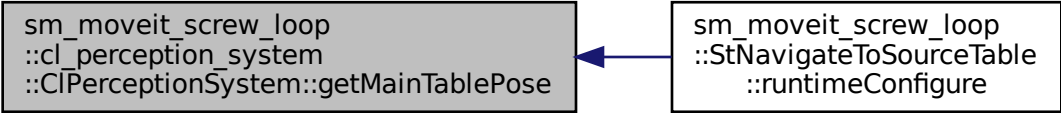


```
sm_moveit_screw_loop  
::cl_perception_system  
::ClPerceptionSystem::getMainTablePose
```



The diagram consists of two rectangular boxes. The box on the left is shaded gray and contains three lines of C++ code. The box on the right is white and contains two lines of C++ code. A blue arrow points from the right box to the left box, indicating a function call or data flow.

```
sm_moveit_screw_loop  
::StNavigateToSourceTable  
::runtimeConfigure
```