

Wheelshare: Smart Surface Classification for Accessible Routing through Built Environments

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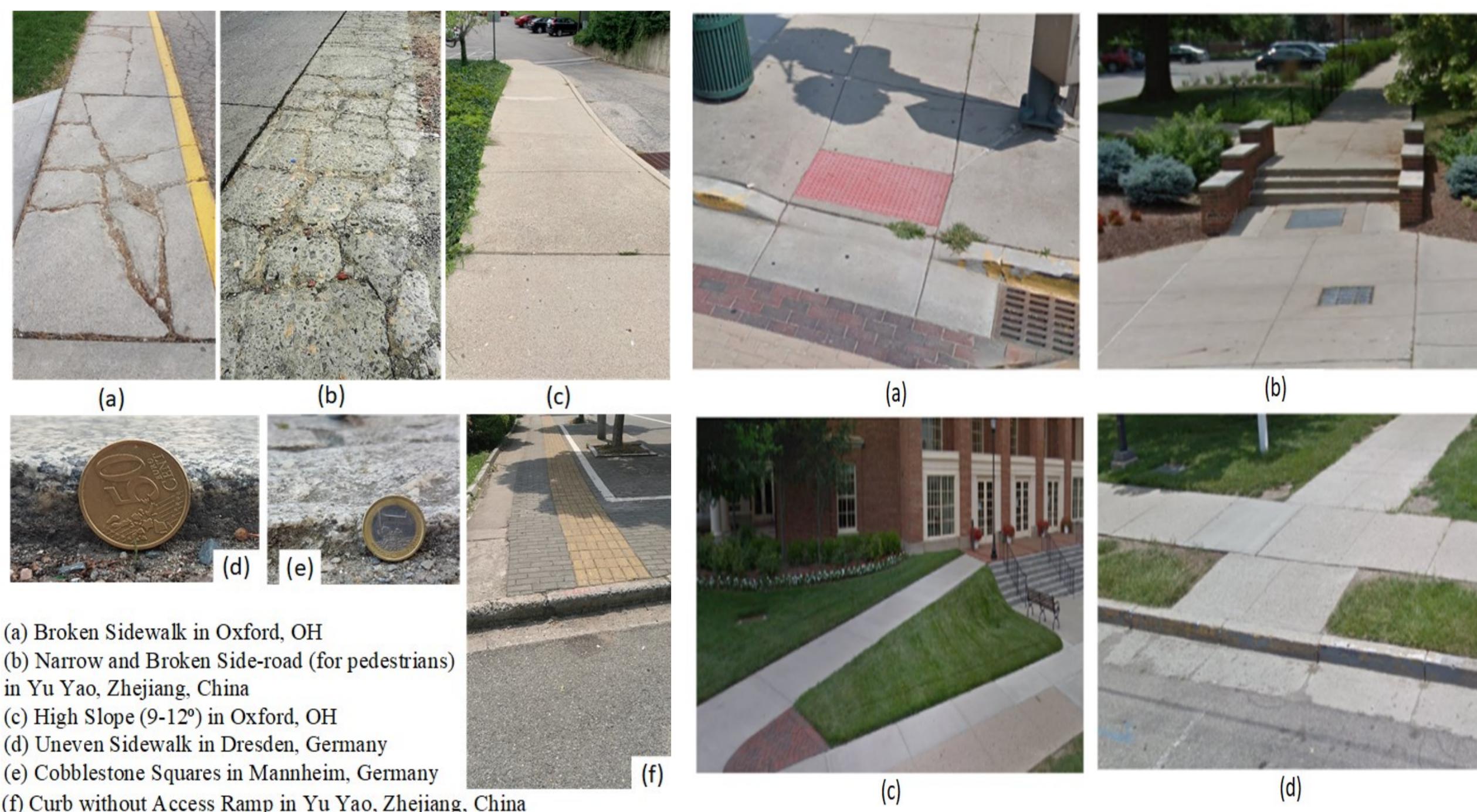


Introduction

- Mobility assistance for differently-abled individuals is an important basic need.
- We proposed the first machine learning enabled accessible routing system which classifies surfaces based on their vibration patterns.
- The system generates multiple routes based on a personalized profile on the type of wheelchair and the information about the environment collected from crowdsourcing
- Data analysis and training of the model uses accelerometer and gyroscope data contributed from 22 participants using a manual wheelchair.

Motivation

- Travelling can be challenging for wheelchair users due to unknown obstacles.
- Not all routes to a destination are friendly to a user who relies on "barrier-free access".
- Emergency situations can impede an individual's ability to travel, even more so when accessibility is required.

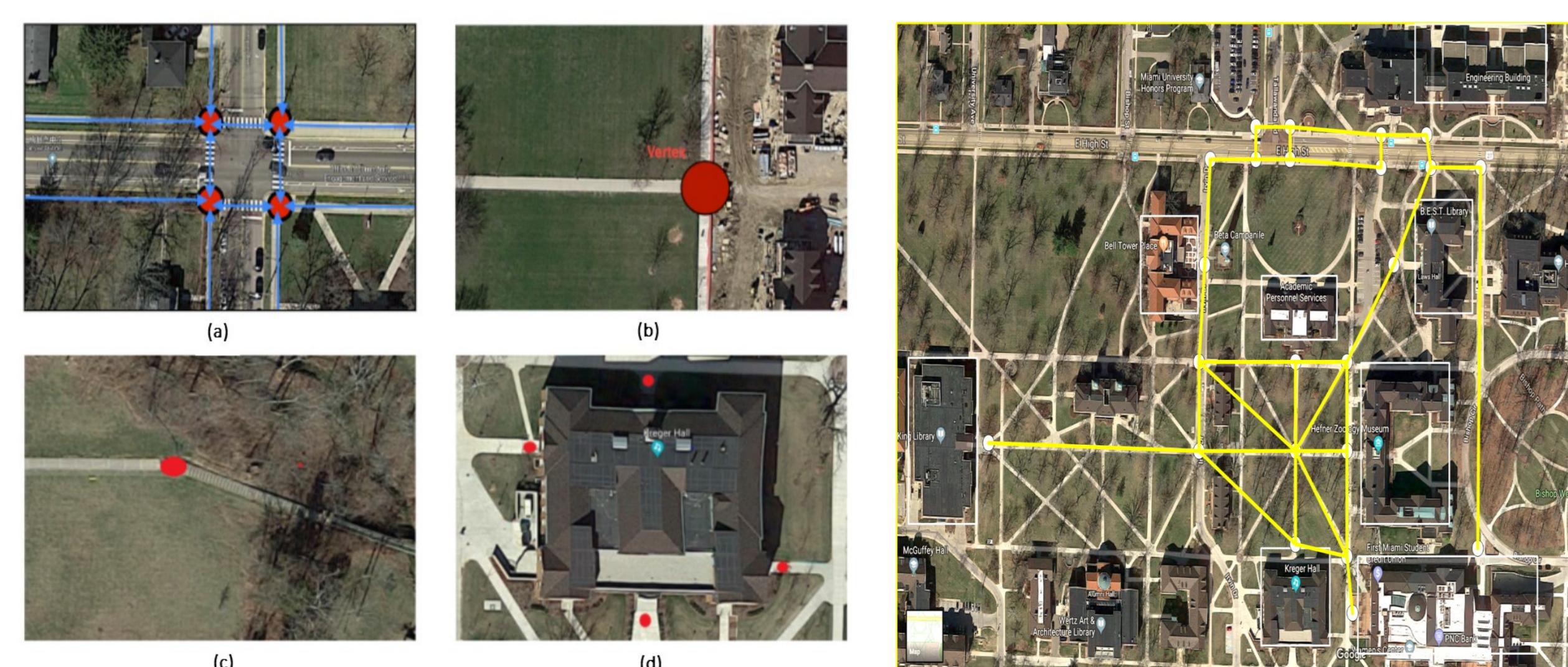


Main objectives

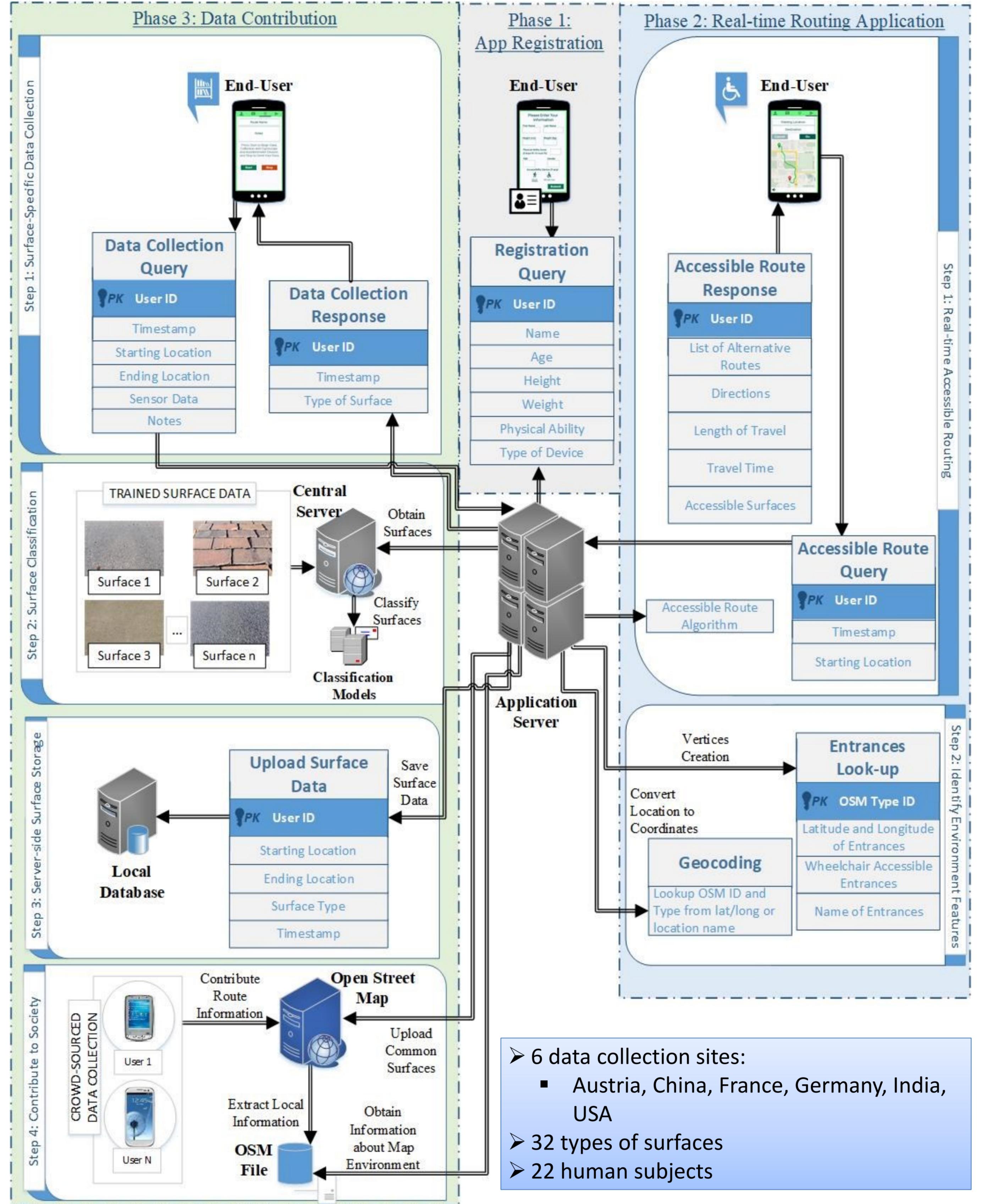
- Generate personalized, accessible routes that allow the user to easily traverse from one place to another.
- Identify multiple routes between two locations based on the built environment of the user
- Build user profile based on the type of wheelchair and preferences
- Use sensor data to identify surface accessibility with 100% accuracy
- Automate surface recognition to identify current surface at real-time.
- Contribute knowledge about the current environment to Open Street Map

Our Approach

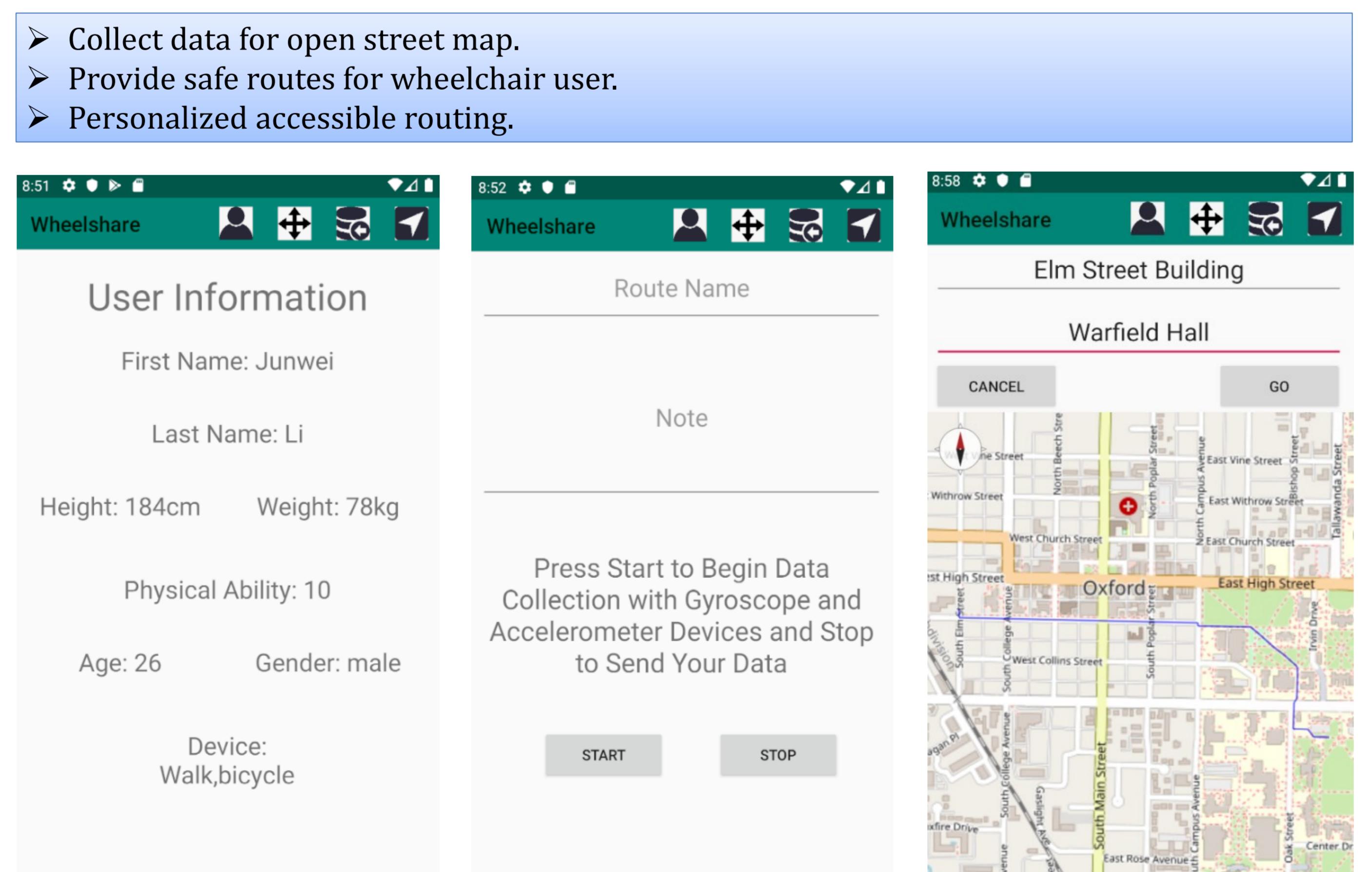
- We first generate an overlay graph on the map of the environment.
- We set vertices on changes in surface type (c), sidewalk junctions and T-intersections (a, b) and if starting from a building, locations of entrances (d)
- Separate scores are assigned depending on type and nature (broken or uneven) of surfaces, steepness of slopes, presence of stairs, height of curbs and presence of crosswalks (with and without pedestrian crossing signals)



Methodology



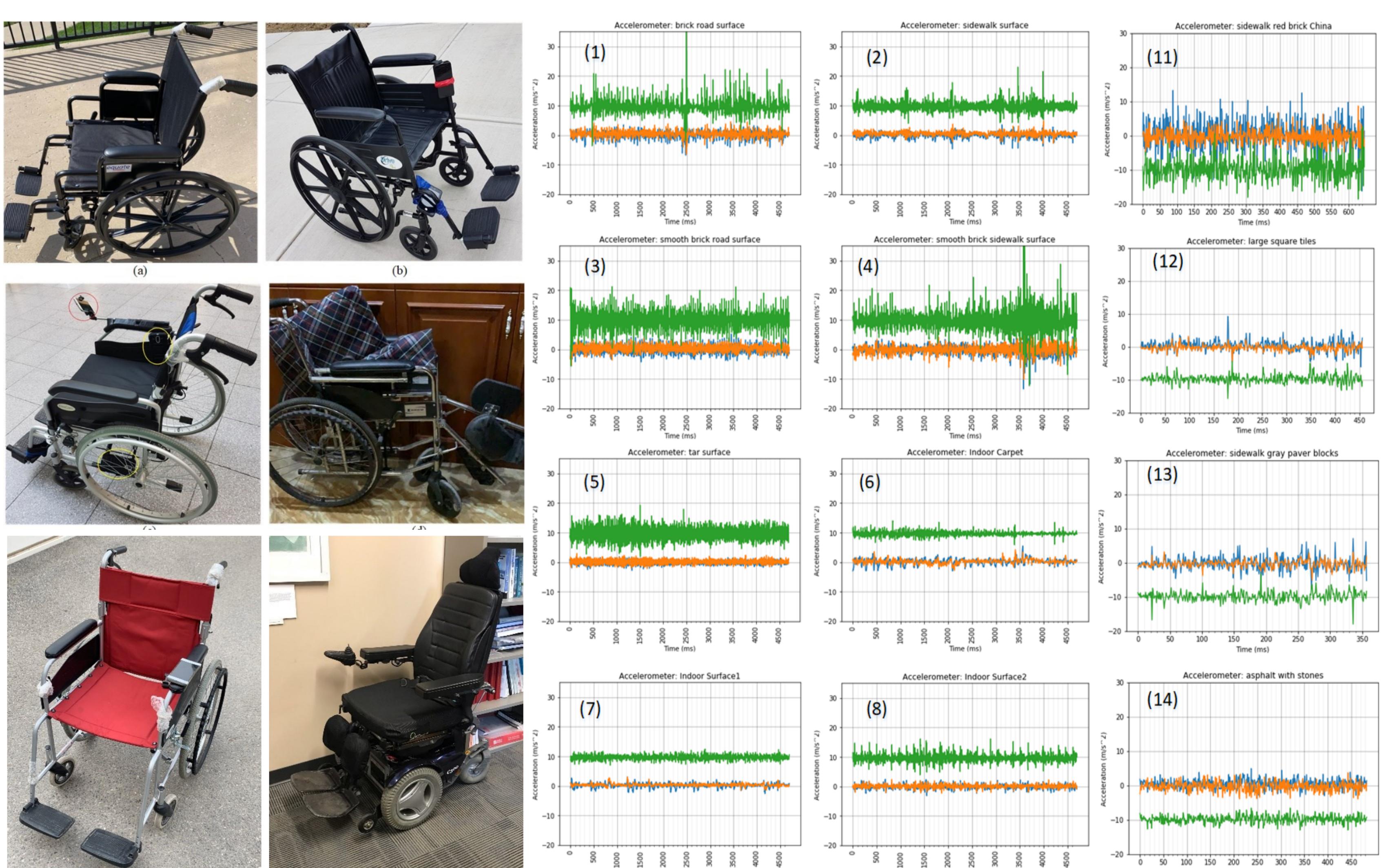
App User Interface



Data



Experiment



Conclusion

- We developed the first-ever sensor-based surface classification approach using machine learning.
- We developed an accessible path routing for wheelchair users.
- Our approach is scalable and personalized.
- We will be able to dynamically re-route users where needed.
- Large scale data collection about surfaces is planned using crowd-sourcing. Collected data will be contributed to the research community using Open Street Map project.

Acknowledgements

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Publication

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