

(a)  $F_{n+1} = F_n + F_{n-1}$  for  $n \geq 2$

$F_1 = F_2 = 1$

$\vec{u}_n = \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix}$

$\vec{u}_{n+1} = A \vec{u}_n \iff$

$\begin{pmatrix} F_{n+2} \\ F_{n+1} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} \iff$

$\begin{pmatrix} F_{n+1} + F_n \\ F_{n+1} \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} F_{n+1} \\ F_n \end{pmatrix} \iff$

$A = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}$

$\det A = 1 \cdot 0 - 1 \cdot 1 = -1 \neq 0 \Rightarrow A$  is invertible

det

$A\vec{v} = \lambda\vec{v} \Rightarrow (A - \lambda I)\vec{v} = \vec{0} \Rightarrow \det(A - \lambda I) = 0 \Rightarrow$

$\det \begin{pmatrix} 1-\lambda & 1 \\ 1 & -\lambda \end{pmatrix} = -\lambda(1-\lambda) - (1 \cdot 1) = \lambda^2 - \lambda - 1 = 0 \iff$

$\lambda = \frac{1 \pm \sqrt{1+4}}{2} = \frac{1 \pm \sqrt{5}}{2}$

The eigenvalues are  $\lambda_1 = \frac{1+\sqrt{5}}{2}$ ,  $\lambda_2 = \frac{1-\sqrt{5}}{2}$

$A\vec{v}_1 = \lambda_1\vec{v}_1 \iff \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 1+\sqrt{5} \\ 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \iff$

$\begin{pmatrix} v_1 + v_2 \\ v_1 \end{pmatrix} = \begin{pmatrix} 1+\sqrt{5} \\ 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \iff v_1 = \frac{1+\sqrt{5}}{2} v_2 \iff$

$\vec{v}_1 = \begin{pmatrix} 1+\sqrt{5} \\ 2 \end{pmatrix}$

$A\vec{v}_2 = \lambda_2\vec{v}_2 \iff \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 1-\sqrt{5} \\ 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \iff$

$\begin{pmatrix} v_1 + v_2 \\ v_1 \end{pmatrix} = \begin{pmatrix} 1-\sqrt{5} \\ 2 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \iff v_1 = \frac{1-\sqrt{5}}{2} v_2 \iff$

$\vec{v}_2 = \begin{pmatrix} 1-\sqrt{5} \\ 2 \end{pmatrix}$

ii The eigenvectors of  $A$  is  $\begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} \\ 2 & 2 \end{pmatrix}$

$\vec{u}_{2020} = A^{2018} \vec{u}_2 = \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} \\ 2 & 2 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

denote this eigenvectors  $\vec{v}_1, \vec{v}_2$

compute  $\vec{v}_1^{-1}$  by Gauss-Jordan elimination.

$\begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1 & 0 \\ 2 & 2 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow R_2 - \frac{2}{1+\sqrt{5}} R_1} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1 & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix}$

$\begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1 & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - \frac{1}{1+\sqrt{5}} R_2} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1 & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix}$

$\begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1 & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow \frac{1}{1+\sqrt{5}} R_1} \begin{pmatrix} 1 & \frac{1-\sqrt{5}}{1+\sqrt{5}} & \frac{1}{1+\sqrt{5}} & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix}$

$\begin{pmatrix} 1 & \frac{1-\sqrt{5}}{1+\sqrt{5}} & \frac{1}{1+\sqrt{5}} & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow \frac{1}{1+\sqrt{5}} R_2} \begin{pmatrix} 1 & \frac{1-\sqrt{5}}{1+\sqrt{5}} & \frac{1}{1+\sqrt{5}} & 0 \\ 0 & 0 & -\frac{2}{1+\sqrt{5}} & 1 \end{pmatrix}$

$\vec{v}_1^{-1} = \begin{pmatrix} \frac{1}{\sqrt{5}} & -\frac{1-\sqrt{5}}{2\sqrt{5}} \\ -\frac{1}{\sqrt{5}} & \frac{1+\sqrt{5}}{2\sqrt{5}} \end{pmatrix}$

$\vec{u}_{2020} = A^{2018} \vec{u}_2$

$= \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & -\frac{1-\sqrt{5}}{2} & \frac{1+\sqrt{5}}{2} & 0 \\ -1 & \frac{1+\sqrt{5}}{2} & 0 & -\frac{1-\sqrt{5}}{2} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\vec{u}_{2020} = \begin{pmatrix} 1 & 0 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1+\sqrt{5} & 1-\sqrt{5} & 1+\sqrt{5} & 0 \\ 1-\sqrt{5} & 1+\sqrt{5} & 0 & 1-\sqrt{5} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$\vec{u}_{2020} = \begin{pmatrix} 1 & 0 \end{pmatrix} A^{2018} \vec{u}_2$

$= \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$= \frac{1}{\sqrt{5}} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

bi the equations are polynomials, so each is  $C^1$  (hence  $C^1$  in an open ball around  $(0,1,0,1)$ )

$x^5 + 3y^2 + z^2 + 2x \mid 0,1,0,1 = 0$

$2xy^2 + 3z^2 + 1 \mid 0,1,0,1 = 0$

$(0,1,0,1)$  solves the system of equations.

$D_{x,y} \vec{F} = \begin{pmatrix} 5x^4 + 2z & 2xy \\ 2y^2 + 3z^2 & 4xy \end{pmatrix}$

$\det D_{x,y} \vec{F}(0,1,0,1) = \det \begin{pmatrix} 2 & 0 \\ 3 & 0 \end{pmatrix} = 0 \cdot 0 - 0 = 0 \Rightarrow$

$D_{x,y} \vec{F}(0,1,0,1)$  is not invertible, so the IFT is not applicable to define  $x, y$  as a function of  $z, t$  in a neighbourhood of  $(0,1,0,1)$ .

ii  $\det D_{x,y} \vec{F}(0,1,-1,1) = \det \begin{pmatrix} 2 & -2 \\ 3 & 0 \end{pmatrix} = 6 \neq 0$

compute  $D_{x,y} \vec{F}$  by Gauss-Jordan elimination

$\begin{pmatrix} 2 & -2 & 1 & 0 \\ 3 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - \frac{2}{3} R_2} \begin{pmatrix} 2 & -2 & 1 & 0 \\ 3 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_1 \leftarrow \frac{1}{3} R_1} \begin{pmatrix} \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} & 0 \\ 3 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \leftarrow \frac{1}{3} R_2} \begin{pmatrix} \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} & 0 \\ 1 & 0 & 0 & \frac{1}{3} \end{pmatrix} \xrightarrow{R_1 \leftarrow R_1 - \frac{2}{3} R_2} \begin{pmatrix} 0 & -\frac{2}{3} & \frac{1}{3} & -\frac{2}{9} \\ 1 & 0 & 0 & \frac{1}{3} \end{pmatrix} \xrightarrow{R_1 \leftarrow -\frac{3}{2} R_1} \begin{pmatrix} 0 & 1 & -\frac{1}{2} & \frac{1}{3} \\ 1 & 0 & 0 & \frac{1}{3} \end{pmatrix}$

$$\left( \begin{array}{cc|cc} 1 & 0 & 0 & 1/3 \\ 0 & 1 & -1/2 & 1/3 \end{array} \right)$$

$$D_{x,y}^{-1} \vec{F} = \begin{pmatrix} 0 & 1/3 \\ -1/2 & 1/3 \end{pmatrix}$$

$$D_{z,t} \vec{F} = \begin{pmatrix} y^2 + 2z & 2x \\ 2xz & 1 \end{pmatrix}$$

$$D_{z,t} \vec{F}(0, 1, -1, 1) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\begin{aligned} D_{z,t} \vec{g}(-1, 1) &= -D_{x,y}^{-1} \vec{F}(0, 1, -1, 1) D_{z,t} \vec{F}(0, 1, -1, 1) \\ &= -\begin{pmatrix} 0 & 1/3 \\ -1/2 & 1/3 \end{pmatrix} \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \\ &= -\begin{pmatrix} 0 & 1/3 \\ 1/2 & 1/3 \end{pmatrix} \end{aligned}$$

$$\partial x / \partial s = 0, \quad \partial x / \partial t = 1/3, \quad \partial y / \partial s = 1/2, \quad \partial y / \partial t = 1/3$$



2a:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is concave iff for all  $\vec{x}, \vec{x}' \in \mathbb{R}^n$ , for all  $t \in (0, 1)$ ,  $f(t\vec{x} + (1-t)\vec{x}') \geq tf(\vec{x}) + (1-t)f(\vec{x}')$ .

ii:  $f$  is concave  $\Rightarrow \forall \vec{x}, \vec{x}' \in \mathbb{R}^n, t \in (0, 1)$ :  
 $f(t\vec{x} + (1-t)\vec{x}') \geq tf(\vec{x}) + (1-t)f(\vec{x}') \Rightarrow$   
 $\forall \dots f(t\vec{x} + (1-t)\vec{x}') \geq t \min\{f(\vec{x}), g(\vec{x}')\} +$   
 $(1-t) \min\{f(\vec{x}'), g(\vec{x}')\}$

$g$  is concave  $\Rightarrow \forall \dots g(t\vec{x} + (1-t)\vec{x}') \geq$   
 $t \min\{f(\vec{x}), g(\vec{x}')\} + (1-t) \min\{f(\vec{x}'), g(\vec{x}')\}$

$\Rightarrow \forall \dots \min\{f(t\vec{x} + (1-t)\vec{x}'), g(t\vec{x} + (1-t)\vec{x}')\} \geq$   
 $t \min\{f(\vec{x}), g(\vec{x}')\} + (1-t) \min\{f(\vec{x}'), g(\vec{x}')\} \Rightarrow$   
 $\min\{f, g\}$  is concave.

iii:  $f(x, y) = \ln x + 3 \ln y \quad (x > 0, y > 0)$

$df(x, y) = (1/x, 3/y)$

$D^2f(x, y) = \begin{pmatrix} -x^{-2} & 0 \\ 0 & -3y^{-2} \end{pmatrix}$

$\text{tr} D^2f(x, y) = -x^{-2} - 3y^{-2} < 0$

$\det D^2f(x, y) = 3x^{-2}y^{-2} > 0$

Both eigenvalues of  $D^2f(x, y)$  are strictly negative,  $D^2f(x, y)$  is negative definite,  $f$  is strictly concave.

$g(x, y) = xy^3 \quad (x, y \in \mathbb{R})$

$Dg(x, y) = (y^3, 3xy^2)$

$D^2g(x, y) = \begin{pmatrix} 0 & 3y^2 \\ 3y^2 & 6xy \end{pmatrix}$

$\text{tr} D^2g(x, y) = 6xy$

$\det D^2g(x, y) = -9y^4 < 0$

The eigenvalues have different signs,  $D^2g(x, y)$  is indefinite,  $g$  is not concave.

$h(x, y) = -x^2 - 3y^2 + 5xy \quad (x, y \in \mathbb{R})$

$Dh(x, y) = (-2x + 5y, -6y + 5x)$

$D^2h(x, y) = \begin{pmatrix} -2 & 5 \\ 5 & -6 \end{pmatrix}$

$\text{tr} D^2h(x, y) = -8 < 0$

$\det D^2h(x, y) = 12 - 25 = -13 < 0$

The eigenvalues have different signs,  $D^2h(x, y)$  is indefinite,  $h$  is not concave.

bi:  $\mu_{ux} = \partial u / \partial x = 1/x$ ,  $\mu_{uy} = \partial u / \partial y = 3/y$   
 Marginal utilities approach infinity as the amount of each good approaches zero, so positivity constraints never bind.

ii:  $\max_{x, y} \ln x + 3 \ln y \quad \text{s.t.}$

$K: x + 4y \leq 20$

$L: 4x + y \leq 20$

$\mathcal{L} = \ln x + 3 \ln y - \lambda_K(x + 4y - 20) - \lambda_L(4x + y - 20)$

FOC<sub>x</sub>:  $1/x - \lambda_K - 4\lambda_L = 0$

FOC<sub>y</sub>:  $3/y - 4\lambda_K - \lambda_L = 0$

CK:  $\lambda_K \geq 0, x + 4y \leq 20, \lambda_K(x + 4y - 20) = 0$

CL:  $\lambda_L \geq 0, 4x + y \leq 20, \lambda_L(4x + y - 20) = 0$

$\lambda_K$  is the marginal utility from an additional unit of capital,  $\lambda_L$  is the marginal utility from an additional unit of labour.

iii: Suppose  $\lambda_K > 0, \lambda_L = 0$ . By FOC<sub>x</sub>, FOC<sub>y</sub>,  
 $1/x = \lambda_K, 3/y = 4\lambda_K \Rightarrow 3/y = 4/x \Rightarrow x = 4/3 y$   
 By CK,  $x + 4y = 20 \Rightarrow 16/3 y = 20 \Rightarrow y = 60/16$   
 $\Rightarrow x = 30/8 = 15/4 \Rightarrow x + 4y = 15/4 + 15 = 63/4 > 20$ ,  
 CL is violated. There is no solution where  $\lambda_K > 0, \lambda_L = 0$ .

Suppose  $\lambda_K = 0, \lambda_L > 0$ . By FOC<sub>x</sub>, FOC<sub>y</sub>,  
 $1/x = 4\lambda_L, 3/y = \lambda_L \Rightarrow 1/x = 12/y \Rightarrow x = 1/12 y$   
 By CL,  $4x + y = 20 \Rightarrow 4/12 y + y = 20 \Rightarrow y = 15$   
 $\Rightarrow x = 5/4 \Rightarrow 4x + y = 5 + 15 = 20$ , CK is  
 violated. There is no solution where  $\lambda_K = 0, \lambda_L > 0$ .

Suppose  $\lambda_K = \lambda_L = 0$ . By FOC<sub>x</sub>,  $1/x = 0$ ,  $x$  is undefined. There is no solution where  $\lambda_K = \lambda_L = 0$ .

Suppose  $\lambda_K, \lambda_L > 0$ . By CL, CK,  $x + 4y = 20$ ,  
 $4x + y = 20 \Rightarrow x = y = 4$ . By FOC<sub>x</sub>, FOC<sub>y</sub>,  
 $1/4 - \lambda_K - 4\lambda_L = 0, 3/4 - 4\lambda_K - \lambda_L = 0 \Rightarrow$   
 $1/5 - 3\lambda_K + 3\lambda_L = 0 \Rightarrow \lambda_K - \lambda_L = 1/6 \Rightarrow$   
 $1/4 - (\lambda_K + 1/6) - 4\lambda_L = 0 \Rightarrow 1/12 - 5\lambda_L = 0 \Rightarrow \lambda_L = 1/60$   
 $\Rightarrow \lambda_K = 1/2 = 5\lambda_L \Rightarrow \lambda_K = 1/60 \Rightarrow \lambda_L = 1/60$   
 KT-FOCs are uniquely satisfied at  $(x, y) = (4, 4)$  with  $\lambda_K = 1/60, \lambda_L = 1/60$ .

iv: From (aiii),  $f$  is the objective function is concave. Each constraint is linear hence convex. The optimisation problem is convex. So KT-FOCs are sufficient for a maximum. The constraint set has non-empty interior, so the KT-FOCs are also necessary. The unique solution corresponds to a unique global maximum. The solution is optimal.

v: The analysis would be unchanged.  $\ln x + 3 \ln y = \ln(xy^3)$ . It is a monotonic transformation, so the maxima of  $\ln x + 3 \ln y$  and  $xy^3$  coincide.





3a  $C_1 \not\geq C_2 \Leftrightarrow$  (by definition of  $\geq$ )

$C_1 \geq C_2$  and  $C_2 \not\geq C_1 \Leftrightarrow$  (by independence)

$$pC_1 + (1-p)C \geq pC_2 + (1-p)C$$

and  $pC_2 + (1-p)C \not\geq pC_1 + (1-p)C \Leftrightarrow$  (by definition)

$$pC_1 + (1-p)C > pC_2 + (1-p)C$$

$C_1 \sim C_2 \Leftrightarrow$  (by definition of  $\sim$ )

$C_1 \geq C_2$  and  $C_2 \geq C_1 \Leftrightarrow$  (by independence)

$$pC_1 + (1-p)C \geq pC_2 + (1-p)C$$

and  $pC_2 + (1-p)C \geq pC_1 + (1-p)C \Leftrightarrow$  (by definition)

$$pC_1 + (1-p)C \sim pC_2 + (1-p)C$$

$C_1 \geq C_2 \Rightarrow$  (by independence)

$$pC_1 + (1-p)C_3 \geq pC_2 + (1-p)C_3$$

$C_3 \geq C_4 \Rightarrow$  (by independence)

$$pC_2 + (1-p)C_3 \geq pC_2 + (1-p)C_4$$

$\Rightarrow$  (by transitivity)

$$pC_1 + (1-p)C_3 \geq pC_2 + (1-p)C_4$$

$$b. C_1 = (3/5, 3/5, 3/5, 3/5, 3/5)$$

$$C_2 = (1/5, 7/5, 0/5, 5/5, 2/5)$$

$C_1$  is a mean-preserving spread of  $C_2$  obtained by reallocating  $2/5$  units of probability mass from outcome -1 to each of outcome -2 and outcome 0 and by reallocating  $1/5$  units of probability mass from outcome +1 to each of outcome 0 and outcome +2.

$C_2$  SSDs  $C_1$ , any risk averse expected utility maximiser prefers  $C_2$  to  $C_1$ .

c. let  $C_p$  and  $C_f$  respectively denote the lottery in poor weather and the lottery in fine weather.  $C_p \succ_{FOSD} C_f$  iff  $C_p$  allocates lower probabilities to worse outcomes. This is iff the cumulative distribution function associated with  $C_f$  is weakly less than that of  $C_p$ , for all  $x$  ~~with a possible outcome~~.  
i.e.  $\sum_{x \leq x} p_i \leq \sum_{x \leq x} p_i$

This is iff  $p_1 \leq 1/3$ ,  $p_1 + p_2 \leq 1/3 + 1/3$ ,  $p_1 + p_2 + p_3 \leq 1/3 + 1/3 + 1/3$ . CR is not monotonically increasing iff it is not the case that  $p_1 \leq p_2 \leq p_3$ . So, for example  $p_1 = 0.2$ ,  $p_2 = 0.41$ ,  $p_3 = 0.39$  satisfies both requirements.

ii Suppose CR is monotonically increasing, i.e.

$$p_1/1/3 \leq p_2/1/3 \leq p_3/1/3 \Leftrightarrow p_1 \leq p_2 \leq p_3. \text{ Given}$$

that  $p_1 + p_2 + p_3 = 1$ ,  $p_3 \geq 1/3$ , otherwise  $p_1 + p_2 > 2/3$ .

$p_1 \leq p_2 \leq p_3 < 1/3$  so  $p_1 + p_2 + p_3 < 1$ . Then  $p_1 + p_2 \leq 2/3$ .

and  $p_1 \leq p_2$  so  $p_1 \leq 1/3$  otherwise  $p_2 \geq p_1 > 1/3$

so  $p_1 + p_2 \geq 2/3$ . So we have  $p_1 \leq 1/3$ ,  $p_1 + p_2 \leq 2/3$ ,

$p_1 + p_2 + p_3 = 1$ . The associated cdf is  $F_f(x)$

$$= \begin{cases} 0 & \text{for } x < \pi_1 \\ p_1 & \text{for } \pi_1 \leq x < \pi_2 \\ p_1 + p_2 & \text{for } \pi_2 \leq x < \pi_3 \\ 1 & \text{for } x \geq \pi_3 \end{cases}$$

all other  $x$ . This is weakly less than the cdf for  $C_p$  for all  $x$ , which is  $F_p(x) = 0$  for  $x < \pi_1$ ,  $1/3$  for  $\pi_1 \leq x < \pi_2$ ,  $2/3$  for  $\pi_2 \leq x < \pi_3$ , 1 for all other  $x$ . So  $C_f$  FOSDs  $C_p$  if CR is monotonically increasing.





4. When effort is observable, principal P offers a contract that just satisfies agent A's participation constraint PC. Such a contract has the form  $(w, e)$ . Any candidate optimum that strictly satisfies PC fails to deviation to a less generous wage  $w$  by sufficiently small amount  $\varepsilon$ .

Suppose P induces  $e=2$ . PC binds,  $u(w, e)=0 \Leftrightarrow \sqrt{w}-2=0 \Leftrightarrow w=4$ . Then P has expected gross (of wage) profit  $E\pi = \frac{1}{4} \cdot 4 + \frac{3}{4} \cdot 40 = 31$  and expected net profit  $E\pi - w = 31 - 4 = 27$ .

Suppose P induces  $e=0$ . PC binds,  $u(w, e)=0 \Leftrightarrow \sqrt{w}-e=0 \Leftrightarrow w=0$ . Then P has  $E\pi = \frac{3}{4} \cdot 4 + \frac{1}{4} \cdot 40 = 13$  and  $E\pi - w = 13$ .

So it is optimal to induce  $e=2$  and P optimally does so by offering contract  $(w, e) = (4, 2)$ .

6. When effort is unobservable, a contract to induce  $e$  must satisfy PC and IC. To induce  $e=0$ , the optimal contract is unchanged from the case with observable effort because IC does not bind. Under a fixed wage, given costly effort,  $e=0$  is strictly incentive compatible, so P induces  $e=0$  with fixed wage schedule  $(w_L, w_H) = (0, 0)$ .

To induce in inducing  $e=2$ , both PC and IC bind. Any candidate optimum such that PC does not bind fails to deviation by reducing  $w_L$  by small amount  $\varepsilon$  such that PC remains satisfied. Such deviation loosens IC because  $\frac{\partial u}{\partial w} > 0$  and yields higher (lower) expected wage hence higher (lower) expected profit.

Any candidate optimum such that IC does not bind fails to deviation consisting in (1) a small mean-preserving (given  $\frac{1}{4}, \frac{3}{4}$  probabilities) contraction of  $w_L, w_H$ , one which continues to satisfy IC given that it is initially "slack" and loosens PC given concavity of  $u$  in  $w$ , and (2) a small decrease in each of  $w_L$  and  $w_H$ , which satisfies IC and PC given both are "slack".

$$PC: \frac{1}{4}(\sqrt{w_L}-2) + \frac{3}{4}(\sqrt{w_H}-2) \geq 0$$

$$IC: \frac{1}{4}(\sqrt{w_L}-2) + \frac{3}{4}(\sqrt{w_H}-2) \geq \frac{3}{4}(\sqrt{w_L}) + \frac{1}{4}(\sqrt{w_H})$$

Both bind.

$$PC \Rightarrow \frac{1}{4}\sqrt{w_L} + \frac{3}{4}\sqrt{w_H} = 2$$

$$IC \Rightarrow \frac{1}{4}\sqrt{w_L} + \frac{3}{4}\sqrt{w_H} - 2 = \frac{3}{4}\sqrt{w_L} + \frac{1}{4}\sqrt{w_H}$$

$$\Rightarrow \frac{1}{2}\sqrt{w_H} - 2 = \frac{1}{2}\sqrt{w_L} \Rightarrow \sqrt{w_H} = \sqrt{w_L} + 4$$

$$\Rightarrow \sqrt{w_L} + 3 = 2 \text{ (reject)}$$

$$\Rightarrow \sqrt{w_L} + 3 = 2 \text{ (reject)}$$

So the positivity constraint on  $w_L$  will bind, then IC binding implies  $\sqrt{w_H} = 4 \Rightarrow w_H = 16$ . The contract will strictly satisfy PC but there is no strictly profitable deviation because the positivity constraint binds.

Under this contract to induce high wage,  $E(\pi - w) = \frac{1}{4}(4-0) + \frac{3}{4}(40-16) = 1+8 = 9 > 13$ . #

It remains optimal to induce high effort. P offers  $(w_L, w_H) = (0, 16)$  and suffers agency cost  $27-19 = 8$ . This cost is incurred because a variable wage scheme is necessary to induce high effort, i.e. make it incentive compatible. Then A is made to bear risk, but A is risk averse and must be compensated for risk-bearing with a higher expected wage. This generally holds but in this case expected wage is also pushed up by the positivity constraint on wage.

If the machine were bad P proposes  $w=0$  because profit is independent of effort, so P is better off inducing low effort (because effort is costly to A and A must be compensated), and P optimally induces low effort with the just incentive compatible fixed wage  $w=0$  found in (a).

If the machine were not bad, again to induce low effort, the optimal contract is the fixed wage contract  $(w_L, w_H) = (0, 0)$ .  $E(\pi - w) = \frac{2}{3}(4-0) + \frac{1}{3}(40-0) = 16$ .

To induce high effort, again PC and IC bind, so the optimal contract is  $(w_L, w_H) = (0, 16)$ . IC and positivity constraint bind.

$$IC: \sqrt{w_H} - 2 \geq \frac{2}{3}\sqrt{w_L} + \frac{1}{3}\sqrt{w_H}$$

$$\Rightarrow \sqrt{w_H} - 2 = \frac{1}{3}\sqrt{w_H} \Rightarrow \frac{2}{3}\sqrt{w_H} = 2 \Rightarrow w_H = 9,$$

$$w_L = 0$$

$$E(\pi - w) = 40 - 9 = 31$$

But in ex ante expectation, when the state of the machine is unknown,  $E(\pi - w) = \frac{1}{4}(16) + \frac{3}{4}(31) = 10\frac{1}{4} = 27\frac{1}{4}$

From (b), under unobservable effort, maximum net profit without inspection is 19. P is

Willing to pay up to  $27\frac{1}{4} - 19 = 8\frac{1}{4}$  for inspection.

~~P induces~~ optimally induces  $e=2$  when either  
(1) it is known that the machine is not bad  
or (2) no inspection has happened. In (1), ~~there~~  
there is no agency cost because the outcome  
is certain and A is not made to bear risk.  
Though the wage schedule offered is still  
variable and expected wage is higher than  
in the observable effort case, it is lower  
than in (2) because ~~the~~ A faces no risk with  
 $e=2$ .