```
# components_

    stateMachine

orthogonal_
+ ISmaccClient()
+ ~ISmaccClient()
+ initialize()
+ getName()
+ postEvent()
+ postEvent()
+ getComponent()
+ getComponent()
+ getType()
+ getStateMachine()
+ connectSignal()
+ requiresClient()
+ getComponents()
# onOrthogonalAllocation()
# createComponent()
# createNamedComponent()
# setStateMachine()
# setOrthogonal()
                  smacc::client_bases
                  ::SmaccSubscriberClient
                       < MessageType >
                  + topicName
                  + queueSize
                  + onFirstMessageReceived_
                  + onMessageReceived_
                  + postMessageEvent
                   + postInitialMessageEvent
                  # nh_
                  - sub
                  - firstMessage_
                  - initialized
                  + SmaccSubscriberClient()
                  + SmaccSubscriberClient()
                  + ~SmaccSubscriberClient()
                   + onMessageReceived()
                  + onFirstMessageReceived()
                  + onOrthogonalAllocation()
                  + initialize()
                  messageCallback()
                   < sensor_msgs::Temperature >
smacc::client_bases
::SmaccSubscriberClient
< sensor_msgs::Temperature >
                                     cl multirole sensor
+ topicName
                                     ::ClMultiroleSensor
+ queueSize
                                           < MessageType >
+ onFirstMessageReceived_
+ onMessageReceived_
                                      + onMessageTimeout_
+ postMessageEvent
                                      + postTimeoutMessageEvent
+ postInitialMessageEvent
                                      + timeout
# nh_
                                     - timeoutTimer_
- sub

    initialized

firstMessage_
- initialized
                                      + CIMultiroleSensor()
                                      + onMessageTimeout()
+ SmaccSubscriberClient()
                                      + onOrthogonalAllocation()
+ SmaccSubscriberClient()
                                      + initialize()
+ ~SmaccSubscriberClient()
                                      # resetTimer()
+ onMessageReceived()
                                      timeoutCallback()
+ onFirstMessageReceived()
+ onOrthogonalAllocation()
+ initialize()
- messageCallback()
                                          < sensor_msgs::Temperature >
                  cl_multirole_sensor
                  ::CIMultiroleSensor
                  < sensor_msgs::Temperature >
                  + onMessageTimeout_
                  + postTimeoutMessageEvent
                  + timeout
                  timeoutTimer_
                  - initialized
                  + CIMultiroleSensor()
                  + onMessageTimeout()
                  + onOrthogonalAllocation()
                  + initialize()
                  # resetTimer()
                  timeoutCallback()
                     sm_dance_bot_2::cl
                      _temperature_sensor
                       ::ClTemperatureSensor
```

+ ClTemperatureSensor()

smacc::ISmaccClient