

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and contains three lines of C++ code. The right box has a white background and contains two lines of C++ code. The arrow indicates a transition or state change between the two configurations.

```
cl_move_base_z::forward  
_local_planner::optionalRobotPose
```