

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::createCarrotGoal
```



A diagram showing a call sequence between two functions. A grey box on the left contains the code for `createCarrotGoal`, and a white box on the right contains the code for `computeCurrentEuclideanAndAngularErrors`. A blue arrow points from the grey box to the white box, indicating a call from the first function to the second.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors
```