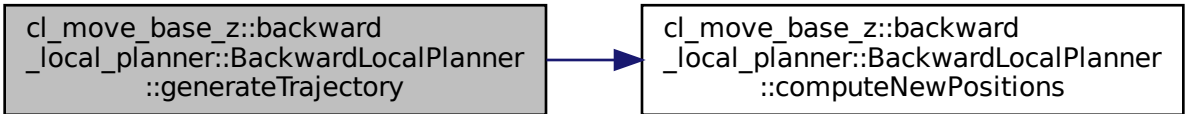
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::generateTrajectory
cl_move_base_z::backward
_local_planner::BackwardLocalPlanner
::computeNewPositions