

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeNewPositions"]
```

A diagram showing a call sequence between two functions. The first function, `cl_move_base_z::backward_local_planner::BackwardLocalPlanner::generateTrajectory`, is shown in a grey box on the left. A blue arrow points from this box to a white box on the right, which contains the function `cl_move_base_z::backward_local_planner::BackwardLocalPlanner::computeNewPositions`.

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cl_move_base_z::backward  
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