

tuck_arm.MoveItThread.
__init__

FollowTeleop::update

HeadTeleop::update

TeleopComponent::start

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graph LR; A[tuck_arm.MoveItThread.__init__] --> D[TeleopComponent::start]; B[FollowTeleop::update] --> D; C[HeadTeleop::update] --> D;
```

The diagram illustrates a dependency or call relationship. Three source functions on the left are connected by blue arrows to a single target function on the right. The target function, 'TeleopComponent::start', is highlighted with a gray background, while the source functions have white backgrounds. The arrows originate from the right side of each source box and point towards the left side of the target box.