

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_2/src/sm_dance_bot_2.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_2/include/sm_dance_bot  
_2/sm_dance_bot_2.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_2/include/sm_dance_bot  
_2/states/ms_dance_bot_recovery  
_mode/ms_dance_bot_recovery_mode.h"]
```

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_recovery
_mode/ms_dance_bot_recovery_mode.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2.cpp