```
smacc::SmaccClientBehavior
  + stateMachine
  + currentState
  + currentOrthogonal
  + SmaccClientBehavior()
  + ~SmaccClientBehavior()
  + getName()
  + onEntry()
  + onExit()
  + postEvent()
  + postEvent()
  + requiresClient()
  + requiresComponent()
  configureEventSourceTypes()
ros publisher client
::CbMutedBehavior< RosMsgType >
```

+ onEntry() + onExit()