```
smacc::ISmaccComponent
# stateMachine
# owner
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# initialize()
# setStateMachine()
# postEvent()
# postEvent()
# configureEventSourceTypes()
# requiresComponent()
# requiresClient()
# onInitialize()
# createSiblingComponent()
# createSiblingNamedComponent()
```

sm_ridgeback_floor _coverage_dynamic_1 ::cl_lidar::CpLidarSensorData

+ lastMessage_ + forwardObstacleDistance

+ SECURITY DISTANCE

+ onInitialize()

+ MessageCallbackStoreDistance ToWall()