

cl_move_base_z::forward
_local_planner::ForwardLocal
Planner::publishGoalMarker



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"] --> B["cl_move_base_z::forward  
_local_planner::optionalRobotPose"]
```

A diagram showing a call to the `publishGoalMarker` method of the `ForwardLocalPlanner` class. The call is made from the `cl_move_base_z::forward` function. The box containing this text is shaded gray.

cl_move_base_z::forward
_local_planner::optionalRobotPose

A diagram showing a call to the `optionalRobotPose` method of the `ForwardLocalPlanner` class. The call is made from the `cl_move_base_z::forward` function. The box containing this text is white.