

```
boost::statechart::  
event< EvWaypoint245  
< TSource, TOrthogonal > >
```

The diagram shows a base class at the top and a derived class at the bottom. The base class is defined with a namespace and an event template. The derived class is defined with a namespace, the same event template, and a public member variable. A blue arrow with an open triangle head points from the derived class to the base class, indicating inheritance.

```
cl_move_base_z::EvWaypoint245  
  < TSource, TOrthogonal >
```

```
+ waypointIndex
```