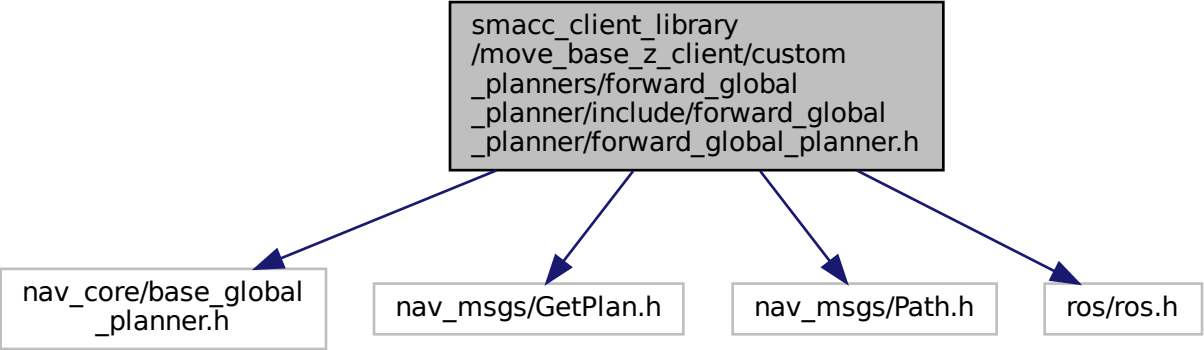


smacc\_client\_library  
/move\_base\_z\_client/custom  
\_planners/forward\_global  
\_planner/include/forward\_global  
\_planner/forward\_global\_planner.h



```
graph TD; A["smacc_client_library  
/move_base_z_client/custom  
_planners/forward_global  
_planner/include/forward_global  
_planner/forward_global_planner.h"] --> B["nav_core/base_global  
_planner.h"]; A --> C["nav_msgs/GetPlan.h"]; A --> D["nav_msgs/Path.h"]; A --> E["ros/ros.h"];
```

The diagram illustrates the dependencies of the `forward_global_planner.h` header file. A central box at the top lists the file's path. Four arrows point from this box to four separate boxes below, each representing a dependency: `nav_core/base_global_planner.h`, `nav_msgs/GetPlan.h`, `nav_msgs/Path.h`, and `ros/ros.h`.

nav\_core/base\_global  
\_planner.h

nav\_msgs/GetPlan.h

nav\_msgs/Path.h

ros/ros.h