franka_hw::FrankaStateHandle - name__ - robot_state_ + FrankaStateHandle() + FrankaStateHandle() + getName() + getRobotState()

franka_hw::FrankaCartesian PoseHandle

- command_
- elbow_
- + FrankaCartesianPoseHandle()
 + FrankaCartesianPoseHandle()
- + setCommand()
- + setCommanu()
- + setCommand()
- + getCommand()

franka_hw::FrankaCartesian VelocityHandle

- command_
- elbow_
- + FrankaCartesianVelocityHandle()
- + FrankaCartesianVelocityHandle()
- + setCommand()
- + setCommand()
- + getCommand()