

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot_2/sm_dance_bot_2.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/ss_s_pattern_1.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/stipattern_rotate_2.h"];
```

smacc_sm_reference
_library/sm_dance_bot_2/include/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/stipattern_rotate_2.h

smacc_sm_reference
_library/sm_dance_bot_2/include/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/ss_s_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot_2/include/sm_dance_bot_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp