```
                                              smacc::ISmaccState
                                               ::getROSNode

                                              sm_dance_bot_strikes
                                              _back::f_pattern_states
                                              ::StiFPatternStartLoop
                                              < SsFPattern1 >::loopCondition

                                              sm_calendar_week::StWednesday
                                                ::runtimeConfigure

                                              sm_calendar_week::StSaturday
                                                ::runtimeConfigure

                                              sm_calendar_week::StFriday
                                                ::runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::s_pattern_states
                                              ::StiSPatternForward4::
                                                runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::s_pattern_states
                                              ::StiSPatternForward2::
                                                runtimeConfigure

                                              sm_calendar_week::StSunday
                                                ::runtimeConfigure

                                              sm_calendar_week::StThursday
                                                ::runtimeConfigure

  smacc::ISmaccState                          sm_calendar_week::StTuesday
   ::requiresClient                             ::runtimeConfigure

                                              sm_calendar_week::StMonday
                                                ::runtimeConfigure

                                              sm_atomic::State2::
                                                runtimeConfigure

                                              sm_dance_bot_2::radial
                                              _motion_states::StiRadialEnd
                                                Point::runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::radial_motion
                                              _states::StiRadialEndPoint
                                                ::runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::StNavigateForward1
                                                ::runtimeConfigure

                                              sm_dance_bot::StNavigate
                                              Forward1::runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::f_pattern_states
                                              ::StiFPatternForward1::
                                                runtimeConfigure

                                              sm_dance_bot::StNavigate
                                              ToWaypointsX::runtimeConfigure

                                              sm_dance_bot_strikes
                                              _back::StNavigateToWaypoints
                                                X::runtimeConfigure
```