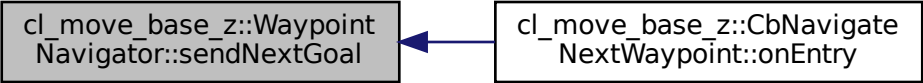


cl\_move\_base\_z::Waypoint  
Navigator::sendNextGoal



```
graph LR; A[cl_move_base_z::CbNavigateNextWaypoint::onEntry] --> B[cl_move_base_z::WaypointNavigator::sendNextGoal];
```

cl\_move\_base\_z::CbNavigate  
NextWaypoint::onEntry