MMC HW 8   continued in HW7

[Extra Pts prob]
5) For real parameter $m_1 = 5\text{kg}$, $m_2 = 5\text{kg}$, the known mass parameter is assumed to be $\widehat{m_1} = 7\text{kg}$ $\widehat{m_2} = 3\text{kg}$, Do computed torque control. and
   In order to reduce the position error, design adaptive controller or sliding mode controller