

```
graph BT; A["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/include/sm_ridgeback  
_floor_coverage_dynamic_1  
/clients/cl_lidar/components  
/cp_lidar_data.h"] <-- B["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/include/sm_ridgeback  
_floor_coverage_dynamic_1  
/orthogonals/or_obstacle_perception.h"]; B <-- C["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/include/sm_ridgeback  
_floor_coverage_dynamic_1  
/sm_ridgeback_floor_coverage  
_dynamic_1.h"]; C <-- D["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/src/sm_ridgeback_floor  
_coverage_dynamic_1.cpp"]
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smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/clients/cl_lidar/components
/cp_lidar_data.h

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/orthogonals/or_obstacle_perception.h

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/sm_ridgeback_floor_coverage
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_coverage_dynamic_1.cpp