

## HW Assignment 2

### Solution

#### Question 1

The characteristic polynomial:

$$\lambda^3 + 5\lambda^2 + 7\lambda + 3 = 0$$

We'll use polynomial division starting with the root -1:

$$\begin{array}{r} \lambda^2 + 4\lambda + 3 \\ \lambda^3 + 5\lambda^2 + 7\lambda + 3 \overline{) \lambda + 1} \\ \underline{-\lambda^3 + \lambda^2} \phantom{+ 7\lambda + 3} \\ 4\lambda^2 + 7\lambda \phantom{+ 3} \\ \underline{-4\lambda^2 + 4\lambda} \phantom{+ 3} \\ 3\lambda + 3 \\ \underline{-3\lambda + 3} \\ 0 \end{array}$$

We got:  $\lambda^3 + 5\lambda^2 + 7\lambda + 3 = (\lambda^2 + 4\lambda + 3)(\lambda + 1) = (\lambda + 1)^2(\lambda + 3)$ , so the solutions of the polynomial are:  $-1, -1$  and  $-3$  making  $y$

$$y(t) = (c_1 + c_2 t)e^{-t} + c_3 e^{-3t}$$

by using the initial conditions we get a linear set of equations:

$$y(0) = c_1 + c_3 = 0$$

$$\dot{y}(0) = -c_1 + c_2 - 3c_3 = 2$$

$$\ddot{y}(0) = c_1 - 2c_2 + 9c_3 = 4$$

making the solution

$$y(t) = (6t - 2)e^{-t} + 2e^{-3t}$$

#### Question 2

Writing the above system using the notation we saw in class  $Q(D)[y](t) = P(D)[x](t)$  we get:

$$Q(D) = \sum_{i=0}^n a_i D^i = D^3 + 5D^2 + 7D + 3$$

$$P(D) = \sum_{i=0}^m b_i D^i = 2D^2 + D$$

when  $n = 3, m = 2$ .

The impulse response is given by  $h(t) = b_n \delta(t) + [P(D)y_n]u(t)$  where:

- $n > m$  and therefor  $b_n = 0$ .

- $P(D) = 2D^2 + D$ .
- $y_n$  is the solution of  $\ddot{y}(t) + 5\dot{y}(t) + 7y(t) = 0$  (same as Q1) using the initial conditions:  
 $y(0) = \dot{y}(0) = 0, \ddot{y}(0) = 1$ :

$$\begin{aligned} y(0) &= c_1 + c_3 = 0 \\ \dot{y}(0) &= -c_1 + c_2 - 3c_3 = 0 \\ \ddot{y}(0) &= c_1 - 2c_2 + 9c_3 = 1 \end{aligned}$$

we get:

$$y_n(t) = \left(\frac{1}{2}t - \frac{1}{4}\right)e^{-t} + \frac{1}{4}e^{-3t}$$

$$h(t) = b_n \delta(t) + [P(D)y_n]u(t) = \left[2\frac{d^2}{dt^2}y_n(t) + \frac{d}{dt}y_n(t)\right]u(t) = \left[\left(\frac{1}{2}t - \frac{7}{4}\right)e^{-t} + \frac{15}{4}e^{-3t}\right]u(t)$$

### Question 3

$$\begin{aligned} y(t) &= x(t) * h(t) = 4e^{-3t}u(t) * \left[\left(\frac{1}{2}te^{-t} - \frac{7}{4}e^{-t} + \frac{15}{4}e^{-3t}\right)u(t)\right] = \\ &= 2e^{-3t}u(t) * te^{-t}u(t) - 7e^{-3t}u(t) * e^{-t}u(t) + 15e^{-3t}u(t) * e^{-3t}u(t) \end{aligned}$$

From the convolution table we get

$$y(t) = [(-4+t)e^{-t} + (4+15t)e^{-3t}]u(t)$$

### Question 4

$$1. \quad \frac{d^2}{dt^2}i(t) + \frac{R}{L}\frac{d}{dt}i(t) + \frac{1}{LC}i(t) = 0.$$

$$2. \quad \text{The roots are } \lambda_{1,2} = \frac{-R \pm \sqrt{R^2 - 4\frac{L}{C}}}{2L}. \text{ The three phases depend on the sign of the discriminant}$$

$$R^2 - 4\frac{L}{C} \begin{matrix} > \\ < \end{matrix} 0:$$

- If  $R^2 - 4\frac{L}{C} > 0$  we get  $\lambda_1 \neq \lambda_2 \in \mathbb{R}$ . Therefore the solution is:  $i(t) = c_1 e^{\lambda_1 t} + c_2 e^{\lambda_2 t}$ .

- If  $R^2 - 4\frac{L}{C} = 0$  we get  $\lambda_1 = \lambda_2 = \frac{-R}{2L} \triangleq \lambda \in \mathbb{R}$ . Therefore the solution is:

$$i(t) = (c_1 + tc_2)e^{\lambda t}.$$

- if  $R^2 - 4\frac{L}{C} < 0$ , define  $\alpha = -\frac{R}{L}, \beta = \frac{\sqrt{4\frac{L}{C} - R^2}}{2L}, c_1 = c_2^* = \frac{c}{2}e^{i\theta}$  and we get:

$$i(t) = c_1 e^{(\alpha+i\beta)t} + c_2 e^{(\alpha-i\beta)t} = ce^{\alpha t} \cos(\beta t + \theta)$$

**Question 5**

In Lathi's book, question 2.4-12.

**Question 6**

The question is from the MIT Open Courseware (exercise 4.3 in the "downloadable version").

1.  $y(t) = \begin{cases} 1 - e^{-t} & t > 0 \\ 0 & t < 0 \end{cases}.$

2.  $y(t) = x(t - 2)$  - convolution with an impulse is equivalent to translation.