

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_states/st_navigate_to
_waypoints_x.h



```
graph BT; A["smacc_sm_reference_library/sm_dance_bot_src/sm_dance_bot.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_include/sm_dance_bot.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_include/sm_dance_bot_states/st_navigate_to_waypoints_x.h"];
```

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
_src/sm_dance_bot.cpp