```
cl_ros_timer::CbTimer
                                                    ::onEntry
                                         sm fetch_screw_loop
                                         _1::cl_gripper::CbOpenGripper
                                                    ::onEntry
                                           sm_fetch_six_table
                                           _pick_n_sort_1::cl_gripper
::CbOpenGripper::onEntry
                                       cl_ros_timer::CbTimerCountdown
                                                 Once::onEntry
                                            sm_fetch_two_table
                                            _pick_n_place_1::cl
                                            _gripper::CbOpenGripper
                                                    ::onEntry
                                           sm_fetch_two_table
                                            whiskey pour::cl gripper
                                           ::CbOpenGripper::onEntry
                                         sm_fetch_screw_loop
                                         _1::cl_gripper::CbCloseGripper
                                                    ::onEntry
                                           sm_fetch_two_table
                                            whiskey pour::cl gripper
                                           ::CbCloseGripper::onEntry
                                           sm_fetch_six_table
                                           _pick_n_sort_1::cl_gripper
::CbCloseGripper::onEntry
                                            sm_fetch_two_table
                                            _pick_n_place_1::cl
                                            _gripper::CbCloseGripper
                                                    ::onEntry
                                       cl_ros_timer::CbTimerCountdown
                                                 Loop::onEntry
                                             sm_dance_bot_2::cl
                                             led::CbLEDOn::onEntry
                                             sm dance bot strikes
                                             _back::cl_led::CbLEDOn
                                                    ::onEntry
                                           sm ridgeback floor
                                           _coverage_dynamic_1
                                           ::cl_led::CbLÉDOn::onEntry
                                            sm ridgeback floor
                                            _coverage_static_1::
                                           cl_led::CbLEDOn::onEntry
                                             sm dance bot::cl led
                                               ::CbLEDOn::onEntry
                                             sm dance bot::cl led
                                              ::CbLEDOff::onEntry
                                            sm dance bot 2::cl
                                             led::CbLEDOff::onEntry
                                             sm_dance_bot_strikes
                                             _back::cl_led::CbLEDOff
                                                    ::onEntry
                                           sm_ridgeback_floor
                                           coverage dynamic 1
                                           ::cl_led::CbLÉDOff::onEntry
                                            sm_ridgeback_floor
                                            coverage static 1::
                                           cl_led::CbLEDOff::onEntry
                                        cl_keyboard::CbDefaultKeyboard
                                               Behavior::onEntry
                                         cl_move_group_interface
                                         ::CbMoveEndEffectorTrajectory
                                                    ::onEntry
                                           cl move group interface
                                           ::CbDetachObject::onEntry
smacc::ISmaccClientBehavior
                                         cl_move_base_z::CbNavigate
       ::requiresClient
                                             NextWaypoint::onEntry
                                           cl move group interface
                                           ::CbExecuteLastTrajectory
                                                    ::onEntry
                                           cl move group interface
                                           ::CbAttachObject::onEntry
                                            cl_move_group_interface
                                            ::CbUndoLastTrajectory
                                                    ::onEntry
                                          sm_dance_bot_strikes
                                           _back::cl_string_publisher
                                          ::CbStringPublisher::onEntry
                                           sm_ridgeback_floor
                                                                                     cl_move_group_interface
                                           _coverage_static_1::
                                                                                     ::CbEndEffectorRotate
                                           cl_string_publisher::
                                           CbStringPublisher::onEntry
                                                                                             ::onEntry
                                          sm dance bot::cl string
                                          _publisher::CbStringPublisher
                                                    ::onEntry
                                           sm_dance_bot_2::cl
                                           _string_publisher::CbString
                                               Publisher::onEntry
                                          sm_ridgeback_floor
                                           _coverage_dynamic_1
                                          ::cl_string_publisher
                                          ::CbStringPublisher::onEntry
                                         cl_move_base_z::CbUndoPath
                                              Backwards::onEntry
                                         cl move group interface
                                         ::CbMoveEndEffector::onEntry
                                          cl_move_group_interface
::CbMoveEndEffectorRelative
                                                    ::onEntry
                                        cl_move_group_interface
                                         :: CbMoveNamedTarget::onEntry
                                           cl_move_group_interface
                                           ::CbMoveCartesianRelative
                                                    ::onEntry
                                           cl_move_base_z::CbRotate
                                                    ::onEntry
                                          cl\_move\_base\_z::CbAbsolute
                                                 Rotate::onEntry
                                           cl_ros_publisher::CbPublish
                                                 Once::onEntry
                                          cl_move_base_z::CbNavigate
                                             Global Position::on Entry
                                          cl_move_base_z::CbNavigate
                                              Backwards::onEntry
                                          cl_ros_publisher::CbDefault
                                              PublishLoop::onEntry
                                          cl_move_base_z::CbNavigate
                                                Forward::onEntry
                                       cl_multirole_sensor
                                        ::CbDefaultMultiRoleSensor
                                        Behavior < sm_dance_bot_strikes
                                        _back::cl_lidar::ClLidarSensor
                                                   >::onEntry
                                                                                   cl_move_group_interface
                                           cl_move_group_interface
                                                                                    ::CbMoveLast Irajectoryinitiai
                                             ::CbMoveJoints::onEntry
                                                                                           State::onEntry
                                         cl move base z::CbUndoPath
                                               Backwards::onExit
```