```
smacc::SmaccClientBehavior

    stateMachine

- currentState
- currentOrthogonal
+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
configureEventSourceTypes()
                   cl multirole sensor
                   :: CbDefault MultiRole Sensor
                       Behavior < ClientType >
                   + sensor
                   + deferedEventPropagation
                   + CbDefaultMultiRoleSensor
                   Behavior()
                   + configureEventSourceTypes()
                   + propagateEvent()
                   + propagateEvent2()
                   + onEntry()
                   + onExit()
                   + onMessageCallback()
                   + getEventLabel()
                          < ClLidarSensor >
cl multirole sensor
::CbDefaultMultiRoleSensor
  Behavior < ClLidarSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
    sm_dance_bot::cl lidar
        ::CbLidarSensor
    + CbLidarSensor()
    + onEntry()
```

+ onMessageCallback()