

```
smacc_sm_reference  
_library/sm_dance_bot  
_2/servers/temperature  
_sensor_node/src/temperature  
_sensor_node.cpp
```



```
graph TD; A["smacc_sm_reference_library/sm_dance_bot_2/servers/temperature_sensor_node/src/temperature_sensor_node.cpp"] --> B["ros/ros.h"]; A --> C["sensor_msgs/Temperature.h"]
```

ros/ros.h

sensor\_msgs/Temperature.h