```
smacc::ISmaccClientBehavior
stateMachine_

    currentState

- currentOrthogonal
+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
configureEventSourceTypes()
smacc::SmaccClientBehavior
+ onEntry()
 + onExit()
              Δ
                   cl multirole sensor
                   ::CbDefaultMultiRoleSensor
                       Behavior < ClientType >
                   + sensor
                   + deferedEventPropagation
                   + CbDefaultMultiRoleSensor
                   Behavior()
                   + configureEventSourceTypes()
                   + propagateEvent()
                   + propagateEvent2()
                   + onEntry()
                   + onExit()
                   + onMessageCallback()
                   + getEventLabel()
                         < ClLidarSensor >
  multirole sensor
:: CbDefault MultiRole Sensor
  Behavior < ClLidar Sensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
   sm_dance_bot::cl lidar
        ::CbLidarSensor
    + CbLidarSensor()
    + onEntry()
    + onMessageCallback()
```