

```
graph BT; A["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/src/sm_ridgeback_floor  
_coverage_dynamic_1.cpp"] --> B["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/sm_ridgeback_floor_coverage  
_dynamic_1.h"]; B --> C["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/include/sm_ridgeback  
_floor_coverage_dynamic_1  
/orthogonals/or_obstacle_perception.h"]; C --> D["smacc_sm_reference  
_library/sm_ridgeback  
_floor_coverage_dynamic  
_1/include/sm_ridgeback  
_floor_coverage_dynamic_1  
/clients/cl_lidar/components  
/cp_lidar_data.h"];
```

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/clients/cl_lidar/components
/cp_lidar_data.h

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/sm_ridgeback_floor_coverage
_dynamic_1.h

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