

```
graph LR; A["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
::update"] --> B["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
::createVirtualCollisionWalls"]; B --> C["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintLateralWorkspace  
::createCollisionBox"]
```

sm_moveit_screw_loop
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::update

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::CpConstraintLateralWorkspace
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