

BaseLocalPlanner

```
classDiagram
    class BaseLocalPlanner {
    }
    class PureSpinningGlobalPlanner {
        + move_base_z_client
        + ::pure_spinning_global_planner::PureSpinningGlobalPlanner()
        + computeVelocityCommands()
        + isGoalReached()
        + setPlan()
        + initialize()
        + initialize()
        + initialize()
    }
    BaseLocalPlanner <|-- PureSpinningGlobalPlanner
```

move_base_z_client
::pure_spinning_global
_planner::PureSpinningGlobal
Planner

+ PureSpinningGlobalPlanner()
+ ~PureSpinningGlobalPlanner()
+ computeVelocityCommands()
+ isGoalReached()
+ setPlan()
+ initialize()
+ initialize()
+ initialize()