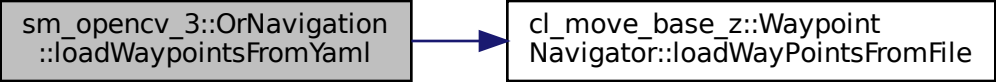


sm\_opencv\_3::OrNavigation  
::loadWaypointsFromYaml



```
graph LR; A[sm_opencv_3::OrNavigation::loadWaypointsFromYaml] --> B[cl_move_base_z::WaypointNavigator::loadWayPointsFromFile]
```

cl\_move\_base\_z::Waypoint  
Navigator::loadWayPointsFromFile