

BaseGlobalPlanner



cl\_move\_base\_z::backward  
\_global\_planner::BackwardGlobal  
Planner

- nh\_
- forwardPathSub\_
- planPub\_
- markersPub\_
- lastForwardPathMsg\_
- costmap\_ros\_
- skip\_straight\_motion  
distance\_
- puresSpinningRadStep\_

- + BackwardGlobalPlanner()
- + ~BackwardGlobalPlanner()
- + makePlan()
- + makePlan()
- + createDefaultBackwardPath()
- + initialize()
- onForwardTrailMsg()
- publishGoalMarker()