## University of Cambridge

## CATAM Part II

# Fourier Transforms of Bessel Functions



#### Question 1

Throughout this project, I have employed Matlab's ODE45 routine to investigate n = 0, 1, 4 for various initial y and y'. I have included some plots in figure 1 below. Different columns represent different values of n, while different rows represent different values of  $y_0$ . Each image has 3 different initial gradients, with y'(0) = -1, 0, 1 being represented in blue, green and red respectively. In all of these plots, we have taken  $x_0 = 1$  and integrated both forwards and backwards.

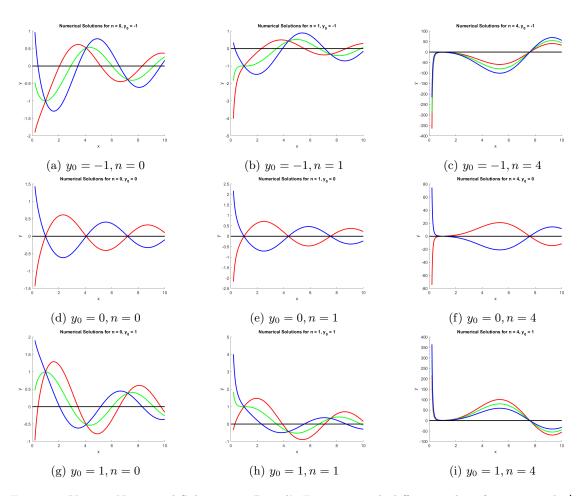


Figure 1: Various Numerical Solutions to Bessel's Equation with different values for n,  $y_0$  and  $y'_0$ .

We observe a few properties:

- 1. The function y almost always diverges at x = 0.
- 2. Solutions always look oscillatory and in the long term they decay like  $1/\sqrt{x}$ , as illustrated in figure 2.
- 3. All solutions with some initial  $y_0$  intersect at the same points. This is true if we include more than three initial gradients, as illustrated in figure 3 below.

  To explain this, note that in the case  $y_0 = 0$ , all nontrivial solutions are scalar multiples of the solution f with  $y_0 = 0$ ,  $y_0' = 1$ . This is since a solution is uniquely defined by  $y_0$  and  $y_0'$ , so if we seek a solution y with  $y_0 = 0$ ,  $y_0' = \lambda$ , then  $\lambda f$  satisfies these initial conditions and hence solves the initial value problem.

Therefore, all the solutions passing through  $(x_0, 0)$  intersect at the same points, their roots. Let's call these x-values  $\lambda_1, \lambda_2, \lambda_3, \ldots$  Now, what if  $y_0 \neq 0$ ? Well, suppose that f and g are both solutions passing through the point  $x_0, y_0$ . Then, f - g passes through  $(x_0, 0)$  so is 0 at

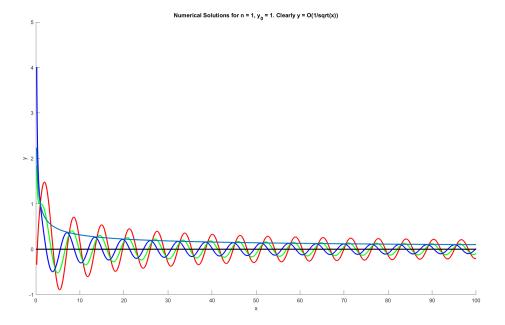


Figure 2: Asymptotically amplitudes decay like  $1/\sqrt{x}$ .

 $\lambda_1, \lambda_2, \lambda_3, \ldots$  Since f and g were arbitrary, all solutions passing through  $(x_0, y_0)$  intersect at  $\lambda_1, \lambda_2, \lambda_3, \ldots$ 

4. As  $n \to \infty$ ,  $\lambda_2 \to \infty$ , initial amplitudes  $\to \infty$  and  $y \to \infty$  much faster as  $x \to \infty$ . At  $x_0 = 0$ , Bessel's equation gives  $n^2 y_0 = 0$ , so we have two cases to consider:

 $n \neq 0$ :

$$u_{k+1} = u_k + hv_k,$$
  
 $v_{k+1} = v_k + hf(x_k, u_k, v_k),$ 

where

$$f(x, u, v) = \frac{(n^2 - x^2)u - xv}{x^2}.$$

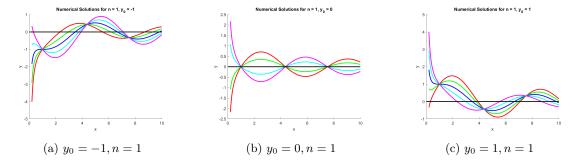


Figure 3: All points passing through  $(x_0, y_0)$  intersect at the same points

So for  $u_0 = 0, v_0 = y'_0$ , we have

$$u_1 = hy_0$$
  
 $v_1 = y'_0 + h \lim_{x \to 0} f(x, y, y'_0).$ 

Note that  $\lim_{x\to 0} f(x,0,y_0') = \lim_{x\to 0} -\frac{y_0'}{x} \to -\infty$ . So  $v_1 = y_1' = -\infty$ . Hence, there is no solution.

| n = 0: Now  $y_0$  is not necessarily 0. Therefore

$$f(x, y_0, y_0') = -(y_0 + \frac{y_0'}{x}) \to -\infty$$
 as  $x \to 0$ , so there is no solution.

#### Question 2

Let  $E_N(x)$  denote the error at x for truncating at N terms.

$$E_N(x) = \left| \sum_{r=N+1}^{\infty} \frac{(-1)^r (\frac{1}{2}x)^{2r+n}}{r!(n+r)!} \right| = \left| \sum_{r=N+1}^{\infty} (-1)^r a_n \right|.$$

This will be an alternating series with coefficients decreasing in magnitude for sufficiently large N. When does this begin? Observe that

$$\frac{|a_{N+2}|}{|a_{N+1}|} = \frac{(\frac{1}{2}x)^{2(N+2)+n}}{(\frac{1}{2}x)^{2(N+1)+n}} \cdot \frac{(N+1)!(n+N+1)!}{(N+2)!(n+N+2)!}$$
$$= \frac{(x/2)^2}{(N+2)(N+n+2)},$$

$$\sup_{x \in [0,X]} \left| \frac{a_{n+2}}{a_{n+1}} \right| \le \frac{(X/2)^2}{(N+2)^2} < 1.$$

We thus require that X/2 < N+2 in order for the series  $\sum_{n\geq N+1} (-1)^n a_n$  to be an alternating series with decreasing magnitudes  $a_n$ . Therefore, by the alternating series bound we have

$$\left| \sum_{n \ge N+1} (-1)^n a_n \right| \le a_{N+1}.$$

So to determine N we will use the following process:

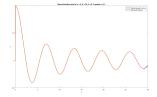
$$N = X/floor(2) - 2$$
 while a\_N > e : # e is some specified error threshold  $N = N+1$  end

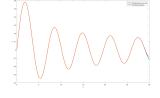
This terminates since  $a_n \to 0$ . For this N we therefore have

$$\sup_{x \in [0,X]} \left| J_n(x) - \sum_{r \le N} \frac{(-1)^r (\frac{1}{2}x)^{2r+n}}{r!(n+r)!} \right| \le \epsilon$$

So we define a function

function [X,J] = series\_soln(n,rangle,h,eps)







- (a) Series Solution for n = 0.
- (b) Series Solution for n = 1.
- (c) Series Solution for n = 0.

Figure 4: Plots of Series Solutions for n = 0, 1, 4.

where n is the order of  $J_n(x)$ , range = X, h is the stepsize and eps =  $\epsilon$  is the error threshold. In figure (4) we have plotted the cases we have plotted the cases of  $n = 0, 1, 4, \text{range} = 30, h = 0.1, \epsilon = 0.1$ .

Our function doesn't work for range  $\geq 40$ . We plot this case in (5) below, but I'm not sure exactly why it happens here. I'm sure that my mathematics is correct so I believe that this is due to limitations of computing power but I do not see why. The order of magnitude for terms x = 45 is less than  $10^{20}$ , and even when we work to 100 decimal digits we get  $J_1(45) \cong -48$ .

To find the order of the terms we're summing, note that for  $x = 2\lambda$ , we have

$$\frac{a_{k+1}(x)}{a_k(x)} = \frac{\lambda^2}{k(k+n+1)}.$$

At the maximum index, m, this becomes less than 1.

$$\lambda^2 = k(k+n+1) \implies k + \frac{n+1}{2} \approx \lambda \text{ (for small n)}.$$

So for n = 1,  $k = \lambda - 1$  gives an approximate index at which  $a_k(x)$  is maximised. To find the value of this maximum, note that

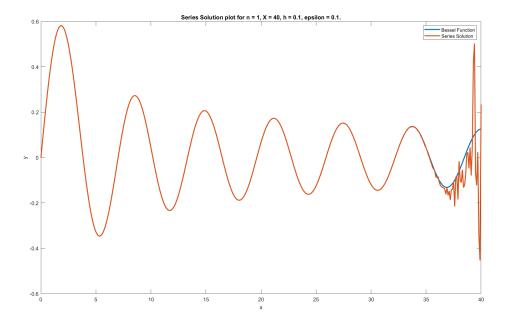


Figure 5: Our method fails for  $X \ge 40$ 

$$a_{\lambda-1}(x) = \frac{(\lambda)^{2(\lambda-1)+1}}{(\lambda-1)!(\lambda)!}$$

$$= \frac{\lambda^{2\lambda}}{(\lambda!)^2}$$
Stirling  $\rightarrow \approx \frac{\lambda^{2\lambda-1}}{2\pi\lambda(\lambda/e)^{2\lambda}}$ 

$$= \frac{e^{2\lambda}}{2\pi\lambda^2}$$

$$= \frac{2e^x}{\pi x^2}.$$

So for x = 50, the maximum terms are of order  $10^{18}$ . I am not sure why my program struggles with this sum.

#### Question 3

For  $\hat{\mathcal{F}} \to F$  we will definitely need  $X \to \infty$  and  $N \to \infty$ , but these conditions alone are not sufficient. suppose we have the functions

$$F(x) = 5 + \sin 2\pi x$$
  

$$G(x) = 5 + \sin 2\pi x + 3\sin 4\pi x + \sin 6\pi x,$$

and we sample these on the intervals [0, N] at the points  $\{0, 1, ..., N\}$ . Then as  $N \to \infty$ , both X and  $N \to \infty$ , yet the DFT is unable to distinguish F and G, so cannot in any sense converge to the Fourier transform.

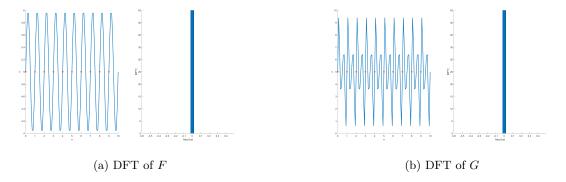


Figure 6: No matter how large X and N are, if  $\Delta x$  is too large, our DFT will fail to distinguish functions which differ in high frequencies.

Thus we need:

- $X \to \infty$ , (range tends to  $\infty$ )
- $N \to \infty$ , (num samples tends to  $\infty$ )
- $\limsup \frac{X}{N} \le \frac{1}{2k_{\max}}$  (sampling frequencies fast enough to resolve all frequencies).

Changing  $\Delta x$  in this way, our DFT distinguishes F and G. Rigorously, we let [a,b] be an interval such that

$$\int_{\mathbb{R}\setminus[a,b]} |F(x)| \, dx < \epsilon/2.$$

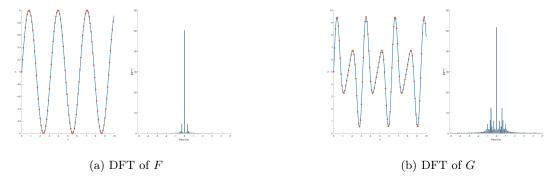


Figure 7: DFT with  $\Delta x = 0.1$  distinguishes between F and G with ease.

By translating we may, without loss of generality, assume that [a, b] = [0, X], and then

$$\hat{\mathcal{F}}_s = \sum_{r=0}^{N-1} F_r \,\omega_N^{-rs} \Delta x$$

$$= \sum_{r=0}^{N-1} F(r\Delta x) \exp\left(-2\pi i r \Delta x s/X\right) \Delta x \quad \xrightarrow[N \to \infty]{} \int_0^x F(x) \exp\left(-2\pi i s x/X\right) dx$$

So for N sufficiently large,  $|\hat{\mathcal{F}}_s - \int_0^X F(x) \exp(-2\pi i s x/X) dx| < \epsilon/2$ . Therefore

$$\left| \hat{\mathcal{F}}_s - \hat{F}(s/X) \right| \le \left| \hat{\mathcal{F}}_s - \int_0^X F(x) \exp(-2\pi i s x/X) \, dx \right| + \left| \int_{\mathbb{R} \setminus [0, X]} F(x) \exp(-2\pi i s x/X) \, dx \right|$$

$$\le \left| \hat{\mathcal{F}}_s - \int_0^X F(x) \exp(-2\pi i s x/X) \, dx \right| + \int_{\mathbb{R} \setminus [0, X]} |F(x)| \, dx$$

$$< \epsilon.$$

So if we let k = s/X, then  $\hat{\mathcal{F}}_{kX} \xrightarrow{X,N\to\infty,\Delta x \text{ small}} \hat{F}(k)$ .

#### Question 4

$$I_1 = \int_0^X F(x) \cos(2\pi kx) \, dx - i \int_0^X F(x) \sin(2\pi kx) \, dx.$$

Since F(x),  $\cos(x)$  and  $\sin(x)$  are real on [0, X] we have

- $\operatorname{Re}(I_1) = \int_0^X F(x) \cos(2\pi kx) dx$
- $\operatorname{Im}(I_1) = -\int_0^X F(x) \sin(2\pi kx) dx$ .

For  $I_2$ , we have

$$I_2 = \int_{-X}^{X} F(x) \cos(2\pi kx) dx - i \int_{-X}^{X} F(x) \sin(2\pi kx) dx$$
$$= 2 \int_{0}^{X} F(x) \cos(2\pi kx) dx + 0,$$

since  $F(x)\cos(2\pi kx)$  is even and  $F(x)\sin(2\pi kx)$  is odd. Therefore:

- $\operatorname{Re}(I_2) = 2 \int_0^X F(x) \cos(2\pi kx) dx = 2\operatorname{Re}(I_1)$
- $Im(I_2) = 0$ .

Next, suppose that we desire an approximation to  $I_2$  and  $F_N \neq F_0$ . The procedure above yields

$$I_2 \approx 2 \operatorname{Re} \left( \sum_{r=0}^{N-1} F_r \omega_N^{-rs} \Delta x \right)$$

$$= \sum_{r=0}^{N-1} F_r (\omega_N^{-rs} + \omega_N^{rs}) \Delta x + \sum_{r=1-N}^{0} F_r \omega_N^{-rs} \Delta x.$$

If  $F_N \neq F_0$  this doesn't give the rectangular approximation to the Riemann integral for  $I_2$ , as the  $F_0$  rectangle is counted twice and  $F_N$  is not counted at all. So if we set  $F_0 = \frac{1}{2}(F_0 + F_N)$  we get

$$I_2 = 2\operatorname{Re}(I_1) \approx \sum_{r=-N}^{N-1} F_r \omega_N^{-rs} \Delta x,$$

as desired. If F is real and odd then

- $\operatorname{Re}(I_2) = 0$
- $\operatorname{Im}(I_2) = 2\operatorname{Im}(I_1)$ .

## Question 5

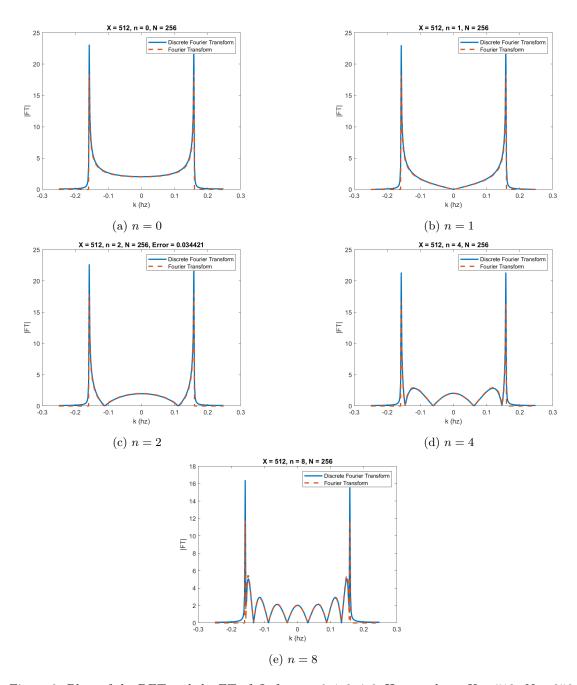


Figure 8: Plots of the DFT and the FT of  $J_n$  for n=0,1,2,4,8. Here we have  $X=512,\,N=256,\,\Delta x=1/2.$ 

The code for question 5 is included in the appendix.

We have chosen X so large in figure (8) because this allows us to resolve frequencies very precisely  $(\Delta k = 1/X)$ .

#### Discussion:

First of all, figures 9.1-9.5 show striking similarity between the FT and DFT. Both capture spikes at  $\pm 1/2\pi$ , which is consistent with the asymptotic form

$$J_n(x) \sim \sqrt{\frac{2}{\pi x}} \cos(x - \frac{n\pi}{2} - \frac{\pi}{4}).$$

At these points, our theoretical formula seems nearly singular, and our DFT replicates this behaviour well.

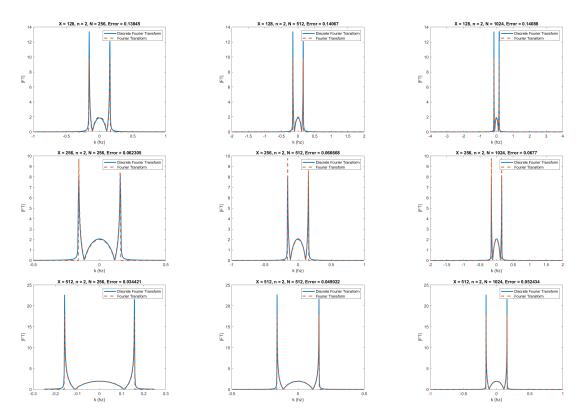


Figure 9: Variation of results for different values of N and X, all for n=2

We calculate the error by evaluating the FT and DFT at 0 and looking at their difference. Surprisingly, these errors are mostly independent of N but do seem to be decreasing as x increases. For a systematic variation of X and N, see figure (9) below.

N	4	8	16	32	64	128	256	512	1024	2048	4096
t	19.305	32.254	53.754	74.167	86.018	69.724	92.643	86.136	88.236	106.837	163.061

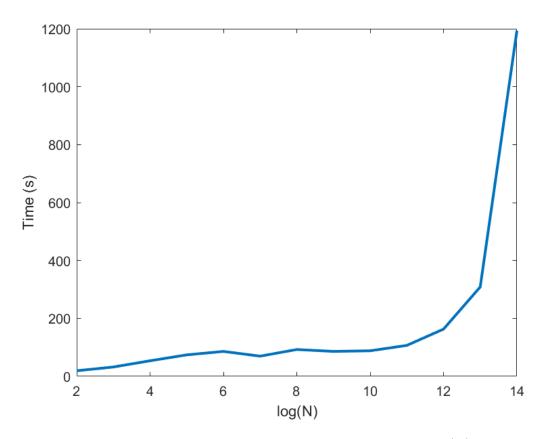


Figure 10: Complexity of program for different values of log(N).

### **Appendix**

```
function [d] = bes(y,x,n)
\% When we write Bessel's Equation down as a system of 1st order ODES we
% have: u = y, v = y. We then have eqns:
% u' = v
v' = ((n^2 - x^2)u - xv)/(x^2).
% In our scheme, y(1) = u, y(2) = v, x = x and order = n
% The vector d(x,y) = [u'(x), v'(x)] = [y'(x), y''(x)]
d = [y(2); ((n^2-x^2)*y(1)-x*y(2))/x^2];
end
function [] = solve(n,y0,LineSpec)
\% This function implements the ode45 ode solver to get solutions of
% Bessel's Equations.
% n = order of Bessel Equation
\% y0 = [u,v] where u = y(1), v = y'(1), for our numerical soln y
[t,y] = ode45(@(x,y) bes(y,x,n),1:0.01:100,y0); %Commencing forward integration
[s,z] = ode45(@(x,z) bes(z,x,n),1:-0.01:0.2,y0); %Commencing backward integration
p1 = plot(t,y(:,1),LineSpec);
                                    % plotting forwards soln
p2 = plot (s,z(:,1),LineSpec);
                                    % plotting backwards soln
\ell = 0.05 %legend([p1],{"x_0 = 1, y_0 = " + y0(1) + ", (dy/dx)_0 = " + y0(2)})
```

```
function [] = diff_ics(c,n,save)
% This script will help us numerically solve Bessel's Equation of order n
% for 3 diff ICS, y(x0) = c, y'(x0) = \{-1,0,1\}
% save = 0 or 1, if save = 1 then save images
hold on
            % This ensures all graphs displayed superimposed
solve(n,[c,1],'r')
solve(n,[c,0],'g')
solve(n,[c,-1],'b')
plot([0,100],[0,0],'k') % Plot x axis in black
xlabel('x')
ylabel('y')
title("Numerical Solutions for n = " + n + ", y_0 = " + c)
if save == 1
    saveas(gcf,"testy"+c+"n"+n+".png")
    clf
end
end
% Little script to print out and save all 9 possible images of diff ICs
for c = [-1, -0.5, 0, 0.5, 1]
    for n = [1]
        diff_ics(c,n)
    end
end
function [X,J] = series_soln(n,range,h,eps)
% This function truncates a sum of the series solution of Bessel's equation
\% of order n. The number of terms is chosen to ensure that within
% [0,range], the error is bounded by the input eps. Here h represents the
% resolution we want to view our domain in
N = floor(range/2)-2;
a = (0.5*range)^(2*(N+1)+n)/(factorial(N+1)*factorial(N+n+1));
while a > eps
    N = N+1;
    a = ((0.5*range))^(2*(N+1)+n)/(factorial(N+1)*factorial(N+n+1));
end
\% Next we compute the solution J
X = 0:h:range; % these are the x vals at which we evaluate our series soln
J = 0.*X;
                % initialising soln
k = 2;
                \% k will index the values of our solution J at X value X(k)
for i = h:h:range% i loops through all values in domain we wish to calculate
    for j = 0:N
                    % \ \ j adds each term in the series we wish to calculate
```

```
taylor_term = (-1)^(j)*(i/2)^(2*j+n)/(factorial(j)*factorial(n+j));
        J(k) = J(k) + taylor_term;
    end
k = k+1;
end
plot(X,besselj(n,X),X,J)
xlabel('x')
ylabel('y')
title("Series Solution plot for n = "+n+", X = "+range+", h = "+h+", epsilon = "+eps+".")
end
function [Y] = DFT(X,F,N)
% We take in a function F defined over a set [0, R] with very small
% stepsize. We then choose how many samples we want to take from this
\mbox{\ensuremath{\mbox{\%}}} interval, N. higher N corresponds to higher sampling freq.
\% This is NOT the code used for Question 5, but rather code used to get an
% intuition for results and develop plots for some of the figures generated
% NOTE: N must divide length(X)-1
A = zeros(N,N); % A will be our DFT matrix
omega_N = exp(2*pi*1i/N); % omega_N is the Nth root of unity
m = length(X);
step = (m-1)/N;
R = X(m); % R is what the notes call X
for j = 0:N-1 % Now we define matrix A
    for k = 0:N-1
        A(j+1,k+1) = (R/N)*omega_N^{(-j*k)};
    end
end
\% Next we take N evenly spaced samples from the vector F and compute its
% DFT Y.
U = X(1:step:m-step)'; % U is a column vector of our sampled x vals
V = F(1:step:m-step)'; % V is a column vector of our sampled y vals
Y = A*V;
L = floor(N/2);
B = zeros(N,N);
B(L+1:N,1:L) = eye(L);
B(1:L,L+1:N) = eye(L);
Y = B*Y;
```

```
% Next plot [0,1/X,2/X,...,(N-1)/X] and Y
freqs = (1/R).*(-L:L-1);
tiledlayout(1,2);
nexttile
hold on
plot(X,F);
scatter(U,V,40,'filled');
xlabel('x')
ylabel('y')
nexttile
hold on
bar(freqs,abs(Y),0.4);
xlabel('freq (hz)')
ylabel('|DFT|')
end
function [] = Q5_Code(X,n,N,save)
% X is the set of input values, will usually be some interval [0,R]
% n is the order of the Bessel Function
\mbox{\%} N is the number of samples we take. Needs to be even.
% if save == 1, we save the image
m = length(X); % This shorthand variable will come in handy later
F = besselj(n,X); % Bessel func of first kind, order n, evaluated at X
R = X(m); % R is what notes call X
% F = 3*\sin(X) + 4*\sin(2*X); % This is just here to test everything
x_step = floor(m/N); % this is not delta_x, but rather the number of entries
\% we have to skip when we are sampling F
V = F(1:x_step:m); % V is our sampled signal
V(1) = 0.5*(V(1)+V(N+1)); % Always need to do this as interval sym abt 0
V = V(1:N);
\% Next we will need to build the matrix to rearrange the DFT vector
B = zeros(N,N);
L = N/2;
B(L+1:N,1:L) = eye(L);
B(1:L,L+1:N) = eye(L);
ft_F = fft(V); % FT of F, evaluated at (-N/2X), (-N/2X + delta_k), ...
ft_F = B*(ft_F)'; % This cyclically permutes the vector N/2 steps forward
if mod(n,2) == 1
    ft_F = 2*imag(ft_F); % Since the domain of F is [-R,R], we have to do this
    ft_F = 2*real(ft_F); % Since the domain of F is [-R,R], we have to do this
end
```

```
ft_F = (R/N).*ft_F;
delta_k = 1/R; % Step size in freq domain
freqs = -(N/(2*R)):delta_k:(N-1)/(2*R); % Frequency domain
\% Next, we define T, the theoretical formula for the FT of J_n
T = 0.*freqs';
i = 1; %This will be our counter
for k = freqs
    if abs(k) >= 1/(2*pi)
        T(i) = 0;
    else
    T(i) = ((2*(-1i)^n)*(1-(2*pi*k)^2)^(-0.5))*chebyshevT(n,2*pi*k);
    end
    i = i+1;
end
plot(freqs,abs(ft_F),freqs,abs(T),'--');
xlabel('k (hz)')
ylabel('|FT|')
legend('Discrete Fourier Transform','Fourier Transform');
er_vec = abs(abs(T)-abs(ft_F));
error = er_vec(N/2 + 1); % This is Error at 0
title("X = "+ R +", n = "+n+", N = "+N+", Error = "+error);
if save == 1
    saveas(gcf,"X"+R+"n"+n+"N"+N+".png")
    clf
end
end
\% Little script to print out and save all 5 possible images of DFTS
for n = [0,1,2,4,8]
    Q5\_Code(X,n,N,1)
end
% Little script to print out and save all possible variations of fig 10
for N = [128, 256, 512, 1024]
    for R = [64, 128, 256.512]
        Q5_Code(0:1/16:R,2,N,1)
    end
end
```