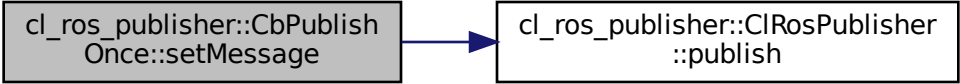


cl\_ros\_publisher::CbPublish  
Once::setMessage



```
graph LR; A[cl_ros_publisher::CbPublishOnce::setMessage] --> B[cl_ros_publisher::ClRosPublisher::publish]
```

cl\_ros\_publisher::ClRosPublisher  
::publish