

```
mecanum_drive_controller  
::MecanumDriveController  
::update
```



```
graph LR; A[mecanum_drive_controller::MecanumDriveController::update] --> B[mecanum_drive_controller::SpeedLimiter::limit];
```

A diagram showing a call from the `mecanum_drive_controller::MecanumDriveController::update` method to the `mecanum_drive_controller::SpeedLimiter::limit` method. The source box is white with a black border, and the target box is gray with a black border. A blue arrow points from the source to the target.

```
mecanum_drive_controller  
::SpeedLimiter::limit
```