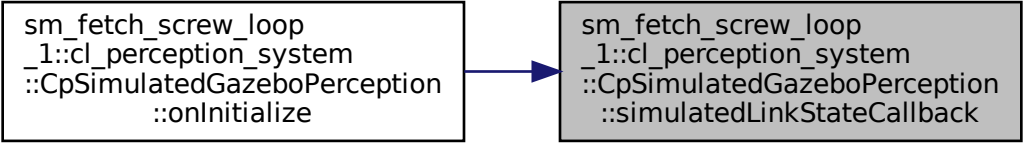


```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::onInitialize
```



The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'sm\_fetch\_screw\_loop', '\_1::cl\_perception\_system', '::CpSimulatedGazeboPerception', and '::onInitialize'. The right box is gray with a black border and contains the text 'sm\_fetch\_screw\_loop', '\_1::cl\_perception\_system', '::CpSimulatedGazeboPerception', and '::simulatedLinkStateCallback'.

```
sm_fetch_screw_loop  
_1::cl_perception_system  
::CpSimulatedGazeboPerception  
    ::simulatedLinkStateCallback
```