

```
graph BT; A["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/include/sm_fetch_robot_asynchronous  
_orthogonals/orthogonals/or_gripper.h"] --> B["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/include/sm_fetch_robot_asynchronous  
_orthogonals/sm_fetch_robot_asynchronous  
_orthogonals.h"]; B --> C["smacc_sm_reference  
_library/sm_fetch_robot  
_asynchronous_orthogonals  
/src/sm_fetch_robot_asynchronous  
_orthogonals_node.cpp"];
```

smacc_sm_reference
_library/sm_fetch_robot
_asynchronous_orthogonals
/include/sm_fetch_robot_asynchronous
_orthogonals/orthogonals/or_gripper.h

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