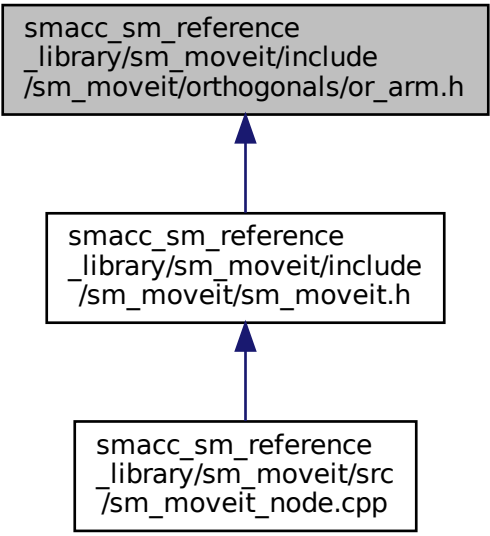


smacc_sm_reference
_library/sm_moveit/include
_sm_moveit/orthogonals/or_arm.h



```
graph BT; A["smacc_sm_reference_library/sm_moveit/src_sm_moveit_node.cpp"] --> B["smacc_sm_reference_library/sm_moveit/include_sm_moveit_sm_moveit.h"]; B --> C["smacc_sm_reference_library/sm_moveit/include_sm_moveit_orthogonals/or_arm.h"];
```

The diagram illustrates a dependency chain between three files. At the bottom is a box containing the file path for a C++ source file: `smacc_sm_reference_library/sm_moveit/src_sm_moveit_node.cpp`. A blue arrow points upwards from this box to a middle box containing the file path for a header file: `smacc_sm_reference_library/sm_moveit/include_sm_moveit_sm_moveit.h`. Another blue arrow points upwards from the middle box to a top box containing the file path for another header file: `smacc_sm_reference_library/sm_moveit/include_sm_moveit_orthogonals/or_arm.h`. The top box has a light gray background, while the other two have white backgrounds.

smacc_sm_reference
_library/sm_moveit/include
_sm_moveit/sm_moveit.h

smacc_sm_reference
_library/sm_moveit/src
_sm_moveit_node.cpp