

cl_ros_publisher::CbPublish
Once::setMessage



```
graph LR; A[cl_ros_publisher::CbPublishOnce::CbPublishOnce] --> B[cl_ros_publisher::CbPublishOnce::setMessage];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'cl_ros_publisher::CbPublishOnce::setMessage'. The box on the right is white and contains the text 'cl_ros_publisher::CbPublishOnce::CbPublishOnce'. A dark blue arrow points from the right box to the left box, indicating a function call or message passing.

cl_ros_publisher::CbPublish
Once::CbPublishOnce