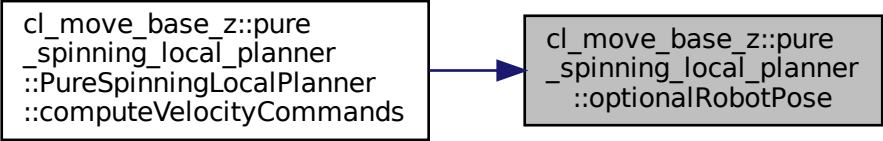


```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A diagram showing a function call. A white rectangular box on the left contains the text 'cl\_move\_base\_z::pure\_spinning\_local\_planner::PureSpinningLocalPlanner::computeVelocityCommands'. A blue arrow points from the right side of this box to a grey rectangular box on the right. The grey box contains the text 'cl\_move\_base\_z::pure\_spinning\_local\_planner::optionalRobotPose'.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```