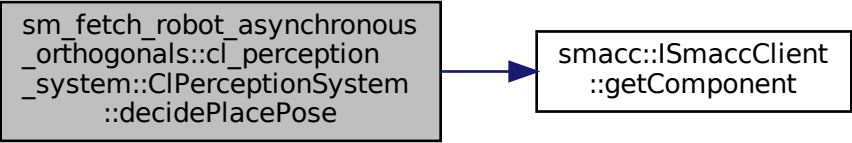


```
sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::CIPerceptionSystem  
::decidePlacePose
```



```
graph LR; A["sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::CIPerceptionSystem  
::decidePlacePose"] --> B["smacc::ISmaccClient  
::GetComponent"]
```

A diagram showing a call from a perception system to a smacc client. On the left, a grey box contains the text: `sm_fetch_robot_asynchronous`, `_orthogonals::cl_perception`, `_system::CIPerceptionSystem`, and `::decidePlacePose`. A blue arrow points from this box to a white box on the right. The white box contains the text: `smacc::ISmaccClient` and `::GetComponent`.

```
smacc::ISmaccClient  
::GetComponent
```