```
sm dance bot strikes
                                      _back::cl_lidar::CpLidarSensor
                                            Data::onInitialize
smacc::client bases
::SmaccSubscriberClient
 ::onMessageReceived
                                      sm_ridgeback_floor
                                      _coverage_dynamic_1
::cl_lidar::CpLidarSensorData
```

::onInitialize