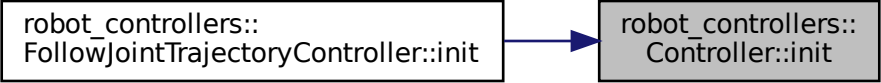


robot_controllers::
FollowJointTrajectoryController::init



```
graph LR; A[robot_controllers::FollowJointTrajectoryController::init] --> B[robot_controllers::Controller::init];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'robot_controllers::FollowJointTrajectoryController::init'. The right box is gray with a black border and contains the text 'robot_controllers::Controller::init'. A blue arrow points from the right side of the left box to the left side of the right box.

robot_controllers::
Controller::init