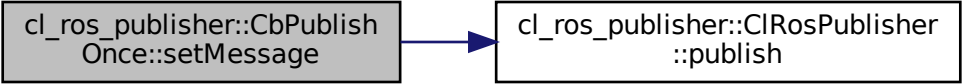


cl_ros_publisher::CbPublish
Once::setMessage



```
graph LR; A[cl_ros_publisher::CbPublishOnce::setMessage] --> B[cl_ros_publisher::ClRosPublisher::publish]
```

cl_ros_publisher::ClRosPublisher
::publish