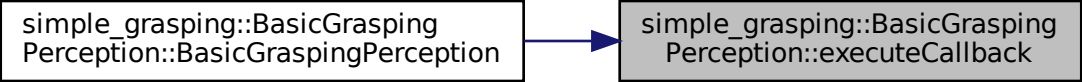


simple_grasping::BasicGrasping
Perception::BasicGraspingPerception



```
graph LR; A[simple_grasping::BasicGraspingPerception::BasicGraspingPerception] --> B[simple_grasping::BasicGraspingPerception::executeCallback];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'simple_grasping::BasicGraspingPerception::BasicGraspingPerception'. The right box is gray with a black border and contains the text 'simple_grasping::BasicGraspingPerception::executeCallback'. The arrow is dark blue.

simple_grasping::BasicGrasping
Perception::executeCallback