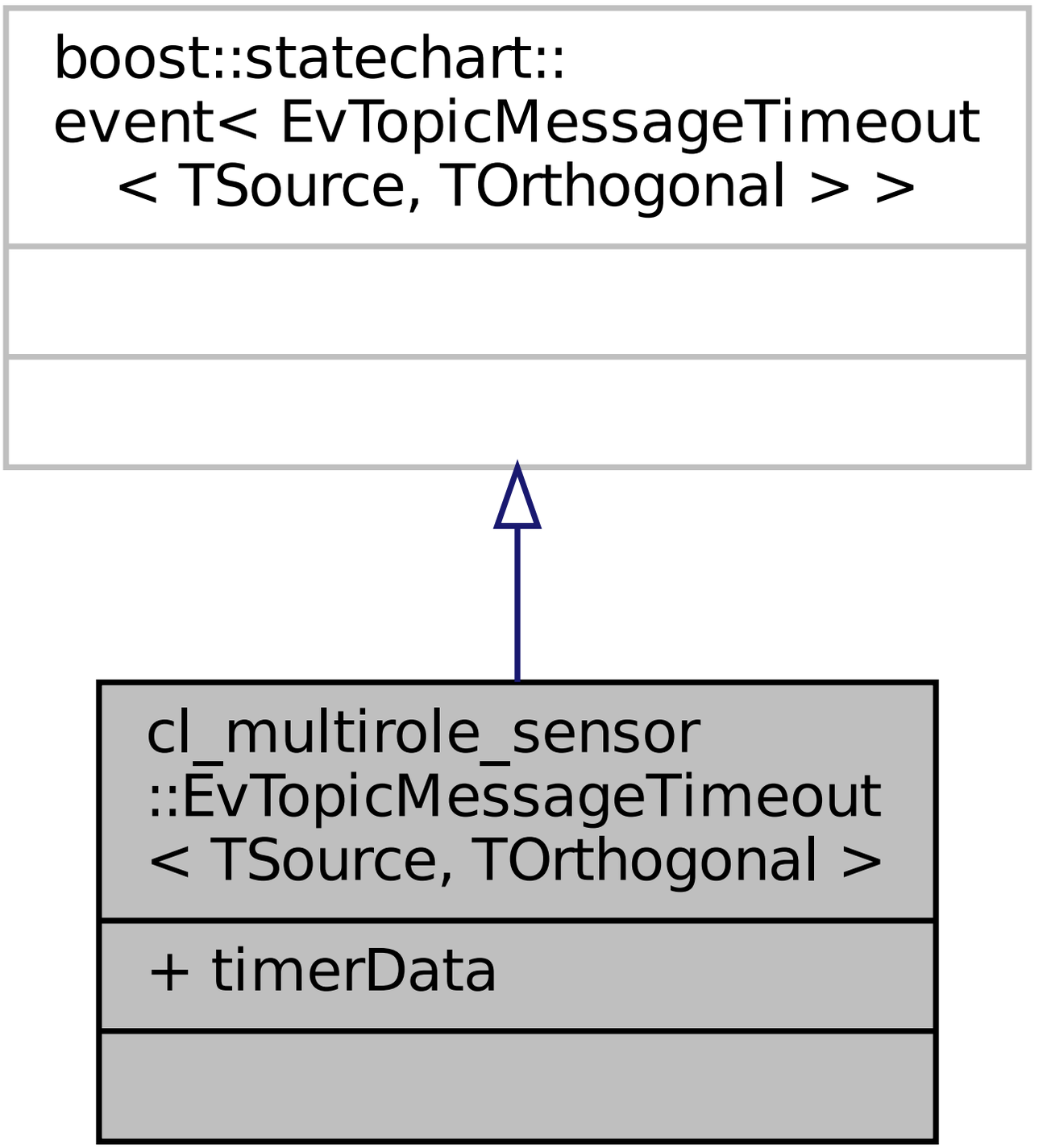
boost::statechart::
event< EvTopicMessageTimeout
< TSource, TOrthogonal > >
cl_multirole_sensor
::EvTopicMessageTimeout
< TSource, TOrthogonal >
+ timerData