



-errors_

+joint_move_in_wrong
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+tau_j_range_violation
+max_path_pose_deviation
_violation
+start_elbow_sign_inconsistent
+cartesian_position_motion
_generator_start_pose_invalid
+cartesian_motion_generator
_joint_acceleration_discontinuity
+cartesian_motion_generator_joint
_position_limits_violation
+joint_velocity_violation
+instability_detected
+joint_reflex
...

