

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintLateralWorkspace  
::createVirtualCollisionWalls
```



The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and a black border, containing four lines of C++ code. The right box has a white background and a black border, containing the same first three lines of code, but with the last line, `::createCollisionBox`, indented further to the right. The blue arrow is positioned between the two boxes, pointing towards the right box.

```
sm_fetch_screw_loop  
_1::cl_move_group_interface  
::CpConstraintLateralWorkspace  
    ::createCollisionBox
```