

tuck_arm.MoveItThread.
__init__

ArmTeleop::update

ArmTeleop::start

```
graph LR; A[tuck_arm.MoveItThread.__init__] --> C[ArmTeleop::start]; B[ArmTeleop::update] --> C;
```

The diagram illustrates a flow or dependency where two functions, `tuck_arm.MoveItThread.__init__` and `ArmTeleop::update`, both point to the `ArmTeleop::start` function. The boxes for the source functions are white with black borders, while the target box is gray with a black border. Blue arrows indicate the direction of the flow from left to right.