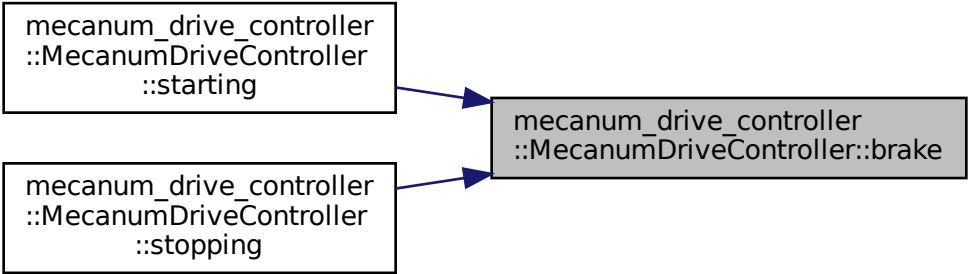


mecanum\_drive\_controller  
::MecanumDriveController  
::starting

mecanum\_drive\_controller  
::MecanumDriveController  
::stopping

mecanum\_drive\_controller  
::MecanumDriveController::brake



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::starting] --> C[mecanum_drive_controller::MecanumDriveController::brake]; B[mecanum_drive_controller::MecanumDriveController::stopping] --> C;
```