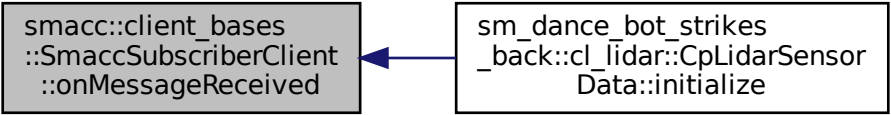


```
smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived
```



```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize"] --> B["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]
```

A diagram showing a call from the `sm_dance_bot_strikes` package to the `smacc::client_bases` package. The `sm_dance_bot_strikes` package is represented by a white box on the right, and the `smacc::client_bases` package is represented by a gray box on the left. A blue arrow points from the `sm_dance_bot_strikes` box to the `smacc::client_bases` box, indicating a call or dependency. The text inside the `sm_dance_bot_strikes` box is `sm_dance_bot_strikes`, `_back::cl_lidar::CpLidarSensor`, and `Data::initialize`. The text inside the `smacc::client_bases` box is `smacc::client_bases`, `::SmaccSubscriberClient`, and `::onMessageReceived`.

```
sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize
```