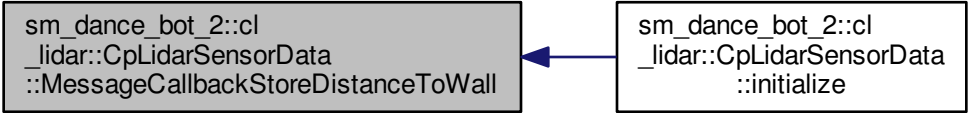


```
sm_dance_bot_2::cl  
_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains three lines of C++ code. The box on the right is white and contains two lines of C++ code. A blue arrow points from the right box to the left box, indicating a function call or message passing.

```
sm_dance_bot_2::cl  
_lidar::CpLidarSensorData  
::initialize
```