

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_superstates/ss_f_pattern_1.h"]; C --> D["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_states/f_pattern_states  
_sti_fpattern_forward_1.h"];
```

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_states/f_pattern_states
_sti_fpattern_forward_1.h

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_superstates/ss_f_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
_include/sm_dance_bot
_sm_dance_bot.h

smacc_sm_reference
_library/sm_dance_bot
_src/sm_dance_bot.cpp