smacc::SmaccClientBehavior

- + stateMachine_
- + currentState + currentOrthogonal
- + SmaccClientBehavior()
- + ~SmaccClientBehavior()
- + getName() + onEntry()
- + onExit()
- + postEvent()
- + postEvent()
- + requiresClient()
- + requiresComponent()
- configureEventSourceTypes()



ros_publisher_client ::CbPublishOnce< RosMsgType >

- deferedPublishFn

- client
- + CbPublishOnce()
- + CbPublishOnce()
 - + setMessage() + onEntry()
- + onExit()