```
# stateMachine
     # components
     + ISmaccClient()
     + ~ISmaccClient()
     + initialize()
     + setStateMachine()
     + getName()
     + postEvent()
     + postEvent()
     + getComponent()
     + configureEventSourceTypes()
     + getType()
                    smacc::client bases
                    ::SmaccSubscriberClient
                           < MessageType >
                    + topicName
                    + queueSize
                    + onFirstMessageReceived_
                    + onMessageReceived_
                    + postMessageEvent
                    + postInitialMessageEvent
                    # nh_
                    - sub
                    - firstMessage_

    initialized

                    + SmaccSubscriberClient()
                    + ~SmaccSubscriberClient()
                    + onMessageReceived()
                    + onFirstMessageReceived()
                    + configureEventSourceTypes()
                    + initialize()
                    - messageCallback()
                    < sensor_msgs::LaserScan >
smacc::client_bases
::SmaccSubscriberClient
 < sensor msgs::LaserScan >
                                     multirole sensor client
+ topicName
                                     ::ClMultiroleSensor< Message
+ queueSize
                                                 Type >
+ onFirstMessageReceived_
+ onMessageReceived_
                                     + onMessageTimeout_
+ postMessageEvent
                                     + postTimeoutMessageEvent
+ postInitialMessageEvent
                                     + timeout
# nh_
                                     timeoutTimer_
                                     - initialized
- sub
- firstMessage_
                                     + ClMultiroleSensor()
- initialized
                                     + onMessageTimeout()
+ SmaccSubscriberClient()
                                     + configureEventSourceTypes()
+ ~SmaccSubscriberClient()
                                     + initialize()
                                     # resetTimer()
+ onMessageReceived()
+ onFirstMessageReceived()
                                     timeoutCallback()
+ configureEventSourceTypes()
+ initialize()
messageCallback()
                                      < sensor_msgs::LaserScan >
           multirole_sensor_client
           ::CIMultiroleSensor< sensor
                 msgs::LaserScan >
           + onMessageTimeout
           + postTimeoutMessageEvent
           + timeout
          - timeoutTimer_
           - initialized
           + ClMultiroleSensor()
           + onMessageTimeout()
           + configureEventSourceTypes()
           + initialize()
           # resetTimer()
           - timeoutCallback()
               sm dance bot::cl lidar
                  ::ClLaserSensor
```

+ ClLaserSensor()

smacc::ISmaccClient