

sm_dance_bot_2::radial
_motion_states::StiRadialEnd
Point::onInitialize

```
graph LR; A["sm_dance_bot_2::radial_motion_states::StiRadialEndPoint::onInitialize"] --> B["smacc::ISmaccClient::getComponent"]; A --> C["smacc::ISmaccState::requiresClient"];
```

smacc::ISmaccClient
::getComponent

smacc::ISmaccState
::requiresClient