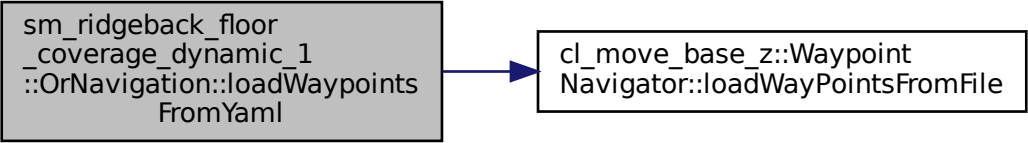


sm_ridgeback_floor
_coverage_dynamic_1
::OrNavigation::loadWaypoints
FromYaml



```
graph LR; A["sm_ridgeback_floor  
_coverage_dynamic_1  
::OrNavigation::loadWaypoints  
FromYaml"] --> B["cl_move_base_z::Waypoint  
Navigator::loadWayPointsFromFile"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'sm_ridgeback_floor', '_coverage_dynamic_1', and '::OrNavigation::loadWaypoints FromYaml' on three lines. The right box has a white background and a black border, containing the text 'cl_move_base_z::Waypoint' and 'Navigator::loadWayPointsFromFile' on two lines. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_move_base_z::Waypoint
Navigator::loadWayPointsFromFile