```
smacc::ISmaccClientBehavior

    stateMachine

    currentState

 - currentOrthogonal
 + ISmaccClientBehavior()
 + ~ISmaccClientBehavior()
 + getStateMachine()
 + getName()
 + requiresClient()
+ requiresComponent()
 # runtimeConfigure()
 # onEntry()
 # onExit()
 # postEvent()
 # postEvent()
 # getCurrentState()
 # executeOnEntry()
 # executeOnExit()
  configureEventSourceTypes()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                Д
                     cl multirole sensor
                     :: CbDefaultMultiRoleSensor
                         Behavior < ClientType >
                      + sensor
                      + deferedEventPropagation
                      + CbDefaultMultiRoleSensor
                      Behavior()
                      + configureEventSourceTypes()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                            < ClTemperatureSensor >
  multirole sensor
::CbDefaultMultiRoleSensor
Behavior < ClTemperatureSensor >
+ sensor
+ deferedEventPropagation
+ CbDefaultMultiRoleSensor
Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
sm_dance_bot_2::cl
_temperature_sensor
 ::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```