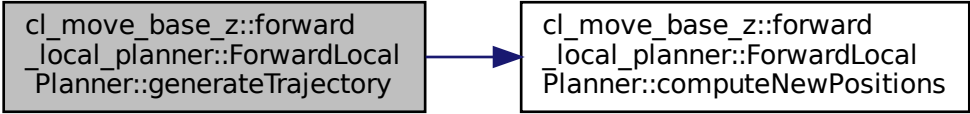


cl\_move\_base\_z::forward  
\_local\_planner::ForwardLocal  
Planner::generateTrajectory



cl\_move\_base\_z::forward  
\_local\_planner::ForwardLocal  
Planner::computeNewPositions