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smacc_sm_reference  
_library/sm_dance_bot  
/servers/temperature_sensor  
_node/src/temperature_sensor  
_node.cpp
```



```
graph TD; A["smacc_sm_reference_library/sm_dance_bot/servers/temperature_sensor_node/src/temperature_sensor_node.cpp"] --> B["ros/ros.h"]; A --> C["sensor_msgs/Temperature.h"]
```

ros/ros.h

sensor\_msgs/Temperature.h