

boost::statechart::
event< EvWaypoint211
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint211< TSource, TOrthogonal > >"]
    class cl_move_base_z_EvWaypoint211["cl_move_base_z::EvWaypoint211< TSource, TOrthogonal >"]
    cl_move_base_z_EvWaypoint211 --|> boost_statechart_event
```

The diagram illustrates an inheritance relationship. A blue arrow with an open triangular head points from the bottom class to the top class. The top class is defined in a white box with a thin grey border, and the bottom class is defined in a grey box with a thick black border. Both boxes are divided into three horizontal sections. The top section of the white box contains the class name, while the other two sections are empty. The top section of the grey box contains the class name, the second section contains the public member variable '+ waypointIndex', and the third section is empty.

cl_move_base_z::EvWaypoint211
< TSource, TOrthogonal >

+ waypointIndex