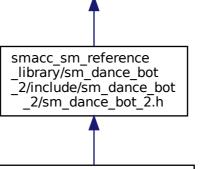
```
smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_run
_mode/st_navigate_to_waypoints_x.h
```



\_library/sm\_dance\_bot \_2/src/sm\_dance\_bot\_2.cpp

smacc\_sm\_reference