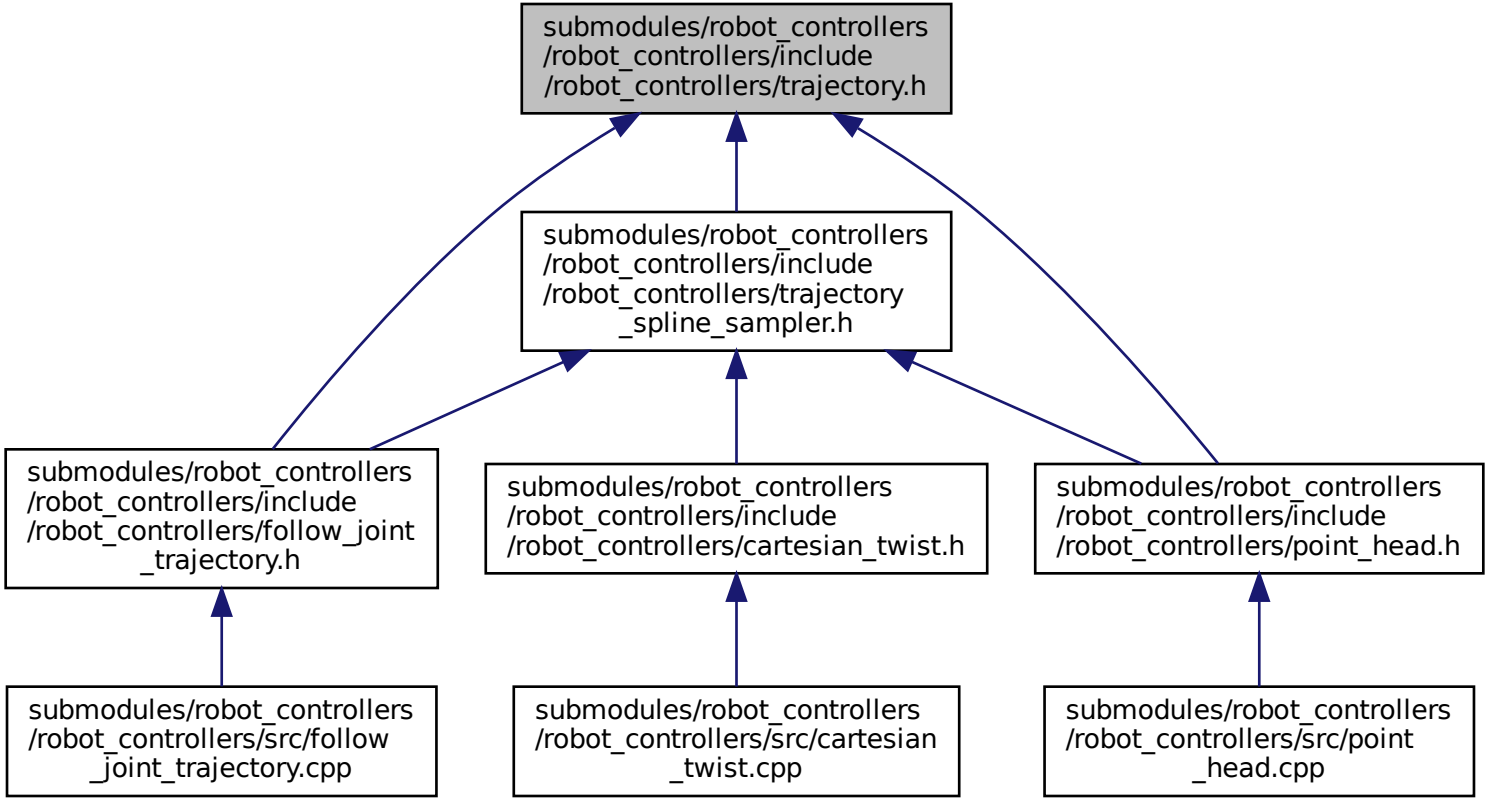
submodules/robot_controllers /robot_controllers/include /robot_controllers/trajectory.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/trajectory _spline_sampler.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/follow_joint _trajectory.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/cartesian_twist.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/point_head.h
submodules/robot_controllers /robot_controllers/src/follow _joint_trajectory.cpp
submodules/robot_controllers /robot_controllers/src/cartesian _twist.cpp
submodules/robot_controllers /robot_controllers/src/point _head.cpp