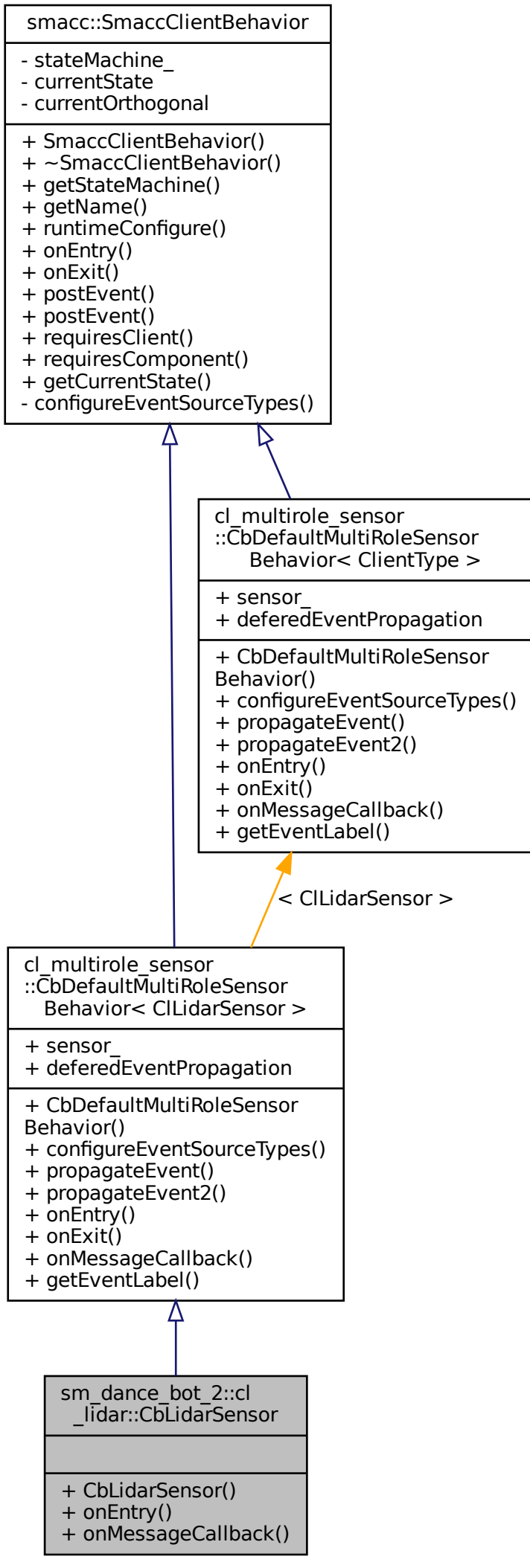
smacc::SmaccClientBehavior
- stateMachine_
- currentState
- currentOrthogonal
+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
- configureEventSourceTypes()
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior< ClientType >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
< ClLidarSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior< ClLidarSensor >
+ sensor_
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_2::cl
_lidar::CbLidarSensor
+ CbLidarSensor()
+ onEntry()
+ onMessageCallback()