Eli Whitaker

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Objective

Motivated UCLA Mechanical Engineering student with a 4.00 GPA and strong background in robotics, coding, and circuit analysis. Seeking hands-on experience to apply my skills in mechanical design, autonomous systems, and control systems to to solve hands-on engineering challenges in robotics and automation.

Education

• University of California, Los Angeles (Cumulative GPA: 4.00)

Bachelor of Science in Mechanical Engineering,

Expected Graduation: June 2026

On track for Summa Cum Laude honors

• Cordova High School, Rancho Cordova

International Baccalaureate Diploma

Graduated: June 2022

Relevant Work and Volunteer Experience

• Structures-Computer Interaction Lab, Undergraduate Research (Summer 2025-Present)

Assisting in the development of an autonomous laser-based weeding system for agricultural automation

- UCLA Recreation, Fitwell Consultant (Summer 2025-Present)

 Managed equipment maintenance tickets, demonstrating organizational skills and facility systems awareness
- Casa Roble High School, Tutoring (Summer 2023)
 Volunteered in AP Calculus & Integrated Math, providing in-class tutoring

Technical Skills

- Engineering Tools: Solidworks, MATLAB, C++, Python, Next.js
- Robotics & Control Systems: Dynamics, Systems Analysis, ROS2

Relevant Coursework

- Statics & Strength of Materials (MECH&AE 101)
- Dynamic Systems (MECH&AE 107)
- Computer-Aided Design and Drafting (MECH&AE 94)
- Kinematic/Dynamics of Robot Systems (MECH&AE C163A/B)

Personal Projects

Catcher Arm

• A planar 2-R manipulator that autonomously intercepts airborne ping-pong balls within a 0.30 m x 0.30 m workspace. Using ROS2, we utilized computer vision, encoder data, and manipulator dynamics theory to create four controllers, three of which involved centralized control.

Custom Instrument Attachment

 Designed and 3D printed a ukulele-mounted accessory using caliper-based contour measurements and SolidWorks modeling.

Awards

• **Dean's Honor List**: Multiple quarters for high academic performance