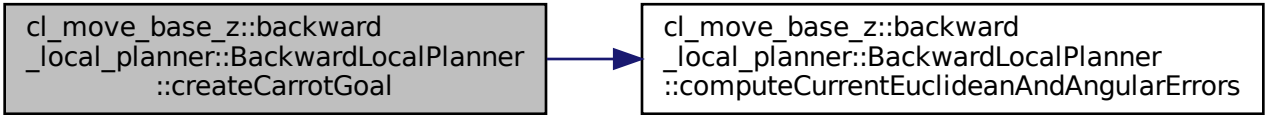


```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::createCarrotGoal
```



```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors
```