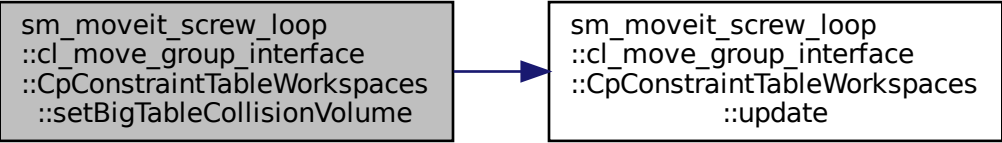


```
sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintTableWorkspaces  
  ::setBigTableCollisionVolume
```



```
graph LR; A["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintTableWorkspaces  
  ::setBigTableCollisionVolume"] --> B["sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintTableWorkspaces  
  ::update"]
```

```
sm_moveit_screw_loop  
::cl_move_group_interface  
::CpConstraintTableWorkspaces  
  ::update
```