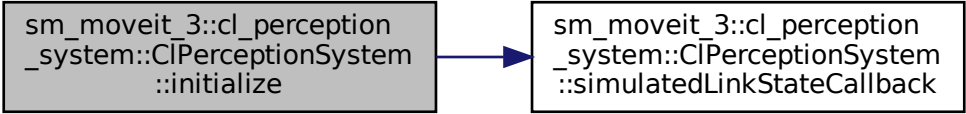


sm_moveit_3::cl_perception
_system::ClPerceptionSystem
::initialize



```
graph LR; A["sm_moveit_3::cl_perception_system::initialize"] --> B["sm_moveit_3::cl_perception_system::simulatedLinkStateCallback"]
```

sm_moveit_3::cl_perception
_system::ClPerceptionSystem
::simulatedLinkStateCallback