Looking for Convergence Rates for the MAP of the Exponential Family

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Abstract

We raise the problem of upper bounding the expected sub-optimality of the maximum likelihood estimate, or a conjugate maximum a posteriori for the exponential family. Surprisingly, we found no solution to this problem in the literature – we are not able to tell how many samples we need to fit a gaussian within a few bits of the true distribution. After displaying some properties and special cases of this problem, we show it is a special case of several optimization algorithms, but it falls out of their scopes, thus highlighting range of progress in the analysis of these algorithms.

1 Plan

- 1. intro to exponential family, and density estimation
- 2. the thing we want to bound
- 3. Examples: gaussian mean and gaussian variance (+other examples, just mentioned)
- 4. Insight: Strongly convex case. (+ self-concordance that is not verified either)
- 5. insight: bias-variance decomposition
- 6. Optimization perspective: SBPP or SBG. But no analysis hold, revealing a flaw of all these techniques.
- 7. Discussion: we believe finding a convergence rate would bring new tools useful to deal with common objects such as barrier losses.

Open questions

Preliminary work. Under review by AISTATS 2022. Do not distribute.

- does a base measure change anything?
- is there multiple conjugate priors?
- misspecified case. Do we have a formula?
- make sure the gaussian entropy is not SC.

2 Introduction and Background

RLP:Goal = disseminate related work to make it look nice. Exponential Families are an elegant and lean way to model a wide variety of data: binary, categorical, natural numbers, positive float, long or short tailed... They are literally the linear model of probabilities. The exponential family for data $X \in \mathcal{X}$ with sufficient statistic T and natural parameter θ is the model

$$p(X|\theta) = \exp(\theta^{\top} T(X) - A(\theta)) , \qquad (1)$$

where A is the log-partition function – i.e. the normalization factor

$$A(\theta) = \log \int e^{\theta^{\top} T(x)} dx \tag{2}$$

where the integral stands for a sum if x has discrete support. RLP:Use base measure instead. Note that an exponential family is entirely specified by its support set \mathcal{X} and its sufficient statistic T. This simple model encompasses both categorical distributions $\mathcal{X} = \{1, \ldots, k\}$ with T(X) being the one-hot encoding, and multivariate normal distributions $\mathcal{X} = \mathbb{R}, T(X) = (X, X^2)$.

Duality The logaritation function A verifies the two following identities

$$\nabla A(\theta) = \mathbb{E}_{p(X|\theta)} \left[T(X) \right] =: \mu \tag{3}$$

$$\nabla^2 A(\theta) = \operatorname{Cov}_{\theta}[T(X)] > 0 \tag{4}$$

where μ is called the mean parameter. If the sufficient statistic T is minimal, then the log-partition function A is strictly convex and its gradient ∇A is a bijection between natural parameters θ and mean parameters μ . The second identity entails that A is strictly-convex. At this point it is useful to introduce the convex conjugate (aka Fenchel-Legendre transform) of the logpartition function

$$A^*(\mu) = \langle \mu, \theta \rangle - A(\theta) . \tag{5}$$

It turns out that A^* matches the common notion of *entropy* in information theory, so we will call it entropy. If A is strictly convex, then its gradient is strictly monotone, so it is a bijection, and its inverse is the gradient of its dual $\nabla A^* \circ \nabla A(\theta) = \theta$ (cf Fig. 1). For a full review of exponential families and their duality, see Wainwright and Jordan (2008, Chapter 3).

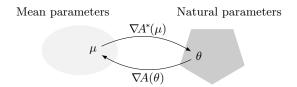


Figure 1: The gradient of the log-partition function and its dual, $(\nabla A, \nabla A^*)$, form a bijection between the natural and mean parameters θ, μ . Figure reproduced from Kunstner et al. (2021).

3 Open Problem

For a well-specified model, the suboptimality on the population log-likelihood is exactly the KL between our current model and the true distribution

$$\mathbb{E}_{X \sim p(.|\theta^*)} \left[-\log p(X|\theta) + \log p(X|\theta^*) \right]$$

= $D_{\text{KL}}(p(.|\theta^*); p(.|\theta))$. (6)

For the exponential family, the KL is also the Bregman divergence induced by the log-partition function (with switched arguments)

$$D_{\mathrm{KL}}(p(.|\theta^*); p(.|\theta)) = \mathcal{B}_A(\theta; \theta^*) . \tag{7}$$

There is a general relationship between Bregman divergences and convex conjugates (notice the argument switching)

$$\mathcal{B}_A(\theta; \theta^*) = \mathcal{B}_{A^*}(\mu^*; \mu) \tag{8}$$

so in the end the suboptimality is a divergence, which can either be seen as a KL between distributions, as a divergence between natural parameters, or as a divergence between mean parameters

$$D_{\mathrm{KL}}(p(.|\theta^*); p(.|\theta)) = \mathcal{B}_A(\theta; \theta^*) = \mathcal{B}_{A^*}(\mu^*; \mu) .$$
 (9)

The question is: how does this quantity behave when θ is the maximum-likelihood or the MAP estimate? Can we get bounds on the following quantities

$$\mathbb{E}_{X_i \sim \theta^*} \left[\mathcal{B}_{A^*} \left(\mathbb{E}[T(X)]; \frac{1}{n} \sum_i T(X_i) \right) \right] \le ?,$$
(10)

$$\mathbb{E}_{X_i \sim \theta^*} \left[\mathcal{B}_{A^*} \left(\mathbb{E}[T(X)]; \frac{n_0 \mu_0 + \sum_i T(X_i)}{n_0 + n} \right) \right] \le ?,$$
(11)

where the outer expectation is on the dataset X_1, \ldots, X_n ?

Remark. What we are looking for is really akin to concentration inequality, expressed with a Bregman divergence instead of a norm. A key difference though, is that the random variable T(X) is connected to the metric A. Indeed expressions (10) or (11) can be infinite for another choice of random variable. For instance, if we plug in $A^*(\mu) = -\log(\mu)$, which defines a divergence on positive numbers, and $T(X) \sim \mathcal{N}(0,1)$ which can be negative.

Remark 2. The expectation of the MLE may be infinite, for instance with $\mathcal{N}(0, \sigma^2)$ and $n \leq 2$. Instead of taking the expectation, we might want to bound this quantity in high probability, without resorting to Markov inequality, but that is a difficult endeavor.

4 Examples

4.1 Gaussian Mean

4.2 Gaussian Variance

The trailing example of this paper is a centered gaussian with unknown variance $\mathcal{N}(0, \sigma^2)$. The density of a centered normal variable is

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2}{2\sigma^2}} \ . \tag{12}$$

Defining $T(X)=X^2$ as the sufficient statistic, we get natural parameter $\theta=-\frac{1}{2\sigma^2}<0$, and mean parameter $\mu=\mathbb{E}[T(X)]=\sigma^2>0$. Mean and natural parameters are roughly inverse of each other

$$\theta = -\frac{1}{2\mu} \ . \tag{13}$$

Now we can match the log-likelihood with the exponential family template to get the log-partition function.

$$\log p(x) = -\frac{x^2}{2\sigma^2} - \frac{1}{2}\log(2\pi\sigma^2) = x^2\theta - A(\theta) \quad (14)$$

$$\implies A(\theta) = -\frac{1}{2}\log(-\theta) + \frac{1}{2}\log(\pi)$$
 (15)

We can use the formula $A^*(\mu) = \mu\theta - A(\theta)$ to get the entropy

$$A^*(\mu) = \frac{1}{2} \left(-\log(\mu) + \log\frac{\pi}{2} - 1 \right) . \tag{16}$$

We can also take gradient and derivative of $A(\theta)$ to retrieve the mean and covariance of the sufficient statistic X^2

$$\nabla A(\theta) = \frac{-1}{2\theta} = \sigma^2 = \mu = \mathbb{E}[X^2] \tag{17}$$

$$\nabla^2 A(\theta) = \frac{1}{2\theta^2} = 2\sigma^4 = 2\mu^2 = \text{Var}(X^2)$$
 (18)

which we confirm thank to wikipedia since $\mathbb{E}[X^4] = 3\sigma^4$ and thus $\text{Var}(X^2) = \mathbb{E}[X^4] - \mathbb{E}[X^2]^2 = 3\sigma^4 - \sigma^4 = 2\sigma^4$.

The logarition function is $A(\theta) = -\log(-\theta)/2 + \text{cst}$, thus the conjugate prior is the exponential family with sufficient statistic $(\theta, \log(-\theta))$, eg a negative Gamma distribution. In particular,

$$p(\theta) \propto \exp(-n_0 A(\theta) + \langle n_0 \mu_0, \theta \rangle)$$
 (19)

$$\propto \exp(\frac{n_0}{2}\log(-\theta) + n_0\mu_0\theta)$$
 (20)

$$\propto (-\theta)^{1+\frac{n_0}{2}-1}e^{-n_0\mu_0(-\theta)}/Z$$
 (21)

from which we infer the shape parameter $\alpha=1+\frac{n_0}{2}$ and the rate parameter $\beta=n_0\mu_0,$ eg $\theta\sim\Gamma(1+\frac{n_0}{2},n_0\mu_0)$. After seeing n samples, the posterior is $\Gamma\left(1+\frac{n_0+n}{2},n_0\mu_0+\sum_i T(X_i)\right)$.

Both the entropy and the log-partition are roughly negative logarithm $z \mapsto -\log(z)$. Which yields the same shape of Bregman divergence, as visible below (all three lines are equal)

$$D_{\mathrm{KL}}(\sigma_*^2; \sigma_n^2) = \frac{1}{2} \left(\frac{\sigma_*^2}{\sigma_n^2} - 1 - \log \frac{\sigma_*^2}{\sigma_n^2} \right)$$
 (22)

$$\mathcal{B}_{A^*}(\mu_*; \mu_n) = \frac{1}{2} \left(\frac{\mu_*}{\mu_n} - 1 - \log \frac{\mu_*}{\mu_n} \right)$$
 (23)

$$\mathcal{B}_A(\theta_n; \theta_*) = \frac{1}{2} \left(\frac{\theta_n}{\theta_*} - 1 - \log \frac{\theta_n}{\theta_*} \right) . \tag{24}$$

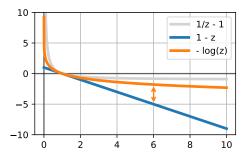
In other words, this divergence measures the discrepancy between the ratio $\frac{\theta_n}{\theta_*} = \frac{\mu_*}{\mu_n}$ and 1 via the function ϕ

$$\phi(z) := \frac{1}{2}(z - 1 - \log(z)) \tag{25}$$

$$\mathcal{B}_A(\theta_n; \theta_*) = \phi(\frac{\theta_n}{\theta_*}) = \phi(\frac{\mu_*}{\mu_n}) \tag{26}$$

as illustrated in Figure 2. We can get a non-transcendental upper bound thanks to the inequality

$$1 - \frac{1}{z} \le \log(z) \implies \phi(z) \le \frac{1}{2}(z + \frac{1}{z}) - 1 = \frac{(z - 1)^2}{2z}$$
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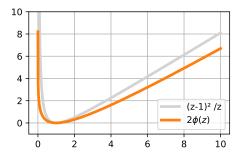
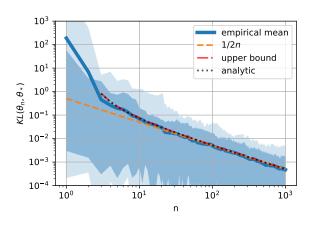


Figure 2: $\phi(z)$ is the Bregman divergence induced by $-\log(z)$. It is a barrier near 0. As a result, it is poorly approximated by quadratics.

References

Kunstner, F., Kumar, R., and Schmidt, M. (2021). Homeomorphic-invariance of EM: Non-asymptotic convergence in KL divergence for exponential families via mirror descent. *AISTATS*.

Wainwright, M. J. and Jordan, M. I. (2008). Graphical models, exponential families, and variational inference. Now Publishers Inc.



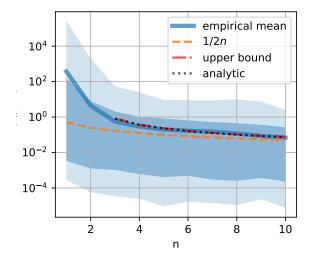


Figure 3: Suboptimality of a Gaussian variance MLE against number of samples n. Bold curve is average over 100 trials, dark shaded area is 90% (dark) confidence interval, light shade is min-max interval. **Left:** as n increases, the suboptimality matches the 1/2N asymptote. **Right:** the first few samples significantly deviate from this behavior. In fact, for n=1 and n=2, the expected value is infinite, but we have a closed form solution and a simple upper-bound for n>2.