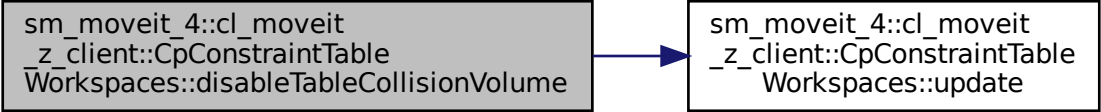


sm\_moveit\_4::cl\_moveit  
\_z\_client::CpConstraintTable  
Workspaces::disableTableCollisionVolume



```
graph LR; A["sm_moveit_4::cl_moveit  
_z_client::CpConstraintTable  
Workspaces::disableTableCollisionVolume"] --> B["sm_moveit_4::cl_moveit  
_z_client::CpConstraintTable  
Workspaces::update"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box has a gray background and a black border, containing three lines of text. The right box has a white background and a black border, also containing three lines of text. A blue arrow points from the right side of the gray box to the left side of the white box.

sm\_moveit\_4::cl\_moveit  
\_z\_client::CpConstraintTable  
Workspaces::update