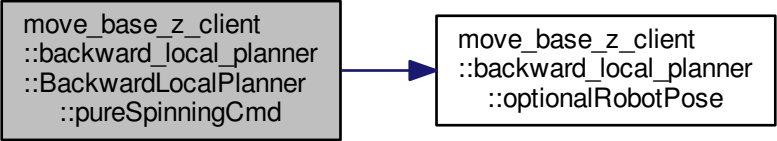


```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
::pureSpinningCmd
```



A diagram illustrating a transformation between two code snippets. On the left, a gray box contains a C++-style namespace call: `move_base_z_client::backward_local_planner::BackwardLocalPlanner::pureSpinningCmd`. A blue arrow points from this box to a white box on the right. The white box contains the equivalent ROS service call: `move_base_z_client::backward_local_planner::optionalRobotPose`.

```
move_base_z_client  
::backward_local_planner  
::optionalRobotPose
```