```
smacc::ISmaccClientBehavior
 - stateMachine

    currentState

    currentOrthogonal

  + ISmaccClientBehavior()
  + ~ISmaccClientBehavior()
  + getStateMachine()
  + getName()
+ requiresClient()
  + requiresComponent()
  # runtimeConfigure()
  # onEntry()
  # onExit()
  # postEvent()
  # postEvent()
  # getCurrentState()
  configureEventSourceTypes()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                Δ
                      cl multirole sensor
                      :: CbDefault MultiRole Sensor
                         Behavior < ClientType >
                      + sensor
                      + deferedEventPropagation
                      + CbDefaultMultiRoleSensor
                      Behavior()
                      + configureEventSourceTypes()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                            < ClTemperatureSensor >
cl multirole sensor
::C̄bDefaultM̄ultiRoleSensor
Behavior < CITemperatureSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
                 Δ
sm_dance_bot_2::cl
_temperature_sensor
 ::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```