

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call to the `computeVelocityCommands` method of the `BackwardLocalPlanner` class. The call is shown in a white box on the left. A blue arrow points from this box to a gray box on the right, which shows the same call but with the `straightBackwardsAndPureSpinCmd` method called on the `_local_planner` object.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::straightBackwardsAndPureSpinCmd
```