HOME WORK #5

Mass parameters: m, = 10 kg m2 = 5 kg

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 $l_1 = l_2 = 0.5 m$

 $\theta_1(0) = 30^\circ$; $\theta_2(0) = 0$; $\theta_2(0) = 150^\circ$; $\theta_2(0) = 0$; $t_y = 1$ Sec When $G_1 = 10 \sin(0.5\pi t)$ is applied $G_2 = 10 \sin(0.5\pi t)$ is applied

find the trajectories of each point &, (t), &, (t) 0 \(\pm t \(\pm 1 \)

We have: $\theta(0) = \begin{bmatrix} \theta_1(0) \\ \theta_2(0) \end{bmatrix} = \begin{bmatrix} 30^{\circ} \\ 150^{\circ} \end{bmatrix}$; $\dot{\theta}(0) = \begin{bmatrix} \theta_1(0) \\ \dot{\theta}_1(0) \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Acceleration at t=0 can be calculated by:

0(0) = M-[6-V-6]

M= [limit delimie et li'(met mi) limit delimie

 $l_{i}m_{i} + l_{i}l_{i}m_{i}c_{i}$ = $\begin{bmatrix} 2.8349 & 0.1676 \\ 0.1676 & 1.25 \end{bmatrix}$

 $-7 \text{ M}^{-1} = \begin{bmatrix} 0,3556 & -0,0476 \\ -0,0476 & 0,8064 \end{bmatrix}$

7(0) = 0

 $V = \begin{bmatrix} -m_1 & l_1 & l_2 & l_2 & l_3 & l_4 & l_4 & l_5 & l_4 \\ m_1 & l_1 & l_2 & l_4 & l_4 & l_5 & l_4 \\ \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$ $G = \begin{bmatrix} m_2 & l_2 & g_{11} & l_1 & l_4 & l_4 & l_4 & l_4 & l_4 \\ m_2 & l_2 & g_{12} & l_4 & l_4 & l_4 & l_4 \end{bmatrix} = \begin{bmatrix} 39, 1928 \\ -24, 525 \end{bmatrix}.$

 $=> \theta(0) = \begin{bmatrix} -15, 1035 \\ 21, 6435 \end{bmatrix}$

besides that,
$$\dot{A}(t + \Delta t)$$

$$\dot{\theta}(t + \Delta t) = \dot{\theta}(t) + \ddot{\theta}(t) \Delta t$$

$$\dot{\theta}$$
 $(0 + \Delta t) = \dot{\theta}(0) + \dot{\theta}(0) \Delta t \omega \dot{\tau}(\Delta t) = \begin{bmatrix} -15, 1036 \\ 21, 6435 \end{bmatrix} - \Delta t$

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$$\theta(0 + \Delta t) = \theta(0) + \dot{\theta}(0) \Delta t + \dot{\theta}(0) \Delta t^{2}$$

$$(2) + (\Delta t) = \begin{bmatrix} 30 \\ 150 \end{bmatrix} + 0 + \frac{1}{2} \begin{bmatrix} -17, 1037 \\ 21, 6437 \end{bmatrix} \Delta t^{2}$$

Replace It to t we obtained the trajectories

$$\Phi(t) = \frac{1}{2} \left[-\frac{15}{21.6435} \right] t^2 + \left[\frac{30}{150} \right].$$