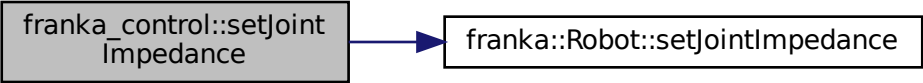


franka_control::setJoint
Impedance



```
graph LR; A[franka_control::setJointImpedance] --> B[franka::Robot::setJointImpedance]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'franka_control::setJointImpedance' on two lines. The right box is white with a black border and contains the text 'franka::Robot::setJointImpedance' on one line. A dark blue arrow points from the right side of the left box to the left side of the right box.

franka::Robot::setJointImpedance