

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/src/sm_dance  
_bot_strikes_back.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/sm_dance_bot_strikes_back.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_strikes_back/include  
/sm_dance_bot_strikes_back  
/clients/cl_lidar/client_behaviors  
/cb_lidar_sensor.h"];
```

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_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/clients/cl_lidar/client_behaviors
/cb_lidar_sensor.h

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_library/sm_dance_bot
_strikes_back/include
/sm_dance_bot_strikes_back
/sm_dance_bot_strikes_back.h

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_library/sm_dance_bot
_strikes_back/src/sm_dance
_bot_strikes_back.cpp