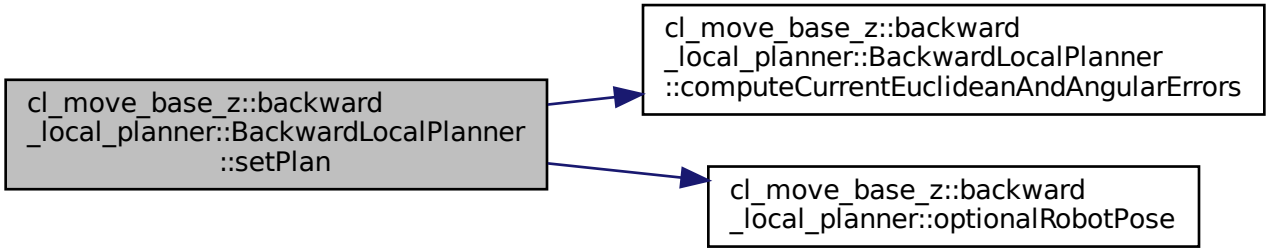
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::setPlan
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::computeCurrentEuclideanAndAngularErrors
cl_move_base_z::backward
_local_planner::optionalRobotPose