## smacc::SmaccClientBehavior stateMachine - currentState currentOrthogonal + SmaccClientBehavior() + ~SmaccClientBehavior() + getStateMachine() + getName() + runtimeConfigure() + onEntry() + onExit() + postEvent() + postEvent() + requiresClient() + requiresComponent()

configureEventSourceTypes()

```
ros publisher client
::CbPublishOnce < RosMsqType >
```

 deferedPublishFn - client

+ getCurrentState()

- + CbPublishOnce() + CbPublishOnce()
- + setMessage()
  - + onEntry() + onExit()