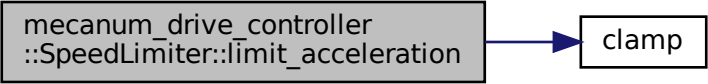


```
mecanum_drive_controller  
::SpeedLimiter::limit_acceleration
```



A diagram illustrating a function call. On the left, a gray rectangular box contains the text `mecanum_drive_controller::SpeedLimiter::limit_acceleration`. A dark blue arrow points from the right side of this box to a white rectangular box on the right, which contains the text `clamp`.

```
clamp
```