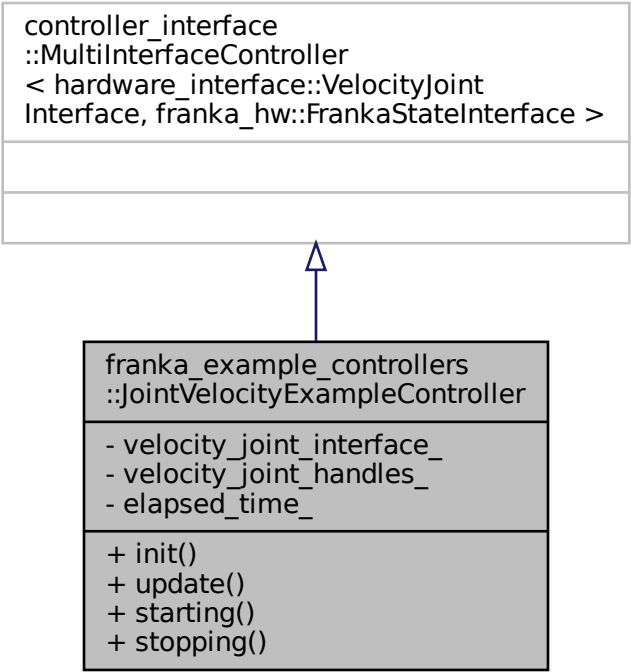


```
controller_interface  
::MultiInterfaceController  
< hardware_interface::VelocityJoint  
Interface, franka_hw::FrankaStateInterface >
```



```
classDiagram
    class controller_interface {
        < MultiInterfaceController
        < hardware_interface::VelocityJointInterface, franka_hw::FrankaStateInterface >
    }
    class franka_example_controllers {
        JointVelocityExampleController
        - velocity_joint_interface_
        - velocity_joint_handles_
        - elapsed_time_
        + init()
        + update()
        + starting()
        + stopping()
    }
    controller_interface <|-- franka_example_controllers
```

```
franka_example_controllers  
::JointVelocityExampleController
```

```
- velocity_joint_interface_  
- velocity_joint_handles_  
- elapsed_time_
```

```
+ init()  
+ update()  
+ starting()  
+ stopping()
```