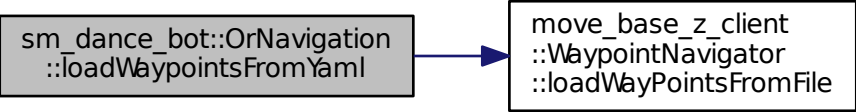


```
sm_dance_bot::OrNavigation  
::loadWaypointsFromYaml
```



```
graph LR; A["sm_dance_bot::OrNavigation  
::loadWaypointsFromYaml"] --> B["move_base_z_client  
::WaypointNavigator  
::loadWayPointsFromFile"]
```

A diagram showing a call from `sm_dance_bot::OrNavigation::loadWaypointsFromYaml` to `move_base_z_client::WaypointNavigator::loadWayPointsFromFile`. The first box is shaded gray and the second is white, connected by a blue arrow.

```
move_base_z_client  
::WaypointNavigator  
::loadWayPointsFromFile
```