

```
boost::statechart::  
event< EvTopicMessageTimeout  
      < TSource, TOrthogonal > >
```

The diagram shows a class hierarchy. At the top is a white box representing the base class `boost::statechart::event< EvTopicMessageTimeout < TSource, TOrthogonal > >`. It has two empty compartments below the header. Below it is a grey box representing the derived class `cl_multirole_sensor::EvTopicMessageTimeout < TSource, TOrthogonal >`. This box has a header compartment, a compartment containing `+ timerData`, and an empty bottom compartment. A blue arrow with an open triangle head points from the top of the grey box to the bottom of the white box, indicating inheritance.

```
cl_multirole_sensor  
::EvTopicMessageTimeout  
< TSource, TOrthogonal >
```

```
+ timerData
```