

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call sequence between two functions. A blue arrow points from the `computeVelocityCommands` function in the left box to the `updateCarrotGoal` function in the right box. The right box has a light gray background.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::updateCarrotGoal
```