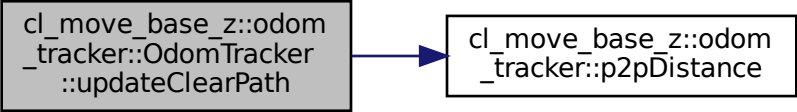


```
cl_move_base_z::odom  
_tracker::OdomTracker  
::updateClearPath
```



```
graph LR; A[cl_move_base_z::odom_tracker::updateClearPath] --> B[cl_move_base_z::odom_tracker::p2pDistance]
```

```
cl_move_base_z::odom  
_tracker::p2pDistance
```