

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



A diagram showing a call from the `computeVelocityCommands` method to the `publishGoalMarker` method. A blue arrow points from the right box to the left box.

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::computeVelocityCommands
```