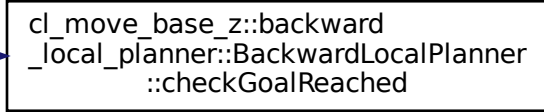


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```

A rectangular box with a black border and a light gray background. It contains three lines of C++ code. The first line is 'cl_move_base_z::backward', the second is '_local_planner::BackwardLocalPlanner', and the third is '::defaultBackwardCmd'.

```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached"]
```

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached
```

A rectangular box with a black border and a white background. It contains three lines of C++ code. The first line is 'cl_move_base_z::backward', the second is '_local_planner::BackwardLocalPlanner', and the third is '::checkGoalReached'.

```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkGoalReached"]
```