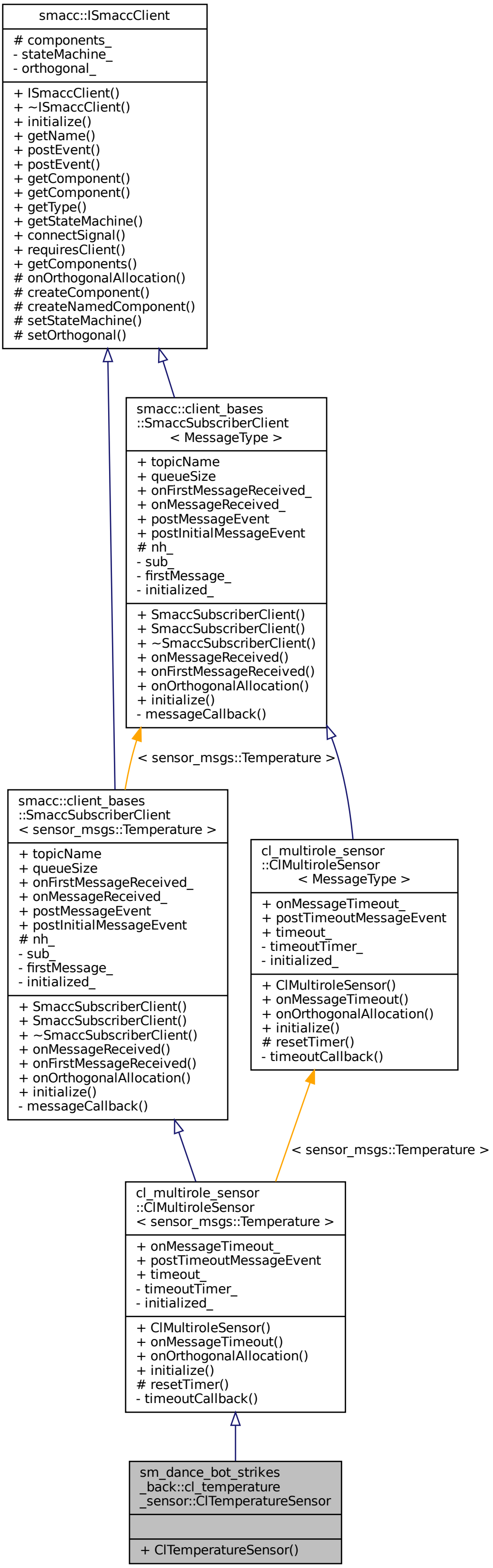
smacc::ISmaccClient
components_
- stateMachine_
- orthogonal_
+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# setStateMachine()
# setOrthogonal()
smacc::client_bases
::SmaccSubscriberClient
< MessageType >
+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
# nh_
- sub_
- firstMessage_
- initialized_
+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
+ initialize()
- messageCallback()
< sensor_msgs::Temperature >
smacc::client_bases
::SmaccSubscriberClient
< sensor_msgs::Temperature >
+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
# nh_
- sub_
- firstMessage_
- initialized_
+ SmaccSubscriberClient()
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
+ initialize()
- messageCallback()
cl_multirole_sensor
::ClMultiroleSensor
< MessageType >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ initialize()
# resetTimer()
- timeoutCallback()
< sensor_msgs::Temperature >
cl_multirole_sensor
::ClMultiroleSensor
< sensor_msgs::Temperature >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ onOrthogonalAllocation()
+ initialize()
# resetTimer()
- timeoutCallback()
sm_dance_bot_strikes
_back::cl_temperature
_sensor::ClTemperatureSensor
+ ClTemperatureSensor()