

sm_atomic_cb::State2
::runtimeConfigure

sm_atomic_cb::State1
::runtimeConfigure

cl_ros_timer::CbTimerCountdown
Once::onTimerTick

```
graph LR; A["sm_atomic_cb::State2::runtimeConfigure"] --> C["cl_ros_timer::CbTimerCountdownOnce::onTimerTick"]; B["sm_atomic_cb::State1::runtimeConfigure"] --> C;
```

The diagram illustrates a dependency or call relationship. On the left, two white rectangular boxes represent state configuration functions: 'sm_atomic_cb::State2::runtimeConfigure' (top) and 'sm_atomic_cb::State1::runtimeConfigure' (bottom). On the right, a gray rectangular box represents a timer callback function: 'cl_ros_timer::CbTimerCountdownOnce::onTimerTick'. Two blue arrows originate from the right side of the left boxes and point towards the left side of the gray box, indicating that both state configuration functions call or depend on the timer callback function.