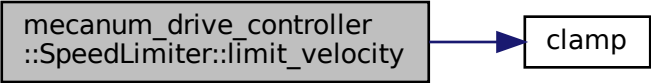


mecanum\_drive\_controller  
::SpeedLimiter::limit\_velocity



```
graph LR; A[mecanum_drive_controller::SpeedLimiter::limit_velocity] --> B[clamp]
```

clamp