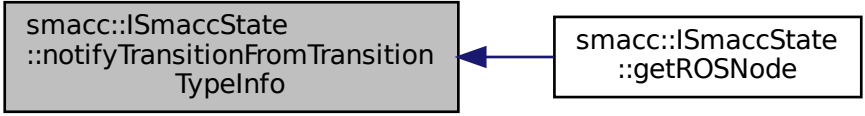
smacc::ISmaccState
::notifyTransitionFromTransition
TypeInfo
smacc::ISmaccState
::getROSNode