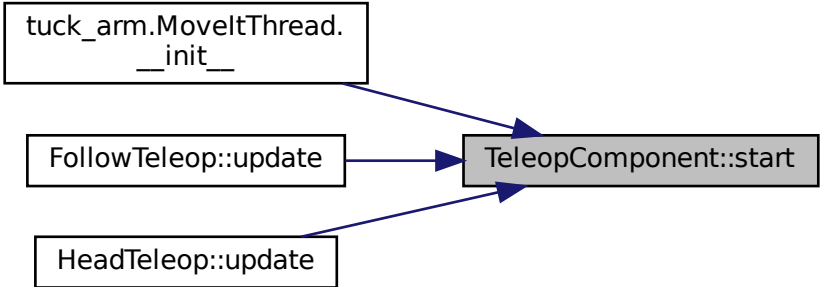


tuck_arm.MoveItThread.
__init__

FollowTeleop::update

HeadTeleop::update

TeleopComponent::start



```
graph LR; A[tuck_arm.MoveItThread.__init__] --> D[TeleopComponent::start]; B[FollowTeleop::update] --> D; C[HeadTeleop::update] --> D;
```