```
smacc::ISmaccComponent

# stateMachine_
# serviceName_
# owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ initialize()
+ setStateMachine()
+ getName()
```

+ configureEventSourceTypes()

```
sm_dance_bot_3::cl
_lidar::CpLidarSensorData
+ lastMessage
```

- + forwardObstacleDistance + SECURITY DISTANCE
- + initialize()

+ postEvent()
+ postEvent()

+ MessageCallbackStoreDistance ToWall()