

```
sm_fetch_screw_loop
_1::cl_move_group_interface
::CpConstraintTableWorkspaces
::disableTableCollisionVolume
```



The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and contains four lines of code. The right box has a white background and contains the same four lines of code, but with an additional line, `::update`, indented under the `Workspaces` line. The arrow is a solid blue line with a triangular head pointing to the right box.

```
sm_fetch_screw_loop
_1::cl_move_group_interface
::CpConstraintTableWorkspaces
    ::update
```