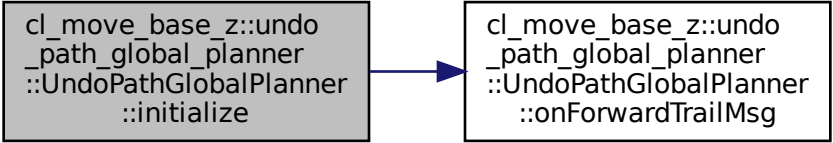


```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::initialize
```



```
graph LR; A["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::initialize"] --> B["cl_move_base_z::undo_path_global_planner::UndoPathGlobalPlanner::onForwardTrailMsg"]
```

```
cl_move_base_z::undo  
_path_global_planner  
::UndoPathGlobalPlanner  
::onForwardTrailMsg
```