

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_superstates/ss_radial  
_pattern_3.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"]
```

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_superstates/ss_radial
_pattern_3.h

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
_src/sm_dance_bot.cpp