# **HW Assignment 6**

Due date: Thursday 14/4/2016

#### **Question 1**

Calculate the inverse Laplace transforms for the following functions and ROCs:

1. 
$$X(s) = \frac{s^2 + 1}{(s+1)^2} \operatorname{Re}\{s\} > -1$$

2. 
$$X(s) = \frac{s+1}{(s+1)^2 + 4}$$
 Re $\{s\} > -1$ 

### **Question 2**

The signal  $x(t) = u(t)e^{-t}$  is passed thorough an LTI system  $h(t) = u(t)e^{-3t}$ . the output is marked y(t).

- Calculate X(s) and H(s).
- Using the convolution property of the Laplace transform, find Y(s).
- Calculate the output y(t).

#### **Question 3**

Consider the LTI system defined by the ODE

$$\ddot{y}(t) - \dot{y}(t) - 2y(t) = x(t)$$

- 1. Calculate the transfer function H(s). Sketch the system's zeros and poles on the s-plane.
- 2. Sketch the ROC for each of the following cases:
  - 2.1. The system is stable.
  - 2.2. The system is casual.
  - 2.3. The system is neither stable nor casual.
- 3. Determine h(t) when the system is casual.

## **Question 4**

What is the casual and stable impulse response of the system

$$\ddot{y}(t) + 5\ddot{y}(t) + 7\dot{y}(t) + 3y(t) = 2\ddot{x}(t) + \dot{x}(t)$$

where x(t) is the input signal and y(t).

Remember the solution (Hint: Ex2 Q2)?