

tuck_arm.TuckThread.run



```
graph LR; A[tuck_arm.TuckThread.run] --> B[tuck_arm.is_moveit_running];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'tuck_arm.TuckThread.run'. A blue arrow points from the right side of this box to the left side of the right box. The right box is gray with a black border and contains the text 'tuck_arm.is_moveit_running'.

tuck_arm.is_moveit
_running