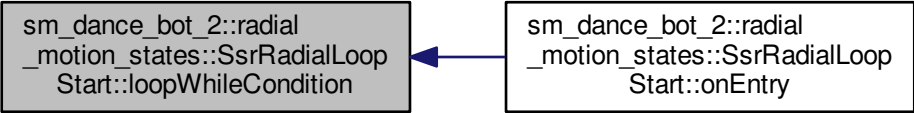


sm_dance_bot_2::radial
_motion_states::SsrRadialLoop
Start::loopWhileCondition



```
graph LR; A["sm_dance_bot_2::radial  
_motion_states::SsrRadialLoop  
Start::onEntry"] --> B["sm_dance_bot_2::radial  
_motion_states::SsrRadialLoop  
Start::loopWhileCondition"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from right to left. The right box is white with a black border and contains the text 'sm_dance_bot_2::radial', '_motion_states::SsrRadialLoop', and 'Start::onEntry'. The left box is gray with a black border and contains the text 'sm_dance_bot_2::radial', '_motion_states::SsrRadialLoop', and 'Start::loopWhileCondition'. A blue arrow points from the right box to the left box.

sm_dance_bot_2::radial
_motion_states::SsrRadialLoop
Start::onEntry