CSCI 466: Networks

Network Layer – Routing (Control Plane)

Reese Pearsall Fall 2022

*All images are stolen from the internet

Announcements

NO CLASS on Monday (10/24)

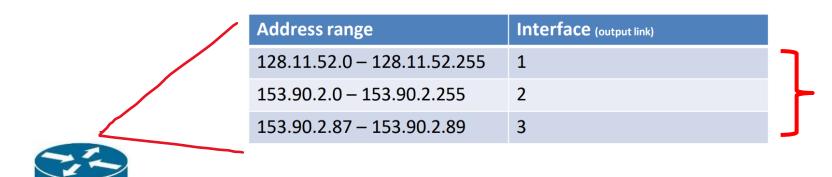
Email/DM me if you need to chat or have questions

PA2 due tonight* at 11:59 PM

→ You can submit it any time this weekend without a late pass and you won't lose points ©

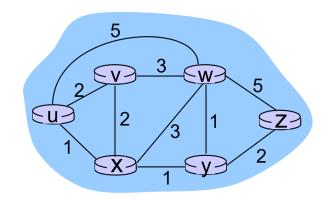
HW2 Released. Due one week from today (10/28)

Forwarding refers to moving packets from a **router's input** to appropriate **router output**, and is implemented in the <u>data plane</u>.



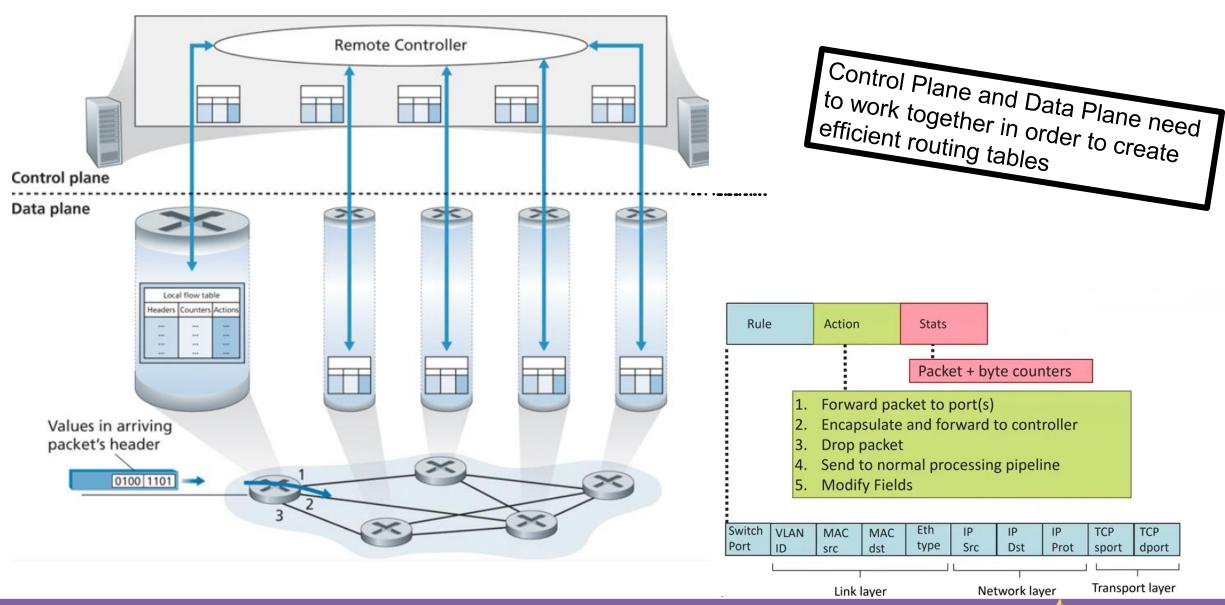
Ideally, this output links are the most optimal path to get to the destination

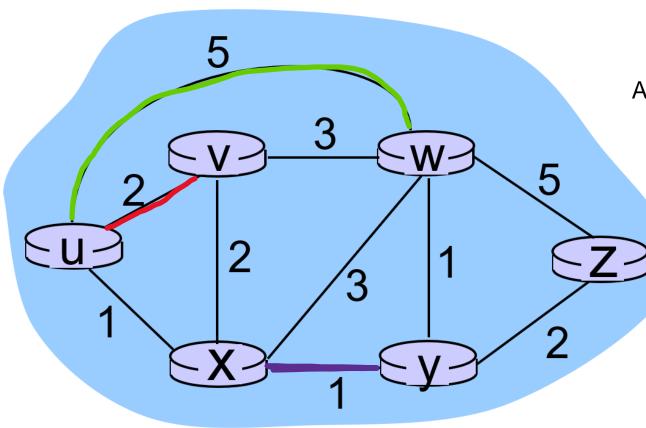
Routing refers to determining the route taken by packets from **source** to **destination**, and is implemented in the <u>control plane</u>.



What is the best way to get from **u** to **z**?

Generalized Forwarding and Software Defines Network (SDN)





An example network with 6 hosts/routers

What do the costs represent??

A graph G consists of N nodes

$$N = \{ u v x w y z \}$$

A node could be a host, a router, or a smaller network!

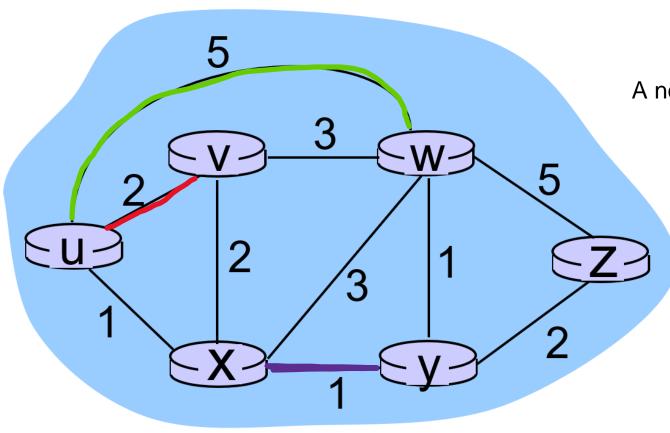
A graph consists of edges E

$$E_1$$
 (u,v) = 2

$$E_2$$
 (u,w) = 5

$$E_6(x,y) = 1$$

In most cases, edges will also have a **cost**



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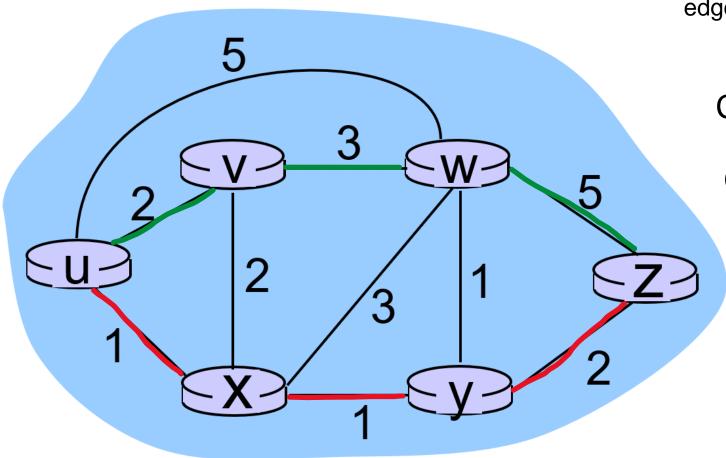
$$E_1$$
 (u,v) = 2

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In most cases, edges will also have a **cost**

What do the costs represent?? Physical distance, time needed, bandwidth, delay



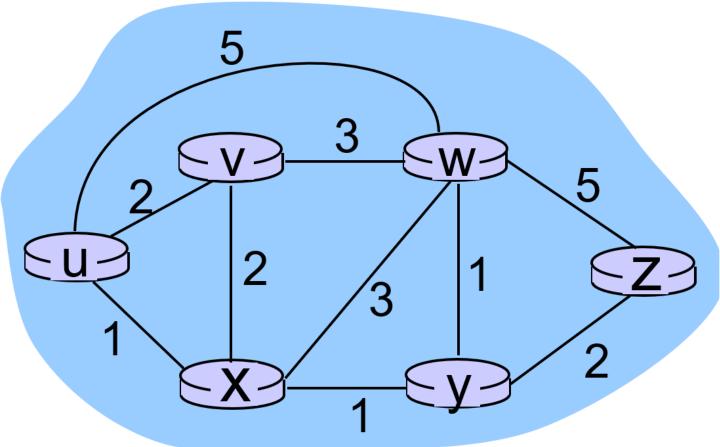
The cost from A to B is the **sum** of the edge weights of the path taken

$$C(u,z) = 1 + 1 + 2 = 4$$

$$C(u,z) = 2 + 3 + 5 = 10$$

If a packet needs to go from U to Z, we want it to take the most optimal path!

Routing algorithm: algorithm that finds the least cost path Do you know any?

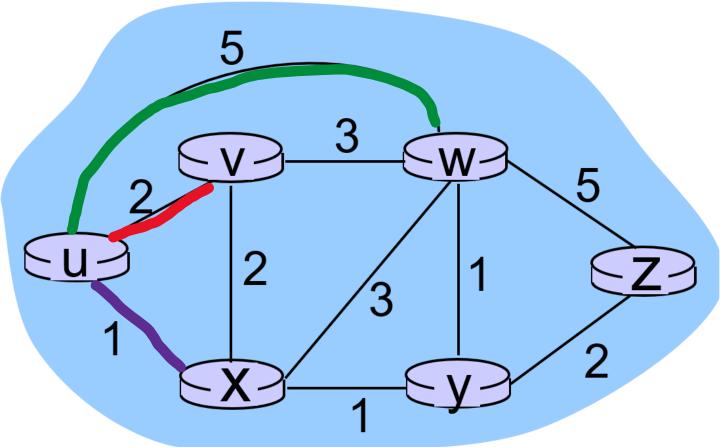


Dijkstra's algorithm is a shortest path algorithm that is guaranteed to find a solution

step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	2, u	5, u	1, u	N/A	N/A
1						
2						
3						
4						
5						

Goal: Find shortest path from u to z

N' is our current optimal path. We must start at u obviously

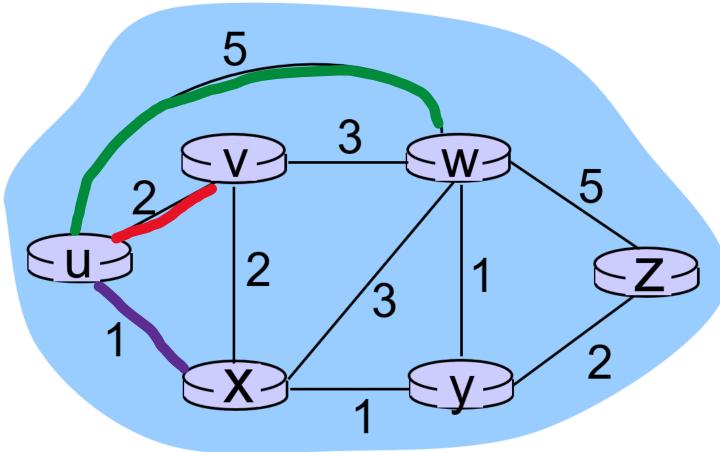


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0	u	2, u	5, u	1, u	N/A	N/A
1						
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3						
4						
5						

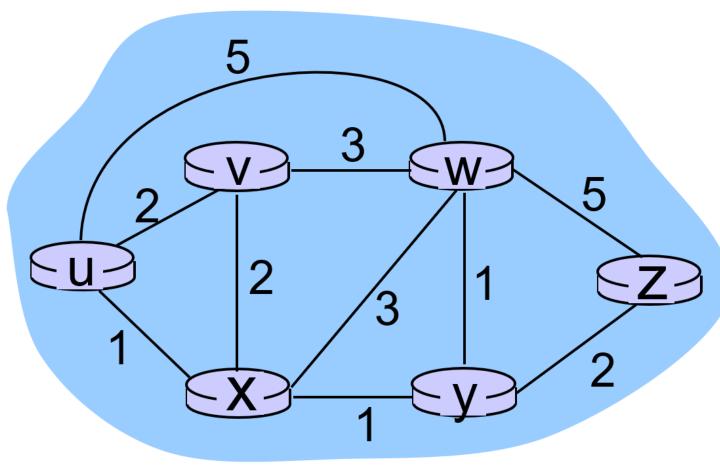
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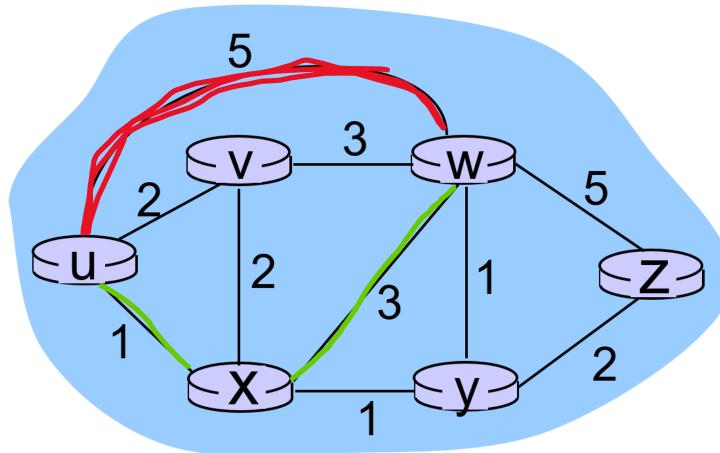
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step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	2, u	5, u	1, u	N/A	N/A
1				1		7
2			The path			
3			get adde path!	ed onto	our	
4			r			
5						



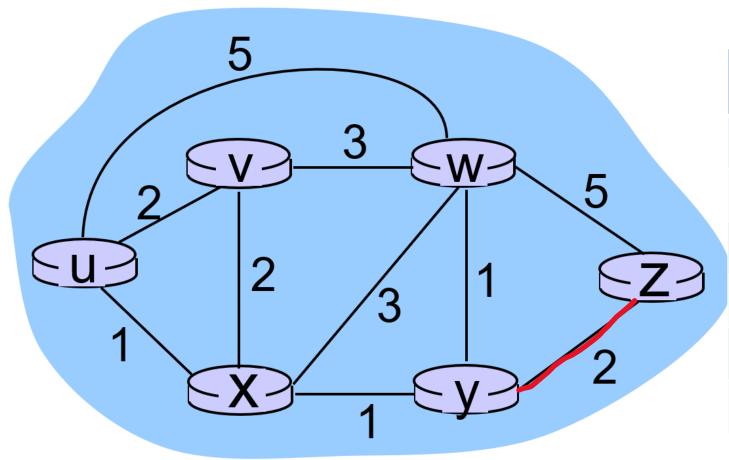
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step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	2, u	5, u	1, u	N/A	N/A
1	ux					
2						
3						
4						
5						



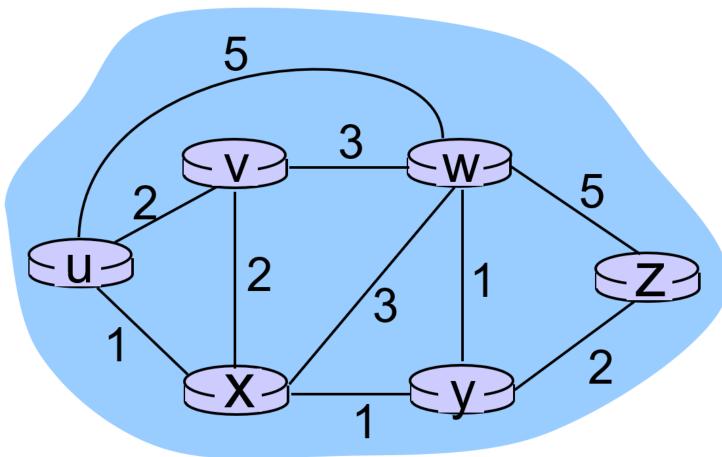
Goal: Find shortest path from u to z

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0	u	2, u	5, u	1 , u	N/A	N/A	
1	ux	2, u	4, x 🗸		2, x	N/A	
2		1	Tr	ne short	test path	from	
3	The shortest path from u to v is still the same		u to w is now 4 (trav through x) instead o				
4				•	4 cost		
5							



Goal: Find shortest path from u to z

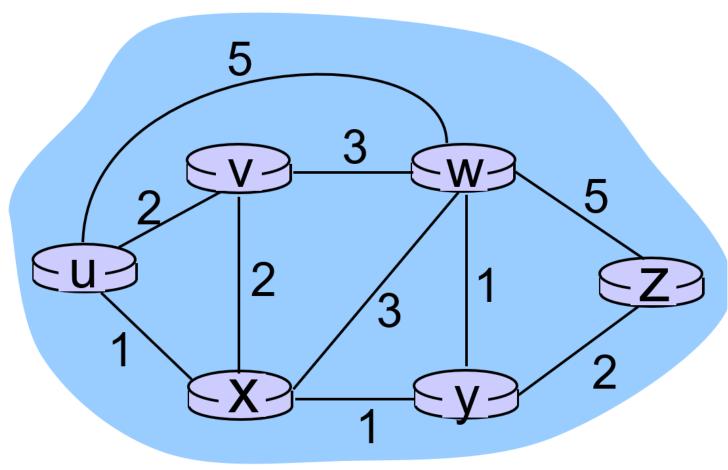
step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)		D(y), p(y)	D(z) p(z)	
0	u	2, u	5, u	1, u		N/A	N/A	
1	ux	2, u	4, x			2, x	N/A	
2	uxy	2, u	3, y				4,y	3
3		We als	so have			v that y		
4		a more optimal path			on our path, we can now			
5		to W r	ow		rea	ch z!		



Dijkstra's algorithm is a shortest path algorithm that is guaranteed to find a solution

step	N'	D(v), p(v)	D(w), p(w)	D(x), p(x)	D(y), p(y)	D(z), p(z)
0	u	2, u	5, u	1, u	N/A	N/A
1	ux	2, u	4, x		2, x	N/A
2	uxy	2, u	3, у			4,y
3	uxyv		3,у			4,y
4						
5						

NEW Goal: Find shortest path from u to any node



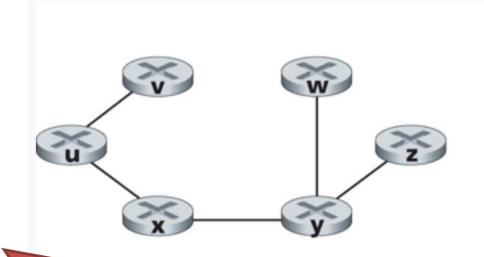
Dijkstra's algorithm is a shortest path algorithm that is guaranteed to find a solution

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0	u	2, u	5, u	1, u	N/A	N/A
1	ux	2, u	4, x		2, x	N/A
2	<mark>uxy</mark>	<mark>2, u</mark>	<mark>3, y</mark>			<mark>4,y</mark>
3	uxyv		3,у			4,y
4	uxyvw					4,у
5	uxyvwz					

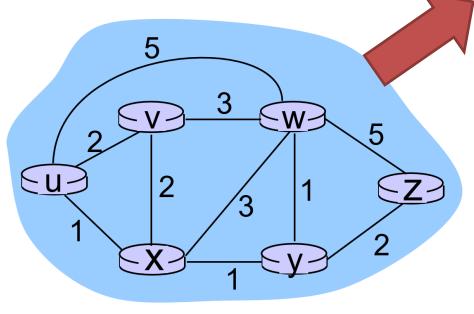
NEW Goal: Find shortest path from u to any node

LS complexity = O(N^2)

Issues? Concerns?



Destination	Link	
V	(u, v)	
W	(u, x)	
X	(u, x)	
У	(u, x)	
Z	(u, x)	





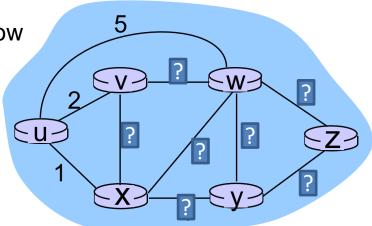
Routing table for node u

We will then run the same algorithm on each node to create its forwarding table!

LS is a **centralized** routing algorithm, which means it has global knowledge about all the edge of the network!

However, it is very likely we will not know information about the network beforehand!

Additionally, path costs can frequently change based on network congestion



- D_x(y) = estimate of least cost from x to y
 x maintains distance vector D_x = [D_x(y): y ∈ N]
- node x:

```
knows cost to each neighbor v: c(x,v) maintains its neighbors' distance vectors. For each neighbor v, x maintains D_v = [D_v(y): y \in N]
```

DV is **not** a centralized algorithm, which means that it does not require global knowledge about network edge costs

key idea:

from time-to-time, each node sends its own distance vector estimate to neighbors

when x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow min_v\{c(x,v) + D_v(y)\}\$$
for each node $y \in N$

Distance vector algorithm

iterative, asynchronous:

each local iteration caused by:
local link cost change
DV update message from
neighbor

distributed:

each node notifies neighbors only when its DV changes neighbors then notify their neighbors if necessary

each node:

wait for (change in local link cost or msg from neighbor) *recompute* estimates if DV to any dest has changed, *notify* neighbors

Comparison of LS and DV algorithms

message complexity

LS: with n nodes, E links, O(nE) msgs sent

DV: exchange between neighbors only

convergence time varies

speed of convergence

- LS: O(n²) algorithm requires O(nE) msgs
 - may have oscillations
- DV: convergence time varies
 - may be routing loops
 - count-to-infinity problem

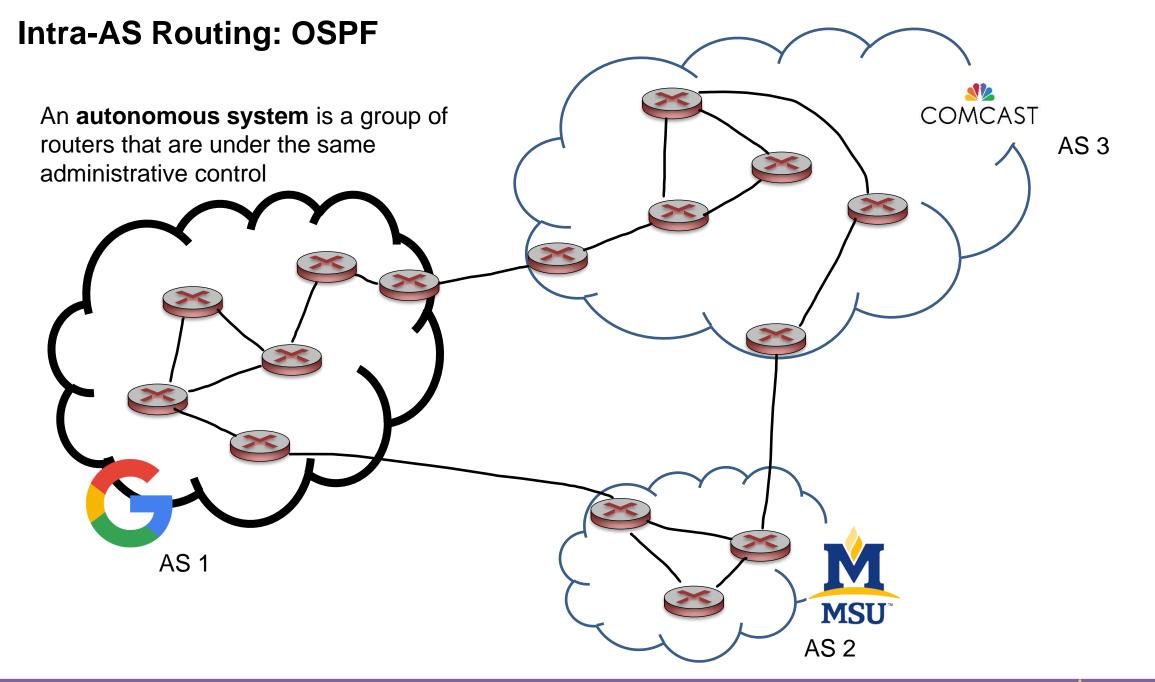
robustness: what happens if router malfunctions?

LS:

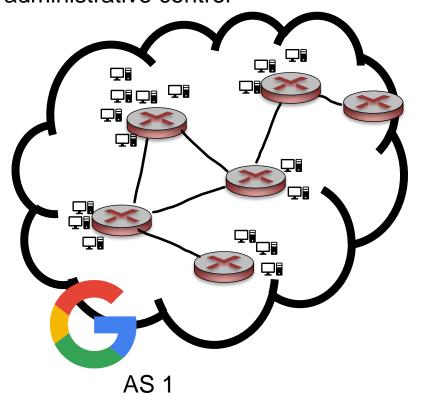
node can advertise incorrect *link* cost each node computes only its own table

DV:

- DV node can advertise incorrect path cost
- each node's table used by others
 error propagate thru
 network



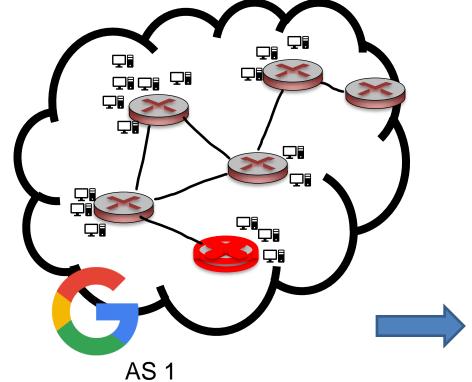
An **autonomous system** is a group of routers that are under the same administrative control



Open Shortest Path First

OSPF is a link-state protocol that uses flooding of link-state information and Dijkstra's least-cost algorithm

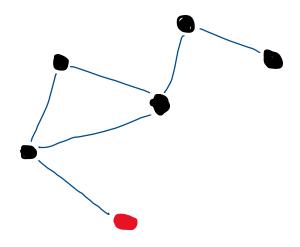
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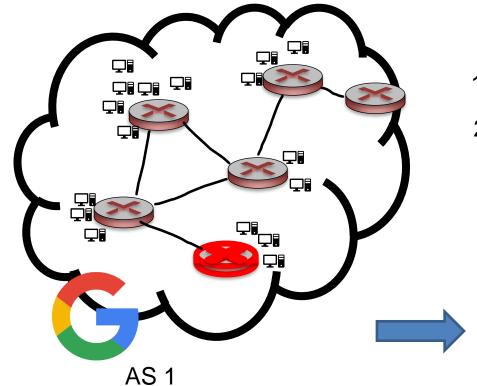


OSPF is a link-state protocol that uses flooding of link-state information and Dijkstra's least-cost algorithm

1. Each router constructors a topological map of the AS



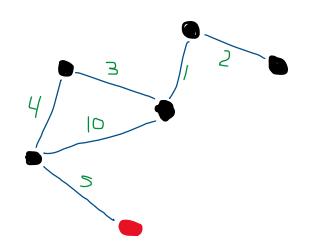
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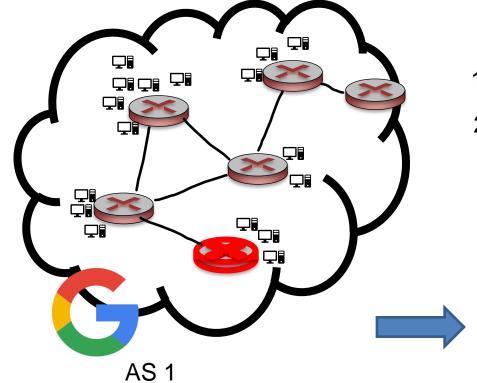
- 1. Each router constructors a topological map of the AS
- 2. Run Dijikstra's to determine shortest path to each subnet



(Edge costs will be set by a network administrator)

(could set all edges to be a cost of 1)

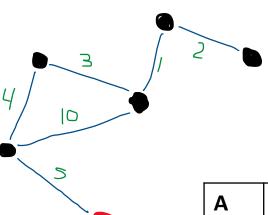
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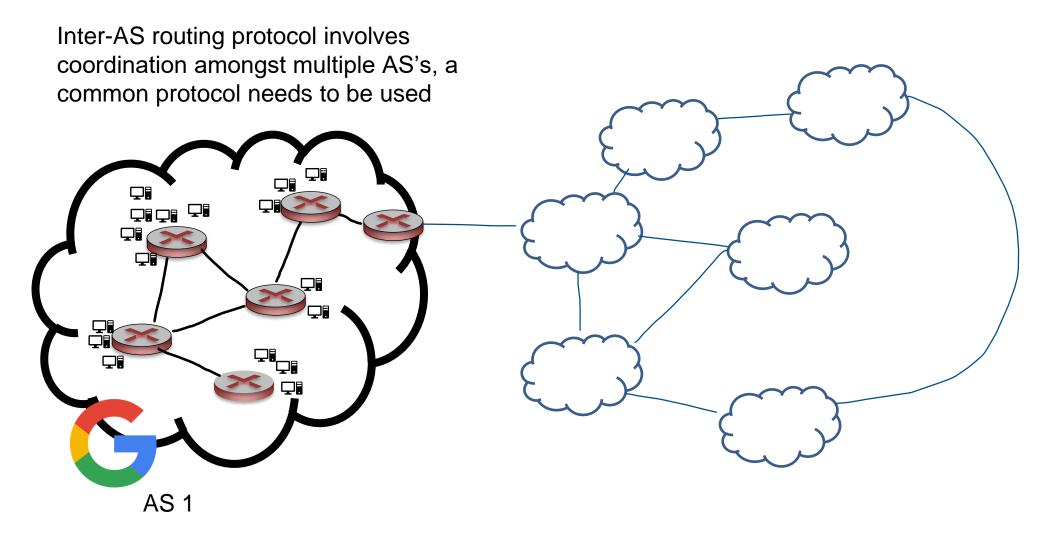


3. Fill in routing table

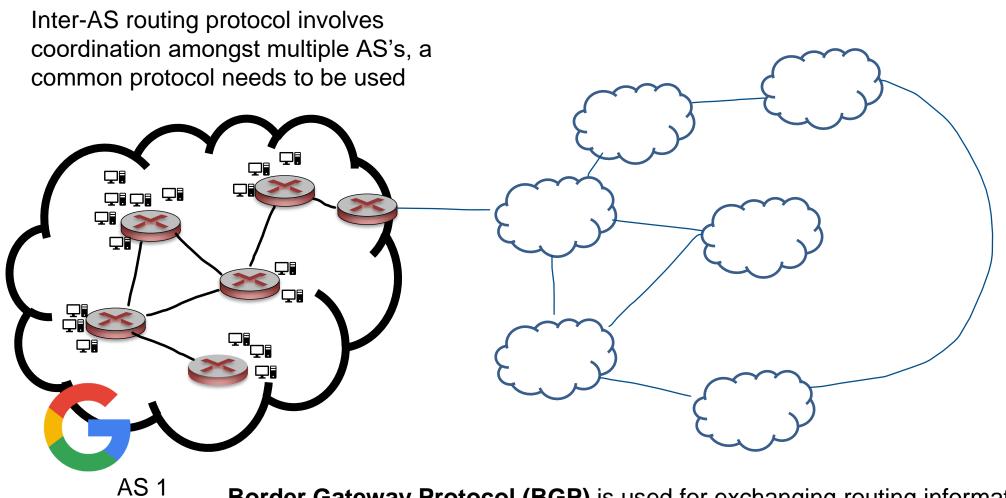
(Edge costs will be set by a network administrator)

(could set all edges to be a cost of 1)

Α	1
В	2
С	3
•••	•••



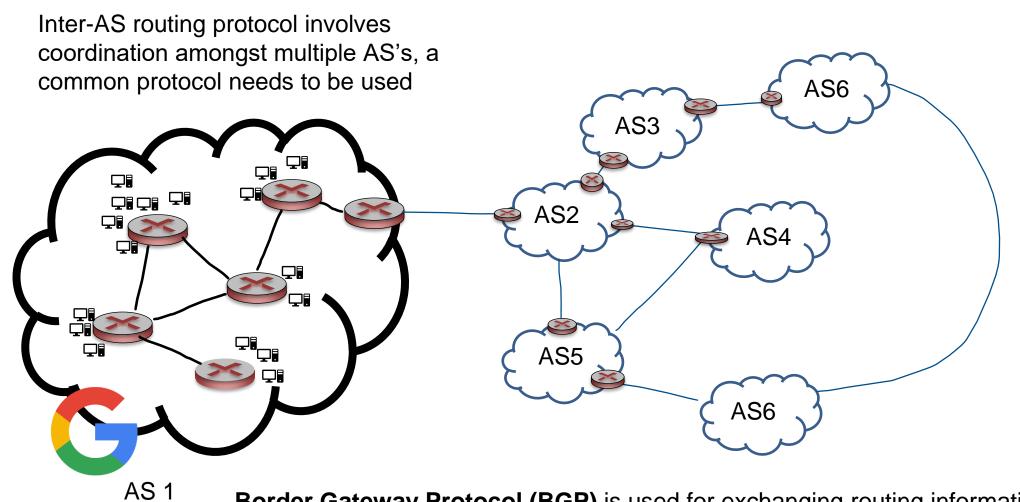
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BGP allows a router to tell other AS's that it exists and needs to be connected

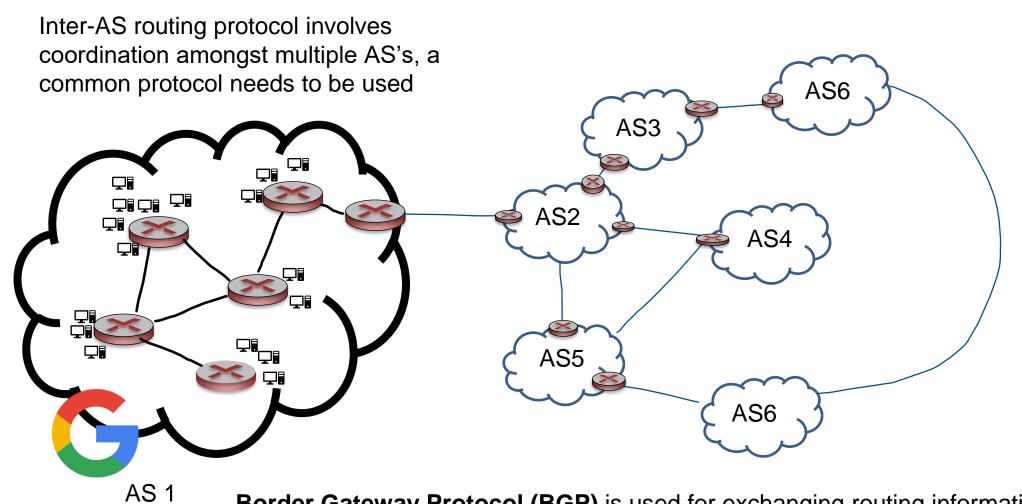
AS consists of gateway routers and internal routers



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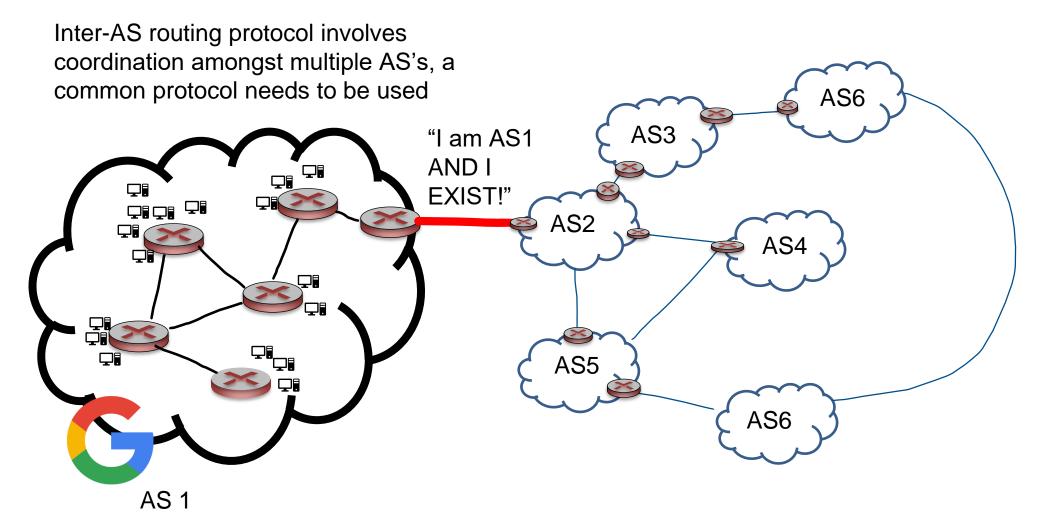
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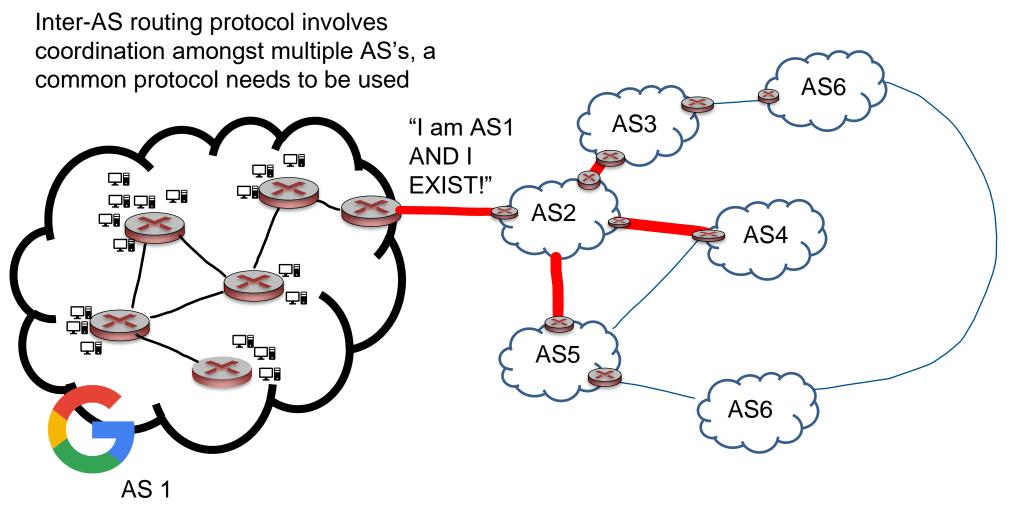
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"A1 EXISTS AND FOUND THROUGH AS2"

Announcements

HW2 due tonight

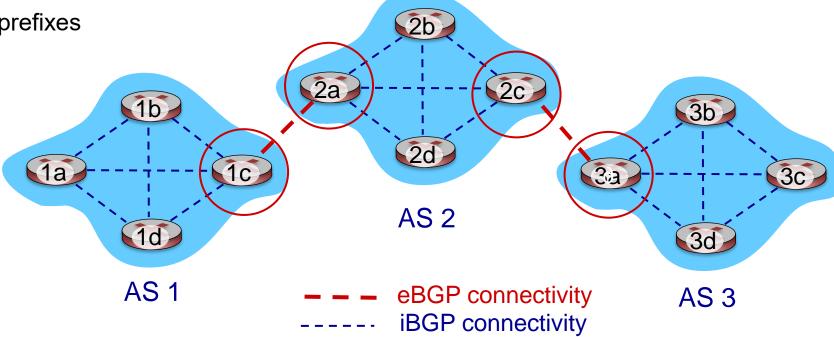
PA3 due Monday November 14th

BGP is the routing protocol used for routing amongst different ISPs + AS

Two important functions

→ Obtain prefix reachability information from neighboring ASs

→ Determine the "best" routes to the prefixes





gateway routers run both eBGP and iBGP protools

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Two important functions

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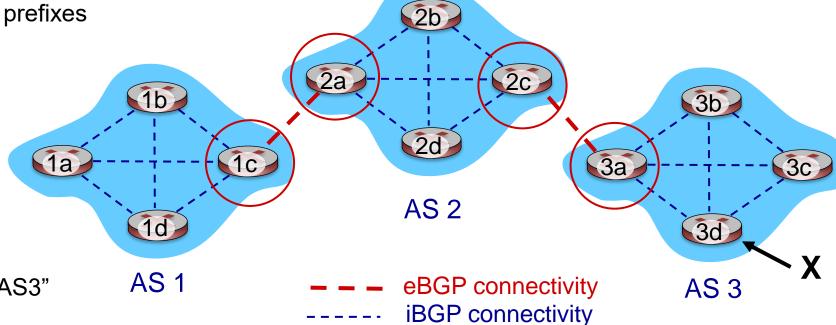
→ Determine the "best" routes to the prefixes

Prefix X connect

External BGP (eBGP)

 $3a \rightarrow 2c$ "Hey I have X"

2a → 1c "Hey AS 3 has X and I have AS3"



Internal BGP (iBGP)

 $2c \rightarrow 2b$

 $2c \rightarrow 2d$

 $2c \rightarrow 2a$



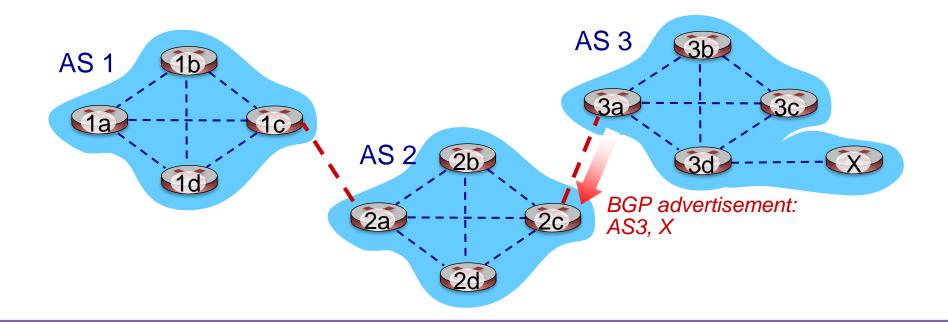
gateway routers run both eBGP and iBGP protools

BGP basics

- BGP session: two BGP routers ("peers") exchange BGP messages over semi-permanent TCP connection:
 - advertising paths to different destination network prefixes (BGP is a "path vector" protocol)

when AS3 gateway router 3a advertises path AS3,X to AS2 gateway router 2c:

AS3 promises to AS2 it will forward datagrams towards X



BGP basics

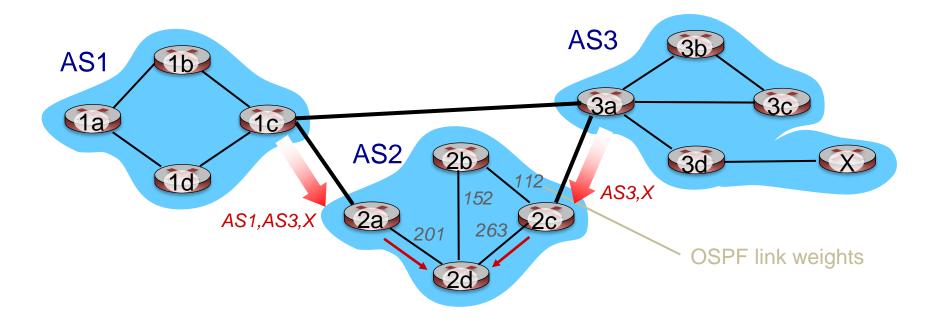
Advertisements with BGP also include "BGP attributes"

Prefix (ip address or subnet) + attributes = "route"

Two important attributes:

- AS-PATH: list of ASes through which prefix advertisement has passed
- NEXT-HOP: indicates specific internal-AS router to next-hop AS

Hot Potato Routing



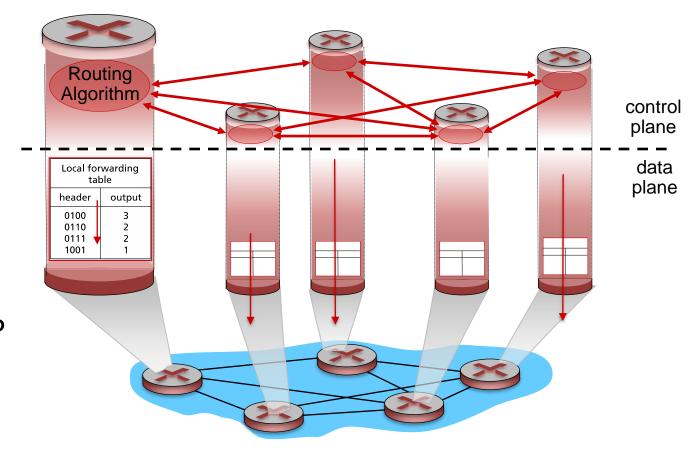
- 2d learns (via iBGP) it can route to X via 2a or 2c
- hot potato routing: choose local gateway that has least intradomain cost (e.g., 2d chooses 2a, even though more AS hops to X): don't worry about inter-domain cost!

ICMP (Internet Control Message Protocol)

used by hosts & routers to	_	0 1	
communicate network-level	<u>I ype</u>		description
	0	0	echo reply (ping)
information	3	0	dest. network unreachable
error reporting: unreachable	3	1	dest host unreachable
host, network, port, protocol	3	2	dest protocol unreachable
echo request/reply (used by	3	3	dest port unreachable
	3	6	dest network unknown
ping)	3	7	dest host unknown
network-layer "above" IP:	4	0	source quench (congestion
ICMP msgs carried in IP			control - not used)
datagrams	8	0	echo request (ping)
ICMP message: type, code plus	9	0	route advertisement
• ,	10	0	router discovery
first 8 bytes of IP datagram	11	0	TTL expired
causing error	12	0	bad IP header

Control Plane Wrap up

- approaches to network control plane
 - per-router control (traditional)
 - logically centralized control (software defined networking)
- traditional routing algorithms
 - routing: link state, distance vectors
 - implementation in Internet: OSPF, BGP
- Internet Control Message Protocol



Next:

- 1. Link Layer
- 2. Security
- 3. Random Topics in session, presentation, and physical layers