

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
/src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
/include/sm_dance_bot  
/states/ms_dance_bot_run  
_mode/radial_motion_states  
/ss_radial_pattern_3.h"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/states/ms\_dance\_bot\_run  
\_mode/radial\_motion\_states  
/ss\_radial\_pattern\_3.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/include/sm\_dance\_bot  
/sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
/src/sm\_dance\_bot.cpp