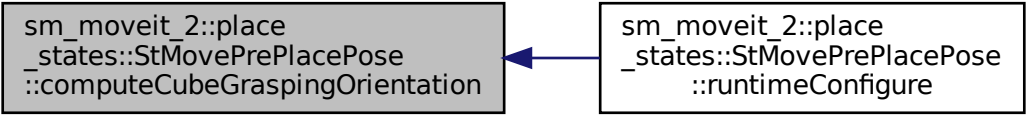


```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::computeCubeGraspingOrientation
```



A diagram showing a call from a function in a white box to a function in a gray box. A blue arrow points from the right box to the left box. The left box is shaded gray and contains the text 'sm_moveit_2::place', '_states::StMovePrePlacePose', and '::computeCubeGraspingOrientation'. The right box is white and contains the text 'sm_moveit_2::place', '_states::StMovePrePlacePose', and '::runtimeConfigure'.

```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::runtimeConfigure
```