

tuck_arm.MoveItThread.
__init__

ArmTeleop::update

ArmTeleop::start

```
graph LR; A[tuck_arm.MoveItThread.__init__] --> C[ArmTeleop::start]; B[ArmTeleop::update] --> C;
```

The diagram illustrates a flow or dependency. Two boxes on the left, 'tuck_arm.MoveItThread.__init__' (top) and 'ArmTeleop::update' (bottom), have blue arrows pointing to a single box on the right, 'ArmTeleop::start'. The 'ArmTeleop::start' box is shaded gray, while the others are white with black borders.