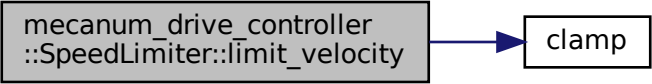


mecanum_drive_controller
::SpeedLimiter::limit_velocity



```
graph LR; A[mecanum_drive_controller::SpeedLimiter::limit_velocity] --> B[clamp];
```

clamp