```
# components

    stateMachine

    orthogonal_

+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# setStateMachine()
# setOrthogonal()
             Д
                   smacc::client_bases
                   ::SmaccSubscriberClient
                        < MessageType >
                   + topicName
                   + queueSize
                   + onFirstMessageReceived_
                   + onMessageReceived_
                   + postMessageEvent
                   + postInitialMessageEvent
                  # nh_
                   - sub
                  - firstMessage_
                   - initialized
                   + SmaccSubscriberClient()
                   + SmaccSubscriberClient()
                   + ~SmaccSubscriberClient()
                   + onMessageReceived()
                   + onFirstMessageReceived()
                   + onOrthogonalAllocation()
                   + initialize()
                   messageCallback()
                  < sensor_msgs::LaserScan >
smacc::client_bases
::SmaccSubscriberClient
< sensor_msgs::LaserScan >
                                   cl_multirole_sensor
+ topicName
                                   ::CIMultiroleSensor
+ queueSize
                                         < MessageType >
+ onFirstMessageReceived_
+ onMessageReceived_
                                   + onMessageTimeout_
+ postMessageEvent
                                   + postTimeoutMessageEvent
+ postInitialMessageEvent
                                   + timeout
# nh_
                                   - timeoutTimer_
- sub
                                   - initialized
firstMessage_
- initialized
                                   + ClMultiroleSensor()
                                   + onMessageTimeout()
+ SmaccSubscriberClient()
                                   + onOrthogonalAllocation()
+ SmaccSubscriberClient()
                                   + initialize()
+ ~SmaccSubscriberClient()
                                   # resetTimer()
+ onMessageReceived()
                                   timeoutCallback()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
+ initialize()
messageCallback()
                                        < sensor_msgs::LaserScan >
                 cl multirole sensor
                 ::ClMultiroleSensor
                  < sensor_msgs::LaserScan >
                 + onMessageTimeout_
                 + postTimeoutMessageEvent
                 + timeout

    timeoutTimer_

    initialized

                 + CIMultiroleSensor()
                 + onMessageTimeout()
                 + onOrthogonalAllocation()
                 + initialize()
                 # resetTimer()
                 timeoutCallback()
                     sm_dance_bot::cl_lidar
                         ::ClLidarSensor
```

+ ClLidarSensor()

smacc::ISmaccClient