

```
graph BT; A["smacc_sm_reference  
_library/sm_moveit_3  
_src/sm_moveit_3_node.cpp"] --> B["smacc_sm_reference  
_library/sm_moveit_3  
_include/sm_moveit_3  
_sm_moveit_3.h"]; B --> C["smacc_sm_reference  
_library/sm_moveit_3  
_include/sm_moveit_3  
_clients/gripper_client  
_client_behaviors/cb_open  
_gripper.h"];
```

smacc_sm_reference
_library/sm_moveit_3
_include/sm_moveit_3
_clients/gripper_client
_client_behaviors/cb_open
_gripper.h

smacc_sm_reference
_library/sm_moveit_3
_include/sm_moveit_3
_sm_moveit_3.h

smacc_sm_reference
_library/sm_moveit_3
_src/sm_moveit_3_node.cpp