```
smacc::ISmaccClientBehavior

    stateMachine

  currentState

    currentOrthogonal

  + ISmaccClientBehavior()
     -ISmaccClientBehavior()
  + getStateMachine()
  + getName()
  + requiresClient()
  + requiresComponent()
  # runtimeConfigure()
  # onEntry()
  # onExit()
  # postEvent()
# postEvent()
  # getCurrentState()
  # executeOnEntry()
  # executeOnExit()
  # dispose()
  onOrthogonalAllocation()
                Δ
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                      cl multirole sensor
                      :: C
b
D
e
f
a
u
l
t
i
R
o
l
e
S
e
n
s
o
r
                        Behavior < ClientType >
                      + sensor
                      + deferedEventPropagation
                      + CbDefaultMultiRoleSensor
                      Behavior()
                      + onOrthogonalAllocation()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                            < ClTemperatureSensor >
  _multirole_sensor
:CbDefaultMultiRoleSensor
Behavior < CITemperatureSensor >
+ sensor
+ deferedEventPropagation

    CbDefaultMultiRoleSensor

Behavior()
+ onOrthogonalAllocation()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
                Δ
sm_dance_bot_2::cl
temperature
              sensor
 ::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```