

smacc::ISmaccState
# stateReactors_ # nh # contextNh # parentState_ # stateInfo_
+ getStateMachine() + getParentState() + getROSNode() + getClassName() + configure() + requiresComponent() + requiresClient() + getGlobalSMDData() + setGlobalSMDData() + createStateReactor() + createStateReactor() + postEvent() + postEvent() + notifyTransition() + notifyTransitionFromTransition TypeInfo() + getStateReactors() + getParam() + setParam() + param() + getOrthogonal() # requestLockStateMachine() # requestUnlockStateMachine()

boost::statechart:: simple_state< MostDerived, Context, InnerInitial, historyMode >

smacc::SmaccState< MostDerived, Context, InnerInitial, historyMode >
+ finishStateThrown + smacc_inner_type
+ SmaccState() + SmaccState() + ~SmaccState() + getStateInfo() + getFullName() + getShortName() + getParentState() + exit() + runtimeConfigure() + onEntry() + onExit() + getGlobalSMDData() + setGlobalSMDData() + requiresComponent() + getStateMachine() + checkWhileLoopConditionAnd ThrowEvent() + throwSequenceFinishedEvent() + configure_orthogonal _runtime() + configure_orthogonal _runtime() + configure_orthogonal() + static_createStateReactor() + initial_deep_construct() + deep_construct() + shallow_construct() - entryStateInternal() - configure_orthogonal _internal()

boost::statechart:: simple_state< StNavigateTo Waypoint1, MsDanceBotRunMode, mpl::list<>, sc::has_deep _history >

smacc::SmaccState< StNavigateToWaypoint1, MsDanceBotRunMode >
+ finishStateThrown + smacc_inner_type
+ SmaccState() + SmaccState() + ~SmaccState() + getStateInfo() + getFullName() + getShortName() + getParentState() + exit() + runtimeConfigure() + onEntry() + onExit() + getGlobalSMDData() + setGlobalSMDData() + requiresComponent() + getStateMachine() + checkWhileLoopConditionAnd ThrowEvent() + throwSequenceFinishedEvent() + configure_orthogonal _runtime() + configure_orthogonal _runtime() + configure_orthogonal() + static_createStateReactor() + initial_deep_construct() + deep_construct() + shallow_construct() - entryStateInternal() - configure_orthogonal _internal()

sm_dance_bot_2::StNavigate ToWaypoint1
+ staticConfigure()

< StNavigateToWaypoint1,  
MsDanceBotRunMode >