


```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
  ::createCarrotGoal
```



A blue arrow points from the right box to the left box, indicating a function call or message passing from the white box to the gray box.

```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
  ::computeVelocityCommands
```