```
research interface
::robot::RequestBase< T >
              < SetCollisionBehavior >
 research interface
 ::robot::RequestBase
 < SetCollisionBehavior >
research interface
::robot::SetCollisionBehavior
         ::Request
+ lower torque thresholds
acceleration
+ upper torque thresholds
acceleration
+ lower torque thresholds
nominal
+ upper torque thresholds
nominal
+ lower force thresholds
acceleration
+ upper force thresholds
acceleration
+ lower force thresholds
nominal
+ upper_force thresholds
nominal
+ Request()
```