

```
mecanum_drive_controller  
::MecanumDriveController::init
```



```
graph LR; A[mecanum_drive_controller  
::MecanumDriveController::init] --> B[mecanum_drive_controller  
::MecanumDriveController  
::setWheelParamsFromUrdf];
```

A diagram showing a call from an initialization function to a parameter-setting function. A blue arrow points from the left box to the right box.

```
mecanum_drive_controller  
::MecanumDriveController  
::setWheelParamsFromUrdf
```