## Praise for Reverse Engineering for Beginners

- "It's very well done .. and for free .. amazing." Daniel Bilar, Siege Technologies, LLC.
- "...excellent and free" Pete Finnigan, Oracle RDBMS security guru.
- "... book is interesting, great job!" Michael Sikorski, author of *Practical Malware Analysis: The Hands-On Guide to Dissecting Malicious Software*.
- "... my compliments for the very nice tutorial!" Herbert Bos, full professor at the Vrije Universiteit Amsterdam, co-author of *Modern Operating Systems (4th Edition)*.
- "... It is amazing and unbelievable." Luis Rocha, CISSP / ISSAP, Technical Manager, Network & Information Security at Verizon Business.
- "Thanks for the great work and your book." Joris van de Vis, SAP Netweaver & Security specialist.
- "... reasonable intro to some of the techniques." (Mike Stay, teacher at the Federal Law Enforcement Training Center, Georgia, US.)
- "I love this book! I have several students reading it at the moment, plan to use it in graduate course." (Sergey Bratus, Research Assistant Professor at the Computer Science Department at Dartmouth College)
- "Dennis @Yurichev has published an impressive (and free!) book on reverse engineering" Tanel Poder, Oracle RDBMS performance tuning expert.

# Reverse Engineering for Beginners



Dennis Yurichev

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Dennis Yurichev <dennis(a)yurichev.com>

## @**()**(\$)=

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Text version (March 22, 2015).

There is probably a newer version of this text, and Russian language version also accessible at beginners.re. E-book reader version is also available on the page.

You may also subscribe to my twitter, to get information about updates of this text, etc: @yurichev

or to subscribe to mailing list .

The cover was made by Andy Nechaevsky: facebook.

<sup>&</sup>lt;sup>6</sup>twitter

<sup>&</sup>lt;sup>7</sup>yurichev.com

# Please donate!

I worked more than one year and half on this book, here are more than 1000 pages, and it's free. Same level books has price tag from \$20 to \$50.

More about it: 0.0.1 on page iv.

I am also looking for a publisher who may want to translate and publish my "Reverse Engineering for Beginners" book to a language other than English/Russian, under the condition that English/Russian version will remain freely available in open-source form. Interested? dennis(a)yurichev.com

Author also available as a freelance teacher of assembly language, reverse engineering, and C language. He can teach remotely via E-Mail, Skype, any other messengers. E-mail: dennis(a)yurichev.com, Skype: dennis.yurichev

Warning: t	his is	shortened	LITE-vers	sion!

It is approximately 6 times shorter than full version (150 pages) and intended to those who wants for very quick introduction to reverse engineering basics. There are nothing about MIPS, ARM, OllyDBG, GCC, GDB, IDA, there are no exercises, examples, etc.

If you still interesting in reverse engieering, full version of the book is always available on my website: beginners.re.

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#### **Preface**

There are several popular meanings of the term "reverse engineering": 1) reverse engineering of software: researching compiled programs; 2) 3D model scanning and reworking in order to make a copy of it; 3) recreating DBMS<sup>8</sup> structure. This book is related to the first meaning.

#### About the author



Dennis Yurichev is an experienced reverse engineer and programmer. His CV is available on his website: yurichev.com. He is open for reverse engineering project offers. He can be contacted by email: dennis(a)yurichev.com, or Skype: dennis.yurichev.

#### **Thanks**

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For illustrations and cover art: Andy Nechaevsky.

Thanks also to all the folks on github.com who have contributed notes and corrections.

Many LETEX packages were used: I would like to thank the authors as well.

#### 0.0.1 Donate

As it turns out, (technical) writing takes a lot of effort and work.

This book is free, available freely and available in source code form <sup>9</sup> (LaTeX), and it will stay so forever.

It is also ad-free.

My current plan for this book is to add lots of information about: PLANS<sup>10</sup>.

If you want me to continue writing on all these topics, you may consider donating.

I worked more than a year on this book  $^{11}$ , there are more than 900 pages. There are at least  $\approx 400$  T<sub>E</sub>X-files,  $\approx 150$  C/C++ source codes,  $\approx 470$  various listings,  $\approx 160$  screenshots.

Price of other books on the same subject varies between \$20 and \$50 on amazon.com.

Ways to donate are available on the page: beginners.re.

Every donor's name will be included in the book! Donors also have a right to ask me to rearrange items in my writing plan.

#### **Donors**

22 \* anonymous, 2 \* Oleg Vygovsky (50+100 UAH), Daniel Bilar (\$50), James Truscott (\$4.5), Luis Rocha (\$63), Joris van de Vis (\$127), Richard S Shultz (\$20), Jang Minchang (\$20), Shade Atlas (5 AUD), Yao Xiao (\$10), Pawel Szczur (40 CHF), Justin Simms (\$20), Shawn the Rock (\$27), Ki Chan Ahn (\$50), Triop AB (100 SEK), Ange Albertini (10 EUR), Sergey Lukianov (300 RUR), Ludvig Gislason (200 SEK), Gérard Labadie (40 EUR), Sergey Volchkov (10 AUD), Vankayala Vigneswararao (\$50), Philippe Teuwen (\$4), Martin Haeberli (\$10), Victor Cazacov (5 EUR), Tobias Sturzenegger (10 CHF), Sonny Thai (\$15), Bayna AlZaabi (\$75), Redfive B.V. (25 EUR), Joona Oskari Heikkilä (5 EUR), Marshall Bishop (\$50), Nicolas Werner (12 EUR), Jeremy Brown

GitHub

<sup>&</sup>lt;sup>8</sup>Database management systems

<sup>&</sup>lt;sup>9</sup>GitHub

<sup>&</sup>lt;sup>10</sup>GitHub

<sup>&</sup>lt;sup>11</sup>Initial git commit from March 2013:

(\$100), Alexandre Borges (\$25), Vladimir Dikovski (50 EUR), Jiarui Hong (100.00 SEK), Jim\_Di (500 RUR), Tan Vincent (\$30), Sri Harsha Kandrakota (10 AUD), Pillay Harish (10 SGD), Timur Valiev (230 RUR), Carlos Garcia Prado (10 EUR), Salikov Alexander (500 RUR), Oliver Whitehouse (30 GBP), Katy Moe (\$14), Maxim Dyakonov (\$3).

## mini-FAQ

Q: Why one should learn assembly language these days?

A: Unless you are OS developer, you probably don't need to write in assembly: modern compilers perform optimizations much better than humans do. <sup>12</sup>. Also, modern CPU<sup>13</sup>s are very complex devices and assembly knowledge would not help you understand its internals. That said, there are at least two areas where a good understanding of assembly may help: first, security/malware research. Second, gaining a better understanding of your compiled code while debugging. Therefore, this book is intended for those who want to understand assembly language rather than to write in it, which is why there are many examples of compiler output.

Q: I clicked on hyperlink inside of PDF-document, how to get back?

A: (Adobe Acrobat Reader) Alt + LeftArrow

Q: May I print this book? Use it for teaching?

A: Of course, that's why book is licensed under Creative Commons terms. Someone may also want to build their own version of book, read here about it.

Q: I want to translate your book to some other language.

A: Read my note to translators.

Q: How would one find a reverse engineering job?

A: There are hiring threads that appear from time to time on reddit devoted to RE<sup>14</sup> (2013 Q3, 2014). Try looking there. A somewhat related hiring thread can be found in the "netsec" subreddit: 2014 Q2.

Q: I have a question...

A: Write me it by email (dennis(a)yurichev.com) or ask your question at my forum: forum.yurichev.com.

#### **About Korean translation**

In January 2015, Acorn publishing company (www.acornpub.co.kr) in South Korea did huge amount of work in translating and publishing my book (state which is it in August 2014) in Korean language.

Now it's available at their website.



<sup>&</sup>lt;sup>12</sup>A very good text about this topic: [Fog13]

<sup>&</sup>lt;sup>13</sup>Central processing unit

<sup>&</sup>lt;sup>14</sup>reddit

Translator is Byungho Min (twitter/tais9).

Cover pictures was done by my artist friend Andy Nechaevsky: facebook/andydinka.

They are also the Korean translation copyright holder.

So if you want to have a *real* book on your shelf in Korean language and/or want to support my work, now you may buy it.

# Part I Code patterns

When I first started learning C and then C++, I used to write small pieces of code, compile them, and look at the assembly language output. This was much easy for me to understand <sup>15</sup>. I did it so many times that the relation between the C/C++ code and what the compiler produced was imprinted deeply in my mind. That is why when I look at assembly code I could instantly grasp what the original C code in general does and looks like. Perhaps this technique could be helpful for someone else and so I'm going to describe some examples here.

Sometimes I use ancient compilers, in order to get the shortest (or simplest) possible code snippet.

## Difference between non-optimized (debug) and optimized (release) versions

A non-optimizing compiler works faster and produces more understandable (verbose, though) code.

An optimizing (release) compiler works slower and tries to produce faster (but not necessarily smaller) code.

One important feature of the debugging code is that there might be debugging information showing connections between each line in source code and machine code addresses. Optimizing compilers tend to produce such output where whole source code lines may be optimized away and not present in the resulting machine code.

Reverse engineer practitioner usually encounters either version because some developers turn on compiler's optimization switches and others do not.

That's why I try to give examples of both versions of code.

<sup>&</sup>lt;sup>15</sup>Frankly speaking, I still do so when I can't understand what some code does.

# A short introduction to the CPU

The CPU is the unit, which executes all of the programs. Short glossary:

**Instruction**: a primitive CPU command. Simplest examples: moving data between registers, working with memory, arithmetic primitives. As a rule, each CPU has its own instruction set architecture (ISA<sup>1</sup>).

**Machine code**: code for the CPU. Each instruction is usually encoded by several bytes.

**Assembly language**: mnemonic code and some extensions like macros which are intended to make a programmer's life easier.

**CPU register**: Each CPU has a fixed set of general purpose registers (GPR<sup>2</sup>).  $\approx 8$  in x86,  $\approx 16$  in x86-64,  $\approx 16$  in ARM. The easiest way to understand a register is to think of it as an untyped temporary variable. Imagine you are working with a high-level PL<sup>3</sup> and you have only 8 32-bit (or 64-bit) variables. Many things can be done using only these!

What is the difference between machine code and a PL? It is much easier for humans to use a high-level PL like C/C++, Java, Python, etc., but it is easier for a CPU to use a much lower level of abstraction. Perhaps, it would be possible to invent a CPU which can execute high-level PL code, but it would be much more complex. On the contrary, it is very inconvenient for humans to use assembly language due to it being low-level. Besides, it is very hard to do it without making a huge amount of annoying mistakes. The program, which converts high-level PL code into assembly, is called a *compiler*.

<sup>&</sup>lt;sup>1</sup>Instruction Set Architecture

<sup>&</sup>lt;sup>2</sup>General Purpose Registers

<sup>&</sup>lt;sup>3</sup>Programming language

# Simplest possible function

Probably the simplest possible function is that one which just returns some constant value. Here it is:

```
int f()
{
     return 123;
};
```

## 2.1 x86

And that's what the optimizing GCC compiler produces:

Listing 2.1: Optimizing GCC

```
f:
mov eax, 123
ret
```

MSVC's result is exactly the same.

There are just two instructions: the first places the value 123 into the EAX register, which is used by convention for storing the return value and the second one is RET, which returns execution to the caller. The caller will take the result from the EAX register.

It has to be noted that MOV is a confusing name for the instruction in both x86 and ARM ISAs. In fact, data is not *moved*, it's rather *copied*.

# Hello, world!

Let's continue with the famous example from the "The C programming Language" [Ker88] book:

```
#include <stdio.h>
int main()
{
    printf("hello, world\n");
    return 0;
}
```

#### 3.1 x86

#### 3.1.1 MSVC

Let's compile it in MSVC 2010:

```
cl 1.cpp /Fa1.asm
```

(/Fa option instructs the compiler to generate assembly listing file)

Listing 3.1: MSVC 2010

```
CONST
        SEGMENT
$SG3830 DB
                 'hello, world', OAH, OOH
        ENDS
CONST
PUBLIC
        _main
        _printf:PROC
EXTRN
; Function compile flags: /Odtp
_TEXT
        SEGMENT
_main
        PROC
        push
                 ebp
        mov
                 ebp, esp
        push
                 OFFSET $SG3830
        call
                 _printf
        add
                 esp, 4
        xor
                 eax, eax
                 ebp
        pop
                 0
        ret
        ENDP
main
_TEXT
        ENDS
```

The compiler generated 1.obj file, which is to be linked into 1.exe.

In our case, the file contains two segments: CONST (for data constants) and \_TEXT (for code).

The string ``hello, world'' in C/C++ has type const char[] [Str13, p176, 7.3.2], however it does not have its own name.

The compiler needs to deal with the string somehow so it defines the internal name \$SG3830 for it.

That is why the example may be rewritten as follows:

```
#include <stdio.h>
const char $SG3830[]="hello, world\n";
int main()
```

CHAPTER 3. HELLO, WORLD! 3.2. X86-64

```
{
    printf($SG3830);
    return 0;
}
```

Let's go back to the assembly listing. As we can see, the string is terminated by a zero byte, which is standard for C/C++ strings. More about C strings: 25.1.1 on page 108.

In the code segment, \_TEXT, there is only one function so far: main().

The function main() starts with prologue code and ends with epilogue code (like almost any function)  $^1$ .

After the function proloque we see the call to the printf() function: CALL \_printf.

Before the call the string address (or a pointer to it) containing our greeting is placed on the stack with the help of the PUSH instruction.

When the printf() function returns the control to the main() function, the string address (or a pointer to it) is still on the stack.

Since we do not need it anymore, the stack pointer (the ESP register) needs to be corrected.

ADD ESP, 4 means add 4 to the ESP register value.

Why 4? Since this is 32-bit program, we need exactly 4 bytes for address passing through the stack. If it was x64 code we would need 8 bytes.

``ADD ESP, 4'' is effectively equivalent to ``POP register'' but without using any register<sup>2</sup>.

Some compilers (like the Intel C++ Compiler) in the same situation may emit POP ECX instead of ADD (e.g., such a pattern can be observed in the Oracle RDBMS code as it is compiled with the Intel C++ compiler). This instruction has almost the same effect but the ECX register contents will be overwritten. The Intel C++ compiler probably uses POP ECX since this instruction's opcode is shorter than ADD ESP, x (1 byte against 3).

Here is an example:

Listing 3.2: Oracle RDBMS 10.2 Linux (app.o file)

.text:0800029A	push	ebx
.text:0800029B	call	qksfroChild
.text:080002A0	pop	ecx

Read more about the stack in section (5 on page 9).

After calling printf(), the original C/C++ code contains the statement return 0 -return 0 as the result of the main() function.

In the generated code this is implemented by the instruction XOR EAX, EAX

XOR is in fact just "eXclusive OR" but the compilers often use it instead of MOV EAX, 0 —again because it is a slightly shorter opcode (2 bytes against 5).

Some compilers emit SUB EAX, EAX, which means *SUBtract the value in the* EAX *from the value in* EAX, which in any case resulting in zero.

The last instruction RET returns the control to the caller. Usually, this is  $C/C++CRT^4$  code, which in its turn returns the control to the  $OS^5$ .

#### 3.2 x86-64

## 3.2.1 MSVC-x86-64

Let's also try 64-bit MSVC:

Listing 3.3: MSVC 2012 x64

```
$SG2989 DB
                  'hello, world', OAH, OOH
        PROC
main
        sub
                 rsp, 40
                 rcx, OFFSET FLAT:$SG2989
        lea
         call
                 printf
        xor
                 eax, eax
                 rsp, 40
        add
        ret
                 n
        ENDP
main
```

<sup>&</sup>lt;sup>1</sup>You can read more about it in section about function prolog and epilog (4 on page 8).

<sup>&</sup>lt;sup>2</sup>CPU flags, however, are modified

<sup>&</sup>lt;sup>3</sup>wikipedia

<sup>&</sup>lt;sup>4</sup>C runtime library

<sup>&</sup>lt;sup>5</sup>Operating System

CHAPTER 3. HELLO, WORLD! 3.3. CONCLUSION

In x86-64, all registers were extended to 64-bit and now their names have an R- prefix. In order to use the stack less often (in other words, to access external memory/cache less often), there exists a popular way to pass function arguments via registers (fastcall). I.e., a part of the function arguments are passed in registers, the rest—via the stack. In Win64, 4 function arguments are passed in RCX, RDX, R8, R9 registers. That is what we see here: a pointer to the string for printf() is now passed not in stack, but in the RCX register.

The pointers are 64-bit now, so they are passed in the 64-bit registers (which have the R - prefix). However, for backward compatibility, it is still possible to access the 32-bit parts, using the E - prefix.

This is how RAX/EAX/AX/AL looks like in 64-bit x86-compatible CPUs:

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
		R.A	X <sup>x64</sup>				
					EA	X	
						Α	Х
						AH	AL

The main() function returns an *int*-typed value, which is, in the C/C++, for better backward compatibility and portability, still 32-bit, so that is why the EAX register is cleared at the function end (i.e., 32-bit part of register) instead of RAX.

There are also 40 bytes allocated in the local stack. This is called "shadow space", about which we are going to talk later: 8.2.1 on page 27.

## 3.3 Conclusion

The main difference between x86/ARM and x64/ARM64 code is that pointer to the string is now 64-bit. Indeed, modern CPUs are 64-bit now because memory is cheaper nowadays. We can add much more memory to our computers and 32-bit pointers are not enough to address it. So all pointers are 64-bit now.

# Function prologue and epilogue

A function prologue is a sequence of instructions at the start of a function. It often looks something like the following code fragment:

```
push ebp
mov ebp, esp
sub esp, X
```

What these instruction do: save the value in the EBP register, sets the value of the EBP register to the value of the ESP and then allocate space on the stack for local variables.

The value in the EBP stays the same over the period of the function execution and is to be used for local variables and arguments access. For the same purpose one can use ESP, but since it changes over time this approach is not too convenient.

The function epilogue frees allocated space in the stack, returns the value in the EBP register back to its initial state and returns the control flow to the callee:

```
mov esp, ebp
pop ebp
ret 0
```

Function prologues and epilogues are usually detected in disassemblers for function delimitation.

#### 4.1 Recursion

Epilogues and prologues can negatively affect the recursion performance. More about recursion in this book: ?? on page ??.

# Stack

The stack is one of the most fundamental data structures in computer science <sup>1</sup>.

Technically, it is just a block of memory in process memory along with the ESP or RSP register in x86 or x64, or the SP<sup>2</sup> register in ARM, as a pointer within that block.

The most frequently used stack access instructions are PUSH and POP (in both x86 and ARM thumb-mode). PUSH subtracts from ESP/RSP/SP 4 in 32-bit mode (or 8 in 64-bit mode) and then writes the contents of its sole operand to the memory address pointed by ESP/RSP/SP.

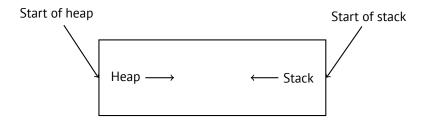
POP is the reverse operation: retrieve the data from memory pointed by SP, loads it into the instruction operand (often a register) and then add 4 (or 8) to the stack pointer.

After stack allocation, the stack pointer points at the bottom of the stack. PUSH decreases the stack pointer and POP increases it. The bottom of the stack is actually at the beginning of the memory allocated for the stack block. It seems strange, but that's the way it is.

## 5.1 Why does the stack grow backwards?

Intuitively, we might think that the stack grow upwards, i.e. towards higher addresses, like any other data structure.

The reason that the stack grows backward is probably historical. When the computers were big and occupied a whole room, it was easy to divide memory into two parts, one for the heap and one for the stack. Of course, it was unknown how big the heap and the stack would be during program execution, so this solution was the simplest possible.



In [RT74] we can read:

The user-core part of an image is divided into three logical segments. The program text segment begins at location 0 in the virtual address space. During execution, this segment is write-protected and a single copy of it is shared among all processes executing the same program. At the first 8K byte boundary above the program text segment in the virtual address space begins a nonshared, writable data segment, the size of which may be extended by a system call. Starting at the highest address in the virtual address space is a stack segment, which automatically grows downward as the hardware's stack pointer fluctuates.

This reminds us how some students write two lecture notes using only one notebook: notes for the first lecture are written as usual, and notes for the second one are written from the end of notebook, by flipping it. Notes may meet each other somewhere in between, in case of lack of free space.

<sup>&</sup>lt;sup>1</sup>wikipedia

<sup>&</sup>lt;sup>2</sup>stack pointer. SP/ESP/RSP in x86/x64. SP in ARM.

## 5.2 What is the stack used for?

#### 5.2.1 Save the function's return address

#### x86

When calling another function with a CALL instruction the address of the point exactly after the CALL instruction is saved to the stack and then an unconditional jump to the address in the CALL operand is executed.

The CALL instruction is equivalent to a PUSH address\_after\_call / JMP operand instruction pair. RET fetches a value from the stack and jumps to it —that is equivalent to a POP tmp / JMP tmp instruction pair. Overflowing the stack is straightforward. Just run eternal recursion:

```
void f()
{
     f();
};
```

MSVC 2008 reports the problem:

...but generates the right code anyway:

```
?f@@YAXXZ PROC
                                                             ; f
; File c:\tmp6\ss.cpp
; Line 2
        push
                 ebp
        mov
                 ebp, esp
; Line 3
                 ?f@@YAXXZ
                                                             ; f
        call
; Line 4
                 ebp
        pop
        ret
?f@@YAXXZ ENDP
                                                             ; f
```

... Also if we turn on the compiler optimization (/0x option) the optimized code will not overflow the stack and will work  $correctly^3$  instead:

## 5.2.2 Passing function arguments

The most popular way to pass parameters in x86 is called "cdecl":

```
push arg3
push arg2
push arg1
call f
add esp, 4*3
```

Callee functions get their arguments via the stack pointer.

Therefore, this is how the argument values are located in the stack before the execution of the f() function's very first instruction:

<sup>&</sup>lt;sup>3</sup>irony here

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ESP	return address
ESP+4	argument#1, marked in IDA4 as arg_0
ESP+8	argument#2, marked in IDA as arg_4
ESP+0xC	argument#3, marked in IDA as arg_8

It is worth noting that nothing obliges programmers to pass arguments through the stack. It is not a requirement. One could implement any other method without using the stack at all.

For example, it is possible to allocate a space for arguments in the heap, fill it and pass it to a function via a pointer to this block in the EAX register. This will work <sup>5</sup>. However, it is a convenient custom in x86 and ARM to use the stack for this purpose.

By the way, the callee function does not have any information about how many arguments were passed. C functions with a variable number of arguments (like printf()) determine their number using format string specifiers (which begin with the % symbol). If we write something like

```
printf("%d %d %d", 1234);
```

printf() will print 1234, and then two random numbers, which were laying next to it in the stack.

That's why it is not very important how we declare the main() function: as main(), main(int argc, char \*argv[]) or main(int argc, char \*argv[], char \*envp[]).

In fact, the CRT-code is calling main() roughly as:

```
push envp
push argv
push argc
call main
...
```

If you declare main() as main() without arguments, they are, nevertheless, still present in the stack, but are not used. If you declare main() as main(int argc, char \*argv[]), you will be able to use first two arguments, and the third will remain "invisible" for your function. Even more, it is possible to declare main(int argc), and it will work.

#### 5.2.3 Local variable storage

A function could allocate space in the stack for its local variables just by shifting the stack pointer towards the stack bottom. Hence, it's very fast, no matter how many local variables are defined.

It is also not a requirement to store local variables in the stack. You could store local variables wherever you like, but traditionally this is how it's done.

#### 5.2.4 x86: alloca() function

It is worth noting the alloca() function.<sup>6</sup>.

This function works like malloc(), but allocates memory directly on the stack.

The allocated memory chunk does not need to be freed via a free() function call, since the function epilogue (4 on page 8) returns ESP back to its initial state and the allocated memory is just *dropped*.

It is worth noting how alloca() is implemented.

In simple terms, this function just shifts ESP downwards toward the stack bottom by the number of bytes you need and sets ESP as a pointer to the *allocated* block. Let's try:

```
#ifdef __GNUC__
#include <alloca.h> // GCC
#else
#include <malloc.h> // MSVC
#endif
#include <stdio.h>

void f()
{
    char *buf=(char*)alloca (600);
#ifdef __GNUC__
    snprintf (buf, 600, "hi! %d, %d, %d\n", 1, 2, 3); // GCC
```

<sup>&</sup>lt;sup>5</sup>For example, in the "The Art of Computer Programming" book by Donald Knuth, in section 1.4.1 dedicated to subroutines[Knu98, section 1.4.1], we could read that one way to supply arguments to a subroutine is simply to list them after the JMP instruction passing control to subroutine. Knuth explains that this method was particularly convenient on IBM System/360.

<sup>&</sup>lt;sup>6</sup>In MSVC, the function implementation can be found in alloca16.asm and chkstk.asm in C:\Program Files (x86)\Microsoft Visual Studio 10.0\VC\crt\src\intel

CHAPTER 5. STACK 5.3. TYPICAL STACK LAYOUT

```
#else
   _snprintf (buf, 600, "hi! %d, %d, %d\n", 1, 2, 3); // MSVC
#endif

puts (buf);
};
```

(\_snprintf() function works just like printf(), but instead of dumping the result into stdout (e.g., to terminal or console), it writes it to the buf buffer. puts() copies buf contents to stdout. Of course, these two function calls might be replaced by one printf() call, but I would like to illustrate small buffer usage.)

#### **MSVC**

Let's compile (MSVC 2010):

Listing 5.1: MSVC 2010

```
. . .
                               ; 00000258H
           eax, 600
    mov
            __alloca_probe_16
    call
           esi, esp
    mov
    push
           3
    push
           2
    push
    push
           OFFSET $SG2672
                              ; 00000258H
    push
           600
    push
           esi
    call
           __snprintf
    push
           esi
    call
            _puts
                              : 000001cH
    add
           esp, 28
```

The sole alloca() argument is passed via EAX (instead of pushing it into the stack) <sup>7</sup>. After the alloca() call, ESP points to the block of 600 bytes and we can use it as memory for the buf array.

#### 5.2.5 (Windows) SEH

SEH<sup>10</sup> records are also stored on the stack (if they present)...

#### 5.2.6 Buffer overflow protection

More about it here (16.2 on page 61).

## 5.3 Typical stack layout

A typical stack layout in a 32-bit environment at the start of a function, before the first instruction execution looks like this:

•••	
ESP-0xC	local variable #2, marked in IDA as var_8
ESP-8	local variable #1, marked in IDA as var_4
ESP-4	saved value of EBP
ESP	return address
ESP+4	argument#1, marked in IDA as arg_0
ESP+8	argument#2, marked in IDA as arg_4
ESP+0xC	argument#3, marked in IDA as arg_8

<sup>&</sup>lt;sup>7</sup>It is because alloca() is rather a compiler intrinsic than a normal function.

One of the reasons we need a separate function instead of just a couple of instructions in the code, is because the MSVC<sup>8</sup> alloca() implementation also has code which reads from the memory just allocated, in order to let the OS map physical memory to this VM<sup>9</sup> region.

<sup>&</sup>lt;sup>10</sup>Structured Exception Handling

# printf() with several arguments

Now let's extend the Hello, world! (3 on page 5) example, replacing printf() in the main() function body with this:

```
#include <stdio.h>
int main()
{
         printf("a=%d; b=%d; c=%d", 1, 2, 3);
         return 0;
};
```

## 6.1 x86

## 6.1.1 x86: 3 arguments

#### **MSVC**

When we compile it with MSVC 2010 Express we get:

```
$SG3830 DB 'a=%d; b=%d; c=%d', 00H
...

push 3
push 2
push 1
push 0FFSET $SG3830
call _printf
add esp, 16 ; 00000010H
```

Almost the same, but now we can see the printf() arguments are pushed onto the stack in reverse order. The first argument is pushed last.

By the way, variables of *int* type in 32-bit environment have 32-bit width, that is 4 bytes.

So, we have 4 arguments here. 4\*4=16 —they occupy exactly 16 bytes in the stack: a 32-bit pointer to a string and 3 numbers of type *int*.

When the stack pointer (ESP register) has changed back by the ADD ESP, X instruction after a function call, often, the number of function arguments could be deduced by simply dividing X by 4.

Of course, this is specific to the *cdecl* calling convention, and only for 32-bit environment.

In certain cases where several functions return right after one another, the compiler could merge multiple ``ADD ESP, X'' instructions into one, after the last call:

```
push a1
push a2
call ...
push a1
call ...
push a1
call a1
push a2
push a2
push a3
call ...
add esp, 24
```

## 6.1.2 x64: 8 arguments

To see how other arguments are passed via the stack, let's change our example again by increasing the number of arguments to 9 (printf() format string + 8 *int* variables):

```
#include <stdio.h>
int main()
{
    printf("a=%d; b=%d; c=%d; d=%d; f=%d; g=%d; h=%d\n", 1, 2, 3, 4, 5, 6, 7, 8);
    return 0;
};
```

#### **MSVC**

As it was mentioned earlier, the first 4 arguments has to be passed through the RCX, RDX, R8, R9 registers in Win64, while all the rest—via the stack. That is exactly what we see here. However, the MOV instruction, instead of PUSH, is used for preparing the stack, so the values are stored to the stack in a straightforward manner.

Listing 6.1: MSVC 2012 x64

```
$SG2923 DB
                  'a=%d; b=%d; c=%d; d=%d; e=%d; f=%d; g=%d; h=%d', OaH, OOH
main
        PR<sub>0</sub>C
        sub
                 rsp, 88
                 DWORD PTR [rsp+64], 8
        mov
                 DWORD PTR [rsp+56], 7
        mov
                 DWORD PTR [rsp+48], 6
        mov
                 DWORD PTR [rsp+40], 5
        mov
                 DWORD PTR [rsp+32], 4
        mov
        mov
                 r9d, 3
        mov
                 r8d, 2
        mov
                 edx, 1
        lea
                 rcx, OFFSET FLAT:$SG2923
        call
                 printf
         ; return 0
                 eax, eax
        xor
                 rsp, 88
        add
         ret
main
        ENDP
TEXT
        ENDS
END
```

The observant reader may ask why are 8 bytes allocated for *int* values, when 4 is enough? Yes, one has to remember: 8 bytes are allocated for any data type shorter than 64 bits. This is established for the convenience's sake: it makes it easy to calculate the address of arbitrary argument. Besides, they are all located at aligned memory addresses. It is the same in the 32-bit environments: 4 bytes are reserved for all data types.

## 6.2 Conclusion

Here is a rough skeleton of the function call:

Listing 6.2: x86

```
PUSH 3rd argument
PUSH 2nd argument
PUSH 1st argument
CALL function
; modify stack pointer (if needed)
```

Listing 6.3: x64 (MSVC)

```
MOV RCX, 1st argument
MOV RDX, 2nd argument
MOV R8, 3rd argument
```

```
MOV R9, 4th argument
...
PUSH 5th, 6th argument, etc (if needed)
CALL function
; modify stack pointer (if needed)
```

## 6.3 By the way

By the way, this difference between the arguments passing in x86, x64, fastcall, ARM and MIPS is a good illustration of the fact that the CPU is oblivious to how the arguments are passed to functions. It is also possible to create a hypothetical compiler able to pass arguments via a special structure without using stack at all.

The CPU is not aware of calling conventions whatsoever.

We may also recall how newcoming assembly language programmers passing arguments into other functions: usually via registers, without any explicit order, or even via global variables. Of course, it works fine.

# scanf()

Now let's use scanf().

## 7.1 Simple example

```
#include <stdio.h>
int main()
{
    int x;
    printf ("Enter X:\n");
    scanf ("%d", &x);
    printf ("You entered %d...\n", x);
    return 0;
};
```

OK, I agree, it is not clever to use scanf() for user interactions nowadays. I wanted, however, to illustrate passing a pointer to a variable of type *int*.

#### 7.1.1 About pointers

Pointers are one of the fundamental concepts in computer science. Often, passing a large array, structure or object as an argument to another function is too expensive, while passing their address is much cheaper. In addition if the callee function needs to modify something in the large array or structure received as a parameter and return back the entire structure then the situation is close to absurd. So the simplest thing to do is to pass the address of the array or structure to the callee function, and let it change what needs to be changed.

A pointer in C/C++ is simply an address of some memory location.

In x86, the address is represented as a 32-bit number (i.e., it is occupying 4 bytes), while in x86-64 it is a 64-bit number (occupying 8 bytes). By the way, that is the reason behind some people's indignation related to switching to x86-64 —all pointers in the x64-architecture require twice as much space.

It is possible to work with untyped pointers only, given some effort; e.g. the standard C function memcpy(), that copies a block from one memory location to another, takes 2 pointers of type void\* as arguments, since it is impossible to predict the type of the data you would like to copy. Data types are not important, only the block size matters.

Pointers are also widely used when a function needs to return more than one value (we are going to get back to this later ). scanf() is such a case. Besides the fact that the function needs to indicate how many values were successfully read, it also needs to return all these values.

In C/C++ the pointer type is only needed for compile-time type checking. Internally, in the compiled code there is no information about pointer types at all.

#### 7.1.2 x86

#### **MSVC**

Here is what we get after compiling with MSVC 2010:

```
CONST SEGMENT

$SG3831 DB 'Enter X:', 0aH, 00H

$SG3832 DB '%d', 00H
```

CHAPTER 7. SCANF() 7.1. SIMPLE EXAMPLE

```
$SG3833
           DB
                  'You entered %d...', OaH, OOH
CONST
         ENDS
PUBLIC
           main
          scanf:PROC
EXTRN
EXTRN
          printf:PROC
; Function compile flags: /Odtp
_TEXT
         SEGMENT
_{x} = -4
                                  ; size = 4
         PROC
_main
           ebp
    push
           ebp, esp
    mov
    push
           ecx
    push
           OFFSET $SG3831 ; 'Enter X:'
            _printf
    call
    add
           esp, 4
           eax, DWORD PTR _x$[ebp]
    lea
    push
           OFFSET $SG3832 ; '%d'
    push
    call
            _scanf
    add
           esp, 8
           ecx, DWORD PTR _x$[ebp]
    mov
    push
    push
           OFFSET $SG3833 ; 'You entered %d...'
            _printf
    call
    add
           esp, 8
    ; return 0
           eax, eax
           esp, ebp
    mov
    pop
           ebp
    ret
           n
         ENDP
main
_TEXT
         ENDS
```

x is a local variable.

According to the C/C++ standard it must be visible only in this function and not from any other external scope. Traditionally, local variables are stored on the stack. There are probably other ways to allocate them, but in x86 that is the way it is.

The goal of the instruction following the function prologue, PUSH ECX, is not to save the ECX state (notice the absence of corresponding POP ECX at the function's end).

In fact it allocates 4 bytes on the stack for storing the x variable.

x is to be accessed with the assistance of the \_x\$ macro (it equals to -4) and the EBP register pointing to the current frame.

Over the span of the function's execution, EBP is pointing to the current stack frame making it possible to access local variables and function arguments via EBP+offset.

It is also possible to use ESP for the same purpose, although that is not very convenient since it changes frequently. The value of the EBP could be perceived as a *frozen state* of the value in ESP at the start of the function's execution.

Here is a typical stack frame layout in 32-bit environment:

EBP-8	local variable #2, marked in IDA as var_8
EBP-4	local variable #1, marked in IDA as var_4
EBP	saved value of EBP
EBP+4	return address
EBP+8	argument#1, marked in IDA as arg_0
EBP+0xC	argument#2, marked in IDA as arg_4
EBP+0x10	argument#3, marked in IDA as arg_8

The scanf() function in our example has two arguments.

The first one is a pointer to the string containing ``%d'' and the second is the address of the x variable.

First, the x variable's address is loaded into the EAX register by the lea eax, DWORD PTR \_x\$[ebp] instruction We could say that in this case LEA simply stores the sum of the EBP register value and the \_x\$ macro in the EAX register. This is the same as lea eax, [ebp-4].

So, 4 is being subtracted from the EBP register value and the result is loaded in the EAX register. Next the EAX register value is pushed into the stack and scanf() is being called.

printf() is being called after that with its first argument - a pointer to the string: ``You entered %d...\n''.

CHAPTER 7. SCANF() 7.2. GLOBAL VARIABLES

The second argument is prepared with: mov ecx, [ebp-4]. The instruction stores the x variable value and not its address, in the ECX register.

Next the value in the ECX is stored on the stack and the last printf() is being called.

#### By the way

By the way, this simple example is a demonstration of the fact that compiler translates list of expressions in C/C++-block into sequential list of instructions. There are nothing between expressions in C/C++, and so in resulting machine code, there are nothing between, control flow slips from one expression to another.

#### 7.1.3 x64

The picture here is similar with the difference that the registers, rather than the stack, are used for arguments passing.

#### **MSVC**

Listing 7.1: MSVC 2012 x64

```
DATA
        SEGMENT
                 'Enter X:', OaH, OOH
$SG1289 DB
$SG1291 DB
                 '%d', 00H
$SG1292 DB
                 'You entered %d...', OaH, OOH
_DATA
        ENDS
_TEXT
        SEGMENT
x$ = 32
        PROC
main
$LN3:
        sub
                 rsp, 56
                 rcx, OFFSET FLAT:$SG1289 ; 'Enter X:'
        lea
        call
                 printf
                 rdx, QWORD PTR x$[rsp]
        lea
        lea
                 rcx, OFFSET FLAT: $SG1291; '%d'
        call
                 scanf
        mov
                 edx, DWORD PTR x$[rsp]
                 rcx, OFFSET FLAT:$SG1292 ; 'You entered %d...'
        lea
        call
                 printf
        ; return 0
        xor
                 eax, eax
        add
                 rsp, 56
        ret
main
        ENDP
_TEXT
        ENDS
```

## 7.2 Global variables

What if the x variable from the previous example was not local but a global one? Then it would have been accessible from any point, not only from the function body. Global variables are considered anti-pattern, but for the sake of the experiment, we could do this.

```
#include <stdio.h>

// now x is global variable
int x;

int main()
{
    printf ("Enter X:\n");
    scanf ("%d", &x);
    printf ("You entered %d...\n", x);
    return 0;
};
```

CHAPTER 7. SCANF() 7.2. GLOBAL VARIABLES

#### 7.2.1 MSVC: x86

```
SEGMENT
DATA
        _x:DWORD
COMM
                   'Enter X:', 0aH, 00H
$SG2456
           DB
$SG2457
            DB
                   '%d', 00H
$SG2458
            DB
                   'You entered %d...', OaH, OOH
         ENDS
_DATA
PUBLIC
           _main
EXTRN
         _scanf:PROC
EXTRN
         _printf:PROC
; Function compile flags: /Odtp
_TEXT
         SEGMENT
_main
         PROC
            ebp
    push
            ebp, esp
    mov
            OFFSET $SG2456
    push
            _printf
    call
    add
            esp, 4
    push
            OFFSET _x
    push
            OFFSET $SG2457
    call
            _scanf
    add
            esp, 8
    mov
            eax, DWORD PTR _x
    push
            eax
    push
            OFFSET $SG2458
            _printf
    call
    add
            esp, 8
    xor
            eax, eax
    pop
            ebp
            n
    ret
         ENDP
_main
_TEXT
         ENDS
```

In this case the x variable is defined in the \_DATA segment and no memory is allocated in the local stack. It is accessed directly, not through the stack. Uninitialized global variables take no space in the executable file (indeed, why one needs to allocate space for variables initially set to zero?), but when someone accesses their address, the OS will allocate a block of zeroes there<sup>1</sup>.

Now let's explicitly assign a value to the variable:

```
int x=10; // default value
```

We got:

```
__DATA SEGMENT
_x DD 0aH
```

Here we see a value 0xA of DWORD type (DD stands for DWORD = 32 bit) for this variable.

If you open the compiled .exe in IDA, you can see the x variable placed at the beginning of the \_DATA segment, and after it you can see text strings.

If you open the compiled .exe from the previous example in IDA, where the value of x was not set, you would see something like this:

```
.data:0040FA80 _x
                               dd?
                                                         DATA XREF: _main+10
.data:0040FA80
                                                           main+22
.data:0040FA84 dword 40FA84
                               dd?
                                                          DATA XREF: memset+1E
                                                          unknown libname 1+28
.data:0040FA84
                                                          DATA XREF:
.data:0040FA88 dword 40FA88
                               dd?
                                                                      sbh find block+5
.data:0040FA88
                                                          ___sbh_free_block+2BC
.data:0040FA8C ; LPVOID lpMem
.data:0040FA8C lpMem
                               dd?
                                                          DATA XREF: _
                                                                      ___sbh_find_block+B
.data:0040FA8C
                                                             sbh_free_block+2CA
.data:0040FA90 dword_40FA90
                                                          DATA XREF: _V6_HeapAlloc+13
                               dd?
.data:0040FA90
                                                            _calloc_impl+72
.data:0040FA94 dword_40FA94
                               dd?
                                                         DATA XREF: ___sbh_free_block+2FE
```

<sup>&</sup>lt;sup>1</sup>That is how a VM behaves

\_x is marked with? with the rest of the variables that do not need to be initialized. This implies that after loading the .exe to the memory, a space for all these variables is to be allocated and filled with zeroes [ISO07, 6.7.8p10]. But in the .exe file these uninitialized variables do not occupy anything. This is convenient for example when using large arrays.

#### 7.2.2 MSVC: x64

Listing 7.2: MSVC 2012 x64

```
_DATA
        SEGMENT
COMM
        x:DWORD
$SG2924 DB
                 'Enter X:', 0aH, 00H
$SG2925 DB
                 '%d', 00H
$SG2926 DB
                 'You entered %d...', OaH, OOH
_DATA
        ENDS
_TEXT
        SEGMENT
        PROC
main
$LN3:
        sub
                 rsp, 40
        lea
                 rcx, OFFSET FLAT: $SG2924; 'Enter X:'
        call
                 printf
        lea
                 rdx, OFFSET FLAT:x
                 rcx, OFFSET FLAT:$SG2925 ; '%d'
        lea
        call
                 scanf
                 edx, DWORD PTR x
        mov
                 rcx, OFFSET FLAT:$SG2926 ; 'You entered %d...'
        lea
        call
                 printf
        ; return 0
        xor
                 eax, eax
        add
                 rsp, 40
        ret
                 0
main
        ENDP
TEXT
        ENDS
```

The code is almost the same as in x86. Please note that the address of the x variable is passed to scanf() using a LEA instruction, while the variable's value is passed to the second printf() using a MOV instruction. ``DWORD PTR'' is a part of the assembly language (no relation to the machine code), indicating that the variable data size is 32-bit and the MOV instruction has to be encoded accordingly.

## 7.3 scanf() result checking

As I noted before, it is slightly old-fashioned to use scanf() today. But if we have to, we need to at least check if scanf() finishes correctly without an error.

By standard, the  $scanf()^2$  function returns the number of fields it has successfully read. In our case, if everything goes fine and the user enters a number scanf() returns 1, or in case of error (or  $EOF^3$ ) - 0. I have added some C code to check the scanf() return value and print error message in case of an error. This works as expected:

<sup>&</sup>lt;sup>2</sup>scanf, wscanf: MSDN

<sup>&</sup>lt;sup>3</sup>End of file

```
C:\...>ex3.exe
Enter X:
123
You entered 123...

C:\...>ex3.exe
Enter X:
ouch
What you entered? Huh?
```

#### 7.3.1 MSVC: x86

Here is what we get in the assembly output (MSVC 2010):

```
eax, DWORD PTR _x$[ebp]
        push
                eax
                OFFSET $SG3833 ; '%d', 00H
        push
        call
                 scanf
        add
                esp, 8
        cmp
                eax, 1
        ine
                SHORT $LN2@main
        mov
                ecx, DWORD PTR _x$[ebp]
        push
                ecx
        push
                OFFSET $SG3834; 'You entered %d...', OaH, OOH
        call
                 printf
        add
                 esp, 8
                SHORT $LN1@main
        jmp
$LN2@main:
                OFFSET $SG3836; 'What you entered? Huh?', OaH, OOH
        push
        call
                 _printf
        add
                esp, 4
$LN1@main:
                eax, eax
```

The Caller function (main()) needs the callee function (scanf()) result, so the callee returns it in the EAX register. We check it with the help of the instruction CMP EAX, 1 (CoMPare). In other words, we compare the value in the EAX register with 1.

A JNE conditional jump follows the CMP instruction. JNE stands for Jump if Not Equal.

So, if the value in the EAX register is not equal to 1, the CPU will pass the execution to the address mentioned in the JNE operand, in our case \$LN2@main. Passing the control to this address results in the CPU executing printf() with the argument ``What you entered? Huh?''. But if everything is fine, the conditional jump is not be be taken, and another printf() call is to be executed, with two arguments: 'You entered %d...' and the value of x.

Since in this case the second printf() has not to be executed, there is a JMP preceding it (unconditional jump). It passes the control to the point after the second printf() and just before the XOR EAX, EAX instruction, which implements return 0.

So, it could be said that comparing a value with another is *usually* implemented by CMP/Jcc instruction pair, where *cc* is *condition code*. CMP compares two values and sets processor flags<sup>4</sup>. Jcc checks those flags and decides to either pass the control to the specified address or not.

This could sound paradoxical, but the CMP instruction is in fact SUB (subtract). All arithmetic instructions set processor flags, not just CMP. If we compare 1 and 1, 1-1 is 0 so the ZF flag would be set (meaning that the last result was 0). In no other circumstances ZF can be set, except when the operands are equal. JNE checks only the ZF flag and jumps only if it is not set. JNE is in fact a synonym for JNZ (*Jump if Not Zero*). Assembler translates both JNE and JNZ instructions into the same opcode. So, the CMP instruction can be replaced with a SUB instruction and almost everything will be fine, with the difference that SUB alters the value of the first operand. CMP is *SUB without saving the result*.

<sup>&</sup>lt;sup>4</sup>x86 flags, see also: wikipedia.

#### 7.3.2 MSVC: x86 + Hiew

This can also be used as a simple example of executable file patching. We may try to patch the executable so the program would always print the input, no matter what we enter.

Assuming that the executable is compiled against external MSVCR\*.DLL (i.e., with /MD option)<sup>5</sup>, we see the main() function at the beginning of the .text section. Let's open the executable in Hiew and find the beginning of the .text section (Enter, F8, F6, Enter, Enter).

We can see this:

```
Hiew: ex3.exe
                                                                                                   a32 PE .00401000 Hiew 8.02 (c)SEN
   C:\Polygon\ollydbg\ex3.exe
                                           DFRO
.00401000: 55
                                                         ebp
                                            push
00401001: 8BEC
                                            mov
                                                         ebp,esp
00401003: 51
                                            push
                                                         ecx
00401004: 6800304000
                                                         000403000 ; 'Enter X:' -- 11
                                            push
.00401009: FF1594204000
                                            call
                                                         printf
0040100F: 83C404
                                            add
                                                         esp,4
.00401012: 8D45FC
                                            lea
                                                         eax,[ebp][-4]
.00401015: 50
                                            push
                                                         eax
.00401016: 680C304000
                                                         00040300C -- E2
                                            push
0040101B: FF158C204000
                                                         scanf
                                            call
00401021: 83C408
                                            add
                                                         esp.8
.00401024: 83F801
                                                         eax,1
                                            CMD
00401027: 7514
                                            jnz
00401029: 8B4DFC
                                                         ecx,[ebp][-4]
                                            mov
0040102C: 51
                                            push
.0040102D: 6810304000
                                                         000403010 ; 'You entered %d...' -- 24
                                            push
.00401032: FF1594204000
                                            call.
                                                         printf
00401038: 83C408
                                            add
                                                         esp,8
                                                         00040104B --E5
0040103B: EB0E
                                            jmps
                                                         000403<mark>024 ;'W</mark>hat you entered? Huh?' --⊡6
.0040103D: 6824304000
                                           3push
00401042: FF1594204000
                                            call
                                                         printf
00401048: 83C404
                                            add
                                                         esp,4
0040104B: 33C0
                                           5xor
                                                         eax,eax
.0040104D: 8BE5
                                            mov
                                                         esp,ebp
.0040104F: 5D
                                                         ebp
                                            pop
.00401050: C3
                                                         eax,000005A4D;' ZM'
00401051: B84D5A0000
                                            mov
                                                     irect 8Table 91byte 10Leave 11Naked 12AddNam
Global 2FilBlk 3CryBlk 4ReLoad 5OrdLdr
                                         6Strin
```

Figure 7.1: Hiew: main() function

Hiew finds ASCIIZ<sup>6</sup> strings and displays them, as it does with the imported functions' names.

<sup>&</sup>lt;sup>5</sup>that's what also called "dynamic linking"

<sup>&</sup>lt;sup>6</sup>ASCII Zero (null-terminated ASCII string)

Move the cursor to address .00401027 (where the JNZ instruction, we have to bypass, is located), press F3, and then type "9090" (meaning two  $NOP^7$ s):

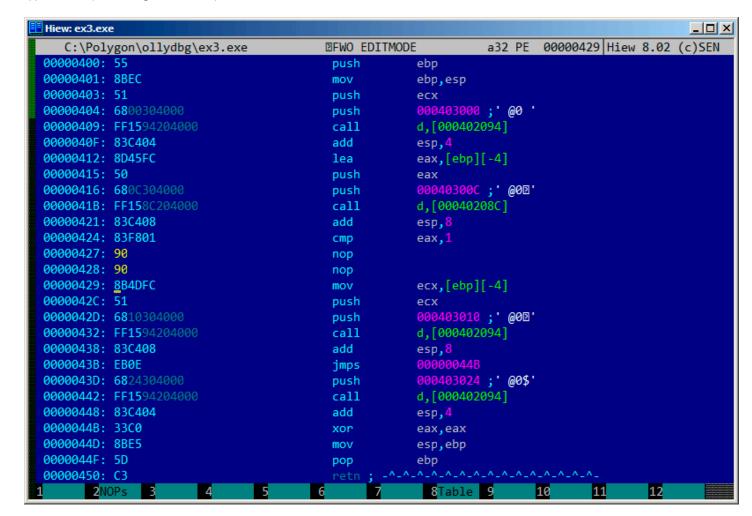


Figure 7.2: Hiew: replacing JNZ with two NOPs

Then press F9 (update). Now the executable is saved to the disk. It will behave as we wanted.

Two NOPs are probably not the most æsthetic approach. Another way to patch this instruction is to write just 0 to the second opcode byte (jump offset), so that JNZ will always jump to the next instruction.

We could also do the opposite: replace first byte with EB while not touching the second byte (jump offset). We would get an unconditional jump that is always triggered. In this case the error message would be printed every time, no matter the input.

#### 7.3.3 MSVC: x64

Since we work here with *int*-typed variables, which are still 32-bit in x86-64, we see how the 32-bit part of the registers (prefixed with E-) are used here as well. While working with pointers, however, 64-bit register parts are used, prefixed with R-.

Listing 7.3: MSVC 2012 x64

```
DATA
        SEGMENT
$SG2924 DB
                 'Enter X:', 0aH, 00H
$SG2926 DB
                 '%d', 00H
                 'You entered %d...', OaH, OOH
$SG2927 DB
$SG2929 DB
                 'What you entered? Huh?', OaH,
_DATA
        ENDS
        SEGMENT
TEXT
x$ = 32
        PROC
main
$LN5:
                 rsp, 56
        sub
```

<sup>&</sup>lt;sup>7</sup>No OPeration

CHAPTER 7. SCANF() 7.3. SCANF() RESULT CHECKING

```
rcx, OFFSET FLAT:$SG2924 ; 'Enter X:'
        lea
                printf
        call
        lea
                rdx, QWORD PTR x$[rsp]
                rcx, OFFSET FLAT:$SG2926 ; '%d'
        lea
        call
                scanf
        cmp
                eax, 1
                SHORT $LN2@main
        jne
                edx, DWORD PTR x$[rsp]
        mov
                rcx, OFFSET FLAT:$SG2927 ; 'You entered %d...'
        lea
        call
                printf
                SHORT $LN1@main
        jmp
$LN2@main:
        lea
                rcx, OFFSET FLAT:$SG2929 ; 'What you entered? Huh?'
        call
                printf
$LN1@main:
        ; return 0
                eax, eax
        xor
        add
                rsp, 56
                0
        ret
        ENDP
main
_TEXT
        ENDS
END
```

# Accessing passed arguments

Now we figured out that the caller function is passing arguments to the callee via the stack. But how does the callee access them?

Listing 8.1: simple example

```
#include <stdio.h>
int f (int a, int b, int c)
{
    return a*b+c;
};
int main()
{
    printf ("%d\n", f(1, 2, 3));
    return 0;
};
```

## 8.1 x86

#### 8.1.1 MSVC

Here is what we get after compilation (MSVC 2010 Express):

Listing 8.2: MSVC 2010 Express

```
SEGMENT
_TEXT
_a$ = 8
                                                           ; size = 4
_b = 12
                                                           ; size = 4
_c = 16
                                                           ; size = 4
_f
        PROC
                ebp
        push
        mov
                ebp, esp
        mov
                eax, DWORD PTR _a$[ebp]
                eax, DWORD PTR _b$[ebp]
        imul
                eax, DWORD PTR _c$[ebp]
        add
        pop
                ebp
                0
        ret
_f
        ENDP
_main
        PROC
        push
                ebp
                ebp, esp
        mov
        push
                3 ; 3rd argument
                2 ; 2nd argument
        push
                1;
                    1st argument
        push
                _f
        call
        add
                esp, 12
        push
        push
                OFFSET $SG2463 ; '%d', OaH, OOH
        call
                 _printf
                esp, 8
        add
        ; return 0
```

```
xor eax, eax
pop ebp
ret 0
_main ENDP
```

What we see is that the main() function pushes 3 numbers onto the stack and calls f(int,int,int). Argument access inside f() is organized with the help of macros like: \_a\$ = 8, in the same way as local variables, but with positive offsets (addressed with plus). So, we are addressing the outer side of the stack frame by adding the \_a\$ macro to the value in the EBP register.

Then the value of a is stored into EAX. After IMUL instruction execution, the value in EAX is a product of the value in EAX and the content of \_b. After that, ADD adds the value in \_c to EAX. The value in EAX does not need to be moved: it is already where it must be. On returning to caller, it takes the EAX value and use it as an argument to printf().

### 8.2 x64

The story is a bit different in x86-64, function arguments (first 4 or first 6 of them) are passed in registers i.e. the callee reads them from there instead of reading them from the stack.

### 8.2.1 MSVC

Optimizing MSVC:

Listing 8.3: Optimizing MSVC 2012 x64

```
$SG2997 DB
                 '%d', 0aH, 00H
        PROC
main
        sub
                 rsp, 40
                 edx, 2
        mov
        lea
                 r8d, QWORD PTR [rdx+1]; R8D=3
                 ecx, QWORD PTR [rdx-1]; ECX=1
        lea
        call
        lea
                 rcx, OFFSET FLAT:$SG2997; '%d'
        mov
                 edx, eax
                 printf
        call
        xor
                 eax, eax
        add
                 rsp, 40
        ret
                 0
        ENDP
main
        PROC
f
         ECX - 1st argument
          EDX - 2nd argument
         ; R8D - 3rd argument
        imul
                 ecx, edx
                 eax, DWORD PTR [r8+rcx]
        lea
        ret
                 0
f
        FNDP
```

As we can see, the compact function f() takes all its arguments from the registers. The LEA instruction here is used for addition, apparently the compiler considered it faster than ADD. LEA is also used in the main() function to prepare the first and third f() arguments. The compiler must have decided that this would work faster than the usual way of loading values into a register — using MOV instruction.

Let's take a look at the non-optimizing MSVC output:

Listing 8.4: MSVC 2012 x64

```
f
                proc near
; shadow space:
arg_0
                = dword ptr
arg_8
                = dword ptr
                              10h
arg_10
                = dword ptr
                              18h
                 ; ECX - 1st argument
                  EDX - 2nd argument
                  R8D - 3rd argument
                mov
                         [rsp+arg_10], r8d
                mov
                         [rsp+arg_8], edx
```

```
[rsp+arg_0], ecx
                 mov
                 mov
                          eax, [rsp+arg_0]
                          eax, [rsp+arg_8]
                 imul
                 add
                          eax, [rsp+arg_10]
                 retn
f
                 endp
main
                 proc near
                         rsp, 28h
                 sub
                          r8d, 3 ; 3rd argument
                 mov
                         edx, 2 ; 2nd argument
                 mov
                 mov
                          ecx, 1; 1st argument
                 call
                          f
                         edx, eax
                 mov
                 lea
                          rcx, $SG2931
                                           ; "%d\n"
                 call
                          printf
                 ; return 0
                 xor
                          eax, eax
                 add
                          rsp, 28h
                 retn
main
                 endp
```

It looks somewhat puzzling because all 3 arguments from the registers are saved to the stack for some reason. This is called "shadow space" <sup>1</sup>: every Win64 may (but is not required to) save all 4 register values there. This is done for two reasons: 1) it is too lavish to allocate a whole register (or even 4 registers) for an input argument, so it will be accessed via stack; 2) the debugger is always aware where to find the function arguments at a break <sup>2</sup>.

So, some large functions can save their input arguments in the "shadows space" if they need to use them during execution, but some small functions (like ours) may not do this.

It is a caller responsibility to allocate "shadow space" in the stack.

<sup>&</sup>lt;sup>1</sup>MSDN

<sup>&</sup>lt;sup>2</sup>MSDN

# More about results returning

In x86, the result of function execution is usually returned  $^{1}$  in the EAX register. If it is byte type or a character (*char*), then the lowest part of register EAX (AL) is used. If a function returns a *float* number, the FPU register ST(0) is used instead.

# 9.1 Attempt to use the result of a function returning *void*

So, what if the main() function return value was declared of type *void* and not *int*? The so-called startup-code is calling main() roughly as follows:

```
push envp
push argv
push argc
call main
push eax
call exit
```

In other words:

```
exit(main(argc,argv,envp));
```

If you declare main() as *void*, nothing is to be returned explicitly (using the *return* statement), then something random, that was stored in the EAX register at the end of main() becomes the sole argument of the exit() function. Most likely, there will be a random value, left from your function execution, so the exit code of program is pseudorandom.

I can illustrate this fact. Please note that here the main() function has a void return type:

```
#include <stdio.h>

void main()
{
    printf ("Hello, world!\n");
};
```

Let's compile it in Linux.

GCC 4.8.1 replaced printf() with puts(), but that's OK, since puts() returns the number of characters printed out, just like printf(). Please notice that EAX is not zeroed before main()'s end. This implies that the value of EAX at the end of main() contains what puts() has left there.

Listing 9.1: GCC 4.8.1

```
.LC0:
         .string "Hello, world!"
main:
         push
                 ebp
        mov
                 ebp, esp
        and
                 esp, -16
         sub
                 esp, 16
                 DWORD PTR [esp], OFFSET FLAT:.LCO
        mov
        call
                 puts
        leave
        ret
```

Let's write a bash script that shows the exit status:

<sup>&</sup>lt;sup>1</sup>See also: MSDN: Return Values (C++): MSDN

### Listing 9.2: tst.sh

```
#!/bin/sh
./hello_world
echo $?
```

And run it:

```
$ tst.sh
Hello, world!
14
```

14 is the number of characters printed.

## 9.2 What if we do not use the function result?

printf() returns the count of characters successfully output, but the result of this function is rarely used in practice. It is also possible to call a function whose essence is in returning a value, and not use it:

```
int f()
{
    // skip first 3 random values
    rand();
    rand();
    rand();
    rand use 4th
    return rand();
};
```

The result of the rand() function is left in EAX, in all four cases. But in the first 3 cases, the value in EAX is just thrown away.

# **GOTO**

The GOTO operator is considered harmful [Dij68], but nevertheless, it can be used reasonably [Knu74], [Yur13, p. 1.3.2]. Here is a very simple example:

```
#include <stdio.h>
int main()
{
    printf ("begin\n");
    goto exit;
    printf ("skip me!\n");
exit:
    printf ("end\n");
};
```

Here is what we've get in MSVC 2012:

Listing 10.1: MSVC 2012

```
$SG2934 DB
                 'begin', OaH, OOH
$SG2936 DB
                 'skip me!', OaH, OOH
                 'end', 0aH, 00H
$SG2937 DB
main
        PROC
        push
                 ebp
        mov
                 ebp, esp
        push
                 OFFSET $SG2934 ; 'begin'
        call
                 _printf
                 esp, 4
        add
                 SHORT $exit$3
        jmp
                 OFFSET $SG2936 ; 'skip me!'
        push
                 _printf
        call
        add
                 esp, 4
$exit$3:
                 OFFSET $SG2937; 'end'
        push
        call
                 _printf
        add
                 esp, 4
        xor
                 eax, eax
        pop
                 ebp
        ret
                 0
        ENDP
main
```

The *goto* statement is just replaced by a JMP instruction, which has the same effect: unconditional jump to another place. The second printf() call can be executed only with human intervention, by using a debugger or patching.

## 10.1 Dead code

The second printf() call is also called "dead code" in compiler terms. This mean, the code will never be executed. So when you compile this example with optimizations, the compiler removes "dead code", leaving no trace of it:

Listing 10.2: Optimizing MSVC 2012

```
$SG2981 DB 'begin', 0aH, 00H
```

CHAPTER 10. GOTO 10.1. DEAD CODE

```
'skip me!', 0aH, 00H
'end', 0aH, 00H
$SG2983 DB
$SG2984 DB
         PROC
_main
                  OFFSET $SG2981 ; 'begin'
         push
                  _printf
         call
         push
                  OFFSET $SG2984 ; 'end'
$exit$4:
         call
                  _printf
         add
                  esp, 8
         xor
                  eax, eax
                  0
         ret
_main
        ENDP
```

However, the compiler forgot to remove the "skip me!" string.

# **Conditional jumps**

# 11.1 Simple example

```
#include <stdio.h>
void f_signed (int a, int b)
    if (a>b)
        printf ("a>b\n");
    if (a==b)
        printf ("a==b\n");
    if (a<b)
        printf ("a<b\n");</pre>
};
void f_unsigned (unsigned int a, unsigned int b)
    if (a>b)
        printf ("a>b\n");
    if (a==b)
        printf ("a==b\n");
    if (a<b)
        printf ("a<b\n");</pre>
};
int main()
    f_signed(1, 2);
    f_unsigned(1, 2);
    return 0;
};
```

#### 11.1.1 x86

#### x86 + MSVC

What we have in the f\_signed() function:

Listing 11.1: Non-optimizing MSVC 2010

```
_a = 8
_b$ = 12
_f_signed PROC
    push
           ebp
    mov
           ebp, esp
           eax, DWORD PTR _a$[ebp]
   mov
           eax, DWORD PTR _b$[ebp]
    cmp
    jle
           SHORT $LN3@f_signed
                                 ; 'a>b'
    push
           OFFSET $SG737
           _printf
    call
    add
           esp, 4
$LN3@f_signed:
           ecx, DWORD PTR _a$[ebp]
```

CHAPTER 11. CONDITIONAL JUMPS 11.1. SIMPLE EXAMPLE

```
ecx, DWORD PTR _b$[ebp]
    cmp
           SHORT $LN2@f_signed
    jne
    push
           OFFSET $SG739
                                  ; 'a==b'
    call
            printf
    add
           esp, 4
$LN2@f_signed:
           edx, DWORD PTR _a$[ebp]
    mov
           edx, DWORD PTR _b$[ebp]
    cmp
           SHORT $LN4@f_signed
    jge
                                  ; 'a<b'
           OFFSET $SG741
    push
    call
           _printf
    add
           esp, 4
$LN4@f_signed:
    pop
           ebp
           0
    ret
_f_signed ENDP
```

The first instruction, JLE, stands for *Jump if Less or Equal*. In other words, if the second operand is larger than first or equal, control is to be passed to address or label mentioned in instruction. If this condition does not trigger (second operand smaller than first), the control flow is not to be altered and the first printf() is to be called. The second check is JNE: *Jump if Not Equal*. Control flow will not change if the operands are equal. The third check is JGE: *Jump if Greater or Equal*—jump if the first operand is larger than the second or if they are equal. So, if all three conditional jumps are triggered, no printf() to be called whatsoever. But it is impossible without special intervention.

The f\_unsigned() function is the same, with the exception that the JBE and JAE instructions are used here instead of JLE and JGE, see below:

Now let's take a look at the f\_unsigned() function

#### Listing 11.2: GCC

```
; size = 4
a$ = 8
_{b} = 12
            size = 4
_f_unsigned PROC
    push
    mov
           ebp, esp
           eax, DWORD PTR _a$[ebp]
    mov
           eax, DWORD PTR _b$[ebp]
    cmp
           SHORT $LN3@f_unsigned
    jbe
                              ; 'a>b'
           OFFSET $SG2761
    push
            _printf
    call
    add
           esp, 4
$LN3@f unsigned:
           ecx, DWORD PTR _a$[ebp]
    mov
           ecx, DWORD PTR b$[ebp]
    jne
           SHORT $LN2@f_unsigned
    push
           OFFSET $SG2763
                              ; 'a==b'
           _printf
    call
    add
           esp, 4
$LN2@f_unsigned:
           edx, DWORD PTR _a$[ebp]
    mov
           edx, DWORD PTR _b$[ebp]
    cmp
    jae
           SHORT $LN4@f_unsigned
           OFFSET $SG2765
    push
           _printf
    call
    add
           esp, 4
$LN4@f_unsigned:
    pop
           ebp
           n
    ret
_f_unsigned ENDP
```

Almost the same, with these different instructions: JBE—Jump if Below or Equal and JAE—Jump if Above or Equal. The difference in these instructions (JA/JAE/JBE/JBE) JG/JGE/JL/JLE is that they work with unsigned numbers.

See also the section about signed number representations (22 on page 101). So, where we see JG/JL instead of JA/JBE or vice-versa, we can almost be sure that the variables are signed or unsigned, respectively.

Here is also the main() function, where there is nothing much new to us:

#### Listing 11.3: main()

```
_main PROC
push ebp
mov ebp, esp
push 2
```

CHAPTER 11. CONDITIONAL JUMPS 11.1. SIMPLE EXAMPLE

```
push
call
                   _f_signed esp, 8
         add
          push
          push
                   _f_unsigned esp, 8
          call
          add
          xor
                    eax, eax
                    ebp
          pop
                    0
          ret
         ENDP
_main
```

CHAPTER 11. CONDITIONAL JUMPS 11.1. SIMPLE EXAMPLE

#### x86 + MSVC + Hiew

We can try to patch the executable file in a way that the f\_unsigned() function will always print "a==b", for any input values.

Here is how it looks in Hiew:

```
Hiew: 7_1.exe
                                                                                                   _ 🗆 🗆
                                                                    a32 PE
                                                                           .00401000 Hiew 8.02
                                                                                                 (c)SEN
    C:\Polygon\ollydbg\7_1.exe
                                           ⊒FRO
.00401000: 55
                                            push
                                                         ebp
.00401001: 8BEC
                                            mov
                                                         ebp, esp
.00401003: 8B4508
                                                         eax,[ebp][8]
                                            mov
00401006: 3B450C
                                                         eax,[ebp][00C]
                                            cmp
00401009: 7E0D
                                            jle
0040100B: 6800B04000
                                            push
                                                        .0004010BF -- E3
00401010: E8AA000000
                                            call
00401015: 83C404
                                            add
                                                         esp,4
00401018: 8B4D08
                                            1mov
                                                         ecx,[ebp][8]
.0040101B: 3B4D0C
                                            cmp
                                                         ecx,[ebp][00C]
.0040101E: 750D
                                                        .00040102D --■4
                                            jnz
                                                         00040B008 ; a==b' --E5
.00401020: 6808B04000
                                            push
                                                         .0004010BF --E3
00401025: E895000000
                                            call
0040102A: 83C404
                                            add
                                                         esp,4
0040102D: 8B5508
                                           4mov
                                                         edx,[ebp][8]
00401030: 3B550C
                                                         edx,[ebp][00C]
                                            cmp
00401033: 7D0D
                                            jge
00401035: 6810B04000
                                            push
                                                         00040B010 --E7
.0040103A: E880000000
                                                        .0004010BF --■3
                                            call
.0040103F: 83C404
                                            add
                                                         esp,4
.00401042: 5D
                                           6pop
                                                         ebp
00401043: C3
00401044: CC
                                            int
00401045: CC
                                            int
00401046: CC
                                            int
00401047: CC
                                            int
00401048: CC
                                            int
                3CryBlk 4ReLoad 5OrdLdn
                                                  7Direct 8Table 91byte 10Leave 11Naked 12AddNam
1Global 2FilBlk
                                          6String
```

Figure 11.1: Hiew: f\_unsigned() function

Essentially, we've got three tasks:

- force the first jump to always trigger;
- force the second jump to never trigger;
- force the third jump to always trigger.

Thus we can point the code flow to the second printf(), and it always print "a==b". Three instructions (or bytes) has to be patched:

- The first jump will now be JMP, but the jump offset is still the same.
- The second jump may be triggered sometimes, but in any case it will jump to the next instruction, because, we set the jump offset to 0. Jump offset is just gets added to the address for the next instruction in these instructions. So if the offset is 0, the jump slips to the next instruction.
- The third jump we convert into JMP just as the first one, so it is always triggering.

That's what we do:

```
Hiew: 7_1.exe
                                                                                                  _ 🗆 🗵
   C:\Polygon\ollydbg\7_1.exe

□FWO EDITMODE

                                                                   a32 PE
                                                                            00000434 Hiew 8.02 (c)SEN
00000400: 55
                                            push
                                                         ebp
00000401: 8BEC
                                                         ebp,esp
                                            mov
00000403: 8B4508
                                            mov
                                                         eax,[ebp][8]
                                                         eax,[ebp][00C]
00000406: 3B450C
                                            cmp
00000409: EB0D
                                                         000000418
                                            imps
0000040B: 6800B04000
                                            push
                                                         00040B000 ; ' @ '
00000410: E8AA000000
                                            call
                                                        0000004BF
00000415: 83C404
                                            add
                                                         esp,4
00000418: 8B4D08
                                                         ecx,[ebp][8]
                                           mov
                                                         ecx,[ebp][00C]
0000041B: 3B4D0C
                                            cmp
                                                            000420
0000041E: 7500
                                            jnz
                                                         00040B008 ;'@2'
00000420: 6808B04000
                                            push
                                                         0000004BF
00000425: E895000000
                                            call
0000042A: 83C404
                                            add
                                                         esp,4
0000042D: 8B5508
                                                         edx,[ebp][8]
                                            mov
00000430: 3B550C
                                                         edx,[ebp][00C]
                                            cmp
00000433: EBOD
                                                         000000442
                                            jmps
                                                         00040B010 ;'@@1'
00000435: 6810B04000
                                            push
0000043A: E880000000
                                                         0000004BF
                                            call
0000043F: 83C404
                                            add
                                                         esp,4
00000442: 5D
                                                         ebp
                                            pop
00000443: C3
00000444: CC
                                            int
00000445: CC
                                            int
00000446: CC
                                            int
00000447: CC
                                            int
00000448: CC
                                            int
      2NOPs
                                5
                                                          8Table 9
                                                                           10
                                                                                   11
                                                                                           12
                        4
```

Figure 11.2: Hiew: let's modify the f\_unsigned() function

If we forget about any of these jumps, then several printf() calls may execute, but we want just one.

# 11.2 Calculating absolute value

A simple function:

```
int my_abs (int i)
{
     if (i<0)
          return -i;
     else
          return i;
};</pre>
```

### 11.2.1 Optimizing MSVC

This is the usual way to generate it:

Listing 11.4: Optimizing MSVC 2012 x64

CHAPTER 11. CONDITIONAL JUMPS 11.3. CONDITIONAL OPERATOR

```
$LN2@my_abs:
; prepare result in EAX:
    mov eax, ecx
    ret 0
my_abs ENDP
```

## 11.3 Conditional operator

The conditional operator in C/C++ is:

```
expression ? expression : expression
```

Here is an example:

```
const char* f (int a)
{
    return a==10 ? "it is ten" : "it is not ten";
};
```

### 11.3.1 x86

Old and non-optimizing compilers generate the code just as if an if/else statement was used:

Listing 11.5: Non-optimizing MSVC 2008

```
$SG746
        DB
                 'it is ten', 00H
$SG747
        DB
                 'it is not ten', 00H
tv65 = -4; this will be used as a temporary variable
_a$ = 8
_f
        PROC
                ebp
        push
        mov
                ebp, esp
        push
                ecx
; compare input value with 10
                DWORD PTR _a$[ebp], 10
        cmp
; jump to $LN3@f if not equal
        jne
                SHORT $LN3@f
; store pointer to the string into temporary variable:
        mov
                DWORD PTR tv65[ebp], OFFSET $SG746 ; 'it is ten'
 jump to exit
                SHORT $LN4@f
        jmp
$LN3@f:
; store pointer to the string into temporary variable:
        mov
                DWORD PTR tv65[ebp], OFFSET $SG747 ; 'it is not ten'
$LN4@f:
; this is exit. copy pointer to the string from temporary variable to EAX.
                eax, DWORD PTR tv65[ebp]
        mov
                esp, ebp
        pop
                ebp
        ret
                0
_f
        FNDP
```

#### Listing 11.6: Optimizing MSVC 2008

```
$SG792
        DB
                 'it is ten', 00H
$SG793
        DB
                 'it is not ten', 00H
_a$ = 8 ; size = 4
_f
        PROC
; compare input value with 10
                DWORD PTR _a$[esp-4], 10
        cmp
                 eax, OFFSET $SG792; 'it is ten'
        mov
; jump to $LN4@f if equal
                SHORT $LN4@f
        je
                eax, OFFSET $SG793 ; 'it is not ten'
        mov
$LN4@f:
                 0
        ret
        ENDP
_f
```

Newer compilers are more concise:

Listing 11.7: Optimizing MSVC 2012 x64

```
'it is ten', 00H
$SG1355 DB
$SG1356 DB
                'it is not ten', 00H
a$ = 8
        PROC
; load pointers to the both strings
                rdx, OFFSET FLAT: $SG1355; 'it is ten'
        lea
                rax, OFFSET FLAT:$SG1356; 'it is not ten'
        lea
; compare input value with 10
                ecx, 10
        cmp
; if equal, copy value from RDX ("it is ten")
; if not, do nothing. pointer to the string "it is not ten" is still in RAX as for now.
                rax, rdx
        cmove
        ret
f
        ENDP
```

Optimizing GCC 4.8 for x86 also uses the CMOVcc instruction, while the non-optimizing GCC 4.8 uses a conditional jumps.

### 11.3.2 Let's rewrite it in an if/else way

```
const char* f (int a)
{
    if (a==10)
        return "it is ten";
    else
        return "it is not ten";
};
```

Interestingly, optimizing GCC 4.8 for x86 was also able to use CMOVcc in this case:

Listing 11.8: Optimizing GCC 4.8

```
.LC0:
        .string "it is ten"
.LC1:
        .string "it is not ten"
f:
.LFB0:
; compare input value with 10
                DWORD PTR [esp+4], 10
        cmp
                edx, OFFSET FLAT:.LC1; "it is not ten"
        mov
                eax, OFFSET FLAT:.LCO; "it is ten"
        mov
; if comparison result is Not Equal, copy EDX value to EAX
; if not, do nothing
        cmovne eax, edx
```

But the optimizing MSVC 2012 is not that good (yet).

# 11.4 Getting minimal and maximal values

#### 11.4.1 32-bit

```
int my_max(int a, int b)
{
      if (a>b)
            return a;
      else
            return b;
};
int my_min(int a, int b)
{
      if (a<b)
            return a;</pre>
```

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```
else
return b;
};
```

Listing 11.9: Non-optimizing MSVC 2013

```
a$ = 8
b$ = 12
_my_min PROC
        push
                 ebp
        mov
                 ebp, esp
                 eax, DWORD PTR _a$[ebp]
        mov
; compare A and B:
        cmp
                 eax, DWORD PTR _b$[ebp]
; jump, if A is greater or equal to B:
                 SHORT $LN2@my_min
        jge
; reload A to EAX if otherwise and jump to exit
                 eax, DWORD PTR _a$[ebp]
        mov
                 SHORT $LN3@my_min
        jmp
        jmp
                 SHORT $LN3@my_min ; this is redundant JMP
$LN2@my_min:
; return B
                eax, DWORD PTR _b$[ebp]
        mov
$LN3@my_min:
        pop
                 ebp
        ret
_my_min ENDP
a$ = 8
_b$ = 12
_my_max PROC
        push
                 ebp
        mov
                 ebp, esp
                 eax, DWORD PTR _a$[ebp]
        mov
; compare A and B:
                 eax, DWORD PTR _b$[ebp]
        cmp
; jump if A is less or equal to B:
        jle
                 SHORT $LN2@my_max
; reload A to EAX if otherwise and jump to exit
        mov
                 eax, DWORD PTR _a$[ebp]
        jmp
                 SHORT $LN3@my_max
        jmp
                 SHORT $LN3@my_max ; this is redundant JMP
$LN2@my_max:
; return B
                 eax, DWORD PTR _b$[ebp]
        mov
$LN3@my_max:
        pop
                 ebp
                 0
        ret
_my_max ENDP
```

These two functions differ only in the conditional jump instruction: JGE ("Jump if Greater or Equal") is used in the first one and JLE ("Jump if Less or Equal") in the second.

There is one unneeded JMP instruction in each function, which MSVC probably left by mistake.

#### 11.5 Conclusion

### 11.5.1 x86

Here's the rough skeleton of a conditional jump:

Listing 11.10: x86

```
CMP register, register/value
Jcc true; cc=condition code
false:
... some code to be executed if comparison result is false ...
JMP exit
true:
... some code to be executed if comparison result is true ...
exit:
```

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## 11.5.2 Branchless

If the body of a condition statement is very short, the conditional move instruction can be used: MOVcc in ARM (in ARM mode), CSEL in ARM64, CMOVcc in x86.

# switch()/case/default

## 12.1 Small number of cases

```
#include <stdio.h>

void f (int a)
{
    switch (a)
    {
       case 0: printf ("zero\n"); break;
       case 1: printf ("one\n"); break;
       case 2: printf ("two\n"); break;
       default: printf ("something unknown\n"); break;
    };
};
int main()
{
    f (2); // test
};
```

#### 12.1.1 x86

### Non-optimizing MSVC

Result (MSVC 2010):

Listing 12.1: MSVC 2010

```
tv64 = -4; size = 4
_a$ = 8
          ; size = 4
      PROC
    push
           ebp
    mov
           ebp, esp
    push
           ecx
           eax, DWORD PTR _a$[ebp]
    mov
           DWORD PTR tv64[ebp], eax
    mov
           DWORD PTR tv64[ebp], 0
    cmp
           SHORT $LN4@f
    jе
           DWORD PTR tv64[ebp], 1
    cmp
           SHORT $LN3@f
    jе
           DWORD PTR tv64[ebp], 2
    cmp
    jе
           SHORT $LN2@f
           SHORT $LN1@f
    jmp
$LN4@f:
           OFFSET $SG739; 'zero', OaH, OOH
    push
    call
           _printf
    add
           esp, 4
           SHORT $LN7@f
    jmp
$LN3@f:
           OFFSET $SG741; 'one', OaH, OOH
    push
    call
           _printf
    add
           esp, 4
```

```
SHORT $LN7@f
    jmp
$LN2@f:
            OFFSET $SG743 ; 'two', OaH, OOH
    push
            _printf
    call
    add
            esp, 4
            SHORT $LN7@f
    jmp
$LN1@f:
    push
            OFFSET $SG745 ; 'something unknown', OaH, OOH
    call
            _printf
    add
            esp, 4
$LN7@f:
    mov
            esp, ebp
    pop
            ebp
            n
    ret
      ENDP
```

Our function with a few cases in switch() is in fact analogous to this construction:

```
void f (int a)
{
    if (a==0)
        printf ("zero\n");
    else if (a==1)
        printf ("one\n");
    else if (a==2)
        printf ("two\n");
    else
        printf ("something unknown\n");
};
```

If we work with switch() with a few cases it is impossible to be sure if it was a real switch() in the source code, or just a pack of if() statements. This implies that switch() is like syntactic sugar for a large number of nested if()s.

There is nothing especially new to us in the generated code, with the exception of the compiler moving input variable a to a temporary local variable tv64  $^{1}$ .

If we compile this in GCC 4.4.1, we'll get almost the same result, even with maximal optimization turned on (-03 option).

#### **Optimizing MSVC**

Now let's turn on optimization in MSVC (/0x): cl 1.c /Fa1.asm /0x

Listing 12.2: MSVC

```
_a$ = 8 ; size = 4
      PROC
_f
    mov
           eax, DWORD PTR _a$[esp-4]
    sub
           eax. 0
           SHORT $LN4@f
    jе
    sub
           eax, 1
           SHORT $LN3@f
    jе
    sub
           eax, 1
    jе
           SHORT $LN2@f
           DWORD PTR _a$[esp-4], OFFSET $SG791 ; 'something unknown', OaH, OOH
    mov
    jmp
           _printf
$LN2@f:
           DWORD PTR _a$[esp-4], OFFSET $SG789; 'two', OaH, OOH
    mov
           _printf
    jmp
$LN3@f:
    mov
           DWORD PTR _a$[esp-4], OFFSET $SG787; 'one', OaH, OOH
    jmp
           _printf
$LN4@f:
           DWORD PTR _a$[esp-4], OFFSET $SG785 ; 'zero', OaH, OOH
    mov
    jmp
           _printf
      ENDP
_f
```

Here we can see some dirty hacks.

First: the value of a is placed in EAX and 0 is subtracted from it. Sounds absurd, but it is done to check if the value in EAX was 0. If yes, the ZF flag is to be set (e.g. subtracting from 0 is 0) and the first conditional jump JE (Jump if Equal or synonym JZ -Jump if Zero) is to be triggered and control flow is to be passed to the \$LN4@f label, where the 'zero' message is

 $<sup>^{1}</sup>$ Local variables in stack are prefixed with tv-that's how MSVC names internal variables for its needs

being printed. If the first jump doesn't get triggered, 1 is subtracted from the input value and if at some stage the result is 0, the corresponding jump is to be triggered.

And if no jump gets triggered at all, the control flow passes to printf() with string argument 'something unknown'. Second: we see something unusual for us: a string pointer is placed into the a variable, and then printf() is called not via CALL, but via JMP. There is a simple explanation for that: the Caller pushes a value to the stack and calls our function via CALL. CALL itself pushes the return address (RA<sup>2</sup>) to the stack and does an unconditional jump to our function address. Our function at any point of execution (since it do not contain any instruction that moves the stack pointer) has the following stack layout:

- ESP-points to RA
- ESP+4-points to the a variable

On the other side, when we need to call printf() here we need exactly the same stack layout, except for the first printf() argument, which needs to point to the string. And that is what our code does.

It replaces the function's first argument with the address of the string and jumps to printf(), as if we didn't call our function f(), but directly printf(). printf() prints a string to stdout and then executes the RET instruction, which POPs RA from the stack and control flow is returned not to f() but rather to f()'s callee, bypassing the end of the f() function.

All this is possible because printf() is called right at the end of the f() function in all cases. In some way, it is similar to the longjmp() $^3$  function. And of course, it is all done for the sake of speed.

#### 12.1.2 Conclusion

A switch() with few cases is indistinguishable from an if/else construction, for example: listing.12.1.1.

### 12.2 A lot of cases

If a switch() statement contains a lot of cases, it is not very convenient for the compiler to emit too large code with a lot JE/JNE instructions.

```
#include <stdio.h>

void f (int a)
{
    switch (a)
    {
       case 0: printf ("zero\n"); break;
       case 1: printf ("one\n"); break;
       case 2: printf ("two\n"); break;
       case 3: printf ("three\n"); break;
       case 4: printf ("four\n"); break;
       default: printf ("something unknown\n"); break;
    };
};
int main()
{
    f (2); // test
};
```

#### 12.2.1 x86

#### Non-optimizing MSVC

We get (MSVC 2010):

Listing 12.3: MSVC 2010

```
tv64 = -4 ; size = 4
_a$ = 8 ; size = 4
_f PROC
    push ebp
    mov ebp, esp
```

<sup>&</sup>lt;sup>2</sup>Return Address

<sup>&</sup>lt;sup>3</sup>wikipedia

```
push
           ecx
           eax, DWORD PTR a$[ebp]
    mov
           DWORD PTR tv64[ebp], eax
    mov
           DWORD PTR tv64[ebp], 4
    cmp
    ja
           SHORT $LN1@f
           ecx, DWORD PTR tv64[ebp]
    mov
           DWORD PTR $LN11@f[ecx*4]
    jmp
$LN6@f:
           OFFSET $SG739; 'zero', OaH, OOH
    push
           _printf
    call
    add
           esp, 4
    jmp
           SHORT $LN9@f
$LN5@f:
    push
           OFFSET $SG741; 'one', 0aH, 00H
    call
            printf
    add
           esp, 4
           SHORT $LN9@f
    jmp
$LN4@f:
           OFFSET $SG743 ; 'two', OaH, OOH
    push
    call
            _printf
    add
           esp, 4
           SHORT $LN9@f
    jmp
$LN3@f:
    push
           OFFSET $SG745; 'three', OaH, OOH
    call
            printf
    add
           esp, 4
           SHORT $LN9@f
    jmp
$LN2@f:
           OFFSET $SG747 ; 'four', OaH, OOH
    push
    call
           _printf
    add
           esp, 4
           SHORT $LN9@f
    jmp
$LN1@f:
    push
           OFFSET $SG749 ; 'something unknown', OaH, OOH
           _printf
    call
    add
           esp, 4
$LN9@f:
    mov
           esp, ebp
    pop
           ebp
    ret
           0
            2 ; align next label
    npad
$LN11@f:
    DD
          $LN6@f ; 0
          $LN5@f ; 1
    DD
    DD
          $LN4@f ; 2
    DD
          $LN3@f ; 3
    DD
          $LN2@f ; 4
_f
```

What we see here is a set of printf() calls with various arguments. All they have not only addresses in the memory of the process, but also internal symbolic labels assigned by the compiler. All these labels are also mentioned in the \$LN11@f internal table.

At the function start, if a is greater than 4, control flow is passed to label LN1@f, where printf() with argument 'something unknown' is called.

But if the value of a is less or equals to 4, then it gets multiplied by 4 and added with the \$LN11@f table address. That is how an address inside the table is constructed, pointing exactly to the element we need. For example, let's say a is equal to 2. 2\*4=8 (all table elements are addresses in a 32-bit process and that is why all elements are 4 bytes wide). The address of the \$LN11@f table + 8 is the table element where the \$LN4@f label is stored. JMP fetches the \$LN4@f address from the table and jumps to it.

This table is sometimes called *jumptable* or *branch table*<sup>4</sup>.

Then the corresponding printf() is called with argument 'two'. Literally, the jmp DWORD PTR \$LN11@f[ecx\*4] instruction implies jump to the DWORD that is stored at address \$LN11@f + ecx \* 4.

is assembly language macro that aligning the next label so that it is to be stored at an address aligned on a 4 byte (or 16 byte) boundary. This is very suitable for the processor since it is able to fetch 32-bit values from memory through the memory bus, cache memory, etc, in a more effective way if it is aligned.

<sup>&</sup>lt;sup>4</sup>The whole method was once called *computed GOTO* in early versions of FORTRAN: wikipedia. Not quite relevant these days, but what a term!

#### Non-optimizing GCC

Let's see what GCC 4.4.1 generates:

Listing 12.4: GCC 4.4.1

```
public f
f
       proc near; CODE XREF: main+10
var_18 = dword ptr -18h
arg_0 = dword ptr 8
               ebp
       push
               ebp, esp
       mov
       sub
               esp, 18h
       cmp
               [ebp+arg_0], 4
       ja
               short loc_8048444
       mov
               eax, [ebp+arg_0]
       shl
               eax, 2
               eax, ds:off_804855C[eax]
       mov
       jmp
loc_80483FE: ; DATA XREF: .rodata:off_804855C
               [esp+18h+var_18], offset aZero ; "zero"
       mov
       call
               _puts
       jmp
               short locret_8048450
loc 804840C: ; DATA XREF: .rodata:08048560
       mov
               [esp+18h+var_18], offset a0ne ; "one"
       call
               _puts
               short locret_8048450
       jmp
loc_804841A: ; DATA XREF: .rodata:08048564
               [esp+18h+var_18], offset aTwo ; "two"
       mov
               _puts
       call
               short locret_8048450
       jmp
loc_8048428: ; DATA XREF: .rodata:08048568
               [esp+18h+var_18], offset aThree; "three"
       mov
       call
               _puts
       jmp
               short locret_8048450
loc_8048436: ; DATA XREF: .rodata:0804856C
               [esp+18h+var_18], offset aFour ; "four"
       call
               _puts
               short locret_8048450
       jmp
loc_8048444: ; CODE XREF: f+A
               [esp+18h+var_18], offset aSomethingUnkno ; "something unknown"
       mov
       call
               _puts
locret_8048450: ; CODE XREF: f+26
                 ; f+34...
       leave
       retn
f
       endp
                                     ; DATA XREF: f+12
off_804855C dd offset loc_80483FE
            dd offset loc_804840C
            dd offset loc_804841A
            dd offset loc_8048428
            dd offset loc_8048436
```

It is almost the same, with a little nuance: argument arg\_0 is multiplied by 4 by shifting it to left by 2 bits (it is almost the same as multiplication by 4) (15.2.1 on page 59). Then the address of the label is taken from the off\_804855C array, stored in EAX, and then ``JMP EAX'' does the actual jump.

#### 12.2.2 Conclusion

Rough skeleton of switch():

Listing 12.5: x86

```
MOV REG, input
CMP REG, 4 ; maximal number of cases
JA default
SHL REG, 2; find element in table. shift for 3 bits in x64.
MOV REG, jump_table[REG]
JMP REG
case1:
    ; do something
    JMP exit
case2:
    ; do something
    JMP exit
case3:
    ; do something
    JMP exit
case4:
    ; do something
    JMP exit
case5:
    ; do something
    JMP exit
default:
    . . .
exit:
    . . . .
jump_table dd case1
           dd case2
           dd case3
           dd case4
           dd case5
```

The jump to the address in the jump table may also be implemented using this instruction: JMP jump\_table[REG\*4]. Or JMP jump\_table[REG\*8] in x64.

A jumptable is just array of pointers, like the one described later: 16.4 on page 66.

## 12.3 When there are several case statements in one block

Here is a very widespread construction: several *case* statements for a single block:

```
#include <stdio.h>
void f(int a)
{
        switch (a)
        case 1:
        case 2:
        case 7:
        case 10:
                 printf ("1, 2, 7, 10\n");
                break;
        case 3:
        case 4:
        case 5:
        case 6:
                printf ("3, 4, 5\n");
        case 8:
        case 9:
        case 20:
        case 21:
                printf ("8, 9, 21\n");
```

```
break;
    case 22:
        printf ("22\n");
        break;
    default:
        printf ("default\n");
        break;
    };
};
int main()
{
    f(4);
};
```

It's too wasteful to generate a block for each possible case, so what is usually done is to generate each block plus some kind of dispatcher.

#### 12.3.1 MSVC

Listing 12.6: Optimizing MSVC 2010

```
'1, 2, 7, 10', 0aH, 00H
 1
    $SG2798 DB
                      '3, 4, 5', 0aH, 00H
'8, 9, 21', 0aH, 00H
'22', 0aH, 00H
    $SG2800 DB
    $SG2802 DB
    $SG2804 DB
                      'default', OaH, OOH
 5
    $SG2806 DB
 6
7
    _a$ = 8
             PROC
8
    _f
9
                      eax, DWORD PTR _a$[esp-4]
             mov
10
             dec
                      eax
             cmp
                      eax, 21
11
                      SHORT $LN1@f
12
             ja
13
                      eax, BYTE PTR $LN10@f[eax]
             movzx
14
                      DWORD PTR $LN11@f[eax*4]
             jmp
15
    $LN5@f:
16
             mov
                      DWORD PTR _a$[esp-4], OFFSET $SG2798 ; '1, 2, 7, 10'
17
             jmp
                      DWORD PTR __imp__printf
    $LN4@f:
18
19
                      DWORD PTR _a$[esp-4], OFFSET $SG2800 ; '3, 4, 5'
             mov
20
                      DWORD PTR __imp__printf
             jmp
21
    $LN3@f:
22
             mov
                      DWORD PTR _a$[esp-4], OFFSET $SG2802 ; '8, 9, 21'
23
             jmp
                      DWORD PTR __imp__printf
24
    $LN2@f:
25
                      DWORD PTR _a$[esp-4], OFFSET $SG2804 ; '22'
             mov
26
                      DWORD PTR __imp__printf
             jmp
27
    $LN1@f:
28
                      DWORD PTR _a$[esp-4], OFFSET $SG2806; 'default'
             mov
                      DWORD PTR
29
             jmp
                                  __imp___printf
                      2 ; align $LN11@f table on 16-byte boundary
30
             npad
31
    $LN11@f:
32
             DD
                      $LN5@f; print '1, 2, 7, 10'
                      $LN4@f ; print '3, 4, 5'
33
             DD
                      $LN3@f; print '8, 9, 21'
34
             DD
35
             DD
                      $LN2@f ; print '22'
36
             DD
                      $LN1@f ; print 'default'
    $LN10@f:
37
                      0 ; a=1
38
             DB
39
             DB
                      0 ; a=2
             DR
                      1; a=3
40
41
             DB
                      1 ; a=4
42
             DB
                      1; a=5
                        ; a=6
43
             DB
                      1
                      0 ; a=7
44
             DB
45
             DB
                      2 ; a=8
                      2
46
             DB
                        ; a=9
47
             DB
                      0 ; a=10
```

```
48
             DB
                       4; a=11
                         ; a=12
49
             DB
50
             DB
                       4 ; a=13
51
             DB
                         ; a=14
             DB
52
                         ; a=15
                         ; a=16
53
             DB
                       4
54
             DB
                       4
                         ; a=17
                       4
55
             DB
                         ; a=18
56
             DB
                       4
                         ; a=19
                       2 ; a=20
57
             DR
                       2 ; a=21
58
             DR
59
             DB
                       3; a=22
60
             ENDP
    _f
```

We see two tables here: the first table (\$LN10@f) is an index table, and the second one (\$LN11@f) is an array of pointers to blocks.

First, the input value is used as an index in the index table (line 13).

Here is a short legend for the values in the table: 0 is the first *case* block (for values 1, 2, 7, 10), 1 is the second one (for values 3, 4, 5), 2 is the third one (for values 8, 9, 21), 3 is the fourth one (for value 22), 4 is for the default block.

There we get an index for the second table of code pointers and we jump to it (line 14).

What is also worth noting is that there is no case for input value 0. That's why we see the DEC instruction at line 10, and the table starts at a=1, because there is no need to allocate a table element for a=0.

This is a very widespread pattern.

So why is this economical? Why isn't it possible to make it as before (12.2.1 on page 45), just with one table consisting of block pointers? The reason is that the elements in index table are 8-bit, hence it's all more compact.

## 12.4 Fall-through

Another very popular usage of switch() is the fall-through. Here is a small example:

```
#define R 1
1
    #define W 2
2
    #define RW 3
5
    void f(int type)
6
7
             int read=0, write=0;
8
9
             switch (type)
10
11
             case RW:
12
                      read=1;
13
             case W:
14
                      write=1;
                      break;
15
16
             case R:
                      read=1;
17
                      break;
18
             default:
19
20
                      break;
21
             };
             printf ("read=%d, write=%d\n", read, write);
22
23
    };
```

If type = 1 (R), read is to be set to 1, if type = 2 (W), write is to be set to 2. In case of type = 3 (RW), both read and write is to be set to 1.

The code at line 14 is executed in two cases: if type = RW or if type = W. There is no "break" for "case RW"x and that's OK.

### 12.4.1 MSVC x86

Listing 12.7: MSVC 2012

```
$SG1305 DB 'read=%d, write=%d', 0aH, 00H

_write$ = -12 ; size = 4

_read$ = -8 ; size = 4
```

```
tv64 = -4
                 ; size = 4
_{type} = 8
                  size = 4
        PROC
                ebp
        push
        mov
                ebp, esp
        sub
                esp, 12
        mov
                DWORD PTR _read$[ebp], 0
        mov
                DWORD PTR _write$[ebp], 0
                eax, DWORD PTR _type$[ebp]
        mov
                DWORD PTR tv64[ebp], eax
        mov
                DWORD PTR tv64[ebp], 1; R
        cmp
                SHORT $LN2@f
        je
                DWORD PTR tv64[ebp], 2; W
        cmp
        je
                SHORT $LN3@f
                DWORD PTR tv64[ebp], 3; RW
        cmp
        jе
                 SHORT $LN4@f
        jmp
                 SHORT $LN5@f
$LN4@f:
        ; case RW:
                DWORD PTR _read$[ebp], 1
        mov
$LN3@f:
       ; case W:
                DWORD PTR _write$[ebp], 1
        mov
                SHORT $LN5@f
        jmp
$LN2@f: ; case R:
        mov
                DWORD PTR _read$[ebp], 1
$LN5@f: ; default
                ecx, DWORD PTR _write$[ebp]
        mov
        push
                ecx
        mov
                edx, DWORD PTR _read$[ebp]
        push
                edx
                OFFSET $SG1305; 'read=%d, write=%d'
        push
                 _printf
        call
        add
                esp, 12
                esp, ebp
        mov
        pop
                ebp
        ret
f
        ENDP
```

The code mostly resembles what is in the source. There are no jumps between labels LN4@f and LN3@f: so when code flow is at LN4@f, read is first set to 1, then write. This is why it's called fall-through: code flow falls through one piece of code (setting read) to another (setting write). If type = W, we land at LN3@f, so no code setting read to 1 is executed.

# Loops

# 13.1 Simple example

#### 13.1.1 x86

There is a special LOOP instruction in x86 instruction set for checking the value in register ECX and if it is not 0, to decrement ECX and pass control flow to the label in the LOOP operand. Probably this instruction is not very convenient, as I never saw any modern compiler emit it automatically. So, if you see this instruction somewhere in code, it is most likely that this is a manually written piece of assembly code.

In C/C++ loops are usually constructed using for(), while() or do/while() statements. Let's start with for().

This statement defines loop initialization (set loop counter to initial value), loop condition (is the counter bigger than a limit?), what is done at each iteration (increment/decrement) and of course loop body.

```
for (initialization; condition; at each iteration)
{
    loop_body;
}
```

The generated code is consisting of four parts as well. Let's start with a simple example:

Result (MSVC 2010):

Listing 13.1: MSVC 2010

```
_i$ = -4
_main
         PROC
    push
           ebp
    mov
           ebp, esp
    push
           DWORD PTR _i$[ebp], 2
                                    ; loop initialization
    mov
           SHORT $LN3@main
    jmp
$LN2@main:
           eax, DWORD PTR _i$[ebp] ; here is what we do after each iteration:
    mov
    add
                                     ; add 1 to (i) value
           DWORD PTR _i$[ebp], eax
```

```
$LN3@main:
                                    ; this condition is checked *before* each iteration
           DWORD PTR _i$[ebp], 10
    cmp
           SHORT $LN1@main
                                     ; if (i) is biggest or equals to 10, lets finish loop'
    jge
           ecx, DWORD PTR _i$[ebp] ; loop body: call printing_function(i)
    mov
    push
           ecx
    call
           _printing_function
    add
           esp, 4
           SHORT $LN2@main
                                     ; jump to loop begin
    qmp
$LN1@main:
                                      loop end
    xor
           eax, eax
    mov
           esp, ebp
    pop
           ebp
    ret
         ENDP
main
```

As we see, nothing special.

Listing 13.2: Optimizing MSVC

```
main
          PROC
    push
            esi
    mov
            esi, 2
$LL3@main:
    push
            esi
    call
            _printing_function
    inc
            esi
    add
            esp, 4
    cmp
            esi, 10
                         ; 0000000aH
    jl
            SHORT $LL3@main
    xor
            eax, eax
    pop
            esi
            0
    ret
          ENDP
main
```

What happens here is that space for the i variable is not allocated in the local stack anymore, but uses an individual register for it, ESI. This is possible in such small functions where there aren't many local variables.

One very important thing is that the f() function must not change the value in ESI. Our compiler is sure here. And if the compiler decides to use the ESI register in f() too, its value would have to be saved at the function's prologue and restored at the function's epilogue, almost like in our listing: please note PUSH ESI/POP ESI at the function start and end.

### 13.1.2 One more thing

In the generated code we can see: after initializing i, the body of the loop is not to be executed, as the condition for i is checked first, and only after that loop body can be executed. And that is correct. Because, if the loop condition is not met at the beginning, the body of the loop must not be executed. This is possible in the following case:

```
for (i=0; i<total_entries_to_process; i++)
  loop_body;</pre>
```

If total\_entries\_to\_process is 0, the body of the loo must not be executed at all. This is why the condition checked before the execution.

However, an optimizing compiler may swap the condition check and loop body, if it sure that the situation described here is not possible (like in the case of our very simple example and Keil, Xcode (LLVM), MSVC in optimization mode).

# 13.2 Memory blocks copying routine

Real-world memory copy routines may copy 4 or 8 bytes at each iteration, use SIMD<sup>1</sup>, vectorization, etc. But for the sake of simplicity, this example is the simplest possible.

<sup>&</sup>lt;sup>1</sup>Single instruction, multiple data

CHAPTER 13. LOOPS 13.3. CONCLUSION

## 13.2.1 Straight-forward implementation

Listing 13.3: GCC 4.9 x64 optimized for size (-Os)

```
my_memcpy:
; RDI = destination address
; RSI = source address
; RDX = size of block
; initialize counter (i) at 0
        xor
                eax, eax
.L2:
; all bytes copied? exit then:
        cmp
                 rax, rdx
                 .L5
        jе
; load byte at RSI+i:
        mov
                 cl, BYTE PTR [rsi+rax]
; store byte at RDI+i:
                BYTE PTR [rdi+rax], cl
        mov
                 rax ; i++
        inc
                 .L2
        jmp
.L5:
        ret
```

### 13.3 Conclusion

Rough skeleton of loop from 2 to 9 inclusive:

#### Listing 13.4: x86

```
mov [counter], 2 ; initialization
  jmp check
body:
  ; loop body
  ; do something here
  ; use counter variable in local stack
  add [counter], 1 ; increment
check:
  cmp [counter], 9
  jle body
```

The increment operation may be represented as 3 instructions in non-optimized code:

#### Listing 13.5: x86

```
MOV [counter], 2 ; initialization

JMP check

body:

; loop body
; do something here
; use counter variable in local stack

MOV REG, [counter] ; increment

INC REG

MOV [counter], REG

check:

CMP [counter], 9

JLE body
```

If the body of the loop is short, a whole register can be dedicated to the counter variable:

#### Listing 13.6: x86

```
MOV EBX, 2; initialization
JMP check
body:
; loop body
; do something here
; use counter in EBX, but do not modify it!
INC EBX; increment
check:
```

CHAPTER 13. LOOPS 13.3. CONCLUSION

```
CMP EBX, 9
JLE body
```

Some parts of the loop may be generated by compiler in different order:

#### Listing 13.7: x86

```
MOV [counter], 2 ; initialization

JMP label_check

label_increment:

ADD [counter], 1 ; increment

label_check:

CMP [counter], 10

JGE exit

; loop body

; do something here

; use counter variable in local stack

JMP label_increment

exit:
```

Usually the condition is checked *before* loop body, but the compiler may rearrange it in a way that the condition is checked *after* loop body. This is done when the compiler is sure that the condition is always *true* on the first iteration, so the body of the loop is to be executed at least once:

#### Listing 13.8: x86

```
MOV REG, 2 ; initialization
body:
    ; loop body
    ; do something here
    ; use counter in REG, but do not modify it!
    INC REG ; increment
    CMP REG, 10
    JL body
```

Using the LOOP instruction. This is rare, compilers are not using it. When you see it, it's a sign that this piece of code is hand-written:

#### Listing 13.9: x86

```
; count from 10 to 1
   MOV ECX, 10
body:
   ; loop body
   ; do something here
   ; use counter in ECX, but do not modify it!
   LOOP body
```

# Simple C-strings processing

# 14.1 strlen()

Let's talk about loops one more time. Often, the strlen() function<sup>1</sup> is implemented using a while() statement. Here is how it is done in the MSVC standard libraries:

```
int my_strlen (const char * str)
{
        const char *eos = str;
        while( *eos++ );
        return( eos - str - 1 );
}
int main()
{
        // test
        return my_strlen("hello!");
};
```

### 14.1.1 x86

#### Non-optimizing MSVC

Let's compile:

```
_{\text{eos}} = -4
                                  ; size = 4
_str$ = 8
                                  ; size = 4
_strlen PROC
    push
            ebp
    mov
            ebp, esp
    push
            ecx
            eax, DWORD PTR _str$[ebp] ; place pointer to string from "str"
    \text{mov}
    mov
            DWORD PTR _eos$[ebp], eax ; place it to local variable "eos"
$LN2@strlen_:
            ecx, DWORD PTR _eos$[ebp] ; ECX=eos
    mov
    ; take 8-bit byte from address in ECX and place it as 32-bit value to EDX with sign extension
            edx, BYTE PTR [ecx]
    movsx
            eax, DWORD PTR _eos$[ebp]
                                        ; EAX=eos
    mov
    add
            eax, 1
                                         ; increment EAX
            DWORD PTR _eos$[ebp], eax ; place EAX back to "eos"
    test
            edx, edx
                                        ; EDX is zero?
    jе
            SHORT $LN1@strlen_
                                        ; yes, then finish loop
    jmp
            SHORT $LN2@strlen_
                                        ; continue loop
$LN1@strlen_:
    ; here we calculate the difference between two pointers
           eax, DWORD PTR _eos$[ebp]
```

<sup>&</sup>lt;sup>1</sup>counting the characters in a string in the C language

```
sub eax, DWORD PTR _str$[ebp]
sub eax, 1 ; subtract 1 and return result
mov esp, ebp
pop ebp
ret 0
_strlen_ ENDP
```

We get two new instructions here: MOVSX and TEST.

The first one - MOVSX - takes a byte from an address in memory and stores the value in a 32-bit register. MOVSX stands for MOV with Sign-Extend. MOVSX sets the rest of the bits, from the 8th to the 31th, to 1 if the source byte is negative or to 0 if is positive.

And here is why.

By default, the *char* type is signed in MSVC and GCC. If we have two values of which one is *char* and the other is *int*, (*int* is signed too), and if the first value contain -2 (coded as 0xFE) and we just copy this byte into the *int* container, it makes 0x000000FE, and this from the point of signed *int* view is 254, but not -2. In signed int, -2 is coded as 0xFFFFFFE. So if we need to transfer 0xFE from a variable of *char* type to *int*, we need to identify its sign and extend it. That is what MOVSX does.

You can also read about it in "Signed number representations" section (22 on page 101).

I'm not sure if the compiler needs to store a *char* variable in EDX, it could just take a 8-bit register part (for example DL). Apparently, the compiler's register allocator works like that.

Then we see TEST EDX, EDX. You can read more about the TEST instruction in the section about bit fields (17 on page 73). Here this instruction just checks if the value in EDX equals to 0.

#### **Optimizing MSVC**

Now let's compile all this in MSVC 2012, with optimizations turned on (/0x):

Listing 14.1: Optimizing MSVC 2012 /Ob0

```
_str$ = 8
                                  ; size = 4
strlen PROC
                 edx, DWORD PTR _str$[esp-4] ; EDX -> pointer to the string
        mov
                                                move to EAX
        mov
                 eax, edx
$LL2@strlen:
                 cl, BYTE PTR [eax]
                                                CL = *EAX
        mov
                                                EAX++
        inc
                 eax
                 cl, cl
                                                CL==0?
        test
                 SHORT $LL2@strlen
        ine
                                                no, continue loop
                                                calculate pointers difference
        sub
                 eax, edx
                                                decrement EAX
        dec
                 eax
        ret
                 0
strlen ENDP
```

Now it is all simpler. Needless to say, the compiler could use registers with such efficiency only in small functions with a few local variables.

INC/DEC— are increment/decrement instructions, in other words: add or substract 1 to/from a variable.

# Replacing arithmetic instructions to other ones

In the pursuit of optimization, one instruction may be replaced by others, or even with a group of instructions.

# 15.1 Multiplication

### 15.1.1 Multiplication using addition

Here is a simple example:

Listing 15.1: Optimizing MSVC 2010

```
unsigned int f(unsigned int a)
{
    return a*8;
};
```

Multiplication by 8 is replaced by 3 addition instructions, which do the same. Apparently, MSVC's optimizer decided that this code can be faster.

```
_TEXT
         SEGMENT
_a$ = 8
_f PROC
; File c:\polygon\c\2.c
                                                                    ; size = 4
                   eax, DWORD PTR _a$[esp-4]
         mov
         add
                   eax, eax
         add
                   eax, eax
         add
                   eax, eax
         ret
         ENDP
_TEXT
         ENDS
END
```

## 15.1.2 Multiplication using shifting

Multiplication and division instructions by a numbers that's a power of 2 are often replaced by shift instructions.

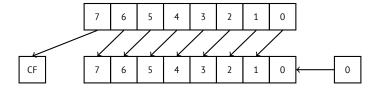
```
unsigned int f(unsigned int a)
{
    return a*4;
};
```

Listing 15.2: Non-optimizing MSVC 2010

```
_a = 8
                 ; size = 4
_f
        PROC
         push
                 ebp
        mov
                 ebp, esp
        mov
                 eax, DWORD PTR _a$[ebp]
         shl
                 eax, 2
         pop
                 ebp
         ret
_f
        FNDP
```

Multiplication by 4 is just shifting the number to the left by 2 bits and inserting 2 zero bits at the right (as the last two bits). It is just like multiplying 3 by 100 —we need to just add two zeroes at the right.

That's how the shift left instruction works:



The added bits at right are always zeroes.

## 15.1.3 Multiplication using shifting/subtracting/adding

It's still possible to get rid of the multiplication operation when you multiply by numbers like 7 or 17 again by using shifting. The mathematics used here is relatively easy.

#### 32-bit

```
#include <stdint.h>
int f1(int a)
{
    return a*7;
};
int f2(int a)
{
    return a*28;
};
int f3(int a)
{
    return a*17;
};
```

x86

Listing 15.3: Optimizing MSVC 2012

```
; a*7
_a$ = 8
_f1
        PROC
                 ecx, DWORD PTR _a$[esp-4]
        mov
; ECX=a
        lea
                 eax, DWORD PTR [ecx*8]
; EAX=ECX*8
        sub
                 eax, ecx
; EAX=EAX-ECX=ECX*8-ECX=ECX*7=a*7
                 0
        ret
        ENDP
_f1
; a*28
_a$ = 8
_f2
        PROC
                 ecx, DWORD PTR _a$[esp-4]
        mov
; ECX=a
        lea
                 eax, DWORD PTR [ecx*8]
; EAX=ECX*8
        sub
                 eax, ecx
; EAX=EAX-ECX=ECX*8-ECX=ECX*7=a*7
        shl
                 eax, 2
; EAX=EAX<<2=(a*7)*4=a*28
        ret
                 0
        ENDP
_f2
```

```
; a*17
_a$ = 8
_f3
        PROC
                eax, DWORD PTR _a$[esp-4]
        mov
; EAX=a
        shl
                eax, 4
; EAX=EAX<<4=EAX*16=a*16
        add
                eax, DWORD PTR _a$[esp-4]
; EAX=EAX+a=a*16+a=a*17
        ret
                0
        ENDP
_f3
```

#### 64-bit

```
#include <stdint.h>
int64_t f1(int64_t a)
{
    return a*7;
};
int64_t f2(int64_t a)
{
    return a*28;
};
int64_t f3(int64_t a)
{
    return a*17;
};
```

### x64

Listing 15.4: Optimizing MSVC 2012

```
; a*7
f1:
                 rax, [0+rdi*8]
        lea
; RAX=RDI*8=a*8
        sub
                 rax, rdi
; RAX=RAX-RDI=a*8-a=a*7
        ret
; a*28
f2:
        lea
                 rax, [0+rdi*4]
; RAX=RDI*4=a*4
                 rdi, 5
        sal
; RDI=RDI<<5=RDI*32=a*32
        sub
                 rdi, rax
; RDI=RDI-RAX=a*32-a*4=a*28
                 rax, rdi
        mov
        ret
; a*17
f3:
        mov
                 rax, rdi
        sal
                 rax, 4
; RAX=RAX<<4=a*16
        add
                 rax, rdi
; RAX=a*16+a=a*17
        ret
```

#### 15.2 Division

## 15.2.1 Division using shifts

Example:

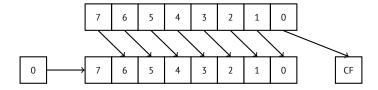
```
unsigned int f(unsigned int a)
{
    return a/4;
};
```

We get (MSVC 2010):

Listing 15.5: MSVC 2010

The SHR (*SHift Right*) instruction in this example is shifting a number by 2 bits to the right. The two freed bits at left (e.g., two most significant bits) are set to zero. The two least significant bits are dropped. In fact, these two dropped bits are the division operation remainder.

The SHR instruction works just like SHL, but in the other direction.



It is easy to understand if you imagine the number 23 in the decimal numeral system. 23 can be easily divided by 10 just by dropping last digit (3 —is division remainder). 2 is left after the operation as a quotient.

So the remainder is dropped, but that's OK, we work on integer values anyway, these are not floating point numbers!

# **Chapter 16**

# **Arrays**

An array is just a set of variables in memory that lie next to each other and that have the same type  $^{1}$ .

# 16.1 Simple example

```
#include <stdio.h>
int main()
{
   int a[20];
   int i;
   for (i=0; i<20; i++)
        a[i]=i*2;
   for (i=0; i<20; i++)
        printf ("a[%d]=%d\n", i, a[i]);
   return 0;
};</pre>
```

#### 16.1.1 x86

#### **MSVC**

Let's compile:

Listing 16.1: MSVC 2008

```
_TEXT
         SEGMENT
_{i} = -84
                                  ; size = 4
_a = -80
                                  ; size = 80
main
           PROC
    push
           ebp
    mov
           ebp, esp
                           ; 00000054H
    sub
           esp, 84
           DWORD PTR _i$[ebp], 0
    mov
           SHORT $LN6@main
    jmp
$LN5@main:
           eax, DWORD PTR _i$[ebp]
   mov
    add
           eax, 1
           DWORD PTR _i$[ebp], eax
    mov
$LN6@main:
    cmp
           DWORD PTR _i$[ebp], 20
                                      ; 00000014H
           SHORT $LN4@main
    jge
           ecx, DWORD PTR _i$[ebp]
    mov
    shl
           ecx, 1
           edx, DWORD PTR _i$[ebp]
    mov
           DWORD PTR _a$[ebp+edx*4], ecx
    mov
           SHORT $LN5@main
    jmp
$LN4@main:
```

<sup>&</sup>lt;sup>1</sup>AKA<sup>2</sup> "homogeneous container"

```
DWORD PTR _i$[ebp], 0
    mov
           SHORT $LN3@main
    jmp
$LN2@main:
           eax, DWORD PTR _i$[ebp]
    mov
    add
           eax, 1
           DWORD PTR _i$[ebp], eax
    mov
$LN3@main:
           DWORD PTR _i$[ebp], 20
                                        ; 00000014H
    cmp
           SHORT $LN1@main
    jge
           ecx, DWORD PTR _i$[ebp]
    mov
           edx, DWORD PTR _a$[ebp+ecx*4]
    mov
    push
           edx
           eax, DWORD PTR _i$[ebp]
    mov
    push
           eax
    push
           OFFSET $SG2463
    call
            _printf
    add
            esp, 12
                            ; 000000cH
            SHORT $LN2@main
    jmp
$LN1@main:
    xor
            eax, eax
    mov
           esp, ebp
    pop
           ebp
            0
    ret
_main
            ENDP
```

Nothing very special, just two loops: the first is a filling loop and second is a printing loop. The shl ecx, 1 instruction is used for value multiplication by 2 in ECX, more about below 15.2.1 on page 59.

80 bytes are allocated on the stack for the array, 20 elements of 4 bytes.

#### 16.2 Buffer overflow

#### 16.2.1 Reading outside array bounds

So, array indexing is just *array[index]*. If you study the generated code closely, you'll probably note the missing index bounds checking, which could check *if it is less than 20*. What if the index is 20 or greater? That's the one C/C++ feature it is often blamed for.

Here is a code that successfully compiles and works:

```
#include <stdio.h>
int main()
{
    int a[20];
    int i;
    for (i=0; i<20; i++)
        a[i]=i*2;
    printf ("a[20]=%d\n", a[20]);
    return 0;
};</pre>
```

Compilation results (MSVC 2008):

Listing 16.2: Non-optimizing MSVC 2008

```
$SG2474 DB
               'a[20]=%d', 0aH, 00H
_{i} = -84 ; size = 4
_a$ = -80 ; size = 80
_main
         PROC
    push
           ebp
    mov
           ebp, esp
    sub
           esp, 84
           DWORD PTR _i$[ebp], 0
    mov
           SHORT $LN3@main
    jmp
$LN2@main:
    mov
           eax, DWORD PTR _i$[ebp]
    add
           eax, 1
```

```
DWORD PTR _i$[ebp], eax
    mov
$LN3@main:
           DWORD PTR _i$[ebp], 20
    cmp
           SHORT $LN1@main
    jge
           ecx, DWORD PTR _i$[ebp]
    mov
    shl
           ecx, 1
           edx, DWORD PTR _i$[ebp]
    mov
           DWORD PTR _a$[ebp+edx*4], ecx
    mov
           SHORT $LN2@main
    jmp
$LN1@main:
    mov
           eax, DWORD PTR _a$[ebp+80]
    push
           eax
    push
           OFFSET $SG2474 ; 'a[20]=%d'
    call
           DWORD PTR __imp__printf
    add
           esp, 8
    xor
           eax, eax
    mov
           esp, ebp
    pop
           ebp
    ret
           0
         ENDP
_main
_TEXT
         ENDS
END
```

When I run it, I get:

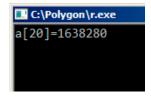


Figure 16.1: OllyDbg: console output

It is just something that was lying in the stack near to the array, 80 bytes away from its first element.

## 16.2.2 Writing beyond array bounds

OK, we read some values from the stack *illegally*, but what if we could write something to it? Here is what we have got:

```
#include <stdio.h>
int main()
{
    int a[20];
    int i;
    for (i=0; i<30; i++)
        a[i]=i;
    return 0;
};</pre>
```

#### **MSVC**

And what we get:

Listing 16.3: Non-optimizing MSVC 2008

```
TEXT
         SEGMENT
_{i} = -84 ; size = 4
_a$ = -80 ; size = 80
_main
        PR0C
push
        ebp
mov
        ebp, esp
 sub
        esp, 84
        DWORD PTR _i$[ebp], 0
mov
        SHORT $LN3@main
jmp
```

```
$LN2@main:
        eax, DWORD PTR _i$[ebp]
mov
add
        eax, 1
        DWORD PTR _i$[ebp], eax
mov
$LN3@main:
cmp
        DWORD PTR _i$[ebp], 30 ; 0000001eH
        SHORT $LN1@main
jge
        ecx, DWORD PTR _i$[ebp]
\text{mov}
                                       ; that instruction is obviously redundant
        edx, DWORD PTR _i$[ebp]
mov
        DWORD PTR _a$[ebp+ecx*4], edx ; ECX could be used as second operand here instead
mov
        SHORT $LN2@main
 jmp
$LN1@main:
xor
        eax, eax
        esp, ebp
mov
 pop
        ebp
ret
        0
        ENDP
_main
```

The compiled program crashes after running. No wonder. Let's see where exactly does it is crash.

Let's load it into OllyDbq, and trace until all 30 elements are written:

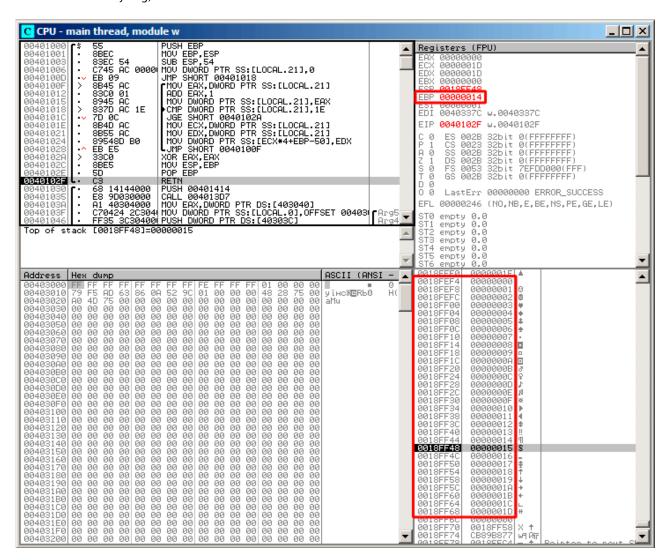


Figure 16.2: OllyDbg: after restoring the value of EBP

Trace until the function end:

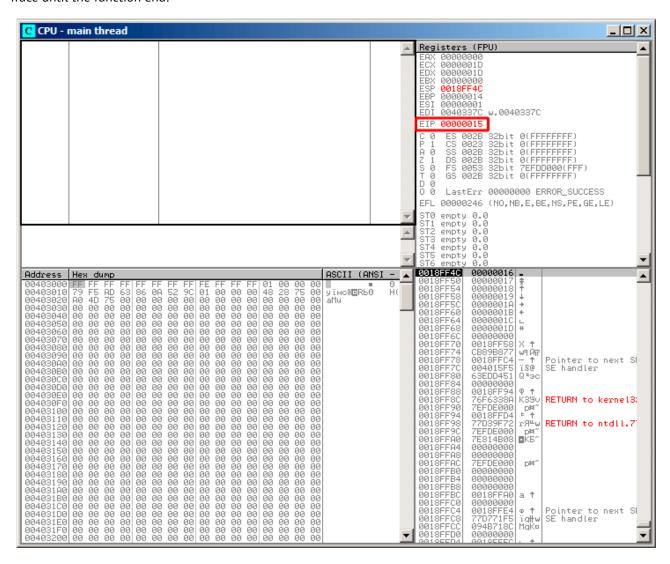


Figure 16.3: OllyDbg: EIP was restored, but OllyDbg can't disassemble at 0x15

Now please keep your eyes on the registers.

EIP is 0x15 now. It is not a legal address for code -at least for win32 code! We got there somehow against our will. It is also interesting that the EBP register contain 0x14, ECX and EDX -0x1D.

Let's study stack layout a bit more.

After the control flow was passed to main(), the value in the EBP register was saved on the stack. Then, 84 bytes were allocated for the array and the i variable. That's (20+1)\*sizeof(int). ESP now points to the  $\_i$  variable in the local stack and after the execution of the next PUSH something, something is appearing next to  $\_i$ .

That's the stack layout while the control is in main():

ESP	4 bytes allocated for <i>i</i> variable
ESP+4	80 bytes allocated for a [20] array
ESP+84	saved EBP value
ESP+88	return address

- a[19]=something statement writes the last int in the bounds of the array (in bounds so far!)
- a [20] = something statement writes something to the place where the value of EBP is saved.

Please take a look at the register state at the moment of the crash. In our case, 20 was written in the 20th element. At the function end, the function epilogue restores the original EBP value. (20 in decimal is 0x14 in hexadecimal). Then RET gets executed, which is effectively equivalent to POP EIP instruction.

The RET instruction takes the return address from the stack (that is the address in CRT), which was called main()), and 21 iss stored there (0x15 in hexadecimal). The CPU traps at address 0x15, but there is no executable code there, so exception gets raised.

Welcome! It is called a buffer overflow<sup>3</sup>.

<sup>&</sup>lt;sup>3</sup>wikipedia

Replace the *int* array with a string (*char* array), create a long string deliberately and pass it to the program, to the function, which doesn't check the length of the string and copies it in a short buffer, and you'll able to point the program to an address to which it must jump. It's not that simple in reality, but that is how it emerged <sup>4</sup>

# 16.3 One more word about arrays

Now we understand why it is impossible to write something like this in C/C++ code <sup>5</sup>:

```
void f(int size)
{
   int a[size];
...
};
```

That's just because the compiler must know the exact array size to allocate space for it in the local stack layout on at the compiling stage.

If you need an array of arbitrary size, allocate it by using malloc(), then access the allocated memory block as an array of variables of the type you need. Or use the C99 standard feature[ISO07, pp. 6.7.5/2], but it looks like alloca() (5.2.4 on page 11) internally.

# 16.4 Array of pointers to strings

Here is an example for an array of pointers.

Listing 16.4: Get month name

```
#include <stdio.h>
const char* month1[]=
{
         "January"
         "February",
         "March",
         "April",
         "May",
         "June"
         "July"
         "August"
         "September",
         "October",
         "November"
         "December"
};
// in 0..11 range
const char* get_month1 (int month)
        return month1[month];
};
```

#### 16.4.1 x64

Listing 16.5: Optimizing MSVC 2013 x64

```
SEGMENT
DATA
                  FLAT: $SG3122
month1
         DQ
         DQ
                  FLAT: $SG3123
         DQ
                  FLAT: $SG3124
         D0
                  FLAT: $SG3125
         D0
                  FLAT: $SG3126
         DQ
                  FLAT: $SG3127
         DQ
                  FLAT: $SG3128
         DQ
                  FLAT: $SG3129
```

<sup>&</sup>lt;sup>4</sup>Classic article about it: [One96].

<sup>&</sup>lt;sup>5</sup>However, it is possible in C99 standard[ISO07, pp. 6.7.5/2]: GCC actually does this by allocating an array dynamically on the stack (like alloca() (5.2.4 on page 11))

```
DQ
                  FLAT: $SG3130
         D0
                   FLAT: $SG3131
         DQ
                   FLAT: $SG3132
         DQ
                   FLAT: $SG3133
                   'January', 00H
'February', 00H
$SG3122 DB
$SG3123 DB
$SG3124 DB
                   'March', 00H
$SG3125 DB
                   'April', 00H
$SG3126 DB
                   'May', 00H
$SG3127 DB
                   'June', 00H
$SG3128 DB
                   'July', 00H
                   'August', 00H
$SG3129 DB
$SG3130 DB
                   'September', 00H
$SG3156 DB
                   '%s', OaH, OOH
                   'October', 00H
'November', 00H
'December', 00H
$SG3131 DB
$SG3132 DB
$SG3133 DB
_DATA
         ENDS
month = 8
get_month1 PROC
         movsxd
                  rax, ecx
                   rcx, OFFSET FLAT:month1
         lea
         mov
                   rax, QWORD PTR [rcx+rax*8]
         ret
get_month1 ENDP
```

The code is very simple:

- The first MOVSXD instruction copies a 32-bit value from ECX (where *month* argument is passed) to RAX with sign-extension (because the *month* argument is of type *int*). The reason for the sign extension is that this 32-bit value is to be used in calculations with other 64-bit values. Hence, it has to be promoted to 64-bit <sup>6</sup>.
- Then the address of the pointer table is loaded into RCX.
- Finally, the input value (*month*) is multiplied by 8 and added to the address. Indeed: we are in a 64-bit environment and all address (or pointers) require exactly 64 bits (or 8 bytes) for storage. Hence, each table element is 8 bytes wide. And that's why to pick a specific element, *month* \* 8 bytes has to be skipped from the start. That's what MOV does. In addition, this instruction also loads the element at this address. For 1, an element would be a pointer to a string that contains "February", etc.

Optimizing GCC 4.9 can do the job even better ':

Listing 16.6: Optimizing GCC 4.9 x64

```
movsx rdi, edi
mov rax, QWORD PTR month1[0+rdi*8]
ret
```

#### 32-bit MSVC

Let's also compile it in the 32-bit MSVC compiler:

Listing 16.7: Optimizing MSVC 2013 x86

```
_month$ = 8
_get_month1 PROC
    mov    eax, DWORD PTR _month$[esp-4]
    mov    eax, DWORD PTR _month1[eax*4]
    ret    0
_get_month1 ENDP
```

The input value does not need to be extended to 64-bit value, so it is used as is. And it's multiplied by 4, because the table elements are 32-bit (or 4 bytes) wide.

<sup>&</sup>lt;sup>6</sup>It is somewhat weird, but negative array index could be passed here as *month*. And if this happens, the negative input value of *int* type is sign-extended correctly and the corresponding element before table is picked. It is not going to work correctly without sign-extension.

<sup>7&</sup>quot;0+" was left in the listing because GCC assembler output is not tidy enough to eliminate it. It's displacement, and it's zero here.

### 16.5 Multidimensional arrays

Internally, a multidimensional array is essentially the same thing as a linear array.

Since the computer memory is linear, it is an one-dimensional array. For convenience, this multi-dimensional array can be easily represented as one-dimensional.

For example, thit is how the elements of the a[3][4] array are placed in one-dimensional array of 12 cells:

[0][0]
[0][0]
[0][1]
[0][2]
[0][3]
[1][0]
[1][1]
[1][2]
[1][3]
[2][0]
[2][1]
[2][2]
[2][3]

Table 16.1: Two-dimensional array represented in memory as one-dimensional

Here is how each cell of 3\*4 array are placed in memory:

0	1	2	3
4	5	6	7
8	9	10	11

Table 16.2: Memory addresses of each cell of two-dimensional array

So, in order to calculate the address of the element we need, we first multiply the first index by 4 (matrix width) and then add the second index. That's called *row-major order*, and this method of array and matrix representation is used in at least C/C++ and Python. The term *row-major order* in plain English language means: "first, write the elements of the first row, then the second row ...and finally the elements of the last row".

Another method for representation is called *column-major order* (the array indices are used in reverse order) and it is used at least in FORTRAN, MATLAB and R. *column-major order* term in plain English language means: "first, write the elements of the first column, then the second column ...and finally the elements of the last column".

Which method is better? In general, in terms of performance and cache memory, the best scheme for data organization is the one, in which the elements are accessed sequentially. So if your function accesses data per row, *row-major order* is better, and vice versa.

#### 16.5.1 Two-dimensional array example

We are going to work with an array of type char, which implies that each element requires only one byte in memory.

#### Row filling example

Let's fill the second row with these values:  $0 \dots 3$ :

Listing 16.8: Row filling example

```
a[1][y]=y;
};
```

I have marked all three rows with red. We see that second row now has values 0, 1, 2 and 3:

Address																
00C33370																
00C33380																
00033390																
00C333A0																
00C333B0	00	00	00	99	00	99	00	99	00	99	00	00	00	00	99	99

Figure 16.4: OllyDbg: array is filled

#### Column filling example

Let's fill the third column with values:  $0 \dots 2$ .

Listing 16.9: Column filling example

I have also marked the three rows in red here. We see that in each row, at third position these values are written: 0, 1 and 2.

Address	Hes	k du	qmp													
00BB3372														00	02	00
00BB3382	00	99	13	50	7E	9A	13	50	7E	9A	00	00	99	99	99	99
00BB3392	00	99	99	99	00	99	00	99	00	99	00	99	99	99	99	99
00BB33A2	00	99	99	99	00	99	00	99	00	99	99	99	99	99	99	99
00BB33B2	00	99	99	00	00	99	00	99	00	00	00	00	00	99	00	00

Figure 16.5: OllyDbg: array is filled

#### 16.5.2 Access two-dimensional array as one-dimensional

I can easily show you how to access a two-dimensional array as one-dimensional array in at least two other ways:

```
#include <stdio.h>
char a[3][4];
char get_by_coordinates1 (char array[3][4], int a, int b)
{
         return array[a][b];
};
char get_by_coordinates2 (char *array, int a, int b)
{
         // treat input array as one-dimensional
         // 4 is array width here
```

Compile and run it: it shows correct values.

What MSVC 2013 did is fascinating, all three routines are just the same!

Listing 16.10: Optimizing MSVC 2013 x64

```
array$ = 8
a$ = 16
b$ = 24
get_by_coordinates3 PROC
; RCX=address of array
 RDX=a
; R8=b
        movsxd rax, r8d
; EAX=b
        movsxd
                r9, edx
; R9=a
        add
                rax, rcx
; RAX=b+address of array
                eax, BYTE PTR [rax+r9*4]
        movzx
; AL=load byte at address RAX+R9*4=b+address of array+a*4=address of array+a*4+b
        ret
get_by_coordinates3 ENDP
array$ = 8
a$ = 16
b$ = 24
get_by_coordinates2 PROC
        movsxd rax, r8d
        movsxd r9, edx
        add
                rax, rcx
        movzx
                eax, BYTE PTR [rax+r9*4]
        ret
get_by_coordinates2 ENDP
array$ = 8
a$ = 16
b$ = 24
get_by_coordinates1 PROC
                rax, r8d
        movsxd
                r9, edx
        movsxd
        add
                rax, rcx
        movzx
                eax, BYTE PTR [rax+r9*4]
        ret
                0
get_by_coordinates1 ENDP
```

#### 16.5.3 Three-dimensional array example

It's thing in multidimensional arrays.

Now we are going to work with an array of type *int*: each element requires 4 bytes in memory. Let's see:

#### Listing 16.11: simple example

```
#include <stdio.h>
int a[10][20][30];

void insert(int x, int y, int z, int value)
{
         a[x][y][z]=value;
};
```

#### x86

We get (MSVC 2010):

Listing 16.12: MSVC 2010

```
DATA
         SEGMENT
COMM
          a:DWORD:01770H
_DATA
         ENDS
PUBLIC
          _insert
          SEGMENT
_TEXT
_x = 8
                           ; size = 4
_{y} = 12
                           ; size = 4
_z = 16
                           ; size = 4
_value = 20
                          ; size = 4
_insert
            PR0C
    push
            ebp
    mov
            ebp, esp
            eax, DWORD PTR _x$[ebp]
    mov
    imul
            eax, 2400
                                             ; eax=600*4*x
            ecx, DWORD PTR _y$[ebp]
    mov
    imul
            ecx, 120
                                            ; ecx=30*4*y
            edx, DWORD PTR _a[eax+ecx] eax, DWORD PTR _z$[ebp]
                                            ; edx=a + 600*4*x + 30*4*y
    lea
    mov
            ecx, DWORD PTR _value$[ebp]
    mov.
            DWORD PTR [edx+eax*4], ecx
                                            ; *(edx+z*4)=value
    mov
            ebp
    pop
            0
    ret
            ENDP
 insert
_TEXT
            ENDS
```

Nothing special. For index calculation, three input arguments are used in the formula  $address = 600 \cdot 4 \cdot x + 30 \cdot 4 \cdot y + 4z$ , to represent the array as multidimensional. Do not forget that the *int* type is 32-bit (4 bytes), so all coefficients must be multiplied by 4.

Listing 16.13: GCC 4.4.1

```
public insert
insert
                proc near
Х
                = dword ptr
                              8
                = dword ptr
                              0Ch
У
                = dword ptr
                              10h
7
                = dword ptr
value
                              14h
                push
                         ebp
                mov
                         ebp, esp
                push
                         ebx
                mov
                         ebx, [ebp+x]
                mov
                         eax, [ebp+y]
                mov
                         ecx, [ebp+z]
                                                       ; edx=y*2
                lea
                         edx, [eax+eax]
                                                       ; eax=y*2
                mov
                         eax, edx
                         eax, 4
                                                       ; eax=(y*2)<<4 = y*2*16 = y*32
                 shl
                         eax, edx
                                                       ; eax=y*32 - y*2=y*30
                 sub
                         edx, ebx, 600
                                                       ; edx=x*600
                 imul
                                                       ; eax=eax+edx=y*30 + x*600
                 add
                         eax, edx
                                                       ; edx=y*30 + x*600 + z
                 lea
                         edx, [eax+ecx]
                 mov
                         eax, [ebp+value]
                 mov
                         dword ptr ds:a[edx*4], eax ; *(a+edx*4)=value
```

CHAPTER 16. ARRAYS 16.6. CONCLUSION

	pop pop retn	ebx ebp
insert	endp	

The GCC compiler does it differently. For one of the operations in the calculation (30y), GCC produces code without multiplication instructions. This is how it done:  $(y+y) \ll 4 - (y+y) = (2y) \ll 4 - 2y = 2 \cdot 16 \cdot y - 2y = 32y - 2y = 30y$ . Thus, for the 30y calculation, only one addition operation, one bitwise shift operation and one subtraction operation are used. This works faster.

## 16.6 Conclusion

An array is a pack of values in memory located adjacently. It's true for any element type, including structures. Access to a specific array element is just a calculation of its address.

# **Chapter 17**

# Manipulating specific bit(s)

A lot of functions define their input arguments as flags in bit fields. Of course, they could be substituted by a set of *bool*-typed variables, but it is not frugally.

# 17.1 Specific bit checking

#### 17.1.1 x86

Win32 API example:

```
HANDLE fh;

fh=CreateFile ("file", GENERIC_WRITE | GENERIC_READ, FILE_SHARE_READ, NULL, OPEN_ALWAYS∠

, FILE_ATTRIBUTE_NORMAL, NULL);
```

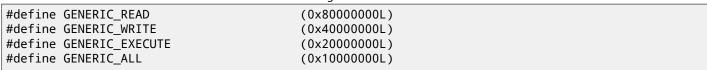
We get (MSVC 2010):

Listing 17.1: MSVC 2010

```
push
push
        128
                                                   ; 00000080H
push
        4
        0
push
push
        1
                                                   ; c0000000H
        -1073741824
push
        OFFSET $SG78813
push
        DWORD PTR __imp__CreateFileA@28
call
        DWORD PTR _fh$[ebp], eax
```

Let's take a look in WinNT.h:

#### Listing 17.2: WinNT.h



Everything is clear, GENERIC\_READ | GENERIC\_WRITE =  $0x80000000 \mid 0x40000000 = 0xC00000000$ , and that value is used as the second argument for the CreateFile()<sup>1</sup> function.

How would CreateFile() check these flags?

If we look in KERNEL32.DLL in Windows XP SP3 x86, we'll find this fragment of code in CreateFileW:

#### Listing 17.3: KERNEL32.DLL (Windows XP SP3 x86)

.text:7C83D429 .text:7C83D42D	test mov	<pre>byte ptr [ebp+dwDesiredAccess+3], 40h [ebp+var_8], 1</pre>
.text:7C83D434	jz	short loc_7C83D417
.text:7C83D436	jmp	loc_7C810817

Here we see the TEST instruction, however it doesn't take the whole second argument, but only the most significant byte (ebp+dwDesiredAccess+3) and checks it for flag 0x40 (which implies the GENERIC\_WRITE flag here)

TEST is basically the same instruction as AND, but without saving the result (recall the fact CMP is merely the same as SUB, but without saving the result (7.3.1 on page 21)).

The logic of this code fragment is as follows:

<sup>&</sup>lt;sup>1</sup>MSDN: CreateFile function

```
if ((dwDesiredAccess&0x40000000) == 0) goto loc_7C83D417
```

If AND instruction leaves this bit, the ZF flag is to be cleared and the JZ conditional jump is not to be triggered. The conditional jump is triggered only if the 0x40000000 bit is absent in dwDesiredAccess variable —then the result of AND is 0, ZF is to be set and the conditional jump is to be triggered.

# 17.2 Specific bit setting/clearing

For example:

```
#include <stdio.h>
#define IS_SET(flag, bit)
                                  ((flag) & (bit))
#define SET_BIT(var, bit)
                                   ((var) \mid = (bit))
#define REMOVE_BIT(var, bit)
                                  ((var) \&= \sim(bit))
int f(int a)
{
    int rt=a;
    SET_BIT (rt, 0x4000);
    REMOVE_BIT (rt, 0x200);
    return rt;
};
int main()
{
    f(0x12340678);
};
```

#### 17.2.1 x86

#### **Non-optimizing MSVC**

We get (MSVC 2010):

Listing 17.4: MSVC 2010

```
_{rt} = -4
                   ; size = 4
_{a} = 8
                   ; size = 4
_f PROC
           ebp
    push
    mov
           ebp, esp
    push
           ecx
    mov
           eax, DWORD PTR _a$[ebp]
    mov
           DWORD PTR _rt$[ebp], eax
            ecx, DWORD PTR _rt$[ebp]
    mov
            ecx, 16384
                                        ; 00004000H
           DWORD PTR
    mov
                       _rt$[ebp], ecx
           edx, DWORD PTR _rt$[ebp]
    mov
                                       ; fffffdffH
    and
            edx, -513
           DWORD PTR _rt$[ebp], edx
    mov
           eax, DWORD PTR _rt$[ebp]
    mov
           esp, ebp
    mov
    pop
           ebp
    ret
           0
    ENDP
```

The OR instruction adds one more bit to value while ignoring the rest.

AND resets one bit. It can be said that AND just copies all bits except one. Indeed, in the second AND operand only the bits that need to be saved are set, just the one do not want to copy is not (which is 0 in the bitmask). It is the easier way to memorize the logic.

#### **Optimizing MSVC**

If we compile it in MSVC with optimization turned on (/0x), the code is even shorter:

#### Listing 17.5: Optimizing MSVC

#### 17.3 Shifts

Bit shifts in C/C++ are implemented using « and » operators.

The x86 ISA has the SHL (SHift Left) and SHR (SHift Right) instructions for this.

Shift instructions are often used in division and multiplications by powers of two:  $2^n$  (e.g., 1, 2, 4, 8, etc): 15.1.2 on page 56, 15.2.1 on page 59.

Shifting operations are also so important because they are often used for specific bit isolation or for constructing a value of several scattered bits.

# 17.4 Counting bits set to 1

Here is a simple example of a function that calculates the number of bits set in the input value. This operation is also called "population count" <sup>2</sup>.

```
#include <stdio.h>
#define IS_SET(flag, bit)
                                 ((flag) & (bit))
int f(unsigned int a)
{
    int i;
    int rt=0;
    for (i=0; i<32; i++)
        if (IS_SET (a, 1<<i))
            rt++;
    return rt;
};
int main()
{
    f(0x12345678); // test
};
```

In this loop, the iteration count value i is counting from 0 to 31, so the  $1 \ll i$  statement is counting from 1 to  $0 \times 80000000$ . Describing this operation in natural language, we would say *shift* 1 *by* n *bits left*. In other words,  $1 \ll i$  statement consequently produces all possible bit positions in a 32-bit number. The freed bit at right is always cleared.

Here is a table of all possible  $1 \ll i$  for  $i = 0 \dots 31$ :

<sup>&</sup>lt;sup>2</sup>modern x86 CPUs (supporting SSE4) even have a POPCNT instruction for it

C/C++ expression	Power of two	Decimal form	Hexadecimal form
1 << 0	1	1	1
1 << 1	$2^1$	2	2
1 << 2	$2^{2}$	4	4
1 << 3	$2^{3}$	8	8
1 << 4	$2^{4}$	16	0x10
1 << 5	$2^{5}$	32	0x20
1 << 6	$2^{6}$	64	0x40
1 « 7	$2^{7}$	128	0x80
1 << 8	$2^{8}$	256	0x100
1 « 9	$2^{9}$	512	0x200
1 << 10	$2^{10}$	1024	0x400
1 « 11	$2^{11}$	2048	0x800
1 « 12	$2^{12}$	4096	0x1000
1 « 13	$2^{13}$	8192	0x2000
1 « 14	$2^{14}$	16384	0x4000
1 « 15	$2^{15}$	32768	0x8000
1 « 16	$2^{16}$	65536	0x10000
1 « 17	$2^{17}$	131072	0x20000
1 « 18	$2^{18}$	262144	0x40000
1 << 19	$2^{19}$	524288	0x80000
1 << 20	$2^{20}$	1048576	0x100000
1 << 21	$2^{21}$	2097152	0x200000
1 << 22	$2^{22}$	4194304	0x400000
1 << 23	$2^{23}$	8388608	0x800000
1 << 24	$2^{24}$	16777216	0x1000000
$1 \ll 25$	$2^{25}$	33554432	0x2000000
1 << 26	$2^{26}$	67108864	0x4000000
1 << 27	$2^{27}$	134217728	0x8000000
1 << 28	$2^{28}$	268435456	0x10000000
1 << 29	$2^{29}$	536870912	0x20000000
1 << 30	$2^{30}$	1073741824	0x40000000
1 « 31	$2^{31}$	2147483648	0x80000000

These constant numbers (bit masks) very often appear in code and a practicing reverse engineer must be able to spot them quickly. You probably haven't to memorize the decimal numbers, but the hexadecimal ones are very easy to remember. These constants are very often used for mapping flags to specific bits. For example, here is excerpt from ssl\_private.h from Apache 2.4.6 source code:

```
/**

* Define the SSL options

*/

#define SSL_OPT_NONE (0)

#define SSL_OPT_RELSET (1<<0)

#define SSL_OPT_STDENVVARS (1<<1)

#define SSL_OPT_EXPORTCERTDATA (1<<3)

#define SSL_OPT_FAKEBASICAUTH (1<<4)

#define SSL_OPT_STRICTREQUIRE (1<<5)

#define SSL_OPT_LEGACYDNFORMAT (1<<7)
```

Let's get back to our example.

The IS\_SET macro checks bit presence in  $\it a. \$ 

The IS\_SET macro is in fact the logical AND operation (AND) and it returns 0 if the specific bit is absent there, or the bit mask, if the bit is present. The if() operator in C/C++ triggers if the expression in it is not zero, it might be even 123456, that is why it always works correctly.

#### 17.4.1 x86

#### **MSVC**

Let's compile (MSVC 2010):

Listing 17.6: MSVC 2010

```
_rt$ = -8 ; size = 4
```

```
_{i} = -4
                      ; size = 4
_a$ = 8
                      ; size = 4
_f PROC
    push
           ebp
           ebp, esp
    mov
           esp, 8
    sub
           DWORD PTR _rt$[ebp], 0
    mov
    mov
           DWORD PTR _i$[ebp], 0
           SHORT $LN4@f
    jmp
$LN3@f:
           eax, DWORD PTR _i$[ebp]
                                       ; increment of i
    mov
    add
           eax, 1
           DWORD PTR _i$[ebp], eax
    mov
$LN4@f:
           DWORD PTR _i$[ebp], 32
                                       ; 00000020H
    cmp
    jge
           SHORT $LN2@f
                                       ; loop finished?
    mov
           edx, 1
           ecx, DWORD PTR _i$[ebp]
    mov
    shl
           edx, cl
                                       ; EDX=EDX<<CL
           edx, DWORD PTR _a$[ebp]
    and
           SHORT $LN1@f
                                       ; result of AND instruction was 0?
    jе
                                       ; then skip next instructions
           eax, DWORD PTR _rt$[ebp]
                                       ; no, not zero
    mov
                                       ; increment rt
    add
           DWORD PTR _rt$[ebp], eax
    mov
$LN1@f:
           SHORT $LN3@f
    jmp
$LN2@f:
    mov
           eax, DWORD PTR _rt$[ebp]
    mov
           esp, ebp
    pop
           ebp
           0
    ret
      ENDP
```

#### 17.4.2 x64

I modified the example slightly to extend it to 64-bit:

#### **Optimizing MSVC 2010**

Listing 17.7: MSVC 2010

```
a$ = 8
f     PROC
; RCX = input value
     xor     eax, eax
     mov     edx, 1
     lea     r8d, QWORD PTR [rax+64]
; R8D=64
     npad     5
$LL4@f:
```

```
test
                 rdx, rcx
 there are no such bit in input value?
; skip the next INC instruction then.
                 SHORT $LN3@f
        jе
        inc
                         ; rt++
                 eax
$LN3@f:
        rol
                 rdx, 1; RDX=RDX << 1
        dec
                         ; R8--
                 SHORT $LL4@f
        jne
        fatret
                 0
        ENDP
f
```

Here the ROL instruction is used instead of SHL, which is in fact "rotate left" instead of "shift left", but in this example it works just as SHL.

R8 here is counting from 64 to 0. It's just like an inverted i.

Here is a table of some registers during the execution:

RDX	R8
0x0000000000000001	64
0x00000000000000002	63
0x0000000000000004	62
0x0000000000000000	61
0x40000000000000000	2
0x8000000000000000	1

#### **Optimizing MSVC 2012**

Listing 17.8: MSVC 2012

```
a$ = 8
       PR<sub>0</sub>C
; RCX = input value
       xor
               eax, eax
       mov
               edx, 1
               r8d, QWORD PTR [rax+32]
       lea
; EDX = 1, R8D = 32
       npad
$LL4@f:
; pass 1
       test
               rdx, rcx
       jе
               SHORT $LN3@f
       inc
               eax
                      ; rt++
$LN3@f:
               rdx, 1 ; RDX=RDX<<1
       rol
; pass 2 ------
       test
               rdx, rcx
               SHORT $LN11@f
        je
                      ; rt++
       inc
               eax
$LN11@f:
               rdx, 1 ; RDX=RDX<<1
       rol
       dec
               r8
                     ; R8--
               SHORT $LL4@f
       fatret 0
       ENDP
f
```

Optimizing MSVC 2012 does almost the same job as optimizing MSVC 2010, but somehow, it generates two identical loop bodies and the loop count is now 32 instead of 64. To be honest, I don't know why. Some optimization trick? Maybe it's better for the loop body to be slightly longer? Anyway, I have added the code here intentionally to show that sometimes the compiler output may be really weird and illogical, but perfectly working.

#### 17.5 Conclusion

Analogous to the C/C++ shifting operators  $\ll$  and  $\gg$ , the shift instructions in x86 are SHR/SHL (for unsigned values) and SAR/SHL (for signed values).

The shift instructions in ARM are LSR/LSL (for unsigned values) and ASR/LSL (for signed values). It's also possible to add shift suffix to some instructions (which are called "data processing instructions").

# 17.5.1 Check for specific bit (known at compile stage)

Test if the 1000000 bit (0x40) is present in the register's value:

Listing 17.9: C/C++

```
if (input&0x40)
...
```

Listing 17.10: x86

```
TEST REG, 40h
JNZ is_set
; bit is not set
```

Listing 17.11: x86

```
TEST REG, 40h
JZ is_cleared
; bit is set
```

Sometimes, AND is used instead of TEST, but the flags that are set are the same.

#### 17.5.2 Check for specific bit (specified at runtime)

This is usually done by this C/C++ code snippet (shift value by n bits right, then cut off lowest bit):

Listing 17.12: C/C++

```
if ((value>>n)&1)
....
```

This is usually implemented in x86 code as:

Listing 17.13: x86

```
; REG=input_value
; CL=n
SHR REG, CL
AND REG, 1
```

Or (shift 1 bit n times left, isolate this bit in input value and check if it's not zero):

Listing 17.14: C/C++

```
if (value & (1<<n))
....
```

This is usually implemented in x86 code as:

Listing 17.15: x86

```
; CL=n
MOV REG, 1
SHL REG, CL
AND input_value, REG
```

#### 17.5.3 Set specific bit (known at compile stage)

Listing 17.16: C/C++

value=value|0x40;

Listing 17.17: x86

OR REG, 40h

### 17.5.4 Set specific bit (specified at runtime)

Listing 17.18: C/C++

value=value|(1<<n);</pre>

This is usually implemented in x86 code as:

Listing 17.19: x86

; CL=n MOV REG, 1 SHL REG, CL OR input\_value, REG

## 17.5.5 Clear specific bit (known at compile stage)

Just apply AND operation with the inverted value:

Listing 17.20: C/C++

value=value&(~0x40);

Listing 17.21: x86

AND REG, OFFFFFBFh

Listing 17.22: x64

AND REG, OFFFFFFFFFFFFFh

This is actually leaving all bits set except one.

## 17.5.6 Clear specific bit (specified at runtime)

Listing 17.23: C/C++

value=value&(~(1<< n));

Listing 17.24: x86

; CL=n MOV REG, 1 SHL REG, CL NOT REG AND input\_value, REG

# **Chapter 18**

# Linear congruential generator as pseudorandom number generator

The linear congruential generator is probably the simplest possible way to generate random numbers. It's not in favour in modern times<sup>1</sup>, but it's so simple (just one multiplication, one addition and one AND operation), we can use it as an example.

```
#include <stdint.h>

// constants from the Numerical Recipes book
#define RNG_a 1664525
#define RNG_c 1013904223

static uint32_t rand_state;

void my_srand (uint32_t init) {
        rand_state=init;
}

int my_rand () {
        rand_state=rand_state*RNG_a;
        rand_state=rand_state+RNG_c;
        return rand_state & 0x7fff;
}
```

There are two functions: the first one is used to initialize the internal state, and the second one is called to generate pseudorandom numbers.

We see that two constants are used in the algorithm. They are taken from [Pre+07]. I defined them using a #define C/C++ statement. It's a macro. The difference between a C/C++ macro and a constant is that all macros are replaced with their value by C/C++ preprocessor, and they don't take any memory, unlike variables. In contrast, a constant is a read-only variable. It's possible to take a pointer (or address) of a constant variable, but impossible to do so with a macro.

The last AND operation is needed because by C-standard, my\_rand() has to return a value in the 0..32767 range. If you want to get 32-bit pseudorandom values, just omit the last AND operation.

#### 18.1 x86

Listing 18.1: Optimizing MSVC 2013

```
BSS
        SEGMENT
_rand_state DD 01H DUP (?)
_BSS
        ENDS
_{init} = 8
_srand
        PROC
                eax, DWORD PTR _init$[esp-4]
        mov
        mov
                DWORD PTR _rand_state, eax
        ret
_srand
        ENDP
TEXT
        SEGMENT
```

<sup>&</sup>lt;sup>1</sup>Mersenne twister is better

```
PROC
_rand
                eax, DWORD PTR _rand_state, 1664525
        imul
        add
                eax, 1013904223
                                          ; 3c6ef35fH
                DWORD PTR _rand_state, eax
        mov
                                          ; 00007fffH
        and
                eax, 32767
                0
        ret
_rand
        ENDP
_TEXT
        ENDS
```

Here we see it: both constants are embedded into the code. There is no memory allocated for them. The my\_srand() function just copies its input value into the internal rand\_state variable.

my\_rand() takes it, calculates the next rand\_state, cuts it and leaves it in the EAX register.

The non-optimized version is more verbose:

Listing 18.2: Non-optimizing MSVC 2013

```
_BSS
        SEGMENT
_rand_state DD
                 01H DUP (?)
_BSS
        ENDS
_init = 8
        PROC
_srand
        push
                 ebp
        mov
                 ebp, esp
                 eax, DWORD PTR _init$[ebp]
        mov
        mov
                 DWORD PTR _rand_state, eax
        pop
                 ebp
        ret
                 0
_srand
        ENDP
_TEXT
        SEGMENT
_rand
        PROC
        push
                 ebp
        mov
                 ebp, esp
                 eax, DWORD PTR _rand_state, 1664525
        imul
        mov
                 DWORD PTR _rand_state, eax
                 ecx, DWORD PTR _rand_state
        mov
        add
                 ecx, 1013904223
                                          ; 3c6ef35fH
        mov
                 DWORD PTR _rand_state, ecx
                 eax, DWORD PTR _rand_state
        mov
                                           ; 00007fffH
                 eax, 32767
        and
                 ebp
        pop
                 0
        ret
        ENDP
_rand
_TEXT
        ENDS
```

#### 18.2 x64

The x64 version is mostly the same and uses 32-bit registers instead of 64-bit ones (because we are working with *int* values here). But my\_srand() takes its input argument from the ECX register rather than from stack:

Listing 18.3: Optimizing MSVC 2013 x64

```
_BSS
        SEGMENT
rand_state DD
                01H DUP (?)
_BSS
        ENDS
init = 8
my_srand PROC
; ECX = input argument
                DWORD PTR rand_state, ecx
        mov
                0
        ret
my_srand ENDP
TEXT
        SEGMENT
my_rand PROC
        imul
                eax, DWORD PTR rand_state, 1664525
                                                           ; 0019660dH
```

CHAFTEN 10	D. LIIVLAN CO	DINUNULINITAL ULINLINATUK AS ESLUDUKANDUI	A NOMBER GENERATOR	10.2. AUT
	add mov	eax, 1013904223 DWORD PTR rand_state, eax	; 3c6ef35fH	
-	and	eax, 32767	; 00007fffH	
	ret	0		
my_rand	ENDP			
_TEXT	ENDS			

# **Chapter 19**

# **Structures**

A C/C++ structure, with some assumptions, is just a set of variables, always stored in memory together, not necessary of the same type  $^{1}$ .

# 19.1 MSVC: SYSTEMTIME example

Let's take the SYSTEMTIME<sup>2</sup> win32 structure that describes time. This is how it's defined:

Listing 19.1: WinBase.h

```
typedef struct _SYSTEMTIME {
    WORD wYear;
    WORD wMonth;
    WORD wDayOfWeek;
    WORD wDay;
    WORD wHour;
    WORD wMinute;
    WORD wSecond;
    WORD wMilliseconds;
} SYSTEMTIME, *PSYSTEMTIME;
```

Let's write a C function to get the current time:

We get (MSVC 2010):

Listing 19.2: MSVC 2010 /GS-

```
_{t} = -16 ; size = 16
_main
           PROC
    push
           ebp
    mov
           ebp, esp
           esp, 16
    sub
           eax, DWORD PTR _t$[ebp]
    lea
    push
           eax
    call
           DWORD PTR
                        _imp___GetSystemTime@4
           ecx, WORD PTR _t$[ebp+12] ; wSecond
    movzx
    push
```

<sup>&</sup>lt;sup>1</sup>AKA "heterogeneous container"

<sup>&</sup>lt;sup>2</sup>MSDN: SYSTEMTIME structure

CHAPTER 19. STRUCTURES 19.1. MSVC: SYSTEMTIME EXAMPLE

```
movzx edx, WORD PTR _t$[ebp+10]; wMinute
   push
          edx
          eax, WORD PTR _t$[ebp+8]; wHour
   movzx
   push
          eax
          ecx, WORD PTR _t$[ebp+6]; wDay
   movzx
   push
          ecx
          edx, WORD PTR _t$[ebp+2]; wMonth
   movzx
          edx
   push
          eax, WORD PTR _t$[ebp] ; wYear
   movzx
   push
          eax
          OFFSET $SG78811 ; '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H
   push
          _printf
   call
   add
          esp, 28
          eax, eax
   xor
   mov
          esp, ebp
   pop
          ebp
          0
   ret
          ENDP
main
```

16 bytes are allocated for this structure in the local stack —that is exactly sizeof(WORD)\*8 (there are 8 WORD variables in the structure).

Pay attention to the fact that the structure begins with the wYear field. It can be said that a pointer to the SYSTEMTIME structure is passed to the GetSystemTime()<sup>3</sup>, but it is also can be said that a pointer to the wYear field is passed, and that is the same! GetSystemTime() writes the current year to the WORD pointer pointing to, then shifts 2 bytes ahead, writes current month, etc, etc.

#### 19.1.1 Replacing the structure with array

The fact that the structure fields are just variables located side-by-side, I can demonstrate by doing the following. Keeping in mind the SYSTEMTIME structure description, I can rewrite this simple example like this:

```
#include <windows.h>
#include <stdio.h>

void main()
{
    WORD array[8];
    GetSystemTime (array);

    printf ("%04d-%02d-%02d %02d:%02d:%02d\n",
        array[0] /* wYear */, array[1] /* wMonth */, array[3] /* wDay */,
        array[4] /* wHour */, array[5] /* wMinute */, array[6] /* wSecond */);

    return;
};
```

The compiler grumbles a bit:

```
systemtime2.c(7) : warning C4133: 'function' : incompatible types - from 'WORD [8]' to '∠ 

↓ LPSYSTEMTIME'
```

But nevertheless, it produces this code:

Listing 19.3: Non-optimizing MSVC 2010

```
$SG78573 DB
                 '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H
_array$ = -16
                 ; size = 16
        PROC
_main
        push
                ebp
        mov
                 ebp, esp
        sub
                 esp, 16
                eax, DWORD PTR _array$[ebp]
        lea
        push
                eax
                DWORD PTR
                            __imp___GetSystemTime@4
        call
                ecx, WORD PTR _array$[ebp+12] ; wSecond
        movzx
        push
                ecx
        movzx
                 edx, WORD PTR _array$[ebp+10]; wMinute
        push
                edx
```

<sup>&</sup>lt;sup>3</sup>MSDN: SYSTEMTIME structure

```
eax, WORD PTR _array$[ebp+8] ; wHoure
       movzx
       push
                eax
                ecx, WORD PTR _array$[ebp+6]; wDay
       movzx
                ecx
       push
                edx, WORD PTR _array$[ebp+2]; wMonth
       movzx
       push
                edx
                eax, WORD PTR _array$[ebp]; wYear
       movzx
       push
                OFFSET $SG78573
       push
                _printf
       call
       add
                esp, 28
       xor
                eax, eax
                esp, ebp
       mov
       pop
                ebp
       ret
       ENDP
_main
```

And it works just as the same!

It is very interesting that the result in assembly form cannot be distinguished from the result of the previous compilation. So by looking at this code, one cannot say for sure if there was a structure declared, or an array.

Nevertheless, no sane person would do it, as it is not convenient. Also the structure fields may be changed by developers, swapped, etc.

## 19.2 Let's allocate space for a structure using malloc()

Sometimes it is simpler to place structures not the in local stack, but in the heap:

Let's compile it now with optimization (/0x) so it would be easy see what we need.

Listing 19.4: Optimizing MSVC

```
_main
          PROC
   push
          esi
   push
          16
           _malloc
   call
   add
          esp, 4
   mov
          esi, eax
   push
          esi
          DWORD PTR
                      __imp___GetSystemTime@4
   call
          eax, WORD PTR [esi+12]; wSecond
   movzx
          ecx, WORD PTR [esi+10]; wMinute
   movzx
   movzx
          edx, WORD PTR [esi+8]; wHour
   push
          eax
   movzx
          eax, WORD PTR [esi+6]; wDay
   push
          ecx
          ecx, WORD PTR [esi+2]; wMonth
   movzx
          edx
   push
          edx, WORD PTR [esi]; wYear
   movzx
   push
          eax
   push
          ecx
```

```
push
           edx
           OFFSET $SG78833
   push
            _printf
   call
   push
           esi
   call
           free
           esp, 32
   add
           eax, eax
   xor
   pop
           esi
           n
   ret
           ENDP
_main
```

So, sizeof(SYSTEMTIME) = 16 and that is exact number of bytes to be allocated by malloc(). It returns a pointer to a freshly allocated memory block in the EAX register, which is then moved into the ESI register. GetSystemTime() win32 function takes care of saving value in ESI, and that is why it is not saved here and continues to be used after the GetSystemTime() call.

New instruction —MOVZX (*Move with Zero eXtend*). It may be used in most cases as MOVSX, but it sets the remaining bits to 0. That's because printf() requires a 32-bit *int*, but we got a WORD in the structure —that is 16-bit unsigned type. That's why by copying the value from a WORD into *int*, bits from 16 to 31 must be cleared, because a random noise may be there, which is left from the previous operations on the register(s).

In this example, I again can represent the structure as an array of 8 WORDs:

We get:

Listing 19.5: Optimizing MSVC

```
$SG78594 DB
                 '%04d-%02d-%02d %02d:%02d:%02d', 0aH, 00H
        PROC
_main
        push
                 esi
        push
                 16
        call
                 _malloc
        add
                 esp, 4
        mov
                 esi, eax
        push
                 DWORD PTR
                              _imp___GetSystemTime@4
        call
                 eax, WORD PTR [esi+12]
        {\tt movzx}
                 ecx, WORD PTR [esi+10]
        movzx
                 edx, WORD PTR [esi+8]
        movzx
        push
                 eax
                 eax, WORD PTR [esi+6]
        movzx
                 ecx
        push
        movzx
                 ecx, WORD PTR [esi+2]
        push
                 edx
        {\tt movzx}
                 edx, WORD PTR [esi]
        push
                 eax
        push
                 ecx
        push
                 edx
                 OFFSET $SG78594
        push
                 _printf
        call
        push
                 esi
        call
                 _free
```

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```
add esp, 32
xor eax, eax
pop esi
ret 0
_main ENDP
```

Again, we got the code cannot be distinguished from the previous one. And again I have to note, you haven't to do this in practice, unless you really know what you are doing.

## 19.3 Fields packing in structure

One important thing is fields packing in structures<sup>4</sup>. Let's take a simple example:

```
#include <stdio.h>
struct s
    char a;
    int b;
    char c;
    int d;
};
void f(struct s s)
    printf ("a=%d; b=%d; c=%d; d=%d\n", s.a, s.b, s.c, s.d);
};
int main()
{
    struct s tmp;
    tmp.a=1;
    tmp.b=2;
    tmp.c=3;
    tmp.d=4;
    f(tmp);
};
```

As we see, we have two *char* fields (each is exactly one byte) and two more -int (each - 4 bytes).

#### 19.3.1 x86

This compiles to:

Listing 19.6: MSVC 2012 /GS- /Ob0

```
_{tmp} = -16
1
2
             PROC
    main
3
        push
               ebp
4
        mov
               ebp, esp
5
        sub
               esp, 16
6
               BYTE PTR _tmp$[ebp], 1
                                            ; set field a
        mov
               DWORD PTR _tmp$[ebp+4], 2
7
        mov
                                           ; set field b
8
        mov
               BYTE PTR _tmp$[ebp+8], 3
                                            ; set field c
9
               DWORD PTR _tmp$[ebp+12], 4 ; set field d
        mov
10
                                             ; allocate place for temporary structure
        sub
               esp, 16
11
        mov
               eax, esp
               ecx, DWORD PTR _tmp$[ebp]
                                            ; copy our structure to the temporary one
12
        mov
13
        mov
               DWORD PTR [eax], ecx
               edx, DWORD PTR _tmp$[ebp+4]
14
        mov
15
               DWORD PTR [eax+4], edx
        mov
16
               ecx, DWORD PTR
        mov
                                _tmp$[ebp+8]
17
        mov
               DWORD PTR [eax+8], ecx
18
        mov
               edx, DWORD PTR _tmp$[ebp+12]
19
        mov
               DWORD PTR [eax+12], edx
20
        call
                 _f
21
        add
               esp, 16
```

<sup>&</sup>lt;sup>4</sup>See also: Wikipedia: Data structure alignment

CHAPTER 19. STRUCTURES 19.3. FIELDS PACKING IN STRUCTURE

```
22
        xor
                eax, eax
23
        mov
                esp, ebp
                ebp
24
        pop
25
        ret
              ENDP
26
    main
27
28
    _s$ = 8 ; size = 16
29
    ?f@@YAXUs@@@Z PROC ; f
30
        push
                ebp
31
        mov
                ebp, esp
32
                eax, DWORD PTR _s$[ebp+12]
        mov
33
        push
                eax
34
                ecx, BYTE PTR _s$[ebp+8]
        movsx
35
        push
                ecx
                edx, DWORD PTR _s$[ebp+4]
36
        mov
37
        push
                edx
38
                eax, BYTE PTR _s$[ebp]
        movsx
39
        push
                OFFSET $SG3842
40
        push
41
        call
                _printf
47
        add
                esp, 20
43
        pop
                ebp
44
        ret
                0
45
    ?f@@YAXUs@@@Z ENDP ; f
46
    TEXT
              ENDS
```

We pass the structure as a whole, but in fact, as we can see, the structure is being copied to a temporary one (a place in stack is allocated in line 10 for it, and then all 4 fields, one by one, are copied in lines  $12 \dots 19$ ), and then its pointer (address) is to be passed. The structure is copied because it's not know if the f() function going to modify the structure or not. If it gets changed, then the structure in main() has to remain as it was. We could use C/C++ pointers, and the resulting code will be almost the same, but without the copying.

As we can see, each field's address is aligned on a 4-byte boundary. That's why each *char* occupies 4 bytes here (like *int*). Why? Because it is easier for the CPU to access memory at aligned addresses and to cache data from it.

However, it is not very economical.

Let's try to compile it with option (/Zp[n] pack structures on n-byte boundary).

Listing 19.7: MSVC 2012 /GS- /Zp1

```
PROC
    _main
1
2
                ebp
        push
3
        mov
                ebp, esp
4
                esp, 12
        sub
5
                BYTE PTR _tmp$[ebp], 1
                                              ; set field a
        mov
                DWORD PTR _tmp$[ebp+1], 2
6
        mov
                                              ; set field b
7
        mov
                BYTE PTR _tmp$[ebp+5], 3
                                              ; set field c
8
                DWORD PTR _tmp$[ebp+6], 4
        mov
                                              ; set field d
9
                esp, 12
                                              ; allocate place for temporary structure
        sub
10
        mov
                eax, esp
11
        mov
                ecx, DWORD PTR _tmp$[ebp]
                                             ; copy 10 bytes
                DWORD PTR [eax], ecx
12
        mov
                edx, DWORD PTR _tmp$[ebp+4]
13
        mov
                DWORD PTR [eax+4], edx
14
        mov
15
                cx, WORD PTR _tmp$[ebp+8]
        mov
16
                WORD PTR [eax+8], cx
        mov
                 _f
17
        call
18
        add
                esp, 12
19
        xor
                eax, eax
20
        mov
                esp, ebp
                ebp
21
        pop
22
        ret
                n
23
    _main
             ENDP
24
    _TEXT
25
             SEGMENT
26
    _s$ = 8 ; size = 10
    ?f@@YAXUs@@@Z PROC
27
                            ; f
28
        push
                ebp
29
        mov
                ebp, esp
30
                eax, DWORD PTR _s$[ebp+6]
        mov
31
        push
              ecx, BYTE PTR _s$[ebp+5]
32
        movsx
```

CHAPTER 19. STRUCTURES 19.3. FIELDS PACKING IN STRUCTURE

```
33
        push
                ecx
34
                edx, DWORD PTR _s$[ebp+1]
        mov
35
        push
                edx
36
        movsx
                eax, BYTE PTR _s$[ebp]
37
        push
                eax
                OFFSET $SG3842
38
        push
                _printf
39
        call
40
        add
                esp, 20
41
        pop
                ebp
47
                n
        ret
43
    ?f@@YAXUs@@@Z ENDP
                             ; f
```

Now the structure takes only 10 bytes and each *char* value takes 1 byte. What does it give to us? Size economy. And as drawback —the CPU accessing these fields slower than it could.

The structure is also copied in main(). Not field-by-field, but directly 10 bytes, using three pairs of MOV. Why not 4? The compiler decided that it's better to copy 10 bytes using 3 MOV pairs than to copy two 32-bit words and two bytes using 4 MOV pairs.

As it can be easily guessed, if the structure is used in many source and object files, all these must be compiled with the same convention about structures packing.

Aside from MSVC /Zp option which sets how to align each structure field, there is also the #pragma pack compiler option, which can be defined right in the source code. It is available in both MSVC<sup>5</sup> and GCC<sup>6</sup>.

Let's get back to the SYSTEMTIME structure that consists of 16-bit fields. How does our compiler know to pack them on 1-byte alignment boundary?

WinNT.h file has this:

#### Listing 19.8: WinNT.h

```
#include "pshpack1.h"
```

And this:

#### Listing 19.9: WinNT.h

```
#include "pshpack4.h" // 4 byte packing is the default
```

The file PshPack1.h looks like:

#### Listing 19.10: PshPack1.h

```
#if ! (defined(lint) || defined(RC_INVOKED))
#if ( _MSC_VER >= 800 && !defined(_M_I86)) || defined(_PUSHPOP_SUPPORTED)
#pragma warning(disable:4103)
#if !(defined( MIDL_PASS )) || defined( __midl )
#pragma pack(push,1)
#else
#pragma pack(1)
#endif
#else
#pragma pack(1)
#endif
#endif /* ! (defined(lint) || defined(RC_INVOKED)) */
```

This tell the compiler how to pack the structures defined after #pragma pack.

#### 19.3.2 One more word

Passing a structure as a function argument (instead of a passing pointer to structure) is the same as passing all structure fields one by one. If the structure fields are packed by default, the f() function can be rewritten as:

```
void f(char a, int b, char c, int d)
{
    printf ("a=%d; b=%d; c=%d; d=%d\n", a, b, c, d);
};
```

And that leads to the same code.

<sup>&</sup>lt;sup>5</sup>MSDN: Working with Packing Structures

<sup>&</sup>lt;sup>6</sup>Structure-Packing Pragmas

CHAPTER 19. STRUCTURES 19.4. NESTED STRUCTURES

#### 19.4 Nested structures

Now what about situations when one structure is defined inside of another?

```
#include <stdio.h>
struct inner struct
{
    int a;
    int b;
};
struct outer_struct
    char a;
    int b;
    struct inner_struct c;
    char d;
    int e;
};
void f(struct outer_struct s)
    printf ("a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d\n",
        s.a, s.b, s.c.a, s.c.b, s.d, s.e);
};
int main()
{
    struct outer_struct s;
    s.a=1;
    s.b=2;
    s.c.a=100;
    s.c.b=101;
    s.d=3;
    s.e=4;
    f(s);
};
```

... in this case, both inner\_struct fields are to be placed between the a,b and d,e fields of the outer\_struct. Let's compile (MSVC 2010):

Listing 19.11: Optimizing MSVC 2010 /Ob0

```
'a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d', OaH, OOH
$SG2802 DB
_TEXT
         SEGMENT
_s = 8
_f
      PROC
           eax, DWORD PTR _s$[esp+16]
    mov
           ecx, BYTE PTR _s$[esp+12]
    movsx
           edx, DWORD PTR _s$[esp+8]
    mov
    push
           eax
    \text{mov}
           eax, DWORD PTR _s$[esp+8]
    push
           ecx
    mov
           ecx, DWORD PTR _s$[esp+8]
    push
           edx
           edx, BYTE PTR _s$[esp+8]
    {\tt movsx}
           eax
    push
    push
           ecx
           edx
    push
           OFFSET SG2802; 'a=%d; b=%d; c.a=%d; c.b=%d; d=%d; e=%d'
    push
           _printf
    call
    add
           esp, 28
    ret
           0
      ENDP
_f
_s = -24
         PR0C
_main
    sub
           esp, 24
    push ebx
```

CHAPTER 19. STRUCTURES 19.5. BIT FIELDS IN A STRUCTURE

```
esi
   push
   push
           edi
           ecx, 2
   mov
   sub
           esp, 24
   mov
           eax, esp
           BYTE PTR
                    _s$[esp+60], 1
   mov
           ebx, DWORD PTR _s$[esp+60]
   mov
   mov
           DWORD PTR [eax], ebx
           DWORD PTR [eax+4], ecx
   mov
           edx, DWORD PTR [ecx+98]
   lea
           esi, DWORD PTR [ecx+99]
   lea
           edi, DWORD PTR [ecx+2]
   lea
           DWORD PTR [eax+8], edx
   mov
           BYTE PTR _s$[esp+76], 3
   mov
           ecx, DWORD PTR _s$[esp+76]
   mov
           DWORD PTR [eax+12], esi
   mov
           DWORD PTR [eax+16], ecx
   mov
           DWORD PTR [eax+20], edi
   mov
   call
           _f
   add
           esp, 24
           edi
   pop
   pop
           esi
           eax, eax
   xor
   pop
           ebx
   add
           esp, 24
   ret
           0
        ENDP
_main
```

One curious thing here is that by looking onto this assembly code, we do not even see that another structure was used inside of it! Thus, we would say, nested structures are unfolded into *linear* or *one-dimensional* structure.

Of course, if we replace the struct inner\_struct c; declaration with struct inner\_struct \*c; (thus making a pointer here) the situation will be quite different.

#### 19.5 Bit fields in a structure

#### 19.5.1 CPUID example

The C/C++ language allows to define the exact number of bits for each structure field. It is very useful if one needs to save memory space. For example, one bit is enough for a *bool* variable. But of course, it is not rational if speed is important.

Let's consider the CPUID<sup>7</sup> instruction example. This instruction returns information about the current CPU and its features. If the EAX is set to 1 before the instruction's execution, CPUID returning this information packed into the EAX register:

3:0 (4 bits)	Stepping
7:4 (4 bits)	Model
11:8 (4 bits)	Family
13:12 (2 bits)	Processor Type
19:16 (4 bits)	Extended Model
27:20 (8 bits)	Extended Family

MSVC 2010 has CPUID macro, but GCC 4.4.1 does not. So let's make this function by ourselves for GCC with the help of its built-in assembler<sup>8</sup>.

```
#include <stdio.h>

#ifdef __GNUC__
static inline void cpuid(int code, int *a, int *b, int *c, int *d) {
    asm volatile("cpuid":"=a"(*a),"=b"(*b),"=c"(*c),"=d"(*d):"a"(code));
}
#endif

#ifdef _MSC_VER
#include <intrin.h>
#endif

struct CPUID_1_EAX
{
```

<sup>&</sup>lt;sup>7</sup>wikipedia

<sup>&</sup>lt;sup>8</sup>More about internal GCC assembler

CHAPTER 19. STRUCTURES 19.5. BIT FIELDS IN A STRUCTURE

```
unsigned int stepping:4;
    unsigned int model:4;
    unsigned int family_id:4;
    unsigned int processor_type:2;
    unsigned int reserved1:2;
    unsigned int extended_model_id:4;
    unsigned int extended_family_id:8;
    unsigned int reserved2:4;
};
int main()
    struct CPUID_1_EAX *tmp;
    int b[4];
#ifdef _MSC_VER
     _cpuid(b,1);
#endif
#ifdef __GNUC_
    cpuid (1, &b[0], &b[1], &b[2], &b[3]);
#endif
    tmp=(struct CPUID_1_EAX *)&b[0];
    printf ("stepping=%d\n", tmp->stepping);
    printf ("model=%d\n", tmp->model);
    printf ("family_id=%d\n", tmp->family_id);
    printf ("processor_type=%d\n", tmp->processor_type);
    printf ("extended_model_id=%d\n", tmp->extended_model_id);
    printf ("extended_family_id=%d\n", tmp->extended_family_id);
    return 0;
};
```

After CPUID fills EAX/EBX/ECX/EDX, these registers are to be written in the b[] array. Then, we have a pointer to the CPUID\_1\_EAX structure and we point it to the value in EAX from the b[] array.

In other words, we treat a 32-bit int value as a structure. Then we read from the structure.

#### **MSVC**

Let's compile it in MSVC 2008 with /0x option:

Listing 19.12: Optimizing MSVC 2008

```
_b$ = -16 ; size = 16
         PR0C
main
    sub
           esp, 16
    push
           ebx
    xor
           ecx, ecx
   mov
           eax, 1
    cpuid
    push
           esi
           esi, DWORD PTR b$[esp+24]
   lea
           DWORD PTR [esi], eax
   mov
           DWORD PTR [esi+4], ebx
   mov
           DWORD PTR [esi+8], ecx
   mov
           DWORD PTR [esi+12], edx
   mov
           esi, DWORD PTR _b$[esp+24]
   mov
   mov
           eax, esi
           eax, 15
    and
    push
           eax
    push
           OFFSET $SG15435; 'stepping=%d', OaH, OOH
    call
           _printf
    mov
           ecx, esi
    shr
           ecx, 4
    and
           ecx, 15
```

CHAPTER 19. STRUCTURES 19.5. BIT FIELDS IN A STRUCTURE

```
push
          ecx
   push
          OFFSET $SG15436 ; 'model=%d', OaH, OOH
   call
          _printf
          edx, esi
   mov
   shr
          edx, 8
   and
          edx, 15
   push
          edx
          OFFSET $SG15437 ; 'family_id=%d', OaH, OOH
   push
          _printf
   call
          eax, esi
   mov
   shr
          eax, 12
   and
          eax, 3
   push
          eax
   push
          OFFSET $SG15438 ; 'processor_type=%d', OaH, OOH
   call
          _printf
   mov
          ecx, esi
          ecx, 16
   shr
          ecx, 15
   and
   push
          ecx
   push
          OFFSET $SG15439 ; 'extended_model_id=%d', OaH, OOH
          _printf
   call
   shr
          esi, 20
   and
          esi, 255
   push
          OFFSET $SG15440 ; 'extended_family_id=%d', OaH, OOH
   push
   call
          _printf
          esp, 48
   add
   pop
          esi
          eax, eax
   xor
          ebx
   pop
          esp, 16
   add
   ret
        ENDP
_main
```

The SHR instruction shifting the value in EAX by the number of bits that must be *skipped*, e.g., we ignore some bits *at the right side*.

The AND instruction clears the unneeded bits *on the left*, or, in other words, leaves only those bits in the EAX register we need.

# Chapter 20

# 64-bit values in 32-bit environment

# 20.1 Returning of 64-bit value

```
#include <stdint.h>

uint64_t f ()
{
    return 0x1234567890ABCDEF;
};
```

## 20.1.1 x86

In a 32-bit environment, 64-bit values are returned from functions in the EDX:EAX register pair.

#### Listing 20.1: Optimizing MSVC 2010

# 20.2 Arguments passing, addition, subtraction

#### 20.2.1 x86

#### Listing 20.2: Optimizing MSVC 2012 /Ob1

```
_a$ = 8
                 ; size = 8
_b = 16
                 ; size = 8
_f_add PROC
                 eax, DWORD PTR _a$[esp-4]
        mov
                 eax, DWORD PTR _b$[esp-4]
        add
                 edx, DWORD PTR _a$[esp]
        mov
                 edx, DWORD PTR _b$[esp]
        adc
        ret
_f_add
        ENDP
_f_add_test PROC
        push
                 5461
                                  ; 00001555H
                                   75939f79H
                 1972608889
        push
                 2874
                                    00000b3aH
        push
                 1942892530
                                  ; 73ce2ff_subH
        push
                 _f_add
        call
                 edx
        push
        push
                 eax
        push
                 OFFSET $SG1436 ; '%I64d', OaH, OOH
        call
                 _printf
        add
                 esp, 28
        ret
                 0
_f_add_test ENDP
_f_sub
        PR0C
                 eax, DWORD PTR _a$[esp-4]
        mov
        sub
                 eax, DWORD PTR _b$[esp-4]
                 edx, DWORD PTR _a$[esp]
        mov
        sbb
                 edx, DWORD PTR _b$[esp]
        ret
_f_sub
        ENDP
```

We can see in the f\_add\_test() function that each 64-bit value is passed using two 32-bit values, high part first, then low part.

Addition and subtraction occur in pairs as well.

In addition, the low 32-bit part are added first. If carry was occurred while adding, the CF flag is set. The following ADC instruction adds the high parts of the values, and also adds 1 if CF = 1.

Subtraction also occurs in pairs. The first SUB may also turn on the CF flag, which is to be checked in the subsequent SBB instruction: if the carry flag is on, then 1 is also to be subtracted from the result.

It is easy to see how the f\_add() function result is then passed to printf().

## 20.3 Multiplication, division

```
#include <stdint.h>

uint64_t f_mul (uint64_t a, uint64_t b)
{
    return a*b;
};

uint64_t f_div (uint64_t a, uint64_t b)
{
    return a/b;
};

uint64_t f_rem (uint64_t a, uint64_t b)
{
    return a % b;
};
```

#### 20.3.1 x86

Listing 20.3: Optimizing MSVC 2012 /Ob1

```
a$ = 8
                 ; size = 8
_b = 16
                 ; size = 8
        PR0C
_f_mul
                DWORD PTR _b$[esp]
        push
                DWORD PTR _b$[esp]
        push
                DWORD PTR _a$[esp+8]
        push
                DWORD PTR _a$[esp+8]
        push
        call
                  _allmul ; long long multiplication
        ret
        ENDP
_f_mul
a$ = 8
                 ; size = 8
_{b} = 16
                 ; size = 8
        PR0C
_f_div
                DWORD PTR _b$[esp]
        push
                DWORD PTR _b$[esp]
        push
                DWORD PTR _a$[esp+8]
        push
                DWORD PTR _a$[esp+8]
        push
        call
                  _aulldiv ; unsigned long long division
        ret
_f_div
        ENDP
_a$ = 8
                 ; size = 8
_b = 16
                 ; size = 8
_f_rem PROC
                DWORD PTR _b$[esp]
        push
                DWORD PTR _b$[esp]
        push
                DWORD PTR _a$[esp+8]
        push
        push
                DWORD PTR _a$[esp+8]
        call
                  _aullrem ; unsigned long long remainder
        ret
_f_rem
        ENDP
```

Multiplication and division are more complex operations, so usually the compiler embeds calls to a library functions doing that.

## 20.4 Shifting right

```
#include <stdint.h>

uint64_t f (uint64_t a)
{
    return a>>7;
};
```

#### 20.4.1 x86

Listing 20.4: Optimizing MSVC 2012 /Ob1

Shifting also occurs in two passes: first the lower part is shifted, then the higher part. But the lower part is shifted with the help of the SHRD instruction, it shifts the value of EDX by 7 bits, but pulls new bits from EAX, i.e., from the higher part. The higher part is shifted using the more popular SHR instruction: indeed, the freed bits in the higher part must be filled with zeroes.

#### 20.5 Converting 32-bit value into 64-bit one

```
#include <stdint.h>
int64_t f (int32_t a)
{
    return a;
};
```

#### 20.5.1 x86

Listing 20.5: Optimizing MSVC 2012

```
_a$ = 8
_f PROC
    mov eax, DWORD PTR _a$[esp-4]
    cdq
    ret 0
_f ENDP
```

Here we also run into necessity to extend a 32-bit signed value into a 64-bit signed one. Unsigned values are converted straightforwardly: all bits in the higher part must be set to 0. But this is not appropriate for signed data types: the sign has to be copied into the higher part of the resulting number. The CDQ instruction does that here, it takes its input value in EAX, extends it to 64-bit and leaves it in the EDX:EAX register pair. In other words, CDQ gets the number sign from EAX (by getting the most significant bit in EAX), and depending of it, sets all 32 bits in EDX to 0 or 1. Its operation is somewhat similar to the MOVSX instruction.

## 64 bits

#### 21.1 x86-64

It is a 64-bit extension to the x86 architecture.

From the reverse engineer's perspective, the most important changes are:

 Almost all registers (except FPU and SIMD) were extended to 64 bits and got a R- prefix. 8 additional registers wer added. Now GPR's are: RAX, RBX, RCX, RDX, RBP, RSP, RSI, RDI, R8, R9, R10, R11, R12, R13, R14, R15.

It is still possible to access the *older* register parts as usual. For example, it is possible to access the lower 32-bit part of the RAX register using EAX:

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
RAX <sup>x64</sup>							
					ΕA	·Χ	
						Α	Х
						AH	AL

The new R8-R15 registers also have their *lower parts*: R8D-R15D (lower 32-bit parts), R8W-R15W (lower 16-bit parts), R8L-R15L (lower 8-bit parts).

7th (byte number)	6th	5th	4th	3rd	2nd	1st	0th
			R8				
R8D							
				•		R	3W
							R8L

The number of SIMD registers was doubled from 8 to 16: XMM0-XMM15.

• In Win64, the function calling convention is slightly different, somewhat resembling fastcall. The first 4 arguments are stored in the RCX, RDX, R8, R9 registers, the rest —in the stack. The Caller function must also allocate 32 bytes so the callee may save there 4 first arguments and use these registers for its own needs. Short functions may use arguments just from registers, but larger ones may save their values on the stack.

System V AMD64 ABI (Linux, \*BSD, Mac OS X)[Mit13] also somewhat resembles fastcall, it uses 6 registers RDI, RSI, RDX, RCX, R8, R9 for the first 6 arguments. All the rest are passed via the stack.

- The C/C++ int type is still 32-bit for compatibility.
- All pointers are 64-bit now.

This provokes irritation sometimes: now one needs twice as much memory for storing pointers, including cache memory, despite the fact that x64 CPUs can address only 48 bits of external RAM<sup>1</sup>.

Since now the number of registers is doubled, the compilers have more space for maneuvering called register allocation. For us this implies that the emitted code containing less number of local variables.

By the way, there are CPUs with much more GPR's, e.g. Itanium (128 registers).

<sup>&</sup>lt;sup>1</sup>Random-access memory

# Part II Important fundamentals

# Signed number representations

There are several methods for representing signed numbers<sup>1</sup>, but "two's complement" is the most popular one in computers. Here is a table for some byte values:

binary	hexadecimal	unsigned	signed (2's complement)
01111111	0x7f	127	127
01111110	0x7e	126	126
		•••	
00000110	0x6	6	6
00000101	0x5	5	5
00000100	0x4	4	4
00000011	0x3	3	3
00000010	0x2	2	2
00000001	0x1	1	1
00000000	0x0	0	0
11111111	0xff	255	-1
11111110	0xfe	254	-2
11111101	0xfd	253	-3
11111100	0xfc	252	-4
11111011	0xfb	251	-5
11111010	0xfa	250	-6
		•••	
10000010	0x82	130	-126
10000001	0x81	129	-127
10000000	0x80	128	-128

The difference between signed and unsigned numbers is that if we represent 0xFFFFFFE and 0x0000002 as unsigned, then the first number (4294967294) is bigger than the second one(2). If we represent them both as signed, the first one is to be -2, and it is smaller than the second (2). That is the reason why conditional jumps (11 on page 32) are present both for signed (e.g. JG, JL) and unsigned (JA, JBE) operations.

For the sake of simplicity, that is what one need to know:

- Number can be signed or unsigned.
- C/C++ signed types:
  - int64\_t (-9223372036854775806..9223372036854775807) or 0x8000000000000000..0x7FFFFFFFFFFFF),
  - int (-2147483646..2147483647 or 0x80000000..0x7FFFFFFF),
  - char (-127..128 or 0x7F..0x80),
  - ssize\_t.

#### Unsigned:

- unsigned int (0..4294967295 or 0..0xFFFFFFFF),
- unsigned char (0..255 or 0..0xFF),

<sup>&</sup>lt;sup>1</sup>wikipedia

- size\_t.
- Signed types have the sign in the most significant bit: 1 mean "minus", 0 mean "plus".
- Promoting to a larger data types is simple: 20.5 on page 98.
- Negation is simple: just invert all bits and add 1. We can remember that a number of inverse sign is located on the opposite side at the same proximity from zero. The addition of one is needed because zero is present in the middle.
- The addition and subtraction operations work well for both signed and unsigned values. But for multiplication and division operations, x86 has different instructions: IDIV/IMUL for signed and DIV/MUL for unsigned.

## **Memory**

There are 3 main types of memory:

- Global memory. AKA "static memory allocation". No need to allocate explicitly, the allocation is done just by declaring variables/arrays globally. These are global variables, residing in the data or constant segments. The are available globally (hence, considered as an anti-pattern). Not convenient for buffers/arrays, because they must have a fixed size. Buffer overflows that occur here usually overwrite variables or buffers reside next to them in memory. There's an example in this book: 7.2 on page 18.
- Stack. AKA "allocate on stack". The allocation is done just by declaring variables/arrays locally in the function. These are usually local variables for the function. Sometimes these local variable are also available to descending functions (if one passes a pointer to a variable to the function to be executed). Allocation and deallocation are very fast, only SP needs to be shifted. But they're also not convenient for buffers/arrays, because the buffer size has to be fixed, unless alloca() (5.2.4 on page 11) (or a variable-length array) is used. Buffer overflows usually overwrite important stack structures: 16.2 on page 61.
- Heap. AKA "dynamic memory allocation". Allocation is done by calling malloc()/free() or new/delete in C++. This is the most convenient method: the block size may be set at runtime. Resizing is possible (using realloc()), but can be slow. This is the slowest way to allocate memory: the memory allocator must support and update all control structures while allocating and deallocating. Buffer overflows usually overwrite these structures. Heap allocations are also source of memory leak problems: each memory block has to be deallocated explicitly, but one may forget about it, or do it incorrectly. Another problem is the "use after free"—using a memory block after free() was called on it, which is very dangerous. Example in this book: 19.2 on page 86.



Finding important/interesting stuff in the code

Minimalism it is not a prominent feature of modern software.

But not because the programmers are writing a lot, but because a lot of libraries are commonly linked statically to executable files. If all external libraries were shifted into an external DLL files, the world would be different. (Another reason for C++ are the STL and other template libraries.)

Thus, it is very important to determine the origin of a function, if it is from standard library or well-known library (like Boost<sup>1</sup>, libpng<sup>2</sup>), or if it is related to what we are trying to find in the code.

It is just absurd to rewrite all code in C/C++ to find what we're looking for.

One of the primary tasks of a reverse engineer is to find quickly the code he/she needs.

The IDA disassembler allow us to search among text strings, byte sequences and constants. It is even possible to export the code to .lst or .asm text files and then use grep, awk, etc.

When you try to understand what some code is doing, this easily could be some open-source library like libpng. So when you see some constants or text strings which look familiar, it is always worth to *google* them. And if you find the opensource project where they are used, then it's enough just to compare the functions. It may solve some part of the problem.

For example, if a program uses XML files, the first step may be determining which XML library is used for processing, since the standard (or well-known) libraries are usually used instead of self-made one.

For example, once I tried to understand how the compression/decompression of network packets worked in SAP 6.0. It is a huge software, but a detailed .PDB with debugging information is present, and that is convenient. I finally came to the idea that one of the functions, that was called CsDecomprLZC, was doing the decompression of network packets. Immediately I tried to google its name and I quickly found the function was used in MaxDB (it is an open-source SAP project).

http://www.google.com/search?q=CsDecomprLZC

Astoundingly, MaxDB and SAP 6.0 software shared likewise code for the compression/decompression of network packets.

<sup>1</sup>http://go.yurichev.com/17036

<sup>&</sup>lt;sup>2</sup>http://go.yurichev.com/17037

# Communication with the outer world (win32)

Sometimes it's enough to observe some function's inputs and outputs in order to understand what it does. That way you can save time.

Files and registry access: for the very basic analysis, Process Monitor<sup>1</sup> utility from SysInternals can help.

For the basic analysis of network accesses, Wireshark<sup>2</sup> can be useful.

But then you will have to to look inside anyway.

The first thing to look for is which functions from the OS's API<sup>3</sup>s and standard libraries are used.

If the program is divided into a main executable file and a group of DLL files, sometimes the names of the functions in these DLLs can help.

If we are interested in exactly what can lead to a call to MessageBox() with specific text, we can try to find this text in the data segment, find the references to it and find the points from which the control may be passed to the MessageBox() call we're interested in.

If we are talking about a video game and we're interested in which events are more or less random in it, we may try to find the rand() function or its replacements (like the Mersenne twister algorithm) and find the places from which those functions are called, and more importantly, how are the results used.

But if it is not a game, and rand() is still used, it is also interesting to know why. There are cases of unexpected rand() usage in data compression algorithms (for encryption imitation): blog.yurichev.com.

#### 24.1 Often used functions in the Windows API

These functions may be among the imported. It is worth to note that not every function might be used in the code that was written by the programmer. A lot of functions might be called from library functions and CRT code.

- Registry access (advapi32.dll): RegEnumKeyEx<sup>4 5</sup>, RegEnumValue<sup>6 5</sup>, RegGetValue<sup>7 5</sup>, RegOpenKeyEx<sup>8 5</sup>, RegQueryValueEx<sup>9 5</sup>.
- Access to text .ini-files (kernel32.dll): GetPrivateProfileString <sup>10 5</sup>.
- Dialog boxes (user32.dll): MessageBox <sup>11 5</sup>, MessageBoxEx <sup>12 5</sup>, SetDlgItemText <sup>13 5</sup>, GetDlgItemText <sup>14 5</sup>.
- Resources access: (user32.dll): LoadMenu <sup>15 5</sup>.
- TCP/IP networking (ws2\_32.dll): WSARecv <sup>16</sup>, WSASend <sup>17</sup>.

```
1http://go.yurichev.com/17301
 <sup>2</sup>http://go.yurichev.com/17303
 <sup>3</sup>Application programming interface
 <sup>5</sup>May have the -A suffix for the ASCII version and -W for the Unicode version
 <sup>6</sup>MSDN
 <sup>7</sup>MSDN
 8MSDN
 <sup>9</sup>MSDN
<sup>10</sup>MSDN
<sup>11</sup>MSDN
<sup>12</sup>MSDN
<sup>13</sup>MSDN
<sup>14</sup>MSDN
<sup>15</sup>MSDN
<sup>16</sup>MSDN
<sup>17</sup>MSDN
```

- File access (kernel32.dll): CreateFile <sup>18 5</sup>, ReadFile <sup>19</sup>, ReadFileEx <sup>20</sup>, WriteFile <sup>21</sup>, WriteFileEx <sup>22</sup>.
- High-level access to the Internet (wininet.dll): WinHttpOpen <sup>23</sup>.
- Checking the digital signature of an executable file (wintrust.dll): WinVerifyTrust <sup>24</sup>.
- The standard MSVC library (if it's linked dynamically) (msvcr\*.dll): assert, itoa, ltoa, open, printf, read, strcmp, atol, atoi, fopen, fread, fwrite, memcmp, rand, strlen, strstr, strchr.

#### 24.2 tracer: Intercepting all functions in specific module

There are INT3 breakpoints in the tracer, that are triggered only once, however, they can be set for all functions in a specific DLL.

```
--one-time-INT3-bp:somedll.dll!.*
```

Or, let's set INT3 breakpoints on all functions with the xml prefix in their name:

```
--one-time-INT3-bp:somedll.dll!xml.*
```

On the other side of the coin, such breakpoints are triggered only once.

Tracer will show the call of a function, if it happens, but only once. Another drawback —it is impossible to see the function's arguments.

Nevertheless, this feature is very useful when you know that the program uses a DLL, but you do not know which functions are actually used. And there are a lot of functions.

For example, let's see, what does the uptime utility from cygwin use:

```
tracer -l:uptime.exe --one-time-INT3-bp:cygwin1.dll!.*
```

Thus we may see all that cygwin1.dll library functions that were called at least once, and where from:

```
One-time INT3 breakpoint: cygwin1.dll! main (called from uptime.exe!OEP+0x6d (0x40106d))
One-time INT3 breakpoint: cygwin1.dll!_geteuid32 (called from uptime.exe!OEP+0xba3 (0x401ba3))
One-time INT3 breakpoint: cygwin1.dll!_getuid32 (called from uptime.exe!OEP+0xbaa (0x401baa))
One-time INT3 breakpoint: cygwin1.dll!_getegid32 (called from uptime.exe!OEP+0xcb7 (0x401cb7))
One-time INT3 breakpoint: cygwin1.dll!_getgid32 (called from uptime.exe!OEP+0xcbe (0x401cbe))
One-time INT3 breakpoint: cygwin1.dll!sysconf (called from uptime.exe!0EP+0x735 (0x401735))
One-time INT3 breakpoint: cygwin1.dll!setlocale (called from uptime.exe!OEP+0x7b2 (0x4017b2))
One-time INT3 breakpoint: cygwin1.dll!_open64 (called from uptime.exe!0EP+0x994 (0x401994))
One-time INT3 breakpoint: cygwin1.dll!_lseek64 (called from uptime.exe!OEP+0x7ea (0x4017ea))
One-time INT3 breakpoint: cygwin1.dll!read (called from uptime.exe!OEP+0x809 (0x401809))
One-time INT3 breakpoint: cygwin1.dll!sscanf (called from uptime.exe!OEP+0x839 (0x401839))
One-time INT3 breakpoint: cygwin1.dll!uname (called from uptime.exe!OEP+0x139 (0x401139))
One-time INT3 breakpoint: cygwin1.dll!time (called from uptime.exe!OEP+0x22e (0x40122e))
One-time INT3 breakpoint: cygwin1.dll!localtime (called from uptime.exe!OEP+0x236 (0x401236))
One-time INT3 breakpoint: cygwin1.dll!sprintf (called from uptime.exe!OEP+0x25a (0x40125a))
One-time INT3 breakpoint: cygwin1.dll!setutent (called from uptime.exe!OEP+0x3b1 (0x4013b1))
One-time INT3 breakpoint: cygwin1.dll!getutent (called from uptime.exe!OEP+0x3c5 (0x4013c5))
One-time INT3 breakpoint: cygwin1.dll!endutent (called from uptime.exe!OEP+0x3e6 (0x4013e6))
One-time INT3 breakpoint: cygwin1.dll!puts (called from uptime.exe!OEP+0x4c3 (0x4014c3))
```

<sup>&</sup>lt;sup>18</sup>MSDN

<sup>&</sup>lt;sup>19</sup>MSDN

<sup>&</sup>lt;sup>20</sup>MSDN

<sup>&</sup>lt;sup>21</sup>MSDN

<sup>&</sup>lt;sup>22</sup>MSDN

<sup>&</sup>lt;sup>23</sup>MSDN

<sup>&</sup>lt;sup>24</sup>MSDN

# **Strings**

#### 25.1 Text strings

#### 25.1.1 C/C++

The normal C strings are zero-terminated (ASCIIZ-strings).

The reason why the C string format is as it is (zero-terminated) is apparently historical. In [Rit79] we read:

A minor difference was that the unit of I/O was the word, not the byte, because the PDP-7 was a word-addressed machine. In practice this meant merely that all programs dealing with character streams ignored null characters, because null was used to pad a file to an even number of characters.

In Hiew or FAR Manager these strings looks like this:

```
int main()
{
      printf ("Hello, world!\n");
};
```

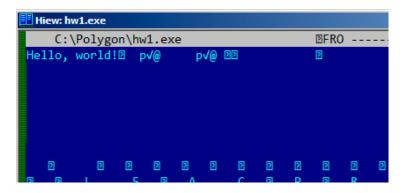


Figure 25.1: Hiew

#### 25.1.2 Borland Delphi

The string in Pascal and Borland Delphi is preceded by an 8-bit or 32-bit string length. For example:

Listing 25.1: Delphi

```
CODE:00518AC8 dd 19h
CODE:00518ACC aLoading___Plea db 'Loading..., please wait.',0
...

CODE:00518AFC dd 10h
CODE:00518B00 aPreparingRun__ db 'Preparing run...',0
```

CHAPTER 25. STRINGS 25.1. TEXT STRINGS

#### 25.1.3 Unicode

Often, what is called Unicode is a methods for encoding strings where each character occupies 2 bytes or 16 bits. This is a common terminological mistake. Unicode is a standard for assigning a number to each character in the many writing systems of the world, but does not describe the encoding method.

The most popular encoding methods are: UTF-8 (is widespread in Internet and \*NIX systems) and UTF-16LE (is used in Windows).

#### UTF-8

UTF-8 is one of the most successful methods for encoding characters. All Latin symbols are encoded just like in ASCII, and the symbols beyond the ASCII table are encoded using several bytes. 0 is encoded as before, so all standard C string functions work with UTF-8 strings just like any other string.

Let's see how the symbols in various languages are encoded in UTF-8 and how it looks like in FAR, using the 437 codepage 1.

```
How much? 100€?

(English) I can eat glass and it doesn't hurt me.
(Greek) Μπορώ να φάω σπασμένα γυαλιά χωρίς να πάθω τίποτα.
(Hungarian) Meg tudom enni az üveget, nem lesz tőle bajom.
(Icelandic) Ég get etið gler án þess að meiða mig.
(Polish) Mogę jeść szkło i mi nie szkodzi.
(Russian) Я могу есть стекло, оно мне не вредит.
(Arabic): أنا قادر على أكل الزجاج و هذا لا يؤلمني.
(Hebrew): אני יכול לאכול זכוכית וזה לא מזיק לי יכול לאכול זכוכית וזה לא מזיק לי יכול לאכול זכוכית וזה לא מזיק לי (Chinese) 我能吞下玻璃而不伤身体。
(Japanese) 私はガラスを食べられます。それは私を傷つけません。
(Hindi) 井 あずせ खा सकता हूँ और मुझे उससे कोई चोट नहीं पहुंचती.
```

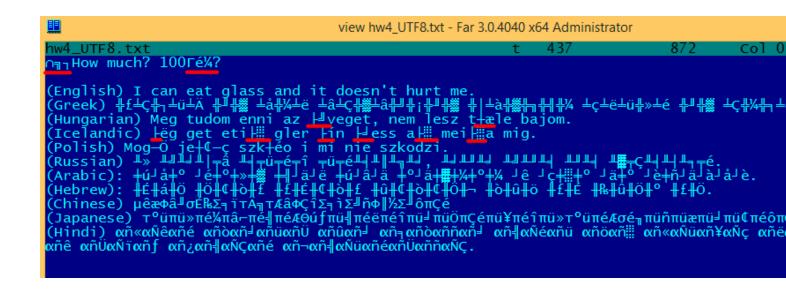


Figure 25.2: FAR: UTF-8

As you can see, the English language string looks the same as it is in ASCII. The Hungarian language uses some Latin symbols plus symbols with diacritic marks. These symbols are encoded using several bytes, I underscored them with red. It's the same story with the Icelandic and Polish languages. I also used the "Euro" currency symbol at the start, which is encoded with 3 bytes. The rest of the writing systems here have no connection with Latin. At least in Russian, Arabic, Hebrew and Hindi we can see some recurring bytes, and that is not surprise: all symbols from a writing system are usually located in the same Unicode table, so their code begins with the same numbers.

At the beginning, before the "How much?" string we see 3 bytes, which are in fact the BOM<sup>2</sup>. The BOM defines the encoding system to be used.

<sup>&</sup>lt;sup>1</sup>I've got the example and translations from here: http://go.yurichev.com/17304

<sup>&</sup>lt;sup>2</sup>Byte order mark

CHAPTER 25. STRINGS 25.1. TEXT STRINGS

#### UTF-16LE

Many win32 functions in Windows have the suffixes -A and -W. The first type of functions works with normal strings, the other with UTF-16LE strings (*wide*). In the second case, each symbol is usually stored in a 16-bit value of type *short*. The Latin symbols in UTF-16 strings look in Hiew or FAR like they are interleaved with zero byte:

```
int wmain()
{
          wprintf (L"Hello, world!\n");
};
```

Figure 25.3: Hiew

We can see this often in Windows NT system files:

```
view ntoskrnl.exe - Far 2.0.1807 x64 Administrator
IDA\Windows 7 x64\ntoskrnl.exe
           VERSION_INFO
                          ₩
                             0040904
                          N !! 0 F i
                  i o n
                                  o r
                                      por
                  nalF
       90ri
               gi
                           l e n a
                  t o
                        Windowso
                  1.7600.16385
              ◆PADDINGXXPADDINGPADDINGXXPADDINGPADDINGXXF
```

Figure 25.4: Hiew

Strings with characters that occupy exactly 2 bytes are called "Unicode" in IDA:

```
.data:0040E000 aHelloWorld:
.data:0040E000 unicode 0, <Hello, world!>
.data:0040E000 dw 0Ah, 0
```

Here is how the Russian language string is encoded in UTF-16LE:



Figure 25.5: Hiew: UTF-16LE

CHAPTER 25. STRINGS 25.2. ERROR/DEBUG MESSAGES

What we can easily spot is that the symbols are interleaved by the diamond character (which has the ASCII code of 4). Indeed, the Cyrillic symbols are located in the fourth Unicode plane  $^3$ . Hence, all Cyrillic symbols in UTF-16LE are located in the 0x400-0x4FF range.

Let's go back to the example with the string written in multiple languages. Here is how it looks like in UTF-16LE.

```
view hw4_UTF16le.txt - Far 3.0.4040 x64 Administrator
  UTF16le.txt
                                                                     Col
                  1 \ 0 \ 0
  O W
        much?
(English)
(Hungarian)
                            tudom
                     Meg
                                       enni
                                                a z
                                                      veget,
   bajom.
                     r g
                          get
                                          gler
(Arabic):
(Hebrew):
                  ∢b²Ç▲T♂N¬sât♀Ç
 Chinese)
\$0%ÄS0@0
                   _yo0%000¶0£0_gy0e0î0~0Y0•0]0î0o0_y£0_Pd0Q0~0[0ô0•0
(Japanese)
                    н
 Hindi
                                          0
                    R
      8
             G
                      §
      9
```

Figure 25.6: FAR: UTF-16LE

Here we can also see the BOM in the beginning. All Latin characters are interleaved with a zero byte. I also underscored in red some characters with diacritic marks (Hungarian and Icelandic languages).

#### 25.1.4 Base64

The base64 encoding is highly popular for the cases when you need to transfer binary data as a text string. In essence, this algorithm encodes 3 binary bytes into 4 printable characters: all 26 Latin letters (both lower and upper case), digits, plus sign ("+") and slash sign ("/"), 64 characters in total.

One distinctive feature of base64 strings is that they often (but not always) end with 1 or 2 padding equality symbol(s) ("="), for example:

AVjbbVSVfcUMu1xvjaMgjNtueRwBbxnyJw8dpGnLW8ZW8aKG3v4Y0icuQT+qEJAp91AOuWs=

WVjbbVSVfcUMu1xvjaMgjNtueRwBbxnyJw8dpGnLW8ZW8aKG3v4Y0icuQT+qEJAp91AOuQ==

The equality sign ("=") is never encounter in the middle of base64-encoded strings.

## 25.2 Error/debug messages

Debugging messages are very helpful if present. In some sense, the debugging messages are reporting what's going on in the program right now. Often these are printf()-like functions, which write to log-files, or sometimes do not writing

<sup>&</sup>lt;sup>3</sup>wikipedia

CHAPTER 25. STRINGS 25.3. SUSPICIOUS MAGIC STRINGS

anything but the calls are still present since the build is not a debug one but *release* one. If local or global variables are dumped in debug messages, it might be helpful as well since it is possible to get at least the variable names. For example, one of such function in Oracle RDBMS is ksdwrt().

Meaningful text strings are often helpful. The IDA disassembler may show from which function and from which point this specific string is used. Funny cases sometimes happen<sup>4</sup>.

The error messages may help us as well. In Oracle RDBMS, errors are reported using a group of functions. You can read more about them here: blog.yurichev.com.

It is possible to find quickly which functions report errors and in which conditions. By the way, this is often the reason for copy-protection systems to inarticulate cryptic error messages or just error numbers. No one is happy when the software cracker quickly understand why the copy-protection is triggered just by the error message.

#### 25.3 Suspicious magic strings

Some magic strings which are usually used in backdoors looks pretty suspicious. For example, there was a backdoor in the TP-Link WR740 home router<sup>5</sup>. The backdoor was activated using the following URL:

http://192.168.0.1/userRpmNatDebugRpm26525557/start\_art.html.

Indeed, the "userRpmNatDebugRpm26525557" string is present in the firmware. This string was not googleable until the wide disclosure of information about the backdoor. You would not find this in any RFC<sup>6</sup>. You would not find any computer science algorithm which uses such strange byte sequences. And it doesn't look like an error or debugging message. So it's a good idea to inspect the usage of such weird strings.

Sometimes, such strings are encoded using base64. So it's a good idea to decode them all and to scan them visually, even a glance should be enough.

More precise, this method of hiding backdoors is called "security through obscurity".

<sup>&</sup>lt;sup>4</sup>blog.yurichev.com

<sup>5</sup>http://sekurak.pl/tp-link-httptftp-backdoor/

<sup>&</sup>lt;sup>6</sup>Request for Comments

# Calls to assert()

Sometimes the presence of the assert() macro is useful too: commonly this macro leaves source file name, line number and condition in the code.

The most useful information is contained in the assert's condition, we can deduce variable names or structure field names from it. Another useful piece of information are the file names —we can try to deduce what type of code is there. Also it is possible to recognize well-known open-source libraries by the file names.

Listing 26.1: Example of informative assert() calls

```
.text:107D4B29 mov
                   dx, [ecx+42h]
.text:107D4B2D cmp
                   edx, 1
                    short loc_107D4B4A
.text:107D4B30 jz
.text:107D4B32 push 1ECh
.text:107D4B37 push offset aWrite_c ; "write.c"
.text:107D4B3C push offset aTdTd_planarcon; "td->td_planarconfig == PLANARCONFIG_CON"...
.text:107D4B41 call ds: assert
                    edx, [ebp-4]
.text:107D52CA mov
.text:107D52CD and edx, 3
.text:107D52D0 test edx, edx
.text:107D52D2 jz
                    short loc_107D52E9
.text:107D52D4 push 58h
.text:107D52D6 push offset aDumpmode_c ; "dumpmode.c"
                                   ; "(n & 3) == 0"
.text:107D52DB push offset aN30
.text:107D52E0 call ds: assert
.text:107D6759 mov cx, [eax+6]
.text:107D675D cmp
                    ecx, 0Ch
.text:107D6760 jle short loc_107D677A
.text:107D6762 push 2D8h
                                   ; "lzw.c"
.text:107D6767 push offset aLzw_c
.text:107D676C push offset aSpLzw_nbitsBit ; "sp->lzw_nbits <= BITS_MAX"</pre>
.text:107D6771 call ds:_assert
```

It is advisable to "google" both the conditions and file names, which can lead us to an open-source library. For example, if we "google" "sp->lzw\_nbits <= BITS\_MAX", this predictably gives us some open-source code that's related to the LZW compression.

## **Constants**

Humans, including programmers, often use round numbers like 10, 100, 1000, in real life as well as in the code.

The practicing reverse engineer usually know them well in hexadecimal representation: 10=0xA, 100=0x64, 1000=0x3E8, 10000=0x2710.

The constants 0xAAAAAAA (101010101010101010101010101010) and

Some algorithms, especially cryptographical ones use distinct constants, which are easy to find in code using IDA. For example, the MD5<sup>3</sup> algorithm initializes its own internal variables like this:

```
var int h0 := 0x67452301
var int h1 := 0xEFCDAB89
var int h2 := 0x98BADCFE
var int h3 := 0x10325476
```

If you find these four constants used in the code in a row, it is very highly probable that this function is related to MD5.

Another example are the CRC16/CRC32 algorithms, whose calculation algorithms often use precomputed tables like this one:

#### Listing 27.1: linux/lib/crc16.c

### 27.1 Magic numbers

A lot of file formats define a standard file header where a magic number<sup>4</sup> is used.

For example, all Win32 and MS-DOS executables start with the two characters "MZ"<sup>5</sup>.

At the beginning of a MIDI file the "MThd" signature must be present. If we have a program which uses MIDI files for something, it's very likely that it must check the file for validity by checking at least the first 4 bytes.

This could be done like this:

(buf points to the beginning of the loaded file in memory)

```
cmp [buf], 0x6468544D ; "MThd"
jnz _error_not_a_MIDI_file
```

...or by calling a function for comparing memory blocks like memcmp() or any other equivalent code up to a CMPSB instruction.

When you find such point you already can say where the loading of the MIDI file starts, also, we could see the location of the buffer with the contents of the MIDI file, what is used from the buffer, and how.

<sup>&</sup>lt;sup>1</sup>Master Boot Record

<sup>&</sup>lt;sup>2</sup>Read-only memory

<sup>&</sup>lt;sup>3</sup>wikipedia

<sup>&</sup>lt;sup>4</sup>wikipedia

<sup>&</sup>lt;sup>5</sup>wikipedia

CHAPTER 27. CONSTANTS 27.2. SEARCHING FOR CONSTANTS

#### 27.1.1 DHCP

This applies to network protocols as well. For example, the DHCP protocol's network packets contains the so-called *magic cookie*: 0x63538263. Any code that generates DHCP packets somewhere must embed this constant into the packet. If we find it in the code we may find where this happens and, not only that. Any program which can receive DHCP packet must verify the *magic cookie*, comparing it with the constant.

For example, let's take the dhcpcore.dll file from Windows 7 x64 and search for the constant. And we can find it, twice: it seems that the constant is used in two functions with descriptive names like DhcpExtractOptionsForValidation() and DhcpExtractFullOptions():

#### Listing 27.2: dhcpcore.dll (Windows 7 x64)

And here are the places where these constants are accessed:

#### Listing 27.3: dhcpcore.dll (Windows 7 x64)

.text:000007FF6480875F	mov	eax, [rsi]
.text:000007FF64808761	cmp	eax, cs:dword_7FF6483CBE8
.text:000007FF64808767	jnz	loc_7FF64817179

And:

#### Listing 27.4: dhcpcore.dll (Windows 7 x64)

.text:000007FF648082C7 .text:000007FF648082CB	mov	eax, [r12] eax, cs:dword 7FF6483CBEC
.text:000007FF648082CB	cmp jnz	loc_7FF648173AF

#### **27.2** Searching for constants

It is easy in IDA: Alt-B or Alt-I. And for searching for a constant in a big pile of files, or for searching in non-executable files, I wrote small utility called *binary grep*<sup>6</sup>.

<sup>&</sup>lt;sup>6</sup>GitHub

# Finding the right instructions

If the program is utilizing FPU instructions and there are very few of them in the code, one can try to check each one manually with a debugger.

For example, we may be interested how Microsoft Excel calculates the formulae entered by user. For example, the division operation.

If we load excel.exe (from Office 2010) version 14.0.4756.1000 into IDA, make a full listing and to find every FDIV instruction (except the ones which use constants as a second operand —obviously, they do not suit us):

```
cat EXCEL.lst | grep fdiv | grep -v dbl_ > EXCEL.fdiv
```

...then we see that there are 144 of them.

We can enter a string like =(1/3) in Excel and check each instruction.

By checking each instruction in a debugger or tracer (one may check 4 instruction at a time), we get lucky and the sought-for instruction is just the 14th:

```
.text:3011E919 DC 33 fdiv qword ptr [ebx]
```

```
PID=13944|TID=28744|(0) 0x2f64e919 (Excel.exe!BASE+0x11e919)
EAX=0x02088006 EBX=0x02088018 ECX=0x00000001 EDX=0x00000001
ESI=0x02088000 EDI=0x00544804 EBP=0x0274FA3C ESP=0x0274F9F8
EIP=0x2F64E919
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=
FPU ST(0): 1.000000
```

ST(0) holds the first argument (1) and second one is in [EBX].

The instruction after FDIV (FSTP) writes the result in memory:

```
.text:3011E91B DD 1E fstp qword ptr [esi]
```

If we set a breakpoint on it, we can see the result:

```
PID=32852|TID=36488|(0) 0x2f40e91b (Excel.exe!BASE+0x11e91b)
EAX=0x00598006 EBX=0x00598018 ECX=0x00000001 EDX=0x00000001
ESI=0x00598000 EDI=0x00294804 EBP=0x026CF93C ESP=0x026CF8F8
EIP=0x2F40E91B
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=C1 P
FPU ST(0): 0.333333
```

Also as a practical joke, we can modify it on the fly:

```
tracer -l:excel.exe bpx=excel.exe!BASE+0x11E91B,set(st0,666)
```

```
PID=36540|TID=24056|(0) 0x2f40e91b (Excel.exe!BASE+0x11e91b)
EAX=0x00680006 EBX=0x00680018 ECX=0x00000001 EDX=0x00000001
ESI=0x00680000 EDI=0x00395404 EBP=0x0290FD9C ESP=0x0290FD58
EIP=0x2F40E91B
FLAGS=PF IF
FPU ControlWord=IC RC=NEAR PC=64bits PM UM OM ZM DM IM
FPU StatusWord=C1 P
FPU ST(0): 0.333333
Set ST0 register to 666.000000
```

Excel shows 666 in the cell, finally convincing us that we have found the right point.

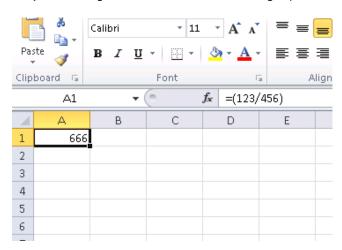


Figure 28.1: The practical joke worked

If we try the same Excel version, but in x64, we will find only 12 FDIV instructions there, and the one we looking for is the third one.

```
tracer.exe -l:excel.exe bpx=excel.exe!BASE+0x1B7FCC,set(st0,666)
```

It seems that a lot of division operations of *float* and *double* types, were replaced by the compiler with SSE instructions like DIVSD (DIVSD is present 268 times in total).

## Suspicious code patterns

#### 29.1 XOR instructions

Instructions like XOR op, op (for example, XOR EAX, EAX) are usually used for setting the register value to zero, but if the operands are different, the "exclusive or" operation is executed. This operation is rare in common programming, but widespread in cryptography, including amateur one. It's especially suspicious if the second operand is a big number. This may point to encrypting/decrypting, checksum computing, etc.

This AWK script can be used for processing IDA listing (.lst) files:

#### 29.2 Hand-written assembly code

Modern compilers do not emit the LOOP and RCL instructions. On the other hand, these instructions are well-known to coders who like to code directly in assembly language. If you spot these, it can be said that there is a high probability that this fragment of code was hand-written.

Also the function prologue/epilogue are not commonly present in hand-written assembly.

Commonly there is no fixed system for passing arguments to functions in the hand-written code.

Example from the Windows 2003 kernel (ntoskrnl.exe file):

```
MultiplyTest proc near
                                          ; CODE XREF: Get386Stepping
              xor
                       CX, CX
loc_620555:
                                          ; CODE XREF: MultiplyTest+E
              push
                        \mathsf{C}\mathsf{X}
              call
                        Multiply
              pop
                        \mathsf{C}\mathsf{X}
                        short locret_620563
              jb
                        loc_620555
              loop
locret_620563:
                                          ; CODE XREF: MultiplyTest+C
MultiplyTest endp
Multiply
                                          ; CODE XREF: MultiplyTest+5
              proc near
                       ecx, 81h
              mov
                       eax, 417A000h
              mov
              mul
                        ecx
              cmp
                        edx, 2
              stc
                        short locret_62057F
              jnz
              cmp
                        eax, 0FE7A000h
              stc
                        short locret_62057F
              jnz
              clc
locret_62057F:
                                          ; CODE XREF: Multiply+10
                                          ; Multiply+18
              retn
```

Multiply endp

Indeed, if we look in the WRK<sup>1</sup> v1.2 source code, this code can be found easily in file WRK-v1.2\base\ntos\ke\i386\cpu.asm.

<sup>&</sup>lt;sup>1</sup>Windows Research Kernel

# Using magic numbers while tracing

Often, our main goal is to understand how the program uses a value that was either read from file or received via network. The manual tracing of a value is often a very labour-intensive task. One of the simplest techniques for this (although not 100% reliable) is to use your own *magic number*.

This resembles X-ray computed tomography is some sense: a radiocontrast agent is injected into the patient's blood, which is then used to improve the visibility of the patient's internal structure in to the X-rays. For example, it is well known how the blood of healthy humans percolates in the kidneys and if the agent is in the blood, it can be easily seen on tomography, how blood is percolating, and are there any stones or tumors.

We can take a 32-bit number like  $0 \times 0 \text{badf} 00 \text{d}$ , or someone's birth date like  $0 \times 11101979$  and write this 4-byte number to some point in a file used by the program we investigate.

Then, while tracing this program with tracer in *code coverage* mode, with the help of *grep* or just by searching in the text file (of tracing results), we can easily see where the value was used and how.

Example of *grepable* tracer results in *cc* mode:

```
      0x150bf66 (_kziaia+0x14), e=
      1 [MOV EBX, [EBP+8]] [EBP+8]=0xf59c934

      0x150bf69 (_kziaia+0x17), e=
      1 [MOV EDX, [69AEB08h]] [69AEB08h]=0

      0x150bf6f (_kziaia+0x1d), e=
      1 [FS: MOV EAX, [2Ch]]

      0x150bf75 (_kziaia+0x23), e=
      1 [MOV ECX, [EAX+EDX*4]] [EAX+EDX*4]=0xf1ac360

      0x150bf78 (_kziaia+0x26), e=
      1 [MOV [EBP-4], ECX] ECX=0xf1ac360
```

This can be used for network packets as well. It is important for the *magic number* to be unique and not to be present in the program's code.

Aside of the tracer, DosBox (MS-DOS emulator) in heavydebug mode is able to write information about all registers' states for each executed instruction of the program to a plain text file<sup>1</sup>, so this technique may be useful for DOS programs as well.

<sup>&</sup>lt;sup>1</sup>See also my blog post about this DosBox feature: blog.yurichev.com

## Other things

#### 31.1 General idea

A reverse engineer should try to be in programmer's shoes as often as possible. To take his/her viewpoint and ask himself, how would one solve some task the specific case.

#### 31.2 Some binary file patterns

Sometimes, we can clearly spot an array of 16/32/64-bit values visually, in hex editor. Here is an example of very typical MIPS code. As we may remember, every MIPS (and also ARM in ARM mode or ARM64) instruction has size of 32 bits (or 4 bytes), so such code is array of 32-bit values. By looking at this screenshot, we may see some kind of pattern. I added vertical red lines for clarity:

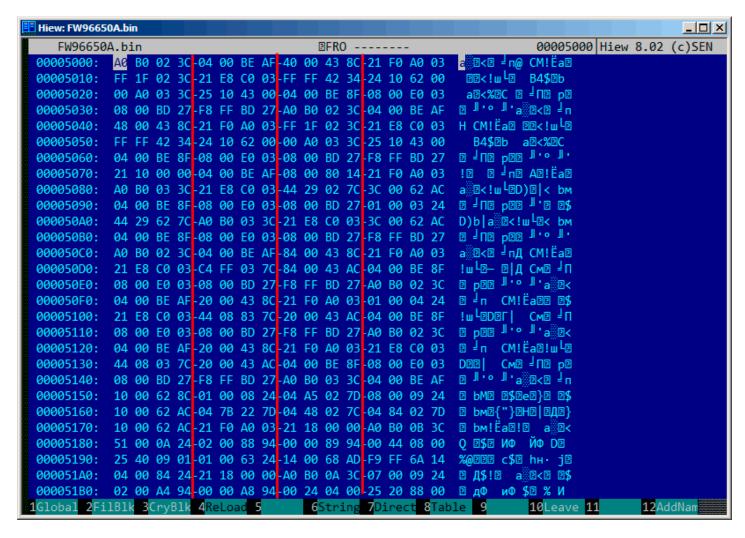


Figure 31.1: Hiew: very typical MIPS code

#### 31.3 Memory "snapshots" comparing

The technique of the straightforward comparison of two memory snapshots in order to see changes was often used to hack 8-bit computer games and for hacking "high score" files.

For example, if you had a loaded game on an 8-bit computer (there isn't much memory on these, but the game usually consumes even less memory) and you know that you have now, let's say, 100 bullets, you can do a "snapshot" of all memory and back it up to some place. Then shoot once, the bullet count goes to 99, do a second "snapshot" and then compare both: the must be must be a byte somewhere which was 100 in the beginning, and now it is 99. Considering the fact that these 8-bit games were often written in assembly language and such variables were global, it can be said for sure which address in memory was holding the bullet count. If you searched for all references to the address in the disassembled game code, it was not very hard to find a piece of code decrementing the bullet count, then to write a NOP instruction there, or a couple of NOP-s, and then have a game with 100 bullets forever. Games on these 8-bit computers were commonly loaded at the same address, also, there were not much different versions of each game (commonly just one version was popular for a long span of time), so enthusiastic gamers knew which bytes must be overwritten (using the BASIC's instruction POKE) at which address in order to hack it. This led to "cheat" lists that contained POKE instructions, published in magazines related to 8-bit games. See also: wikipedia.

Likewise, it is easy to modify "high score" files, this does not work with just 8-bit games. Notice your score count and back up the file somewhere. When the "high score" count gets different, just compare the two files, it can even be done with the DOS utility FC<sup>1</sup> ("high score" files are often in binary form). There will be a point where a couple of bytes are different and it is easy to see which ones are holding the score number. However, game developers are aware of such tricks and may defend the program against it.

#### 31.3.1 Windows registry

It is also possible to compare the Windows registry before and after a program installation. It is a very popular method of finding which registry elements are used by the program. Probably, this is the reason why the "windows registry cleaner" shareware is so popular.

#### 31.3.2 Blink-comparator

Comparison of files or memory snapshots remind us blink-comparator <sup>2</sup>: a device used by astronomers in past, intended to find moving celestial objects. Blink-comparator allows to switch quickly between two photographies shot in different time, so astronomer would spot the difference visually. By the way, Pluto was discovered by blink-comparator in 1930.

<sup>&</sup>lt;sup>1</sup>MS-DOS utility for comparing binary files

<sup>&</sup>lt;sup>2</sup>http://go.yurichev.com/17348

**Part IV** 

**Tools** 

# Disassembler

#### 32.1 IDA

An older freeware version is available for download <sup>1</sup>.

¹http://go.yurichev.com/17031

# Debugger

#### 33.1 tracer

I use tracer<sup>1</sup> instead of a debugger.

I stopped using a debugger eventually, since all I need from it is to spot the function's arguments while executing, or registers' state at some point. To load a debugger each time is too much, so I wrote the small utility *tracer*. It has a console interface, works from the command line, enables us to intercept function execution, sets breakpoints at arbitrary places, spot registers' state, modifies it, etc.

However, for learning purposes it is highly advisable to trace code in a debugger manually, watch how the registers' state changes (e.g. classic SoftICE, OllyDbg, WinDbg highlighting changed registers), flags, data, change them manually, watch the reaction, etc.

<sup>&</sup>lt;sup>1</sup>yurichev.com

# **Decompilers**

There is only one known, publicly available, high-quality decompiler to C code: Hex-Rays: http://go.yurichev.com/17033

## Other tools

- Microsoft Visual Studio Express<sup>1</sup>: Stripped-down free version of Visual Studio, convenient for simple experiments.
- Hiew<sup>2</sup> for small modifications of code in binary files.
- binary grep: the small utility for searching constants (or just any byte sequence) in a big pile of files, including non-executable: GitHub.

<sup>1</sup>http://go.yurichev.com/17034

<sup>&</sup>lt;sup>2</sup>http://go.yurichev.com/17035

# Part V Books/blogs worth reading

# **Books**

36.1 Windows

[RA09].

36.2 C/C++

[ISO13].

36.3 x86 / x86-64

[Int13], [AMD13]

36.4 ARM

ARM manuals: http://go.yurichev.com/17024

## 36.5 Cryptography

[Sch94]

# **Blogs**

#### 37.1 Windows

- Microsoft: Raymond Chen
- nynaeve.net

## **Other**

There are two excellent RE<sup>1</sup>-related subreddits on reddit.com: ReverseEngineering and REMath ( on the topics for the intersection of RE and mathematics).

There is also a RE part of the Stack Exchange website: reverseengineering.stackexchange.com.

On IRC there a ##re channel on FreeNode<sup>2</sup>.

 $<sup>^1 {\</sup>it Reverse Engineering}$ 

<sup>&</sup>lt;sup>2</sup>freenode.net

# **Afterword**

# **Questions?**

Do not hesitate to mail any questions to the author: <dennis(a)yurichev.com>
Any suggestions, what also should be added to my book?
There is also a support forum, you can ask any questions there:

#### http://go.yurichev.com/17010

Please, also do not hesitate to send me any corrections (including grammar ones (you see how horrible my English is?)), etc.

I'm working on the book a lot, so the page, listings numbers, etc, are changing very rapidly. Please, do not refer to page/listing numbers in your emails to me. There is much simpler method: just make a screenshot of the page, then underline the place where you see the error in a graphics editor, and send me it. I'll fix it much faster in this manner. And if you familiar with git and LaTeX you can fix the error right in the source code:

GitHub.

# Warning: this is shortened LITE-version!

It is approximately 6 times shorter than full version (150 pages) and intended to those who wants for very quick introduction to reverse engineering basics. There are nothing about MIPS, ARM, OllyDBG, GCC, GDB, IDA, there are no exercises, examples, etc.

If you still interesting in reverse engieering, full version of the book is always available on my website: beginners.re.

Z

Acronyms used	,
OS Operating System	6
PL Programming language	3
ROM Read-only memory	114
RA Return Address	43
SP stack pointer. SP/ESP/RSP in x86/x64. SP in ARM	9
PC Program Counter. IP/EIP/RIP in x86/64. PC in ARM	138
IDA Interactive Disassembler and debugger developed by Hex-Rays	
MSVC Microsoft Visual C++	
AKA Also Known As	
CRT C runtime library	6
CPU Central processing unit	v
SIMD Single instruction, multiple data	51
DBMS Database management systems	iv
ISA Instruction Set Architecture	3
SEH Structured Exception Handling	12
NOP No OPeration	23
RAM Random-access memory	99
API Application programming interface	106
ASCIIZ ASCII Zero (null-terminated ASCII string)	22
VM Virtual Memory	
WRK Windows Research Kernel	119
GPR General Purpose Registers	3
<b>RE</b> Reverse Engineering	131
ROM Byte order mark	109

#### CHAPTER 39. OUESTIONS?

	Master Boot Record	114
RFC R	Request for Comments	112
EOF E	End of file	.20

## **Glossary**

```
decrement Decrease by 1. 50, 55, 122
increment Increase by 1. 50, 55
product Multiplication result. 26
stack pointer A register pointing to a place in the stack. 6, 9, 11, 13, 136
quotient Division result. 59
anti-pattern Generally considered as bad practice. 18, 103
callee A function being called by another. 8, 10, 11, 16, 21, 25, 26, 43, 99
caller A function calling another. 4, 6, 21, 25–27, 43, 99
heap usually, a big chunk of memory provided by the OS so that applications can divide it by themselves as they wish.
      malloc()/free() work with the heap. 9, 11, 86
jump offset a part of the JMP or Jcc instruction's opcode, to be added to the address of the next instruction, and this is how
     the new PC<sup>1</sup> is calculated. May be negative as well. 23, 35
NOP "no operation", idle instruction. 122
PDB (Win32) Debugging information file, usually just function names, but sometimes also function arguments and local
     variables names. 105
POKE BASIC language instruction for writing a byte at a specific address. 122
register allocator The part of the compiler that assigns CPU registers to local variables. 55, 99
reverse engineering act of understanding how the thing works, sometimes in order to clone it. i, iv
stack frame A part of the stack that contains information specific to the current function: local variables, function arguments,
      RA, etc. 17, 26
stdout standard output. 12, 43
tracer My own simple debugging tool. You can read more about it here: 33.1 on page 125. 107, 116, 120
Windows NT Windows NT, 2000, XP, Vista, 7, 8. 110
```

<sup>&</sup>lt;sup>1</sup>Program Counter. IP/EIP/RIP in x86/64. PC in ARM.

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