```
smacc::ISmaccClientBehavior

    stateMachine

    currentState

    currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
# dispose()
- onOrthogonalAllocation()
smacc::SmaccClientBehavior
 + onEntry()
 + onExit()
    cl ros timer::CbTimer

    timerClient

    postTimerEvent

- C
+ onEntry()
+ onExit()
+ onOrthogonalAllocation()
+ onClientTimerTickCallback()
```