

```
graph BT; A["smacc_sm_reference  
_library/sm_panda_moveit  
/franka_ros/franka_control  
/src/franka_control_node.cpp"] --> B["smacc_sm_reference  
_library/sm_panda_moveit  
/franka_ros/franka_hw/include  
/franka_hw/franka_hw.h"]; C["smacc_sm_reference  
_library/sm_panda_moveit  
/franka_ros/franka_hw/src  
/franka_hw.cpp"] --> B;
```

smacc_sm_reference
_library/sm_panda_moveit
/franka_ros/franka_hw/include
/franka_hw/franka_hw.h

smacc_sm_reference
_library/sm_panda_moveit
/franka_ros/franka_control
/src/franka_control_node.cpp

smacc_sm_reference
_library/sm_panda_moveit
/franka_ros/franka_hw/src
/franka_hw.cpp