

```
robot_controllers::  
SplineTrajectorySampler  
::SplineTrajectorySampler
```



A diagram consisting of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains three lines of C++ code. The right box is gray with a black border and contains two lines of C++ code.

```
robot_controllers::  
CubicSpline
```