

fetch_arm::IKFastKinematics
Plugin::getSolution

main

ikfast::IkSolutionList
::GetSolution

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graph LR; A[fetch_arm::IKFastKinematicsPlugin::getSolution] --> C[ikfast::IkSolutionList::GetSolution]; B[main] --> C;
```

The diagram illustrates a call graph with three nodes. The node 'fetch_arm::IKFastKinematicsPlugin::getSolution' is a white rectangle with a black border. The node 'main' is a smaller white rectangle with a black border. The node 'ikfast::IkSolutionList::GetSolution' is a gray rectangle with a black border. Two blue arrows point from the first two nodes to the third node, indicating that both functions call 'ikfast::IkSolutionList::GetSolution'.