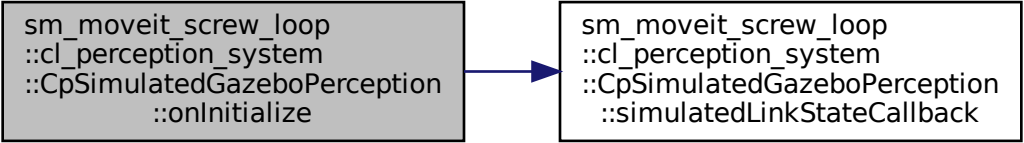


```
sm_moveit_screw_loop  
::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::onInitialize
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains four lines of C++ code. The right box has a white background and contains four lines of C++ code. The arrow originates from the right side of the left box and points to the left side of the right box.

```
sm_moveit_screw_loop  
::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::simulatedLinkStateCallback
```