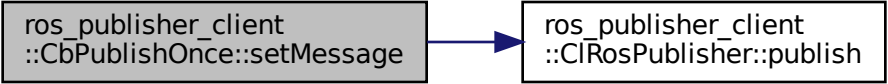


ros_publisher_client
::CbPublishOnce::setMessage



```
graph LR; A[ros_publisher_client::CbPublishOnce::setMessage] --> B[ros_publisher_client::ClRosPublisher::publish]
```

ros_publisher_client
::ClRosPublisher::publish