smacc::ISmaccClient

components_
- stateMachine_

+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ configureEventSourceTypes()
+ getType()
+ getStateMachine()
+ connectSignal()
# createComponent()

ros_timer_client::ClRosTimer

nh_
timer
duration
oneshot
postTimerEvent_
onTimerTick_

+ ClRosTimer()
+ ~ClRosTimer()
+ initialize()
+ onTimerTick()
+ configureEventSourceTypes()
# timerCallback()