

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot_2/include/sm_dance_bot_2/stipattern_rotate_1.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot_2/include/sm_dance_bot_2/ss_s_pattern_1.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot_2/sm_dance_bot_2.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp"]
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot\_2/include/sm\_dance\_bot\_2/stipattern\_rotate\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot\_2/include/sm\_dance\_bot\_2/ss\_s\_pattern\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot\_2/sm\_dance\_bot\_2.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot\_2/src/sm\_dance\_bot\_2.cpp