

MathMatrixPack package documentation

**Wolfram Mathematica[®] 10.0 package for matrices with labeled
entries**

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1 Formatting rules

This section presents the following formatting rules in the kernel of Mathematica when Package MathMatrixPack is used.

1.1 Trigonometric functions

```
1 $PrePrint = # /. {
2   Csc[xArgument_] :> 1/Defer @ Sin[xArgument],
3   Sec[xArgument_] :> 1/Defer @ Cos[xArgument],
4   Tan[xArgument_] :> Defer @ Sin[xArgument]/Defer @ Cos[xArgument],
5   Cot[xArgument_] :> Defer @ Cos[xArgument]/Defer @ Sin[xArgument]
6 } &;
7
8 Unprotect[Cos, Sin];
9 Format[Cos[xArgument_]] := Subscript[c, xArgument]
10 Format[Sin[xArgument_]] := Subscript[s, xArgument]
11 Protect[Cos, Sin];
```

This piece of code modifies the default display notation for trigonometric functions in Mathematica: $\sin(*)$, $\cos(*)$, $\tan(*)$, $\cot(*)$, $\sec(*)$, $\csc(*)$ are denoted respectively as s_* , c_* , s_*/c_* , c_*/s_* , $1/c_*$ and $1/s_*$ for any (assigned or unassigned) variable used in the code.

1.2 Derivatives

```
1 Format[Subscript[ Subscript[xArgument_, xIndexes1__], xIndexes2__]'[t_]]
2   :=
3   Subscript[ Subscript[ Overscript[xArgument, "."], xIndexes1],
4     xIndexes2][t]
5 Format[Subscript[ Subscript[xArgument_, xIndexes1__], xIndexes2__]''[t_]]
6   :=
7   Subscript[ Subscript[ Overscript[xArgument, ".."], xIndexes1],
8     xIndexes2][t]
9 Format[Subscript[xArgument_, xIndexes1__]'[t_]] :=
10  Subscript[ Overscript[xArgument, "."], xIndexes1][t]
```

```

7 Format[Subscript[xArgument_, xIndexes1__]' '[t_]] :=
8   Subscript[ Overscript[xArgument, ".."], xIndexes1][t]
9 Format[xArgument_' [t_]] :=
10   Overscript[xArgument, "."][t]
11 Format[xArgument_'' [t_]] :=
12   Overscript[xArgument, ".."][t]
13
14 SymbolReplacements = {
15   Subscript[ Subscript[xBase_, xIndexes__], xIndexes2__]' [t] ->
16     Subscript[ Subscript[ Overscript[xBase, "."], xIndexes], xIndexes2],
17   Subscript[ Subscript[xBase_, xIndexes__]' '[t] ->
18     Subscript[Subscript[ Overscript[xBase, ".."], xIndexes], xIndexes2],
19   Subscript[xBase_, xIndexes__]' [t] ->
20     Subscript[ Overscript[xBase, "."], xIndexes],
21   Subscript[xBase_, xIndexes__]' '[t] ->
22     Subscript[ Overscript[xBase, ".."], xIndexes],
23   xVariable_' [t] -> Overscript[xVariable, "."],
24   xVariable_'' [t] -> Overscript[xVariable, ".."],
25   xVariable_[t] -> xVariable
26 };

```

This piece of code modifies the display notation for first and second order time derivatives: $\zeta'[t]$ and $\zeta''[t]$ are denoted respectively as $\dot{\zeta}[t]$ and $\ddot{\zeta}[t]$.

`SymbolReplacements` is a list of rules for formatting first and second order time derivatives. Whenever this list of rules is used, $\zeta'[t]$ and $\zeta''[t]$ will be replaced respectively by $\dot{\zeta}$ and $\ddot{\zeta}$.

1.3 Round-off rules

```

1 RoundOffRules = {
2   xNumber_?NumericQ /; Abs[xNumber] < 10^-12 -> 0,
3   xNumber_?NumericQ /; Abs[xNumber - 1] < 10^-12 -> 1,
4   xNumber_?NumericQ /; Abs[xNumber + 1] < 10^-12 -> -1
5 };

```

RoundOffRules is a list of rules for formatting numbers. Whenever this list of rules is used, numbers in the ranges $]-10^{-12}, +10^{-12}[$ and $]1-10^{-12}, 1+10^{-12}[$ will be displayed as 0 and 1, respectively.

1.4 Displaying matrices

```

1 SMatrixForm[xA_Association, xL_: Automatic] :=
2   If[ KeyExistsQ[xA, "Column_Labels"],
3     MatrixForm[
4       xA["Matrix"],
5       TableHeadings -> ({xA["Row_Labels"], xA["Column_Labels"]} /.
6         SymbolReplacements),
7       TableAlignments -> xL
8     ],
9     MatrixForm[
10      xA["Matrix"],
11      TableHeadings -> ({xA["Row_Labels"], None} /. SymbolReplacements),
12      TableAlignments -> xL
13    ]

```

```

1 STableForm[xA_Association, xL_: Left] :=
2   If[ KeyExistsQ[xA, "Column_Labels"],
3     TableForm[
4       xA["Matrix"],
5       TableHeadings -> ({xA["Row_Labels"], xA["Column_Labels"]} /.
6         SymbolReplacements),
7       TableAlignments -> xL
8     ],
9     TableForm[
10      xA["Matrix"],
11      TableHeadings -> ({xA["Row_Labels"], None} /. SymbolReplacements),
12      TableAlignments -> xL
13    ]

```

`SMatrixForm` and `STableForm` extend the application of the built-in functions `MatrixForm` and `TableForm` to matrices given by `Association` elements.

2 General purpose functions

This section presents some general purpose functions that can be used for other applications than the modelling of multibody systems.

2.1 Set complement

```
1 SetComplement[xMainSet_, xDiffSet_] :=
2   Select[xMainSet, Not[MemberQ[xDiffSet, #]] &]
```

`SetComplement` returns the elements of the list `xMainSet` that are not in `xDiffSet` in the same order of occurrence in `xMainSet` (unlike the built-in function `Complement` that does the same operation but sorts the output list).

2.2 Delete redundant expressions

```
1 RedundantElim[xX_] := DeleteDuplicates @ (DeleteCases[Simplify @ xX, 0])
   ;
```

`RedundantElim` deletes all repeated elements and all exact zeros (with head `Integer`) of a list.

2.3 Simplify Associations

```
1 SSimplify[xA_Association] := Association @
2   MapThread[#1 -> #2 &, {First /@ (Normal @ xA), Simplify@(Last /@ (
   Normal @ xA))}, 1]
3
4 SSimplify[xX_] := Simplify[xX]
```

`SSimplify` is an extension of the built-in function `Simplify` applicable to `Association` elements.

2.4 Replacements in Associations

```
1 SReplaceRepeated[xA_Association, xL_List] :=
2   Association @ MapThread[ #1 -> #2 &, {
3     First /@ (Normal@xA),
4     ReplaceRepeated[(Last /@ (Normal @ xA)), xL]
5   }, 1]
6
7 SReplaceRepeated[xX_, xL_List] :=
8   ReplaceRepeated[xX, xL]
9
10 SReplaceFullSimplify[xA_Association, xRules_List] :=
11   Association @ MapThread[ #1 -> #2 &, {
12     First /@ (Normal @ xA),
13     FullSimplify[ FullSimplify[ Expand[(Last /@ (Normal @ xA)) //.
14       xRules] //. xRules] //. xRules]
15   }, 1]
16
17 SReplaceFullSimplify[xX_, xRules_List] :=
18   FullSimplify[ FullSimplify[ Expand[(Flatten @ {xX}) //. xRules] //.
19     xRules] //. xRules]
20
21 SReplaceSimplify[xA_Association, xRules_List] :=
22   Association @ MapThread[ #1 -> #2 &, {
23     First /@ (Normal @ xA),
24     Simplify[ Simplify[ Expand[(Last /@ (Normal @ xA)) //. xRules] //.
25       xRules] //. xRules]
26   }, 1]
27
28 SReplaceSimplify[xX_, xRules_List] :=
29   Simplify[ Simplify[ Expand[(Flatten @ {xX}) //. xRules] //. xRules]
30     //. xRules]
```

SReplaceRepeated is an extension of the built-in function ReplaceRepeated applicable to Association elements.

SReplaceFullSimplify and SReplaceSimplify are functions that simultaneously perform replacements and simplify the resulting expressions. They apply the built-in functions ReplaceRepeated, Expand and FullSimplify or Simplify to the corresponding expressions (normally List or Association elements).

2.5 Rename keys and values in Associations

```

1 SRename[xIn_Association, xNamingRules_, xExtraRules_: {}] :=
2   Association @ MapThread[ #1 -> #2 &, {
3     If[Head[#] === String,
4       StringReplace[#, xNamingRules], #] & /@ (First /@ Normal @ (xIn)),
5     Map[SReplaceRepeated[#, xExtraRules] &, Map[SReplaceRepeated[#,
6       xNamingRules] &,
7       Map[SReplaceRepeated[#, xExtraRules] &, (Last /@ Normal @ xIn), All
          ], All], All]
          }, 1]

```

SRename[xIn, xNamingRules] replaces, according to xNamingRules, string occurrences both in the keys and values of the Association element xIn.

SRename[xIn, xNamingRules, xExtraRules] also applies replacements according to xExtraRules to the values of the Association element xIn.

2.6 List variables in expressions

```

1 GetVariables[xX_List, xExcept_List: {}] :=
2   Complement[ DeleteDuplicates @ Cases[xX, xVariable_[t], Infinity],
3     xExcept]
4
5 GetVariables[xX_Association, xExcept_List: {}] :=
6   Complement[ DeleteDuplicates @ Cases[xX["Matrix"], xVariable_[t],
7     Infinity], xExcept]

```

GetVariables returns a list of all time dependent variables in a given symbolic expression xX (which can be either a List or an Association). With the optional argument xExcept_List the user can list the variables that must not be listed in the output.

```

1 HeadList = {

```

```

2 Or, And,
3 Equal, Unequal, Inequality
4 Less, LessEqual,
5 Greater, GreaterEqual
6 };
7
8 GetAllVariables[xNumber_?NumericQ] :=
9   Sequence[]
10
11 GetAllVariables[{}] :=
12   Sequence[]
13
14 GetAllVariables[xRelationalOperator_] /; MemberQ[HeadList,
15   xRelationalOperator] :=
16   Sequence[]
17
18 GetAllVariables[x_List] :=
19   DeleteDuplicates @ (Flatten @ (Union @ (GetAllVariables[#] & /@ x)))
20
21 GetAllVariables[Derivative[xNumber_Integer][xFunction_][xArgument_]] :=
22   Module[{xVariable},
23     If[MemberQ[Attributes[xFunction], NumericFunction] || MemberQ[
24       HeadList, xFunction],
25       (*-TRUE-*)
26       xVariable = GetAllVariables[{xArgument}],
27       (*-FALSE-*)
28       xVariable = Derivative[xNumber][xFunction][xArgument]
29     ];
30   ]
31
32 GetAllVariables[xFunction_Symbol[xArgument_]] :=
33   Module[{xVariable},
34     If[MemberQ[Attributes[xFunction], NumericFunction] || MemberQ[
35       HeadList, xFunction],

```



```

34      (*-TRUE-*)
35      xVariable = GetAllVariables[{xArgument}],
36      (*-FALSE-*)
37      xVariable = xFunction[xArgument]
38  ];
39  xVariable
40  ];
41
42  GetAllVariables[xOther_] :=
43  xOther

```

`GetAllVariables` returns a list of all symbolic variables (both time dependent variables and non-numeric parameters) in a given symbolic expression.

3 Matrix calculus

In package `MathMatrixPack`, matrices must have row and column labels in order to perform correctly the operations of matrix sum/assemble and matrix multiplication. Thus, in this package a matrix is represented by an `Association` element with 3 keys:

- "Matrix": a two dimensional array (`List` element) representing the matrix itself.
- "RowLabels": an ordered `List` providing the indexes of the respective rows of the declared matrix.
- "ColumnLabels": an ordered `List` providing the indexes of the respective columns of the declared matrix.

3.1 Sum, assemble and partitioning of matrices - `AngleBracket` operator

Wolfram Mathematica has some operators without built-in meanings. In `MathMatrixPack`, the operator `AngleBracket`, displayed as $\langle X, Y, \dots \rangle$, is used to perform the operations of sum, assemble and partitioning of matrices. The definitions for this operator are shown in the following piece of code:

```

1  Matrix2Rule[xA_Association] /; (ArrayDepth[xA["Matrix"]] > 1) :=
2  Association @ Flatten @ MapThread[ (#1 -> #2) &, {

```

```

3   Outer[{#1, #2} &, xA["Row_Labels"], xA["Column_Labels"]],
4   xA["Matrix"]
5   }, 2]
6
7 Matrix2Rule[xA_Association] :=
8   Association @ Flatten @ MapThread[ (#1 -> #2) &, {
9     xA["Row_Labels"],
10    xA["Matrix"]
11    }, 1]

1 AngleBracket[xA__Association] :=
2   Module[{xAList, xRowLabels, xColumnLabels, xRList},
3     xAList = List[xA];
4     xRowLabels = Union @ (Join @@ ({#["Row_Labels"]} & /@ xAList));
5     If[ And @@ (KeyExistsQ[#, "Column_Labels"] & /@ xAList),
6       xColumnLabels = Union @ (Join @@ ({#["Column_Labels"]} & /@ xAList)
7         );
8       xRList = Association @ ((# -> Plus @@ DeleteCases[# /. (Matrix2Rule
9         /@ xAList), #]) & /@
10         Flatten[Outer[{#1, #2} &, xRowLabels, xColumnLabels], 1]);
11       Association[
12         "Matrix" -> Outer[{#1, #2} &, xRowLabels, xColumnLabels] /.
13         xRList,
14         "Row_Labels" -> xRowLabels,
15         "Column_Labels" -> xColumnLabels
16       ],
17       xRList = Association @ ((# -> Plus @@ DeleteCases[# /. (Matrix2Rule
18         /@ xAList), #]) & /@
19         xRowLabels);
20       Association[
21         "Matrix" -> xRowLabels /. xRList,
22         "Row_Labels" -> xRowLabels
23       ]
24     ]
25   ]

```

```

22
23 AngleBracket[xMatrix_List, xLabels_List] /; (ArrayDepth[xMatrix] === 1)
    :=
24   AngleBracket @ Association[
25     "Matrix" -> xMatrix,
26     "Row_Labels" -> xLabels
27   ]
28
29 AngleBracket[xMatrix_List, xColumnLabels_List, xRowLabels_List: {}] /; (
    ArrayDepth[xMatrix] > 1) :=
30   AngleBracket @ Association[
31     "Matrix" -> xMatrix,
32     "Row_Labels" -> If[xRowLabels === {},
33       Range @ (First @ (Dimensions @ xMatrix)),
34       xRowLabels
35     ],
36     "Column_Labels" -> xColumnLabels
37   ]
38
39 AngleBracket[0, xRowLabels_List] :=
40   AngleBracket @ Association[
41     "Matrix" -> Array[0 &, {Length @ xRowLabels}],
42     "Row_Labels" -> xRowLabels
43   ]
44
45 AngleBracket[0, xColumnLabels_List, xRowLabels_List] :=
46   AngleBracket @ Association[
47     "Matrix" -> Array[0 &, {Length @ xRowLabels, Length @ xColumnLabels
48       }],
49     "Row_Labels" -> xRowLabels,
50     "Column_Labels" -> xColumnLabels
51   ]
52 AngleBracket[1, xLabels_List] :=
53   Association[

```

```

54 "Matrix" -> IdentityMatrix[Length @ xLabels],
55 "Row_Labels" -> xLabels,
56 "Column_Labels" -> xLabels
57 ]
58
59 AngleBracket[1, xColumnLabels_List, xRowLabels_List] :=
60 Module[{xId},
61   xId = Intersection[xColumnLabels, xRowLabels];
62   AngleBracket[
63     Association[
64       "Matrix" -> IdentityMatrix[Length @ xId],
65       "Row_Labels" -> xId,
66       "Column_Labels" -> xId
67     ],
68     AngleBracket[0, xColumnLabels, xRowLabels]
69   ]
70 ]
71
72 AngleBracket[xA_Association, xRowLabels_List] /; KeyExistsQ[xA, "Column_
  Labels"] :=
73 AngleBracket[
74   AngleBracket[0, xA["Column_Labels"], xRowLabels],
75   Association[
76     "Matrix" -> Part[xA["Matrix"],
77       Flatten @ (Position[xA["Row_Labels"], #] & /@ Intersection[
78         xRowLabels, xA["Row_Labels"]]), All],
79     "Row_Labels" -> Intersection[xRowLabels, xA["Row_Labels"]],
80     "Column_Labels" -> xA["Column_Labels"]
81   ]
82 ]
83 AngleBracket[xA_Association, xRowLabels_List] :=
84 AngleBracket[
85   AngleBracket[0, xRowLabels],
86   Association[

```

```

87     "Matrix" -> Part[xA["Matrix"],
88         Flatten@(Position[xA["Row_Labels"], #] & /@ Intersection[
            xRowLabels, xA["Row_Labels"]]]),
89     "Row_Labels" -> Intersection[xRowLabels, xA["Row_Labels"]]
90 ]
91 ]
92
93 AngleBracket[xA_Association, xRowLabel_] /; KeyExistsQ[xA, "Column_
    Labels"] :=
94 If[First @ Dimensions @ (xA["Column_Labels"]) == 1,
95     Part[xA["Matrix"], First @ (Flatten @ (Position[xA["Row_Labels"],
        xRowLabel]))], 1],
96     AngleBracket @ Association[
97         "Matrix" -> Part[xA["Matrix"], Flatten @ (Position[xA["Row_Labels"]
            ], xRowLabel)], All],
98         "Row_Labels" -> {xRowLabel},
99         "Column_Labels" -> xA["Column_Labels"]
100     ]
101 ]
102
103 AngleBracket[xA_Association, xRowLabel_] :=
104     Part[xA["Matrix"], First @ (Flatten @ (Position[xA["Row_Labels"],
        xRowLabel])))]
105
106 AngleBracket[xA_Association, xRowLabels_List, xColumnLabels_List] :=
107     AngleBracket[
108         AngleBracket[0, xColumnLabels, xRowLabels],
109         Association[
110             "Matrix" -> Part[xA["Matrix"],
111                 Flatten @ (Position[xA["Row_Labels"], #] & /@ Intersection[
                    xRowLabels, xA["Row_Labels"]]]),
112                 Flatten @ (Position[xA["Column_Labels"], #] & /@ Intersection[
                    xColumnLabels, xA["Column_Labels"]]]),
113             "Row_Labels" -> Intersection[xRowLabels, xA["Row_Labels"]],
114             "Column_Labels" -> Intersection[xColumnLabels, xA["Column_Labels"]]

```

```

115     ]
116 ]
117
118 AngleBracket[xA_Association, All, xColumnLabels_List] :=
119   AngleBracket[
120     AngleBracket[0, xColumnLabels, xA["Row_Labels"]],
121     Association[
122       "Matrix" -> Part[xA["Matrix"], All,
123         Flatten @ (Position[xA["Column_Labels"], #] & /@ Intersection[
124           xColumnLabels, xA["Column_Labels"]])],
125       "Row_Labels" -> xA["Row_Labels"],
126       "Column_Labels" -> Intersection[xColumnLabels, xA["Column_Labels"]]
127     ]
128 ]
129 AngleBracket[xA_Association, xRowLabels_List, xColumnLabel_] :=
130   AngleBracket[
131     AngleBracket[0, {xColumnLabel}, xRowLabels],
132     Association[
133       "Matrix" -> Transpose @ ({Part[xA["Matrix"],
134         Flatten @ (Position[xA["Row_Labels"], #] & /@ Intersection[
135           xRowLabels, xA["Row_Labels"]])],
136       First @ (Flatten @ (Position[xA["Column_Labels"], xColumnLabel]))
137         ]}),
138     "Row_Labels" -> Intersection[xRowLabels, xA["Row_Labels"]],
139     "Column_Labels" -> {xColumnLabel}
140 ]
141 AngleBracket[xA_Association, All, xColumnLabel_] :=
142   AngleBracket @ Association[
143     "Matrix" -> Transpose @ ({Part[xA["Matrix"], All,
144       First @ (Flatten @ (Position[xA["Column_Labels"], xColumnLabel]))
145         ]}),
146     "Row_Labels" -> xA["Row_Labels"],

```

```

146     "Column_Labels" -> {xColumnLabel}
147 ]
148
149 AngleBracket[xA_Association, xRowLabel_, xColumnLabels_List] :=
150 AngleBracket [
151     AngleBracket[0, xColumnLabels, {xRowLabel}],
152     Association[
153         "Matrix" -> Part[xA["Matrix"], First @ Flatten @ (Position[xA["Row_Labels"], xRowLabel])],
154         Flatten @ (Position[xA["Column_Labels"], #] & /@ Intersection[
155             xColumnLabels, xA["Column_Labels"]])],
156         "Row_Labels" -> {xRowLabel},
157         "Column_Labels" -> Intersection[xColumnLabels, xA["Column_Labels"]]
158     ]
159
160 AngleBracket[xA_Association, xRowLabel_, xColumnLabel_] :=
161 Part[xA["Matrix"], First @ Flatten @ (Position[xA["Row_Labels"],
162     xRowLabel])],
163 First @ Flatten @ (Position[xA["Column_Labels"], xColumnLabel])]
164
165 AngleBracket[xFunction_, xA_Association] :=
166 If[KeyExistsQ[xA, "Column_Labels"],
167     AngleBracket @ Association[
168         "Matrix"-> xFunction @ (xA["Matrix"]),
169         "Column_Labels"-> xA["Column_Labels"],
170         "Row_Labels"-> xA["Row_Labels"]
171     ],
172     AngleBracket @ Association[
173         "Matrix"-> xFunction @ (xA["Matrix"]),
174         "Row_Labels"-> xA["Row_Labels"]
175     ]
176
177 SApply[xFunction_, xA_Association] := AngleBracket[xFunction, xA]

```

When `AngleBracket` is called with a sequence of matrices (sequence of `Association` elements, $\langle X, Y, \dots \rangle$), the output is a new `Association` element (representing a matrix) consisting of an assemble of the inputs in which elements having simultaneously the same row and column labels are added up. The "`RowLabels`" and "`ColumnLabels`" lists of the output consist of a sorted version of the union of all the respective lists of the inputs. Thus, in this usage, `AngleBracket` operator performs the operations of matrix sum and assemble.

Let `xV` be a `List` element representing a column-matrix. `AngleBracket[xV, xRowLabels]` or $\langle xV, xRowLabels \rangle$ gives the `Association` element representing the column-matrix `xV` whose rows are labeled by `xRowLabels`.

Let `xM` be a `List` element representing a matrix (two-dimensional array). `AngleBracket[xM, xColumnLabels]` or $\langle xM, xColumnLabels \rangle$ gives the `Association` element representing the matrix `xM` whose rows are labeled by a sequence of integers and the columns are labeled by `xColumnLabels`. `AngleBracket[xM, xColumnLabels, xRowLabels]` or $\langle xM, xColumnLabels, xRowLabels \rangle$ gives the `Association` element representing the matrix `xM` whose rows are labeled by `xRowLabels` and the columns are labeled by `xColumnLabels`.

`AngleBracket[0, xRowLabels]` or $\langle 0, xRowLabels \rangle$ gives the `Association` element representing the null column-matrix whose rows are labeled by `xRowLabels`. `AngleBracket[0, xColumnLabels, xRowLabels]` or $\langle 0, xColumnLabels, xRowLabels \rangle$ gives the `Association` element representing the null matrix whose rows are labeled by `xRowLabels` and the columns are labeled by `xColumnLabels`. `AngleBracket[1, xLabels]` or $\langle 1, xLabels \rangle$ gives the `Association` element representing the identity whose rows and columns are labeled by `xLabels`. `AngleBracket[1, xColumnLabels, xRowLabels]` or $\langle 1, xColumnLabels, xRowLabels \rangle$ gives the `Association` element representing the matrix defined by the Kronecker Delta function whose rows are labeled by `xRowLabels` and the columns are labeled by `xColumnLabels`.

`SApply[xFunction, xX]` or $\langle xFunction, xX \rangle$ applies the unary function `xFunction` to the entry whose key is "`Matrix`" in the `Association` `xX`.

All the other uses of `AngleBracket` correspond to partitioning of matrices. In these cases `AngleBracket` is called with a sequence of two or three arguments (the third argument is optional), in which the first one must correspond to a matrix (`Association` element), the second one can be a list of row labels, a single row label or the keyword `All` and the third (optional) can be a list of column labels or a single column label. When

a the first argument represents a column-matrix and the second is a single row label, or when the first represent a matrix, the second is a single row label and the third, a single column label, then the output of the operator is a the expression of the corresponding element (i.e., not a List nor an Association). In all the other cases, the output is an Association representing a matrix constituted only by the corresponding rows and columns of the input matrix. When the keyword All is used in the second argument, all rows of the original matrix are selected. When the third argument is not used, all the columns of the original matrix are selected.

3.2 Matrix multiplication and multiplication of a matrix by a scalar

```

1 CircleDot[xX_Association, xY_Association] /;
2   And[xX["Matrix"] === {}, ArrayDepth[xY["Matrix"]] === 1] :=
3   Association[
4     "Matrix" -> {},
5     "Row_Labels" -> {}
6   ]
7
8 CircleDot[xX_Association, xY_Association] /;
9   And[xX["Matrix"] === {}] :=
10  Association[
11    "Matrix" -> {},
12    "Row_Labels" -> {},
13    "Column_Labels" -> xY["Column_Labels"]
14  ]
15
16 CircleDot[xX_Association, xY_Association] /;
17   And[ArrayDepth[xX["Matrix"]] === 1, ArrayDepth[xY["Matrix"]] === 1] :=
18   Module[{xA, xB, xU},
19     xU = Association[
20       "Matrix" -> Array[0&, Length @ #],
21       "Row_Labels" -> #
22     ] & @ Union[xX["Row_Labels"], xY["Row_Labels"]];
23     xA = SAssemble[xX, xU];
24     xB = SAssemble[xY, xU];

```

```

25     xA["Matrix"].xB["Matrix"]
26 ]
27
28 CircleDot[xX_Association, xY_Association] /;
29 And[ArrayDepth[xY["Matrix"]] === 1] :=
30 Module[{xA, xB},
31     xA = Association[
32         "Matrix" -> Array[0&, {Length @ #1, Length @ #2}],
33         "Row_Labels" -> #1,
34         "Column_Labels" -> #2
35     ] & @@ {xX["Row_Labels"], Union[xX["Column_Labels"], xY["Row_Labels"]]}];
36     xB = Association[
37         "Matrix" -> Array[0&, Length @ #],
38         "Row_Labels" -> #
39     ] & @ Union[xX["Column_Labels"], xY["Row_Labels"]];
40     xA = SAssemble[xX, xA];
41     xB = SAssemble[xY, xB];
42     Association[
43         "Matrix" -> xA["Matrix"].xB["Matrix"],
44         "Row_Labels" -> xA["Row_Labels"]
45     ]
46 ]
47
48 CircleDot[xX_Association, xY_Association] :=
49 Module[{xA, xB},
50     xA = Association[
51         "Matrix" -> Array[0&, {Length @ #1, Length @ #2}],
52         "Row_Labels" -> #1,
53         "Column_Labels" -> #2
54     ] & @@ {xX["Row_Labels"], Union[xX["Column_Labels"], xY["Row_Labels"]]}];
55     xB = Association[
56         "Matrix" -> Array[0&, {Length @ #1, Length @ #2}],
57         "Row_Labels" -> #1,

```

```

58     "Column_Labels" -> #2
59     ] & @@ {Union[xX["Column_Labels"], xY["Row_Labels"]], xY["Column_
        Labels"]};
60     xA = SAssemble[xX, xA];
61     xB = SAssemble[xY, xB];
62     Association[
63         "Matrix" -> xA["Matrix"].xB["Matrix"],
64         "Row_Labels" -> xA["Row_Labels"],
65         "Column_Labels" -> xB["Column_Labels"]
66     ]
67 ]
68
69 CircleDot[xX_Association, xY_List] :=
70     xX["Matrix"].xY
71
72 CircleDot[xX_Association, xY_] :=
73     SApply[(xY #)&, xX]
74
75 CircleDot[xY_, xX_Association] :=
76     SApply[(xY #)&, xX]
77
78 SDot = CircleDot;

```

In the package MathMatrixPack, the operator CircleDot, denote by $X \odot Y$ or the function SDot[X, Y] is used to denote the operations of matrix multiplication and multiplication of a matrix by a scalar. In the case of matrix multiplication, either both CircleDot arguments are Association elements or the first one is an Association element and the second one a List element. If the second argument is an Association, the output will be an Association representing the matrix multiplication between both input arguments. If the second argument is a List, the output will be a List representing the matrix multiplication between both input arguments. In the case of multiplication of a matrix by a scalar, one argument must be an Association and the other an scalar. The order of the arguments is not relevant in this case, and the output is an Association representing the corresponding multiplication of the matrix by the scalar.

3.3 Matrix transposition

```
1 SuperDagger[xX_Association] :=
2   Association[
3     "Matrix"->Transpose @ xX["Matrix"],
4     "Column_Labels"-> xX["Row_Labels"],
5     "Row_Labels"-> xX["Column_Labels"]
6   ]
7
8 STranspose[xX_Association] := SuperDagger[xX]
```

In the package MathMatrixPack, the operator SuperDagger, denote by X^\dagger is used to denote the operation of transposition of matrices. It extends the use of the built-in function Transpose (that is applicable to List elements representing matrices) to Association elements representing matrices. The unary function STranspose does the same as the operator SuperDagger.

3.4 Affine Transformations

```
1 BracketingBar[xX_Association] :=
2   AffineTransform[xX["Matrix"]]
3
4 BracketingBar[xX_List /; Dimensions[xX]=={3,3}] :=
5   AffineTransform[xX]
6
7 BracketingBar[xX_List /; Dimensions[xX]=={4,4}] :=
8   LinearFractionalTransform[xX]
```

In the package MathMatrixPack, the operator BracketingBar, denote by $\vdash X \vdash$ is used to convert matrices into affine operators. Whenever the (single) argument of the operator is an Association, the output is a TransformationFunction given by the application of the built-in AffineTransform to the Association entry whose key is "Matrix". The same kind of output will be obtained if the argument of the operator is a 3×3 List element. However, when the argument is a 4×4 List element, the corresponding TransformationFunction is obtained by the application of the built-in LinearFractionalTransform function (whose output represents a homogeneous transformation).

3.5 Coefficient arrays

```
1 SCoefficientArrays[xA_Association, xVariables_List, xRules_List:{}] :=
2   Module[{x},
3     x["Row_Labels"] = xA["Row_Labels"];
4     x["Expressions"] = Flatten @ (xA["Matrix"]);
5     x["Coefficient_Arrays"] = CoefficientArrays[x["Expressions"] //.
6       xRules, xVariables];
7     {
8       Association[
9         "Matrix" -> Part[#, 1]& @ x["Coefficient_Arrays"],
10        "Row_Labels" -> x["Row_Labels"]
11      ],
12      Association[
13        "Matrix" -> Part[#, 2]& @ x["Coefficient_Arrays"],
14        "Row_Labels" -> x["Row_Labels"],
15        "Column_Labels" -> xVariables
16      ]
17    ]
18
19
20 SMatrixCoefficientArrays[xA_Association, xRules_List: {}] :=
21   Module[{xxMatrix, xxVariables, xxRowLabels, xxColumnLabels,
22     xxCoefficientMatrices},
23     xxMatrix = xA["Matrix"] //. xRules;
24     xxRowLabels = xA["Row_Labels"];
25     xxColumnLabels = xA["Column_Labels"];
26     xxVariables = Union @ GetVariables[xxMatrix];
27     xxCoefficientMatrices = CoefficientArrays[xxMatrix,xxVariables];
28     {
29       Association[ Union@@{
30         {
31           1->
32           Association[
33             "Matrix"->Normal@Part[xxCoefficientMatrices,1],
```

```

33     "Column_Labels"->xxColumnLabels,
34     "Row_Labels"->xxRowLabels
35 ]
36 },
37 MapThread[ (#1-> Association[
38     "Matrix"->Normal@Part[xxCoefficientMatrices,2,All,All,#2],
39     "Column_Labels"->xxColumnLabels,
40     "Row_Labels"->xxRowLabels
41 ])&, {#,Range@Length@#}, 1]& @ xxVariables
42 }],
43 xxVariables
44 }
45 ]

```

`SCoefficientArrays` is an extension of the built-in function `CoefficientArrays` that is applicable to matrices represented by `Association` elements. This function can be called with two or three arguments (being the third optional), i.e., both syntaxes `SCoefficientArrays[M, V, R]` and `SCoefficientArrays[M, V]` are valid. In both cases, the function transforms the `Association` element `M` in a `List` of expressions `E`, applies to this list the transformation rules `R` whenever they are defined, and returns a `List` element $\{K, H\}$, containing two `Association` elements, `K` and `H`, such that the affine part of `E` (i.e., terms of the expressions in `E` that are either independent or linear dependent of the variables in `V`) is given by $\langle K, H \odot V \rangle$.

In order to understand how the function `SMatrixCoefficientArrays` works, consider a matrix \mathbf{M} that may be dependent of some scalar variables (v_1, \dots, v_r) , i.e., $\mathbf{M} = \underline{\mathbf{M}}(v_1, \dots, v_r)$. If \mathbf{M} is affine with respect to these variables, then there is a list of constant matrices $\mathbf{M}_1, \mathbf{M}_{v_1}, \dots, \mathbf{M}_{v_r}$ such that:

$$\mathbf{M} = 1 \mathbf{M}_1 + \sum_{k=1}^r v_k \mathbf{M}_{v_k}$$

`SMatrixCoefficientArrays[M]` or `SMatrixCoefficientArrays[M,R]` are valid syntaxes for this function, with `M` being an `Association` element representing a matrix \mathbf{M} and with `M` being an optional `List` of replacement rules, to be applied to this matrix. The output is the `List` $\{X, V\}$, with `X` being an `Association` element of the form

```

1 Association[1 -> M1, v1 -> Mv1, ..., vr -> Mvr ]

```

($M_1, M_{v_1}, \dots, M_{v_r}$ are the Association elements representing the corresponding coefficient matrices $M_1, M_{v_1}, \dots, M_{v_r}$) and with V being the List $\{v_1, \dots, v_r\}$.

3.6 Linear Solve

```

1 SLinearSolve[xX_Association,xY_Association] :=
2   Module[{xA,xB},
3     xA = SAssemble[xX];
4     xB = SAssemble[xY];
5     If[xA["Row_Labels"] === xB["Row_Labels"],
6       Association[
7         "Matrix" -> LinearSolve[xA["Matrix"], xB["Matrix"]],
8         "Column_Labels" -> xB["Column_Labels"],
9         "Row_Labels" -> xA["Column_Labels"]
10      ],
11      "Error"
12    ]
13  ]

```

SLinearSolve extends the application of the built-in function LinearSolve (originally applicable to a pair of List elements representing matrices) to pairs of Association elements representing matrices. The output of SLinearSolve[A, B] is an Association element Z such that $A \odot Z == B$.

```

1 SLeastSquares[xX_Association,xY_Association] :=
2   Module[{xA,xB},
3     xA = SAssemble[xX];
4     xB = SAssemble[xY];
5     If[xA["Row_Labels"] === xB["Row_Labels"],
6       Association[
7         "Matrix" -> LeastSquares[xA["Matrix"], xB["Matrix"]],
8         "Column_Labels" -> xB["Column_Labels"],
9         "Row_Labels" -> xA["Column_Labels"]
10      ],
11      "Error"
12    ]
13  ]

```

SLeastSquares extends the application of the built-in function LeastSquares (originally applicable to a pair of List elements representing matrices) to pairs of Association elements representing matrices. The output of SLeastSquares[A, B] is an Association element Z which is a least squares solution for X in the matrix equation $\langle A \odot X, B \rangle == 0$.

```

1 LSSolver[xEquations_List, xGenVariables_List, xIndVariables_List,
2   xRules_List: {}, xExtraRules_List: {}, xSize_Integer: 0,
3   xTestParameters_List: {}, xSymmetry_: Automatic] :=
4   Module[{xIn, xSol, xXe, xXi, xC},
5     xXi = Union[Complement[GetVariables @ xEquations, xGenVariables],
6       xIndVariables];
7     xIn = Select[xEquations, (Length[#] <= xSize) &];
8     xXe = Complement[GetVariables @ xIn, xXi];
9     xSol = Flatten @ (Quiet @ Solve[(# == 0) & /@ xIn, xXe]);
10    (* xS = Jacobi[
11      xGenVariables //. xSol,
12      Union[Complement[xGenVariables, First /@ xSol], xXi],
13      xGenVariables
14    ]; *)
15    xIn = Collect[RedundantElim @ (Expand @ (xEquations //. xSol) //.
16      xExtraRules), xX_[t], Simplify] //. xRules;
17    xC = LSReferenceOrthogonalComplement[
18      Jacobi[#, Union[GetVariables[#, xXi]] & @ xIn ,
19      xXi, xSymmetry, xTestParameters
20    ];
21    (* xS = xS ~SDot~ xC; *)
22    {
23      Union[
24        xSol,
25        Select[ MapThread[(#1 -> #2) &,
26          {#["Row_Labels"], (#["Matrix"].#["Column_Labels"])} /.
27            (xSymmetry["Extra_Rules"] //. Missing[xX_] -> {})),
28          1] & @ xC, Not @ (Expand[First[#] - Last[#]] == 0) &]],
29      xC["Test_Parameters"]
30    }

```


3.7 Jacobians

```

1 Jacobi[xExpressionsList_, xVariablesList_] :=
2   Association[
3     "Matrix" -> D[xExpressionsList, {xVariablesList}],
4     "ColumnLabels" -> xVariablesList,
5     "RowLabels" -> Range @@ Dimensions @ xExpressionsList
6   ]
7
8 Jacobi[xExpressionsList_, xVariablesList_, xExpressionsLabels_] :=
9   Association[
10    "Matrix" -> D[xExpressionsList, {xVariablesList}],
11    "ColumnLabels" -> xVariablesList,
12    "RowLabels" -> xExpressionsLabels
13  ]

```

Jacobi obtains the Jacobian matrix of a given list of expressions with respect to a list of variables. The syntax of this function is `Jacobi[E, V, L]` or `Jacobi[E, V]` (i.e., the third argument is optional). `E` is an expression or a list of symbolic expressions, `V` is a list of variables and `L` is a list of labels for the corresponding expressions. The output is an `Association` element, representing the Jacobian matrix of `E` with respect to the variables in `V`. The `"ColumnLabels"` entry of the output is the list `V` and the `"RowLabels"` entry is `L`, if it is an input argument, or a list of positive integer indexes, otherwise.

3.8 Orthogonal complement

```

1 OrthogonalComplement[xJacobian_] :=
2   Module[{x},
3     x["NullSpaceMatrix"] = Transpose @ NullSpace[xJacobian["Matrix"]];
4     x["IndependentVariations"] = (Range @ Part[Dimensions[x["NullSpace
5       Matrix"]], 2]);
6     Association[

```

```

6      "Matrix" -> x["NullSpaceMatrix"],
7      "ColumnLabels" -> x["IndependentVariations"],
8      "RowLabels" -> xJacobian["ColumnLabels"]
9  ]
10 ]
11
12 OrthogonalComplement[xJacobian_, xLabel_String] :=
13 Module[{x},
14   x["NullSpaceMatrix"] = Transpose @ NullSpace[xJacobian["Matrix"]];
15   x["IndependentVariations"] = Subscript[OverTilde[q], xLabel, #][t] & /
      @
16   (Range @ Part[Dimensions[x["NullSpaceMatrix"]], 2]);
17   Association[
18     "Matrix" -> x["NullSpaceMatrix"],
19     "ColumnLabels" -> x["IndependentVariations"],
20     "RowLabels" -> xJacobian["ColumnLabels"]
21   ]
22 ]
23
24 OrthogonalComplement[xJacobian_, xIndependentVariablesList_List] :=
25 Module[{x, xOrthogonalComplement},
26   {x["Number of Constraints"], x["Number of Variables"]} = Dimensions[
      xJacobian["Matrix"]];
27   x["Number of Degrees of Freedom"] = x["Number of Variables"] - x["
      Number of Constraints"];
28   If[ x["Number of Degrees of Freedom"] === Length @
      xIndependentVariablesList,
29     (*-TRUE-*)
30     x["IndependentVariablesColumnIndexes"] =
31       Flatten[ Position[xJacobian["ColumnLabels"], #] & /@
          xIndependentVariablesList, Infinity];
32     x["RedundantVariablesColumnIndexes"] =
33       Complement[Range @@ Dimensions @ xJacobian["ColumnLabels"], x["
          IndependentVariablesColumnIndexes"]];
34     xOrthogonalComplement = Association[

```

```

35     "Matrix" -> Array[0&, {x["Number_of_Variables"], x["Number_of_
        Degrees_of_Freedom"]}],
36     "Column_Labels" -> xIndependentVariablesList,
37     "Row_Labels" -> xJacobian["Column_Labels"]
38 ];
39 xOrthogonalComplement[["Matrix", x["Independent_Variables_Column_
        Indexes"]]] =
40     IdentityMatrix @ x["Number_of_Degrees_of_Freedom"];
41 xOrthogonalComplement[["Matrix", x["Redundant_Variables_Column_
        Indexes"]]] =
42     LinearSolve @@ {
43         xJacobian[["Matrix", All, x["Redundant_Variables_Column_
            Indexes"]]],
44         -xJacobian[["Matrix", All, x["Independent_Variables_Column_
            Indexes"]]]
45     };
46 xOrthogonalComplement,
47 (*-FALSE-*)
48 "Error"
49 ]
50 ]

```

OrthogonalComplement calculates an orthogonal complement of a (Jacobian) matrix. Two syntaxes are possible for this function:

- OrthogonalComplement[A] calculates *an* orthogonal complement for the matrix represented by the Association element A using the built-in NullSpace function. The output is an Association element C whose "Row_Labels" entry is equal to the "Column_Labels" entry of the input argument and whose "Column_Labels" entry is a list of positive integer indexes; also, $A \odot C == 0$.
- OrthogonalComplement[A, V] calculates *the* orthogonal complement for the matrix represented by the Association element A with respect to the independent set of variables represented by the List element V using the built-in LinearSolve function. The output is an Association element C whose "Row_Labels" entry is equal to the "Column_Labels" entry of the input argument and whose "Column_Labels" entry is equal to V; also, $A \odot C == 0$.

```

1 LSNumericalOrthogonalComplement[xJacobian_,
  xIndependentVariablesList_List] :=
2 Module[{x, xOrthogonalComplement},
3   {x["Number_of_Constraints"], x["Number_of_Variables"]} = Dimensions[
    xJacobian["Matrix"]];
4   x["Number_of_Degrees_of_Freedom"] = Part[Dimensions @
    xIndependentVariablesList, 1];
5   x["Independent_Variables_Column_Indexes"] =
6     Flatten[Position[xJacobian["Column_Labels"], #]& /@
    xIndependentVariablesList, Infinity];
7   x["Redundant_Variables_Column_Indexes"] =
8     Complement[Range @@ Dimensions @ xJacobian["Column_Labels"], x["
    Independent_Variables_Column_Indexes"]];
9   xOrthogonalComplement = Association[
10    "Matrix" -> Array[0&, {x["Number_of_Variables"], x["Number_of_Degrees
    of_Freedom"]}],
11    "Column_Labels" -> xIndependentVariablesList,
12    "Row_Labels" -> xJacobian["Column_Labels"]
13   ];
14   xOrthogonalComplement[["Matrix", x["Independent_Variables_Column_
    Indexes"]]] =
15     IdentityMatrix @ x["Number_of_Degrees_of_Freedom"];
16   xOrthogonalComplement[["Matrix", x["Redundant_Variables_Column_
    Indexes"]]] =
17     LeastSquares @@ {
18       xJacobian[["Matrix", All, x["Redundant_Variables_Column_Indexes"
        ]]],
19       -xJacobian[["Matrix", All, x["Independent_Variables_Column_
        Indexes"]]]
20     };
21   xOrthogonalComplement
22 ]
23

```

```

24 LSReferenceOrthogonalComplement[xJacobian_Association,
    xIndependentVariables_List,
25 xSymmetry_: Automatic, xTestParameters_List: {}, xNZero_Rational:1
    10^-5] :=
26 Module[{x, xNC, xSC, xNTestParameters},
27   xNTestParameters = Union[
28     xTestParameters,
29     If[xSymmetry === Automatic,
30       (#-> RandomReal[1])& /@ (GetAllVariables[(Flatten @ (Union @@ (
        Normal @
31       (#["Matrix"])& @ xJacobian)))) /. xTestParameters]],
32     xSymmetry["Function"] /@ (GetAllVariables[(Flatten @ (Union @@ (
        Normal @
33       (#["Matrix"])& @ xJacobian)))) /. xTestParameters]])
34   ]
35 ];
36 xNC = LSNumericalOrthogonalComplement[
37   SReplaceRepeated[xJacobian, xNTestParameters],
38   xIndependentVariables
39 ];
40 xNC = AppendTo[xNC, "Matrix" -> Round[xNC["Matrix"], xNZero]];
41 x["Column_Labels"] = xNC["Column_Labels"] /. SymbolReplacements;
42 x["Row_Labels"] = xNC["Row_Labels"] /. SymbolReplacements;
43
44 x["New_Parameters"] = {};
45 If[xSymmetry === Automatic,
46   (*-TRUE-*)
47   Function[xRowLabel,
48     x["Row_Number"] = First @ (Flatten @ Position[x["Row_Labels"],
        xRowLabel]);
49     x["Parameters_Values"] = Flatten @ (Part[xNC["Matrix"], x["Row_
        Number"]]);
50     x["Parameters_Names"] = Flatten @
51       ((Function[{xColumnLabel}, Subscript[OverBar[\[CapitalGamma]],
        xRowLabel, xColumnLabel])) /@

```

```

52      x["ColumnLabels"]);
53      x["NewParameters:1"] = MapThread[(#2-> #1)&, {x["Parameters_
      Values"], x["Parameters_Names"]}, 1];
54      x["NewParameters:2"] = (Flatten @ (Normal @ DeleteCases[
      Association[x["NewParameters:1"]], _Integer]));
55      xNTestParameters = Union[xNTestParameters, N[x["NewParameters:2"
      ]]];
56      x["NewParameters"] = Union[
57          x["NewParameters"],
58          (Reverse /@ x["NewParameters:2"]),
59          (Reverse /@ x["NewParameters:2"]) /. ((xA->xB_ )->(-xA->-xB )
          )
60      ];
61      ]/@ x["RowLabels"],
62      (*-FALSE-*)
63      Function[{xRowLabel},
64          If[Intersection[xSymmetry["Secondary"],
65              Flatten @ (Characters /@ Select[xRowLabel /. {Subscript[xV_,
                  xS_] -> {xV, xS}, xV_ -> {xV}}, StringQ]]
66              ] === {}
67              (* Not @ And[
68                  StringQ[Quiet @ Last[xRowLabel]],
69                  StringTake[Last[xRowLabel], -1] === xSymmetry["Secondary"]
70              ] *),
71              x["RowNumber"] = First @ (Flatten @ Position[x["RowLabels"],
                  xRowLabel]);
72              x["NewSubscript"] = If[Intersection[xSymmetry["Primary"],
73                  Flatten @ (Characters /@ Select[xRowLabel /. {Subscript[xV_,
                          xS_] -> {xV, xS}, xV_ -> {xV}}, StringQ]]
74                  ] === {}
75                  (* Quiet @ (StringTake[Last[xRowLabel], -1] === xSymmetry["
                          Primary"]) *),
76                  xRowLabel,
77                  Subscript @@ (If[StringQ[#], StringReplace[#, (# -> "")& /@
                          xSymmetry["Primary"]], #] & /@

```

```

78      (xRowLabel /. (Subscript[xV_, xS_] -> {xV, xS})))
79    ];
80    x["Parameters_Values"] = Flatten @ (Part[xNC["Matrix"], x["Row_
      Number"]]);
81    x["Parameters_Names"] = Flatten @ ((Function[{xLabel},
82      Subscript[OverBar[\[CapitalGamma]], x["New_Subscript"],
      xLabel]
83      ]) /@ x["Column_Labels"]);
84    x["New_Parameters:1"] = MapThread[(#2 -> #1) &,
85      {x["Parameters_Values"], x["Parameters_Names"]}, 1];
86    x["New_Parameters:2"] = (Flatten @ (Normal @
87      DeleteCases[Association[x["New_Parameters:1"]], _Integer]));
88    xNTestParameters = Union[xNTestParameters, N[x["New_Parameters
      :2"]]];
89    x["New_Parameters"] = Union[
90      x["New_Parameters"],
91      (Reverse /@ x["New_Parameters:2"]),
92      (Reverse /@ x["New_Parameters:2"]) /. ((xA_ -> xB_) -> (-xA
      -> -xB))
93    ];
94    ];
95    ] /@ x["Row_Labels"];
96    ];
97    xSC = Association[xNC, "Matrix"-> (xNC["Matrix"] /. x["New_
      Parameters"]),
98      "Test_Parameters" -> xNTestParameters];
99    xSC
100  ]
101
102
103 LLinearizedOrthogonalComplement[xLinearizedJacobian_Association,
      xIndependentVariables_List,
104    xCoordinatesReplacements_: {}, xSymmetry_: Automatic,
      xTestParameters_List: {}, xNZero_Rational:1 10^-5] :=
105    Module[{x, xE, xLSOC, xCoordinates, xLinearizedJacobianCoefficients,

```

```

106 xNTestParameters, xNA1, xNC1, xNCq, xSC1, xSCq},
107
108 {xLinearizedJacobianCoefficients, xCoordinates} =
109   SMatrixCoefficientArrays[xLinearizedJacobian];
110 xNTestParameters = Union[
111   xTestParameters,
112   If[xSymmetry === Automatic,
113     (#-> RandomReal[1])& /@ (GetAllVariables[(Flatten @ (Union @@ (
114       Normal @
115       ("Matrix"))& /@ xLinearizedJacobianCoefficients))) //
116       xTestParameters]),
117     xSymmetry["Function"] /@ (GetAllVariables[(Flatten @ (Union @@ (
118       Normal @
119       ("Matrix"))& /@ xLinearizedJacobianCoefficients))) //
120       xTestParameters])
121   ]
122 ];
123
124 xNA1 = SReplaceRepeated[xLinearizedJacobianCoefficients[1],
125   xNTestParameters];
126 xNC1 = LSNumericalOrthogonalComplement[xNA1, xIndependentVariables];
127 xNC1 = AppendTo[xNC1, "Matrix" -> Round[xNC1["Matrix"], xNZero]];
128 x["ColumnLabels"] = xNC1["ColumnLabels"] //. SymbolReplacements;
129 x["RowLabels"] = xNC1["RowLabels"] //. SymbolReplacements;
130
131 xE = 1 10^-3;
132 xNCq = Association[
133   (#->SAssemble[
134     (+1/(2 xE)) ~SDot~ SAssemble[ LSNumericalOrthogonalComplement[
135       SAssemble[ xNA1, (+xE) ~SDot~ SReplaceRepeated[
136         xLinearizedJacobianCoefficients[#],
137         xNTestParameters]], xIndependentVariables],
138     (-1) ~SDot~ xNC1],
139     (-1/(2 xE)) ~SDot~ SAssemble[ LSNumericalOrthogonalComplement[

```



```

134      SAssemble[ xNA1, (-xE) ~SDot~ SReplaceRepeated[
135          xLinearizedJacobianCoefficients[#],
136          xNTestParameters]], xIndependentVariables],
137      (-1) ~SDot~ xNC1]
138  ]& /@ xCoordinates
139  ];
140
141  (xNCq[#] = AppendTo[xNCq[#], "Matrix" -> Round[xNCq[#] ["Matrix"],
142      xNZero]])& /@ xCoordinates;
143
144  x["NewParameters"]={};
145  If[xSymmetry === Automatic,
146      (*-TRUE-*)
147      Function[xRowLabel,
148          x["RowNumber"] = First @ (Flatten @ Position[x["RowLabels"],
149              xRowLabel]);
150          x["ParametersValues"] = Flatten @ (Join[Part[xNC1["Matrix"], x["
151              RowNumber"]],
152              Join @@ ((Part[xNCq[#] ["Matrix"], x["RowNumber"]])& /@
153                  xCoordinates)]];
154          x["ParametersNames"] = Flatten @ (Join[
155              ((Function[{xColumnLabel}, Subscript[OverBar[\[CapitalDelta]
156                  ],1,xRowLabel,xColumnLabel]]) /@
157                  x["ColumnLabels"]),
158              Join @@ (
159                  ((Function[{xColumnLabel}, Subscript[OverBar[\[CapitalDelta]
160                      ],#,xRowLabel,xColumnLabel]]) /@
161                      x["ColumnLabels"])& /@ (xCoordinates //.
162                          SymbolReplacements)
163                  )
164              ]]);
165          x["NewParameters:1"] = MapThread[(#2-> #1)&, {x["Parameters_
166              Values"], x["ParametersNames"]}, 1];

```

```

159 x["NewParameters:2"] = (Flatten @ (Normal @ DeleteCases[
      Association[x["NewParameters:1"]], _Integer]));
160 xNTestParameters = Union[xNTestParameters, N[x["NewParameters:2"
      ]]];
161 x["NewParameters"] = Union[
162   x["NewParameters"],
163   (Reverse /@ x["NewParameters:2"]),
164   (Reverse /@ x["NewParameters:2"]) /. ((xA_>xB_ )->(-xA->-xB )
      )
165   ];
166   ]/@ x["RowLabels"],
167   (*-FALSE-*)
168   Function[{xRowLabel},
169     If[Intersection[xSymmetry["Secondary"],
170       Flatten @ (Characters /@ Select[xRowLabel /. {Subscript[xV_,
          xS__] -> {xV, xS}, xV_ -> {xV}}, StringQ))
171       ] === {}
172       (* Not @ And[
173         StringQ[Quiet @ Last[xRowLabel]],
174         MemberQ[xSymmetry["Secondary"], StringTake[Last[xRowLabel],
          -1]]
175       ] *),
176       x["RowNumber"] = First @ (Flatten @ Position[x["RowLabels"],
          xRowLabel]);
177       x["NewSubscript"] = If[Intersection[xSymmetry["Primary"],
178         Flatten @ (Characters /@ Select[xRowLabel /. {Subscript[xV_,
          xS__] -> {xV, xS}, xV_ -> {xV}}, StringQ))
179         ] === {}
180         (* Quiet @ (StringTake[Last[xRowLabel], -1] === xSymmetry["
          Primary"]) *) ,
181       xRowLabel,
182       Subscript @@ (If[StringQ[#], StringReplace[#, (# -> "")& /@
          xSymmetry["Primary"]], #] & /@
183         (xRowLabel /. (Subscript[xV_, xS__] -> {xV, xS})))
184       ];

```

```

185     x["Parameters_Values"] = Flatten @ (Join[
186         Part[xNC1["Matrix"], x["Row_Number"]],
187         Join @@ ((Part[xNCq[#]["Matrix"], x["Row_Number"]]) & /@
            xCoordinates)
188     ]);
189     x["Parameters_Names"] = Flatten @ (Join[
190         (Function[{xLabel},
191             Subscript[OverBar[\[CapitalDelta]], 1, x["New_Subscript"],
192                 xLabel]
193         ]) /@ x["Column_Labels"],
194         Join @@ ((
195             Function[{xLabel},
196                 Subscript[OverBar[\[CapitalDelta]], #, x["New_Subscript"],
197                     xLabel]
198             ]) /@ x["Column_Labels"]
199         ) & /@ (xCoordinates /. SymbolReplacements))
200     ];
201     x["New_Parameters:1"] = MapThread[(#2 -> #1) &,
202         {x["Parameters_Values"], x["Parameters_Names"]}, 1];
203     x["New_Parameters:2"] = (Flatten @ (Normal @
204         DeleteCases[Association[x["New_Parameters:1"]], _Integer]));
205     xNTestParameters = Union[xNTestParameters, N[x["New_Parameters
206         :2"]]];
207     x["New_Parameters"] = Union[
208         x["New_Parameters"],
209         (Reverse /@ x["New_Parameters:2"]),
210         (Reverse /@ x["New_Parameters:2"]) /. ((xA_ -> xB_) -> (-xA
211             -> -xB))
212     ];
213     ] /@ x["Row_Labels"];
214 ];
215
216 xSC1 = Association[xNC1, "Matrix"-> (xNC1["Matrix"] /. x["New_
217     Parameters"])]];

```

```

214 (xSCq[#] = Association[xNCq[#], "Matrix"-> (xNCq[#]["Matrix"] // . x[
      "New_Parameters"])))& /@ xCoordinates;
215 xLSOC = SAssemble[xSC1, Inner[#1 ~SDot~ #2&, xCoordinates, xSCq /@
      xCoordinates, SAssemble]];
216 xLSOC["Test_Parameters"] = xNTestParameters;
217 xLSOC
218 ]

```

LSLinearizedOrthogonalComplement provides an symbolic expression for the linearized form of the orthogonal complement of a non-linear Jacobian matrix. The syntax for this function is `LSLinearizedOrthogonalComplement[J,V,R,C,Z,P]`:

- J is an Association element representing a non-linear Jacobian matrix.
- V is a List of the variables among the "Column_Labels" of J that are considered as independent.
- R is a List element consisting of replacement rules for the reference values of the generalized variables in the expression of J (*optional argument whose default value is an empty List*).
- C is a List element consisting of replacement rules for the linearized expressions of some of the generalized variables in the expression of J (*optional argument whose default value is an empty List*).
- Z is a rational number expressing the precision of the numerical algorithms present in the function; numbers whose difference is less than Z are considered as equal during the execution of the algorithm (*optional argument whose default value is $1 \cdot 10^{-5}$*).
- P is a List element consisting of replacement rules for the values of some of the parameters in the expression of J (*optional argument whose default value is an empty List*).

The output of this function is a List element {A,C,T} in which:

- A is an Association element representing the symbolic linearized expression of J.
- C is an Association element representing the symbolic linearized expression of an orthogonal complement of J.

- T is a List element consisting of replacement rules for the test values (i.e., random or prescribed values used in the algorithm for obtaining the expression of C) of the parameters of the symbolic expression of J.

4 Rotation and homogeneous transformations

4.1 Rotation transformation

```

1 Rotation = Function @ Module[{x},
2   x["TransformList"] = List[##] /. {
3     "x" -> (RotationTransform[#, {1,0,0}]&),
4     "y" -> (RotationTransform[#, {0,1,0}]&),
5     "z" -> (RotationTransform[#, {0,0,1}]&),
6     "X" -> (RotationTransform[#, {1,0,0}]&),
7     "Y" -> (RotationTransform[#, {0,1,0}]&),
8     "Z" -> (RotationTransform[#, {0,0,1}]&)
9   };
10  Function[(TransformationMatrix @ (Simplify @ Inner[(#1 @ #2)&, x["
      TransformList"], List[##], Dot]))][[1;;3,1;;3]]]
11 ];
12
13 HomogToRot = #[[1;;3,1;;3]]&;
14
15 QuatToRot = {
16   {#1^2-#2^2-#3^2+#4^2,2 #1 #2-2 #3 #4,2 #1 #3+2 #2 #4},
17   {2 #1 #2+2 #3 #4,-#1^2+#2^2-#3^2+#4^2,2 #2 #3-2 #1 #4},
18   {2 #1 #3-2 #2 #4,2 #2 #3+2 #1 #4,-#1^2-#2^2+#3^2+#4^2}
19 }&;

```

$\text{Rotation}[\mathbf{e}_1, \dots, \mathbf{e}_r][\theta_1, \dots, \theta_r]$ gives the transformation matrix associated to successive rotations around the axes $\mathbf{e}_1, \dots, \mathbf{e}_r$ (being $\theta_1, \dots, \theta_r$ the corresponding rotation angles). In this syntax, an axis \mathbf{e}_k can be defined either by a List element representing the three Cartesian coordinates of a vector aligned to the axis of rotation in the local basis coordinates or by a String element "x", "y" or "z" whenever any of the canonical local axis is the corresponding axis of rotation.

4.2 Homogeneous transformation

```

1 Homogeneous = Function @ Module[{x},
2   x["TransformList"] = List[##] /. {
3     "Rx" -> (RotationTransform[#, {1,0,0}]&),
4     "Ry" -> (RotationTransform[#, {0,1,0}]&),
5     "Rz" -> (RotationTransform[#, {0,0,1}]&),
6     "R"[xVector_] -> (RotationTransform[#, xVector]&),
7     "Tx" -> (TranslationTransform[# {1,0,0}]&),
8     "Ty" -> (TranslationTransform[# {0,1,0}]&),
9     "Tz" -> (TranslationTransform[# {0,0,1}]&),
10    "T"[xVector_] -> (TranslationTransform[# xVector]&)
11   };
12   Function[TransformationMatrix @ (Simplify @ Inner[(#1 @ #2)&, x["
      TransformList"], List[##], Dot])]
13 ];

```

$\text{Homogeneous}[H_1, \dots, H_r][\xi_1, \dots, \xi_r]$ gives the homogeneous transformation matrix associated to successive rotations or translations H_1, \dots, H_r (being ξ_1, \dots, ξ_r the corresponding rotation angles or displacements). In this syntax, H_k can be defined either a rotation "R"[\mathbf{e}_k] around an axis defined by \mathbf{e}_k or a translation "T"[\mathbf{e}_k] in the direction of \mathbf{e}_k (being \mathbf{e}_k a List element representing the three Cartesian coordinates of a vector in the local basis coordinates). When the rotation is around a canonical local axis, the following syntaxes are allowed for the H_k : "Rx", "Ry" or "Rz". Analogously, when a translation is in the directions of a canonical local axis, the following syntaxes are allowed for the H_k : "Tx", "Ty" or "Tz".

4.3 Angular velocity

```

1 SkewToVec = If[ And @@ (Flatten @ PossibleZeroQ[# + Transpose[#]]),
   {#[[3,2]], #[[1,3]], #[[2,1]]}&;
2 VecToSkew = {{0, -#[[3]], #[[2]]}, {#[[3]], 0, -#[[1]]}, {-#[[2]],
   #[[1]], 0}}&;
3
4 AngularVelocity[xRotationMatrix_List] /; (Dimensions[xRotationMatrix
   ]==={3,3}) :=

```

```

5 Simplify @ (SkewToVec @ ((Transpose @ xRotationMatrix).D[
    xRotationMatrix, t]))

```

SkewToVec converts any 3×3 skew-symmetric List element representing a matrix into a 3 entries List. VecToSkew is its corresponding inverse function.

AngularVelocity obtains the angular velocity, in terms of local basis components (3 entries List), given the corresponding 3×3 List element representing a rotation transformation.

5 Plotting and visualization

5.1 General options

```

1 SetOptions[Plot, BaseStyle -> {FontFamily -> "Arial", FontSize -> 16}];
2 SetOptions[Plot3D, BaseStyle -> {FontFamily -> "Arial", FontSize ->
    14}];
3 SetOptions[ParametricPlot, BaseStyle -> {FontFamily -> "Arial", FontSize
    -> 16}];
4 SetOptions[ParametricPlot3D, BaseStyle -> {FontFamily -> "Arial",
    FontSize -> 14}];
5 SetOptions[ListPlot, BaseStyle -> {FontFamily -> "Arial", FontSize ->
    16}];

```

Package MathMatrixPack sets the FontFamily and FontSize for the following built-in plot functions:

- Plot: Arial, 16
- Plot3D: Arial, 14
- ParametricPlot: Arial, 16
- ParametricPlot3D: Arial, 14
- ListPlot: Arial, 16

5.2 Custom plot

```

1 Style8 = {
2   {Hue[0.6, 1, 1], Thickness[0.005]},
3   {Hue[0.3, 1, 1], Thickness[0.006], Dashed},
4   {Hue[1, 1, 1], Thickness[0.007], Dotted},
5   {Hue[0.1, 1, 1], Thickness[0.005]},
6   {Hue[0.9, 1, 1], Thickness[0.006], Dashed},
7   {Hue[0.5, 1, 1], Thickness[0.007], Dotted},
8   {Hue[0.2, 1, 1], Thickness[0.005]},
9   {Hue[0.8, 1, 1], Thickness[0.006], Dashed}
10  };
11
12 SPlot[xExpression_, xInterval_, xFrameLabel_ : {}, xLegend_ : {},
13       xPlotLabel_String : "", xScale_ : 1.15] :=
14   Module[{xStyle = Style8},
15     TableForm[ {
16       Plot[
17         xExpression,
18         xInterval,
19         PlotStyle -> Style8,
20         PlotRange -> Full,
21         Frame -> True,
22         GridLines -> Automatic,
23         ImageSize -> xScale {500, 300},
24         FrameLabel -> xFrameLabel,
25         PlotLabel -> xPlotLabel
26       ],
27       Graphics[ {
28         Black,
29         Directive[FontFamily -> "Arial", FontSize -> 16],
30         MapIndexed[ Text[#1, {10 (First[#2] - 1) + 6, 0}] &, xLegend],
31         MapIndexed[ Join[
32           Last[xStyle = RotateLeft @ xStyle],
33           {Line[{10 (First[#2] - 1), 0}, {10 (First[#2] - 1) + 3, 0}]}

```



```

34     xLegend
35     ]
36     },
37     ImageSize -> 1.15 {500, 30}]]}
38     ]
39 ];

```

SPlot is a customized version of the built-in function Plot for showing in the same frame up to 8 plots with their respective legends. The corresponding list of styles used in this plot are set in the List element Style8. SPlot syntax requires 5 arguments:

- The first argument must be a List of functions to be plot.
- The second argument must be a List of three elements: the first is the symbol denoting the independent variable, and the second and the third defining the range of this variable.
- The third argument is a List of 2 String elements representing representing the labels of the axes.
- The fourth argument is the title of the plot.
- The fifth argument is a List of legend labels.

For example, consider the following usage of the function:

```

1  SPlot[Sin[# t] & /@ #, {t, 0, Pi/2}, {"t", "Sin(nt)"},
2  "Sin(nt) for several values of n", #] & @ Range[8]

```

The corresponding output is presented in Figure 1.

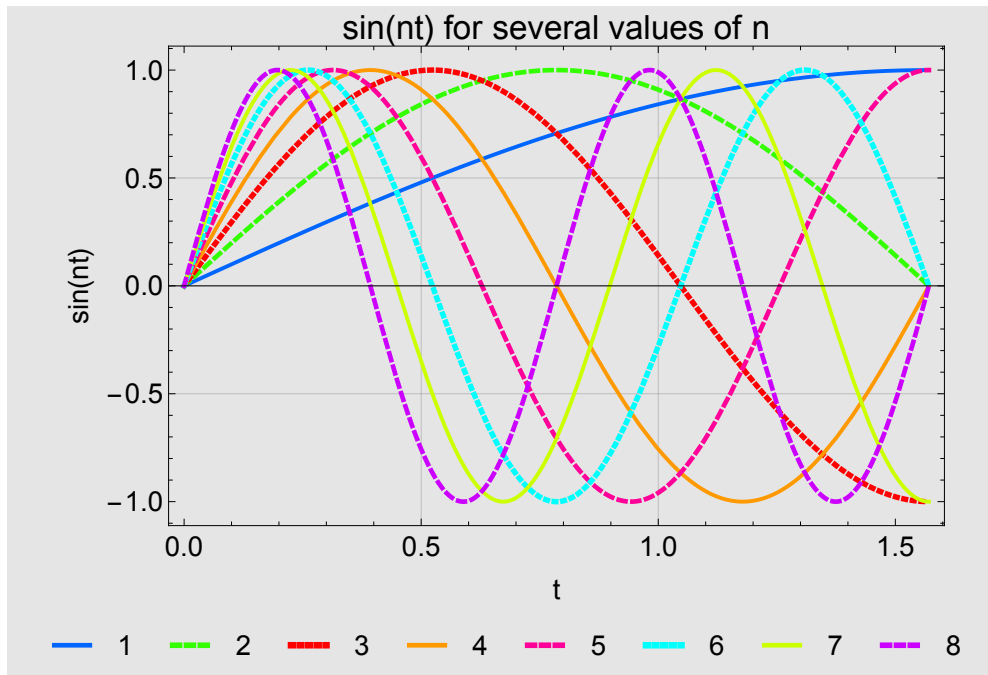


Figure 1: Example of output of the function SPlot

5.3 SMatrixPlot

```

1 SMatrixPlot[xA_Association] /; KeyExistsQ[xA, "Column_Labels"] :=
    MatrixPlot[
2   xA["Matrix"],
3   FrameTicks -> {
4     Transpose[{Range @@ Dimensions @ xA["Row_Labels"], xA["Row_Labels"]}],
5     Transpose[{Range @@ Dimensions @ xA["Column_Labels"], xA["Column_Labels"]}]
6   } /. SymbolReplacements,
7   ColorFunction -> (RGBColor[
8     (0.00130 (1 - #) + 0.99985 #) (2 # - 1)^2,
9     (0.35656 (1 - #) + 0.085864 #) (2 # - 1)^2,
10    (0.56796 (1 - #)) (2 # - 1)^2,
11    0.13 + (2 # - 1)^2
12  ] &),

```

```

13 ColorRules -> {xN_ /; Not @ NumberQ[xN] -> RGBColor[0.63521, 0.99995,
    0.19208]}
14 ]
15
16 SMatrixPlot[xA_Association] := MatrixPlot[
17   Transpose @ {xA["Matrix"]},
18   FrameTicks -> {
19     Transpose[{Range @@ Dimensions @ xA["Row_Labels"], xA["Row_Labels"
20       ]}],
21     Transpose[{Range @@ Dimensions @ {""}, {""}]}]
22   } /. SymbolReplacements,
23   ColorFunction -> (RGBColor[
24     (0.00130 (1 - #) + 0.99985 #) (2 # - 1)^2,
25     (0.35656 (1 - #) + 0.085864 #) (2 # - 1)^2,
26     (0.56796 (1 - #)) (2 # - 1)^2,
27     0.13 + (2 # - 1)^2
28   ] &),
29   ColorRules -> {xN_ /; Not @ NumberQ[xN] -> RGBColor[0.63521, 0.99995,
    0.19208]}
30 ]

```

SMatrixPlot extends the application of the built-in functions MatrixPlot to matrices given by Association elements.

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