```
smacc::ISmaccClientBehavior
    - stateMachine
    - currentState

    currentOrthogonal

    + ISmaccClientBehavior()
       ~ISmaccClientBehavior()
    + getStateMachine()
    + getName()
    + requiresClient()
    + requiresComponent()
    # runtimeConfigure()
    # onEntry()
    # onExit()
    # postEvent()
    # postEvent()
    # getCurrentState()
    # executeOnEntry()
    # executeOnExit()
    configureEventSourceTypes()
     smacc::SmaccClientBehavior
     + onEntry()
     + onExit()
                        cl multirole sensor
                        ::CbDefaultMultiRoleSensor
                            Behavior < ClientType >
                        + sensor
                        + deferedEventPropagation
                        + CbDefaultMultiRoleSensor
                        Behavior()
                        + configureEventSourceTypes()
                        + propagateEvent()
                        + propagateEvent2()
                        + onEntry()
                        + onExit()
                        + onMessageCallback()
                        + getEventLabel()
                               < ClTemperatureSensor >
     multirole_sensor
   ::C̄bDefaultM̄ultiRoleSensor
  Behavior < ClTemperatureSensor >
  + sensor
  + deferedEventPropagation

    + CbDefaultMultiRoleSensor

  Behavior()
  + configureEventSourceTypes()
   + propagateEvent()
  + propagateEvent2()
  + onEntry()
  + onExit()
   + onMessageCallback()
  + getEventLabel()
sm_dance_bot::cl_temperature
_sensor::CbConditionTemperatureSensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```