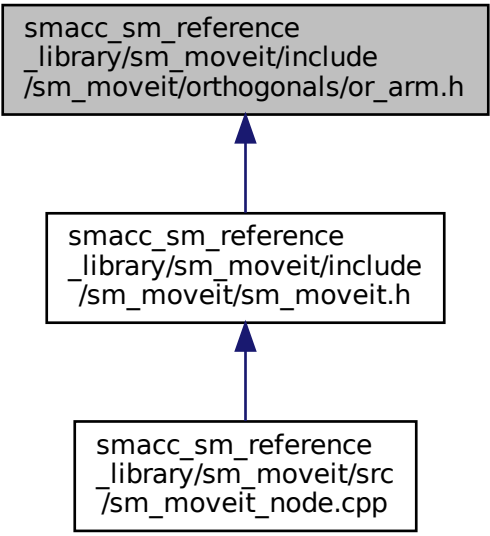


smacc\_sm\_reference  
\_library/sm\_moveit/include  
\_sm\_moveit/orthogonals/or\_arm.h



```
graph BT; A["smacc_sm_reference_library/sm_moveit/src_sm_moveit_node.cpp"] --> B["smacc_sm_reference_library/sm_moveit/include_sm_moveit_sm_moveit.h"]; B --> C["smacc_sm_reference_library/sm_moveit/include_sm_moveit_orthogonals/or_arm.h"];
```

The diagram illustrates a dependency chain between three files. At the bottom is a box containing the source file path: `smacc_sm_reference_library/sm_moveit/src_sm_moveit_node.cpp`. A blue arrow points upwards from this box to a middle box containing the header file path: `smacc_sm_reference_library/sm_moveit/include_sm_moveit_sm_moveit.h`. Another blue arrow points upwards from the middle box to the top box, which contains the path: `smacc_sm_reference_library/sm_moveit/include_sm_moveit_orthogonals/or_arm.h`. The top box has a light gray background, while the others are white.

smacc\_sm\_reference  
\_library/sm\_moveit/include  
\_sm\_moveit/sm\_moveit.h

smacc\_sm\_reference  
\_library/sm\_moveit/src  
\_sm\_moveit\_node.cpp