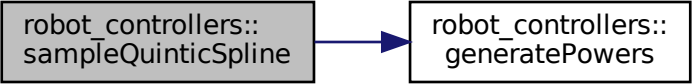


```
robot_controllers::  
sampleQuinticSpline
```



```
graph LR; A[robot_controllers::sampleQuinticSpline] --> B[robot_controllers::generatePowers]
```

```
robot_controllers::  
generatePowers
```