

# Lecture 6 (supplemental): Stochastic Block Models

Aaron Clauset

 @aaronclauset

Assistant Professor of Computer Science  
University of Colorado Boulder  
External Faculty, Santa Fe Institute

# **what is structure?**

# **what is structure?**

- makes data different from noise
  - makes a network different from a random graph

# **what is structure?**

- makes data different from noise
  - makes a network different from a random graph
- helps us compress the data
  - describe the network succinctly
  - capture most relevant patterns

# what is structure?

- makes data different from noise
  - makes a network different from a random graph
- helps us compress the data
  - describe the network succinctly
  - capture most relevant patterns
- helps us generalize,  
from data we've seen to data we haven't seen:
  - i. from one part of network to another
  - ii. from one network to others of same type
  - iii. from small scale to large scale (coarse-grained structure)
  - iv. from past to future (dynamics)

# statistical inference

- imagine graph  $G$  is drawn from an ensemble or **generative model**: a probability distribution  $\Pr(G | \theta)$  with parameters  $\theta$
- $\theta$  can be continuous or discrete; represents structure of graph

# statistical inference

- imagine graph  $G$  is drawn from an ensemble or **generative model**: a probability distribution  $\Pr(G | \theta)$  with parameters  $\theta$
- $\theta$  can be continuous or discrete; represents structure of graph
- inference (MLE): given  $G$ , find  $\theta$  that maximizes  $\Pr(G | \theta)$
- inference (Bayes): compute or sample from posterior distribution  $\Pr(\theta | G)$

# statistical inference

- imagine graph  $G$  is drawn from an ensemble or **generative model**: a probability distribution  $\Pr(G | \theta)$  with parameters  $\theta$
  - $\theta$  can be continuous or discrete; represents structure of graph
  - inference (MLE): given  $G$ , find  $\theta$  that maximizes  $\Pr(G | \theta)$
  - inference (Bayes): compute or sample from posterior distribution  $\Pr(\theta | G)$
- 

- if  $\theta$  is partly known, constrain inference and determine the rest
- if  $G$  is partly known, infer  $\theta$  and use  $\Pr(G | \theta)$  to generate the rest
- if model is good fit (application dependent), we can generate synthetic graphs structurally similar to  $G$
- if part of  $G$  has low probability under model, flag as possible anomaly

# statistical inference

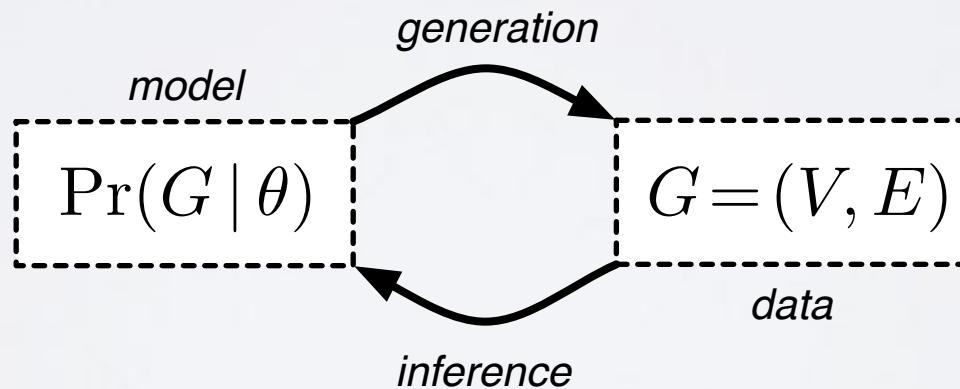
- imagine graph  $G$  is drawn from an ensemble or **generative model**: a probability distribution  $\Pr(G|\theta)$  with parameters  $\theta$
  - $\theta$  can be continuous or discrete; represents structure of graph
  - inference (MLE): given  $G$  and  $\theta$  that maximize  $\Pr(G|\theta)$
  - inference (Bayes): compute sample from posterior distribution  $\Pr(\theta|G)$
  - if  $\theta$  is partly known, constrain inference and determine the rest
  - if  $G$  is partly known, infer  $\theta$  and use  $\Pr(G|\theta)$  to generate the rest
  - if model is good fit (application dependent), we can generate synthetic graphs structurally similar to  $G$
  - if part of  $G$  has low probability under model, flag as possible anomaly
- statistical inference = principled approach to learning from data**
- combines tools from statistics, machine learning, information theory, and statistical physics**
- quantifies uncertainty**
- separates the model from the learning**

# statistical inference: key ideas

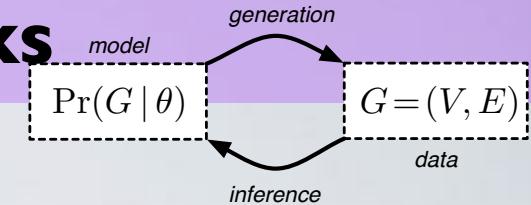
- interpretability
  - model parameters have meaning for scientific questions
- auxiliary information
  - node & edge attributes, temporal dynamics (beyond static binary graphs)
- scalability
  - fast algorithms for fitting models to big data (methods from physics, machine learning)
- model selection
  - which model is better? is this model bad? how many communities?
- partial or noisy data
  - extrapolation, interpolation, hidden data, missing data
- anomaly detection
  - low probability events under generative model

# generative models for complex networks

- define a parametric probability distribution over networks  $\Pr(G | \theta)$
- **generation** : given  $\theta$ , draw  $G$  from this distribution
- **inference** : given  $G$ , choose  $\theta$  that makes  $G$  likely



# generative models for complex networks



general form

$$\Pr(G \mid \theta) = \prod_{ij} \Pr(A_{ij} \mid \theta)$$

edge generation function

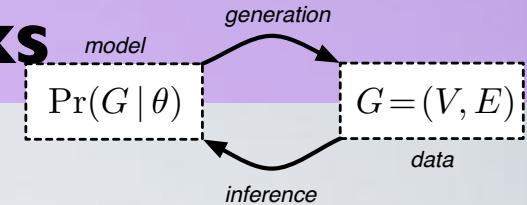
assumptions about “structure” go into  $\Pr(A_{ij} \mid \theta)$

$$\text{consistency } \lim_{n \rightarrow \infty} \Pr(\hat{\theta} \neq \theta) = 0$$

requires that edges be conditionally independent [Shalizi, Rinaldo 2011]

two general classes of these models

# generative models for complex networks



## stochastic block models

$k$  types of vertices,  $\Pr(A_{ij} \mid M, z)$  depends only on node types  $z_i, z_j$   
originally invented by sociologists [Holland, Laskey, Leinhardt 1983]

many, many flavors, including

binomial SBM [Holland et al. 1983, Wang & Wong 1987]

simple assortative SBM [Hofman & Wiggins 2008]

mixed-membership SBM [Airoldi et al. 2008]

hierarchical SBM [Clauset et al. 2006, 2008, Peixoto 2014]

fractal SBM [Leskovec et al. 2005]

infinite relational model [Kemp et al. 2006]

degree-corrected SBM [Karrer & Newman 2011]

SBM + topic models [Ball et al. 2011]

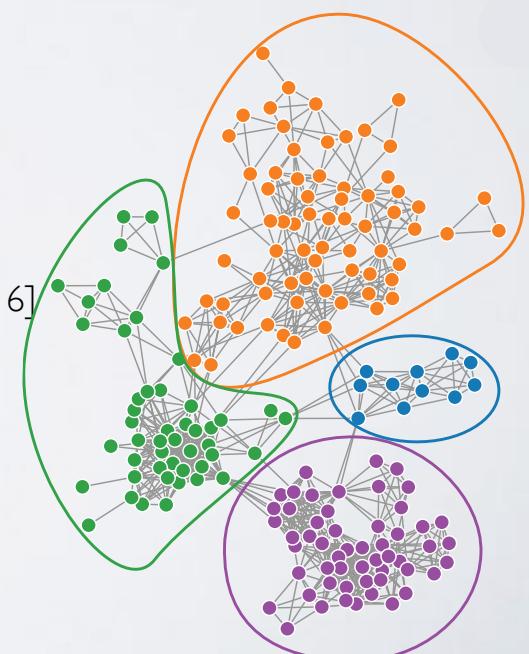
SBM + vertex covariates [Mariadassou et al. 2010, Newman & Clauset 2016]

SBM + edge weights [Aicher et al. 2013, 2014, Peixoto 2015]

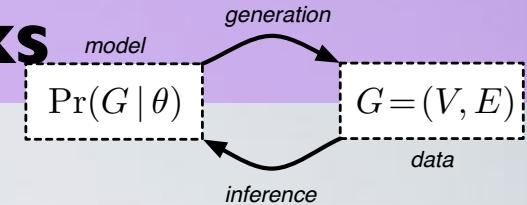
bipartite SBM [Larremore et al. 2014]

multilayer SBM [Peixoto 2015, Valles-Català et al. 2016]

and many others



# generative models for complex networks

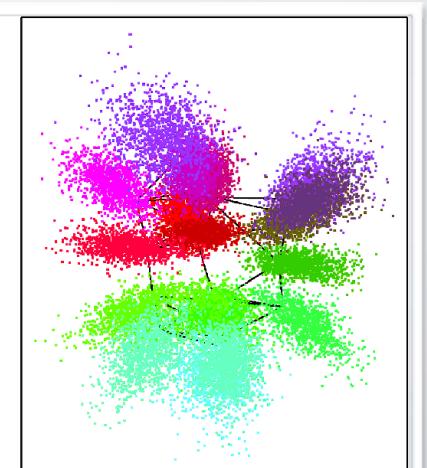
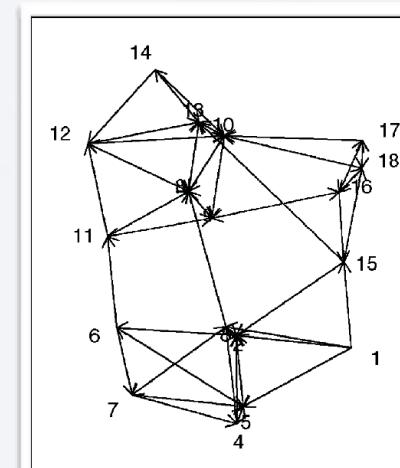


## latent space models

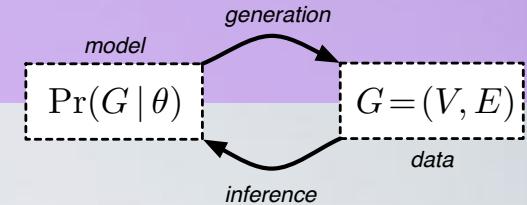
nodes live in a latent space,  $\Pr(A_{ij} | f(x_i, x_j))$  depends only on vertex-vertex proximity  
originally invented by statisticians [Hoff, Raftery, Handcock 2002]

### many, many flavors, including

- logistic function on vertex features [Hoff et al. 2002]
- social status / ranking [Ball, Newman 2013]
- nonparametric metadata relations [Kim et al. 2012]
- multiplicative attribute graphs [Kim & Leskovec 2010]
- nonparametric latent feature model [Miller et al. 2009]
- infinite multiple memberships [Morup et al. 2011]
- ecological niche model [Williams et al. 2010]
- hyperbolic latent spaces [Boguna et al. 2010]
- and many others

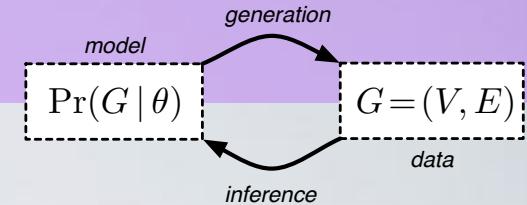


# opportunities and challenges



- richly annotated data
  - edge weights, node attributes, time, etc.
  - = new classes of generative models
- generalize from  $n = 1$  to ensemble
  - useful for modeling checking, simulating other processes, etc.
- many familiar techniques
  - frequentist and Bayesian frameworks
  - makes probabilistic statements about observations, models
  - predicting missing links  $\approx$  leave- $k$ -out cross validation
  - approximate inference techniques (EM, VB, BP, etc.)
  - sampling techniques (MCMC, Gibbs, etc.)
- learn from partial or noisy data
  - extrapolation, interpolation, hidden data, missing data

# opportunities and challenges

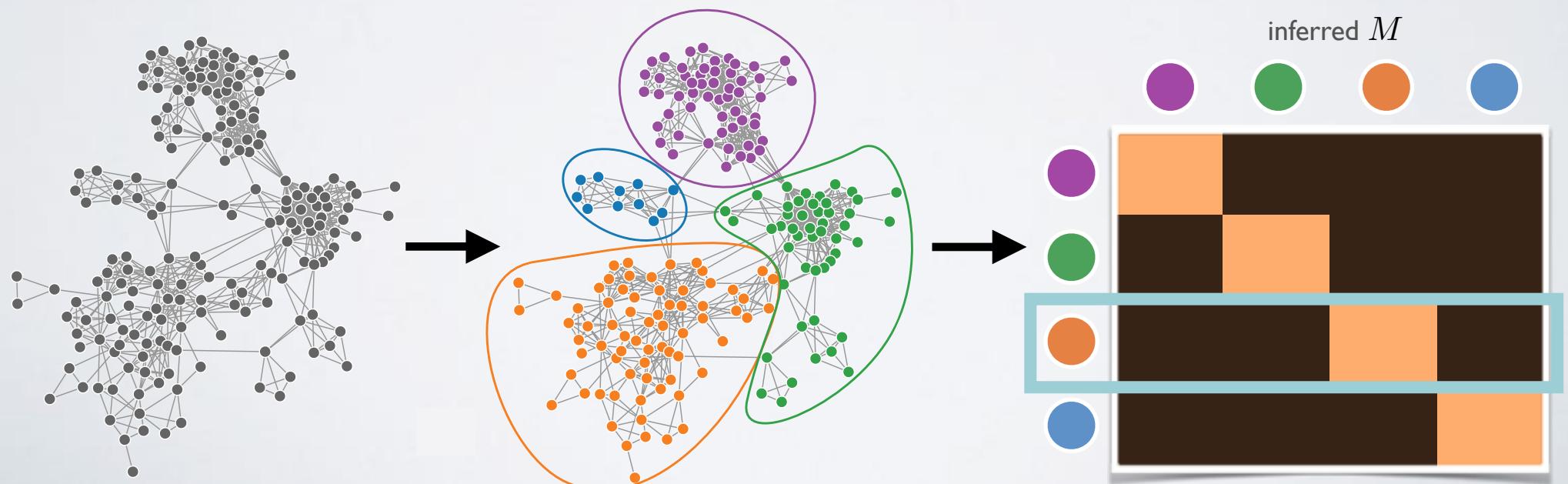


- only two classes of models
  - stochastic block models (categorical latent variables)
  - latent space models (ordinal / continuous latent variables)
- bootstrap / resampling for network data
  - critical missing piece
  - depends on what is independent in the data
- model comparison
  - naive AIC, BIC, marginalization, LRT can be wrong for networks
  - what is goal of modeling: realistic representation or accurate prediction?
- model assessment / checking?
  - how do we know a model has done well? what do we check?
- what is  $v$ -fold cross-validation for networks?
  - Omit  $n^2/v$  edges? Omit  $n/v$  nodes? What?

# the stochastic block model

- each vertex  $i$  has type  $z_i \in \{1, \dots, k\}$  ( $k$  vertex types or groups)
- stochastic block matrix  $M$  of group-level connection probabilities
- probability that  $i, j$  are connected =  $M_{z_i, z_j}$

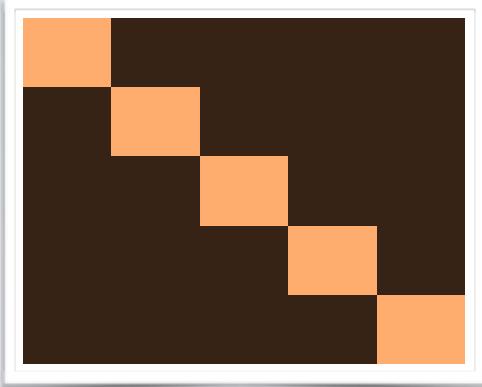
community = vertices with same pattern of inter-community connections



# the stochastic block model

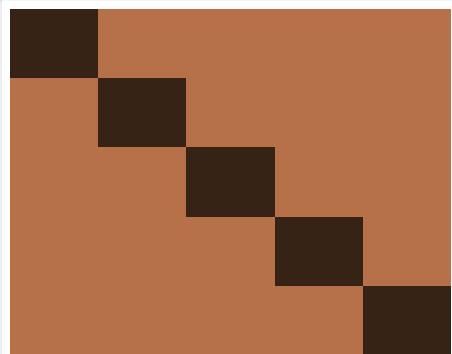
**assortative**

edges within groups



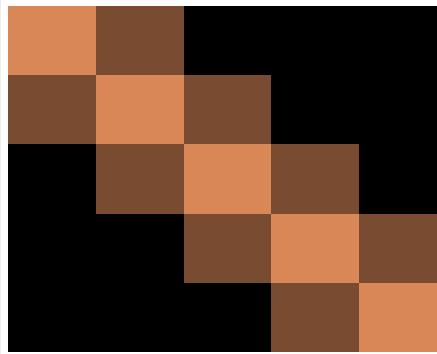
**disassortative**

edges between groups



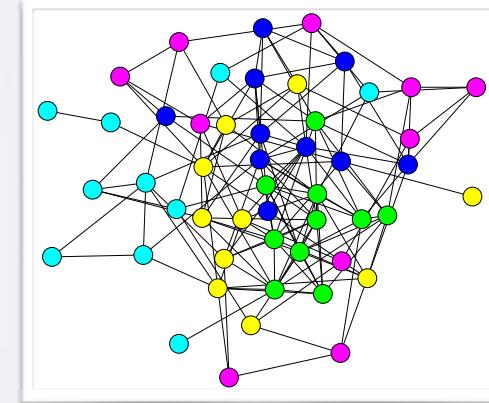
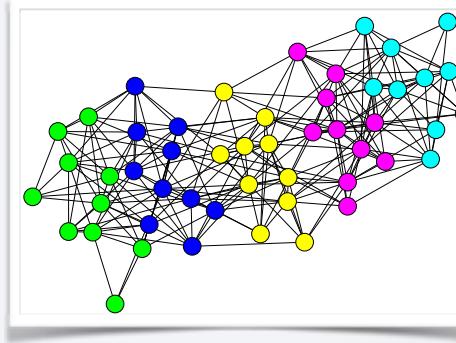
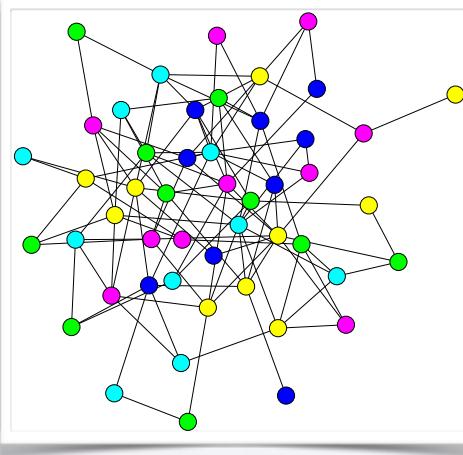
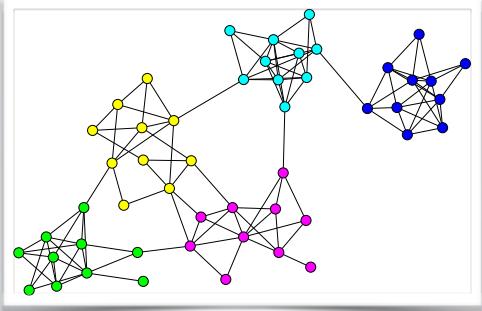
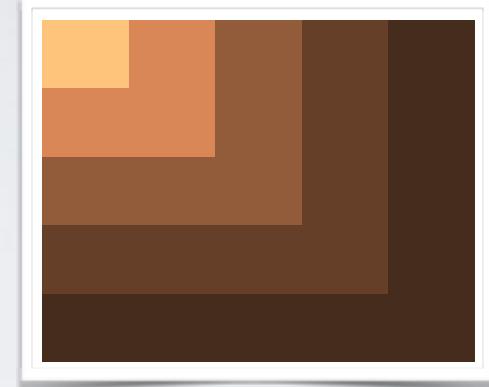
**ordered**

linear group hierarchy



**core-periphery**

dense core, sparse periphery



# the stochastic block model

likelihood function

the probability of  $G$  given labeling  $z$  and block matrix  $M$

$$\Pr(G \mid z, M) = \underbrace{\prod_{(i,j) \in E} M_{z_i, z_j}}_{\text{edge}} / \underbrace{\prod_{(i,j) \notin E} (1 - M_{z_i, z_j})}_{\text{non-edge probability}}$$

# the stochastic block model

likelihood function

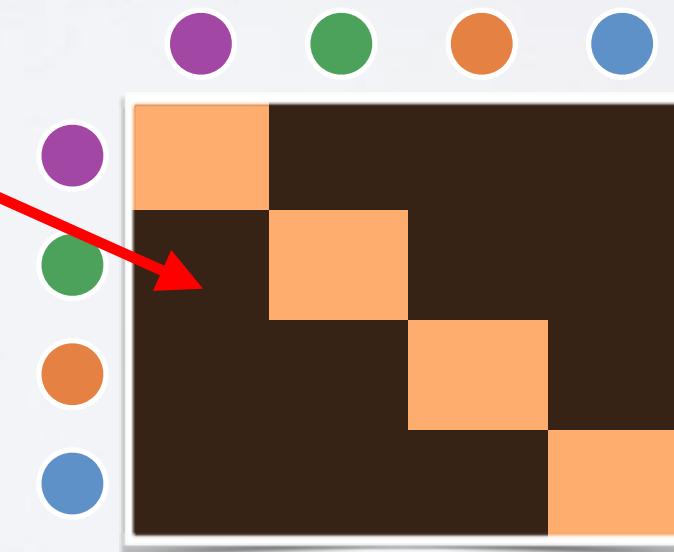
the probability of  $G$  given labeling  $z$  and block matrix  $M$

$$\Pr(G \mid z, M) = \prod_{(i,j) \in E} M_{z_i, z_j} \prod_{(i,j) \notin E} (1 - M_{z_i, z_j})$$

$$= \prod_{rs} M_{r,s}^{e_{r,s}} (1 - M_{r,s})^{n_s n_r - e_{r,s}}$$

(Bernoulli edges)

Bernoulli random graph  
with parameter  $M_{r,s}$



# the stochastic block model

the most general SBM

$$\Pr(A \mid z, \theta) = \prod_{i,j} f(A_{ij} \mid \theta_{\mathcal{R}(z_i, z_j)})$$

$A_{ij}$  : value of adjacency

$\mathcal{R}$  : partition of adjacencies

$f$  : probability function

$\theta_{a,*}$  : pattern for  $a$ -type adjacencies

Binomial = simple graphs  
Poisson = multi-graphs  
Normal = weighted graphs  
etc.

$\theta_{11}$	$\theta_{12}$	$\theta_{13}$	$\theta_{14}$
$\theta_{21}$	$\theta_{22}$	$\theta_{23}$	$\theta_{24}$
$\theta_{31}$	$\theta_{32}$	$\theta_{33}$	$\theta_{34}$
$\theta_{41}$	$\theta_{42}$	$\theta_{43}$	$\theta_{44}$

# **the stochastic block model**

degree-corrected SBM ( $f = \text{Poisson}$ )

# the stochastic block model

degree-corrected SBM ( $f = \text{Poisson}$ )

key assumption  $\Pr(i \rightarrow j) = \theta_i \theta_j \omega_{z_i, z_j}$

stochastic block matrix  $\omega_{r,s}$

(degree) propensity of node  $\theta_i$

likelihood:

$$\Pr(A | z, \theta, \omega) = \prod_{i < j} \frac{(\theta_i \theta_j \omega_{z_r, z_j})^{A_{ij}}}{A_{ij}!} \exp(-\theta_i \theta_j \omega_{z_r, z_j})$$

where  $\hat{\theta}_i = \underbrace{\frac{k_i}{\sum_j k_j \delta_{z_i, z_j}}}_{\text{fraction of } i\text{'s group's stubs on } i}$

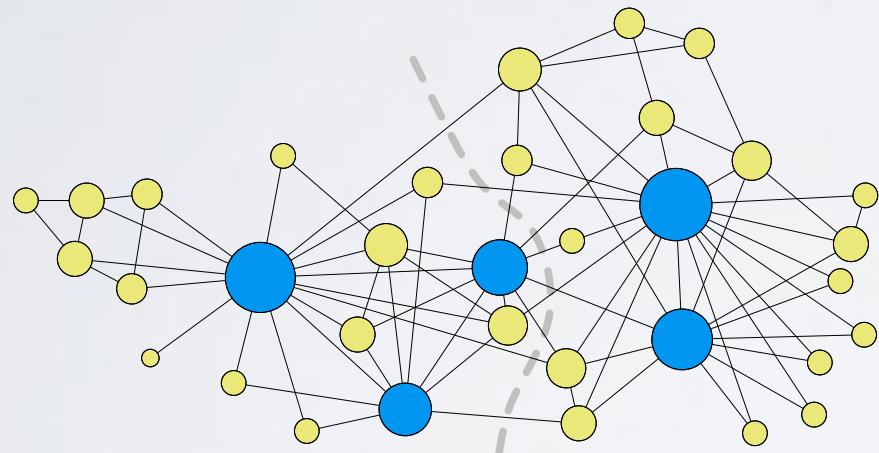
$$\hat{\omega}_{rs} = m_{rs} = \underbrace{\sum_{ij} A_{ij} \delta_{z_i, r} \delta_{z_j, s}}_{\text{total number of edges between } r \text{ and } s}$$

# **the stochastic block model**

comparing SBM vs. DC-SBM : Zachary karate club

# the stochastic block model

comparing SBM vs. DC-SBM : Zachary karate club



**SBM**

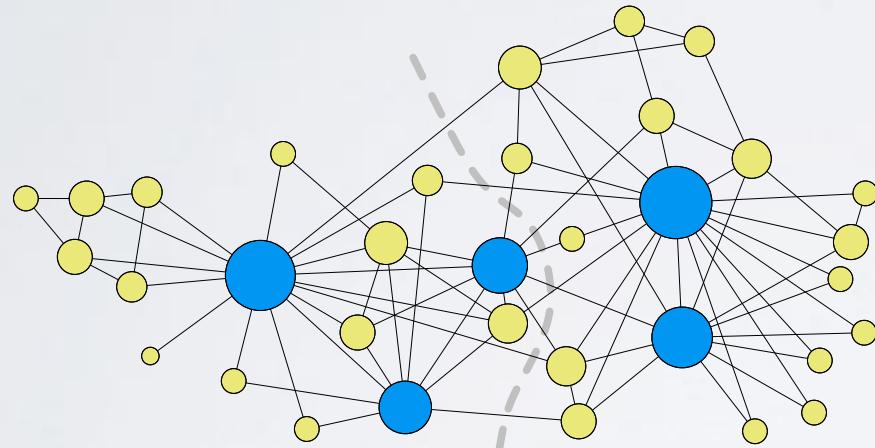
leader/follower division

**DC-SBM**

social group division

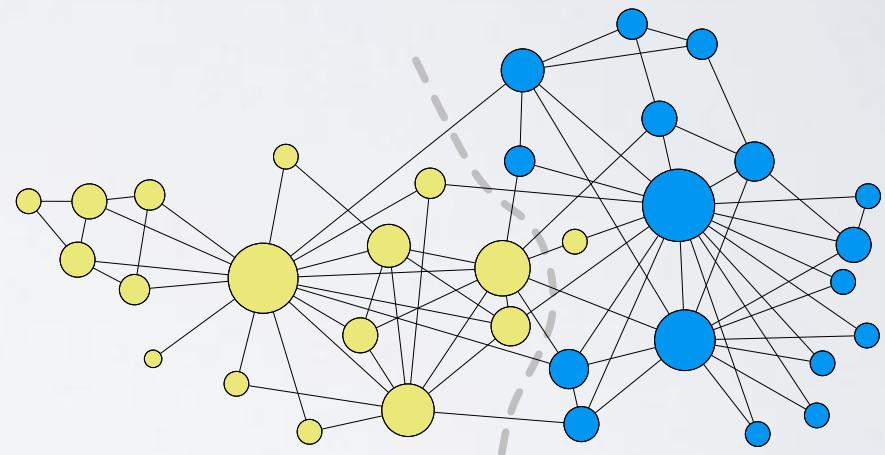
# the stochastic block model

comparing SBM vs. DC-SBM : Zachary karate club



**SBM**

leader/follower division

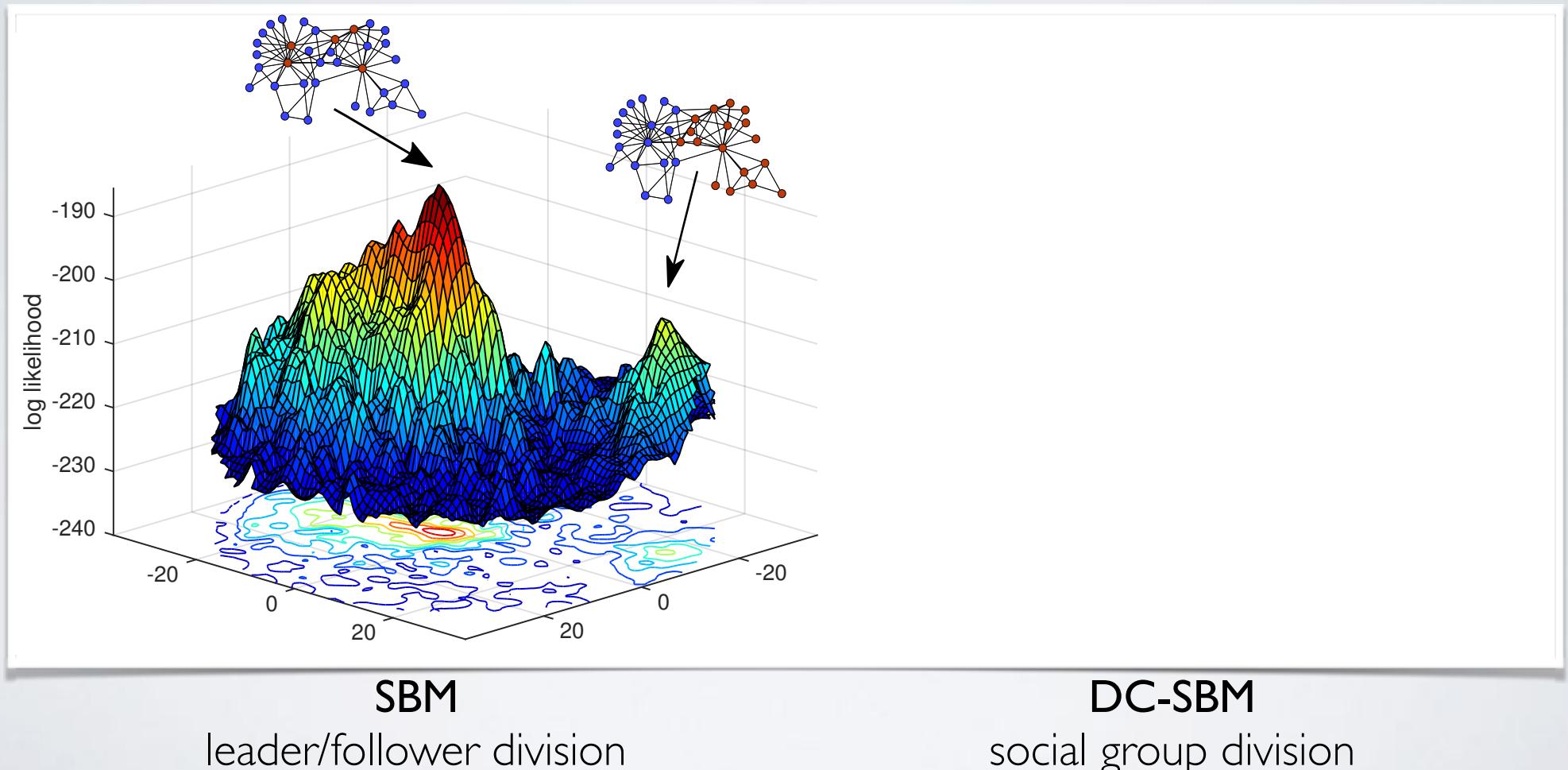


**DC-SBM**

social group division

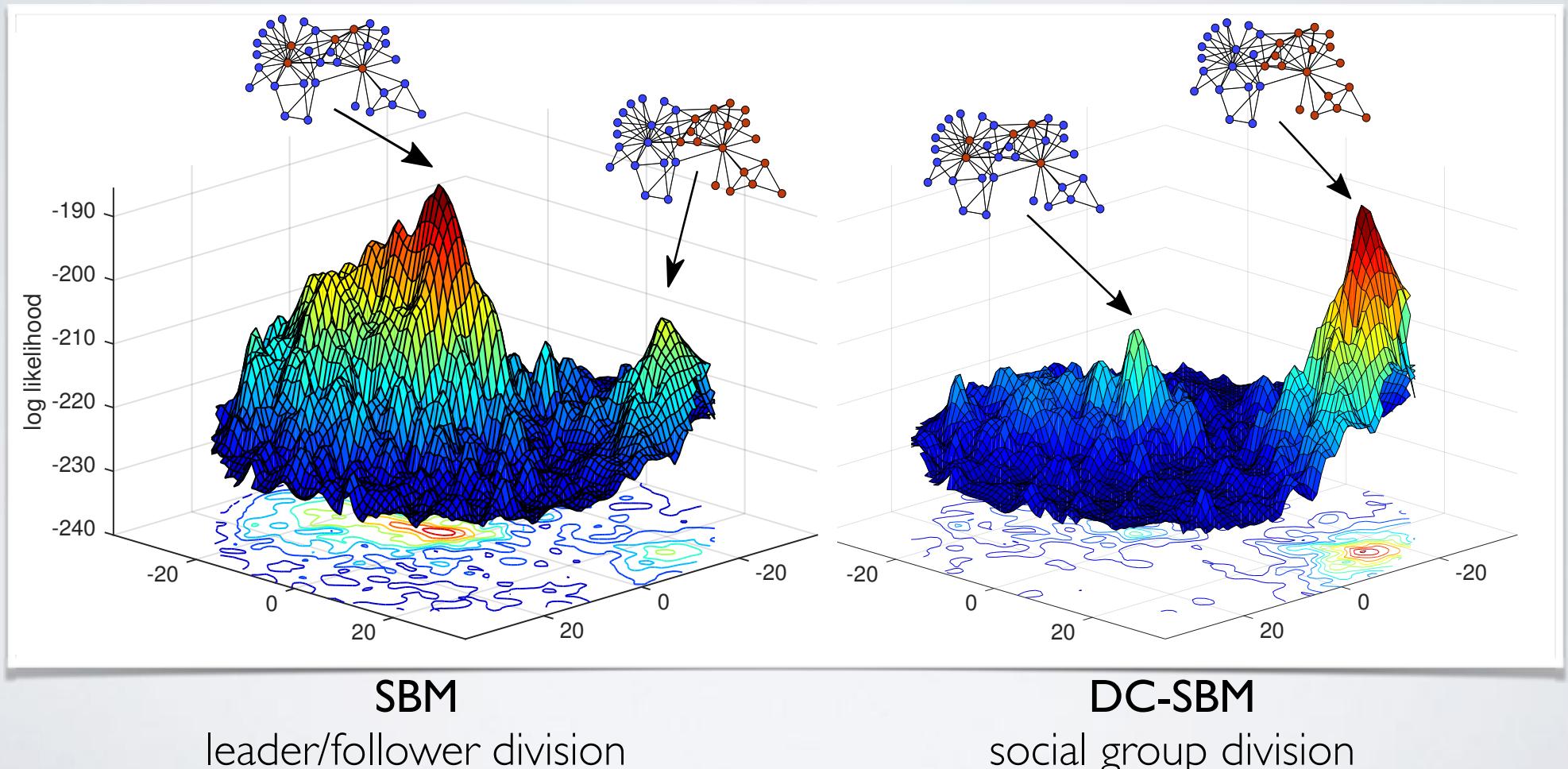
# the stochastic block model

comparing SBM vs. DC-SBM : Zachary karate club



# the stochastic block model

comparing SBM vs. DC-SBM : Zachary karate club



# **extending the SBM**

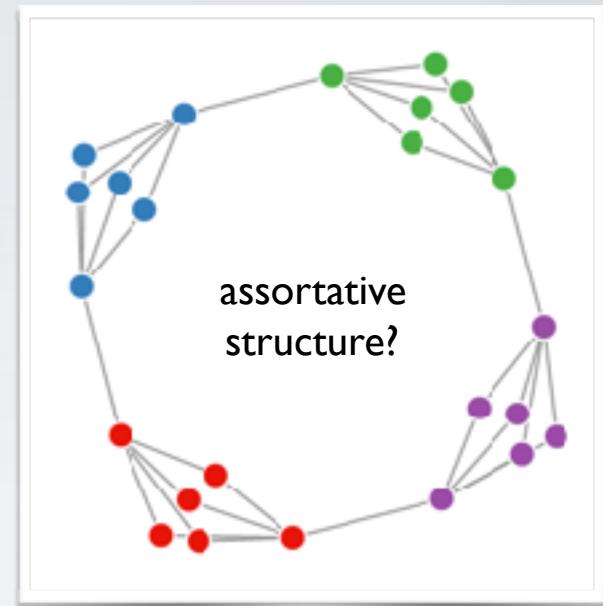
many variants! we'll cover three:

- bipartite community structure
- weighted community structure
- hierarchical community structure

# bipartite networks

many networks are bipartite

- scientists and papers (co-authorship networks)
- actors and movies (co-appearance networks)
- words and documents (topic modeling)
- plants and pollinators
- genes and genomes
- etc.

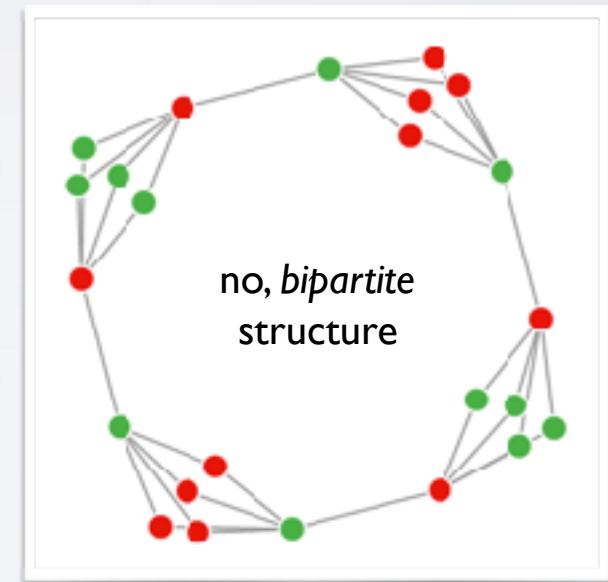
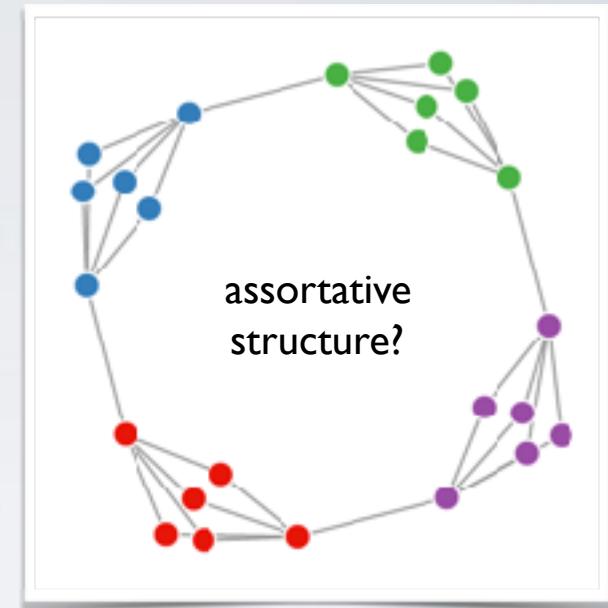


# bipartite networks

many networks are bipartite

- scientists and papers (co-authorship networks)
- actors and movies (co-appearance networks)
- words and documents (topic modeling)
- plants and pollinators
- genes and genomes
- etc.

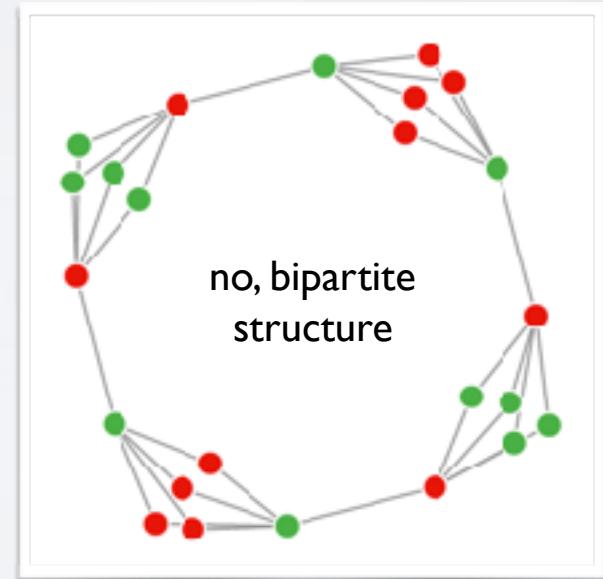
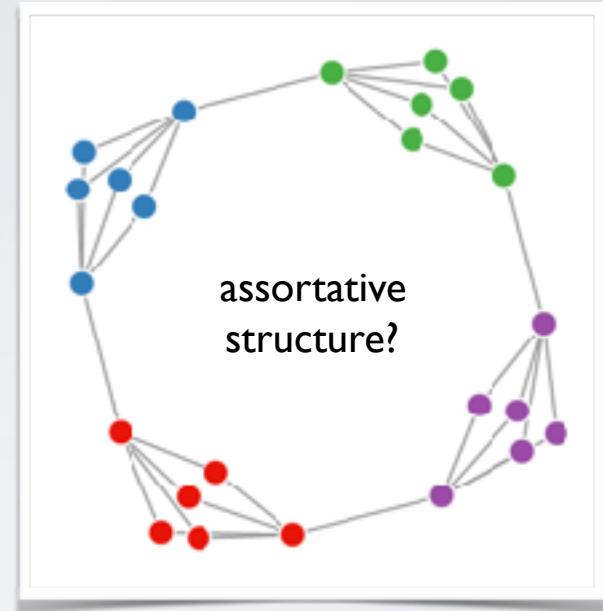
most analyses focus on one-mode projections  
which discard information



# bipartite networks

## bipartite stochastic block model (biSBM)

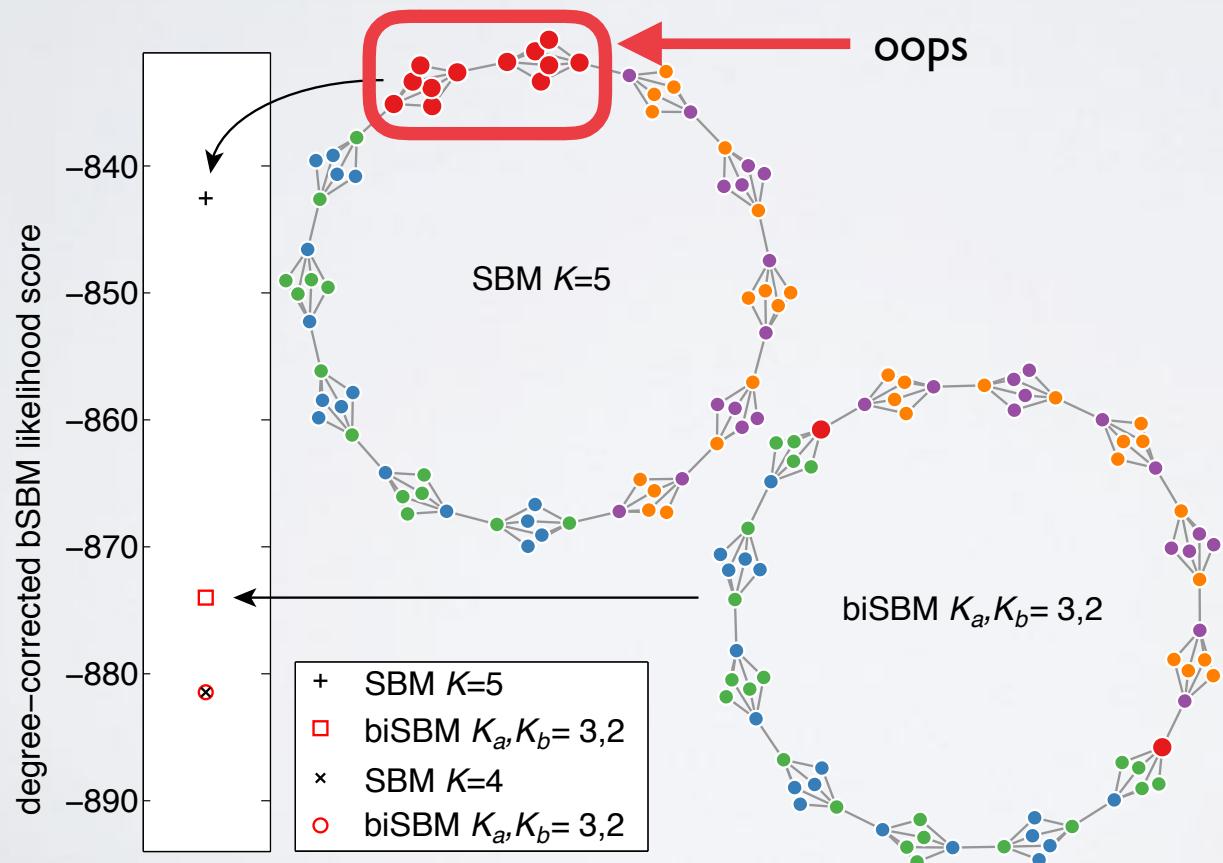
- exactly the SBM, but model knows network is bipartite
- if  $\text{type}(z_i) = \text{type}(z_j)$   
then require  $M_{z_i, z_j} = 0$
- inference proceeds as before



# bipartite networks

SBM can learn bipartite structure on its own

but often over fits or returns mixed-type groups



# bipartite networks

## bipartite stochastic block model (biSBM)

- how do we know it works well?

# bipartite networks

## bipartite stochastic block model (biSBM)

- how do we know it works well?
- synthetic networks with *planted partitions*

$$\omega^{\text{planted}} = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \alpha & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & \beta & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & \gamma & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & 0 & \delta \\ \alpha & 0 & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & \beta & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \gamma & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & \delta & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

**easy case:**  
4x4 easy-to-see communities

$$\omega^{\text{planted}} = \begin{pmatrix} \cdot & \cdot & \cdot & \epsilon & 0 \\ \cdot & \cdot & \cdot & 0 & \epsilon \\ \cdot & \cdot & \cdot & \gamma & \gamma \\ \epsilon & 0 & \gamma & \cdot & \cdot \\ 0 & \epsilon & \gamma & \cdot & \cdot \end{pmatrix}$$

**hard case:**  
3x2 hard-to-see communities

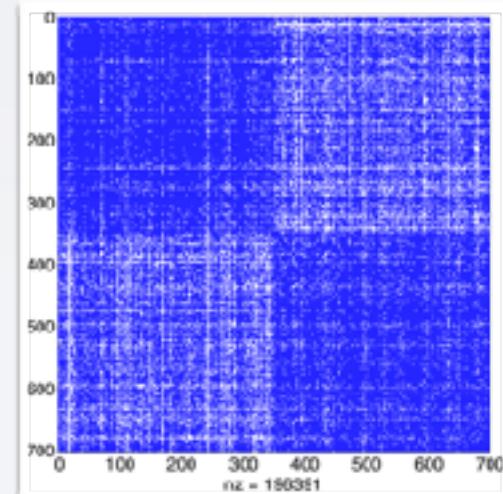
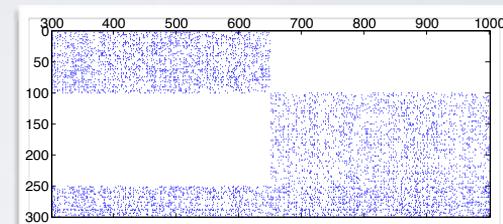
# bipartite networks

## bipartite stochastic block model (biSBM)

- how do we know it works well?
- synthetic networks with *planted partitions*

$$\omega^{\text{planted}} = \begin{pmatrix} \cdot & \cdot & \cdot & \cdot & \alpha & 0 & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & \beta & 0 & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & \gamma & 0 \\ \cdot & \cdot & \cdot & \cdot & 0 & 0 & 0 & \delta \\ \alpha & 0 & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & \beta & 0 & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & \gamma & 0 & \cdot & \cdot & \cdot & \cdot \\ 0 & 0 & 0 & \delta & \cdot & \cdot & \cdot & \cdot \end{pmatrix}$$

**easy case:**  
4x4 easy-to-see communities

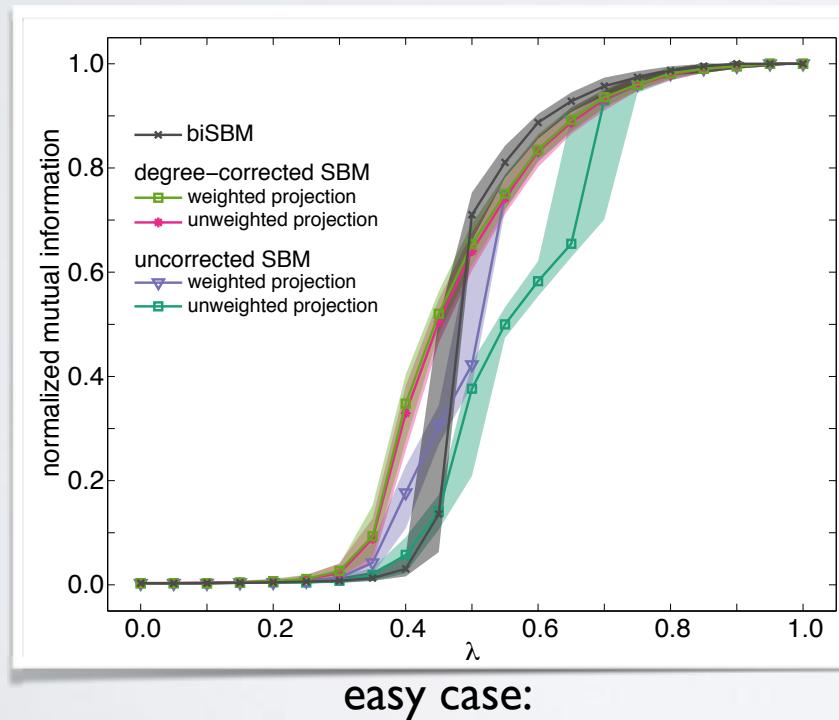


**hard case:**  
3x2 hard-to-see communities

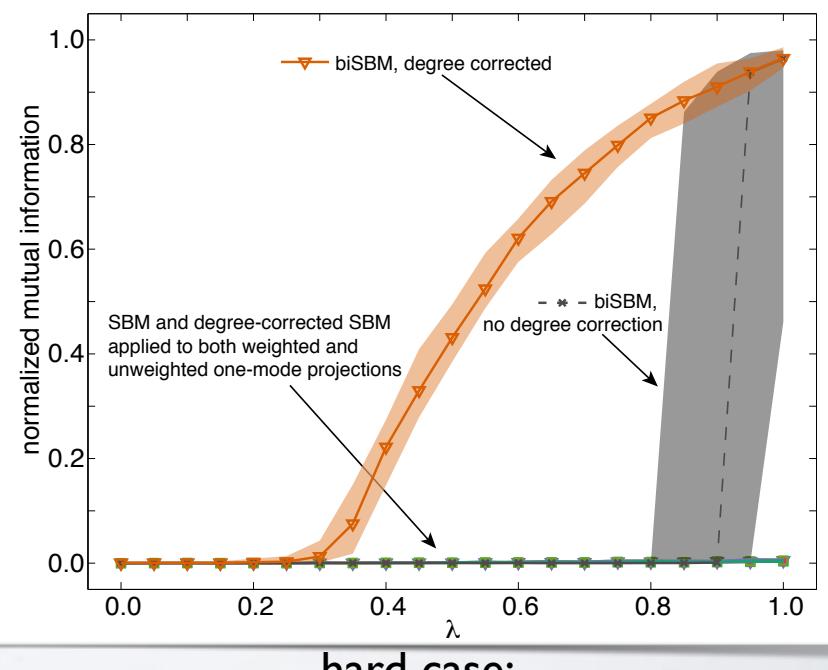
# bipartite networks

## bipartite stochastic block model (biSBM)

- how do we know it works well?
- synthetic networks with *planted partitions*



easy case:  
4x4 easy-to-see communities



hard case:  
3x2 hard-to-see communities

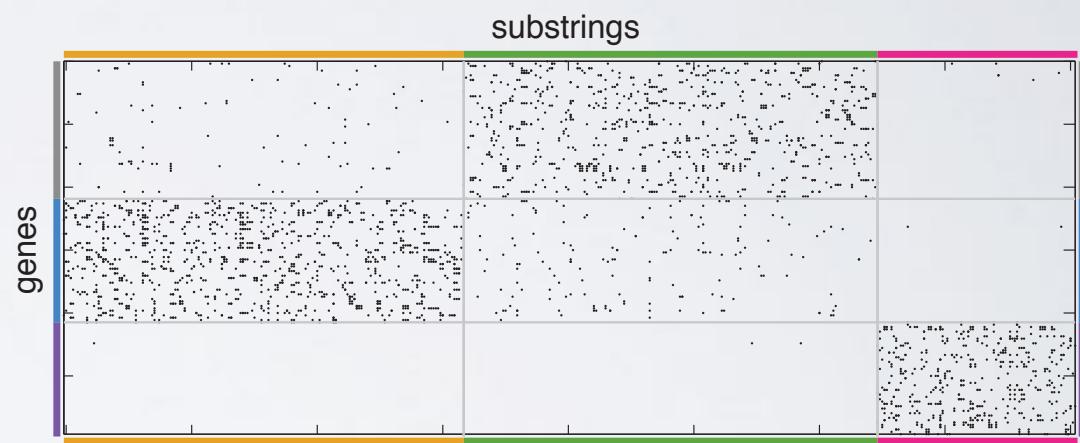
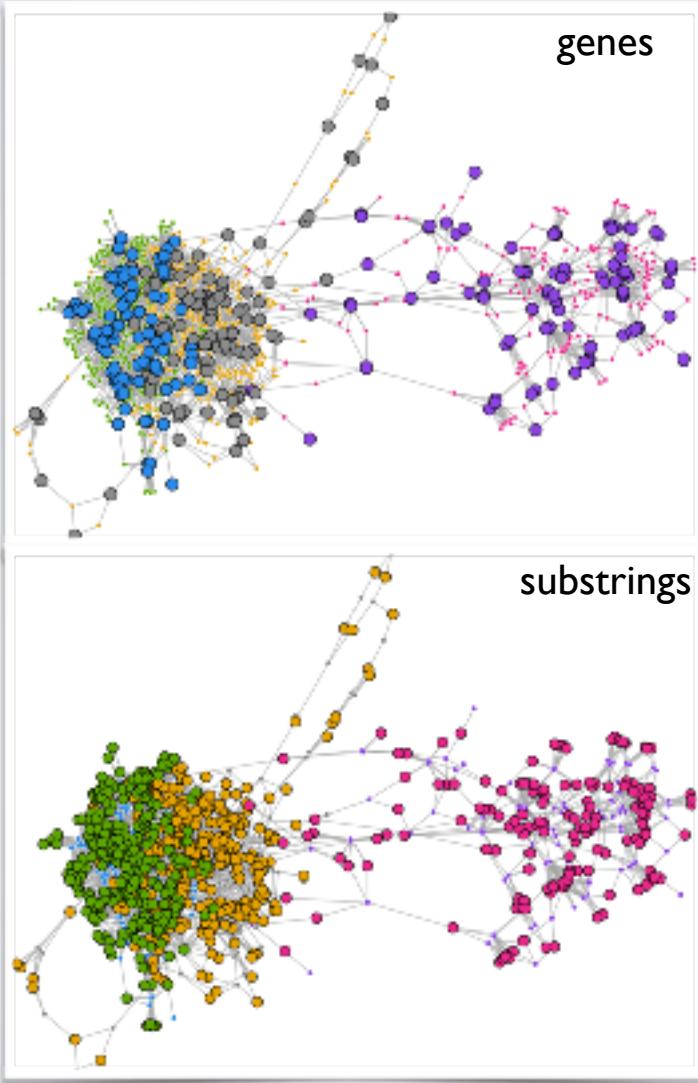
# bipartite networks

## bipartite stochastic block model (biSBM)

- always find pure-type communities
- more accurate than modeling one-mode projections (even weighted projections)
- finds communities in *both* modes

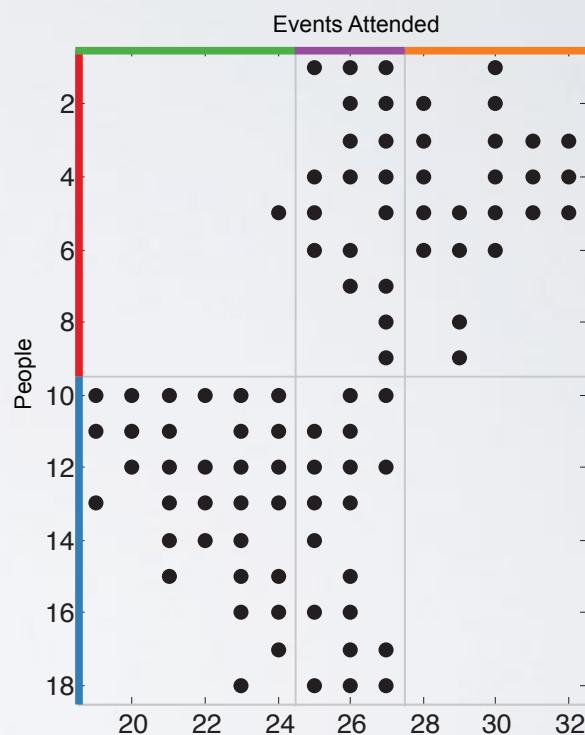
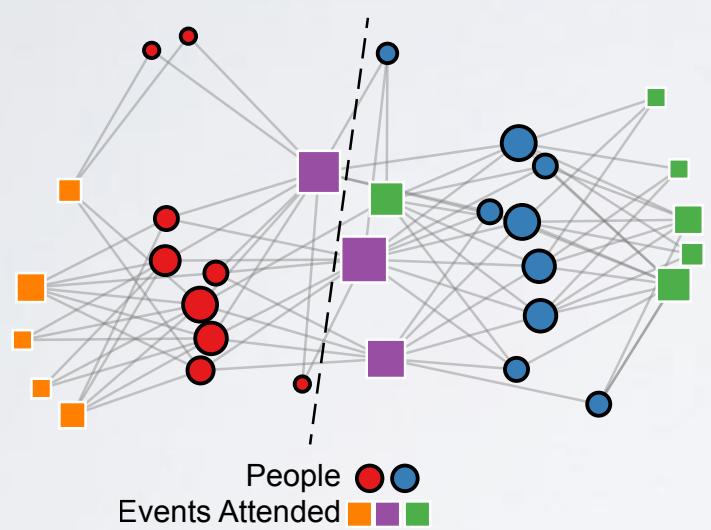
# bipartite networks

example I: malaria gene network



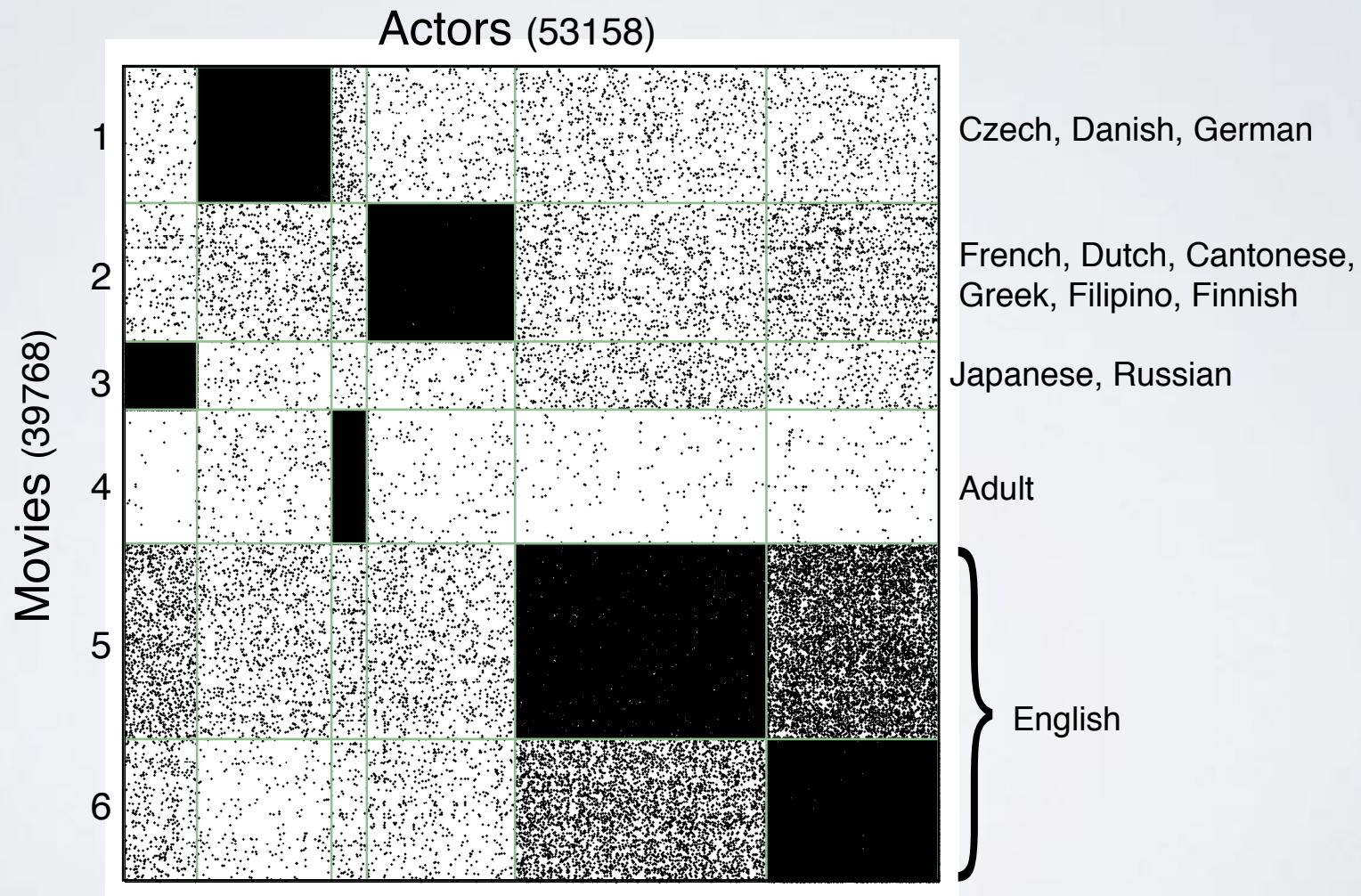
# bipartite networks

example 2: Southern Women network



# bipartite networks

example 3: IMDb



# bipartite networks

## other approaches

PRL 110, 148701 (2013)

PHYSICAL REVIEW LETTERS

week ending  
5 APRIL 2013

### Parsimonious Module Inference in Large Networks

Tiago P. Peixoto\*

*Institut für Theoretische Physik, Universität Bremen, Hochschulring 18, D-28359 Bremen, Germany*

(Received 19 December 2012; published 5 April 2013; publisher error corrected 5 April 2013)

minimum description length (MDL) principle

learns that a network is bipartite

OPEN  ACCESS Freely available online



### Predicting Human Preferences Using the Block Structure of Complex Social Networks

Roger Guimerà<sup>1,2\*</sup>, Alejandro Llorente<sup>3</sup>, Esteban Moro<sup>4,5,3</sup>, Marta Sales-Pardo<sup>2</sup>

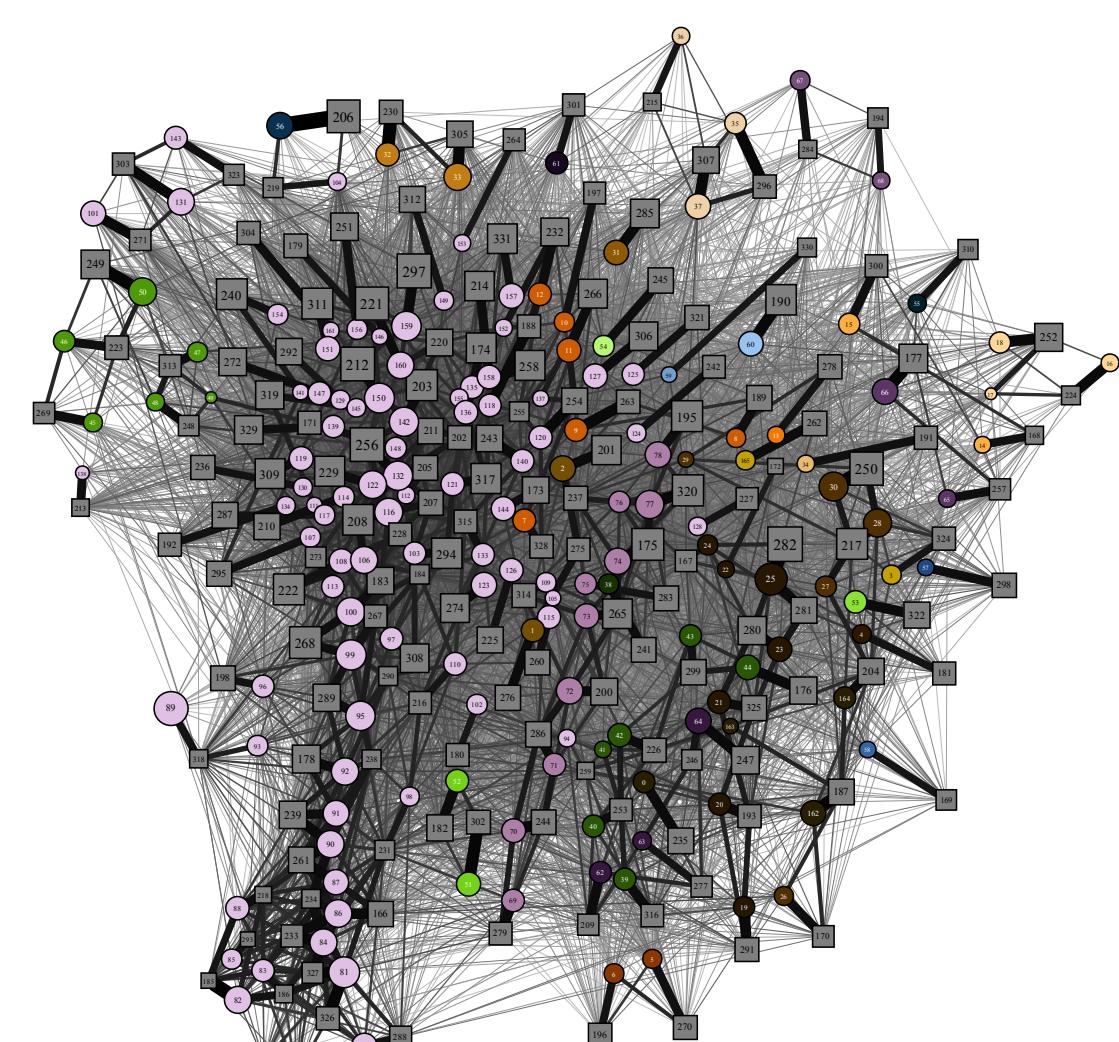
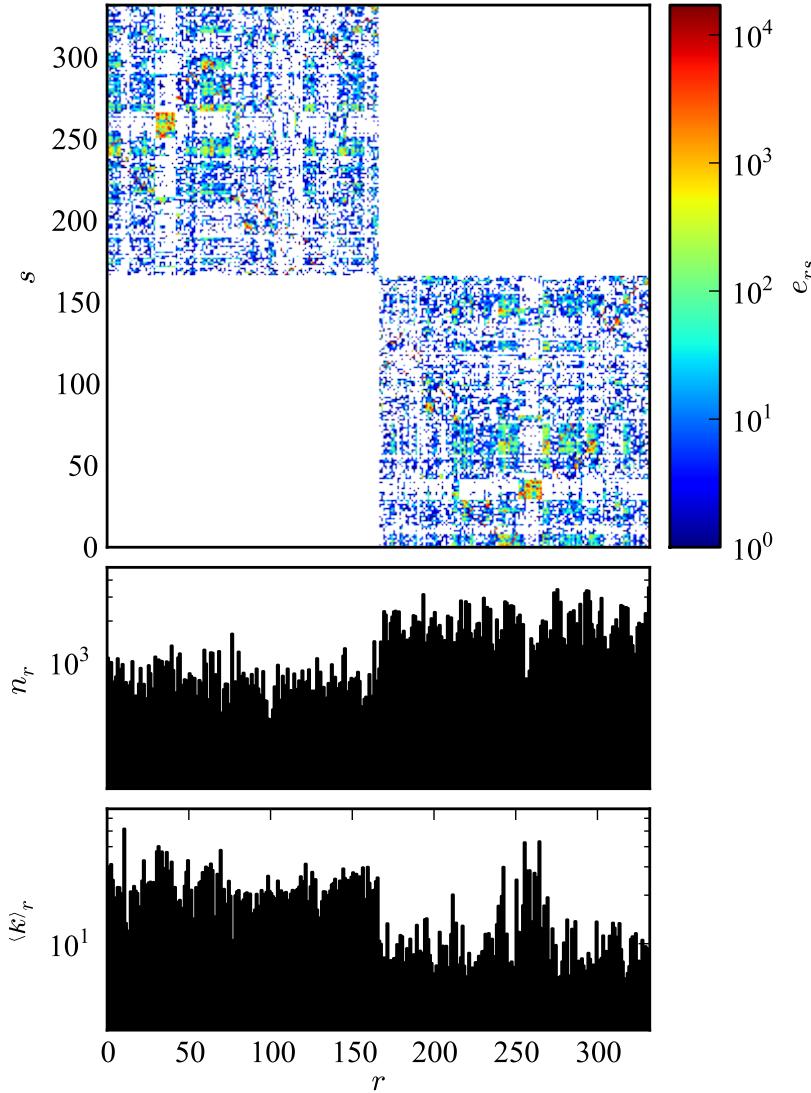
marginalize over bipartite SBM parameterizations

# bipartite networks

## Parsimonious Module Inference in Large Networks

Tiago P. Peixoto\*

Institut für Theoretische Physik, Universität Bremen, Hochschulring 18, D-28359 Bremen, Germany  
 (Received 19 December 2012; published 5 April 2013; publisher error corrected 5 April 2013)

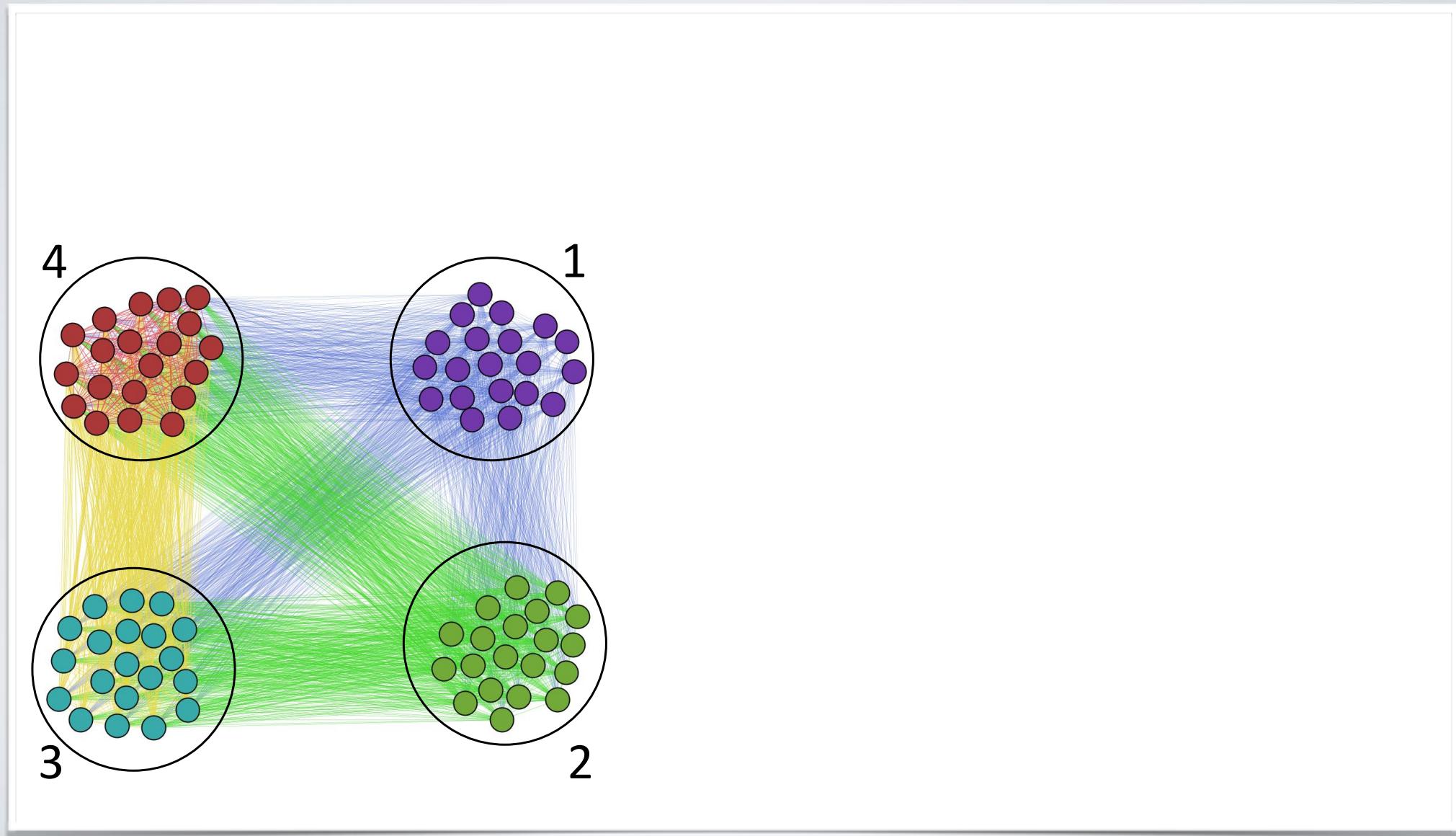


# weighted networks

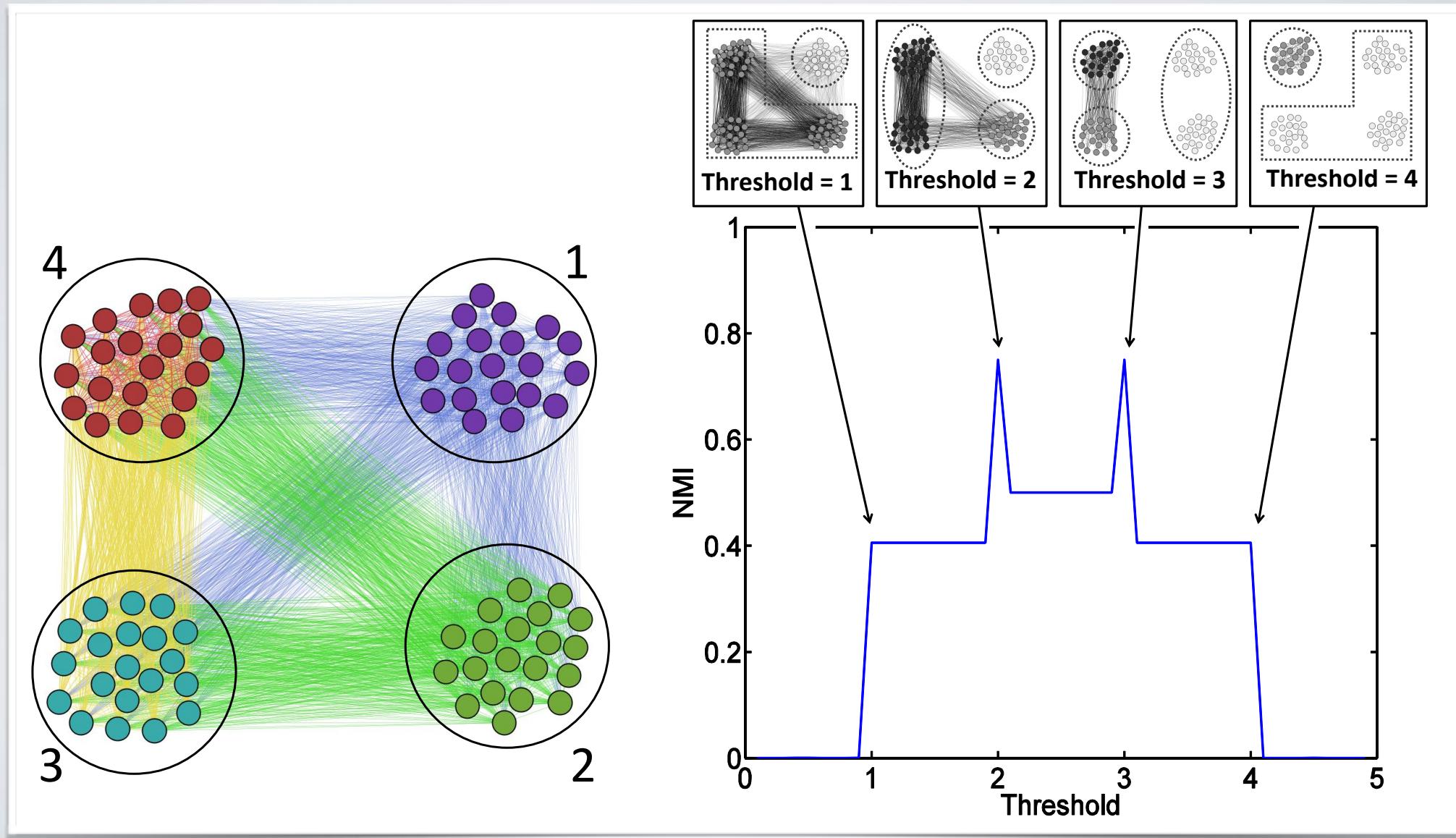
most interactions are weighted

- frequency of interaction
- strength of interaction
- outcome of interaction
- etc.
- **but!** thresholding discards information and can obscure underlying structure

# weighted networks



# weighted networks



# weighted networks

## Valued Ties Tell Fewer Lies: Why Not To Dichotomize Network Edges With Thresholds\*

Andrew C. Thomas<sup>†</sup>

Joseph K. Blitzstein<sup>‡</sup>

- how will the results depend on the threshold?
- what impact does noise have, under threshold?

# recall...

the most general SBM

$$\Pr(A \mid z, \theta) = \prod_{i,j} f(A_{ij} \mid \theta_{\mathcal{R}(z_i, z_j)})$$

$A_{ij}$  : value of adjacency

$\mathcal{R}$  : partition of adjacencies

$f$  : probability function

$\theta_{a,*}$  : pattern for  $a$ -type adjacencies

Binomial = simple graphs  
Poisson = multi-graphs  
Normal = weighted graphs  
etc.

$\theta_{11}$	$\theta_{12}$	$\theta_{13}$	$\theta_{14}$
$\theta_{21}$	$\theta_{22}$	$\theta_{23}$	$\theta_{24}$
$\theta_{31}$	$\theta_{32}$	$\theta_{33}$	$\theta_{34}$
$\theta_{41}$	$\theta_{42}$	$\theta_{43}$	$\theta_{44}$

# weighted networks

## weighted stochastic block model (WSBM)

- model edge existence and edge weight separately
  - edge existence: SBM
  - edge weights: exponential family distribution
- log-likelihood:

$$\ln \Pr(G | M, z, \theta, f) = \alpha \ln \Pr(G | M, z) + (1 - \alpha) \ln \Pr(G | \theta, z, f)$$

edge-existence  
[binomial distribution]  
 $M_{z_i, z_j}$

edge-weights  
[exponential-family distribution]  
 $\theta_{z_i, z_j}$

Poisson, Normal, Gamma,  
Exponential, Pareto, etc.

# weighted networks

## weighted stochastic block model (WSBM)

- model edge existence and edge weight separately
- edge existence: SBM
- edge weights: exponential family distribution  
log-likelihood:

$$\ln \Pr(G \mid M, z, \theta, f) = \alpha \ln \Pr(G \mid M, z) + (1 - \alpha) \ln \Pr(G \mid \theta, z, f)$$



mixing parameter

$\alpha = 1$  only model edge existence (ignore weights)

$\alpha = 0$  only model edge weights (ignore non-edges)

# weighted networks

American football, NFL 2009 season



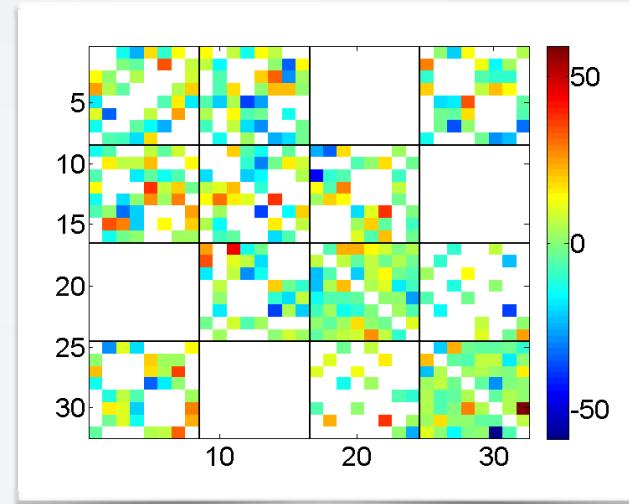
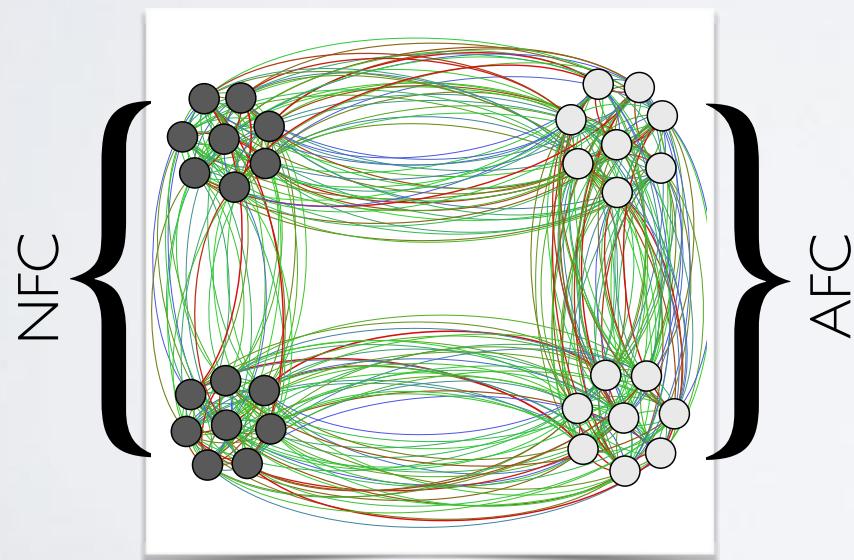
- 32 teams, 2 “divisions”, 4 “subdivisions”
- edge existence: who plays whom
- edge weight: mean score difference

# weighted networks

American football, NFL 2009 season



- 32 teams, 2 “divisions”, 4 “subdivisions”
- SBM ( $\alpha=1$ ) recovers subdivisions perfectly



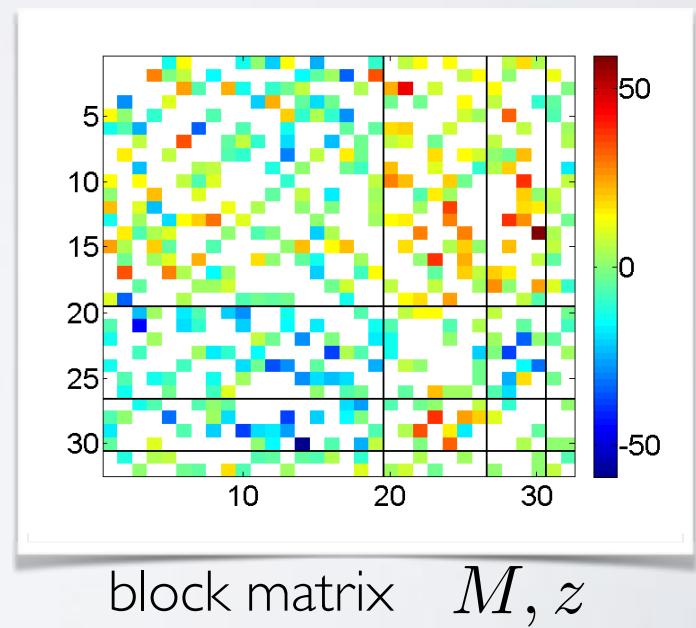
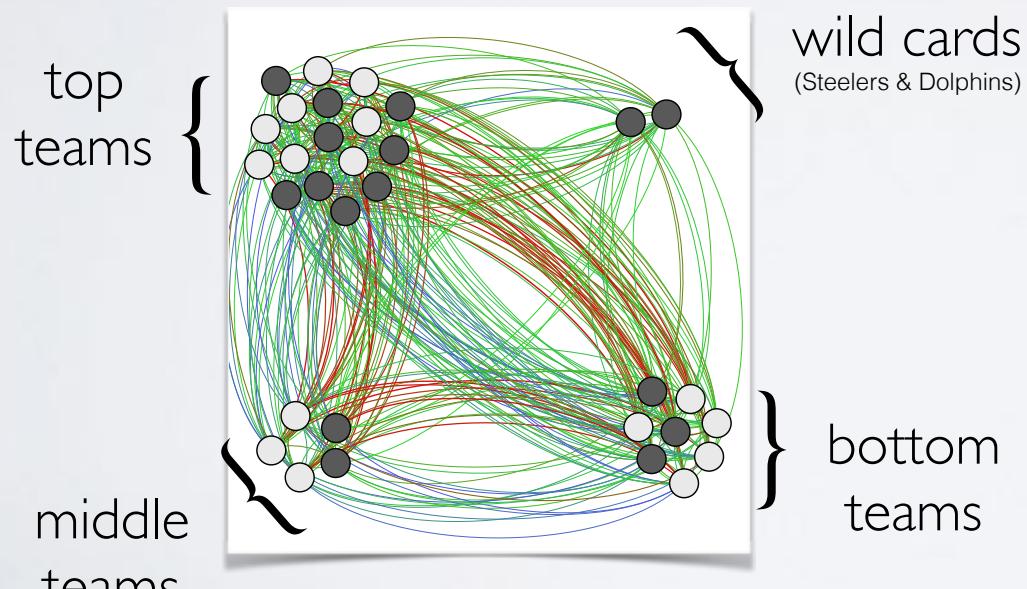
block matrix  $M_z$

# weighted networks



American football, NFL 2009 season

- 32 teams, 2 “divisions”, 4 “subdivisions”
- WSBM ( $\alpha=0$ ) recovers team skill hierarchy



# weighted networks

## adding weights to the SBM

- what does  $A_{ij} = 0$  mean?  
no edge or weight=0 edge or non-observed edge?
- how will we model the distribution of edge weights?
- edge existences and edge weights may contain *different* large-scale structure  
(conference structure vs. skill hierarchy)

# **weighted networks**

other approaches

# weighted networks

## other approaches

PHYSICAL REVIEW E **92**, 042807 (2015)

### Inferring the mesoscale structure of layered, edge-valued, and time-varying networks

Tiago P. Peixoto <sup>\*</sup>

*Institut für Theoretische Physik, Universität Bremen, Hochschulring 18, D-28359 Bremen, Germany*

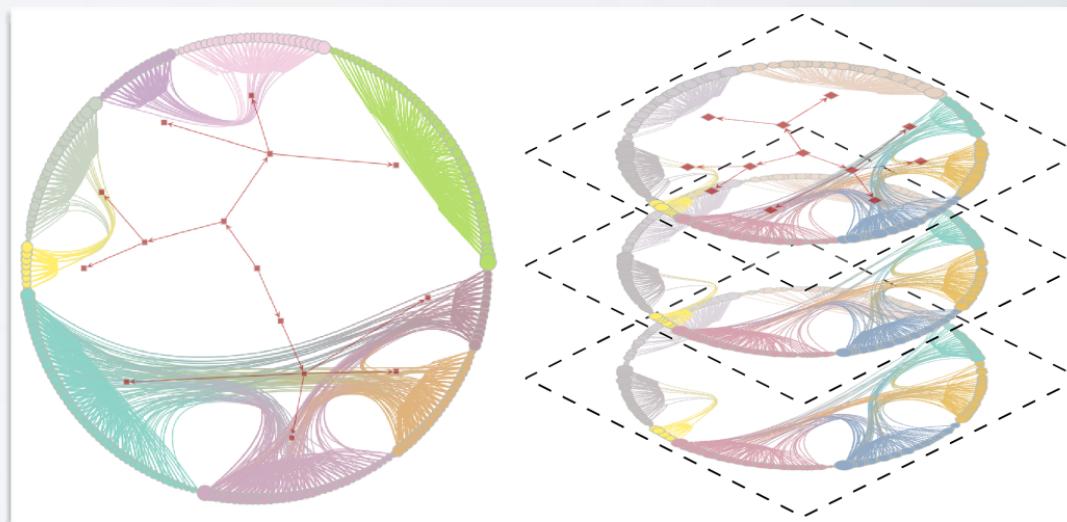
bin the edge weights into  $C$  ranges

$C$  bins =  $C$  layers of a multi-layer SBM

common node labels

each layer has its own block matrix

infer  $C, M_c, z$

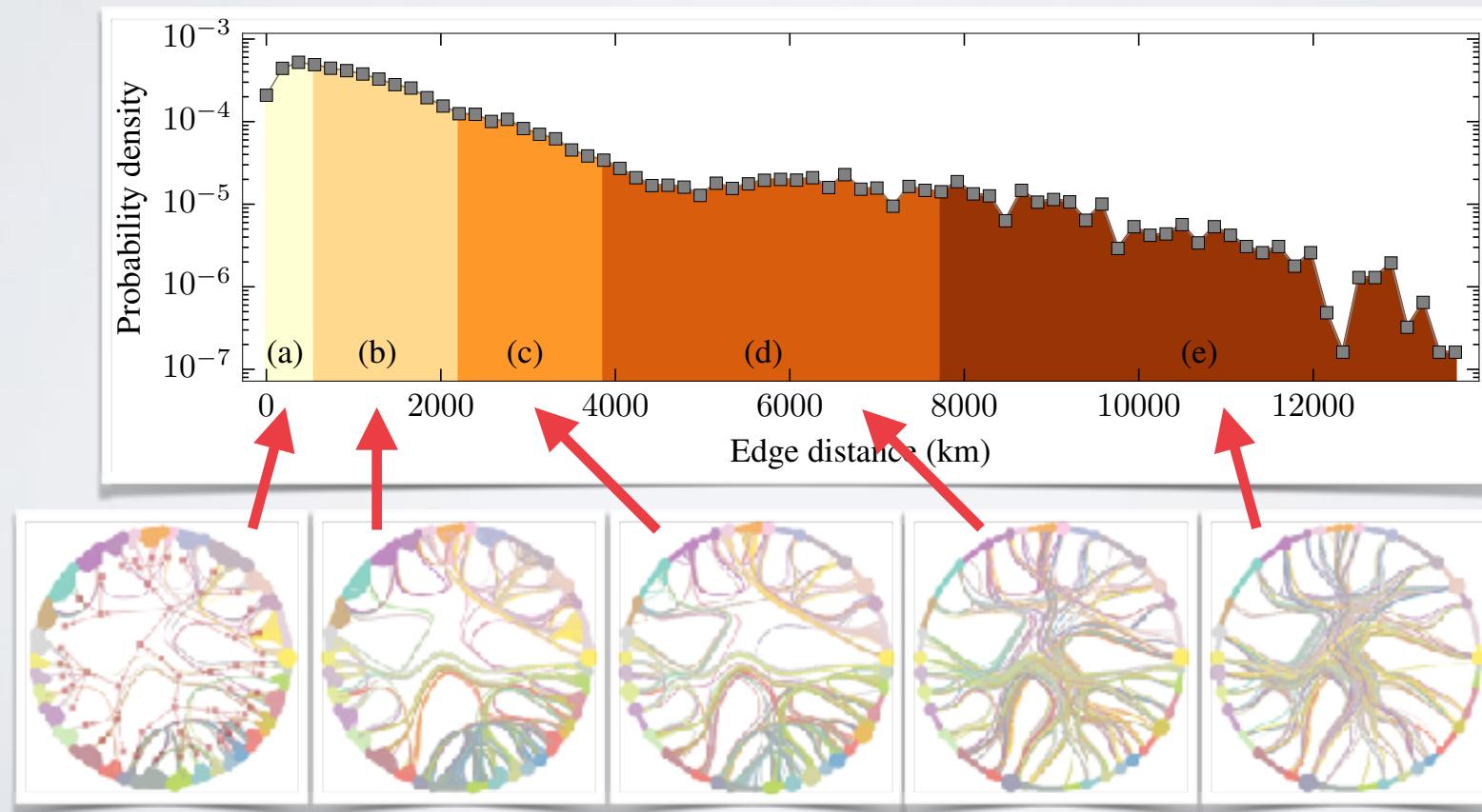


# weighted networks

other approaches (discretized weights = SBM layers)

OpenFlights airport network

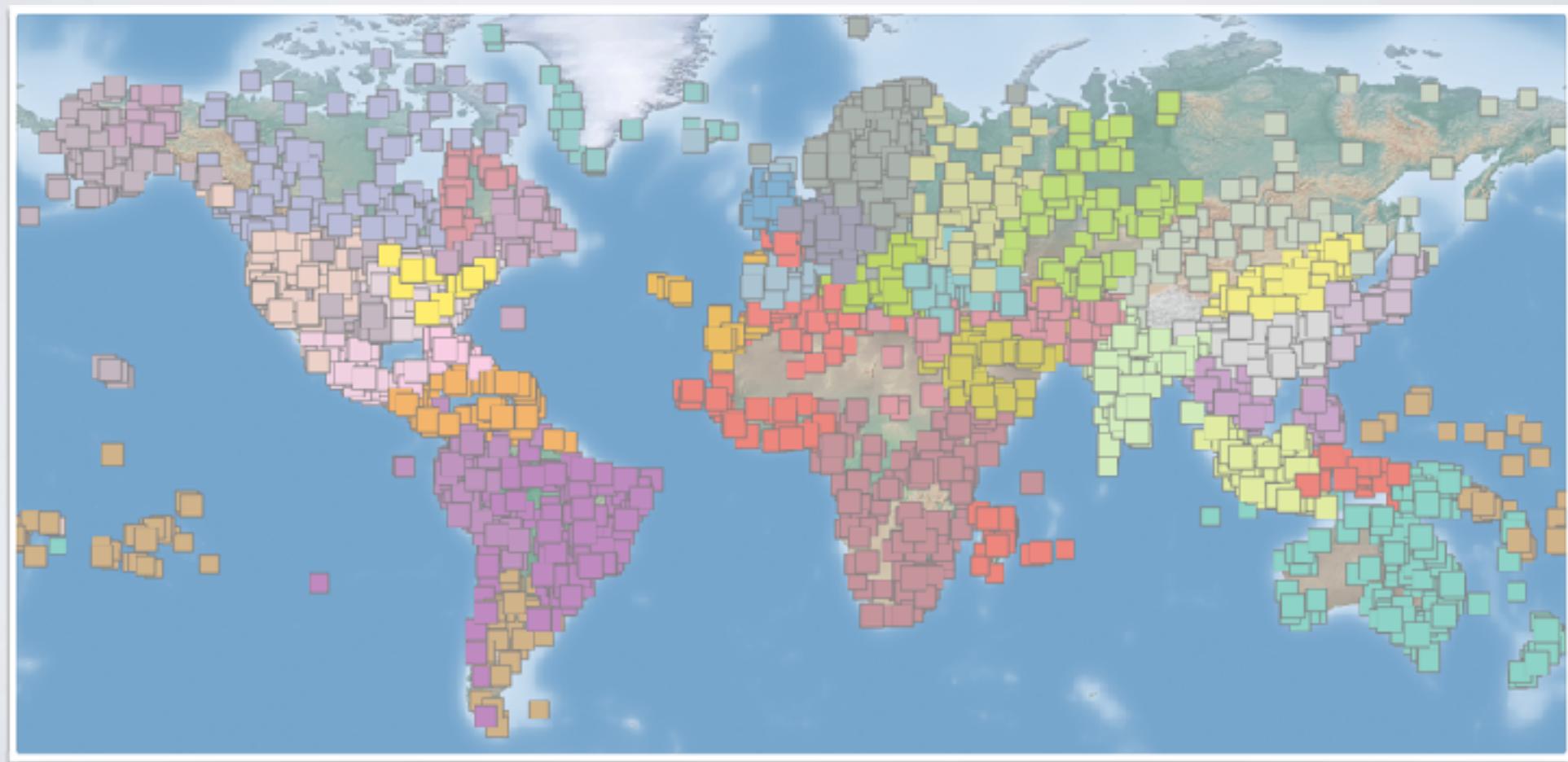
edge weights = distance (km)



# weighted networks

other approaches (discretized weights = SBM layers)

OpenFlights airport network



**fin**

