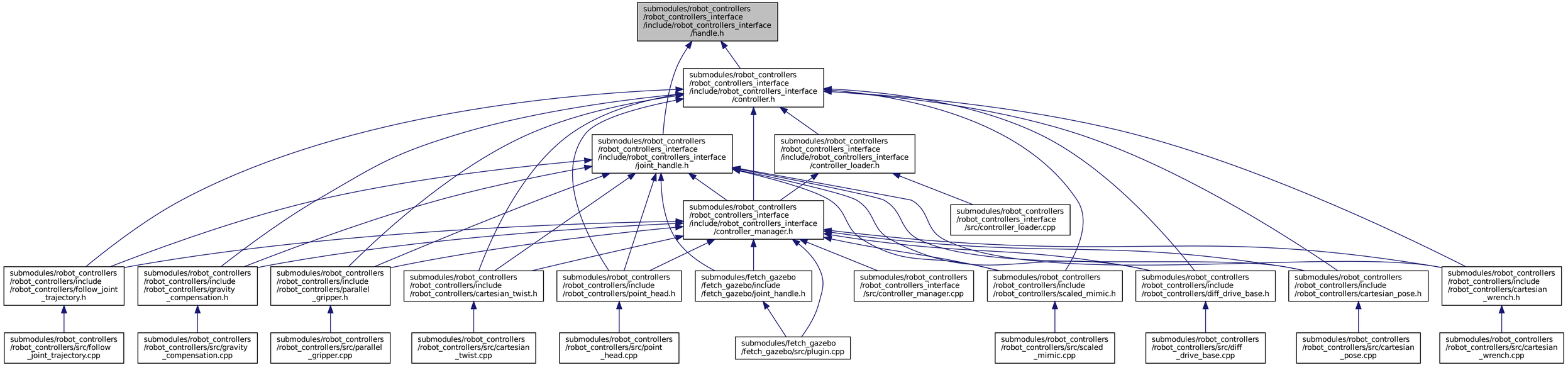
submodules/robot_controllers /robot_controllers_interface /include/robot_controllers_interface /handle.h
submodules/robot_controllers /robot_controllers_interface /include/robot_controllers_interface /controller.h
submodules/robot_controllers /robot_controllers_interface /include/robot_controllers_interface /joint_handle.h
submodules/robot_controllers /robot_controllers_interface /include/robot_controllers_interface /controller_loader.h
submodules/robot_controllers /robot_controllers_interface /include/robot_controllers_interface /controller_manager.h
submodules/robot_controllers /robot_controllers_interface /src/controller_loader.cpp
submodules/robot_controllers /robot_controllers/include /robot_controllers/follow_joint _trajectory.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/gravity _compensation.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/parallel _gripper.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/cartesian_twist.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/point_head.h
submodules/fetch_gazebo /fetch_gazebo/include /fetch_gazebo/joint_handle.h
submodules/robot_controllers /robot_controllers_interface /src/controller_manager.cpp
submodules/robot_controllers /robot_controllers/include /robot_controllers/scaled_mimic.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/diff_drive_base.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/cartesian_pose.h
submodules/robot_controllers /robot_controllers/include /robot_controllers/cartesian _wrench.h
submodules/robot_controllers /robot_controllers/src/follow _joint_trajectory.cpp
submodules/robot_controllers /robot_controllers/src/gravity _compensation.cpp
submodules/robot_controllers /robot_controllers/src/parallel _gripper.cpp
submodules/robot_controllers /robot_controllers/src/cartesian _twist.cpp
submodules/robot_controllers /robot_controllers/src/point _head.cpp
submodules/fetch_gazebo /fetch_gazebo/src/plugin.cpp
submodules/robot_controllers /robot_controllers/src/scaled _mimic.cpp
submodules/robot_controllers /robot_controllers/src/diff _drive_base.cpp
submodules/robot_controllers /robot_controllers/src/cartesian _pose.cpp
submodules/robot_controllers /robot_controllers/src/cartesian _wrench.cpp