

# Reese Critchlow

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## EDUCATION

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### University of British Columbia

Bachelor of Applied Science in Engineering Physics, GPA: 4.0

September 2020 – December 2025 (expected)

Vancouver, BC, Canada

## EXPERIENCE

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### Research Engineer Co-op

September 2023 – Present

UBC Molecular Mechatronics Lab

Vancouver, BC

- Developing a control and feedback system for a robotic hand, using a Raspberry Pi, electrical components, and embedded systems, advancing research in soft humanoid robotics.
- Creating firmware in C, PCBs in Altium, and hardware in OnShape to develop 3 new soft force sensors to the Honda Robotics Institute, for use on the Asimo robot.
- Investigating the use of various systems for improved robotic hand grasping, using principles in control theory and machine learning.

### Software Developer Co-op

May 2023 – August 2023

D-Wave Systems

Burnaby, BC

- Designed improvements to testing infrastructures in Common Lisp, Parachute, and Jenkins to increase the number of readable, comprehensive, and informative test results by over 500% to over 40 developers and physicists.
- Handled the refactoring of a component of D-Wave's solver stack in Common Lisp and Redis, reducing compute usage and increasing efficiency of systems.
- Analyzed the viability of new approaches to quantum processor development using software analysis, giving staff scientists the potential to increase chip yield.

### Software Developer Co-op

January 2022 – April 2022

Brave Technology Coop

Vancouver, BC

- Built an internal web app in React to streamline product provisioning and manage IoT devices, reducing the amount of labour between time of sale and order delivery.
- Constructed REST APIs in Node.js/Express.js to integrate services such as AWS, Twilio, Particle IoT, and ClickUp, allowing better integration with existing software systems.
- Integrated APIs with a PostgreSQL database to translate data between the company's backend and the frontend, improving data access.

## PROJECTS

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### License Plate Identifying Robot

June 2020 – Present

- Constructed control software in Python and ROS for a simulated robot in a Gazebo environment.
- Implemented a neural network in TensorFlow to classify the driving state of on-robot camera images in order to navigate a road network, as well as a second network to recognize characters from images of car license plates.
- Identified environmental features and reduced dimensionality of images using OpenCV and computer vision techniques to improve accuracy and decrease data input to neural networks.

## VOLUNTEERING AND COMMUNITY INVOLVEMENT

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### Club Lead

September 2023 – Present

UBC Nordic Ski Team

Vancouver, BC

- Managing the logistics, training plan, coaching, finances, fundraising and team dynamics of a competitive Nordic ski team with 34 rostered athletes.
- Working to foster a team environment which values equity, diversity, and inclusion, as well as competitive performance, which has led to roster growth of over 60%.
- Coordinating the logistics for training camps and race trips for all club athletes, allowing both novice skiers to develop racing skills at local races and seasoned skiers to compete at a national collegiate level.

## TECHNICAL SKILLS

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**Languages:** Python, Common Lisp, Java, Javascript, C++, C, HTML, CSS

**Frameworks & Libraries:** React, Node.js, Parachute, Express.js, REST APIs

**Developer Tools:** Git, Emacs, Linux, Jenkins, Atlassian Suite

**Miscellaneous:** Embedded Systems, Redis, Altium, OnShape, ROS, Raspberry Pi, Twilio