ControllerPID

-mkp: double-mki: double-mkd: double

+ControllerPID(kp: double, ki: double, kd: double)

~ControllerPID()

+outputPID(refSig: double, feedbackSig: double, timeDelta: double): double

+getKP(): double +getKI(): double +getKD(): double

+setKP(kp: double): void +setKI(ki: double): void +setKD(kd: double): void