

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```



A diagram showing a call to the `defaultBackwardCmd` method of the `BackwardLocalPlanner` class. A blue arrow points from this call to the `checkGoalReached` method of the same class, indicating a sequence of operations or a state transition.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached
```