smacc::SmaccClientBehavior

- stateMachine_
- currentState
- currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
- configureEventSourceTypes()

ros_timer_client::CbTimer

- timerClient_
- postTimerEvent_
- c_

+ onEntry()
+ onExit()
+ configureEventSourceTypes()