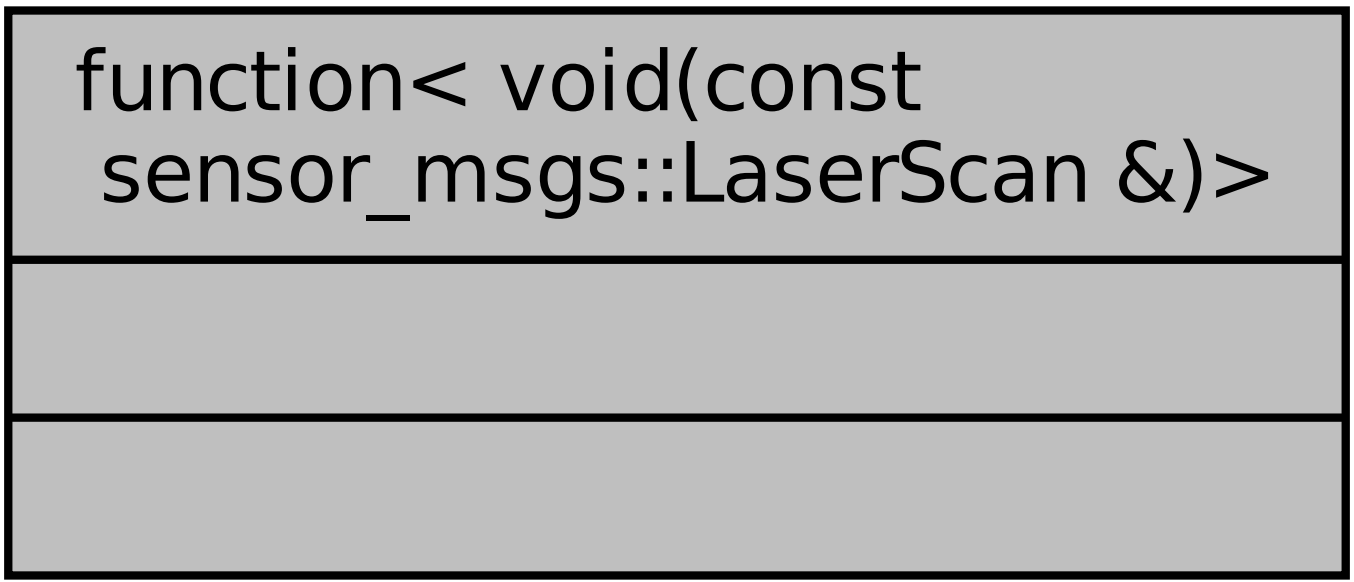
function< void(const
sensor_msgs::LaserScan &)>