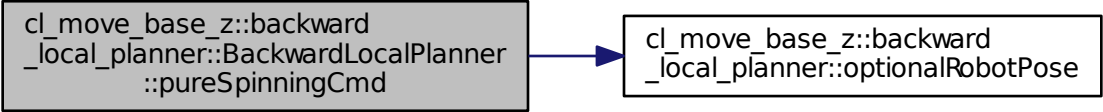


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::pureSpinningCmd
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::pureSpinningCmd"] --> B["cl_move_base_z::backward  
_local_planner::optionalRobotPose"]
```

A diagram showing a transformation from a `BackwardLocalPlanner` command to an `optionalRobotPose` command. A blue arrow points from the left box to the right box.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```