



Scalable Quantum Control with Semi-Automatic Differentiation

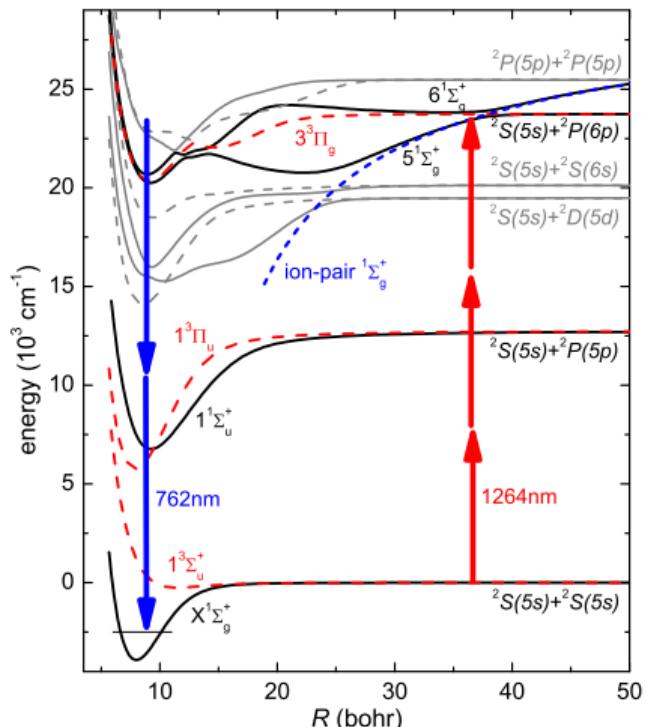
Michael H. Goerz, Sebastián C. Carrasco, Vladimir S. Malinovsky

DEVCOM Army Research Lab

CQE Workshop on Scalable Quantum Control

August 15, 2022

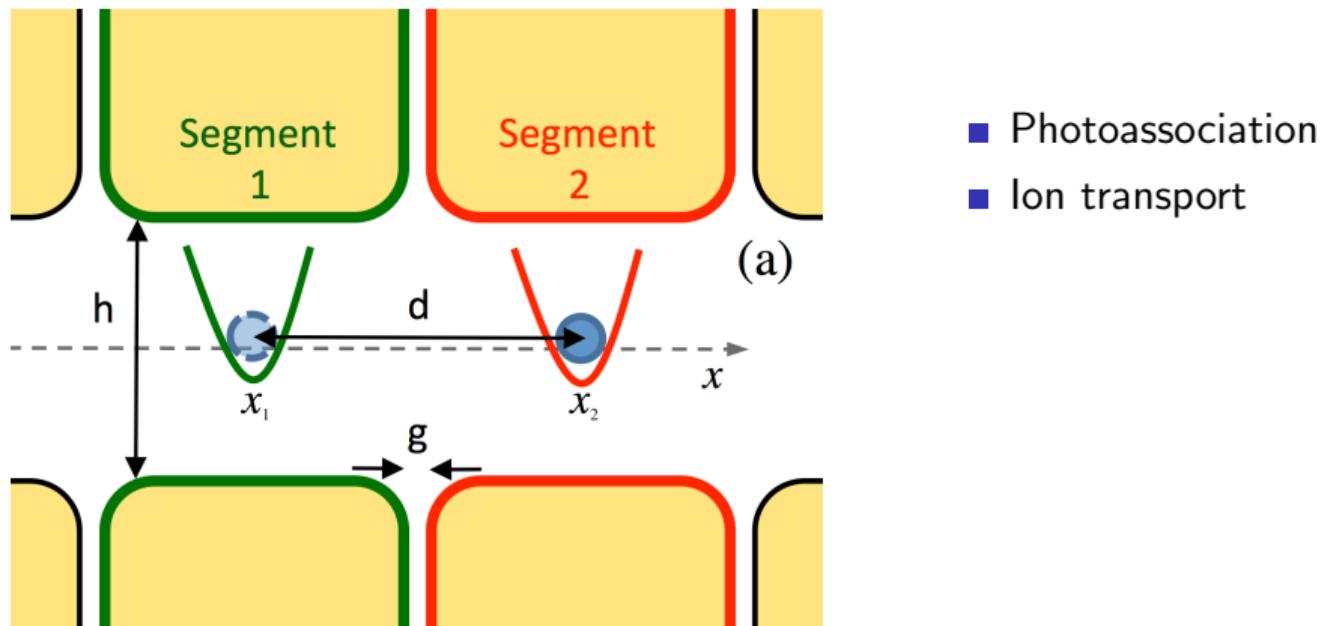
Optimal Control Tasks



■ Photoassociation

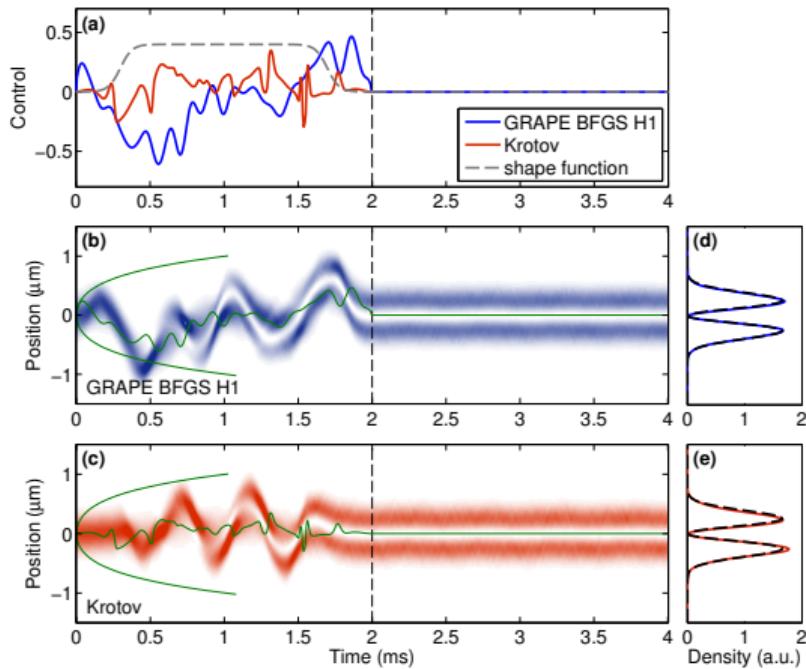
Tomza et al. Phys. Rev. A 86, 043424 (2012)

Optimal Control Tasks



Fürst et al. New J. Phys. 16, 075007 (2014)

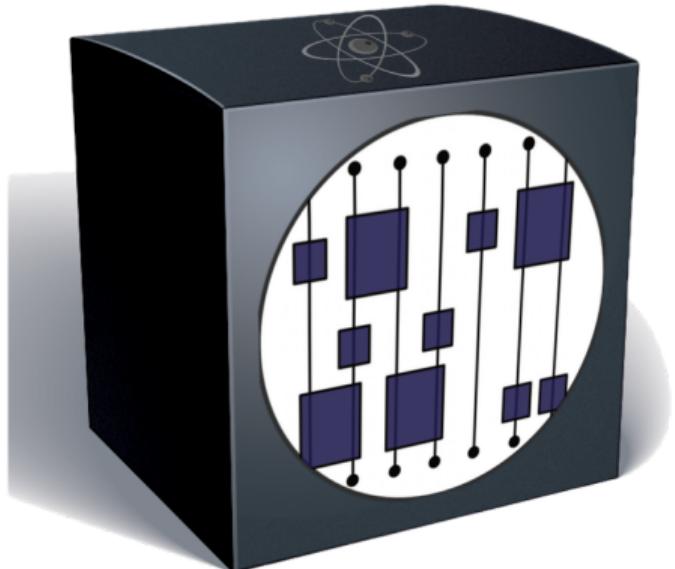
Optimal Control Tasks



- Photoassociation
- Ion transport
- BEC wave function splitting

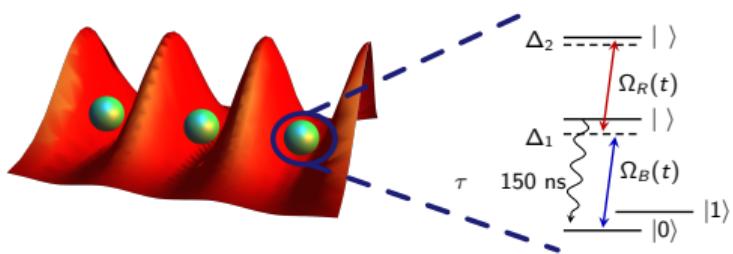
Jäger et al. Phys. Rev. A 90, 033628 (2014)

Optimal Control Tasks



- Photoassociation
- Ion transport
- BEC wave function splitting
- Quantum gates

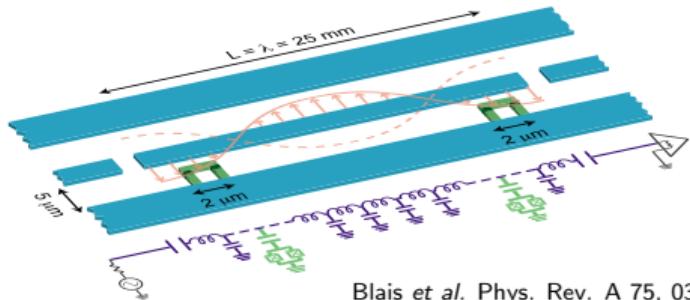
Optimal Control Tasks



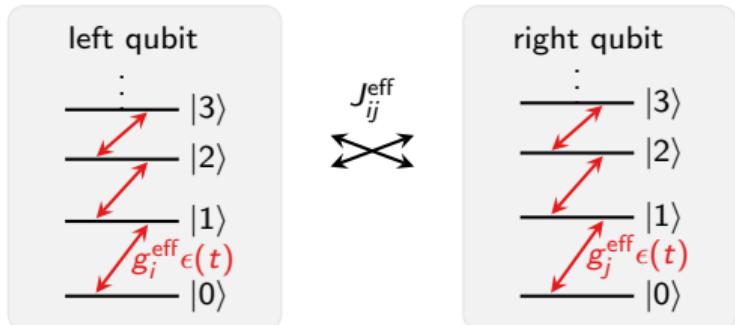
- Photoassociation
- Ion transport
- BEC wave function splitting
- Quantum gates
 - Rydberg atoms

Goerz *et al.* Phys. Rev. A 90, 032329 (2014)

Optimal Control Tasks



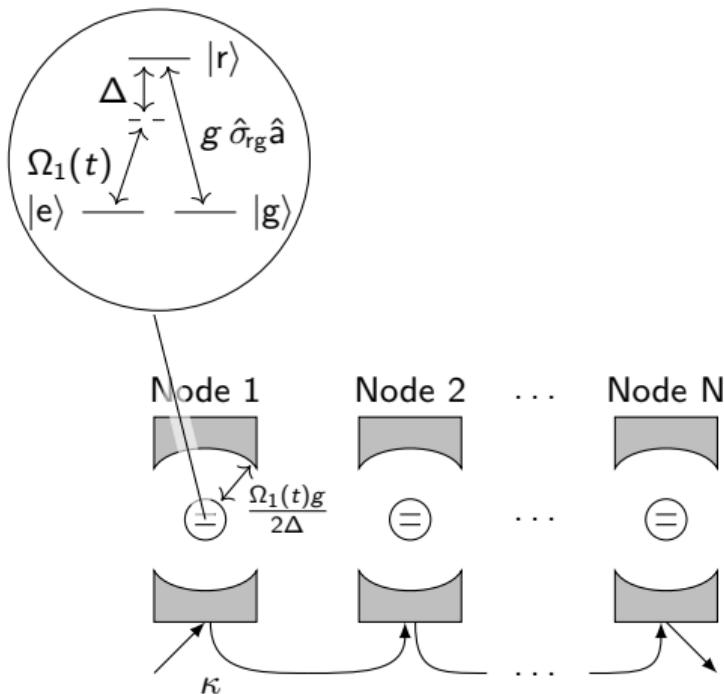
- Photoassociation
- Ion transport
- BEC wave function splitting
- Quantum gates
 - Rydberg atoms
 - Superconducting qubits



Goerz *et al.* EPJ Quantum Tech. 2, 21 (2015)

Goerz *et al.* npj Quantum Information 3, 37 (2017)

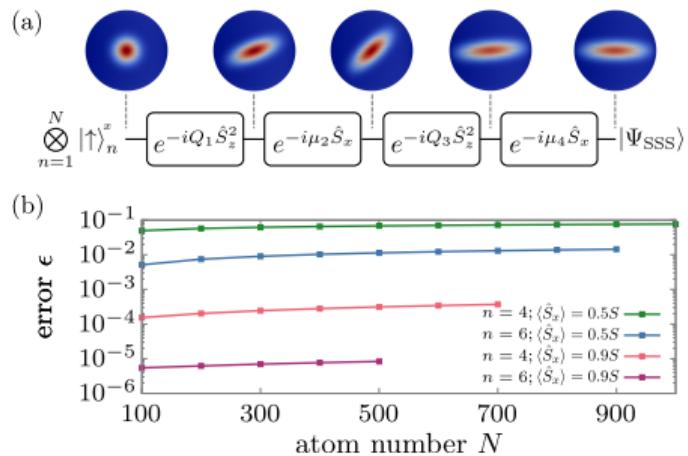
Optimal Control Tasks



- Photoassociation
- Ion transport
- BEC wave function splitting
- Quantum gates
 - Rydberg atoms
 - Superconducting qubits
- Entanglement in quantum networks

Goerz, Jacobs. Qu. Sci. Technol. 3, 045005 (2018)

Optimal Control Tasks



- Photoassociation
- Ion transport
- BEC wave function splitting
- Quantum gates
 - Rydberg atoms
 - Superconducting qubits
- Entanglement in quantum networks
- Spin-squeezed states

Carrasco *et al.*, Phys. Rev. Applied 17, 064050 (2022)

Quantum Control Problem

“Pulse-level” control

- Bunch of states: $\{|\Psi_k(t)\rangle\}$
 - e.g. two-qubit gate: $|00\rangle, |01\rangle, |10\rangle, |11\rangle$
- Hamiltonian(s) with control fields: $\hat{H}_k(\{\epsilon_l(t)\}) \rightarrow$ time propagation
 - assume piecewise-constant: ϵ_{ln} for n 'th time interval of l 'th control

Functional

$$J(\{\epsilon_{nl}\}) = J_T(\{|\Psi_k(T)\rangle\}) + \int_0^T g_a(\{\epsilon_l(t)\}, t) dt + \int_0^T g_b(\{|\Psi_k(t)\rangle\}, t) dt$$

Gradient-based “open loop” optimization

$$(\nabla J)_{ln} \equiv \frac{\partial J}{\partial \epsilon_{ln}} \quad \Rightarrow \quad \text{L-BFGS-B}$$

Scalability

Driving cutting-edge quantum technology with optimal control?

- Bigger (open) systems — hard numerics
- More flexibility — better functionals, novel methods

Efficient Quantum Control

1984

An accurate and efficient scheme for propagating the time dependent Schrödinger equation

1986

Coherent pulse sequence induced control of selectivity of reactions:
Exact quantum mechanical calculations

1988

J. Phys. Chem. 1988, 92, 2087–2100

2087

Time-Dependent Quantum-Mechanical Methods for Molecular Dynamics

1992

J. Phys. A: Math. Gen. 25 (1992) 1283–1307. Printed in the UK

Solution of the time-dependent Liouville–von Neumann

1994

Annu. Rev. Phys. Chem. 1994, 45: 145–78
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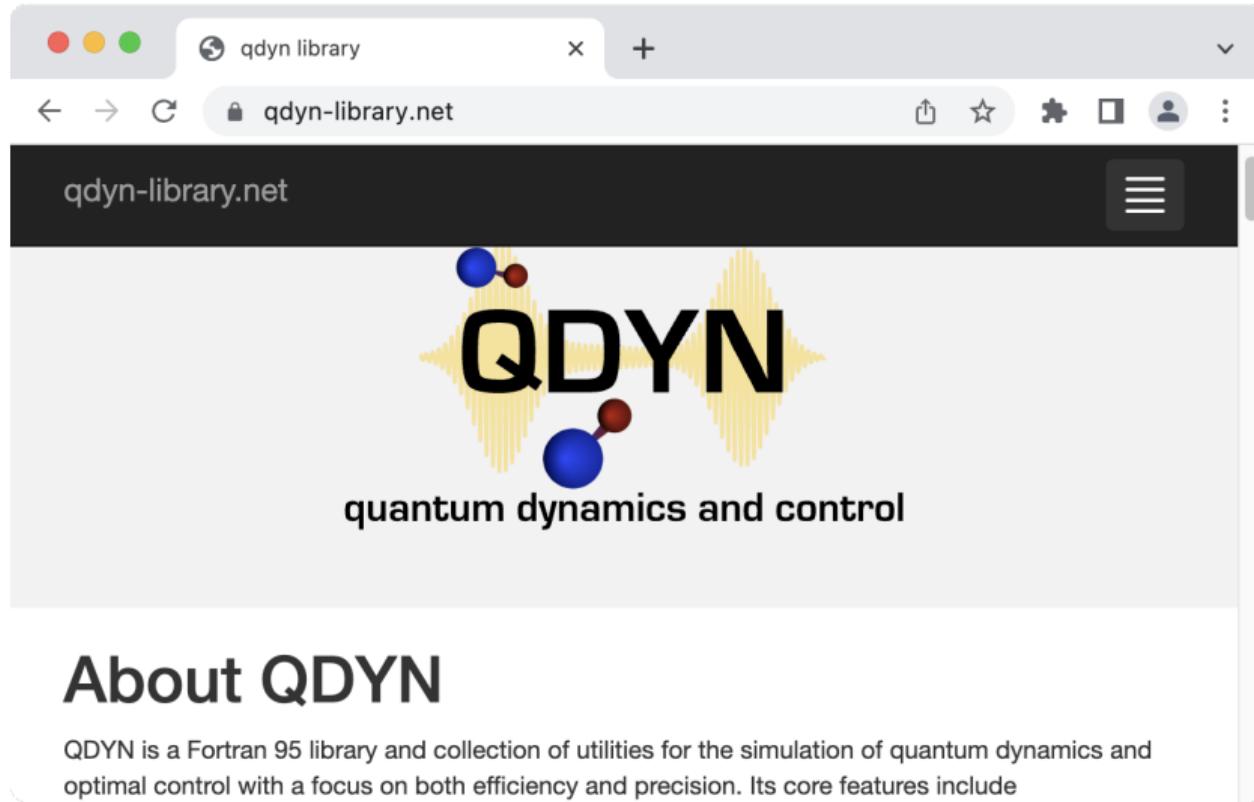
PROPAGATION METHODS FOR
QUANTUM MOLECULAR
DYNAMICS

Ronnie Kosloff

Efficient Quantum Control

- Get your data structures right
 - grid representation (FFT), sparsity
- Get your propagation right
 - polynomial expansions, in-place BLAS
- Set up simultaneous “objectives” via states
 - parallelization

QDYN



qdyn library

qdyn-library.net

qdyn-library.net

qdyn-library.net

QDYN

quantum dynamics and control

About QDYN

QDYN is a Fortran 95 library and collection of utilities for the simulation of quantum dynamics and optimal control with a focus on both efficiency and precision. Its core features include



C. Koch group
FU Berlin



Fortran

Scalability

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Automatic Differentiation (AD)

PHYSICAL REVIEW A **95**, 042318 (2017)

Speedup for quantum optimal control from automatic differentiation based on graphics processing units

Nelson Leung,^{1,*} Mohamed Abdelhafez,¹ Jens Koch,² and David Schuster¹

PHYSICAL REVIEW A **99**, 052327 (2019)

Gradient-based optimal control of open quantum systems using quantum trajectories and automatic differentiation

Mohamed Abdelhafez,^{1,*} David I. Schuster,¹ and Jens Koch²

PHYSICAL REVIEW A **101**, 022321 (2020)

Universal gates for protected superconducting qubits using optimal control

Mohamed Abdelhafez^①, Brian Baker^②, András Gyenis^③, Pranav Mundada^③, Andrew A. Houck,^③ David Schuster,¹ and Jens Koch²

Automatic Differentiation (AD)

backward-mode “adjoint”

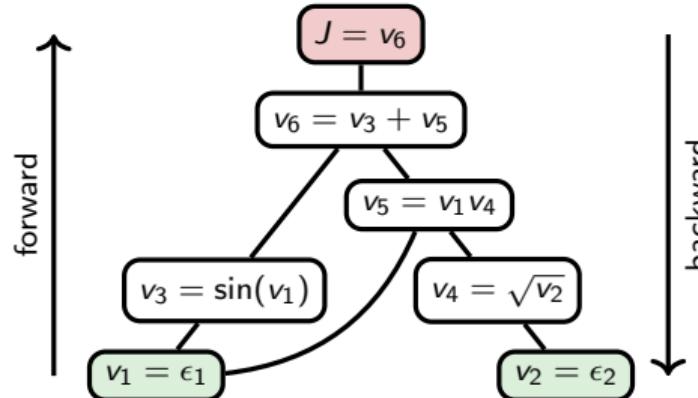
$$\bar{v}_j \equiv \frac{\partial J}{\partial v_j}$$

$$= \sum_i \bar{v}_i \frac{\partial v_i}{\partial v_j}$$

sum over all v_i

which depend on v_j

$$J(\epsilon_1, \epsilon_2) = \sin(\epsilon_1) + \epsilon_1 \sqrt{\epsilon_2}$$



Automatic Differentiation (AD)

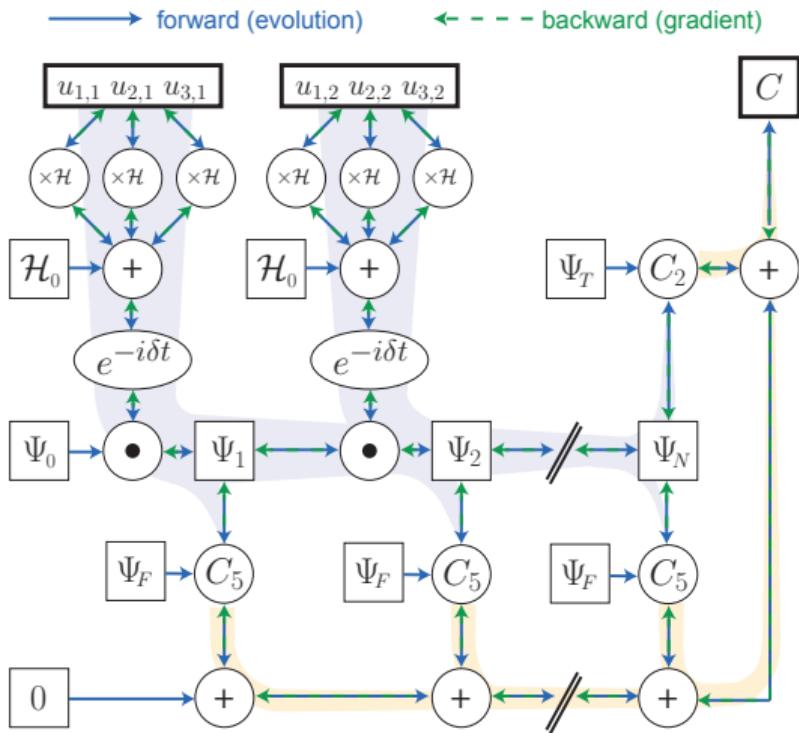


Fig. 2 in Leung *et al.* Phys. Rev. A 95, 042318 (2017)

AD Advantages

- Arbitrary functionals

μ	Cost-function contribution	$C_\mu(\mathbf{u})$
1	Target-gate infidelity	$1 - \text{tr}(K_T^\dagger K_N)/D ^2$
2	Target-state infidelity	$1 - \langle \Psi_T \Psi_N \rangle ^2$
3	Control amplitudes	$ \mathbf{u} ^2$
4	Control variations	$\sum_{j,k} u_{k,j} - u_{k,j-1} ^2$
5	Occupation of forbidden state	$\sum_j \langle \Psi_F \Psi_j \rangle ^2$
6	Evolution time (target gate)	$1 - \frac{1}{N} \sum_j \text{tr}(K_T^\dagger K_j)/D ^2$
7	Evolution time (target state)	$1 - \frac{1}{N} \sum_j \langle \Psi_T \Psi_j \rangle ^2$

Table 1 in Leung *et al.* Phys. Rev. A 95, 042318 (2017)

- Arbitrary equations of motion

e.g., quantum trajectories — Abdelhafez *et al.* Phys. Rev. A 99, 052327 (2019)

- GPU support

Entanglement Measures

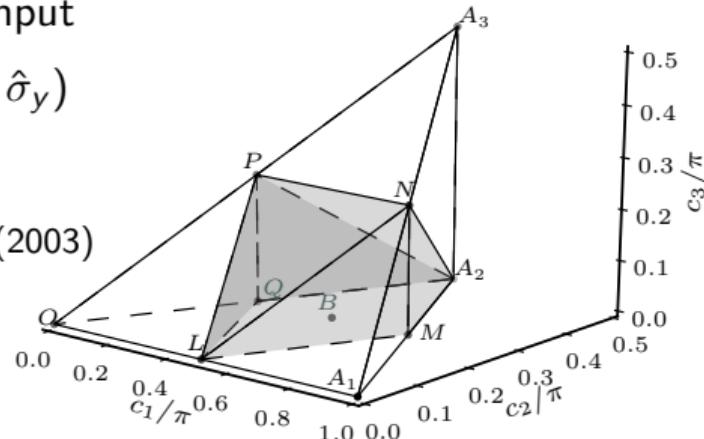
Quantum Gate Concurrence

Max concurrence that can be generated for a separable input

- 1 $c_1, c_2, c_3 \propto \text{eigvals}(\hat{U}\tilde{U})$; $\tilde{U} = (\hat{\sigma}_y \otimes \hat{\sigma}_y)\hat{U}(\hat{\sigma}_y \otimes \hat{\sigma}_y)$
- 2 $C(\hat{U}) = \max |\sin(c_{1,2,3} \pm c_{3,1,2})|$

Childs *et al.* Phys. Rev. A 68, 052311 (2003)

Not analytic!



Entanglement Measures

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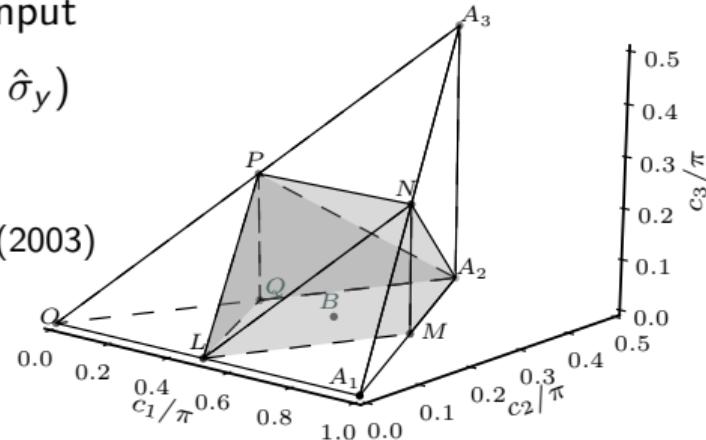
Childs *et al.* Phys. Rev. A 68, 052311 (2003)

Perfect Entanglers Functional

Find a two-qubit gate with maximum entangling power

$$\begin{aligned} F_{PE} &= \left(\frac{1}{\det U_B} \right) \left(\frac{1}{4} (\text{tr}^2[U_B^T U_B] - \text{tr}[U_B^T U_B U_B^T U_B]) \right) \left(\frac{1}{16} \text{Re}^2[\text{tr}[U_B^T U_B]] \right) + \\ &+ \left(\frac{2}{\det U_B} \right) \left(\frac{1}{4} (\text{tr}^2[U_B^T U_B] - \text{tr}[U_B^T U_B U_B^T U_B]) \right) \left(\frac{1}{16} \text{Im}^2[\text{tr}[U_B^T U_B]] \right) \\ &\quad \left(\frac{1}{16} \text{Re}[\text{tr}^2[U_B^T U_B]] \right) \end{aligned}$$

U_B : projection into logical subspace, in Bell basis



Watts *et al.* Phys. Rev. A 91, 062306 (2015)
Goerz *et al.* Phys. Rev. A 91, 062307 (2015)

Entanglement Measures

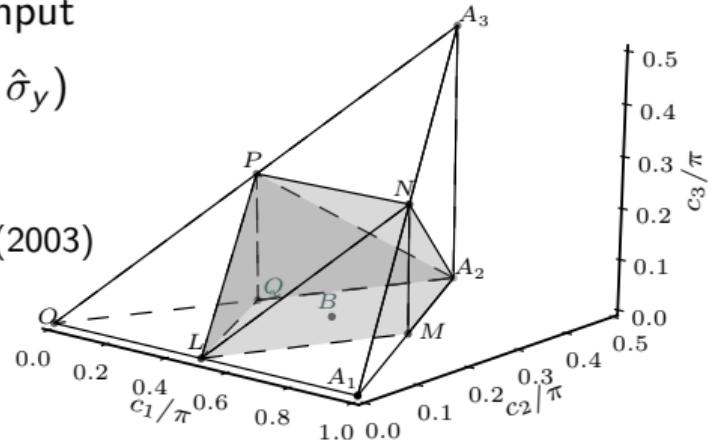
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Childs *et al.* Phys. Rev. A 68, 052311 (2003)

To a computer, everything is analytic!



Entanglement Measures

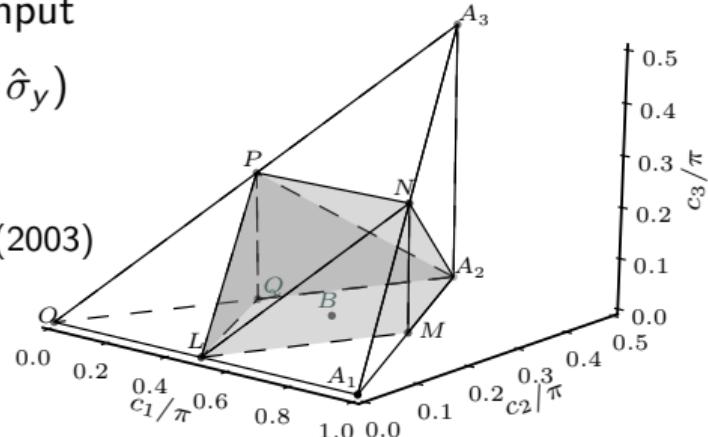
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Childs *et al.* Phys. Rev. A 68, 052311 (2003)

To a computer, everything is analytic!



Quantum Fisher Information

$$F(\hat{\rho}) = \sum_{i \neq j} \frac{2(p_i - p_j)^2}{p_i + p_j} \left| \left\langle \phi_i \left| \hat{S}_z \right| \phi_j \right\rangle \right|^2$$

where p_i , $|\phi_i\rangle$ are eigenvalues / eigenstates of $\hat{\rho}$

— Ma *et al.* Phys. Rep. 509, 89 (2011)

AD Compromises

1 Numerical scaling

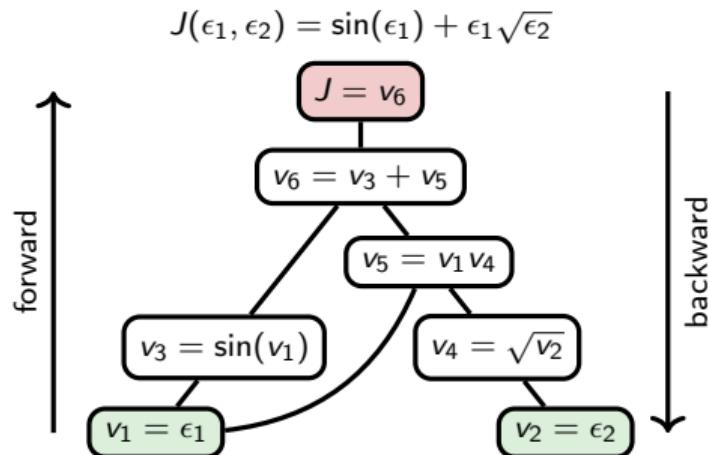
- AD memory overhead
- computational overhead (at least on CPU)

2 Framework limitations

- Complex numbers?
- In-place operations?
- Double-precision?

3 Code reuse

- Re-implement propagation methods?
- Re-use existing GRAPE implementation?



We don't have to compromise!

Semi-Automatic Differentiation

arXiv:2205.15044

Quantum Optimal Control via Semi-Automatic Differentiation

Michael H. Goerz, Sebastián C. Carrasco, and Vladimir S. Malinovsky

DEVCOM Army Research Laboratory, 2800 Powder Mill Road, Adelphi, MD 20783, USA

ant-ph] 27 May 2022

We develop a framework of “semi-automatic differentiation” that combines existing gradient-based methods of quantum optimal control with automatic differentiation. The approach allows to optimize practically any computable functional and is implemented in two open source Julia packages, `GRAPE.jl` and `Krotov.jl`, part of the `QuantumControl.jl` framework. Our method is based on formally rewriting the optimization functional in terms of propagated states, overlaps with target states, or quantum gates. An analytical application of the chain rule then allows to separate the time propagation and the evaluation of the functional when calculating the gradient. The former can be evaluated with great efficiency via a modified GRAPE scheme. The latter is evaluated with automatic differenti-

Funding

DEVCOM Army Research Laboratory, Cooperative Agreement Numbers W911NF-16-2-0147,
W911NF-21-2-0037; DTRA-TRC No. DTR19-CI-019



arXiv:2205.15044

Semi-Automatic Differentiation

$$\mathcal{J}(\{\varepsilon_{\text{ne}}\}) = \mathcal{J}_T(\{\varepsilon \sim t_u(\tau)\}) + \dots$$

$$\nabla \mathcal{J} = \frac{\partial \mathcal{J}_T}{\partial \varepsilon_{\text{ne}}}$$

$$\frac{\partial \mathcal{J}_T}{\partial \varepsilon_{\text{ne}}} = 2 \operatorname{Re} \left[\sum_n \underbrace{\frac{\partial \mathcal{J}_T}{\partial |\langle x_n(\tau) \rangle|}}_{\langle x_n(\tau) \rangle} \cdot \frac{\partial |\langle x_n(\tau) \rangle|}{\varepsilon_{\text{ne}}} \right] ; \quad \langle x_n(\tau) \rangle = \frac{\partial \mathcal{J}_T}{\partial \langle t_u(\tau) \rangle}$$

$$= 2 \operatorname{Re} \left[\sum_n \frac{\partial}{\partial \varepsilon_{\text{ne}}} \langle x_n(\tau) | \sim t_u(\tau) \rangle \right]$$

arXiv:2205.15044

Semi-Automatic Differentiation

$$\frac{\partial}{\partial \epsilon_{\text{ne}}} \langle x_k(\tau) | \hat{U}_N \dots \hat{U}_1 | \tau_k(0) \rangle ; \hat{U}_n = e^{-i \hat{H}_n \Delta t}$$

$$= \underbrace{\langle x_k(\tau) | \hat{U}_N \dots \hat{U}_{n+1} \frac{\partial \hat{U}_n}{\partial \epsilon_{\text{ne}}} \hat{U}_{n-1} \dots \hat{U}_1 | \tau_k(0) \rangle}_{\text{bw}} \uparrow \underbrace{\hat{U}_{n-1} \dots \hat{U}_1 | \tau_k(0) \rangle}_{\text{fw}}$$

$$|\tau_k(\tau)\rangle = \frac{\partial \mathcal{J}\tau}{\partial \langle \tau_k(\tau) |}$$

$$\mathcal{J}\tau(\hat{A})$$

$$\hat{A}_{ik} = \langle q_i | \tau_k \rangle$$

$$\frac{\partial \mathcal{J}\tau}{\partial \langle \tau_k(\tau) |} = \sum_i \frac{\partial \mathcal{J}\tau}{\partial u_{ik}} |q_i\rangle$$

Gradient of Time Evolution Operator

$$\begin{pmatrix} \frac{\partial \hat{U}_n^\dagger}{\partial \epsilon_{n1}} |\chi_k(t_n)\rangle \\ \vdots \\ \frac{\partial \hat{U}_n^\dagger}{\partial \epsilon_{nL}} |\chi_k(t_n)\rangle \\ \hat{U}_n^\dagger |\chi_k(t_n)\rangle \end{pmatrix} = \exp \left[-i \begin{pmatrix} \hat{H}_n^\dagger & 0 & \dots & 0 & \hat{H}_n^{(1)\dagger} \\ 0 & \hat{H}_n^\dagger & \dots & 0 & \hat{H}_n^{(2)\dagger} \\ \vdots & & \ddots & & \vdots \\ 0 & 0 & \dots & \hat{H}_n^\dagger & \hat{H}_n^{(L)\dagger} \\ 0 & 0 & \dots & 0 & \hat{H}_n^\dagger \end{pmatrix} dt_n \right] \begin{pmatrix} 0 \\ \vdots \\ 0 \\ |\chi_k(t_n)\rangle \end{pmatrix}$$

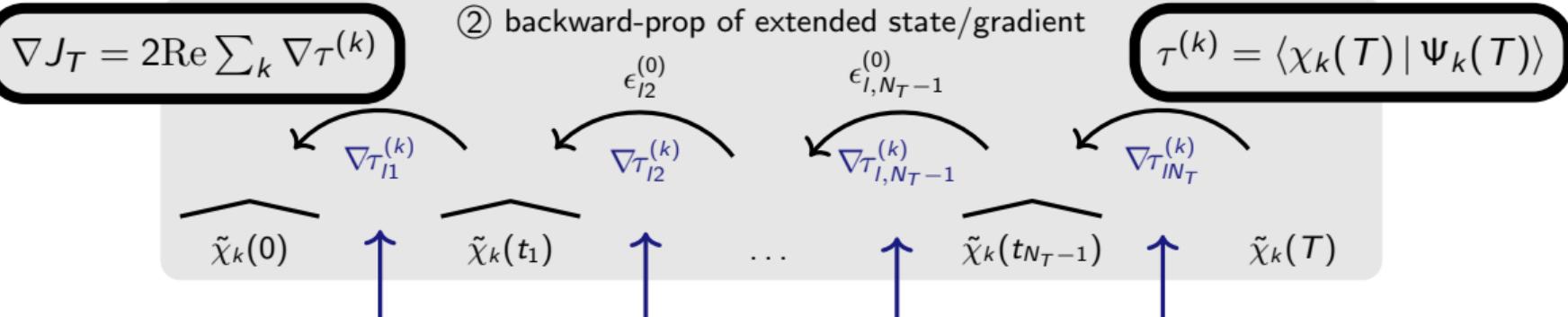
$$\hat{U}_n = \exp[-i\hat{H}_n dt_n]; \quad \hat{H}_n^{(I)} = \frac{\partial \hat{H}_n}{\partial \epsilon_I(t)}$$

— Goodwin, Kuprov, J. Chem. Phys. 143, 084113 (2015)

Generalized GRAPE scheme

$$\nabla J_T = 2\text{Re} \sum_k \nabla \tau^{(k)}$$

② backward-prop of extended state/gradient



ϕ_k

$\Psi_k(t_1)$

...

$\Psi_k(t_{N_T-1})$

$\Psi_k(T)$

$\epsilon_{I/1}^{(0)}$

$\epsilon_{I/2}^{(0)}$

$\epsilon_{I,N_T-1}^{(0)}$

$\epsilon_{IN_T}^{(0)}$

① forward-prop and storage with guess

GRAPE.jl



The screenshot shows a GitHub browser window with the URL github.com/JuliaQuantumControl/GRAPE.jl. The page displays the `README.md` file. At the top, there are navigation icons for back, forward, and search, along with a GitHub logo and a plus sign for creating a new repository. Below the header, there are standard GitHub interface elements like a download icon, a star icon, a puzzle piece icon, a user profile icon, and a more options icon.

The main content area starts with the title **GRAPE.jl**. Below the title, there are several status indicators: a green button for "Mar 2022 v0.1.1", blue buttons for "docs stable" and "docs dev", a CI badge with "CI passing", a codecov badge with "81%", and a user icon. The text below the badges describes the package as an implementation of (second-order) Gradient Ascent Pulse Engineering (GRAPE) extended with automatic differentiation, part of `QuantumControl.jl` and the `JuliaQuantumControl` organization.

Installation

For normal usage, the `GRAPE` package should be installed as part of `QuantumControl.jl`:

```
pkg> add QuantumControl
```



JuliaQuantumControl

The screenshot shows the GitHub repository page for 'JuliaQuantumControl'. The page includes the repository logo (three spheres), the repository name 'JuliaQuantumControl', a brief description 'Julia Framework for Quantum Optimal Control', a link to the repository, and navigation links for Overview, Repositories (11), Packages, People (3), and Projects.

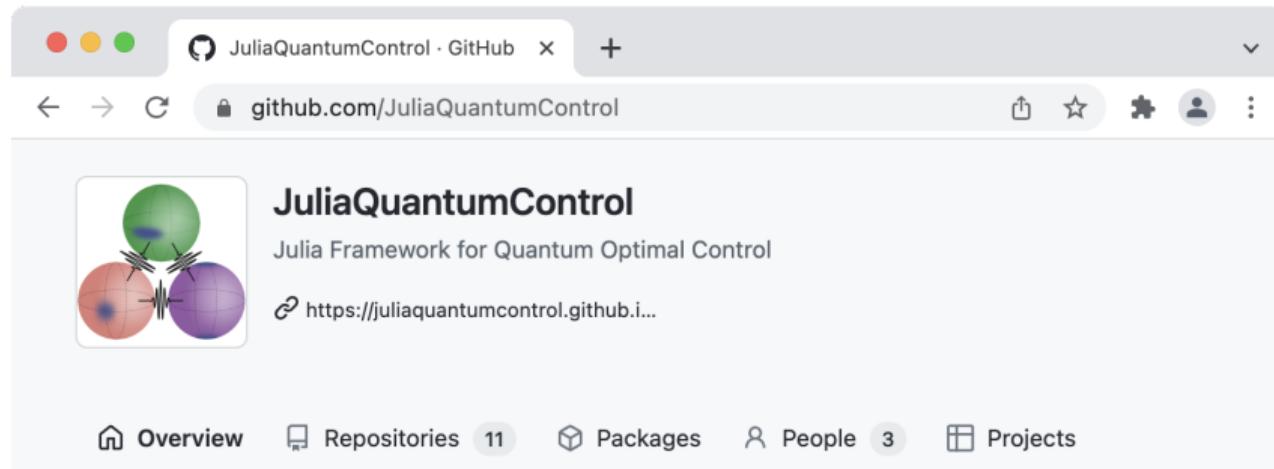


README.md

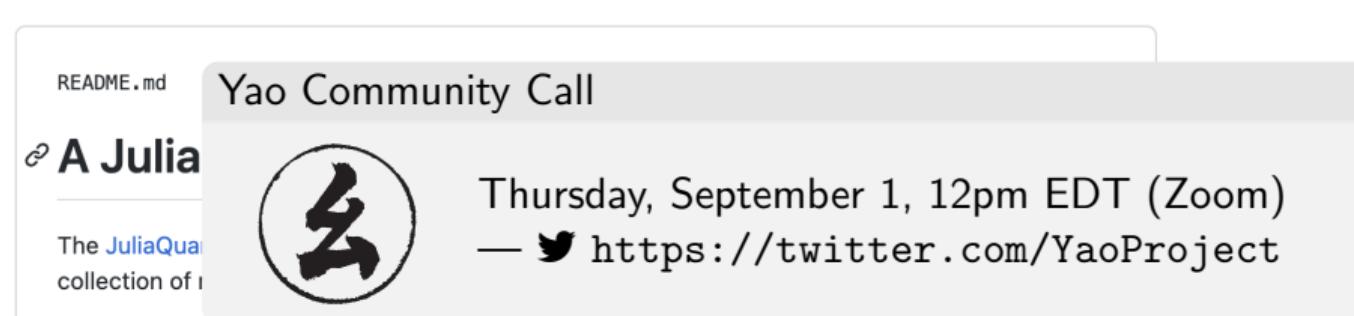
A Julia Framework for Quantum Optimal Control.

The [JuliaQuantumControl](#) organization collects packages implementing a comprehensive collection of methods of open-loop quantum optimal control.

JuliaQuantumControl



A screenshot of a web browser showing the GitHub repository page for "JuliaQuantumControl". The page includes the repository logo (three spheres), the repository name, a brief description ("Julia Framework for Quantum Optimal Control"), a link to the repository, and navigation links for Overview, Repositories (11), Packages, People (3), and Projects.



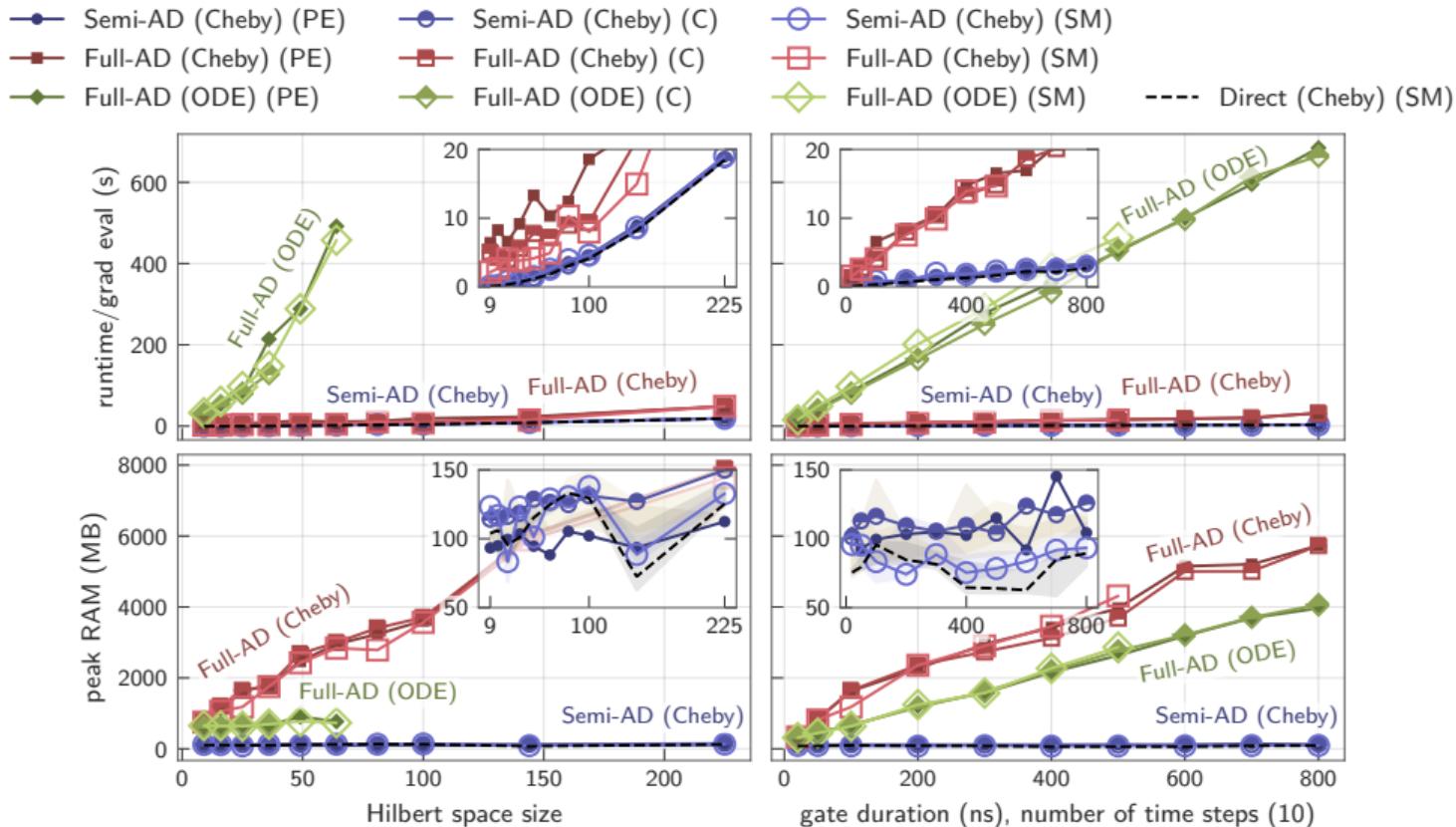
Yao Community Call

Thursday, September 1, 12pm EDT (Zoom)
— <https://twitter.com/YaoProject>

The JuliaQuantumControl collection of

A JuliaQuantumControl logo featuring a stylized black 'Z' shape inside a circle.

Benchmarks



Conclusion

AD-enhanced optimal control without compromises!

arXiv:2205.15044

- Use optimal data structures
- Use polynomial in-place propagators
- Use semi-AD implementation of GRAPE

- propagation and optimal control are independent
- AD and GPU computing are independent
- Full power of AD with near-zero overhead

Thank you