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graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/f_pattern_states  
/sti_fpattern_forward_2.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/superstates/ss_f_pattern_1.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/states/f_pattern_states
/sti_fpattern_forward_2.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/superstates/ss_f_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
/include/sm_dance_bot
/sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
/src/sm_dance_bot.cpp