

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_2/include/sm_dance_bot  
_2/orthogonals/or_navigation.h"] <-- B["smacc_sm_reference  
_library/sm_dance_bot  
_2/include/sm_dance_bot  
_2/sm_dance_bot_2.h"]; B <-- C["smacc_sm_reference  
_library/sm_dance_bot  
_2/src/sm_dance_bot_2.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/orthogonals/or_navigation.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2.cpp