Basics

Fundamental Assumption
Data is iid for unknown P: $(x_i,y_i) \sim P(X,Y)$

True risk and estimated error
True risk: $R(w) = \int P(x,y)(y-w^Tx)^2 \partial x \partial y = \mathbb{E}_{x,y}[(y-w^Tx)^2]$

Est. error: $\hat{R}_D(w) = \frac{1}{|D|}\sum_{(x,y)\in D}(y-w^Tx)^2$

Standardization
Centered data with unit variance: $\tilde{x}_i = \frac{x_i-\hat{\mu}}{\hat{\sigma}}$

$\hat{\mu} = \frac{1}{n}\sum_{i=1}^n x_i$, $\hat{\sigma}^2 = \frac{1}{n}\sum_{i=1}^n(x_i-\hat{\mu})^2$

Parametric vs. Nonparametric
Parametric: have finite set of parameters. e.g. linear regression, linear perceptron

Nonparametric: grow in complexity with the size of the data, more expressive. e.g. k-NN

Gradient Descent
1. Pick arbitrary $w_0 \in \mathbb{R}^d$
2. $w_{t+1} = w_t - \eta_t \nabla \hat{R}(w_t)$

Stochastic Gradient Descent (SGD)
1. Pick arbitrary $w_0 \in \mathbb{R}^d$
2. $w_{t+1} = w_t - \eta_t \nabla_w l(w_t;x',y')$, with u.a.r. data point $(x',y') \in D$

Regression
Solve $w^* = \underset{w}{\operatorname{argmin}}\ \hat{R}(w)+\lambda C(w)$

Linear Regression
$\hat{R}(w) = \sum_{i=1}^n(y_i-w^Tx_i)^2 = ||Xw-y||_2^2$
$\nabla_w\hat{R}(w) = -2\sum_{i=1}^n(y_i-w^Tx_i)\cdot x_i$
$w^* = (X^TX)^{-1}X^Ty$

Ridge regression
$\hat{R}(w) = \sum_{i=1}^n(y_i-w^Tx_i)^2 + \lambda||w||_2^2$
$\nabla_w\hat{R}(w) = -2\sum_{i=1}^n(y_i-w^Tx_i)\cdot x_i + 2\lambda w$
$w^* = (X^TX+\lambda I)^{-1}X^Ty$

L1-regularized regression (Lasso)
$\hat{R}(w) = \sum_{i=1}^n(y_i-w^Tx_i)^2 + \lambda||w||_1$

Classification
Solve $w^* = \underset{w}{\operatorname{argmin}}\ l(w;x_i,y_i)$, l ...loss function

0/1 loss
$l_{0/1}(w;y_i,x_i) = 1$ if $y_i \neq \operatorname{sign}(w^Tx_i)$ else 0

Perceptron algorithm
Use $l_P(w;y_i,x_i) = \max(0,-y_iw^Tx_i)$ and SGD

$\nabla_w l_P(w;y_i,x_i) = \begin{cases} 0 & \text{if } y_iw^Tx_i \geq 0 \\ -y_ix_i & \text{otherwise} \end{cases}$

Data lin. separable $\Rightarrow$ obtains a lin. separator

Support Vector Machine (SVM)
Hinge loss: $l_H(w;x_i,y_i) = \max(0,1-y_iw^Tx_i)$

$\nabla_w l_H(w;y,x) = \begin{cases} 0 & \text{if } _iw^Tx_i \geq 1 \\ -y_ix_i & \text{otherwise} \end{cases}$

$w^* = \underset{w}{\operatorname{argmin}}\ \lambda||w||_2^2 + l_H(w;x_i,y_i)$

For L1-SVM (feature selection) use $||w||_1$

Kernels

Properties of kernel
$k:\mathcal{X}\times\mathcal{X}\to\mathbb{R}$, k must be some inner product (symmetric, positive-definite, linear) for some space $\mathcal{V}$. i.e. $k(\mathbf{x},\mathbf{x}') = \langle\varphi(\mathbf{x}),\varphi(\mathbf{x}')\rangle_{\mathcal{V}}$
$\Rightarrow k$ is symmetric and p.s.d.

Kernel matrix
$K = \begin{bmatrix} k(x_1,x_1) & ... & k(x_1,x_n) \\ \vdots & \ddots & \vdots \\ k(x_n,x_1) & ... & k(x_n,x_n) \end{bmatrix}$

Positive semi-definite matrices $\Leftrightarrow$ kernels k

Important kernels
Linear: $k(x,y) = x^Ty$
Polynomial: $k(x,y) = (x^Ty+1)^d$
Gaussian: $k(x,y) = exp(-||x-y||_2^2/(2h^2))$
Laplacian: $k(x,y) = exp(-||x-y||_1/h)$

Composition rules
Valid kernels k_1,k_2, also valid kernels: $k_1(x,y)+k_2(x,y)$; $k_1(x,y)\cdot k_2(x,y)$; $c\cdot k_1(x,y)$, $c>0$;

Reformulating the perceptron
Ansatz: $w^* \in \operatorname{span}(X) \Rightarrow w = \sum_{j=1}^n \alpha_j y_j x_j$
$\alpha^* = \underset{\alpha\in\mathbb{R}^n}{\min}\frac{1}{n}\sum_{i=1}^n\max(0,-\sum_{j=1}^n\alpha_jy_i,y_jx_i^Tx_j)$

Kernelized perceptron and SVM
Use α^Tk_i instead of w^Tx_i,
use $\alpha^TD_yKD_y\alpha$ instead of $||w||_2^2$
$k_i = [y_1k(x_i,x_1),...,y_nk(x_i,x_n)]$, $D_y = \operatorname{diag}(y)$
Prediction: $f(\hat{x}) = \operatorname{sign}(\sum_{i=1}^n\alpha_iy_ik(x_i,\hat{x}))$

Kernelized linear regression (KLR)
Ansatz: $w^* = \sum_{i=1}^n\alpha_ix$
$\alpha^* = \underset{\alpha}{\operatorname{argmin}}\frac{1}{n}||\alpha^TK-y||_2^2+\lambda\alpha^TK\alpha$
$= (K+\lambda I)^{-1}y$

Prediction: $f(\hat{x}) = \sum_{i=1}^n\alpha_ik(x_i,\hat{x})$

Imbalance

Cost Sensitive Classification
Replace loss by: $l_{CS}(w;x,y) = c_yl(w;x,y)$

Metrics
$n = n_++n_-$, $n_+ = TP+FN$, $n_- = TN+FP$
Accuracy: $\frac{TP+TN}{n}$, Precision: $\frac{TP}{TP+FP}$
Recall/TPR: $\frac{TP}{n_+}$, FPR: $\frac{FP}{n_-}$
F1 score: $\frac{2TP}{2TP+FP+FN}$
ROC Curve: $y = \text{TPR}$, $x = \text{FPR}$

Multi-class

Hinge loss
$l_{MC-H}(w^{(1)},...,w^{(c)};x,y) = $
$\max(0,1+\underset{j\in\{1,\cdots,y-1,y+1,\cdots,c\}}{\max}w^{(j)T}x-w^{(y)T}x)$

Neural network
Parameterize feature map: $\phi(x,\theta)$ instead of $\phi(x)$, usually: $\phi(x,\theta) = \varphi(\theta^Tx) = \varphi(z)$
$\Rightarrow w^* = \underset{w,\theta}{\operatorname{argmin}}\sum_{i=1}^n l(y_i;\sum_{j=1}^m w_j\phi(x_i,\theta_j))$

Activation functions
Sigmoid: $\frac{1}{1+exp(-z)}$, $\varphi'(z) = (1-\varphi(z))\cdot\varphi(z)$

Tanh: $\varphi(z) = tanh(z) = \frac{exp(z)-exp(-z)}{exp(z)+exp(-z)}$

ReLu: $\varphi(z) = max(z,0)$

Predict: forward propagation
$v^{(0)} = x$; for $l=1,...,L-1$:
$v^{(l)} = \varphi(z^{(l)})$, $z^{(l)} = W^{(l)}v^{(l-1)}$
$f = W^{(L)}v^{(L-1)}$
Predict f for regression, $\operatorname{sign}(f)$ for class.

Compute gradient: backpropagation
Output layer: $\delta_j = l'_j(f_j)$, $\frac{\partial}{\partial w_{j,i}} = \delta_j v_i$
Hidden layer $l=L-1,...,1$:
$\delta_j = \varphi'(z_j)\cdot\sum_{i\in Layer_{l+1}}w_{i,j}\delta_i$, $\frac{\partial}{\partial w_{j,i}} = \delta_j v_i$

Learning with momentum
$a \leftarrow m\cdot a + \eta_t\nabla_W l(W;y,x)$; $W \leftarrow W-a$

Clustering

k-mean
$\hat{R}(\mu) = \sum_{i=1}^n\underset{j\in\{1,...k\}}{\min}||x_i-\mu_j||_2^2$

$\hat{\mu} = \underset{\mu}{\operatorname{argmin}}\ \hat{R}(\mu)$ ...non-convex, NP-hard

Algorithm (Lloyd's heuristic): Choose starting centers, assign points to closest center, update centers to mean of each cluster, repeat

Dimension reduction

PCA
$D = x_1,...,x_n \subset \mathbb{R}^d$, $\Sigma = \frac{1}{n}\sum_{i=1}^n x_ix_i^T$, $\mu=0$
$(W,z_1,...,z_n) = \operatorname{argmin}\sum_{i=1}^n||Wz_i-x_i||_2^2$,
$W = (v_1|...|v_k) \in \mathbb{R}^{d\times k}$, orthogonal; $z_i = W^Tx_i$
v_i are the eigen vectors of Σ

Kernel PCA
Kernel PC: $\alpha^{(1)},...,\alpha^{(k)} \in \mathbb{R}^n$, $\alpha^{(i)} = \frac{1}{\sqrt{\lambda_i}}v_i$,
$K = \sum_{i=1}^n\lambda_iv_iv_i^T$, $\lambda_1 \geq ... \geq \lambda_d \geq 0$
New point: $\hat{z} = f(\hat{x}) = \sum_{j=1}^n\alpha_j^{(i)}k(\hat{x},x_j)$

Autoencoders
Find identity function: $x \approx f(x;\theta)$
$f(x;\theta) = f_{decode}(f_{encode}(x;\theta_{encode});\theta_{decode})$

Probability modeling
Find $h:X\to Y$ that min. pred. error: $R(h) = \int P(x,y)l(y;h(x))\partial y x \partial y = \mathbb{E}_{x,y}[l(y;h(x))]$

For least squares regression
Best h: $h^*(x) = \mathbb{E}[Y|X=x]$
Pred.: $\hat{y} = \hat{\mathbb{E}}[Y|X=\hat{x}] = \int\hat{P}(y|X=\hat{x})y\partial y$

Maximum Likelihood Estimation (MLE)
$\theta^* = \underset{\theta}{\operatorname{argmax}}\ \hat{P}(y_1,...,y_n|x_1,...,x_n,\theta)$

E.g. lin. + Gauss: $y_i = w^Tx_i+\varepsilon_i, \varepsilon_i \sim \mathcal{N}(0,\sigma^2)$
i.e. $y_i \sim \mathcal{N}(w^Tx_i,\sigma^2)$, With MLE (use argmin $-\log$): $w^* = \underset{w}{\operatorname{argmin}}\sum(y_i-w^Tx_i)^2$

Bias/Variance/Noise
Prediction error $= Bias^2+Variance+Noise$

Maximum a posteriori estimate (MAP)

Assume bias on parameters, e.g. $w_i \in \mathcal{N}(0, \beta^2)$

Bay.: $P(w|x,y) = \frac{P(w|x)P(y|x,w)}{P(y|x)} = \frac{P(w)P(y|x,w)}{P(y|x)}$

Logistic regression

Link func.: $\sigma(w^T x) = \frac{1}{1+exp(-w^T x)}$ (Sigmoid)

$P(y|x,w) = Ber(y; \sigma(w^T x)) = \frac{1}{1+exp(-yw^T x)}$

Classification: Use $P(y|x,w)$, predict most likely class label.

MLE: $\underset{w}{argmax}\, P(y_{1:n}|w, x_{1:n})$

$\Rightarrow w^* = \underset{w}{argmin} \sum_{i=1}^{n} log(1 + exp(-y_i w^T x_i))$

SGD update: $w = w + \eta_t y x \hat{P}(Y = -y|w, x)$

$\hat{P}(Y = -y|w, x) = \frac{1}{1+exp(yw^T x)}$

MAP: Gauss. prior $\Rightarrow ||w||_2^2$, Lap. p. $\Rightarrow ||w||_1$

SGD: $w = w(1 - 2\lambda \eta_t) + \eta_t y x \hat{P}(Y = -y|w, x)$

Bayesian decision theory

- Conditional distribution over labels $P(y|x)$
- Set of actions $\mathcal{A}$
- Cost function $C: Y \times \mathcal{A} \to \mathbb{R}$

$a^* = \underset{a \in \mathcal{A}}{argmin}\, \mathbb{E}[C(y,a)|x]$

Calculate $\mathbb{E}$ via sum/integral.

Classification: $C(y,a) = [y \neq a]$; asymmetric:

$C(y,a) = \begin{cases} c_{FP} & \text{, if } y = -1,\ a = +1 \\ c_{FN} & \text{, if } y = +1,\ a = -1 \\ 0 & \text{, otherwise} \end{cases}$

Regression: $C(y,a) = (y-a)^2$; asymmetric:

$C(y,a) = c_1 max(y-a, 0) + c_2 max(a-y, 0)$

E.g. $y \in \{-1, +1\}$, predict $+$ if $c_+ < c_-$,

$c_+ = \mathbb{E}(C(y, +1)|x) = P(y = 1|x) \cdot 0 + P(y = -1|x) \cdot c_{FP}$, c_- likewise

Discriminative / generative modeling

Discr. estimate $P(y|x)$, generative $P(y,x)$

Approach (generative): $P(x,y) = P(x|y) \cdot P(y)$
- Estimate prior on labels $P(y)$
- Estimate cond. distr. $P(x|y)$ for each class y
- Pred. using Bayes: $P(y|x) = \frac{P(y)P(x|y)}{P(x)}$

$P(x) = \sum_y P(x,y)$

Examples

MLE for $P(y) = p = \frac{n_+}{n}$

MLE for $P(x_i|y) = \mathcal{N}(x_i; \mu_{i,y}, \sigma_{i,y}^2)$:

$\hat{\mu}_{i,y} = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} x$

$\hat{\sigma}_{i,y}^2 = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} (x - \hat{\mu}_{i,y})^2$

MLE for Poi.: $\lambda = avg(x_i)$

$\mathbb{R}^d$: $P(X = x|Y = y) = \prod_{i=1}^{d} Pois(\lambda_y^{(i)}, x^{(i)})$

Deriving decision rule

$P(y|x) = \frac{1}{Z} P(y) P(x|y)$, $Z = \sum_y P(y) P(x|y)$

$y^* = \underset{y}{amax}\, P(y|x) = \underset{y}{amax}\, P(y) \prod_{i=1}^{d} P(x_i|y)$

Gaussian Bayes Classifier

$\hat{P}(x|y) = \mathcal{N}(x; \hat{\mu}_y, \hat{\Sigma}_y)$

$\hat{\mu}_y = \frac{1}{n_y} \sum_{i:y_i = y} x_i \in \mathbb{R}^d$

$\hat{\Sigma}_y = \frac{1}{n_y} \sum_{i:y_i = y} (x_i - \hat{\mu}_y)(x_i - \hat{\mu}_y)^T \in \mathbb{R}^{d \times d}$

Fisher's lin. discrim. analysis (LDA, c=2)

Assume: $p = 0.5$; $\hat{\Sigma}_- = \hat{\Sigma}_+ = \hat{\Sigma}$

discriminant function: $f(x) = log\frac{p}{1-p} +$

$\frac{1}{2}[log\frac{|\hat{\Sigma}_-|}{|\hat{\Sigma}_+|} + ((x - \hat{\mu}_-)^T \hat{\Sigma}_-^{-1}(x - \hat{\mu}_-)) -$

$((x - \hat{\mu}_+)^T \hat{\Sigma}_+^{-1}(x - \hat{\mu}_+))]$

Predict: $y = sign(f(x)) = sign(w^T x + w_0)$

$w = \hat{\Sigma}^{-1}(\hat{\mu}_+ - \hat{\mu}_-)$;

$w_0 = \frac{1}{2}(\hat{\mu}_-^T \hat{\Sigma}^{-1} \hat{\mu}_- - \hat{\mu}_+^T \hat{\Sigma}^{-1} \hat{\mu}_+)$

Outlier Detection

$P(x) \leq \tau$

Categorical Naive Bayes Classifier

MLE for feature distr.: $\hat{P}(X_i = c|Y = y) = \theta_{c|y}^{(i)}$

$\theta_{c|y}^{(i)} = \frac{Count(X_i = c, Y = y)}{Count(Y = y)}$

Prediction: $y^* = \underset{y}{argmax}\, \hat{P}(y|x)$

Missing data

Mixture modeling

Model each c. as probability distr. $P(x|\theta_j)$

$P(D|\theta) = \prod_{i=1}^{n} \sum_{j=1}^{k} w_j P(x_i|\theta_j)$

$L(w, \theta) = -\sum_{i=1}^{n} log \sum_{j=1}^{k} w_j P(x_i|\theta_j)$

Gaussian-Mixture Bayes classifiers

Estimate prior $P(y)$; Est. cond. distr. for each class: $P(x|y) = \sum_{j=1}^{k_y} w_j^{(y)} \mathcal{N}(x; \mu_j^{(y)}, \Sigma_j^{(y)})$

Hard-EM algorithm

Initialize parameters $\theta^{(0)}$

E-step: Predict most likely class for each point: $z_i^{(t)} = \underset{z}{argmax}\, P(z|x_i, \theta^{(t-1)})$

$= \underset{z}{argmax}\, P(z|\theta^{(t-1)}) P(x_i|z, \theta^{(t-1)})$;

M-step: Compute the MLE: $\theta^{(t)} = \underset{\theta}{argmax} P(D^{(t)}|\theta)$, i.e. $\mu_j^{(t)} = \frac{1}{n_j} \sum_{i:z_i = j} x_j$

Soft-EM algorithm

E-step: Calc p for each point and cls.: $\gamma_j^{(t)}(x_i)$

M-step: Fit clusters to weighted data points:

$w_j^{(t)} = \frac{1}{n} \sum_{i=1}^{n} \gamma_j^{(t)}(x_i)$; $\mu_j^{(t)} = \frac{\sum_{i=1}^{n} \gamma_j^{(t)}(x_i) x_i}{\sum_{i=1}^{n} \gamma_j^{(t)}(x_i)}$

$\sigma_j^{(t)} = \frac{\sum_{i=1}^{n} \gamma_j^{(t)}(x_i)(x_i - \mu_j^{(t)})^T (x_i - \mu_j^{(t)})}{\sum_{i=1}^{n} \gamma_j^{(t)}(x_i)}$

Soft-EM for semi-supervised learning

labeled y_i: $\gamma_j^{(t)}(x_i) = [j = y_i]$, unlabeled:

$\gamma_j^{(t)}(x_i) = P(Z = j|x_i, \mu^{(t-1)}, \Sigma^{(t-1)}, w^{(t-1)})$

Useful math

Probabilities

$\mathbb{E}_x[X] = \begin{cases} \int x \cdot p(x) \partial x & \text{if continuous} \\ \sum_x x \cdot p(x) & \text{otherwise} \end{cases}$

$Var[X] = \mathbb{E}[(X - \mu_X)^2] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$

$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$; $p(Z|X, \theta) = \frac{p(X, Z|\theta)}{p(X|\theta)}$

$P(x,y) = P(y|x) \cdot P(x) = P(x|y) \cdot P(y)$

Bayes Rule

$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$

P-Norm

$||x||_p = (\sum_{i=1}^{n} |x_i|^p)^{\frac{1}{p}}$, $1 \leq p < \infty$

Some gradients

$\nabla_x ||x||_2^2 = 2x$

$f(x) = x^T A x$; $\nabla_x f(x) = (A + A^T) x$

E.g. $\nabla_w log(1 + exp(-yw^T x)) =$

$\frac{1}{1+exp(-yw^T x)} \cdot exp(-yw^T x) \cdot (-yx) =$

$\frac{1}{1+exp(yw^T x)} \cdot (-yx)$

Convex / Jensen's inequality

$g(x)$ convex $\Leftrightarrow g''(x) > 0 \Leftrightarrow x_1, x_2 \in \mathbb{R}, \lambda \in [0,1]$:

$g(\lambda x_1 + (1-\lambda) x_2) \leq \lambda g(x_1) + (1-\lambda) g(x_2)$

Gaussian / Normal Distribution

$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} exp(-\frac{(x-\mu)^2}{2\sigma^2})$

Multivariate Gaussian

$\Sigma =$ covariance matrix, $\mu =$ mean

$f(x) = \frac{1}{2\pi\sqrt{|\Sigma|}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$

Empirical: $\Sigma = \frac{1}{n} \sum_{i=1}^{n} x_i x_i^T$ (needs centered data points)

Positive semi-definite matrices

$M \in \mathbb{R}^{n \times n}$ is psd $\Leftrightarrow$

$\forall x \in \mathbb{R}^n : x^T M x \geq 0 \Leftrightarrow$

all eigenvalues of M are positive: $\lambda_i \geq 0$