

sm\_dance\_bot::cl\_service3  
::CbService3::onEntry

sm\_dance\_bot\_2::cl  
\_service3::CbService3  
::onEntry

sm\_dance\_bot\_strikes  
\_back::cl\_service3::CbService3  
::onEntry

smacc::client\_bases  
::SmaccServiceClient::call

```
graph LR; A[sm_dance_bot::cl_service3::CbService3::onEntry] --> D[smacc::client_bases::SmaccServiceClient::call]; B[sm_dance_bot_2::cl_service3::CbService3::onEntry] --> D; C[sm_dance_bot_strikes_back::cl_service3::CbService3::onEntry] --> D;
```

The diagram illustrates a call relationship in a codebase. Three source functions, each in a white box with a black border, point via blue arrows to a single target function in a gray box with a black border. The source functions are: 1) `sm_dance_bot::cl_service3::CbService3::onEntry`, 2) `sm_dance_bot_2::cl_service3::CbService3::onEntry`, and 3) `sm_dance_bot_strikes_back::cl_service3::CbService3::onEntry`. The target function is `smacc::client_bases::SmaccServiceClient::call`.