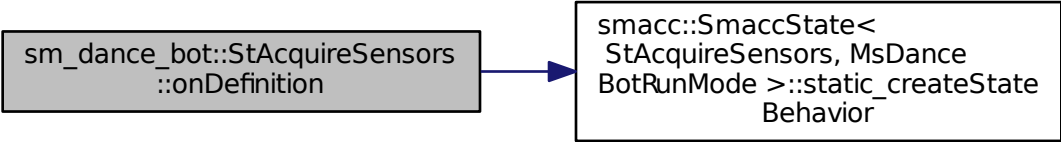


```
sm_dance_bot::StAcquireSensors  
::onDefinition
```



```
graph LR; A[sm_dance_bot::StAcquireSensors::onDefinition] --> B[smacc::SmaccState<StAcquireSensors, MsDanceBotRunMode>::static_createStateBehavior];
```

```
smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Behavior
```