

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::generateTrajectory
```

A blue arrow points from the right box to the left box, indicating a function call from computeVelocityCommands to generateTrajectory.

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands
```