

mecanum\_drive\_controller  
::MecanumDriveController::init



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::init] --> B[mecanum_drive_controller::MecanumDriveController::cmdVelCallback];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'mecanum\_drive\_controller' followed by '::MecanumDriveController::init' on the next line. The right box is gray with a black border and contains the text 'mecanum\_drive\_controller' followed by '::MecanumDriveController' on the next line, and '::cmdVelCallback' on the third line.

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::MecanumDriveController  
::cmdVelCallback