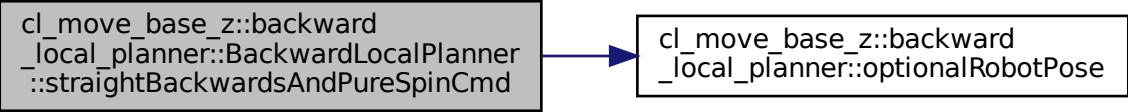


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```



A diagram showing a function call. On the left, a grey rectangular box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::straightBackwardsAndPureSpinCmd'. A blue arrow points from the right side of this box to the right side of a white rectangular box on the right. The white box contains the text 'cl_move_base_z::backward' and '_local_planner::optionalRobotPose'.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```