```
smacc::ISmaccClientBehavior
 - stateMachine
  currentState
 - currentOrthogonal
 + ISmaccClientBehavior()
    ~ISmaccClientBehavior()
 + getStateMachine()
 + getName()
+ requiresClient()
 + requiresComponent()
 # runtimeConfigure()
 # onEntry()
 # onExit()
 # postEvent()
 # postEvent()
 # getCurrentState()
 # executeOnEntry()
 # executeOnExit()
 # dispose()
 - configureEventSourceTypes()
  smacc::SmaccClientBehavior
  + onEntry()
  + onExit()
                Δ
                         multirole sensor
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                          Behavior < ClientType >
                      + deferedEventPropagation
                      + CbDefaultMultiRoleSensor
                      Behavior()
                      + configureEventSourceTypes()
                      + propagateEvent()
                      + propagateEvent2()
                      + onEntry()
                      + onExit()
                      + onMessageCallback()
                      + getEventLabel()
                             < ClTemperatureSensor >
cl_multirole_sensor
::CbDefaultMultiRoleSensor
Behavior < CITemperatureSensor >
+ sensor
+ deferedEventPropagation

    CbDefaultMultiRoleSensor

Behavior()
+ configureEventSourceTypes()
+ propagateEvent()
+ propagateEvent2()
+ onEntry()
+ onExit()
+ onMessageCallback()
+ getEventLabel()
                 Д
sm_dance_bot_strikes
back::cl_temperature
sensor::CbConditionTemperature
              Sensor
+ CbConditionTemperatureSensor()
+ onMessageCallback()
```