

```
sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure"] --> B["smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor"]
```

A diagram showing a call to the staticConfigure method of the StAcquireSensors struct. The call is made from the sm\_dance\_bot\_strikes\_back function. An arrow points from this call to the static\_createState method of the SmaccState struct, which is a template class for SmaccState, parameterized by StAcquireSensors, MsDanceBotRunMode, and a Reactor.

```
smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor
```