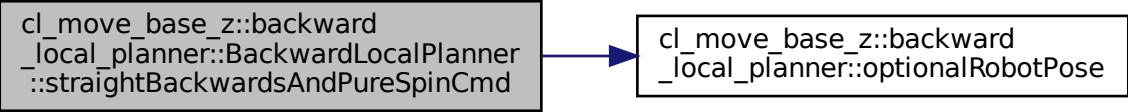


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```



A diagram showing a transformation from a specific planner command to a more general pose. A blue arrow points from the left box to the right box.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```