

```
sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::CIPerception  
System::update
```



```
graph LR; A["sm_fetch_two_table  
_pick_n_place_1::cl  
_perception_system::CIPerception  
System::update"] --> B["cl_move_base_z::Pose  
::toPoseStampedMsg"]
```

```
cl_move_base_z::Pose  
::toPoseStampedMsg
```