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graph BT; A[smacc_sm_reference_library/sm_dance_bot_2/src/sm_dance_bot_2.cpp] --> B[smacc_sm_reference_library/sm_dance_bot_2/include/sm_dance_bot_2/sm_dance_bot_2.h]; B --> C[smacc_sm_reference_library/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/ss_s_pattern_1.h]; C --> D[smacc_sm_reference_library/sm_dance_bot_2/states/ms_dance_bot_run_mode/s_pattern_states/sti_spattern_rotate_3.h];
```

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_run
_mode/s_pattern_states/sti
_spattern_rotate_3.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/states/ms_dance_bot_run
_mode/s_pattern_states/ss
_s_pattern_1.h

smacc_sm_reference
_library/sm_dance_bot
_2/include/sm_dance_bot
_2/sm_dance_bot_2.h

smacc_sm_reference
_library/sm_dance_bot
_2/src/sm_dance_bot_2.cpp