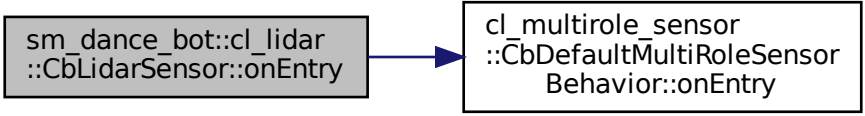
sm_dance_bot::cl_lidar
::CbLidarSensor::onEntry
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior::onEntry