smacc::ISmaccComponent

- # stateMachine
- # owner
- + ISmaccComponent()
- + ~ISmaccComponent()
- + getName()
- # initialize()
- # setStateMachine()
- # postEvent()
- # postEvent()
- # onOrthogonalAllocation()
- # requiresComponent()
- # requiresClient()
- # onInitialize()
- # createSiblingComponent()
- # createSiblingNamedComponent()

smacc::ISmaccUpdatable

- periodDuration
- lastUpdate
- + ISmaccUpdatable()
- + ISmaccUpdatable()
- + executeUpdate()
- + setUpdatePeriod()
- # update()

sm fetch robot asynchronous orthogonals::cl move group interface::CpConstraintLateralWorkspace

- planningSceneInterface
- movegroupclient
- referenceFrame lateralDistance
- offset - size
- enabled
- alreadyRemoved
- + enable()
- + disable()
- + CpConstraintLateralWorkspace()
- + onInitialize()
- + update()
- + createCollisionBox()
- + createVirtualCollisionWalls()