

sm_atomic_cb::State2
::runtimeConfigure

sm_atomic_cb::State1
::runtimeConfigure

cl_ros_timer::CbTimerCountdown
Once::onTimerTick

```
graph LR; A["sm_atomic_cb::State2::runtimeConfigure"] --> C["cl_ros_timer::CbTimerCountdownOnce::onTimerTick"]; B["sm_atomic_cb::State1::runtimeConfigure"] --> C;
```

The diagram illustrates a dependency or call relationship. On the left, there are two white rectangular boxes. The top box contains the text 'sm_atomic_cb::State2::runtimeConfigure' and the bottom box contains 'sm_atomic_cb::State1::runtimeConfigure'. On the right, there is a single gray rectangular box containing the text 'cl_ros_timer::CbTimerCountdownOnce::onTimerTick'. Two blue arrows originate from the right side of the two white boxes and point towards the left side of the gray box, indicating that both state configuration functions are associated with or call the timer callback function.