```
smacc::ISmaccClientBehavior
  - stateMachine
  currentState

    currentOrthogonal

  + ISmaccClientBehavior()
     ~ISmaccClientBehavior()
  + getStateMachine()
  + getName()
+ requiresClient()
  + requiresComponent()
  # runtimeConfigure()
  # onEntry()
  # onExit()
  # postEvent()
  # postEvent()
  # getCurrentState()
  # executeOnEntry()
  # executeOnExit()
  # dispose()
  - onOrthogonalAllocation()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                 Δ
                          multirole sensor
                       :: C
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                         Behavior < ClientType >
                       + deferedEventPropagation
                       + CbDefaultMultiRoleSensor
                       Behavior()
                       + onOrthogonalAllocation()
                       + propagateEvent()
                       + propagateEvent2()
                       + onEntry()
                       + onExit()
                       + onMessageCallback()
                       + getEventLabel()
                             < ClTemperatureSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < CITemperatureSensor >
+ sensor
+ deferedEventPropagation

    + CbDefaultMultiRoleSensor

Behavior()
+ onOrthogonalAllocation()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
                  Д
sm_dance_bot_strikes
_back::cl_temperature
_sensor::CbConditionTemperature
               Sensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```