


```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```

A blue arrow points from the right box to the left box, indicating a call to the computeVelocityCommands method.

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```