unique_ptr< franka ::Robot::Impl >

mutex

-impl_

-control_mutex_

franka::Robot
+ Robot() + Robot() + operator=() + ~Robot() + read() + readOnce() + loadModel() + serverVersion() + control() + control() + control() + control() + control() + control() + control() + control() + control() + getVirtualWall() + setCollisionBehavior() + setCollisionBehavior() + setJointImpedance() + setCartesianImpedance() + setGuidingMode() + setK() + setEE() + setLoad() + setFilters() + automaticErrorRecovery() + stop() * control() * control() * control() * control() * control() * control() * control() * control() * control() * getVirtualWall() * setCollisionBehavior() * setCollisionBehavior() * setJointImpedance() * setCartesianImpedance() * setGuidingMode() * setK() * setEE() * setLoad() * setFilters() * automaticErrorRecovery() * stop()