

sm_ridgeback_floor
_coverage_dynamic_1
::radial_motion_states
::StiRadialLoopStart::onEntry

```
graph LR; A["sm_ridgeback_floor<br/>_coverage_dynamic_1<br/>::radial_motion_states<br/>::StiRadialLoopStart::onEntry"] --> B["smacc::SmaccState<<br/>StiRadialLoopStart,<br/>SS >::checkWhileLoopCondition<br/>AndThrowEvent"]; A --> C["sm_ridgeback_floor<br/>_coverage_dynamic_1<br/>::radial_motion_states<br/>::StiRadialLoopStart::loopWhile<br/>Condition"];
```

smacc::SmaccState<
StiRadialLoopStart,
SS >::checkWhileLoopCondition
AndThrowEvent

sm_ridgeback_floor
_coverage_dynamic_1
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::StiRadialLoopStart::loopWhile
Condition