

sm_dance_bot::cl_service3
::CbService3::onEntry

sm_dance_bot_2::cl
_service3::CbService3
::onEntry

sm_dance_bot_strikes
_back::cl_service3::CbService3
::onEntry

smacc::client_bases
::SmaccServiceClient::call

```
graph LR; A[sm_dance_bot::cl_service3::CbService3::onEntry] --> D[smacc::client_bases::SmaccServiceClient::call]; B[sm_dance_bot_2::cl_service3::CbService3::onEntry] --> D; C[sm_dance_bot_strikes_back::cl_service3::CbService3::onEntry] --> D;
```

The diagram illustrates a call flow where three different source functions (all named `onEntry` within `CbService3` classes) point to a single target function `call` within the `SmaccServiceClient` class. The target box is shaded gray, while the source boxes are white with black borders. Arrows are blue and point from each source box to the target box.