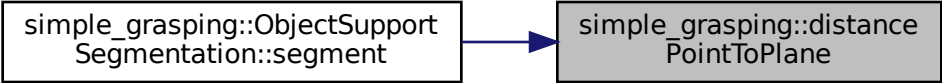


simple_grasping::ObjectSupport
Segmentation::segment



```
graph LR; A[simple_grasping::ObjectSupport Segmentation::segment] --> B[simple_grasping::distance PointToPlane];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow pointing from left to right. The left box is white with a black border and contains the text 'simple_grasping::ObjectSupport' on the top line and 'Segmentation::segment' on the bottom line. The right box is gray with a black border and contains the text 'simple_grasping::distance' on the top line and 'PointToPlane' on the bottom line. A dark blue arrow points from the right side of the left box to the left side of the right box.

simple_grasping::distance
PointToPlane