

```
graph BT; A["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/src/sm_fetch_robot_asynchronous  
_orthogonals_node.cpp"] --> B["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/include/sm_fetch_robot_asynchronous  
_orthogonals/sm_fetch_robot_asynchronous  
_orthogonals.h"]; B --> C["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/include/sm_fetch_robot_asynchronous  
_orthogonals/orthogonals/or_gripper.h"];
```

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smacc\_sm\_reference  
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\_orthogonals/sm\_fetch\_robot\_asynchronous  
\_orthogonals.h

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