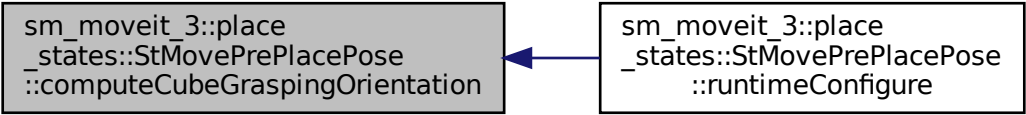


```
sm_moveit_3::place  
_states::StMovePrePlacePose  
::computeCubeGraspingOrientation
```



A diagram showing a call from a function in one state to a function in another state. A blue arrow points from the `::runtimeConfigure` function in the right box to the `::computeCubeGraspingOrientation` function in the left box.

```
sm_moveit_3::place  
_states::StMovePrePlacePose  
::runtimeConfigure
```