

```
controller_interface
::MultiInterfaceController
< franka_hw::FrankaPoseCartesian
Interface, franka_hw::FrankaStateInterface >
```



```
franka_example_controllers
::ElbowExampleController
```

- cartesian_pose_interface_
- cartesian_pose_handle_
- elapsed_time_
- initial_pose_
- initial_elbow_

- + init()
- + starting()
- + update()