

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



A diagram showing a call to the `publishGoalMarker` method. A grey box on the left contains the code snippet. A blue arrow points from this box to a white box on the right, which contains the code snippet for the `publishGoalMarker` method's implementation.

```
cl_move_base_z::forward  
_local_planner::optionalRobotPose
```