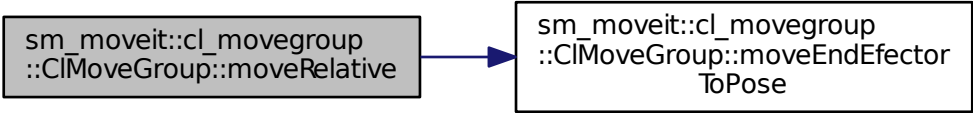


sm_moveit::cl_movegroup
::ClMoveGroup::moveRelative



```
graph LR; A["sm_moveit::cl_movegroup  
::ClMoveGroup::moveRelative"] --> B["sm_moveit::cl_movegroup  
::ClMoveGroup::moveEndEffector  
ToPose"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains the text 'sm_moveit::cl_movegroup' followed by '::ClMoveGroup::moveRelative' on the next line. The right box has a white background and contains the text 'sm_moveit::cl_movegroup' followed by '::ClMoveGroup::moveEndEffector' on the next line, and 'ToPose' on the third line.

sm_moveit::cl_movegroup
::ClMoveGroup::moveEndEffector
ToPose