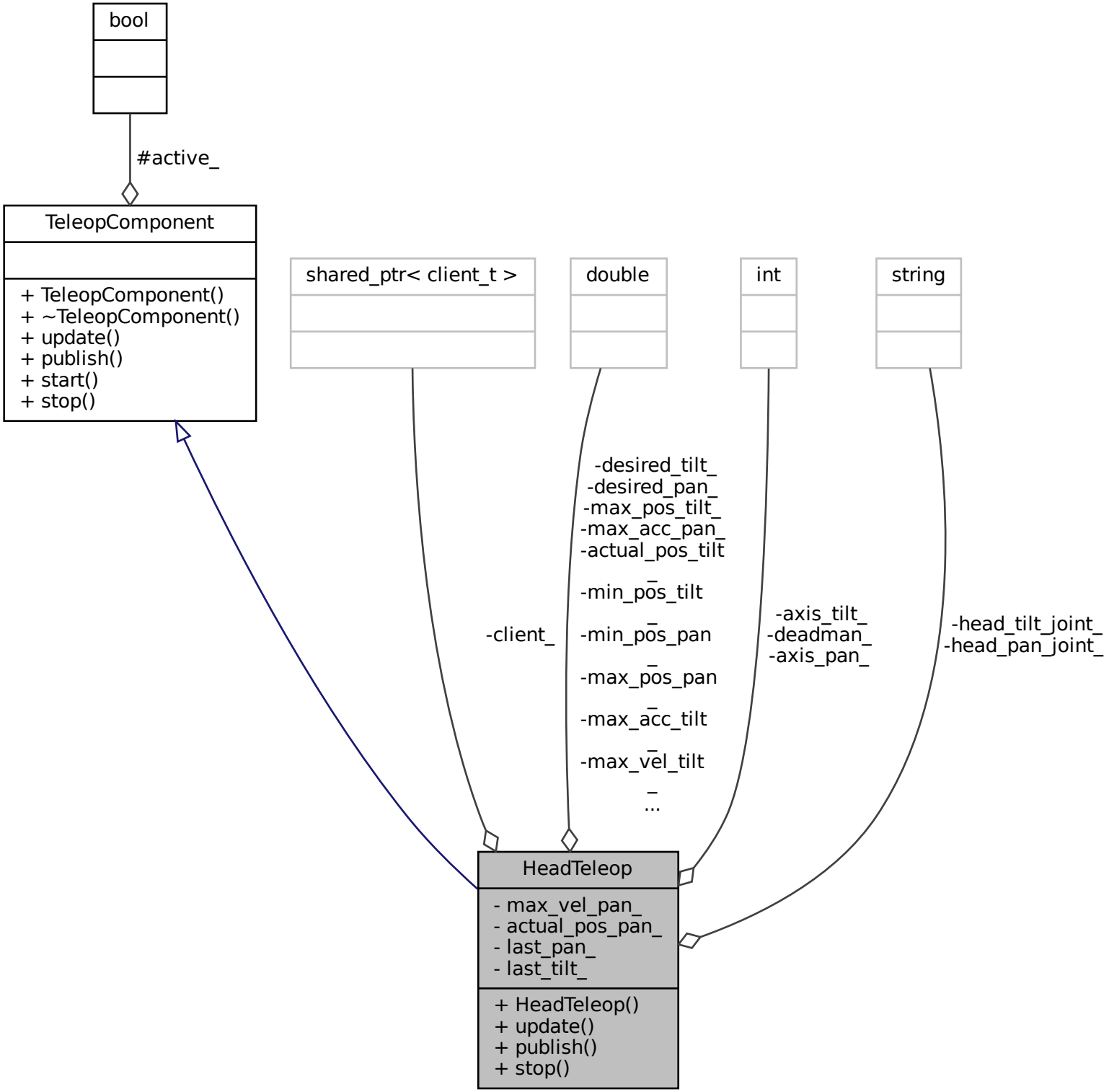
bool
#active_
TeleopComponent
+ TeleopComponent()
+ ~TeleopComponent()
+ update()
+ publish()
+ start()
+ stop()
shared_ptr< client_t >
double
int
string
-client_
-desired_tilt_
-desired_pan_
-max_pos_tilt_
-max_acc_pan_
-actual_pos_tilt_
-min_pos_tilt_
-min_pos_pan_
-max_pos_pan_
-max_acc_tilt_
-max_vel_tilt_
...
-axis_tilt_
-deadman_
-axis_pan_
-head_tilt_joint_
-head_pan_joint_
HeadTeleop
- max_vel_pan_
- actual_pos_pan_
- last_pan_
- last_tilt_
+ HeadTeleop()
+ update()
+ publish()
+ stop()