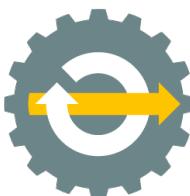

Python Exercise II: Audio denoising through FIR Wiener filtering

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Introduction and theoretical reference

In this exercise, we consider a radio frequency (RF) communication system consisting of an emitter and a receiver. Interference originating from the RF environment and from thermal noise of the system cause signal degradation at the receiver. Since the nature of these aberrations is stochastic, Wiener filtering can be used to subtract the effects of the distortion.

Consider the signal configuration displayed in Figure 1 (see also Figure 7.6 on page 145 of the reader).

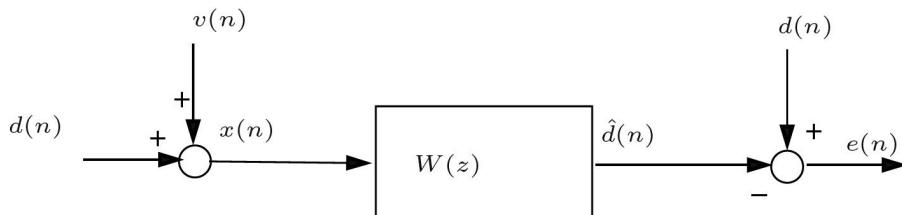


Figure 1: The problem configuration of the denoising problem.

In the configuration of Figure 1, all signals are discrete-time and real. The corrupted signal $x(n) = d(n) + v(n)$ contains both the signal of interest $d(n)$ and noise $v(n)$, which is uncorrelated to $d(n)$. In this assignment you will design a FIR filter $W(z)$, used to estimate the ground truth signal from $x(n)$ and from the statistical properties of the noise. That is, the filter $W(z)$ can be written as:

$$W(z) = w(0) + w(1)z^{-1} + \cdots + w(m-1)z^{-m+1} \quad (1)$$

such that using the measurable signals $x(n)$ and the additional information about the noise, the estimation of the ground truth signal can be obtained.

A thorough discussion of the denoising problem can be found in Subsection 7.3.3 of the reader [1].

Assignment description

Here, we will describe the assignment. As the COVID-measures prevent us from letting you record your own signals, we have done the experiment for you and provide you with the raw recordings. Therefore, we also provide you with the procedure we followed to record the signals.

To help you with reporting, you can use the provided Jupyter notebook as your report. We strongly encourage using the notebook, as hints are already provided for you. After you have answered the questions and are finished with the assignment, you can export the Jupyter notebook as a PDF (File > Download as > LaTeX or PDF).

Preparation

Make sure that the files `Audio.py`, `Communication.py` and `denoising-scheme.jpg`, as well as the recorded signals `gong_5cm.mat`, `gong_100cm.mat`, `gong_250cm.mat` and `noise.mat` are included in the same directory as the Jupyter notebook or your own code.

Install the following modules to your python using pip:

1. `pyserial`
2. `sounddevice`
3. `scipy`

For that you can use usual command prompt (in Windows use Start button – > "cmd") or if you use Anaconda, "Anaconda prompt". The full command for installing a python package is

```
pip install package_name
```

Obtaining the data

In this section, the transmission experiment from the introduction is described. As the COVID-measures prevent us from letting you record your own signals, we have done the experiment for you and we provide you with the raw recordings. Here, we describe the experimental setup that we used to record the signals. The experimental setup is shown in Figure 2.

For this experiment, two Arduino MK1000's are used. These Arduino microcontrollers are able to send and receive signals through radio frequency (RF) wireless transmission. As such, the first microcontroller is configured as a sender, used to send a wav-file `gong.wav`. The second microcontroller is configured as a receiver and it is linked to the sender. By simultaneously activating both microcontrollers, the receiver will record the signal sent by the sender.

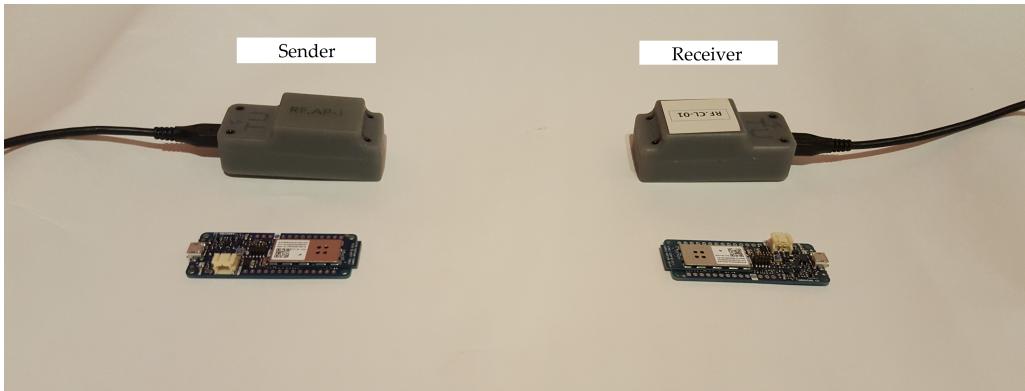


Figure 2: Experimental setup to send and receive sounds. The Arduino MK1000 microcontrollers are contained in the grey boxes.

However, the signal transmission is affected by RF noise. Examples of sources of this noise are disturbances in the RF band, distance-dependent noise caused by the distance between the microcontrollers and thermal distortion of the signal. These noise sources act additively on the sent signal `gong.wav`. For distances of 5 cm, 100 cm and 250 cm between the microcontrollers, we recorded `gong_5cm.mat`, `gong_100cm.mat` and `gong_250cm.mat` respectively, which you can listen to later in this assignment.

To filter the noise from the signal using denoising, we also need a recording of the noise for every distance of 5 cm, 100 cm and 250 cm between the microcontrollers. The total noise has a complicated spectrum, so to save you some mathematical work we solely focus on ambient, distance-independent noise. This noise is assumed to be zero-mean and white, and a measurement of this noise is contained in `noise.mat`.

NB. The recorded values in `gong_5cm.mat`, `gong_100cm.mat`, `gong_250cm.mat` and `noise.mat` are expressed in decibels relative to full scale (dB-FS), which is a unit used to express signal amplitudes in digital systems.

With these signals, you have enough information to calculate the weights of a FIR Wiener filter. This assignment will guide you through this process. A snippet of code is provided to you in the Jupyter notebook, which will help you with importing the signals.

Deliverables

You are required to hand-in a report, showing your results and answering the questions about this exercise. Python scripts should be included as text in your report.

To help you with reporting, we provided a Jupyter notebook on Brightspace, which you can use as your report. We strongly encourage using the notebook, as hints and code snippets are already provided for you. After you have answered the questions and are finished with the assignment, you can export the Jupyter notebook as a PDF (instructions on how to do so are included in the notebook).

The report or exported Jupyter notebook should be dated and handed in before the deadline (see Course Schedule on Brightspace). The report should be handed in digitally by only one group member, but make sure the names and student numbers of all group members are included in the report or exported Jupyter notebook.

Bibliography

- [1] M. Verhaegen, *Stochastic Processes for Physics Students: An Introduction*, Feb. 2017
- [2] M. Hayes, *Statistical Digital Signal Processing and Modeling*, John Wiley & Sons, New York, 1996.