

```
sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall
```

A blue arrow points from the right side of the second box to the left side of the first box.

```
sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::onInitialize
```