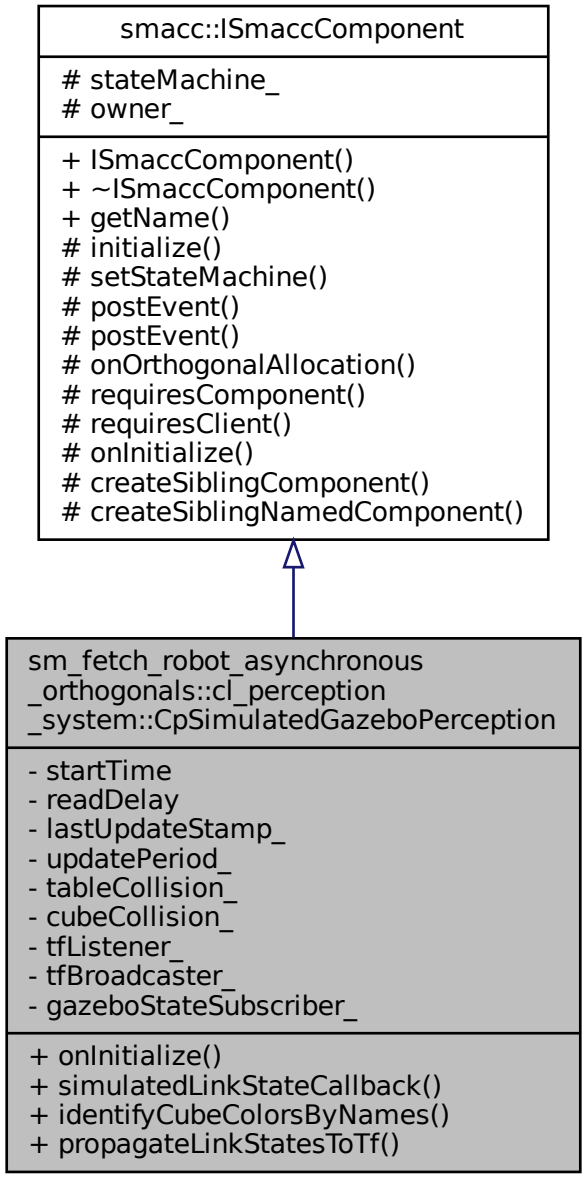
smacc::ISmaccComponent
stateMachine_
owner_
+ ISmaccComponent()
+ ~ISmaccComponent()
+ getName()
# initialize()
# setStateMachine()
# postEvent()
# postEvent()
# onOrthogonalAllocation()
# requiresComponent()
# requiresClient()
# onInitialize()
# createSiblingComponent()
# createSiblingNamedComponent()
sm_fetch_robot_asynchronous
_orthogonals::cl_perception
_system::CpSimulatedGazeboPerception
- startTime
- readDelay
- lastUpdateStamp_
- updatePeriod_
- tableCollision_
- cubeCollision_
- tfListener_
- tfBroadcaster_
- gazeboStateSubscriber_
+ onInitialize()
+ simulatedLinkStateCallback()
+ identifyCubeColorsByNames()
+ propagateLinkStatesToTf()