```
smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/orthogonals/or_obstacle
_perception.h
```
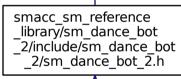
```
smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h
```

```
smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2
/sm_dance_bot_2_node.cpp
```