

```
sm_fetch_robot_asynchronous  
_orthogonals::cl_move_group  
_interface::CpConstraintLateralWorkspace  
::createVirtualCollisionWalls
```



```
sm_fetch_robot_asynchronous  
_orthogonals::cl_move_group  
_interface::CpConstraintLateralWorkspace  
::createCollisionBox
```