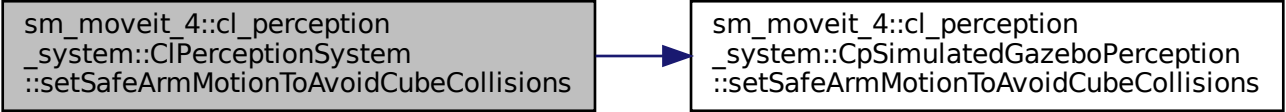


```
sm_moveit_4::cl_perception  
_system::ClPerceptionSystem  
::setSafeArmMotionToAvoidCubeCollisions
```



```
graph LR; A["sm_moveit_4::cl_perception  
_system::ClPerceptionSystem  
::setSafeArmMotionToAvoidCubeCollisions"] --> B["sm_moveit_4::cl_perception  
_system::CpSimulatedGazeboPerception  
::setSafeArmMotionToAvoidCubeCollisions"]
```

```
sm_moveit_4::cl_perception  
_system::CpSimulatedGazeboPerception  
::setSafeArmMotionToAvoidCubeCollisions
```