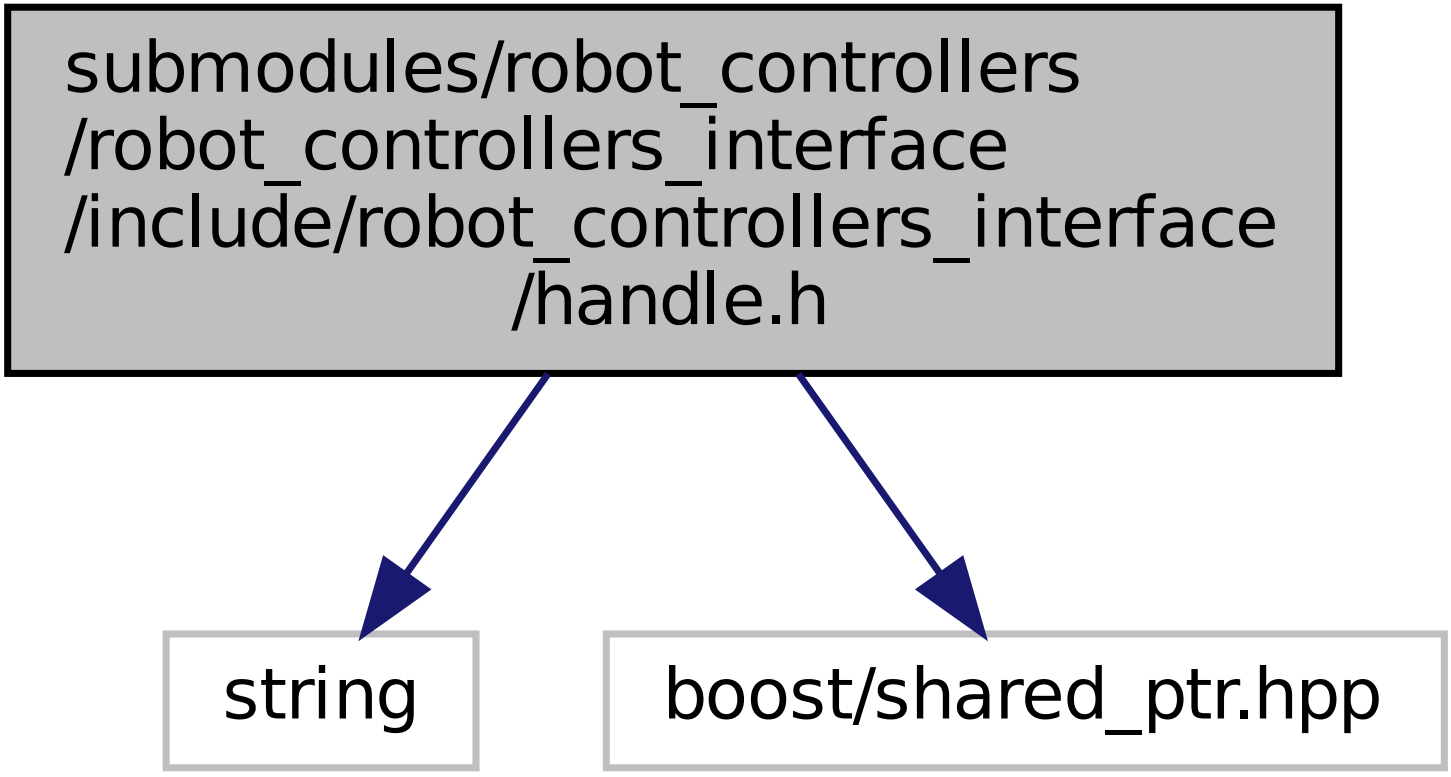
submodules/robot_controllers
/robot_controllers_interface
/include/robot_controllers_interface
/handle.h
string
boost/shared_ptr.hpp