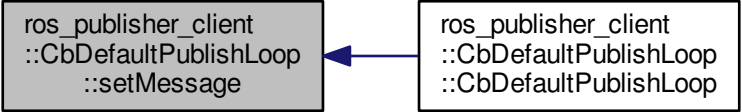


```
ros_publisher_client  
::CbDefaultPublishLoop  
  ::setMessage
```



```
graph LR; A[ros_publisher_client  
::CbDefaultPublishLoop  
::setMessage] --> B[ros_publisher_client  
::CbDefaultPublishLoop  
::CbDefaultPublishLoop];
```

```
ros_publisher_client  
::CbDefaultPublishLoop  
::CbDefaultPublishLoop
```