

sm_ridgeback_floor
_coverage_dynamic_1
::cl_lidar::CpLidarSensorData
::onInitialize

```
graph LR; A["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::onInitialize"] --> B["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall"]; A --> C["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]
```

The diagram shows a state machine node (shaded gray) on the left with two outgoing transitions (blue arrows) to two other state machine nodes (white) on the right. The left node contains the text: sm_ridgeback_floor, _coverage_dynamic_1, ::cl_lidar::CpLidarSensorData, and ::onInitialize. The top-right node contains: sm_ridgeback_floor, _coverage_dynamic_1, ::cl_lidar::CpLidarSensorData, and ::MessageCallbackStoreDistanceToWall. The bottom-right node contains: smacc::client_bases, ::SmaccSubscriberClient, and ::onMessageReceived.

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smacc::client_bases
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