

tuck_arm.MoveItThread.
__init__

ArmTeleop::update

ArmTeleop::start

```
graph LR; A[tuck_arm.MoveItThread.__init__] --> C[ArmTeleop::start]; B[ArmTeleop::update] --> C;
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The diagram illustrates a flow or dependency where two functions, 'tuck_arm.MoveItThread.__init__' and 'ArmTeleop::update', both point to a central function 'ArmTeleop::start'. The boxes for the source functions are white with black borders, while the target box is gray with a black border. Blue arrows indicate the direction of the flow from left to right.