

```
graph BT; A["smacc_sm_reference  
library/sm_moveit_3  
/include/sm_moveit_3  
/states/pick_states/st  
_close_gripper.h"] --> B["smacc_sm_reference  
library/sm_moveit_3  
/include/sm_moveit_3  
/superstates/ss_pick_object.h"]; B --> C["smacc_sm_reference  
library/sm_moveit_3  
/include/sm_moveit_3  
/sm_moveit_3.h"]; C --> D["smacc_sm_reference  
library/sm_moveit_3  
/src/sm_moveit_3_node.cpp"];
```

smacc\_sm\_reference  
library/sm\_moveit\_3  
/include/sm\_moveit\_3  
/states/pick\_states/st  
\_close\_gripper.h

smacc\_sm\_reference  
library/sm\_moveit\_3  
/include/sm\_moveit\_3  
/superstates/ss\_pick\_object.h

smacc\_sm\_reference  
library/sm\_moveit\_3  
/include/sm\_moveit\_3  
/sm\_moveit\_3.h

smacc\_sm\_reference  
library/sm\_moveit\_3  
/src/sm\_moveit\_3\_node.cpp