

mecanum_drive_controller
::MecanumDriveController::init



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::init] --> B[mecanum_drive_controller::MecanumDriveController::cmdVelCallback];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'mecanum_drive_controller' followed by '::MecanumDriveController::init' on the next line. The right box is gray with a black border and contains the text 'mecanum_drive_controller' followed by '::MecanumDriveController' on the next line, and '::cmdVelCallback' on the third line. A blue arrow points from the right side of the left box to the left side of the right box.

mecanum_drive_controller
::MecanumDriveController
::cmdVelCallback