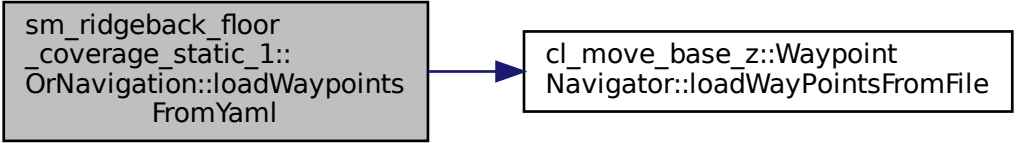


sm_ridgeback_floor
_coverage_static_1::
OrNavigation::loadWaypoints
FromYaml

A blue arrow points from the right side of the first box to the left side of the second box.

```
cl_move_base_z::Waypoint  
Navigator::loadWayPointsFromFile
```