

```
mecanum_drive_controller  
::MecanumDriveController  
::update
```



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::update] --> B[mecanum_drive_controller::Odometry::getLinearY];
```

A diagram showing a call from the `mecanum_drive_controller::MecanumDriveController::update` method to the `mecanum_drive_controller::Odometry::getLinearY` method. The call is represented by a blue arrow pointing from the left box to the right box.

```
mecanum_drive_controller  
::Odometry::getLinearY
```