

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands"] --> B["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"]
```

A diagram showing a call sequence between two functions. On the right is a white box containing the code for `cl_move_base_z::forward`, which calls `_local_planner::ForwardLocalPlanner::computeVelocityCommands`. A blue arrow points from this box to a gray box on the left, which contains the code for `cl_move_base_z::forward` calling `_local_planner::ForwardLocalPlanner::publishGoalMarker`.

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands
```