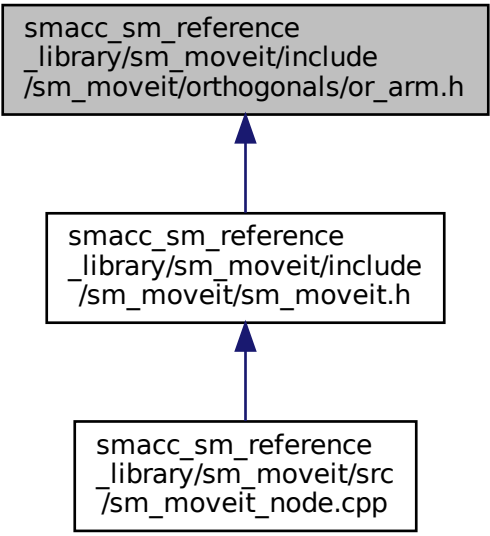


smacc_sm_reference
_library/sm_moveit/include
_sm_moveit/orthogonals/or_arm.h



```
graph BT; A["smacc_sm_reference_library/sm_moveit/src_sm_moveit_node.cpp"] --> B["smacc_sm_reference_library/sm_moveit/include_sm_moveit_sm_moveit.h"]; B --> C["smacc_sm_reference_library/sm_moveit/include_sm_moveit_orthogonals/or_arm.h"];
```

The diagram illustrates a dependency chain between three files. At the bottom is a box containing the C++ source file path. An upward-pointing blue arrow connects it to a middle box containing a header file path. Another upward-pointing blue arrow connects the middle box to the top box, which contains another header file path. The top box has a light gray background, while the others are white.

smacc_sm_reference
_library/sm_moveit/include
_sm_moveit/sm_moveit.h

smacc_sm_reference
_library/sm_moveit/src
_sm_moveit_node.cpp