

```
mecanum_drive_controller  
::MecanumDriveController  
::update
```



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::update] --> B[mecanum_drive_controller::Odometry::update];
```

A diagram showing a function call. On the left, a white box with a black border contains the text 'mecanum\_drive\_controller::MecanumDriveController::update'. A blue arrow points from the right side of this box to the left side of a gray box with a black border on the right. The gray box contains the text 'mecanum\_drive\_controller::Odometry::update'.

```
mecanum_drive_controller  
::Odometry::update
```