

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/states/st\_navigate\_to\_waypoints\_x.h



```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/states/st_navigate_to_waypoints_x.h"]
```

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\_library/sm\_dance\_bot  
\_strikes\_back/include  
/sm\_dance\_bot\_strikes\_back  
/sm\_dance\_bot\_strikes\_back.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_strikes\_back/src/sm\_dance  
\_bot\_strikes\_back.cpp