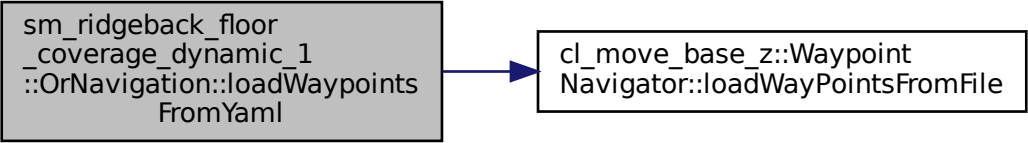


sm\_ridgeback\_floor  
\_coverage\_dynamic\_1  
::OrNavigation::loadWaypoints  
FromYaml



```
graph LR; A["sm_ridgeback_floor  
_coverage_dynamic_1  
::OrNavigation::loadWaypoints  
FromYaml"] --> B["cl_move_base_z::Waypoint  
Navigator::loadWayPointsFromFile"]
```

The diagram consists of two rectangular boxes connected by a dark blue arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'sm\_ridgeback\_floor', '\_coverage\_dynamic\_1', and '::OrNavigation::loadWaypoints FromYaml' on three lines. The right box has a white background and a black border, containing the text 'cl\_move\_base\_z::Waypoint' and 'Navigator::loadWayPointsFromFile' on two lines.

cl\_move\_base\_z::Waypoint  
Navigator::loadWayPointsFromFile