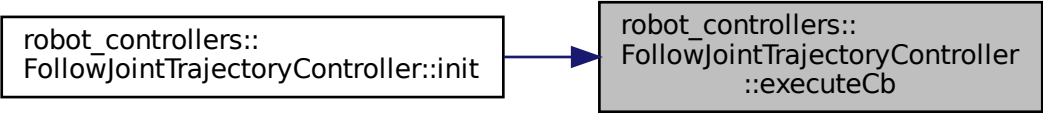


```
robot_controllers::  
FollowJointTrajectoryController::init
```



```
robot_controllers::  
FollowJointTrajectoryController  
::executeCb
```