```
fake cube perception
 node.FakePerceptionNode
+ planning scene
+ tf_broacaster
+ tf listener
+ pub
+ update planning scene
+ last update
+ update period
+ table collision
+ cube collision
+ init ()
+ update()
+ simulated link state
callback()
+ propagate link states
to tf()
+ init ()
+ update()
+ simulated link state
callback()
+ propagate link states
to tf()
+ init ()
+ update()
+ simulated link state
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```