

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::findInitialCarrotGoal'. The right box has a white background and contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeCurrentEuclideanAndAngularErrors ToCarrotGoal'. The arrow is a solid blue line with a triangular arrowhead pointing towards the right box.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
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ToCarrotGoal
```