


```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'cl_move_base_z::pure _spinning_local_planner ::optionalRobotPose'. The box on the right is white with a black border and contains the text 'cl_move_base_z::pure _spinning_local_planner ::PureSpinningLocalPlanner ::computeVelocityCommands'. A blue arrow points from the right box to the left box, indicating a function call.

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```