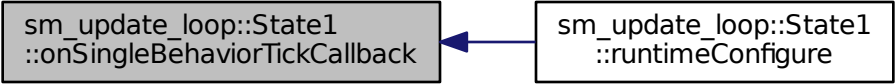


sm_update_loop::State1
::onSingleBehaviorTickCallback



```
graph LR; A[sm_update_loop::State1::runtimeConfigure] --> B[sm_update_loop::State1::onSingleBehaviorTickCallback];
```

The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'sm_update_loop::State1::onSingleBehaviorTickCallback'. The box on the right is white and contains the text 'sm_update_loop::State1::runtimeConfigure'. A dark blue arrow points from the right box to the left box, indicating a call or relationship between the two.

sm_update_loop::State1
::runtimeConfigure