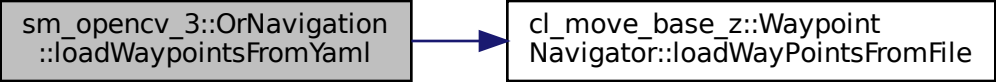


sm_opencv_3::OrNavigation
::loadWaypointsFromYaml



```
graph LR; A[sm_opencv_3::OrNavigation::loadWaypointsFromYaml] --> B[cl_move_base_z::WaypointNavigator::loadWayPointsFromFile]
```

cl_move_base_z::Waypoint
Navigator::loadWayPointsFromFile