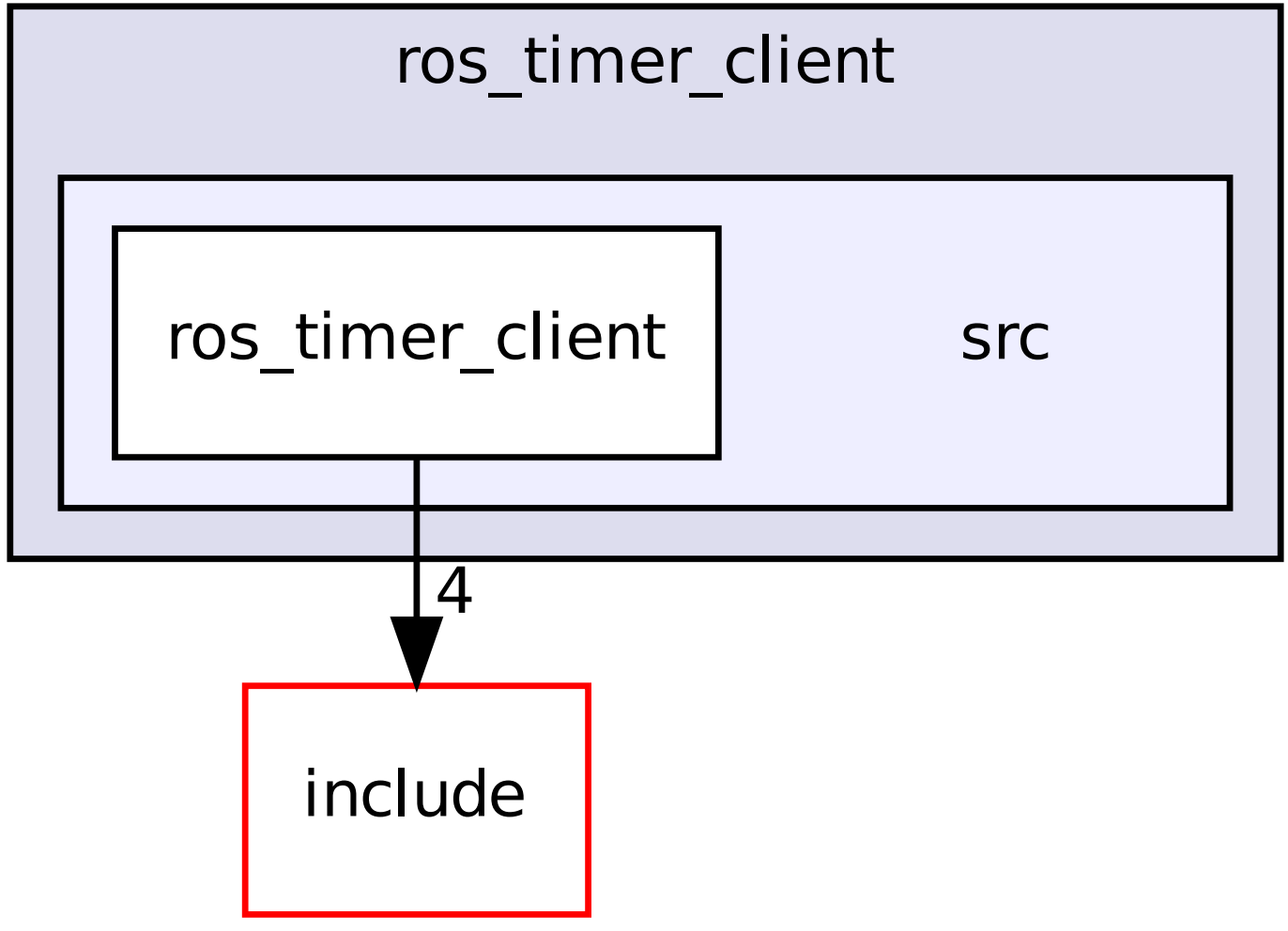
ros_timer_client
ros_timer_client
src
4
include