

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::computeVelocityCommands
```



A diagram showing a call sequence between two function calls. A blue arrow points from the first box to the second box. The first box is white with a black border, and the second box is gray with a black border.

```
cl_move_base_z::backward  
_local_planner::BackwardLocalPlanner  
::updateCarrotGoal
```