

```
boost::statechart::  
event< EvWaypoint115  
< TSource, TObjectTag > >
```

The diagram shows a base class at the top and a derived class at the bottom. The base class is defined by a box with three sections: the top section contains the class name and template parameters, and the two bottom sections are empty. The derived class is defined by a box with three sections: the top section contains the class name and template parameters, the middle section contains a public member variable, and the bottom section is empty. A blue arrow with an open triangular head points from the top of the derived class box to the bottom of the base class box, indicating inheritance.

```
cl_move_base_z::EvWaypoint115  
  < TSource, TObjectTag >
```

```
+ waypointIndex
```