smacc::ISmaccClientBehavior Δ smacc::SmaccClientBehavior stateMachine - currentState - currentOrthogonal + SmaccClientBehavior() + ~SmaccClientBehavior() + getStateMachine() + getName() + runtimeConfigure() + onEntry() + onExit() + postEvent() + postEvent() + requiresClient() + requiresComponent() + getCurrentState() configureEventSourceTypes() _multirole_sensor ::CbDefaultMultiRoleSensor Behavior < ClientType > + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() < ClTemperatureSensor > cl multirole sensor :CbDefaultMultiRoleSensor Behavior < ClTemperatureSensor > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() sm_dance_bot::cl_temperature sensor::CbConditionTemperatureSensor + CbConditionTemperatureSensor() + onMessageCallback()