

```
boost::statechart::  
event< EvWaypoint244  
< TSource, TObjectTag > >
```

The diagram shows a base class at the bottom and a derived class at the top. The base class is shaded gray and has three sections: the first contains the class name and template parameters, the second contains a public member variable, and the third is empty. The derived class is white and has three sections: the first contains the class name and template parameters, and the next two are empty. A blue arrow with an open triangular head points from the base class to the derived class, indicating inheritance.

```
cl_move_base_z::EvWaypoint244  
  < TSource, TObjectTag >
```

```
+ waypointIndex
```