```
move_base_z_client
::forward_local_planner
::ForwardLocalPlanner::
computeNewPositions
```

```
move_base_z_client
::forward_local_planner
::ForwardLocalPlanner::
generateTrajectory
```

```
move_base_z_client
::forward_local_planner
::ForwardLocalPlanner::
computeVelocityCommands
```