```
fake cube perception
 node.FakePerceptionNode
+ planning scene
+ tf_broacaster
+ tf listener
dug +
+ update planning scene
+ last update
+ update period
+ table collision
+ cube collision
+ init ()
+ update()
+ simulated link state
callback()
+ propagate link states
to tf()
__ _
+ _ init ()
+ update()
+ simulated link state
callback()
+ propagate link states
_to_tf()
   init ()
+ update()
+ simulated link state
callback()
+ propagate link states
_to_tf()
   init ()
+ update()
+ simulated link state
callback()
+ propagate link states
to tf()
   init ()
+ update()
+ simulated link state
callback()
+ propagate link states
to tf()
```