```
smacc::SmaccClientBehavior
+ stateMachine
+ currentState
+ currentOrthogonal
+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getName()
+ onEntry()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
configureEventSourceTypes()
```

ros_publisher_client ::CbMutedBehavior< RosMsgType > + onEntry()

+ onExit()