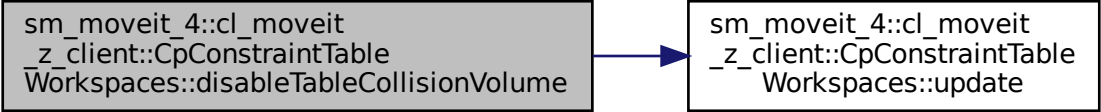


sm_moveit_4::cl_moveit
_z_client::CpConstraintTable
Workspaces::disableTableCollisionVolume



```
graph LR; A["sm_moveit_4::cl_moveit  
_z_client::CpConstraintTable  
Workspaces::disableTableCollisionVolume"] --> B["sm_moveit_4::cl_moveit  
_z_client::CpConstraintTable  
Workspaces::update"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains three lines of text. The right box has a white background and contains three lines of text. The text in both boxes is identical except for the last line, which changes from 'disableTableCollisionVolume' to 'update'.

sm_moveit_4::cl_moveit
_z_client::CpConstraintTable
Workspaces::update