```
smacc::ISmaccClientBehavior
stateMachine_
- currentState

    currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
+ getNode()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
onOrthogonalAllocation()
              Д
smacc::SmaccClientBehavior
+ onEntry()
+ onExit()
                    cl multirole sensor
                    ::CbDefaultMultiRoleSensor
                      Behavior< ClientType >
                    + sensor
                    + deferedEventPropagation

    + CbDefaultMultiRoleSensor

                    Behavior()
                    + onOrthogonalAllocation()
                    + propagateEvent()
                    + propagateEvent2()
                    + onEntry()
                    + onExit()
                    + onMessageCallback()
                    + getEventLabel()
                           < sm_ridgeback_floor
                           coverage_dynamic_1::
                          cl lidar::ClLidarSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < sm_ridgeback_floor
 _coverage_dynamic_1::cl_lidar
       ::ClLidarSensor >
+ sensor
+ deferedEventPropagation

    + CbDefaultMultiRoleSensor

Behavior()
+ onOrthogonalAllocation()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
   sm_ridgeback_floor
    coverage dynamic 1
   ::cl_lidar::CbLidarSensor
   + CbLidarSensor()
   + onEntry()
```

+ onMessageCallback()