```
move_group_interface
                                             _client::CbDetachObject
                                                    ::onEntry
                                            sm_moveit_4::cl_gripper
                                            ::CbOpenGripper::onEntry
                                            sm_moveit::cl_gripper
                                            ::CbOpenGripper::onEntry
                                            sm_moveit_2::cl_gripper
                                            ::CbOpenGripper::onEntry
                                            sm_moveit_3::cl_gripper
                                            ::CbOpenGripper::onEntry
                                        cl_ros_timer::CbTimerCountdown
                                                  Once::onEntry
                                            sm_moveit_2::cl_gripper
                                            ::CbCloseGripper::onEntry
                                            sm moveit 3::cl gripper
                                            ::CbCloseGripper::onEntry
                                            sm_moveit_4::cl_gripper
                                            ::CbCloseGripper::onEntry
                                            sm_moveit::cl_gripper
                                            ::CbCloseGripper::onEntry
                                        cl_ros_timer::CbTimerCountdown
                                                  Loop::onEntry
                                             move_group_interface
                                             _client::CbAttachObject
                                                    ::onEntry
                                             sm_dance_bot_2::cl
                                              led::CbLEDOn::onEntry
                                              sm dance bot::cl led
                                               ::CbLEDOff::onEntry
                                             sm dance bot 2::cl
                                             led::CbLEDOff::onEntry
                                             sm_dance_bot_strikes
_back::cl_led::CbLEDOff
                                                    ::onEntry
                                              sm_dance_bot::cl_led
                                               ::CbLEDOn::onEntry
                                             sm_dance_bot_strikes
                                             _back::cl_led::CbLEDOn
                                                    ::onEntry
smacc::ISmaccClientBehavior
                                        cl_keyboard::CbDefaultKeyboard
       ::requiresClient
                                                Behavior::onEntry
                                          cl_move_base_z::CbNavigate
                                             NextWaypoint::onEntry
                                           sm_dance_bot_strikes
                                            back::cl_string_publisher
                                           ::CbStringPublisher::onEntry
                                          sm_dance_bot::cl_string
                                          _publisher::CbStringPublisher
                                                    ::onEntry
                                           sm_dance_bot_2::cl
                                            _string_publisher::CbString
                                                Publisher::onEntry
                                          cl_move_base_z::CbUndoPath
                                               Backwards::onEntry
                                           move_group_interface
                                            client::CbMoveEndEffector
                                                    ::onEntry
                                             move_group_interface
                                              _client::CbMoveJoints
                                                    ::onEntry
                                       move_group_interface
                                       client::CbMoveEndEffectorRelative
                                                    ::onEntry
                                          move_group_interface
                                          client::CbMoveNamedTarget
                                                    ::onEntry
                                        move_group_interface
                                        _client::CbMoveCartesianRelative
                                                    ::onEntry
                                           cl_move_base_z::CbRotate
                                                    ::onEntry
                                           cl_ros_publisher::CbPublish
                                                  Once::onEntry
                                          cl_move_base_z::CbAbsolute
                                                 Rotate::onEntry
                                          cl_move_base_z::CbNavigate
                                                Forward::onEntry
                                           cl_ros_publisher::CbDefault
                                              PublishLoop::onEntry
                                          cl_move_base_z::CbNavigate
                                               Backwards::onEntry
                                          cl_move_base_z::CbNavigate
                                             GlobalPosition::onEntry
                                        cl multirole sensor
                                        ::CbDefaultMultiRoleSensor
                                        Behavior < sm_dance_bot_strikes
                                        back::cl lidar::ClLidarSensor
                                                   >::onEntry
```

cl\_move\_base\_z::CbUndoPath Backwards::onExit

cl\_ros\_timer::CbTimer ::onEntry