

boost::statechart::
event< EvWaypoint251
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint251< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint251["cl_move_base_z::EvWaypoint251< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint251 --|> boost_statechart_event
```

The diagram illustrates an inheritance relationship. A blue arrow with an open triangular head points from the bottom class to the top class. The top class is defined in a white box with a thin grey border, and the bottom class is defined in a grey box with a thick black border. Both boxes are divided into three horizontal sections. The top section of the white box contains the class name. The top section of the grey box contains the class name and its template parameters. The middle section of the grey box contains a public member variable. The bottom section of the grey box is empty.

cl_move_base_z::EvWaypoint251
< TSource, TOrthogonal >

+ waypointIndex