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graph RL; A[cl_move_base_z::CbNavigate  
GlobalPosition::onEntry] --> B[cl_move_base_z::CbNavigate  
GlobalPosition::execute]; B --> C[cl_move_base_z::CbNavigate  
GlobalPosition::readStartPoseFrom  
ParameterServer];
```

cl_move_base_z::CbNavigate
GlobalPosition::readStartPoseFrom
ParameterServer

cl_move_base_z::CbNavigate
GlobalPosition::execute

cl_move_base_z::CbNavigate
GlobalPosition::onEntry