

boost::statechart::
event< EvWaypoint200
< TSource, TOrthogonal > >

```
classDiagram
    class boost_statechart_event["boost::statechart::event< EvWaypoint200< TSource, TOrthogonal > >"]
    class cl_move_base_z_ev_waypoint200["cl_move_base_z::EvWaypoint200< TSource, TOrthogonal >"]
    cl_move_base_z_ev_waypoint200 --|> boost_statechart_event
```

The diagram consists of two rectangular boxes. The top box is white with a thin grey border and contains the text 'boost::statechart::event< EvWaypoint200< TSource, TOrthogonal > >'. It is divided into three horizontal sections by thin grey lines. The bottom box is grey with a thick black border and contains the text 'cl_move_base_z::EvWaypoint200< TSource, TOrthogonal >' and '+ waypointIndex'. It is also divided into three horizontal sections by thin black lines. A blue arrow with an open triangular head points from the top of the bottom box to the bottom of the top box, indicating a generalization relationship.

cl_move_base_z::EvWaypoint200
< TSource, TOrthogonal >

+ waypointIndex