smacc::ISmaccClientBehavior

- stateMachine_
- currentState
- currentOrthogonal

+ ISmaccClientBehavior()
+ ~ISmaccClientBehavior()
+ getStateMachine()
+ getName()
+ requiresClient()
+ requiresComponent()
# runtimeConfigure()
# onEntry()
# onExit()
# postEvent()
# postEvent()
# getCurrentState()
# executeOnEntry()
# executeOnExit()
- configureEventSourceTypes()

smacc::SmaccClientBehavior

+ onEntry()
+ onExit()

cl_multirole_sensor ::CbDefaultMultiRoleSensor Behavior< ClientType >

+ sensor_
+ deferedEventPropagation

+ CbDefaultMultiRoleSensor Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()

< ClLidarSensor >

cl_multirole_sensor ::CbDefaultMultiRoleSensor Behavior< ClLidarSensor >

+ sensor_
+ deferedEventPropagation

+ CbDefaultMultiRoleSensor Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()

sm_dance_bot_2::cl _lidar::CbLidarSensor

+ CbLidarSensor()
+ onEntry()
+ onMessageCallback()