

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_superstates/ss_radial  
_pattern_3.h"] <--> B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B <--> C["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_superstates/ss\_radial  
\_pattern\_3.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_src/sm\_dance\_bot.cpp