

```
move_base_z_client  
::CbNavigateGlobalPosition  
::readStartPoseFromParameterServer
```



```
graph LR; A["move_base_z_client  
::CbNavigateGlobalPosition  
::readStartPoseFromParameterServer"] --> B["smacc::ISmaccState  
::getParam"]
```

A diagram showing a call from the `move_base_z_client` to the `smacc::ISmaccState::getParam` method. The call is represented by a blue arrow pointing from the left box to the right box.

```
smacc::ISmaccState  
::getParam
```