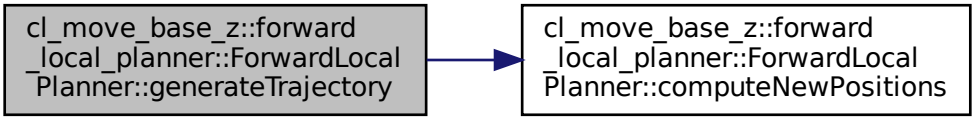
cl_move_base_z::forward_local_planner::ForwardLocalPlanner::generateTrajectory
cl_move_base_z::forward_local_planner::ForwardLocalPlanner::computeNewPositions