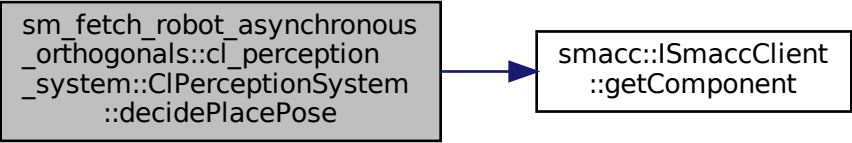


```
sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::ClPerceptionSystem  
::decidePlacePose
```



```
graph LR; A["sm_fetch_robot_asynchronous  
_orthogonals::cl_perception  
_system::ClPerceptionSystem  
::decidePlacePose"] --> B["smacc::ISmaccClient  
::GetComponent"]
```

A diagram showing a call from the ClPerceptionSystem to the ISmaccClient::GetComponent method. The call is represented by a blue arrow pointing from the left box to the right box.

```
smacc::ISmaccClient  
::GetComponent
```