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graph BT; A[smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/sti_spattern_rotate_1.h] --> B[smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/ss_s_pattern_1.h]; B --> C[smacc_sm_reference_library/sm_dance_bot_2/sm_dance_bot_2.h]; C --> D[smacc_sm_reference_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp];
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smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_2/include/sm\_dance\_bot  
\_2/states/ms\_dance\_bot\_run  
\_mode/s\_pattern\_states/sti  
\_spattern\_rotate\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_2/include/sm\_dance\_bot  
\_2/states/ms\_dance\_bot\_run  
\_mode/s\_pattern\_states/ss  
\_s\_pattern\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_2/include/sm\_dance\_bot  
\_2/sm\_dance\_bot\_2.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_2/src/sm\_dance\_bot\_2.cpp