

```
graph BT; A["smacc_sm_reference_library/sm_moveit_2_src/sm_moveit_2_node.cpp"] --> B["smacc_sm_reference_library/sm_moveit_2_include/sm_moveit_2/sm_moveit_2.h"]; B --> C["smacc_sm_reference_library/sm_moveit_2_include/sm_moveit_2/st_initial_posture.h"];
```

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
\_include/sm\_moveit\_2  
/states/st\_initial\_posture.h

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
\_include/sm\_moveit\_2  
/sm\_moveit\_2.h

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
\_src/sm\_moveit\_2\_node.cpp