

sm_ridgeback_floor
_coverage_dynamic_1
::cl_lidar::CpLidarSensorData
::onInitialize

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graph LR; A["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::onInitialize"] --> B["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall"]; A --> C["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"];
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