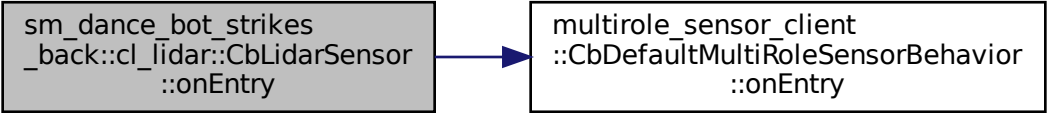


```
sm_dance_bot_strikes  
_back::cl_lidar::CbLidarSensor  
::onEntry
```



A diagram showing a call from a state machine to a client. On the left, a grey rectangular box contains the text 'sm_dance_bot_strikes', '_back::cl_lidar::CbLidarSensor', and '::onEntry'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'multirole_sensor_client', '::CbDefaultMultiRoleSensorBehavior', and '::onEntry'.

```
multirole_sensor_client  
::CbDefaultMultiRoleSensorBehavior  
::onEntry
```