```
smacc::ISmaccState
                                          ::getROSNode
                                 sm_dance_bot_strikes
                                  _back::f_pattern_states
                                 ::StiFPatternStartLoop
                                 < SsFPattern1 >::loopCondition
                                   sm_pr2_plugs::StNavigate
                                       ::runtimeConfigure
                                   sm_pr2_plugs::StGetOutlet
                                   Locations::runtimeConfigure
                                   sm_pr2_plugs::StWiggleOut
                                       ::runtimeConfigure
                                    sm_pr2_plugs::StClearLeft
                                     Arm::runtimeConfigure
                                    sm_pr2_plugs::StUnplug
                                       ::runtimeConfigure
                                     sm_pr2_plugs::StPlugIn
                                       ::runtimeConfigure
                                   sm_pr2_plugs::StPullBack
                                   FromWall::runtimeConfigure
                                  sm pr2 plugs::StRecoverStow
                                     Plug::runtimeConfigure
                                   sm_pr2_plugs::StSafetyTuck
                                       ::runtimeConfigure
                                    sm_pr2_plugs::StStowLeft
Arm::runtimeConfigure
                                  sm_pr2_plugs::StCloseGripper
::runtimeConfigure
                                   sm_pr2_plugs::StStowPlug
                                        ::runtimeConfigure
                                  sm_pr2_plugs::StSucceedFree
                                     Base::runtimeConfigure
                                  sm_pr2_plugs::StSucceedTuck
                                       ::runtimeConfigure
                                  sm_pr2_plugs::StDetectOutlet
                                       ::runtimeConfigure
                                   sm_pr2_plugs::StUntuckAt
                                    Outlet::runtimeConfigure
                                    sm_pr2_plugs::StFailLower
Spine::runtimeConfigure
                                    sm_pr2_plugs::StFailOpen
                                    Gripper::runtimeConfigure
                                    sm_pr2_plugs::StFailTuck
                                     Arms::runtimeConfigure
                                   sm_pr2_plugs::StFetchPlug
                                        ::runtimeConfigure
                                   sm_pr2_plugs::StFailUntuck
                                       ::runtimeConfigure
                                     sm_dance_bot_strikes
                                      back::s_pattern_states
                                     ::StiSPatternForward4::
                                        runtimeConfigure
smacc::ISmaccState
  ::requiresClient
                                   sm_pr2_plugs::StNavigate
                                   ToOutlet::runtimeConfigure
                                  sm_calendar_week::StSunday
                                       ::runtimeConfigure
                                 sm_calendar_week::StThursday
                                       ::runtimeConfigure
                                sm_calendar_week::StWednesday
                                       ::runtimeConfigure
                                  sm_calendar_week::StFriday
                                       ::runtimeConfigure
                                 sm calendar week::StSaturday
                                       ::runtimeConfigure
                                     sm_dance_bot_strikes
                                      _back::s_pattern_states
                                     ::StiSPatternForward2::
                                        runtimeConfigure
                                  sm_calendar_week::StTuesday
                                       ::runtimeConfigure
                                       sm atomic::State2::
                                        runtimeConfigure
                                  sm_calendar_week::StMonday
                                       ::runtimeConfigure
                                  sm_pr2_plugs::StFailStill
                                  Unplugged::runtimeConfigure
                                    sm_dance_bot_strikes
                                     back::radial_motion
                                     states::StiRadialEndPoint
                                       ::runtimeConfigure
                                   sm_dance_bot_strikes
_back::StNavigateForward1
                                       ::runtimeConfigure
                                   sm_dance_bot::StNavigate Forward1::runtimeConfigure
                                  sm_pr2_plugs::StGoallsLocal
                                        ::runtimeConfigure
                               sm_pr2_plugs::StProcessRecharge
                                  Command::runtimeConfigure
                                     sm dance bot strikes
                                      back::f_pattern_states
                                     ::StiFPatternForward1::
                                        runtimeConfigure
                                      sm_three_some::ss1
                                       states::StiState3::
                                        runtimeConfigure
                                   sm_three_some::StState3
                                        ::runtimeConfigure
                                      sm three some::ss1
                                       states::StiState2::
                                        runtimeConfigure
                                    sm_three_some::StState1
                                        ::runtimeConfigure
                                 sm dance bot::StNavigate
                                 ToWaypointsX::runtimeConfigure
                                  sm_dance_bot_strikes
                                  back::StNavigateToWaypoints
                                       X::runtimeConfigure
                                   sm three some::StState2
                                        ::runtimeConfigure
```