

submodules/ridgeback
/ridgeback_control/src
/speed_limiter.cpp

```
graph TD; A["submodules/ridgeback<br/>/ridgeback_control/src<br/>/speed_limiter.cpp"] --> B["algorithm"]; A --> C["mecanum_drive_controller<br/>/speed_limiter.h"]
```

algorithm

mecanum_drive_controller
/speed_limiter.h