```
smacc::ISmaccComponent
   # stateMachine
   # serviceName
   # owner
   + ISmaccComponent()
   + ~ISmaccComponent()
   + initialize()
   + setStateMachine()
   + getName()
   + postEvent()
   + postEvent()
   + configureEventSourceTypes()
move_base z client
   ::odom tracker::OdomTracker
# robotBasePathPub
# odomSub
# minPointDistanceForwardThresh
# minPointDistanceBackward
Thresh
# minPointAngularDistanceForward
Thresh
# minPointAngularDistanceBackward
Thresh
# publishMessages
# baseTrajectory
# workingMode
# pathStack
# subscribeToOdometryTopic
# m mutex
+ OdomTracker()
+ processOdometryMessage()
+ setWorkingMode()
+ setPublishMessages()
+ pushPath()
+ popPath()
+ clearPath()
+ setStartPoint()
+ getPath()
# rtPublishPaths()
# updateForward()
# updateBackward()
```