```
# stateMachine_
# serviceName_
# owner_
+ ISmaccComponent()
+ ~ISmaccComponent()
+ initialize()
+ setStateMachine()
```

+ postEvent()+ postEvent()+ configureEventSourceTypes()



sm\_dance\_bot\_2::cl \_lidar::CpLidarSensorData

+ lastMessage\_ + forwardObstacleDistance

+ SECURITY\_DISTANCE

+ getName()

+ initialize()+ MessageCallbackStoreDistance

ToWall()