

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a function call. A white box on the left contains the code snippet. A blue arrow points from the white box to a gray box on the right, which contains the same code snippet with the last line replaced by a default command.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```