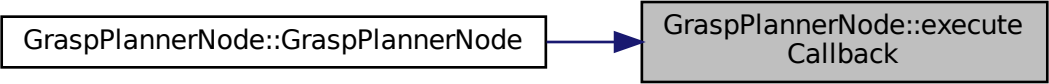


GraspPlannerNode::GraspPlannerNode



```
graph LR; A[GraspPlannerNode::GraspPlannerNode] --> B[GraspPlannerNode::execute  
Callback];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'GraspPlannerNode::GraspPlannerNode'. The right box is gray with a black border and contains the text 'GraspPlannerNode::execute' on the top line and 'Callback' on the bottom line. A blue arrow points from the right side of the left box to the left side of the right box.

GraspPlannerNode::execute  
Callback