

```
graph BT; A["smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/sm_dance_bot_strikes_back.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/clients/cl_lidar/client_behaviors/cb_lidar_sensor.h"];
```

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/clients/cl_lidar/client_behaviors
/cb_lidar_sensor.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back.cpp