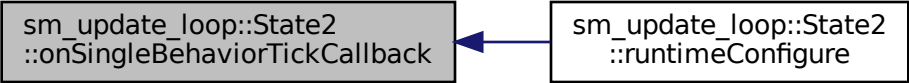


sm\_update\_loop::State2  
::onSingleBehaviorTickCallback



```
graph LR; A[sm_update_loop::State2::runtimeConfigure] --> B[sm_update_loop::State2::onSingleBehaviorTickCallback];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'sm\_update\_loop::State2' followed by '::onSingleBehaviorTickCallback' on the next line. The box on the right is white and contains the text 'sm\_update\_loop::State2' followed by '::runtimeConfigure' on the next line. A dark blue arrow points from the right box to the left box, indicating a call or relationship between the two.

sm\_update\_loop::State2  
::runtimeConfigure