## smacc::ISmaccClientBehavior smacc::SmaccClientBehavior stateMachine - currentState - currentOrthogonal smacc::ISmaccUpdatable + SmaccClientBehavior() periodDuration + ~SmaccClientBehavior() lastUpdate + getStateMachine() + getName() + ISmaccUpdatable() + runtimeConfigure() + ISmaccUpdatable() + onEntry() + executeUpdate() + onExit() + setUpdatePeriod() + postEvent() # update() + postEvent() + requiresClient() + requiresComponent() + getCurrentState() configureEventSourceTypes() cl ros publisher::CbDefault PublishLoop - deferedPublishFn - client + CbDefaultPublishLoop() + CbDefaultPublishLoop() + setMessage() + onEntry() + update() + onExit()