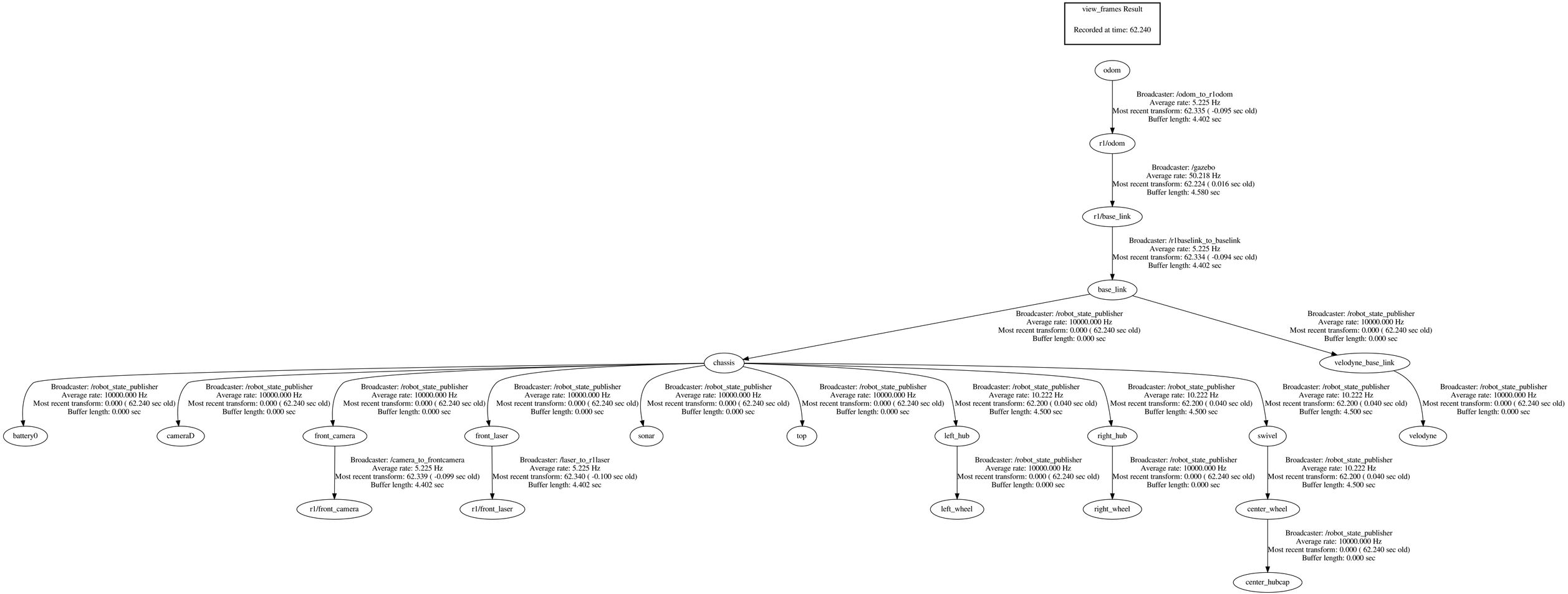
view_frames Result
Recorded at time: 62.240
odom
Broadcaster: /odom_to_r1odom
Average rate: 5.225 Hz
Most recent transform: 62.335 (-0.095 sec old)
Buffer length: 4.402 sec
r1/odom
Broadcaster: /gazebo
Average rate: 50.218 Hz
Most recent transform: 62.224 (0.016 sec old)
Buffer length: 4.580 sec
r1/base_link
Broadcaster: /r1baselink_to_baselink
Average rate: 5.225 Hz
Most recent transform: 62.334 (-0.094 sec old)
Buffer length: 4.402 sec
base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
chassis
velodyne_base_link
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
battery0
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
cameraD
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
front_camera
Broadcaster: /camera_to_frontcamera
Average rate: 5.225 Hz
Most recent transform: 62.339 (-0.099 sec old)
Buffer length: 4.402 sec
r1/front_camera
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
front_laser
Broadcaster: /laser_to_r1laser
Average rate: 5.225 Hz
Most recent transform: 62.340 (-0.100 sec old)
Buffer length: 4.402 sec
r1/front_laser
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
sonar
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
top
Broadcaster: /robot_state_publisher
Average rate: 10.222 Hz
Most recent transform: 62.200 (0.040 sec old)
Buffer length: 4.500 sec
left_hub
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
left_wheel
Broadcaster: /robot_state_publisher
Average rate: 10.222 Hz
Most recent transform: 62.200 (0.040 sec old)
Buffer length: 4.500 sec
right_hub
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
right_wheel
Broadcaster: /robot_state_publisher
Average rate: 10.222 Hz
Most recent transform: 62.200 (0.040 sec old)
Buffer length: 4.500 sec
swivel
Broadcaster: /robot_state_publisher
Average rate: 10.222 Hz
Most recent transform: 62.200 (0.040 sec old)
Buffer length: 4.500 sec
center_wheel
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
center_hubcap
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (62.240 sec old)
Buffer length: 0.000 sec
velodyne