

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::publishGoalMarker"]
```

A diagram showing a call sequence. A white box on the left contains the code for `computeVelocityCommands`. A blue arrow points from this box to a gray box on the right, which contains the code for `publishGoalMarker`.

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cl_move_base_z::backward  
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```