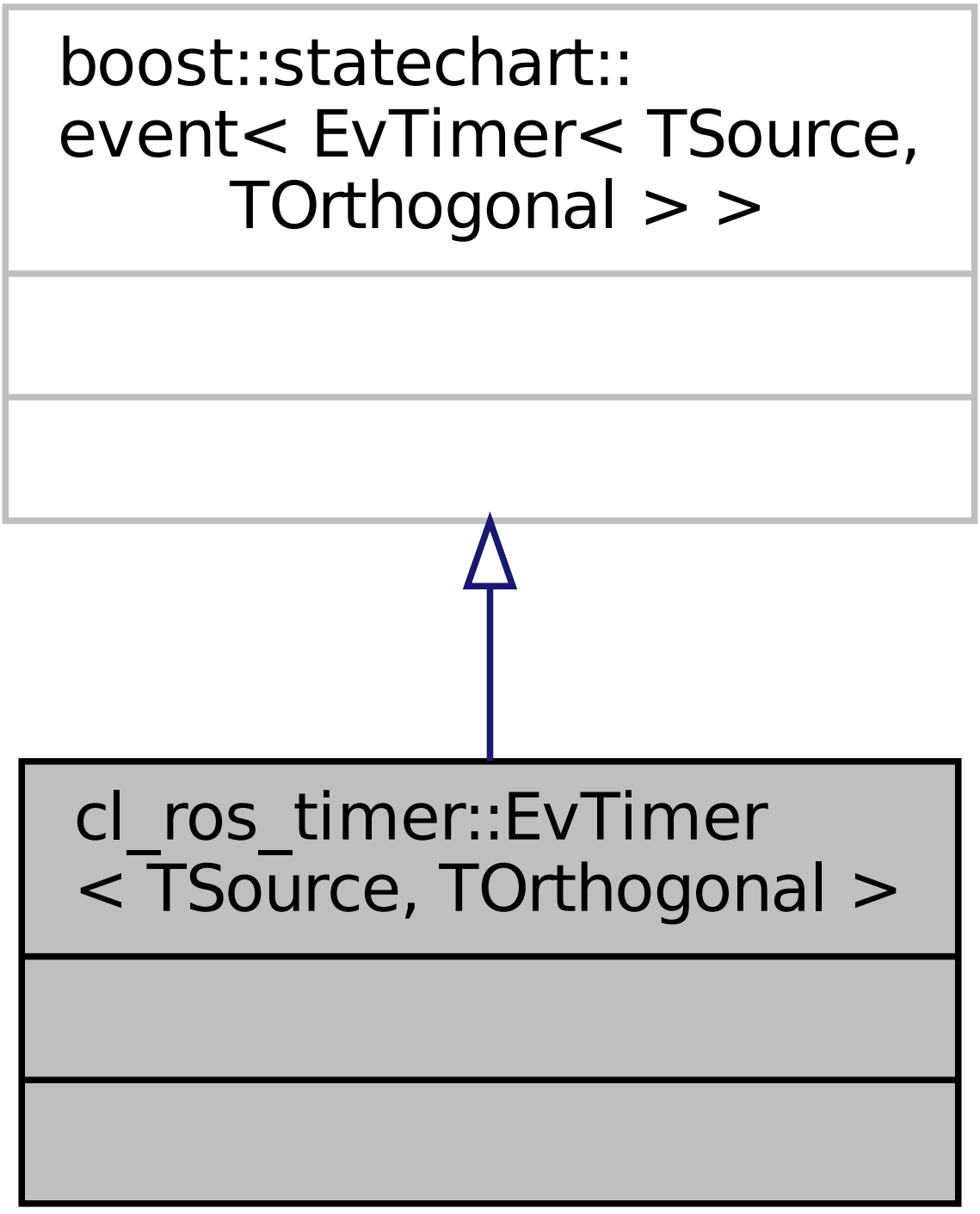
boost::statechart::
event< EvTimer< TSource,
TOrthogonal > >
cl_ros_timer::EvTimer
< TSource, TOrthogonal >