

```
graph BT; A["smacc_sm_reference  
_library/sm_moveit_3  
_include/sm_moveit_3  
_states/pick_states/st  
_close_gripper.h"] --> B["smacc_sm_reference  
_library/sm_moveit_3  
_include/sm_moveit_3  
_superstates/ss_pick_object.h"]; B --> C["smacc_sm_reference  
_library/sm_moveit_3  
_include/sm_moveit_3  
_sm_moveit_3.h"]; C --> D["smacc_sm_reference  
_library/sm_moveit_3  
_src/sm_moveit_3_node.cpp"];
```

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_states/pick\_states/st  
\_close\_gripper.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_superstates/ss\_pick\_object.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_sm\_moveit\_3.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_src/sm\_moveit\_3\_node.cpp