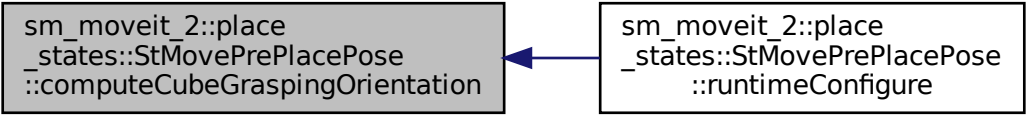


```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::computeCubeGraspingOrientation
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains the text 'sm\_moveit\_2::place', '\_states::StMovePrePlacePose', and '::computeCubeGraspingOrientation'. The box on the right is white and contains the text 'sm\_moveit\_2::place', '\_states::StMovePrePlacePose', and '::runtimeConfigure'. A blue arrow points from the right box to the left box, indicating a function call or dependency.

```
sm_moveit_2::place  
_states::StMovePrePlacePose  
::runtimeConfigure
```