Dhok)= 1 = 0x = the Hypothesis which generates if (predictions) D cost frakon: n jilog (h (x)) + (1-yi)/(log(1-ha(xi))) D Gradient update role:

Oj = 0 - x Z (ho(x'i)) - y'i) x'j DUECTORIZATION OF COST: $\frac{1}{2} \left(\frac{1}{2} \cdot \frac{1}{2} \left(\frac{1}{2} \left($ D VECTORIZATION OF GRASIENT O= 1 X' Sigmoid (XO) => 0 = 12 1/2m EMMX1 D (Kotting decision boundary décision boundasy defil ed as signald(0) I Argument of Graphod for must be 0'

E) hg(x) = 0, x, + 0, x, + 0, x, = 0 (5) x3 = - \frac{0.x + 0, x}{3}. Ly hok)= P, x, + Ozxz +Ozxz = v as 3 - cool x eg: $pld_x = [mh(x_2), max(x_2)]$ (x-coolds of plat) = Directly - coords now; P_{2} = $\left(\frac{-1}{2} \times \left[\frac{1}{2} \times \frac{1}{2} + \times_{2} \frac{1}{2}\right]\right)$ the plat (plat_x, plat_y)

Coole for creating higher order Polynomals Transform X $\begin{bmatrix} x_1^4 x_2^2 \\ \vdots \\ \vdots \\ \vdots \end{bmatrix} = 0 \quad \begin{bmatrix} x_1^2 x_1^2 x_1^3 x_2^4 \\ \vdots \\ \vdots \\ \vdots \\ \vdots \end{bmatrix}$ where $x^{(i)}$ for is represents another polynomial $(eg(x^2)^2(x^2)^2)$, degree = 6; out = ones(87e(X(:,1)) -0[100-D/m] for 1 = 1; degree (es) = 0: i and (:, end+1) = (X1(1-j) * Xj) 3. Step out = (X13-2 · X22) = D X1 x2 [REGULARIZED LOG REG] Intercept Remembes to exclude On in the D cost func J(O) = 1 7 [y (bo(x)) - (1-y) (log (1-ho(x))] +2 2 92 D Gradient