

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::pureSpinningCmd
```



A diagram showing a transformation from a specific command to a more general pose. On the left, a grey rectangular box contains the text 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::pureSpinningCmd'. A blue arrow points from the right side of this box to the right side of a white rectangular box on the right. The white box contains the text 'cl_move_base_z::backward', '_local_planner::optionalRobotPose', and 'Pose'.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose  
Pose
```