

smacc_sm_reference
_library/sm_panda_moveit
/libfranka/src/robot_impl.h

```
graph BT; A["smacc_sm_reference_library/sm_panda_moveit/libfranka/src/robot.cpp"] --> C["smacc_sm_reference_library/sm_panda_moveit/libfranka/src/robot_impl.h"]; B["smacc_sm_reference_library/sm_panda_moveit/libfranka/src/robot_impl.cpp"] --> C;
```

This diagram illustrates a dependency structure in a codebase. At the top is a header file, `robot_impl.h`, which is referenced by two source files below it: `robot.cpp` and `robot_impl.cpp`. The header file box is shaded gray, while the source file boxes are white. Blue arrows point from each source file to the header file.

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_library/sm_panda_moveit
/libfranka/src/robot.cpp

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/libfranka/src/robot_impl.cpp