

BaseGlobalPlanner



cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner

- nh_
- forwardPathSub_
- planPub_
- markersPub_
- lastForwardPathMsg_
- costmap_ros_
- skip_straight_motion
distance_
- puresSpinningRadStep_

- + BackwardGlobalPlanner()
- + ~BackwardGlobalPlanner()
- + makePlan()
- + makePlan()
- + createDefaultBackwardPath()
- + initialize()
- onForwardTrailMsg()
- publishGoalMarker()