smacc::SmaccClientBehavior

+ stateMachine_
+ currentState
+ currentOrthogonal

+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getName()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
- configureEventSourceTypes()

ros_publisher_client ::CbPublishOnce< RosMsgType >

- deferedPublishFn
- client_

+ CbPublishOnce()
+ CbPublishOnce()
+ setMessage()
+ onEntry()
+ onExit()