

Rigid body dynamics

- Coriolis acceleration

$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + \underbrace{2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r}}_{\text{Coriolis acceleration}} + \underbrace{\vec{\alpha}_{ib} \times \vec{r}}_{\text{Euler acceleration}} + \underbrace{\vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})}_{\text{Centrifugal acceleration}}$$

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$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + \boxed{2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r}} + \textcolor{red}{\text{oval}} \vec{\alpha}_{ib} \times \vec{r} + \boxed{\vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})}$$

- Transversal acceleration

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$$\vec{a}_p = \vec{a}_o + \frac{{}^b d^2}{dt^2} \vec{r} + \boxed{2\vec{\omega}_{ib} \times \frac{{}^b d}{dt} \vec{r}} + \textcolor{red}{\text{oval}} \vec{\alpha}_{ib} \times \vec{r} + \textcolor{green}{\text{rectangle}} \vec{\omega}_{ib} \times (\vec{\omega}_{ib} \times \vec{r})$$

- Transversal acceleration

- Centripetal acceleration