

```
violation
+ cartesian_reflex
+ max_goal_pose_deviation
  violation
+ cartesian_velocity
_profile_safety_violation
+ joint_position_motion
_generator_start_pose
  invalid
+ joint_motion_generator
_position_limits_violation
+ joint_motion_generator
_velocity_limits_violation
+ joint_motion_generator
_velocity_discontinuity
+ joint_motion_generator
_acceleration_discontinuity
+ cartesian_motion_generator
_elbow_limit_violation
+ cartesian_motion_generator
_velocity_limits_violation
+ cartesian_motion_gene
_velocity_discontinuity
+ cartesian_motion_generator
_acceleration_discontinuity
+ cartesian_motion_generator
_elbow_sign_inconsistent
+ cartesian_motion_generator
 start_elbow_invalid
+ cartesian_motion_generator

_joint_velocity_limits_violation

+ cartesian_motion_generator

_joint_velocity_discontinuity
+ cartesian_position
_motion_generator_invalid_frame
+ force_controller_desired
 force
           tolerance violation
+ controller_torque_discontinuity
+ communication_constraints
 violation
+ power_limit_violation
+ joint_p2p_insufficient
_torque_for_planning
+ Errors()
+ Errors()
```

+ operator=() + Errors()

+ operator bool() + operator std::string()