


```
cl_move_base_z::pure  
_spinning_local_planner  
::optionalRobotPose
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from right to left. The left box is shaded gray and contains the text 'cl_move_base_z::pure', '_spinning_local_planner', and '::optionalRobotPose'. The right box is white with a black border and contains the text 'cl_move_base_z::pure', '_spinning_local_planner', '::PureSpinningLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from the right box to the left box, indicating a call to the 'computeVelocityCommands' method.

```
cl_move_base_z::pure  
_spinning_local_planner  
::PureSpinningLocalPlanner  
::computeVelocityCommands
```