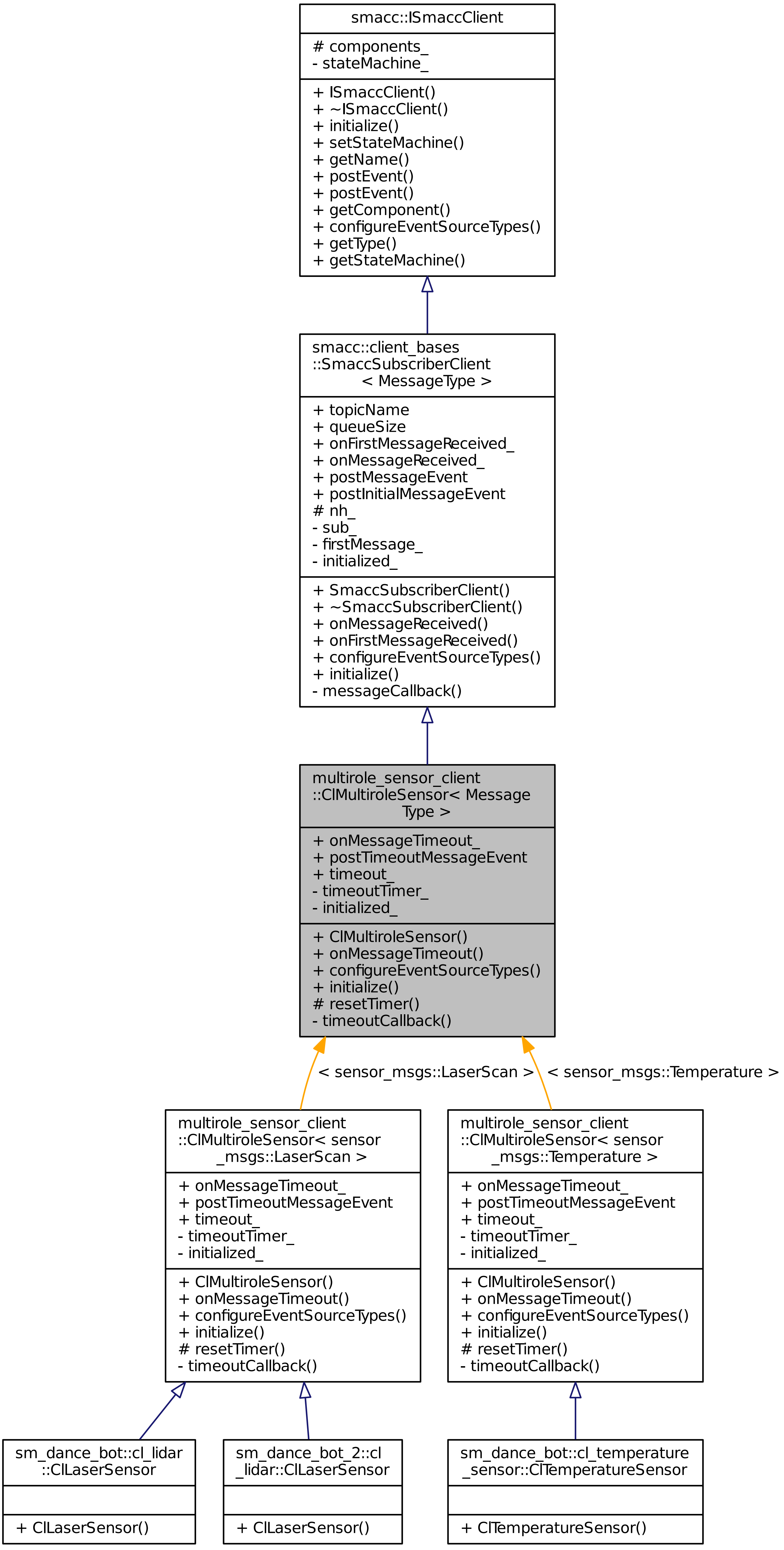
smacc::ISmaccClient
# components_
- stateMachine_
+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ setStateMachine()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ configureEventSourceTypes()
+ getType()
+ getStateMachine()
smacc::client_bases ::SmaccSubscriberClient < MessageType >
+ topicName
+ queueSize
+ onFirstMessageReceived_
+ onMessageReceived_
+ postMessageEvent
+ postInitialMessageEvent
# nh_
- sub_
- firstMessage_
- initialized_
+ SmaccSubscriberClient()
+ ~SmaccSubscriberClient()
+ onMessageReceived()
+ onFirstMessageReceived()
+ configureEventSourceTypes()
+ initialize()
- messageCallback()
multirole_sensor_client ::ClMultiroleSensor< Message Type >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ configureEventSourceTypes()
+ initialize()
# resetTimer()
- timeoutCallback()
< sensor_msgs::LaserScan >
< sensor_msgs::Temperature >
multirole_sensor_client ::ClMultiroleSensor< sensor _msgs::LaserScan >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ configureEventSourceTypes()
+ initialize()
# resetTimer()
- timeoutCallback()
multirole_sensor_client ::ClMultiroleSensor< sensor _msgs::Temperature >
+ onMessageTimeout_
+ postTimeoutMessageEvent
+ timeout_
- timeoutTimer_
- initialized_
+ ClMultiroleSensor()
+ onMessageTimeout()
+ configureEventSourceTypes()
+ initialize()
# resetTimer()
- timeoutCallback()
sm_dance_bot::cl_lidar ::ClLaserSensor
+ ClLaserSensor()
sm_dance_bot_2::cl _lidar::ClLaserSensor
+ ClLaserSensor()
sm_dance_bot::cl_temperature _sensor::ClTemperatureSensor
+ ClTemperatureSensor()