$$\rho = \underbrace{\begin{array}{c} L_1 & x_0 \\ L_2 & L_4 \\ L_2 & x_3 & x_5 \\ \end{array}}_{x_1} \qquad (T, \mathbf{v}, \mathbf{t}) = \underbrace{\begin{array}{c} x_0 \\ x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_2 & x_3 & x_5 \\ \end{array}}_{x_2} \qquad (T, \mathbf{v}, \mathbf{t}) = \underbrace{\begin{array}{c} x_0 \\ x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_2 & x_3 & x_5 \\ \end{array}}_{x_3} \qquad (T, \mathbf{v}, \mathbf{t}) = \underbrace{\begin{array}{c} x_0 \\ x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_3} \begin{pmatrix} b_3 \\ b_3 \\ x_3 \end{pmatrix} \begin{pmatrix} b_2 \\ b_3 \\ x_3 \end{pmatrix} \begin{pmatrix} b_2 \\ x_3 \\ \end{pmatrix} \begin{pmatrix} b_2 \\ x_4 \\ \end{array}}_{x_3} \qquad (T, \mathbf{v}, \mathbf{t}') = \underbrace{\begin{array}{c} x_0 \\ x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_3} \begin{pmatrix} x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_5} \begin{pmatrix} x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_5} \begin{pmatrix} x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}}_{x_5} \begin{pmatrix} x_1 & x_4 \\ x_2 & x_3 & x_5 \\ \end{array}$$