```
smacc::ISmaccComponent
# stateMachine
# owner
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# initialize()
# setStateMachine()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# onlnitialize()
# createSiblingComponent()
# createSiblingNamedComponent()
cl move base z::odom
       tracker::OdomTracker
# robotBasePathPub
# robotBasePathStackedPub
# odomSub
# recordPointDistanceThreshold
# recordAngularDistanceThreshold
# clearPointDistanceThreshold
# clearAngularDistanceThreshold
# odomFrame
# publishMessages
# baseTrajectory
# workingMode
# pathStack
# aggregatedStackPathMsq
# subscribeToOdometryTopic
# m mutex
+ OdomTracker()
+ processOdometryMessage()
+ setWorkingMode()
+ setPublishMessages()
+ pushPath()
+ popPath()
+ clearPath()
+ setStartPoint()
+ setStartPoint()
+ getPath()
+ logStateString()
# rtPublishPaths()
# updateRecordPath()
# updateClearPath()
# updateAggregatedStackPath()
```