


```
sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::decidePlacePose
```



The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains three lines of C++ code. The right box is white with a black border and contains two lines of C++ code. A blue arrow points from the right side of the gray box to the left side of the white box.

```
smacc::ISmaccClient  
::getComponent
```