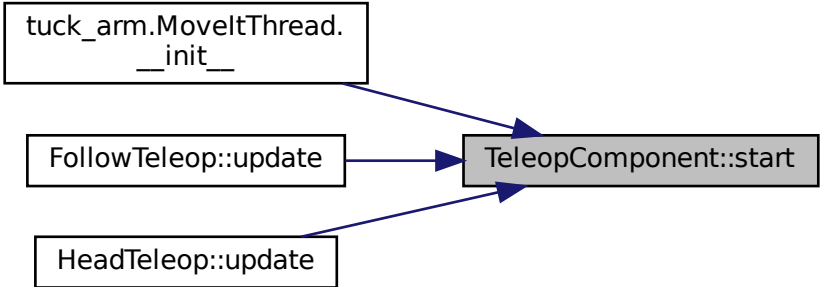


tuck\_arm.MoveItThread.  
\_\_init\_\_

FollowTeleop::update

HeadTeleop::update

TeleopComponent::start



```
graph LR; A[tuck_arm.MoveItThread.__init__] --> D[TeleopComponent::start]; B[FollowTeleop::update] --> D; C[HeadTeleop::update] --> D;
```