

```
graph RL; S3["sm_moveit_screw_loop  
::place_states::StNavigation  
Posture::runtimeConfigure"] --> S2["sm_moveit_screw_loop  
::place_states::StNavigation  
Posture::onSuccessfulExit"]; S2 --> S1["sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::nextCube"];
```

sm_moveit_screw_loop
::cl_perception_system
::ClPerceptionSystem::nextCube

sm_moveit_screw_loop
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