smacc::SmaccClientBehavior - stateMachine - currentState currentOrthogonal + SmaccClientBehavior() + ~SmaccClientBehavior() + getStateMachine() + getName() + runtimeConfigure() + onEntry() + onExit() + postEvent() + postEvent() + requiresClient() + requiresComponent() + getCurrentState() configureEventSourceTypes() multirole sensor :: CbDefault MultiRole Sensor Behavior < ClientType > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() < ClTemperatureSensor > cl multirole sensor ::CbDefaultMultiRoleSensor Behavior < ClTemperatureSensor > + sensor + deferedEventPropagation + CbDefaultMultiRoleSensor Behavior() + configureEventSourceTypes() + propagateEvent() + propagateEvent2() + onEntry() + onExit() + onMessageCallback() + getEventLabel() sm dance bot 2::cl temperature_sensor ::CbConditionTemperatureSensor + CbConditionTemperatureSensor() + onMessageCallback()