

```
move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::makePlan
```

```
graph LR; A["move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::makePlan"] --> B["move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::createDefaultBackwardPath"]; A --> C["move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::publishGoalMarker"]
```

```
move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::createDefaultBackwardPath
```

```
move_base_z_client  
::backward_global_planner  
::BackwardGlobalPlanner  
::publishGoalMarker
```