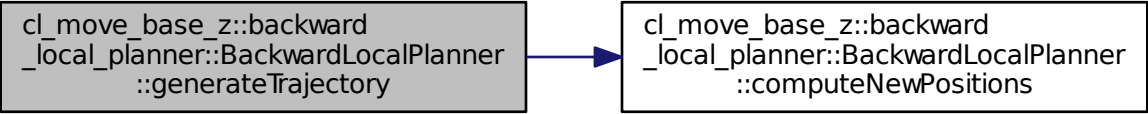


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::generateTrajectory"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeNewPositions"]
```

A diagram showing a call sequence between two functions. The left box, with a gray background, contains the code for `generateTrajectory`. A blue arrow points from this box to a right box, which contains the code for `computeNewPositions`. Both boxes have a black border and contain the same namespace and class information: `cl_move_base_z::backward` and `_local_planner::BackwardLocalPlanner`.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeNewPositions
```