

```
smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/servers  
/temperature_sensor_node  
/src/temperature_sensor_node.cpp
```

```
graph TD; A["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/servers  
/temperature_sensor_node  
/src/temperature_sensor_node.cpp"] --> B["ros/ros.h"]; A --> C["sensor_msgs/Temperature.h"]
```

ros/ros.h

sensor\_msgs/Temperature.h