

```
graph BT; A["smacc_sm_reference_library/sm_moveit_3/src/sm_moveit_3_node.cpp"] --> B["smacc_sm_reference_library/sm_moveit_3/include/sm_moveit_3/sm_moveit_3.h"]; B --> C["smacc_sm_reference_library/sm_moveit_3/include/sm_moveit_3/superstates/ss_pick_object.h"]; C --> D["smacc_sm_reference_library/sm_moveit_3/include/sm_moveit_3/states/pick_states/st_grasp_approach.h"];
```

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_states/pick\_states/st  
\_grasp\_approach.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_superstates/ss\_pick\_object.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_include/sm\_moveit\_3  
\_sm\_moveit\_3.h

smacc\_sm\_reference  
\_library/sm\_moveit\_3  
\_src/sm\_moveit\_3\_node.cpp