

fetch_arm::IKFastKinematics
Plugin::getSolution

main

ikfast::IkSolutionList
::GetSolution

```
graph LR; A["fetch_arm::IKFastKinematics  
Plugin::getSolution"] --> C["ikfast::IkSolutionList  
::GetSolution"]; B["main"] --> C;
```

The diagram illustrates a call graph with three nodes. The top-left node, labeled 'fetch_arm::IKFastKinematics Plugin::getSolution', is a white rectangle with a black border. The bottom-left node, labeled 'main', is also a white rectangle with a black border. The right node, labeled 'ikfast::IkSolutionList ::GetSolution', is a gray rectangle with a black border. Two blue arrows point from the right side of the top-left node and the right side of the bottom-left node to the left side of the right node, indicating that both functions call 'ikfast::IkSolutionList ::GetSolution'.