

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot_2/include/sm_dance_bot_2/sti_fpattern_rotate_2.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot_2/include/sm_dance_bot_2/ss_f_pattern_1.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot_2/sm_dance_bot_2.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot_2/include/sm_dance_bot_2/sti_fpattern_rotate_2.h

smacc_sm_reference
_library/sm_dance_bot_2/include/sm_dance_bot_2/ss_f_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp