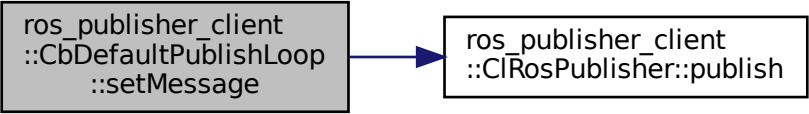


```
ros_publisher_client  
::CbDefaultPublishLoop  
::setMessage
```



```
graph LR; A[ros_publisher_client::CbDefaultPublishLoop::setMessage] --> B[ros_publisher_client::CIRosPublisher::publish];
```

```
ros_publisher_client  
::CIRosPublisher::publish
```