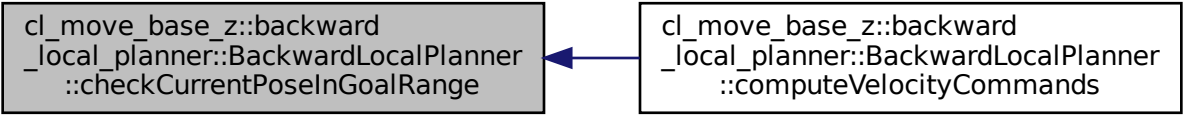


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::checkCurrentPoseInGoalRange
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::checkCurrentPoseInGoalRange'. The box on the right is white and contains the text 'cl\_move\_base\_z::backward', '\_local\_planner::BackwardLocalPlanner', and '::computeVelocityCommands'. A blue arrow points from the right box to the left box, indicating a function call.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```