smacc::SmaccClientBehavior

- + stateMachine_
- + currentState
- + currentOrthogonal
- + SmaccClientBehavior()
- + ~SmaccClientBehavior() + getName()
- + onEntry()
- + onExit()
- + postEvent()
- + postEvent()
- + requiresClient()
- + requiresComponent()
- configureEventSourceTypes()



ros timer client::CbTimer

- timerClient_
- postTimerEvent_
- c_
- + onEntry()
- + onExit()
 + configureEventSourceTypes()