

```
graph BT; A["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_states/st_navigate_to  
_waypoint_1.h"] --> B["smacc_sm_reference  
_library/sm_dance_bot  
_include/sm_dance_bot  
_sm_dance_bot.h"]; B --> C["smacc_sm_reference  
_library/sm_dance_bot  
_src/sm_dance_bot.cpp"];
```

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_states/st\_navigate\_to  
\_waypoint\_1.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_include/sm\_dance\_bot  
\_sm\_dance\_bot.h

smacc\_sm\_reference  
\_library/sm\_dance\_bot  
\_src/sm\_dance\_bot.cpp