```
franka hw::FrankaStateHandle
- name

    robot state

+ FrankaStateHandle()
+ FrankaStateHandle()
+ getName()
+ getRobotState()
franka hw::FrankaCartesian
         PoseHandle

    command

- elbow
+ FrankaCartesianPoseHandle()
+ FrankaCartesianPoseHandle()
+ setCommand()
```

+ setCommand()
+ getCommand()