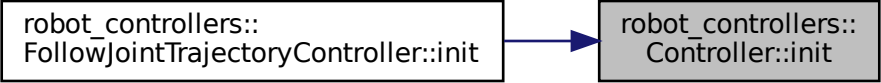


robot\_controllers::  
FollowJointTrajectoryController::init



```
graph LR; A[robot_controllers::  
FollowJointTrajectoryController::init] --> B[robot_controllers::  
Controller::init]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is white with a black border and contains the text 'robot\_controllers::' on the first line and 'FollowJointTrajectoryController::init' on the second line. The right box is gray with a black border and contains the text 'robot\_controllers::' on the first line and 'Controller::init' on the second line. A blue arrow points from the right side of the left box to the left side of the right box.

robot\_controllers::  
Controller::init