MMC HW3

Using MatLab,

1. Program Forward Kinematics for Puma 560 robot

with your assumed values for DRW00001f0442de

and DRW00001f0442e0=> DRW00001f0442e2

then, when DRW00001f0442e4=[ 30deg 90 90 30 30 30], Find DRW00001f0442e6

2. Program Inverse Kinematics for Puma 560 robot.

Find the 8 solution sets corresponding to the DRW00001f0442e8of prob. 1.

and make sure that one among your solution sets must be

[ 30deg 90 90 30 30 30].