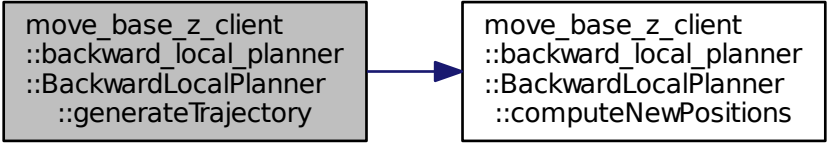


```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
  ::generateTrajectory
```



```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
  ::computeNewPositions
```