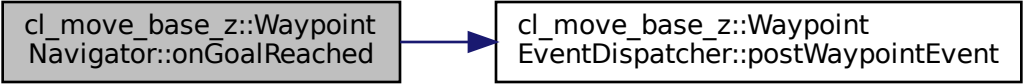


cl\_move\_base\_z::Waypoint  
Navigator::onGoalReached



```
graph LR; A["cl_move_base_z::Waypoint  
Navigator::onGoalReached"] --> B["cl_move_base_z::Waypoint  
EventDispatcher::postWaypointEvent"]
```

cl\_move\_base\_z::Waypoint  
EventDispatcher::postWaypointEvent