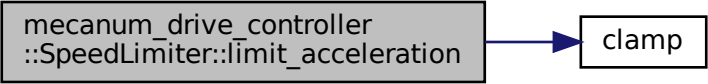


mecanum_drive_controller
::SpeedLimiter::limit_acceleration



```
graph LR; A["mecanum_drive_controller  
::SpeedLimiter::limit_acceleration"] --> B["clamp"]
```

clamp