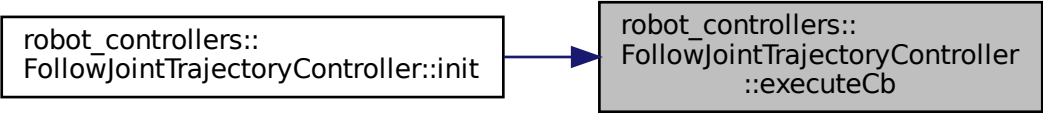


robot\_controllers::  
FollowJointTrajectoryController::init



```
graph LR; A["robot_controllers::  
FollowJointTrajectoryController::init"] --> B["robot_controllers::  
FollowJointTrajectoryController  
::executeCb"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'robot\_controllers::' followed by 'FollowJointTrajectoryController::init' on the next line. The right box is gray with a black border and contains the text 'robot\_controllers::' followed by 'FollowJointTrajectoryController' on the next line, and '::executeCb' on the third line.

robot\_controllers::  
FollowJointTrajectoryController  
::executeCb