```
sm_ferrari::cl_subscriber
::CbMySubscriberBehavior
::onEntry

smacc::client_bases
::SmaccSubscriberClient
::onMessageReceived

sm_dance_bot_strikes
_back::cl_lidar::CpLidarSensor
Data::onInitialize
```

sm_ridgeback_floor _coverage_dynamic_1 ::cl_lidar::CpLidarSensorData ::onInitialize