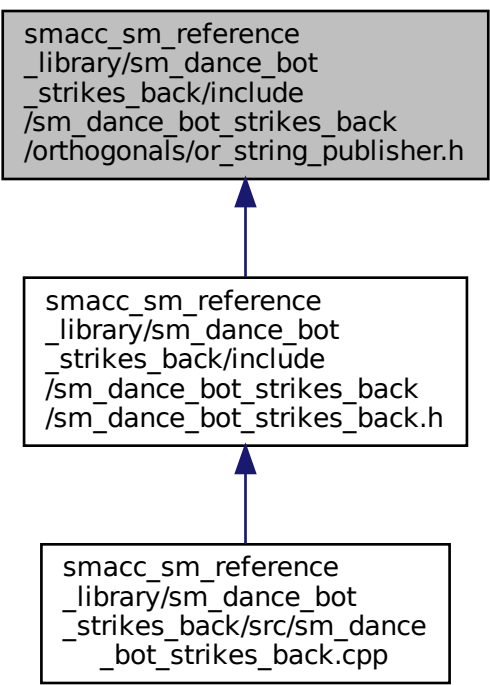


smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/orthogonals/or_string_publisher.h



```
graph BT; A["smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp"] --> B["smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/orthogonals/or_string_publisher.h"]
```

The diagram illustrates a dependency chain between three files. At the bottom is a box containing the source file path: `smacc_sm_reference_library/sm_dance_bot_strikes_back/src/sm_dance_bot_strikes_back.cpp`. A blue arrow points upwards from this box to a middle box. The middle box contains the header file path: `smacc_sm_reference_library/sm_dance_bot_strikes_back/include/sm_dance_bot_strikes_back/orthogonals/or_string_publisher.h`. Another blue arrow points upwards from the middle box to a top box, which contains the same header file path as the middle box. The top box has a gray background, while the middle and bottom boxes have white backgrounds.

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.h

smacc_sm_reference
_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back.cpp