

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
/states/st\_navigate\_to  
\_waypoints\_x.h



```
graph BT; A["smacc_sm_reference_library/sm_dance_bot_src/sm_dance_bot.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_include/sm_dance_bot.h"]; B --> C["smacc_sm_reference_library/sm_dance_bot_include/sm_dance_bot_states/st_navigate_to_waypoints_x.h"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_src/sm\_dance\_bot.cpp