

# Microeconomic Analysis Supplementary Exercises 1

4a) (210618 21)

$$\vec{x} = (1, 0, 3), \vec{y} = (-5, 3, 1), \vec{z} = (-1, 1, 2)$$

Consider system of linear equations

$$10x - 50y + 10z = a \quad (1)$$

$$00x + 30y + 10z = b \quad (2)$$

$$30x + 10y + 20z = c \quad (3)$$

From (2),

$$10x - 50y + 10z = a \quad (1)$$

$$00x + 30y + 10z = b \quad (2)$$

$$30x + 10y + 20z = c \quad (3)$$

$$\text{From (2), } dy = \frac{b - dz}{3} \quad (4)$$

$$\text{Sub (4) into (1), } dx = \frac{5(b - dz)}{3} - dz = a,$$

~~dx~~

$$10x - 50y + 10z = \beta_1 \quad (1)$$

$$00x + 30y + 10z = \beta_2 \quad (2)$$

$$30x + 10y + 20z = \beta_3 \quad (3)$$

$$\text{From (2), } dy = (\beta_2 - dz)/3 \quad (4)$$

$$\text{Sub (4) into (1), } dx = 5\beta_2/3 - 2dz/3 = \beta_1,$$

$$dx = \beta_1 + 5\beta_2/3 - 2dz/3 \quad (5)$$

$$\text{Sub (4), (5) into (3), } 3\beta_1 + 5\beta_2 - 2dz + (\beta_2 - dz)/3 + 2dz = \beta_3,$$

$$-dz/3 + 3\beta_1 + 16\beta_2/3 = \beta_3, \quad -dz = 9$$

$$-dz + 9\beta_1 + 16\beta_2 = \beta_3$$

$$dz = 9\beta_1 + 16\beta_2 - \beta_3 \quad (6)$$

$$\text{Sub (6) into (5)}$$

$$dx = \beta_1 + 5\beta_2/3 - 18\beta_1/3 - 32\beta_2/3 + 2\beta_3/3 \quad (7)$$

$$\text{Sub (6) into (4)}$$

$$dy = \beta_2/3 - 3\beta_1 - 16\beta_2/3 + \beta_3/3$$

$$\vec{\beta} = (\beta_1, \beta_2, \beta_3) = (-15/3\beta_1 - 9\beta_2 + 7/3\beta_3) \vec{x}$$

$$+ (3\beta_1 - 5\beta_2 + 1/3\beta_3) \vec{y}$$

$$+ (9\beta_1 + 16\beta_2 - \beta_3) \vec{z}$$

$$\forall \vec{\beta} \in \mathbb{R}^3: \vec{\beta} \text{ is a linear combination of } \vec{x}, \vec{y} \text{ and } \vec{z}.$$

$$\text{So } \vec{x}, \vec{y} \text{ and } \vec{z} \text{ form a basis.}$$

$$\text{By definition of a basis, } \vec{x}, \vec{y} \text{ and } \vec{z} \text{ form a basis of } \mathbb{R}^3$$

$$\text{ii } \vec{f} = (4, -1, 2) \text{ in the basis } (\vec{x}, \vec{y}, \vec{z})$$

$$\vec{f} = (4, -1, 2)$$

$$\vec{f} = (4, -1, 6) \text{ in the standard basis since}$$

$$\begin{pmatrix} 1 & -5 & -1 \\ 0 & 3 & 1 \\ 3 & 1 & 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 4 \\ -1 \\ 6 \end{pmatrix}$$

$$b_i: 1, e^x, e^{2x}, \dots, e^{nx}$$

$$= 1, 1, 1, \dots, 1 \text{ when } x=0$$

$$1, e, e^2, \dots, e^n \text{ when } x=1$$

$$1, e^2, e^4, \dots, e^{2n} \text{ when } x=2$$

$$\vdots$$

$$1, e^n, e^{2n}, \dots, e^{n^2} \text{ when } x=n$$

$$\text{The linear system of functions is not linearly}$$

$$\text{independent iff } \nexists a_0, a_1, \dots, a_n \in \mathbb{R} \text{ s.t.}$$

$$\exists i: a_i \neq 0 \text{ and } \forall x \in \mathbb{D}: \sum_{i=0}^n a_i f_i(x) = 0 \text{ iff.}$$

$$\nexists \vec{a} \in \mathbb{R}^{n+1}: \vec{a} \neq \vec{0}^{n+1} \text{ and}$$

$$\text{only iff } \nexists \vec{a} \in \mathbb{R}^{n+1}: \vec{a} \neq \vec{0}^{n+1} \text{ and } \vec{f} \cdot \vec{a} = 0$$

Suppose the system of functions is linearly dependent.

Let  $F$  be the  $n \times n$  matrix

$$F = \begin{pmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & e & e^2 & \dots & e^n \\ 1 & e^2 & e^4 & \dots & e^{2n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & e^n & e^{2n} & \dots & e^{n^2} \end{pmatrix}$$

Then there is no  $n$ -vector  $\vec{a} = (a_0, a_1, a_2, \dots, a_n)$  such that  $\exists i: a_i \neq 0$  and  $\vec{f} \cdot \vec{a} = 0^{n+1}$



2 (200604 Q1)

$$F_{n+1} = F_n + F_{n-1} \text{ for } n \geq 2$$

$$F_1 = F_2 = 1$$

$$\vec{u}_n = \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix}, \quad \vec{u}_{n+1} = \begin{pmatrix} F_{n+2} \\ F_{n+1} \end{pmatrix} = \begin{pmatrix} F_{n+1} + F_n \\ F_{n+1} \end{pmatrix}$$

Let  $A$  be a  $2 \times 2$  matrix  $\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$  such that

$$\vec{u}_{n+1} = A \cdot \vec{u}_n$$

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \cdot \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} = \begin{pmatrix} a_{11}F_{n+1} + a_{12}F_n \\ a_{21}F_{n+1} + a_{22}F_n \end{pmatrix} = \begin{pmatrix} F_{n+1} + F_n \\ F_{n+1} \end{pmatrix}$$

By inspection,  $A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$

$$\det A = 1 \times 0 - 1 \times 1 = -1$$

$A$  is invertible iff  $\det A \neq 0$ , so  $A$  is invertible

An eigenvalue and eigenvector of an  $n$ -square matrix  $A$  are a scalar  $\lambda$  and  $n$ -dimensional vector  $\vec{x}$  such that  $A \cdot \vec{x} = \lambda \vec{x}$ .

$$\text{Then } A \cdot \vec{x} = \lambda I \cdot \vec{x} = (\lambda I) \cdot \vec{x}, \quad (A - \lambda I) \vec{x} = \vec{0}$$

$$\det(A - \lambda I) = \det \begin{pmatrix} 1-\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = -\lambda(1-\lambda) - 1 \times 1 = 0$$

$$= \lambda^2 - \lambda - 1 = 0$$

By the quadratic formula,

$$\lambda = \frac{1 \pm \sqrt{5}}{2} \text{ or } \frac{1}{2} \pm \frac{\sqrt{5}}{2}, \quad \lambda_1 = \frac{1}{2} + \frac{\sqrt{5}}{2}, \quad \lambda_2 = \frac{1}{2} - \frac{\sqrt{5}}{2}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \vec{x}_1 = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \vec{x}_1$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ x_1 \end{pmatrix} = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$x_1 = \frac{1}{2} + \frac{\sqrt{5}}{2} x_2, \quad (x_1 + x_2) = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) x_1$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \vec{x}_1 = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \vec{x}_1$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\begin{pmatrix} x_1 + x_2 \\ x_1 \end{pmatrix} = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$\left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) x_1 + x_2 = 0$$

$$x_1 + \left( \frac{1}{2} - \frac{\sqrt{5}}{2} \right) x_2 = 0$$

Solving simultaneously,

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ x_1 \end{pmatrix} = \left( \frac{1}{2} + \frac{\sqrt{5}}{2} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ x_1 \end{pmatrix} = \left( \frac{1}{2} - \frac{\sqrt{5}}{2} \right) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} - \frac{\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

Eigen values and eigenvectors

$$\lambda_1 = \frac{1}{2} + \frac{\sqrt{5}}{2}, \quad \vec{x}_1 = \begin{pmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

$$\lambda_2 = \frac{1}{2} - \frac{\sqrt{5}}{2}, \quad \vec{x}_2 = \begin{pmatrix} \frac{1}{2} - \frac{\sqrt{5}}{2} \\ 1 \end{pmatrix}$$

Let  $S = \begin{pmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & \frac{1}{2} - \frac{\sqrt{5}}{2} \\ 1 & 1 \end{pmatrix}$  Transforms from standard basis to eigenbasis

$$SS^{-1} = I, \quad \begin{pmatrix} \frac{1}{2} + \frac{\sqrt{5}}{2} & \frac{1}{2} - \frac{\sqrt{5}}{2} \\ 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} s_{11}^{-1} & s_{12}^{-1} \\ s_{21}^{-1} & s_{22}^{-1} \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$S^{-1} = \begin{pmatrix} 1 & -\left(\frac{1}{2} + \frac{\sqrt{5}}{2}\right) \\ 1 & \left(\frac{1}{2} + \frac{\sqrt{5}}{2}\right) \end{pmatrix} \text{ "Makes eigenvectors to be the basis"}$$





~~Efficient~~  
c. ~~Firms mix over a larger interval and are more~~  
~~invest more on average when the probability of~~  
~~facing an efficient opponent increases. Since~~  
~~inefficient firms never invest, efficient firms compete~~  
~~only with other efficient firms, and so must~~  
~~compete more aggressively when competition~~  
~~increases.~~

3 (190530 Q1)

$$A = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix}$$

scalar  $\lambda$  and vector  $\vec{v}$  are an eigenvalue and an eigenvector of  $A$  iff  $A \cdot \vec{v} = \lambda \vec{v}$ , iff  $A \vec{v} = \lambda (I \vec{v})$  iff

$$(A - \lambda I) \vec{v} = \vec{0}$$

$$\text{iff } A \cdot \vec{v} = (\lambda I) \cdot \vec{v}$$

$$\text{iff } (A - \lambda I) \cdot \vec{v} = \vec{0}$$

$$\text{iff } \det(A - \lambda I) = 0$$

$$\lambda = 1, A - \lambda I = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{pmatrix} - 1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

$$\det(A - \lambda I) = 1 \det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} - 1 \det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} + 1 \det \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} = 0 - 0 + 0 = 0$$

so  $\lambda = 1$  is an eigenvalue of  $A$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} v_1 + v_2 + v_3 \\ v_1 + v_2 + v_3 \\ v_1 + v_2 + v_3 \end{pmatrix} = \vec{0} \text{ iff } \vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$$

$$v_1 + v_2 + v_3 = 0$$

All  $\vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$  are eigenvectors of  $A$  with eigenvalue

$$\lambda = 1 \text{ iff } v_1 + v_2 + v_3 = 0$$

$$\lambda = 4, A - \lambda I = \begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$\det(A - \lambda I) = -2 \det \begin{pmatrix} -2 & 1 \\ 1 & -2 \end{pmatrix} - 1 \det \begin{pmatrix} 1 & 1 \\ 1 & -2 \end{pmatrix} + 1 \det \begin{pmatrix} 1 & -2 \\ 1 & 1 \end{pmatrix} = -2(3) - 1(-3) + 1(3) = 0$$

so  $\lambda = 4$  is an eigenvalue of  $A$

$$\begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \cdot \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} -2v_1 + v_2 + v_3 \\ v_1 - 2v_2 + v_3 \\ v_1 + v_2 - 2v_3 \end{pmatrix} = \vec{0}$$

$$\text{iff } v_1 = v_2 = v_3$$

All  $\vec{v} = \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix}$  are eigenvectors of  $A$  with eigenvalue

$$\lambda = 4 \text{ iff } v_1 = v_2 = v_3$$

"  $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \text{ and } \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  are eigenvectors of  $A$  that

form a basis of  $\mathbb{R}^3$

$V = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$  is a matrix such that

$$VAV^{-1} = D \text{ for } D = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$V^{-1}VDV^{-1}V = D = V^{-1}AV$$

$V$  can be interpreted as a change of basis matrix from the eigenbasis formed by  $\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \text{ and } \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  to the standard basis.

$$AV = VDV^{-1}V$$

$$V \cdot V^{-1} = I$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} v_{11}^{-1} & v_{12}^{-1} & v_{13}^{-1} \\ v_{21}^{-1} & v_{22}^{-1} & v_{23}^{-1} \\ v_{31}^{-1} & v_{32}^{-1} & v_{33}^{-1} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Solving by calculator,

$$V^{-1} = \begin{pmatrix} -1 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{pmatrix}$$

$$AV = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4096 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1 & 1 & 1 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} -4096 & 4096 & 4096 \\ 1 & 0 & -1 \\ 1 & -1 & 0 \end{pmatrix} = \begin{pmatrix} -4094 & 4095 & 4095 \\ -4095 & 4096 & 4095 \\ -4095 & 4095 & 4096 \end{pmatrix}$$

$\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \text{ and } \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$  are eigenvectors of  $A$  that

form a basis of  $\mathbb{R}^3$ . Let  $V = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix}$  then

$$VDV^{-1} = A \text{ for } D = \begin{pmatrix} 4 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ so } D = V^{-1}AV$$

Informally,  $V^{-1}$  transforms is a transformation from the standard basis to the eigenbasis,  $D$  is the analogue of  $A$  in the eigenbasis, and  $V$  is a transformation of the eigenbasis to the standard basis.

$$\text{Solving by calculator, } V^{-1} = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$$

$$AV = VDV^{-1} = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4096 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \left( \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} \right) = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4096 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 4096 & 4096 & 4096 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 4098 & 4095 & 4095 \\ 4095 & 4098 & 4095 \\ 4095 & 4095 & 4098 \end{pmatrix} = \begin{pmatrix} 1366 & 1365 & 1365 \\ 1365 & 1366 & 1365 \\ 1365 & 1365 & 1366 \end{pmatrix}$$