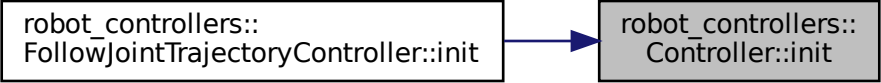


robot\_controllers::  
FollowJointTrajectoryController::init



```
graph LR; A[robot_controllers::FollowJointTrajectoryController::init] --> B[robot_controllers::Controller::init];
```

The diagram illustrates a function call. A white rectangular box on the left contains the text 'robot\_controllers::FollowJointTrajectoryController::init'. A dark blue arrow points from the right side of this box to a gray rectangular box on the right. The gray box contains the text 'robot\_controllers::Controller::init'.

robot\_controllers::  
Controller::init