

Advanced Linear Algebra

Chapter 4: Determinant

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Definition

- $M_n(F)$: the set of all $n \times n$ matrices defined over F
- A function $D : M_n(F) \rightarrow F$ is called a **determinant** function if the three conditions are satisfied.

1) **n -linearity**:

$$D \left(\begin{bmatrix} \alpha \mathbf{a}_1 + \beta \mathbf{b}_1 \\ M \end{bmatrix} \right) = \alpha D \left(\begin{bmatrix} \mathbf{a}_1 \\ M \end{bmatrix} \right) + \beta D \left(\begin{bmatrix} \mathbf{b}_1 \\ M \end{bmatrix} \right)$$

2) **alternating property**: For $i \neq j$, let $B = P_{ij}A$ with row interchanging P_{ij} .

$$D(B) = -D(A).$$

3) **identity matrix**:

$$D(I) = 1.$$

Additional Properties (1)

4) If the two rows of A are equal, then $\det(A) = 0$.

$$\begin{vmatrix} a & b \\ a & b \end{vmatrix} = 0.$$

5) Subtracting a multiple of one row from another row preserves $\det(A)$.

$$\begin{vmatrix} a - lc & b - ld \\ c & d \end{vmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix}.$$

6) If A has a zero row, then $\det(A) = 0$.

$$\begin{vmatrix} 0 & 0 \\ c & d \end{vmatrix} = 0.$$

Additional Properties (2)

- 7) If A is triangular, $\det(A)$ is the product of all the diagonal entries.

$$\begin{vmatrix} a & b \\ 0 & d \end{vmatrix} = ad.$$

- 8) $\det(A) = 0$ if and only if A is singular.

- 9) Product of two matrices:

$$\det(AB) = \det(A) \det(B).$$

- 10) Transpose:

$$\det(A^T) = \det(A).$$

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2×2 Case

$$\begin{aligned}\begin{vmatrix} a & b \\ c & d \end{vmatrix} &= \begin{vmatrix} a & 0 \\ c & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & d \end{vmatrix} \\ &= \begin{vmatrix} a & 0 \\ c & 0 \end{vmatrix} + \begin{vmatrix} a & 0 \\ 0 & d \end{vmatrix} + \begin{vmatrix} 0 & b \\ c & 0 \end{vmatrix} + \begin{vmatrix} 0 & b \\ 0 & d \end{vmatrix} \\ &= ad \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + bc \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} \\ &= ad - bc.\end{aligned}$$

3×3 Case

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \\ = \begin{vmatrix} a_{11} & & \\ & a_{22} & \\ & & a_{33} \end{vmatrix} + \begin{vmatrix} & a_{12} & \\ & & a_{23} \\ a_{31} & & \end{vmatrix} + \begin{vmatrix} & & a_{13} \\ a_{21} & & \\ & a_{32} & \end{vmatrix} \\ + \begin{vmatrix} a_{11} & & \\ & & a_{23} \\ & a_{32} & \end{vmatrix} + \begin{vmatrix} & & a_{13} \\ & a_{22} & \\ a_{31} & & \end{vmatrix} + \begin{vmatrix} & a_{12} & \\ a_{21} & & \\ & & a_{33} \end{vmatrix} \\ = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} \\ - a_{11}a_{23}a_{32} - a_{13}a_{22}a_{31} - a_{12}a_{21}a_{33}.$$

Permutation

- Let S_n be the set of all permutations of $\{1, 2, \dots, n\}$.
- Expression: a permutation σ of order 5 can be represented in these ways -

$$\sigma = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 2 & 1 & 4 & 5 & 3 \end{pmatrix},$$

or

$$\sigma(1) = 2, \sigma(2) = 1, \sigma(3) = 4, \sigma(4) = 5, \sigma(5) = 3.$$

- Any permutation can be represented as a product of inversions:

$$\sigma = (3\ 4)(3\ 5)(1\ 2).$$

(Note that there are multiple representations for a σ , but the parity of the # of inversions is invariant.)

Permutation Matrix

- A matrix P is called a permutation matrix if it is a $(0, 1)$ -matrix such that 1 appears exactly once at every row and every column.
- An $n \times n$ permutation matrix P_σ corresponding to a permutation σ on $\{1, \dots, n\}$ is given by

$$(P_\sigma)_{i,j} = \begin{cases} 1, & \text{if } j = \sigma(i) \\ 0, & \text{otherwise.} \end{cases}$$

- Example

$$\sigma = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} \quad \leftrightarrow \quad P_\sigma = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

General Formula for Determinant

- Let S_n be the set of all permutations of $\{1, 2, \dots, n\}$.
- The determinant function of an $n \times n$ matrix $A = (a_{i,j})_{1 \leq i,j \leq n}$ is given by

$$\det(A) = \sum_{\sigma \in S_n} a_{1,\sigma(1)} a_{2,\sigma(2)} \cdots a_{n,\sigma(n)} \det(P_\sigma)$$

- However, it may be too complex to compute the determinant of a large matrix in this way.

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Determinant for 3×3 Matrices

$$\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \\ = \begin{vmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \\ = \begin{vmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & 0 & 0 \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \\ = \begin{vmatrix} a_{11} & 0 & 0 \\ 0 & a_{22} & a_{23} \\ 0 & a_{32} & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & a_{12} & 0 \\ a_{21} & 0 & a_{23} \\ a_{31} & 0 & a_{33} \end{vmatrix} + \begin{vmatrix} 0 & 0 & a_{13} \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & 0 \end{vmatrix}.$$

(**Exercise:** Expand with respect to the second row.)

Formula for $n \times n$ Matrices

- M_{ij} (Minor of a_{ij} in A):
the determinant of the $(n - 1) \times (n - 1)$ matrix after removing the i th row and the j th column from A
- A_{ij} (cofactor of a_{ij} in A):

$$A_{ij} = (-1)^{i+j} M_{ij}$$

- Laplace expansion for determinant:

$$\det(A) = \sum_{j=1}^n a_{ij} A_{ij}$$

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Application 1: Calculation of Inverse

- Note that

$$\sum_{j=1}^n a_{ij} A_{kj} = \begin{cases} 0, & \text{if } i \neq k \\ \det(A), & \text{if } i = k. \end{cases}$$

- Therefore,

$$\begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{n1} & \cdots & a_{nn} \end{bmatrix} \underbrace{\begin{bmatrix} A_{11} & \cdots & A_{n1} \\ \vdots & \ddots & \vdots \\ A_{1n} & \cdots & A_{nn} \end{bmatrix}}_{\text{adj}(A): \text{adjoint matrix of } A}$$
$$= \begin{bmatrix} \det(A) & & \\ & \ddots & \\ & & \det(A) \end{bmatrix}$$

Application 2: Cramer's Rule

- For an $n \times n$ matrix A , $\mathbf{x} = [x_1 \ \cdots \ x_n]^T$ and $\mathbf{b} = [b_1 \ \cdots \ b_n]^T$, assume that $A\mathbf{x} = \mathbf{b}$.
- Let \mathbf{a}_i be the i th column of A . Insert \mathbf{b} at the j th column.

$$\begin{aligned} & \det(\mathbf{a}_1 \ \cdots \ \mathbf{b} \ \cdots \ \mathbf{a}_n) \\ &= \det\left(\mathbf{a}_1 \ \cdots \ \sum_{k=1}^n x_k \mathbf{a}_k \ \cdots \ \mathbf{a}_n\right) \\ &= \sum_{k=1}^n \det(\mathbf{a}_1 \ \cdots \ x_k \mathbf{a}_k \ \cdots \ \mathbf{a}_n) \\ &= x_j \cdot \det(A). \end{aligned}$$

- Therefore,

$$x_j = \frac{\det[\mathbf{a}_1 \ \cdots \ \mathbf{b} \ \cdots \ \mathbf{a}_n]}{\det(A)}.$$

General Form of Laplace Expansion (1)

- Fix m row in A . Then,

$$\begin{aligned}\det(A) = \sum_{\{j_1, \dots, j_m\} \subseteq \mathbb{Z}_n} & \det(A(i_1, \dots, i_m)(j_1, \dots, j_m)) \\ & \cdot \det(A^c(i_1, \dots, i_m)(j_1, \dots, j_m)) \\ & \cdot (-1)^{i_1 + \dots + i_m + j_1 + \dots + j_m}\end{aligned}$$

where $A(i_1, \dots, i_m)(j_1, \dots, j_m)$ is the $m \times m$ submatrix of A consisting of the intersections of the rows i_1, \dots, i_m and the columns j_1, \dots, j_m , and A^c is the $(n - m) \times (n - m)$ submatrix consisting of the remained rows and columns.

General Form of Laplace Expansion (2)

- Let

$$A = \begin{bmatrix} 2 & 3 & 1 & 0 \\ 1 & 1 & 0 & 0 \\ 1 & 3 & 2 & 1 \\ 0 & 1 & 2 & 1 \end{bmatrix}.$$

- Expansion with $i_1 = 1$ and $i_2 = 2$:

$$\begin{aligned} \det(A) = & \begin{vmatrix} 2 & 3 \\ 1 & 1 \end{vmatrix} \cdot \begin{vmatrix} 2 & 1 \\ 2 & 1 \end{vmatrix} (-1)^{1+2+1+2} + \begin{vmatrix} 2 & 1 \\ 1 & 0 \end{vmatrix} \cdot \begin{vmatrix} 3 & 1 \\ 1 & 1 \end{vmatrix} (-1)^{1+2+1+3} \\ & + \begin{vmatrix} 2 & 0 \\ 1 & 0 \end{vmatrix} \cdot \begin{vmatrix} 3 & 2 \\ 1 & 2 \end{vmatrix} (-1)^{1+2+1+4} + \begin{vmatrix} 3 & 1 \\ 1 & 0 \end{vmatrix} \cdot \begin{vmatrix} 1 & 1 \\ 0 & 1 \end{vmatrix} (-1)^{1+2+2+3} \\ & + \begin{vmatrix} 3 & 0 \\ 1 & 0 \end{vmatrix} \cdot \begin{vmatrix} 1 & 2 \\ 0 & 2 \end{vmatrix} (-1)^{1+2+2+4} + \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} \cdot \begin{vmatrix} 1 & 3 \\ 0 & 1 \end{vmatrix} (-1)^{1+2+3+4} \end{aligned}$$

- Exercise:** Expand with $i_1 = 1$ and $i_2 = 3$, and calculate $\det(A)$.

Volume of a Parallelogram

- In the right-angled system, the area (or volume) of the parallelogram represented by $\mathbf{a} = (a_1, a_2)$ and $\mathbf{b} = (b_1, b_2)$ is given by $\det(A)$, where

$$A = \begin{bmatrix} \mathbf{a} \\ \mathbf{b} \end{bmatrix}.$$