```
                                        cl_ros_timer::CbTimer
                                        ::onEntry

                                        move_group_interface
                                        _client::CbDetachObject
                                        ::onEntry

                                        sm_fetch_six_table
                                        _pick_n_sort_1::cl_gripper
                                        ::CbOpenGripper::onEntry

                                        sm_fetch_two_table
                                        _pick_n_place_1::cl
                                        _gripper::CbOpenGripper
                                        ::onEntry

                                        cl_ros_timer::CbTimerCountdown
                                        Once::onEntry

                                        sm_fetch_two_table
                                        _pick_n_place_1::cl
                                        _gripper::CbCloseGripper
                                        ::onEntry

                                        sm_fetch_six_table
                                        _pick_n_sort_1::cl_gripper
                                        ::CbCloseGripper::onEntry

                                        cl_ros_timer::CbTimerCountdown
                                        Loop::onEntry

                                        move_group_interface
                                        _client::CbAttachObject
                                        ::onEntry

                                        sm_dance_bot_2::cl
                                        _led::CbLEDOn::onEntry

                                        sm_dance_bot::cl_led
                                        ::CbLEDOff::onEntry

                                        sm_dance_bot_2::cl
                                        _led::CbLEDOff::onEntry

                                        sm_dance_bot_strikes
                                        _back::cl_led::CbLEDOff
                                        ::onEntry

                                        sm_dance_bot::cl_led
                                        ::CbLEDOn::onEntry

                                        sm_dance_bot_strikes
                                        _back::cl_led::CbLEDOn
                                        ::onEntry

                                        cl_keyboard::CbDefaultKeyboard
                                        Behavior::onEntry

                                        cl_move_base_z::CbNavigate
                                        NextWaypoint::onEntry

smacc::ISmaccClientBehavior                sm_dance_bot_strikes
::requiresClient                           _back::cl_string_publisher
                                        ::CbStringPublisher::onEntry

                                        sm_dance_bot::cl_string
                                        _publisher::CbStringPublisher
                                        ::onEntry

                                        sm_dance_bot_2::cl
                                        _string_publisher::CbString
                                        Publisher::onEntry

                                        cl_move_base_z::CbUndoPath
                                        Backwards::onEntry

                                        move_group_interface
                                        _client::CbMoveEndEffector
                                        ::onEntry

                                        move_group_interface
                                        _client::CbMoveJoints
                                        ::onEntry

                                        move_group_interface
                                        _client::CbMoveEndEffectorRelative
                                        ::onEntry

                                        move_group_interface
                                        _client::CbMoveNamedTarget
                                        ::onEntry

                                        move_group_interface
                                        _client::CbMoveCartesianRelative
                                        ::onEntry

                                        cl_move_base_z::CbRotate
                                        ::onEntry

                                        cl_ros_publisher::CbPublish
                                        Once::onEntry

                                        cl_move_base_z::CbAbsolute
                                        Rotate::onEntry

                                        cl_move_base_z::CbNavigate
                                        Forward::onEntry

                                        cl_move_base_z::CbNavigate
                                        Backwards::onEntry

                                        cl_ros_publisher::CbDefault
                                        PublishLoop::onEntry

                                        cl_move_base_z::CbNavigate
                                        GlobalPosition::onEntry

                                        cl_multirole_sensor
                                        ::CbDefaultMultiRoleSensor
                                        Behavior< sm_dance_bot_strikes
                                        _back::cl_lidar::ClLidarSensor
                                                >::onEntry

                                        cl_move_base_z::CbUndoPath
                                        Backwards::onExit
```