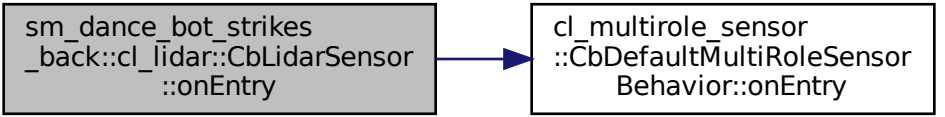
sm_dance_bot_strikes
_back::cl_lidar::CbLidarSensor
::onEntry
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior::onEntry