

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeNewPositions"]
```

A diagram showing a call sequence between two methods. A grey box on the left contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::generateTrajectory'. A blue arrow points from this box to a white box on the right. The white box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeNewPositions'.

```
cl_move_base_z::backward  
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