```
research interface
::robot::ResponseBase< T >
+ status
+ ResponseBase()
              < GetCartesianLimit >
  research interface
  ::robot::ResponseBase
  < GetCartesianLimit >
  + status
  + ResponseBase()
 research interface
 ::robot::GetCartesianLimit
        ::Response
 + object world size
 + object frame
 + object activation
 + Response()
 + Response()
```