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graph BT; A["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/src/sm_ridgeback_floor_coverage_dynamic_1.cpp"] --> B["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/sm_ridgeback_floor_coverage_dynamic_1.h"]; B --> C["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/include/sm_ridgeback_floor_coverage_dynamic_1/orthogonals/or_obstacle_perception.h"]; C --> D["smacc_sm_reference_library/sm_ridgeback_floor_coverage_dynamic_1/include/sm_ridgeback_floor_coverage_dynamic_1/clients/cl_lidar/components/cp_lidar_data.h"]
```

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/clients/cl_lidar/components
/cp_lidar_data.h

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/orthogonals/or_obstacle_perception.h

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/include/sm_ridgeback
_floor_coverage_dynamic_1
/sm_ridgeback_floor_coverage
_dynamic_1.h

smacc_sm_reference
_library/sm_ridgeback
_floor_coverage_dynamic
_1/src/sm_ridgeback_floor
_coverage_dynamic_1.cpp