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nav_core::BaseLocalPlanner
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move_base_z_client
::forward_local_planner
    ::ForwardLocalPlanner
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- costmapRos_
- goalMarkerPublisher_
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- k_alpha_
- k_betta_
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+ ForwardLocalPlanner()
+ ~ForwardLocalPlanner()
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+ isGoalReached()
+ setPlan()
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+ initialize()
+ initialize()
- publishGoalMarker()
- generateTrajectory()
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