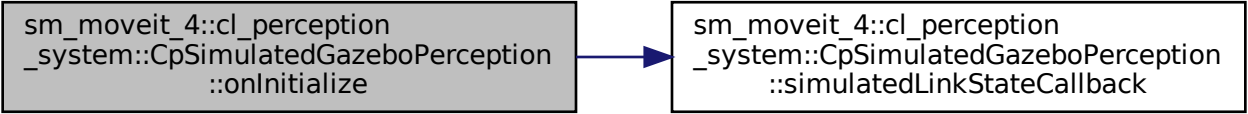


```
sm_moveit_4::cl_perception  
_system::CpSimulatedGazeboPerception  
::onInitialize
```



A diagram showing a call from the `onInitialize` method to the `simulatedLinkStateCallback` method. The left box, representing the caller, has a gray background and contains the text `sm_moveit_4::cl_perception`, `_system::CpSimulatedGazeboPerception`, and `::onInitialize`. A blue arrow points from the right side of this box to the left side of the right box. The right box, representing the callee, has a white background and contains the text `sm_moveit_4::cl_perception`, `_system::CpSimulatedGazeboPerception`, and `::simulatedLinkStateCallback`.

```
sm_moveit_4::cl_perception  
_system::CpSimulatedGazeboPerception  
::simulatedLinkStateCallback
```