

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintLateralWorkspace  
::createVirtualCollisionWalls
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and a black border, containing four lines of C++ code. The right box has a white background and a black border, containing the same first three lines of code, but with the last line, `::createCollisionBox`, indented further to the right. The blue arrow is positioned between the two boxes, pointing from the right side of the left box to the left side of the right box.

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createCollisionBox
```