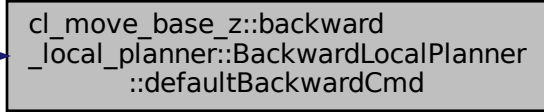


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```

A rectangular box with a black border containing the text of a function call. The text is left-aligned and consists of three lines: 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::computeVelocityCommands'.

```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd"]
```

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd
```

A rectangular box with a black border and a light gray fill, containing the text of a function call. The text is left-aligned and consists of three lines: 'cl_move_base_z::backward', '_local_planner::BackwardLocalPlanner', and '::defaultBackwardCmd'. A blue arrow points from the left box to this box.

```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::defaultBackwardCmd"]
```