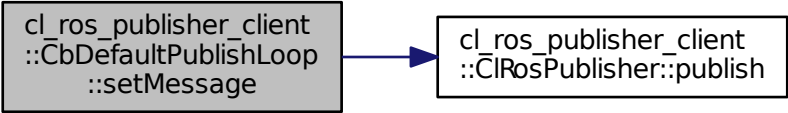


```
cl_ros_publisher_client  
::CbDefaultPublishLoop  
::setMessage
```



```
graph LR; A["cl_ros_publisher_client  
::CbDefaultPublishLoop  
::setMessage"] --> B["cl_ros_publisher_client  
::CIRosPublisher::publish"]
```

```
cl_ros_publisher_client  
::CIRosPublisher::publish
```