```
move_group_interface
                                               client::CbDetachObject
                                                      ::onEntry
                                              sm_fetch_six_table
                                              _pick_n_sort_1::cl_gripper
                                              ::CbOpenGripper::onEntry
                                              sm_fetch_two_table
                                              _pick_n_place_1::cl
                                              _gripper::CbOpenGripper
                                                      ::onEntry
                                          cl_ros_timer::CbTimerCountdown
                                                    Once::onEntry
                                              sm_fetch_two_table
                                              _pick_n_place_1::cl
                                              _gripper::CbCloseGripper
                                                      ::onEntry
                                              sm_fetch_six_table
                                              _pick_n_sort_1::cl_gripper
                                              ::CbCloseGripper::onEntry
                                          cl_ros_timer::CbTimerCountdown
                                                    Loop::onEntry
                                               move_group_interface
                                               _client::CbAttachObject
                                                      ::onEntry
                                                sm_dance_bot::cl_led
                                                 ::CbLEDOff::onEntry
                                               sm_dance_bot_strikes
_back::cl_led::CbLEDOff
                                                      ::onEntry
                                             sm_ridgeback_floor
                                              _coverage_dynamic 1
                                             ::cl_led::CbLEDOff::onEntry
                                              sm_ridgeback_floor
                                              _coverage_static_1::
cl_led::CbLEDOff::onEntry
                                                sm_dance_bot::cl_led
                                                 ::CbLEDOn::onEntry
                                               sm dance bot strikes
                                               _back::cl_led::CbLEDOn
                                                      ::onEntry
                                             sm ridgeback floor
                                              _coverage_dynamic_1
                                              ::cl_led::CbLEDOn::onEntry
                                              sm ridgeback floor
                                               _coverage_static_1::
                                              cl led::CbLEDOn::onEntry
                                          cl_keyboard::CbDefaultKeyboard
                                                  Behavior::onEntry
                                            cl_move_base_z::CbNavigate
                                               NextWaypoint::onEntry
smacc::ISmaccClientBehavior
       ::requiresClient
                                             sm_dance_bot_strikes
_back::cl_string_publisher
                                             ::CbStringPublisher::onEntry
                                             sm_ridgeback_floor
                                             _coverage_dynamic_1
::cl_string_publisher
                                             ::CbStringPublisher::onEntry
                                             sm_ridgeback_floor
                                              _coverage_static_1::
                                             cl_string_publisher::
                                             CbStringPublisher::onEntry
                                            sm_dance_bot::cl_string
                                            _publisher::CbStringPublisher
                                                      ::onEntry
                                            cl_move_base_z::CbUndoPath
                                                 Backwards::onEntry
                                             move_group_interface
                                              client::CbMoveEndEffector
                                                      ::onEntry
                                                move_group_interface
                                                _client::CbMoveJoints
                                                      ::onEntry
                                         move_group_interface
                                         client::CbMoveEndEffectorRelative
                                                      ::onEntry
                                            move_group_interface
                                            client::CbMoveNamedTarget
                                                      ::onEntry
                                          move_group_interface
                                          client::CbMoveCartesianRelative
                                                      ::onEntry
                                             cl_move_base_z::CbRotate
                                                      ::onEntry
                                             cl_ros_publisher::CbPublish
                                                   Once::onEntry
                                            cl_move_base_z::CbAbsolute
                                                   Rotate::onEntry
                                            cl_move_base_z::CbNavigate
                                                 Backwards::onEntry
                                             cl_ros_publisher::CbDefault
                                                PublishLoop::onEntry
                                            cl_move_base_z::CbNavigate
                                                  Forward::onEntry
                                            cl_move_base_z::CbNavigate
                                               GlobalPosition::onEntry
                                          cl multirole sensor
                                          ::CbDefaultMultiRoleSensor
                                          Behavior< sm_dance_bot_strikes
_back::cl_lidar::ClLidarSensor
                                                      >::onEntry
```

cl_move_base_z::CbUndoPath Backwards::onExit

cl_ros_timer::CbTimer ::onEntry