

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/ms_dance_bot_run  
_mode/radial_motion_states  
/ss_radial_pattern_2.h"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/ms_dance_bot_run
_mode/radial_motion_states
/ss_radial_pattern_2.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp