

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_orthogonals/or_string  
_publisher.h"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_orthogonals/or_string
_publisher.h

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
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smacc_sm_reference
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