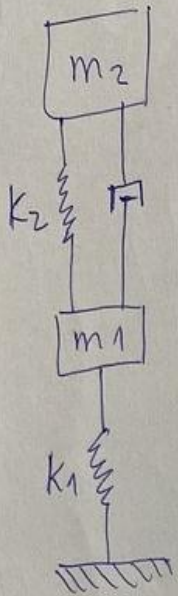


## Lecture 4

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Equations of Motion using Newton's Second Law:

$$m_i \ddot{x}_i = \text{sum of forces on } m_i \quad (1)$$

⊕ For  $m_1$ : forces acting on  $m_1$ 

- Spring force from  $k_1$ :  $-k_1 x_1$
- Spring force from  $k_2$ :  $k_2(x_2 - x_1)$
- Damping force from  $b$ :  $b(\dot{x}_2 - \dot{x}_1)$

$$(1) \Rightarrow m_1 \ddot{x}_1 = -k_1 x_1 + k_2(x_2 - x_1) + b(\dot{x}_2 - \dot{x}_1)$$

⊕ For  $m_2$ :

- Spring force from  $k_2$ :  $-k_2(x_2 - x_1)$
- Damping force from  $b$ :  $-b(\dot{x}_2 - \dot{x}_1)$

$$(1) \Rightarrow m_2 \ddot{x}_2 = -k_2(x_2 - x_1) - b(\dot{x}_2 - \dot{x}_1)$$

## Lecture 5

Mass-spring-damper example :

$$m\ddot{y} + b\dot{y} + ky = 0$$

$$\Rightarrow \ddot{y} + \frac{b}{m}\dot{y} + \frac{k}{m}y = 0 \Rightarrow \ddot{y} + 4\dot{y} + 40y = 0 \quad (1)$$

Assume a solution of the form  $y(t) = e^{rt}$

$$(1) \Rightarrow r^2 + 4r + 40 = 0$$

$$\Rightarrow r = \frac{-4 \pm \sqrt{-144}}{2}$$

$$\text{Since } \sqrt{-144} = 12i, \text{ we have } r = \frac{-4 \pm 12i}{2} = -2 \pm 6i$$

$$\therefore \text{General free response } y(t) = e^{-2t} (C_1 \cos(6t) + C_2 \sin(6t))$$

$$\text{where } \begin{cases} r = \alpha \pm i\omega \text{ (with } \alpha = -2, \omega = 6) \end{cases}$$

$$\begin{cases} C_1, C_2 \text{ are constants determined by initial conditions} \end{cases}$$

## Lecture 6

Let  $m = 1$ ,  $b = 4$ ,  $k = 40$  and  $u(t) = 1(t)$ , find  $x(t)$

```
2   m = 1;
3   b = 4;
4   k = 40;
5
6   s = tf('s');
7   H = (b*s + k) / (m*s^2 + b*s + k);
8   t = linspace(0, 5, 500);
9   u = ones(size(t));
10  x = lsim(H, u, t);
11
12  figure;
13  plot(t, x, 'LineWidth', 2);
14  title('Car Suspension Response using lsim');
15  xlabel('Time (sec)');
16  ylabel('x(t)');
17  grid on;
```

