



-max_angular_z_speed
-xy_goal_tolerance
-yaw_goal_tolerance
-k_beta_
-k_rho_
-carrot_angular
distance_
-betta_offset
-alpha_offset
-k_alpha_
-carrot_distance
...
-waitingStamp_
-goalMarkerPublisher_
-waitingTimeout_
-plan_
-costmapRos_
-currentPoseIndex_
-waiting_
-goalReached_

