

```
graph BT; A["smacc_sm_reference_library/sm_moveit_2/include/sm_moveit_2/st_navigation_posture.h"] --> B["smacc_sm_reference_library/sm_moveit_2/include/sm_moveit_2/superstates/ss_pick_object.h"]; B --> C["smacc_sm_reference_library/sm_moveit_2/include/sm_moveit_2/sm_moveit_2.h"]; C --> D["smacc_sm_reference_library/sm_moveit_2/src/sm_moveit_2_node.cpp"];
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smacc\_sm\_reference  
\_library/sm\_moveit\_2  
/include/sm\_moveit\_2  
/states/pick\_states/st  
\_navigation\_posture.h

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
/include/sm\_moveit\_2  
/superstates/ss\_pick\_object.h

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
/include/sm\_moveit\_2  
/sm\_moveit\_2.h

smacc\_sm\_reference  
\_library/sm\_moveit\_2  
/src/sm\_moveit\_2\_node.cpp