```
robot controllers::
     .
Handle
                         string
+ Handle()
+ ~Handle()
+ getName()
- Handle()
operator=()
                         -name
     robot_controllers::
             Controller
     + Controller()
     + ~Controller()
     + init()
     + start()
     + stop()
     + reset()
     + update()
     + getName()
     + getType()
     + getCommandedNames()
     + getClaimedNames()
```