```
smacc::ISmaccClientBehavior
 - stateMachine
 - currentState

    currentOrthogonal

 + ISmaccClientBehavior()
 + ~ISmaccClientBehavior()
 + getStateMachine()
 + getName()
 + requiresClient()
 + requiresComponent()
 # runtimeConfigure()
 # onEntry()
 # onExit()
 # postEvent()
 # postEvent()
 # getCurrentState()
 configureEventSourceTypes()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                       multirole sensor
                     :: CbDefault MultiRole Sensor
                        Behavior < ClientType >
                     + sensor
                     + deferedEventPropagation
                     + CbDefaultMultiRoleSensor
                     Behavior()
                     + configureEventSourceTypes()
                     + propagateEvent()
                     + propagateEvent2()
                     + onEntry()
                     + onExit()
                     + onMessageCallback()
                     + getEventLabel()
                           < ClTemperatureSensor >
cl multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < ClTemperatureSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_strikes
back::cl_temperature
sensor::CbConditionTemperature
             Sensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```