BaseGlobalPlanner

A

cl_move_base_z::backward
_global_planner::BackwardGlobal
Planner

- nh_ - planPub_ - markersPub

- costmap_ros_ - skip_straight_motion _distance_

- puresSpinningRadStep_

+ BackwardGlobalPlanner() + ~BackwardGlobalPlanner()

+ makePlan() + makePlan()

+ createDefaultBackwardPath() + initialize()

- onForwardTrailMsg()- publishGoalMarker()