

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```



A diagram showing a function call. On the left, a grey rectangular box contains the text: `cl_move_base_z::pure`, `_spinning_local_planner`, `::PureSpinningLocalPlanner`, and `::computeVelocityCommands`. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text: `cl_move_base_z::pure`, `_spinning_local_planner`, and `::optionalRobotPose`.

```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```