

sm\_ridgeback\_floor  
\_coverage\_dynamic\_1  
::cl\_lidar::CpLidarSensorData  
::onInitialize

```
graph LR; A["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::onInitialize"] --> B["sm_ridgeback_floor  
_coverage_dynamic_1  
::cl_lidar::CpLidarSensorData  
::MessageCallbackStoreDistanceToWall"]; A --> C["smacc::client_bases  
::SmaccSubscriberClient  
::onMessageReceived"];
```

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