


```
sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::decidePlacePose
```



```
graph LR; A["sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::decidePlacePose"] --> B["smacc::ISmaccClient  
::getComponent"]
```

A diagram showing a call from the `sm_moveit_screw_loop` package to the `smacc::ISmaccClient::getComponent` interface. The call is represented by a blue arrow pointing from the left box to the right box.

```
smacc::ISmaccClient  
::getComponent
```