```
+ stateMachine
       + currentState
       + currentOrthogonal
       + SmaccClientBehavior()
       + ~SmaccClientBehavior()
       + getName()
       + onEntry()
       + onExit()
       + postEvent()
       + postEvent()
       + requiresClient()
       + requiresComponent()

    configureEventSourceTypes()

                      multirole_sensor_client
                      ::CbDefaultMultiRoleSensorBehavior
                                 < ClientType >
                      + sensor
                      + deferedEventPropagation
                      + CbDefaultMultiRoleSensor
                      Behavior()
                      + configureEventSourceTypes()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                              < CILaserSensor >
multirole sensor client
::CbDefaultMultiRoleSensorBehavior
        < CILaserSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
      sm dance bot::cl lidar
          ::CbLidarSensor
      + CbLidarSensor()
      + onEntry()
      + onMessageCallback()
```

smacc::SmaccClientBehavior