

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call to the `computeVelocityCommands` method of the `BackwardLocalPlanner` class. The call is shown in a white box on the left, with a blue arrow pointing to a gray box on the right. The gray box shows the same call but with the method name `straightBackwardsAndPureSpinCmd` instead of `computeVelocityCommands`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```