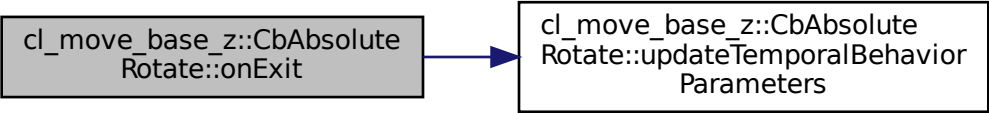


cl_move_base_z::CbAbsolute
Rotate::onExit



```
graph LR; A["cl_move_base_z::CbAbsolute<br/>Rotate::onExit"] --> B["cl_move_base_z::CbAbsolute<br/>Rotate::updateTemporalBehavior<br/>Parameters"]
```

The diagram consists of two rectangular boxes connected by a horizontal blue arrow pointing from left to right. The left box has a light gray background and contains the text 'cl_move_base_z::CbAbsolute' and 'Rotate::onExit' on two lines. The right box has a white background and contains the text 'cl_move_base_z::CbAbsolute', 'Rotate::updateTemporalBehavior', and 'Parameters' on three lines.

cl_move_base_z::CbAbsolute
Rotate::updateTemporalBehavior
Parameters