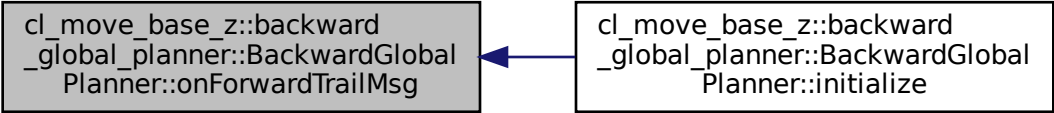


```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::onForwardTrailMsg
```

A blue arrow points from the 'initialize' method in the right box to the 'onForwardTrailMsg' method in the left box.

```
cl_move_base_z::backward  
_global_planner::BackwardGlobal  
Planner::initialize
```