

```
boost::statechart::  
event< EvTopicMessageTimeout  
    < TSource, TOrthogonal > >
```

The diagram shows a class hierarchy. The base class, `boost::statechart::event< EvTopicMessageTimeout < TSource, TOrthogonal > >`, is represented by a white box with a thin black border. It has three horizontal compartments, with the first containing the class name and the others being empty. The derived class, `cl_multirole_sensor::EvTopicMessageTimeout`, is represented by a grey box with a thin black border. It has three horizontal compartments: the first contains the class name, the second contains the member `+ timerData`, and the third is empty. A blue arrow with an open triangular head points from the top of the derived class box to the bottom of the base class box, indicating inheritance.

```
cl_multirole_sensor  
::EvTopicMessageTimeout  
< TSource, TOrthogonal >
```

```
+ timerData
```