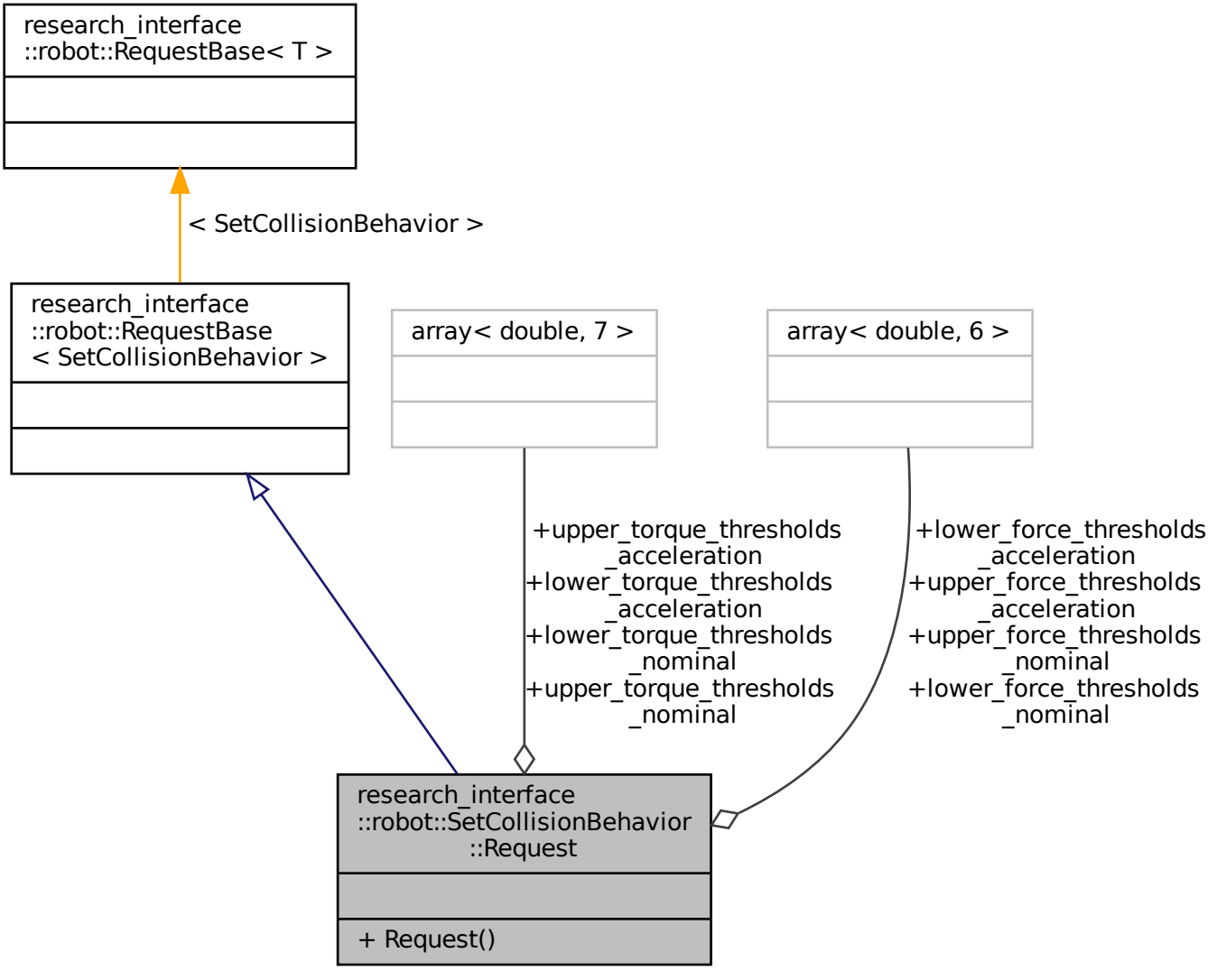
research_interface
::robot::RequestBase< T >
< SetCollisionBehavior >
research_interface
::robot::RequestBase
< SetCollisionBehavior >
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array< double, 6 >
+upper_torque_thresholds
_acceleration
+lower_torque_thresholds
_acceleration
+lower_torque_thresholds
_nominal
+upper_torque_thresholds
_nominal
+lower_force_thresholds
_acceleration
+upper_force_thresholds
_acceleration
+upper_force_thresholds
_nominal
+lower_force_thresholds
_nominal
research_interface
::robot::SetCollisionBehavior
::Request
+ Request()