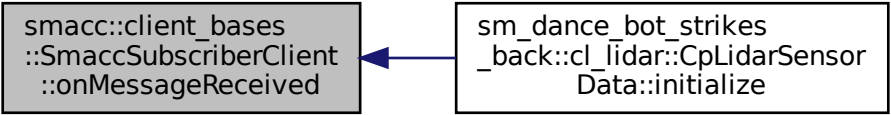


```
smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived
```



```
graph LR; A["sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize"] --> B["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"]
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'smacc::client\_bases', '::SmaccSubscriberClient', and '::onMessageReceived' stacked vertically. The box on the right is white and contains the text 'sm\_dance\_bot\_strikes', '\_back::cl\_lidar::CpLidarSensor', and 'Data::initialize' stacked vertically. A blue arrow points from the right box to the left box, indicating a function call or message passing.

```
sm_dance_bot_strikes  
_back::cl_lidar::CpLidarSensor  
Data::initialize
```