

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



A diagram showing a call to the `publishGoalMarker` method of the `ForwardLocalPlanner` class. The call is shown in a gray box on the left, with a blue arrow pointing to a white box on the right. The white box contains the same call but with the `optionalRobotPose` parameter added to the `forward` method call.

```
cl_move_base_z::forward  
_local_planner::optionalRobotPose
```