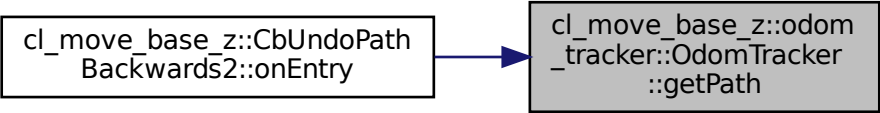


cl\_move\_base\_z::CbUndoPath  
Backwards2::onEntry



```
graph LR; A["cl_move_base_z::CbUndoPathBackwards2::onEntry"] --> B["cl_move_base_z::odometerTracker::getPath"]
```

cl\_move\_base\_z::odometerTracker::getPath