

PHYS 301 Notes  
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## Midterm 1

### Calculus Review

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#### Spherical Coordinates:

Sometimes, spherical coordinates are easier to work with than cartesian coordinates. When using spherical coordinates, there are some key things to note:

1. The coordinates themselves::  
 $\phi$ : Equatorial Azimuth  $[0, 2\pi]$  (from the “ $x$ ” axis)  
 $\theta$ : Axial Azimuth  $[0, \pi]$  (from the “ $z$ ” axis)  
 $r$ : Radial Distance

2. The infinitesimal displacement is different:

$$d\vec{l} = dr \hat{r} + r d\theta \hat{\theta} + r \sin \theta d\phi \hat{\phi}$$

3. The volume element is different:

$$d\tau = r^2 \sin \theta dr d\theta d\phi$$

Cylindrical Coordinates:: See textbook, this would be too redundant.

#### Rules for Irrotational Fields/Conservative Fields:

1.  $\vec{\nabla} \times \vec{F} = \vec{0}$  everywhere.
2.  $\int_a^b \vec{F} \cdot d\vec{l}$  is independent of path, for any given end points.
3.  $\oint \vec{F} \cdot d\vec{l} = 0$  for any closed loop.
4.  $\vec{F}$  is the gradient of some scalar function:  $\vec{F} = -\nabla V$ .

It is important to note that since  $\vec{E} = -\nabla V$ , then all electrostatic fields are irrotational.

#### Rules for Divergence-less fields.:

1.  $\vec{\nabla} \cdot \vec{F} = 0$  everywhere.
2.  $\int \vec{F} \cdot d\vec{a}$  is independent of surface, for any given boundary line.
3.  $\oint \vec{F} \cdot d\vec{a} = 0$  for any closed surface.
4.  $\vec{F}$  is the curl of some vector function.

## Electric Fields

It is important to recognize the notation in the Griffith's textbook, which is used primarily for this course when working with Fields and directions:

$\vec{r}$ : distance from the origin to a "field point".

$\vec{r}'$ : distance from the origin to the charge

$\vec{r}_{\text{sep}}$ : distance from the charge to the "field point"

Thus, it is given that  $\vec{r}_{\text{sep}} = \vec{r} - \vec{r}'$ .

Now, while working with Coulomb's law, we can define the electric field due to a point charge to be:

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{q}{||\vec{r}_{\text{sep}}||^2} \vec{r}_{\text{sep}}$$

Types of Field Integrations: There exist three main types of field integrations:

<u>Line Charge</u>	<u>Surface Charge</u>	<u>Volume Charge</u>
$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\lambda(\vec{r}')}{  \vec{r}_{\text{sep}}  ^2} \vec{r}_{\text{sep}} dl'$	$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\sigma(\vec{r}')}{  \vec{r}_{\text{sep}}  ^2} \vec{r}_{\text{sep}} da'$	$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{  \vec{r}_{\text{sep}}  ^2} \vec{r}_{\text{sep}} d\tau'$

Gauss's Law: Gauss's law is as follows:

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q_{\text{encl}}}{\epsilon_0} \qquad \vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

By knowing the geometry and symmetry of a situation however, Gauss's law can require no integration whatsoever. This is when we know that field is the same for every point on a surface.

## Electric Potential

The potential of a point in a field relative to another is defined as:

$$V(\vec{r}) \equiv - \int_{\mathcal{O}}^{\vec{r}} \vec{E} \cdot d\vec{l}$$

Which is often referred to as the potential difference between two points:

$$V(\vec{b}) - V(\vec{a}) = - \int_{\vec{a}}^{\vec{b}} \vec{E} \cdot d\vec{l}$$

It is also to be noted the relation between field and potential:

$$\vec{E} = -\nabla V$$

Remark: it is important to note that unlike electric field, electric potential is a scalar. It has no direction, and should be handled accordingly.

Potential can also be obtained for a volume charge:

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{||\vec{r}_{\text{sep}}||} d\tau'$$

Similar formulae can be extrapolated for line and surface charge distributions, analogous to those for electric fields.

## Work and Energy in Electrostatics

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To calculate the work that it takes to get from one point to another in a field, we can use a work integral. We can also employ the potential difference.

$$W = \int_{\mathbf{a}}^{\mathbf{b}} \vec{F} \cdot d\vec{l} = -Q \int_{\mathbf{a}}^{\mathbf{b}} \vec{E} \cdot d\vec{l} = Q[V(\vec{b}) - V(\vec{a})]$$

It is important to note that for the second form of this integral uses **negative**  $Q$ , not positive. This is because the integral by default describes the amount of work that the field does, not the work that is required. One can use a positive value of  $Q$  if trying to find out how much work the field does.

It is also to be noted that the potential of a system is the work that is required to create the system per unit charge.

Work and Point Charges: We can also describe the amount of work that it takes to assemble a collection of point charges:

$$W = \frac{1}{2} \sum_{i=1}^n q_i V(\vec{r}_i)$$