

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/clients/cl_lidar/components  
/cp_lidar_data.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/orthogonals/or_obstacle_perception.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance  
_bot_strikes_back.cpp"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/clients/cl\_lidar/components  
/cp\_lidar\_data.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/orthogonals/or\_obstacle\_perception.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back.cpp