

cl_ros_timer::CbTimer
::configureEventSourceTypes



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graph LR; A[cl_ros_timer::CbTimer::configureEventSourceTypes] --> B[cl_ros_timer::CbTimer::onClientTimerTickCallback]
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The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_ros_timer::CbTimer' followed by '::configureEventSourceTypes' on the next line. The right box is white and contains the text 'cl_ros_timer::CbTimer' followed by '::onClientTimerTickCallback' on the next line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_ros_timer::CbTimer
::onClientTimerTickCallback