

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::findInitialCarrotGoal'. The right box has a white background and a black border, containing the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::computeCurrentEuclideanAndAngularErrors ToCarrotGoal'. A dark blue arrow points from the right side of the left box to the left side of the right box.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```