

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"]
```

A diagram showing a call from the `computeVelocityCommands` method to the `publishGoalMarker` method. The call is represented by a blue arrow pointing from the right box to the left box. The left box has a gray background, while the right box has a white background.

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands
```