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graph BT; A["smacc_sm_reference<br/>library/sm_dance_bot<br/>/src/sm_dance_bot.cpp"] --> B["smacc_sm_reference<br/>library/sm_dance_bot<br/>/include/sm_dance_bot<br/>/sm_dance_bot.h"]; B --> C["smacc_sm_reference<br/>library/sm_dance_bot<br/>/include/sm_dance_bot<br/>/states/ms_dance_bot_run<br/>_mode/st_navigate_to_waypoints_x.h"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/states/ms\_dance\_bot\_run  
\_mode/st\_navigate\_to\_waypoints\_x.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp