

INFO251 – Applied Machine Learning

Lab 12
Emily Aiken

Announcements

- **PS7** due Monday May 2
 - **Quiz 2** on Thursday, April 28
 - **Let us know via email or piazza if you have a DSP accommodation or time conflict**
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Agenda

- Topics covered in AML
 - ML algorithms “cheat sheet”
 - Practice quiz questions
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Topics covered in AML

1. Causal inference

- Linear regression
- Fixed effects and panel data
- Instrumental variables
- Regression discontinuity

2. Supervised Learning, Part 1

- K-nearest neighbors
- Linear regression
- Logistic regression
- Ridge and LASSO
- Support vector machines

3. Optimization and Loss Functions

- Mean squared error
- Logistic loss
- Hinge (RELU) loss
- Cross entropy loss
- Gradient descent

4. Supervised Learning, Part 2

- Naïve Bayes
- Decision Trees
- Random Forests
- Gradient Boosting

5. Neural Networks

- Perceptron
- Fully Connected Networks
- Autoencoders
- Convolutional Neural Networks
- Recurrent Neural Networks

6. Fairness

- Independence, sufficiency, separation
- Protected attributes and privilege
- p% rule
- Thresholding
- Fairness constrained classification

7. Unsupervised Learning

- K-means clustering
- Hierarchical clustering
- Dimensionality reduction
- Principal components analysis

8. Practical ML

- Train-test splits
- Cross validation
- Imputation
- Normalization
- Standardization
- Feature engineering
- Imbalanced data
- Regularization
- Overfitting
- Bias-variance trade-off
- Interpretability

Python programming tools covered in AML

Tool	Purpose
<code>numpy</code>	Coding up algorithms, vectorized computation
<code>pandas</code>	Storing real-world tabular data
<code>matplotlib</code> , <code>seaborn</code>	Visualization
<code>statsmodels</code>	Linear regression for causal inference
<code>scikit-learn</code>	Supervised and unsupervised learning pipelines
<code>xgboost</code> , <code>catboost</code> , <code>lightgbm</code>	Gradient boosting models
<code>keras</code> and <code>tensorflow</code>	Neural networks

ML Algorithms Summary: Linear Models

Algorithm	Applications	Hyperparameters	Description	Pros	Cons
Linear Regression	Regression	--	Prediction for observation is linear combination of features, weights determined via optimization (gradient descent).	<ul style="list-style-type: none">• Directly interpretable coefficients• Closed form solution• Scalable	<ul style="list-style-type: none">• Overly simplistic model• Cannot learn nonlinear decision boundaries• Overfitting
LASSO/Ridge Regression	Regression	<ul style="list-style-type: none">• Regularization (L1 or L2)• Regularization strength (lambda)	Regularized linear regression, penalizing size of weight vector	<ul style="list-style-type: none">• Reduces overfitting• Optimal regularization determined through cross validation• Feature selection (Ridge only)	<ul style="list-style-type: none">• Cannot learn nonlinear decision boundaries
Logistic Regression	Classification	<ul style="list-style-type: none">• Regularization (L1 or L2)• Regularization strength (lambda)	Regression optimizing logistic loss to produce calibrated class probabilities	<ul style="list-style-type: none">• Directly interpretable coefficients• Scalable• Option to add regularization	<ul style="list-style-type: none">• Cannot learn nonlinear decision boundaries
Support Vector Machines	Classification	<ul style="list-style-type: none">• Regularization strength (C)	Maximize margin around separating hyperplane, with penalties for misclassification	<ul style="list-style-type: none">• Easy to regularize• Works with kernels	<ul style="list-style-type: none">• Performs badly when data not linearly separable• Linear decision boundary only• No class probabilities

ML Algorithms Summary: Nonlinear Models

Algorithm	Applications	Hyperparameters	Description	Pros	Cons
K-Nearest Neighbors	Regression, Classification	<ul style="list-style-type: none">Neighbors (K)Distance metric	Prediction for observation is average of target value for K closest observations in training set.	<ul style="list-style-type: none">Simple, intuitive, interpretableNo training required	<ul style="list-style-type: none">SlowMust choose a good distance metric
Naïve Bayes	Classification, text data	<ul style="list-style-type: none">Additive smoothing parameter	MAP estimate for most likely class given the data (features)	<ul style="list-style-type: none">Generative modelEasy, parallelizable estimation	<ul style="list-style-type: none">Conditional independence assumption violated
Decision Trees	Regression, Classification	<ul style="list-style-type: none">Maximum depthMinimum samples in leaves	Recursively grow a tree splitting on a feature value at each node	<ul style="list-style-type: none">Can learn nonlinear decision boundariesMost interpretable model	<ul style="list-style-type: none">Simple, underfitting model
Random Forests	Regression, Classification	<ul style="list-style-type: none">Maximum depthMinimum samples in leavesNumber of trees	Ensemble method aggregating multiple trees via averaging (regression) or voting (classification)	<ul style="list-style-type: none">Can learn highly nonlinear decision boundariesCan cross validate a number of parametersParallelizable	<ul style="list-style-type: none">Difficult to interpret
Gradient Boosting	Regression, Classification	<ul style="list-style-type: none">All of aboveLearning rate	Ensemble method where trees built sequentially based on where previous trees performed badly	<ul style="list-style-type: none">Can learn highly nonlinear decision boundariesTypically more accurate than random forests	<ul style="list-style-type: none">Difficult to interpretLess parallelizable

ML Algorithms Summary: Neural Networks

Algorithm	Applications	Hyperparameters	Description	Pros	Cons
Fully Connected Neural Network	Tabular data	<ul style="list-style-type: none">• Number of hidden layers• Number of nodes in hidden layers• Activation functions• Regularization/dropout	All nodes in layer of network connected to all nodes in next layer.	<ul style="list-style-type: none">• Faster to train (than more complex network)• Work well for tabular data	<ul style="list-style-type: none">• Expensive to train• Must choose a good distance metric• Overfitting risk
Convolutional Neural Network	Image data, graph data	<ul style="list-style-type: none">• Filter size and stride• Pooling• Number of fully connected layers at the end• Regularization/dropout	Convolutional layers use matrix multiplication to learn spatial dependencies, pooling layers reduce image size/complexity.	<ul style="list-style-type: none">• Very good at learning dependencies in spatial data	<ul style="list-style-type: none">• Expensive to train• Overfitting risk
Recurrent Neural Network	Time series data, text data	<ul style="list-style-type: none">• Network structure (RNN, LSTM, GRU)• Regularization	Recurrent connections allow information to be passed from one input to the next	<ul style="list-style-type: none">• Very good at learning temporal dependencies	<ul style="list-style-type: none">• Long-term dependencies lost in standard RNNs
Autoencoder	Reconstruction	<ul style="list-style-type: none">• Number of nodes in hidden layer (degree of dimensionality reduction)• Activation functions	By training to predict the input, outputs of hidden layer are lower dimensional embedding of input	<ul style="list-style-type: none">• Learn lower dimensional embedding of data	<ul style="list-style-type: none">• Expensive compared to other dimensionality reduction techniques (PCA)

ML Algorithms Summary: Unsupervised Methods

Algorithm	Applications	Hyperparameters	Description	Pros	Cons
K-means clustering	Unsupervised Learning (Clustering)	<ul style="list-style-type: none">Distance metricNumber of clusters	Assign cluster centers randomly. Then, repeat until converged: assign all observations to closest cluster center, assign cluster centers as mean of observations in cluster.	<ul style="list-style-type: none">Guaranteed to convergeIntuitive	<ul style="list-style-type: none">Spherical clustersAll observations assigned to single clusterNot always clear how to pick number of clustersSensitive to random seed
Hierarchical Clustering	Unsupervised Learning (Clustering)	<ul style="list-style-type: none">Distance metricLinkage function	Agglomerative clustering starts with all observations in single clusters and links nearby clusters recursively, divisive clustering starts with all observations in single cluster and splits clusters recursively.	<ul style="list-style-type: none">Doesn't require number of clusters (k)	<ul style="list-style-type: none">Expensive to computeSensitive to linkage functionSensitive to random seed
Principal Components Analysis	Unsupervised Learning (Dimensionality Reduction)	<ul style="list-style-type: none">Number of components	Project data into lower dimensional subspace defined by principal components, where components maximize variation explained from original data and are all orthogonal.	<ul style="list-style-type: none">Very computationally efficientCan reduce overfitting for supervised learning	<ul style="list-style-type: none">Information may be lost in lower dimensional embedding (check variance explained)Components not interpretable

Practice Quiz Question 1

Linear regression

Using the Boston Housing dataset, you run a linear regression to predict the median house value of a neighborhood based on whether it is adjacent to the Charles river (RIV) and the crime rate (CRIM). The results are at right. Which of the following are true?

	Coefficient	95% confidence interval
Intercept	35	[33.6, 37.2]
RIV	9.7	[7.6, 10.8]
CRIM	-1.3	[-3.7, 0.2]

- (A) An area far from the Charles with no crime would have an expected median housing value of \$35
 - (B) For a 1% increase in the crime rate, there is a 1.3% decrease in housing value on average
 - (C) Being next to the Charles river increases housing value by \$9.7 on average
 - (D) Both crime rate and adjacency to the Charles river are significant predictors at a 0.05 level
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Practice Quiz Question 2

ROC curve

Which of the following are true about the receiver operating characteristic (ROC) curve? Check all that apply.

- (A) The ROC curve traces the trade-off between the false positive rate and true positive rate of a classifier, depending on the classification threshold
 - (B) One way to calibrate the optimal point on the curve is finding the point closest to the upper left hand corner
 - (C) The maximum value for the area under the curve score is 0.5
 - (D) A random classifier achieves an area under the curve score of 0.5
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Practice Quiz Question 3

Computational complexity

Rank the following models from least to most expensive computation in the training phase: k nearest neighbors, LASSO regression, naïve bayes, random forest, neural network

- (A) LASSO regression < naïve bayes < k nearest neighbors < NN < random forest
 - (B) Naïve bayes < k nearest neighbors < random forest < LASSO regression < NN
 - (C) K nearest neighbors < naïve bayes < LASSO regression < random forest < NN
 - (D) K nearest neighbors < LASSO regression < NN < random forest < naïve bayes
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Practice Quiz Question 4

Fairness

Which of the following strategies can help ameliorate bias in machine learning classifiers? Check all that apply.

- (A) “Fairness through awareness”
 - (B) Alternative classification boundaries for protected classes
 - (C) Leaving protected features out of the training data
 - (D) Fairness constrained classification
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Practice Quiz Question 4

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Practice Quiz Question 5

Random forests

A random forest is an example of which type of ensemble learning method?

- (A) Bagging
 - (B) Boosting
 - (C) Voting
 - (D) Stacking
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Practice Quiz Question 6

Clustering

Which of the following are requirements for a clustering distance metric? Check all that apply.

- (A) Symmetric
 - (B) Non-negative
 - (C) Convex
 - (D) Satisfies Fisher's inequality
 - (E) Satisfies triangle inequality
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Practice Quiz Question 7

$$DB = \frac{1}{n} \sum_{i=1}^n \max_{i \neq j} \left(\frac{\sigma_i + \sigma_j}{d(c_i, c_j)} \right)$$

Davies-Bouldin

Recall the Davies-Bouldin index, at right. Which of the following are true about the Davies-Bouldin index?

- (A) It is used to choose the optimal number of clusters in k-means clustering.
 - (B) It takes into account both the distance between clusters and the distance within clusters.
 - (C) The goal is to maximize the metric.
 - (D) It is monotonically decreasing with the number of clusters.
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Practice Quiz Question 8

Convolutional neural networks

*Which of the following is true about pooling layers in convolutional neural networks?
Check all that apply.*

- (A) The most common pooling aggregations are minimum, mean, and maximum
 - (B) Pooling reduces the dimensionality of the data and network
 - (C) Pooling helps reduce overfitting
 - (D) The most common pooling kernel is 2x2 with a stride width of 2
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Practice Quiz Question 8

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Practice Quiz Question 9

Decision trees

True or false: A decision tree can learn a nonlinear decision boundary.

(A) True

(B) False

Practice Quiz Question 9

Decision trees

True or false: A decision tree can learn a nonlinear decision boundary.

- ☒ (A) True
 - ☐ (B) False
-

Practice Quiz Question 10

Regularization

*Which of the following is an example of regularization in a machine learning model?
Check all that apply.*

- (A) Ridge regression
 - (B) LASSO regression
 - (C) Decision tree pruning
 - (D) Dropout layers and sparse neural networks
 - (E) Principal components analysis
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Practice Quiz Question 10

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