

```
cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker
```



```
graph LR; A["cl_move_base_z::forward  
_local_planner::ForwardLocal  
Planner::publishGoalMarker"] --> B["cl_move_base_z::forward  
_local_planner::optionalRobotPose"]
```

A diagram showing a transition from a state on the left to a state on the right. The left state is represented by a gray box containing the text 'cl_move_base_z::forward', '_local_planner::ForwardLocal', and 'Planner::publishGoalMarker'. A blue arrow points from this box to a white box on the right. The right box contains the text 'cl_move_base_z::forward', '_local_planner::optionalRobotPose'.

```
cl_move_base_z::forward  
_local_planner::optionalRobotPose
```