

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"]
```

The diagram illustrates a sequence of function calls. A box on the right, representing the caller, contains the code `cl_move_base_z::forward`, `_local_planner::ForwardLocal`, and `Planner::computeVelocityCommands`. A blue arrow points from this box to a box on the left, representing the callee. The callee box contains the code `cl_move_base_z::forward`, `_local_planner::ForwardLocal`, and `Planner::publishGoalMarker`. The callee box has a light gray background, while the caller box has a white background.

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands
```