


cl_move_base_z::PlannerSwitcher
::dynreconfCallback



```
graph LR; A[cl_move_base_z::PlannerSwitcher::dynreconfCallback] --> B[cl_move_base_z::PlannerSwitcher::updatePlanners];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_move_base_z::PlannerSwitcher' followed by '::dynreconfCallback' on a new line. The right box is white with a black border and contains the text 'cl_move_base_z::PlannerSwitcher' followed by '::updatePlanners' on a new line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_move_base_z::PlannerSwitcher
::updatePlanners