

```
sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure
```



```
graph LR; A["sm_dance_bot_strikes  
_back::StAcquireSensors  
::staticConfigure"] --> B["smacc::SmaccState<  
StAcquireSensors, MsDance  
BotRunMode >::static_createState  
Reactor"]
```

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smacc::SmaccState<  
StAcquireSensors, MsDance  
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