franka::RobotControl + ~RobotControl() + startMotion() + finishMotion() + cancelMotion() + update() + throwOnMotionError() + realtimeConfig() franka::Robot::Impl network - loaaer - realtime config - ri version - motion generator mode - current move motion generator mode - controller mode current move controller mode - message id + Impl() + update() + throwOnMotionError() + readOnce() + serverVersion() + realtimeConfig() + startMotion() + cancelMotion() + finishMotion() + executeCommand() + loadModel() # motionGeneratorRunning() # controllerRunning() handleCommandResponse() handleCommandResponse() sendRobotCommand() receiveRobotState() updateState()