```
franka_hw::FrankaStateHandle

- name__
- robot_state_

+ FrankaStateHandle()
+ FrankaStateHandle()
+ getName()
+ getRobotState()

franka_hw::FrankaCartesian
VelocityHandle
```

+ FrankaCartesianVelocityHandle() + FrankaCartesianVelocityHandle()

command\_elbow

+ setCommand() + setCommand() + getCommand()