

```
smacc_client_library  
/move_base_z_client/custom  
_planners/forward_global  
_planner/include/forward_global  
_planner/move_base_z_client_tools.h
```



```
graph TD; A["smacc_client_library  
/move_base_z_client/custom  
_planners/forward_global  
_planner/include/forward_global  
_planner/move_base_z_client_tools.h"] --> B["ros/ros.h"]; A --> C["geometry_msgs/PoseStamped.h"]
```

ros/ros.h

geometry_msgs/PoseStamped.h