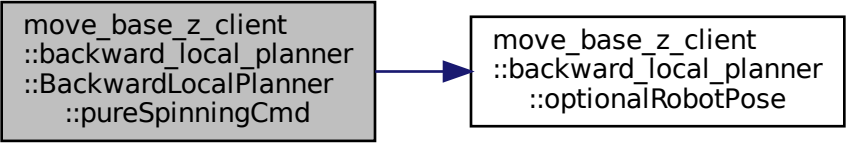


```
move_base_z_client  
::backward_local_planner  
::BackwardLocalPlanner  
  ::pureSpinningCmd
```



```
move_base_z_client  
::backward_local_planner  
  ::optionalRobotPose
```