

```
boost::statechart::  
event< EvTopicMessageTimeout  
    < TSource, TOrthogonal > >
```

The diagram shows a class hierarchy. The base class, `boost::statechart::event< EvTopicMessageTimeout < TSource, TOrthogonal > >`, is represented by a white box with a thin black border. The derived class, `cl_multirole_sensor::EvTopicMessageTimeout`, is represented by a grey box with a thick black border. A blue arrow with an open triangular head points from the derived class to the base class, indicating inheritance. The derived class box is divided into three horizontal sections: the top section contains the class name, the middle section contains the member `+ timerData`, and the bottom section is empty.

```
cl_multirole_sensor  
::EvTopicMessageTimeout  
< TSource, TOrthogonal >
```

```
+ timerData
```