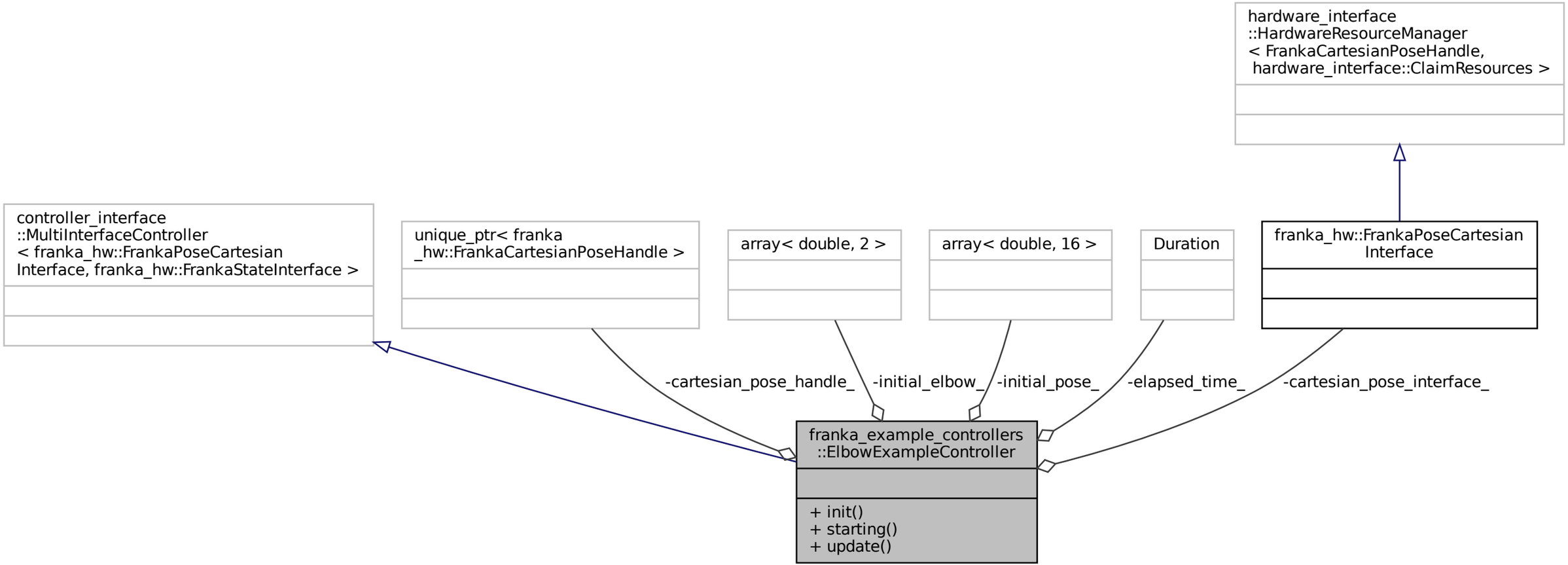
hardware_interface
::HardwareResourceManager
< FrankaCartesianPoseHandle,
hardware_interface::ClaimResources >
controller_interface
::MultiInterfaceController
< franka_hw::FrankaPoseCartesian
Interface, franka_hw::FrankaStateInterface >
unique_ptr< franka
_hw::FrankaCartesianPoseHandle >
array< double, 2 >
array< double, 16 >
Duration
franka_hw::FrankaPoseCartesian
Interface
-cartesian_pose_handle_
-initial_elbow_
-initial_pose_
-elapsed_time_
-cartesian_pose_interface_
franka_example_controllers
::ElbowExampleController
+ init()
+ starting()
+ update()