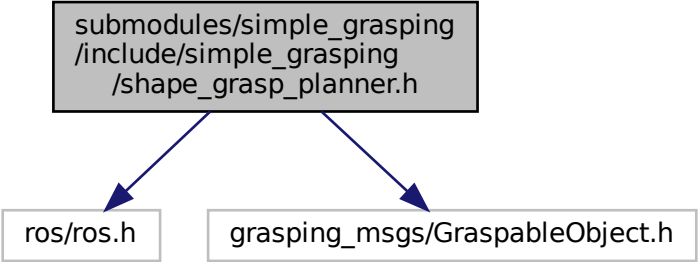


submodules/simple_grasping
/include/simple_grasping
/shape_grasp_planner.h



```
graph TD; A["submodules/simple_grasping  
/include/simple_grasping  
/shape_grasp_planner.h"] --> B["ros/ros.h"]; A --> C["grasping_msgs/GraspableObject.h"]
```

ros/ros.h

grasping_msgs/GraspableObject.h