											SUCCESS											
sm_dance_bot::StAcquireSensors ::ON_SENSORS_AVAILABLE	sm_dance_bot::StNavigate ToWaypointsX::TRANSITION_1	sm_dance_bot::StNavigate ToWaypointsX::TRANSITION_2	sm_dance_bot::StNavigate ToWaypointsX::TRANSITION_3	sm_dance_bot::StNavigate ToWaypointsX::TRANSITION_4	sm_dance_bot::StNavigate ToWaypointsX::TRANSITION_5	sm_dance_bot_2::StNavigate ToWaypointsX::TRANSITION_1	sm_dance_bot_2::StNavigate ToWaypointsX::TRANSITION_2	sm_dance_bot_2::StNavigate ToWaypointsX::TRANSITION_3	sm_dance_bot_2::StNavigate ToWaypointsX::TRANSITION_4	sm_dance_bot_2::StNavigate ToWaypointsX::TRANSITION_5	sm_dance_bot_3::StAcquire Sensors::ON_SENSORS_AVAILABLE	sm_dance_bot_3::StNavigate ToWaypointsX::TRANSITION_1	sm_dance_bot_3::StNavigate ToWaypointsX::TRANSITION_2	sm_dance_bot_3::StNavigate ToWaypointsX::TRANSITION_3	sm_dance_bot_3::StNavigate ToWaypointsX::TRANSITION_4	sm_dance_bot_3::StNavigate ToWaypointsX::TRANSITION_5	sm_packML::StAborted ::CLEAR	sm_packML::StComplete ::RESET	sm_packML::StHeld:: UNHOLD	sm_packML::Stldle:: START	sm_packML::StStopped ::RESET	sm_packML::StSuspended ::UNSUSPEND