

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
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Planner::publishGoalMarker"]
```

A diagram showing a call from the `computeVelocityCommands` method to the `publishGoalMarker` method. The `computeVelocityCommands` box is white, and the `publishGoalMarker` box is gray. A blue arrow points from the `computeVelocityCommands` box to the `publishGoalMarker` box.

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