smacc::ISmaccComponent

stateMachine_
serviceName_
owner_

+ ISmaccComponent()
+ ~ISmaccComponent()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
+ configureEventSourceTypes()

cl_move_base_z::Waypoint Navigator

+ waypointsEventDispatcher
+ client_
+ currentWaypoint_
- waypoints_
- succeddedConnection_

+ WaypointNavigator()
+ initialize()
+ insertWaypoint()
+ removeWaypoint()
+ loadWayPointsFromFile()
+ setWaypoints()
+ setWaypoints()
+ sendNextGoal()
+ getWaypoints()
+ getCurrentWaypointIndex()
+ configureEventSourceTypes()
- onGoalReached()