

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::pureSpinningCmd
```



A diagram showing a transformation from a specific command to a more general pose. A blue arrow points from a grey box on the left to a white box on the right. The grey box contains the command `cl_move_base_z::backward`, the planner `_local_planner::BackwardLocalPlanner`, and the command type `::pureSpinningCmd`. The white box contains the same command `cl_move_base_z::backward` but with a different planner `_local_planner::optionalRobotPose`.

```
cl_move_base_z::backward  
_local_planner::optionalRobotPose
```