

mecanum\_drive\_controller  
::MecanumDriveController  
::starting

mecanum\_drive\_controller  
::MecanumDriveController  
::stopping

mecanum\_drive\_controller  
::MecanumDriveController::brake

```
graph LR; A["mecanum_drive_controller  
::MecanumDriveController  
::starting"] --> C["mecanum_drive_controller  
::MecanumDriveController::brake"]; B["mecanum_drive_controller  
::MecanumDriveController  
::stopping"] --> C;
```

The diagram illustrates a state transition for a MecanumDriveController. On the left, there are two white rectangular boxes representing initial states: 'mecanum\_drive\_controller ::MecanumDriveController ::starting' and 'mecanum\_drive\_controller ::MecanumDriveController ::stopping'. Blue arrows point from each of these boxes to a single gray rectangular box on the right, which represents the target state: 'mecanum\_drive\_controller ::MecanumDriveController::brake'.