

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal
```



```
graph LR; A["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::findInitialCarrotGoal"] --> B["cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal"]
```

A diagram showing a call to the `findInitialCarrotGoal` method. A grey box on the left contains the code snippet. A blue arrow points from this box to a white box on the right, which contains the code snippet for the `computeCurrentEuclideanAndAngularErrorsToCarrotGoal` method.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeCurrentEuclideanAndAngularErrors  
ToCarrotGoal
```