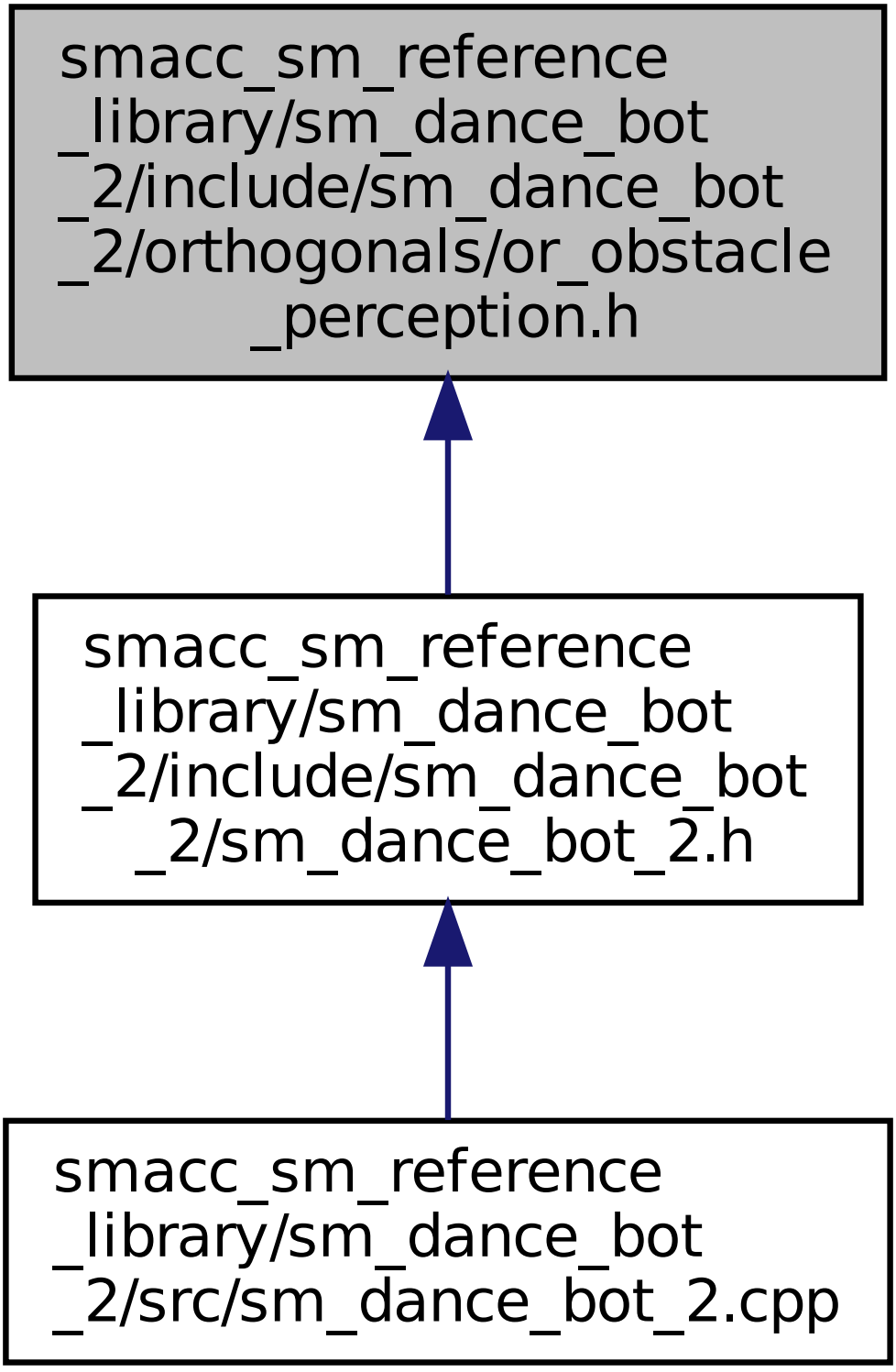
smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/orthogonals/or_obstacle
_perception.h
smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h
smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2.cpp