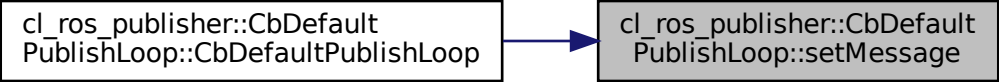


cl_ros_publisher::CbDefault
PublishLoop::CbDefaultPublishLoop



```
graph LR; A["cl_ros_publisher::CbDefault  
PublishLoop::CbDefaultPublishLoop"] --> B["cl_ros_publisher::CbDefault  
PublishLoop::setErrorMessage"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'cl_ros_publisher::CbDefault' on the first line and 'PublishLoop::CbDefaultPublishLoop' on the second line. The right box is gray with a black border and contains the text 'cl_ros_publisher::CbDefault' on the first line and 'PublishLoop::setErrorMessage' on the second line. A blue arrow points from the right side of the left box to the left side of the right box.

cl_ros_publisher::CbDefault
PublishLoop::setErrorMessage