

The image shows a web browser window with multiple tabs. The active tab is 'index.php'. The browser's address bar is empty. The main content area displays a code editor with the following HTML and CSS code:

```
1 <!DOCTYPE html>
2 <html>
3 <head>
4   <meta name="viewport" content="width=device-width, initial-scale=1">
5 </head>
6 <body>
7   <div class="slidecontainer">
8     <div class="slider" style="width: 100%; height: 25px; background-color: #d3d3d3; border: 1px solid black; position: relative; margin-bottom: 10px;">
9       <div class="slider-thumb" style="width: 25px; height: 25px; background-color: #04AA6D; border: 1px solid black; position: absolute; top: -10px; left: 0; margin-top: 5px;">

The code defines a slider interface. It includes a viewport meta tag for responsive design. The CSS defines a slider container with a width of 100% and a height of 25px. The slider itself is a div with a width of 100%, height of 25px, and a background color of #d3d3d3. The slider thumb is a div with a width of 25px, height of 25px, and a background color of #04AA6D. The slider thumb is positioned at the left end of the slider.


```

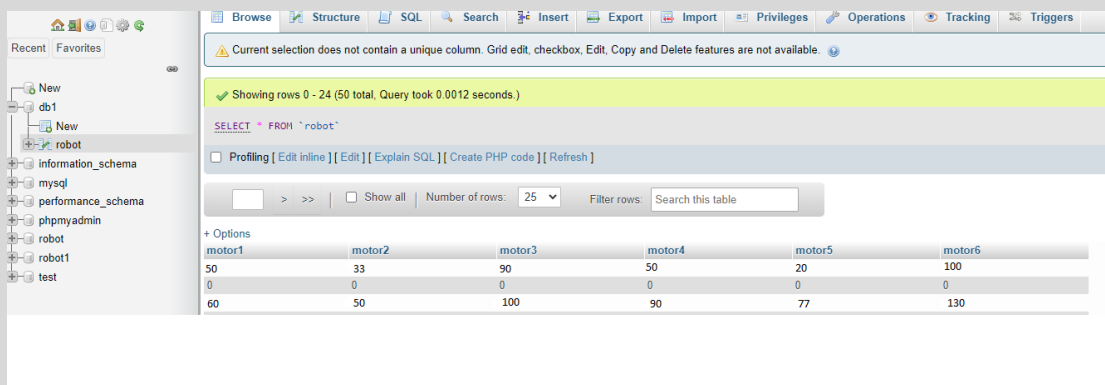
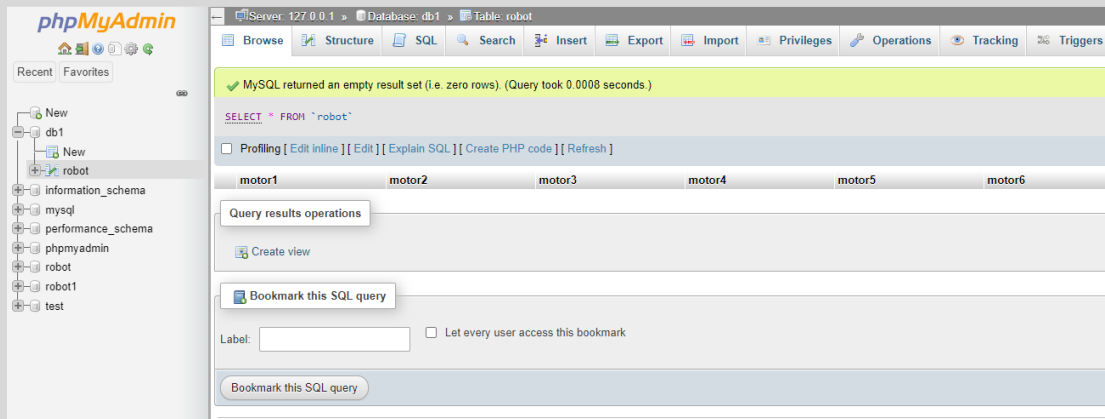
```
new 1 x new 2.sql x 9.sql x new3.html x index.php x new 3 x
39 </head>
40 <body>
41
42 <h1>Robot Control</h1>
43
44 <div class="slidecontainer">
45 <p>motor1</p>
46 <input type="range" min="1" max="180"
47 value="50">
48
49 <div class="slidecontainer">
50 <p>motor2</p>
51 <input type="range" min="1" max="180"
52 value="50">
53
54 <div class="slidecontainer">
55 <p>motor3</p>
56 <input type="range" min="1" max="180"
57 value="50">
58
59 <div class="slidecontainer">
60 <p>motor4</p>
61 <input type="range" min="1" max="180"
62 value="50">
63
64 <div class="slidecontainerr">
65 <p>motor5</p>
66 <input type="range" min="1" max="180"
67 value="50">
68
69 <div class="slidecontainer">
70 <p>motor6</p>
71 <input type="range" min="1" max="180"
72 value="50">
73 <p> </p>
74 <button class="save">save</button>
75
76 <button class="start">start</button>
```

```
new 1 x new 2.sql x 9.sql x new3.html x index.php x new 3 x
77 </div>
78
79
80 <p>motor1: </p>
81 <input type="range" min="1" max="100"
82 value="50" class="slider" id="myRange">
83 </div>
84 <p>motor2: </p>
85 <input type="range" min="1" max="100"
86 value="50" class="slider" id="myRange">
87 </div>
88
89 <p>motor3: </p>
90 <input type="range" min="1" max="100"
91 value="50" class="slider" id="myRange">
92 </div>
93
94 <p>motor4: </p>
95 <input type="range" min="1" max="100"
96 value="50" class="slider" id="myRange">
97 </div>
98
99 <p>motor5: </p>
100 <input type="range" min="1" max="100"
101 value="50" class="slider" id="myRange">
102 </div>
103
104 <p>motor6: </p>
105 <input type="range" min="1" max="100"
106 value="50" class="slider" id="myRange">
107 </div>
108
109
110 </body>
111 </html>
112
113
114 <php
```

```

111 </html>
112
113
114 <php
115 $servername = "localhost";
116 $username = "username";
117 $password = "";
118 $db="test";
119
120 $my_query= "";
121 $my_query = "select * from name where 1 ";
122 $result= mysqli_query($mysqli, $my_query);
123
124 $connection = new mysqli("localhost","root", "", "db1");
125 $stmt = $connection->prepare("select * from robot ");
126 $stmt->execute();
127 $result= $stmt->get_result();
128 echo"<table>";
129 while ($row=$result->fetch_assoc()){
130     echo "<tr><td>". $row['motor1', 'motor2', 'motor3', 'motor4', 'motor5', 'motor6'].</td></tr>";
131 }
132 echo"<table>";
133 $conn = new mysqli($servername,$username,$password, $db);
134
135 if($conn->connect_error){
136     die("Connection failed: " . $conn->connect_error);
137 }
138 echo "Connected successfully";
139
140 $sql = "INSERT INTO robot(motor1, motor2, motor3, motor4, motor5, motor6)
141 VALUES ('<div class='POST'></div>)'";
142 $result= mysqli_query($mysqli, $my_query);
143 if (mysqli_query($conn, $sql)){
144     echo
145 } else{
146     echo "Error: " . $sql .
147 }
148 ?>

```



phpmyadmin

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Table structureRelation view

#	Name	Type	Collation	Attributes	Null	Default	Comments	Extra	Action
<input type="checkbox"/>	1	motor1	int(11)		No	None			Change Drop More
<input type="checkbox"/>	2	motor2	int(11)		No	None			Change Drop More
<input type="checkbox"/>	3	motor3	int(11)		No	None			Change Drop More
<input type="checkbox"/>	4	motor4	int(11)		No	None			Change Drop More
<input type="checkbox"/>	5	motor5	int(11)		No	None			Change Drop More
<input type="checkbox"/>	6	motor6	int(11)		No	None			Change Drop More

☐ Check all

With selected:

[Browse](#) [Change](#) [Drop](#) [Primary](#) [Unique](#) [Index](#) [Spatial](#) [Fulltext](#)

[Add to central columns](#) [Remove from central columns](#)

Robot Control

motor1

motor2

motor3

motor4

motor5

motor6

save

start