## smacc::SmaccClientBehavior + stateMachine + currentState + currentOrthogonal + SmaccClientBehavior() + ~SmaccClientBehavior() + getName() + onEntry() + onExit() + postEvent() + postEvent() + requiresClient() + requiresComponent() configureEventSourceTypes() multirole sensor client ::CbDefaultMultiRoleSensorBehavior < ClientType > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() < ClTemperatureSensor > multirole\_sensor\_client ::CbDefaultMultiRoleSensorBehavior < ClTemperatureSensor > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() sm\_dance\_bot::cl\_temperature sensor::CbConditionTemperatureSensor + CbConditionTemperatureSensor() + onMessageCallback()