BaseGlobalPlanner

A

cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner

- planPub_ - markersPub_ - costmap ros

- nh

skip_straight_motion _distance_puresSpinningRadStep_

+ BackwardGlobalPlanner() + ~BackwardGlobalPlanner()

+ ~BackwardGlobalPlanner() + makePlan() + makePlan()

+ createDefaultBackwardPath() + initialize()

- onForwardTrailMsg()- publishGoalMarker()