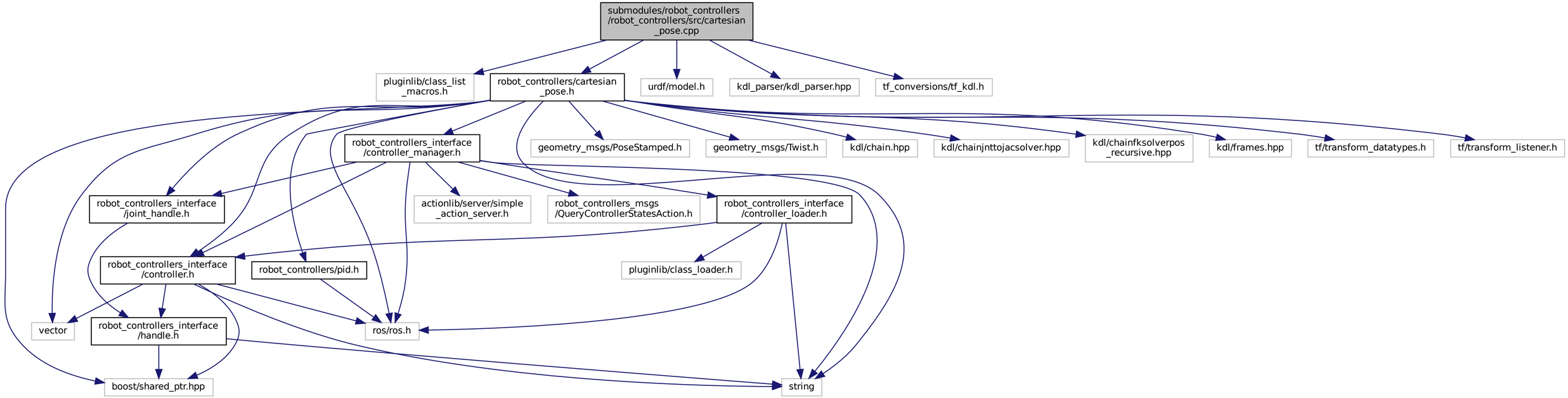
submodules/robot_controllers/robot_controllers/src/cartesian_pose.cpp
pluginlib/class_list_macros.h
robot_controllers/cartesian_pose.h
urdf/model.h
kdl_parser/kdl_parser.hpp
tf_conversions/tf_kdl.h
robot_controllers_interface/controller_manager.h
geometry_msgs/PoseStamped.h
geometry_msgs/Twist.h
kdl/chain.hpp
kdl/chainjnttojacsolver.hpp
kdl/chainfksolverpos_recursive.hpp
kdl/frames.hpp
tf/transform_datatypes.h
tf/transform_listener.h
robot_controllers_interface/joint_handle.h
actionlib/server/simple_action_server.h
robot_controllers_msgs/QueryControllerStatesAction.h
robot_controllers_interface/controller_loader.h
robot_controllers_interface/controller.h
robot_controllers/pid.h
pluginlib/class_loader.h
vector
robot_controllers_interface/handle.h
ros/ros.h
boost/shared_ptr.hpp
string