```
franka::RobotControl
   + ~RobotControl()
   + startMotion()
   + finishMotion()
  + cancelMotion()
   + update()
   + throwOnMotionError()
   + realtimeConfig()
     franka::Robot::Impl
- network
- loaaer
- realtime config
- ri version
- motion generator mode
- current move motion
generator mode
- controller mode

    current move controller

mode
- message id
+ Impl()
+ update()
+ throwOnMotionError()
+ readOnce()
+ serverVersion()
+ realtimeConfig()
+ startMotion()
+ cancelMotion()
+ finishMotion()
+ executeCommand()
+ loadModel()
# motionGeneratorRunning()
# controllerRunning()
- handleCommandResponse()

    handleCommandResponse()

sendRobotCommand()
receiveRobotState()
updateState()
```