

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeNewPositions"]
```

A diagram showing a call sequence between two methods. A grey box on the left contains the code for `generateTrajectory`, and a white box on the right contains the code for `computeNewPositions`. A blue arrow points from the grey box to the white box, indicating a call from `generateTrajectory` to `computeNewPositions`.

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cl_move_base_z::backward  
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```