```
smacc::ISmaccClientBehavior
 smacc::SmaccClientBehavior

    stateMachine

    currentState

- currentOrthogonal
+ SmaccClientBehavior()
+ ~SmaccClientBehavior()
+ getStateMachine()
+ getName()
+ runtimeConfigure()
+ onEntrv()
+ onExit()
+ postEvent()
+ postEvent()
+ requiresClient()
+ requiresComponent()
+ getCurrentState()
configureEventSourceTypes()
    cl ros timer::CbTimer

    timerClient

- postTimerEvent
+ onEntry()
+ onExit()
+ configureEventSourceTypes()
+ onClientTimerTickCallback()
```