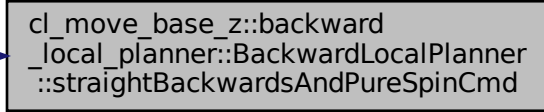


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```

A rectangular box with a black border containing the code snippet above. A blue arrow points from the right side of this box to the left side of the box on the right.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```

A rectangular box with a black border and a light gray fill, containing the code snippet above. A blue arrow points from the left side of this box to the right side of the box on the left.