

nav_core::BaseGlobalPlanner



cl_move_base_z::undo
_path_global_planner
::UndoPathGlobalPlanner

- nh_
- forwardPathSub_
- planPub_
- markersPub_
- lastForwardPathMsg_
- costmap_ros_
- cmd_server_
- skip_straight_motion
_distance
- puresSpinningRadStep_

- + UndoPathGlobalPlanner()
- + ~UndoPathGlobalPlanner()
- + makePlan()
- + makePlan()
- + createDefaultUndoPathPlan()
- + initialize()
- onForwardTrailMsg()
- publishGoalMarker()