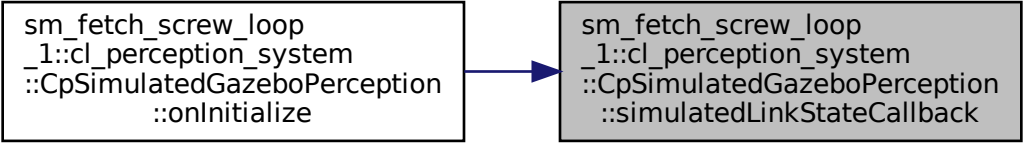


```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::onInitialize
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box is white with a black border and contains four lines of C++ code. The right box is light gray with a black border and contains four lines of C++ code. The arrow originates from the right side of the first box and points to the left side of the second box.

```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::simulatedLinkStateCallback
```