

cl_ros_timer::CbTimer
::configureEventSourceTypes



```
graph LR; A["cl_ros_timer::CbTimer  
::configureEventSourceTypes"] --> B["cl_ros_timer::CbTimer  
::onClientTimerTickCallback"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'cl_ros_timer::CbTimer' followed by '::configureEventSourceTypes' on the next line. The right box is white and contains the text 'cl_ros_timer::CbTimer' followed by '::onClientTimerTickCallback' on the next line. A dark blue arrow points from the right side of the left box to the left side of the right box.

cl_ros_timer::CbTimer
::onClientTimerTickCallback