

sm\_ridgeback\_floor  
\_coverage\_static\_1::  
OrNavigation::loadWaypoints  
FromYaml

```
graph LR; A["sm_ridgeback_floor  
_coverage_static_1::  
OrNavigation::loadWaypoints  
FromYaml"] --> B["cl_move_base_z::Waypoint  
Navigator::loadWayPointsFromFile"]
```

A diagram showing a transition from a state machine to a command. A blue arrow points from the left box to the right box.

cl\_move\_base\_z::Waypoint  
Navigator::loadWayPointsFromFile