

# Bernoulli Factories

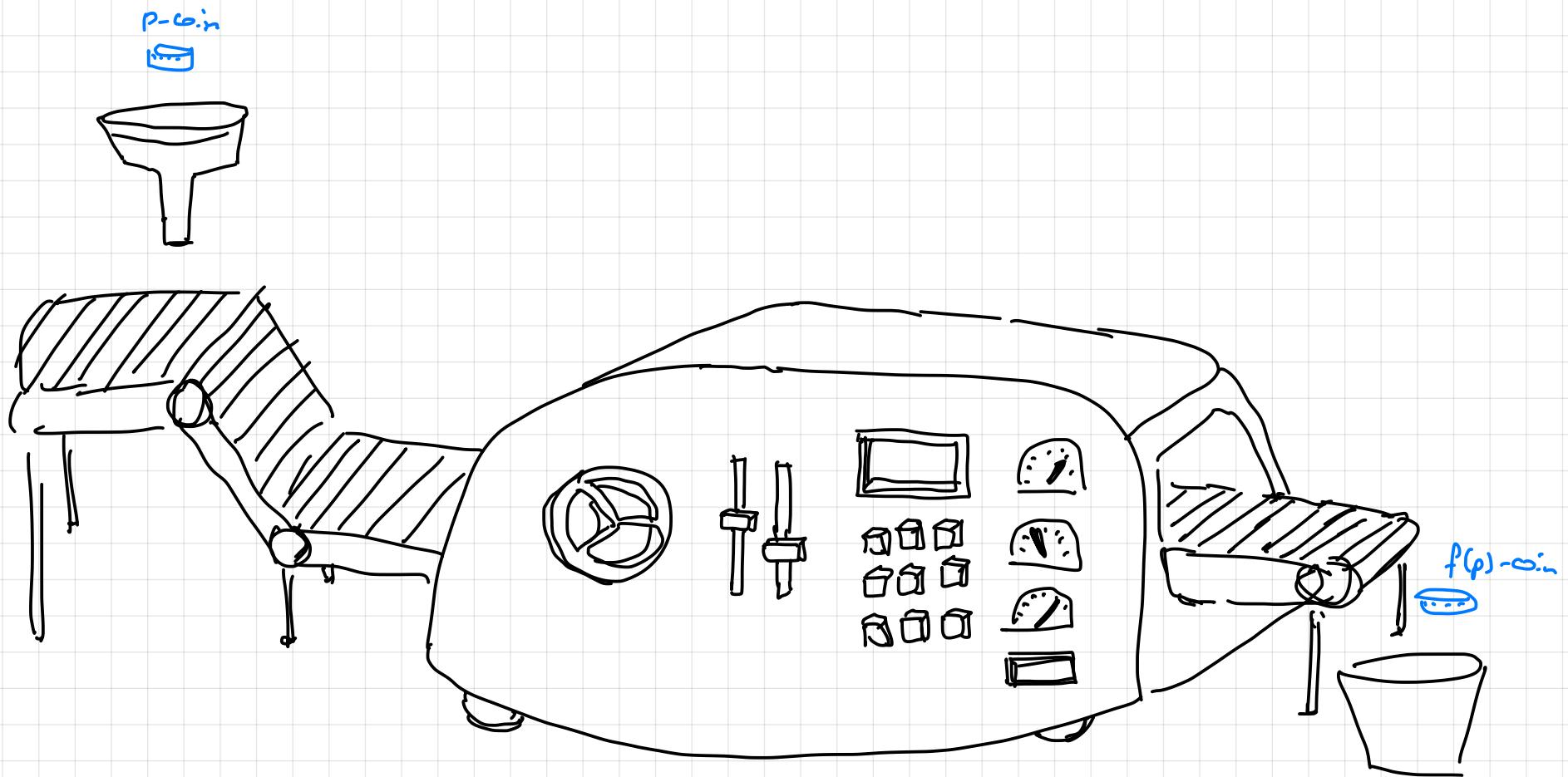
Renato Pees Leme  
(Google Research)



[www.renatoppl.com/bernoulli](http://www.renatoppl.com/bernoulli)

(Bernoulli wearing  
a factory hat)

# Bernoulli Factories



## Examples of Simple Factories

$$\textcircled{1} \quad f(p) = p^2$$

$$\textcircled{2} \quad f(p) = p(1-p)$$

\textcircled{3} Bernstein monomials:

## Single Parameter Bernoulli Factories

Given a function  $f: S \subseteq (0,1) \rightarrow \{0,1\}$ .

design an algorithm (decision tree)

that samples an  $f(p)$ -coin from a  $p$ -coin  
(of unknown bias).

[Keane O'Brien 1994]

## Von Neumann's Procedure

Sample an unbiased coin from a biased one

$$\textcircled{4} \quad f(p) = \frac{1}{2} \quad \text{for } p \in (0,1)$$

## Von Neumann's Procedure

Sample a coin of bias  $x$  from a biased one

- ⑤  $f(p) = x$  for some fixed  $x \in [0, 1]$

# Bernstein Polynomials

(6) Bernstein polynomials  $f(p) = \dots$

$$(7) f(p) = \frac{p}{2-p}$$

## Other Examples

⑧ Moment Generating Functions , e.g.  $f(p) = e^{p-1}$

## Complete Characterization

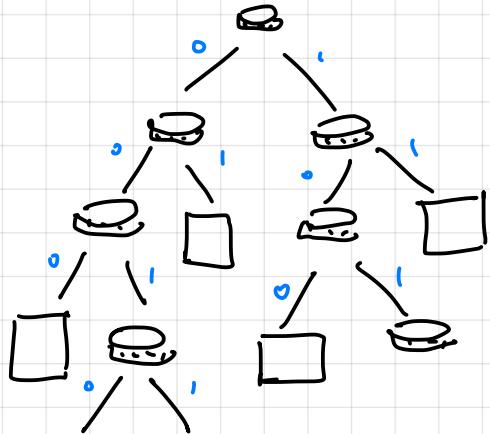
which functions  $f : S \subseteq (0,1) \rightarrow [0,1]$

admit Bernoulli factories?

① What is a general factory?

② Examples of functions that don't admit factories

# Generic Factory



Factory = Decision Tree

Nodes:

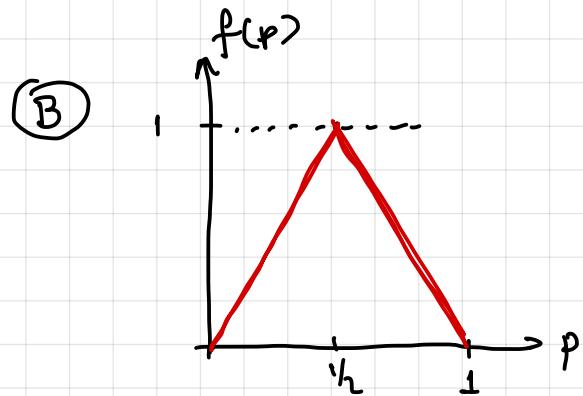
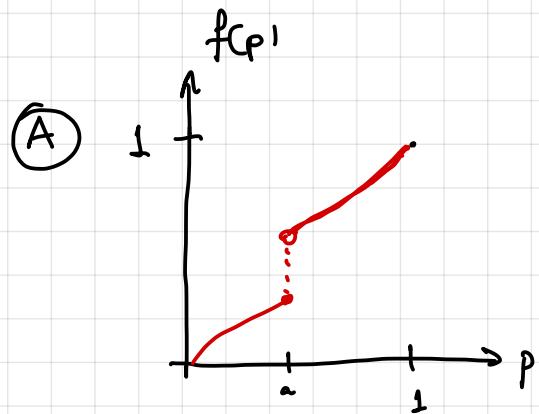
{		( $p$ -coin)
		(helper coin)

• Finite vs Infinite:

• Termination:

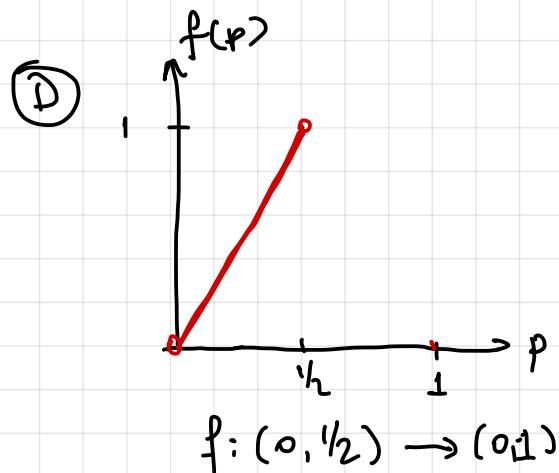
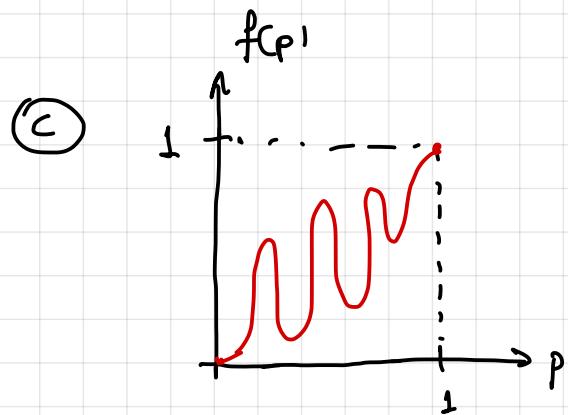
•  $P[F(p)=1] =$

## Functions w/out Factories



## Functions w/out Factories

Test Your Intuition. Which of those functions has a factory?



## Theorem (Keane, O'Brien)

Function  $f: S \subseteq (0,1) \rightarrow (0,1)$  admits a factor if:

(1)  $f$  is continuous

(2)  $f$  is constant or poly-bounded

$$\exists n \text{ s.t. } \min [f(p), 1-f(p)] \geq \min (p^n, (1-p)^n)$$

Proof: Necessity:

Lemma  $\Rightarrow$  Thm

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---

Lemma: Given  $f$  as in Thm, there is a function  $g$  implementable by a finite factory s.t.

$$0 \leq f(p) - \frac{1}{4} g(p) \leq \frac{3}{4}$$

s.t.  $\frac{4}{3} (f(p) - \frac{1}{4} g(p))$  is poly-bounded.

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---

Lemma (Proof by picture)

Lemma: Given  $f$  as in Thm, there is a function  $g$  implementable by a finite factory s.t.

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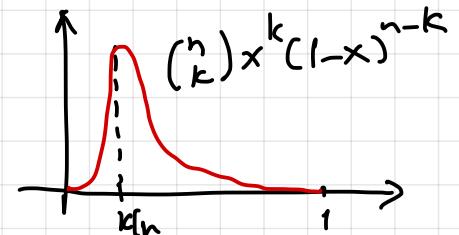
s.t.  $\frac{4}{3} (f(p) - \frac{1}{4} g(p))$  is poly-bounded.

## Alternative Proof (Nagy-Péter)

① Bernstein approximation: given continuous function  $f: [0,1] \rightarrow \mathbb{R}$

$$\text{define } Q_n[f](x) = \sum_{k=0}^n f\left(\frac{k}{n}\right) \binom{n}{k} x^k (1-x)^{n-k}$$

then:  $Q_n[f](x) \rightarrow f(x)$  uniformly.



② Polya's Thm: If  $g(x,y)$  is a real homogeneous polynomial such that.

$g(x,y) > 0 \quad \forall x,y > 0$  then  $\exists n$  s.t all coefficients of  $(x+y)^n g(x,y)$  are non-negative.

Idea: If  $f: (0,1) \rightarrow [\varepsilon, 1-\varepsilon]$  use ① to construct approximations and

② to sketch the functions together in a series.

# Fast Simulation

(Mossel-Perez 2002)  
(Naor-Perez 2005)

$N = \# \text{ coins tossed until output}$  (random variable)

Properties of  $f$

Properties of  $N$

continuous  $\iff N < \infty$  a.s. (i.e it terminates)

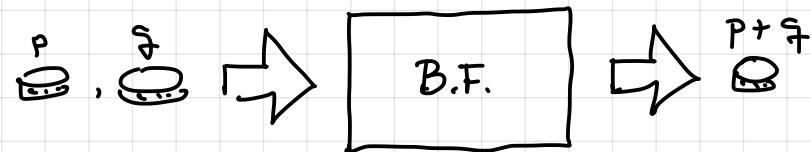
real-analytic  $\iff P(N \leq n) \leq O(p^n)$  exponential tail.  $p = p(f) < 1$ .

Lipschitz  $\iff E[N] < \infty$

rational  $\iff N$  via finite automata

## Problem: Sum of Two Coins

Given two coins  $\begin{array}{c} p \\ \text{\textcircled{H}} \end{array}$ ,  $\begin{array}{c} q \\ \text{\textcircled{T}} \end{array}$  with the promise that  $p+q \leq 1-\varepsilon$ , sample from a  $(p+q)$ -biased coin.

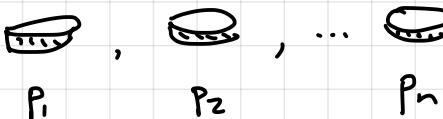
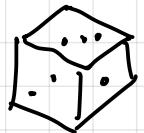


# Coins to Dice

(Mossel - Peres 2002)

(Dushni et al 2017)

(Morino et al 2020)



$$X = \begin{cases} 1 & \text{w.p. } p_1 \\ 2 & \text{w.p. } p_2 \\ \dots \\ n & \text{w.p. } p_n \end{cases}$$

(Bernoulli Race).

## Rational Functions

Factors for  $f(p) = \frac{\sum_{i=0}^k a_i p^i}{\sum_{i=0}^k b_i p^i}$        $f: (0,1) \rightarrow (0,\infty)$ .

① Bernoulli race between two coins ☈ and ☋

## Rational Functions

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- ② Polya's Thm: If  $g(x,y)$  is a real homogeneous polynomial such that  $g(x,y) > 0 \quad \forall x, y > 0$  then  $\exists n$  s.t all coefficients of  $(x+y)^n g(x,y)$  are non-negative.

$$a(x) = \sum_i a_i x^i$$

$$A(x,y) =$$

$$b(x) = \sum_i b_i x^i$$

$$B(x,y) =$$

## Rational Functions



$$P(X=i) = \frac{f_i(x_1 \dots x_n)}{g_i(x_1 \dots x_n)}$$

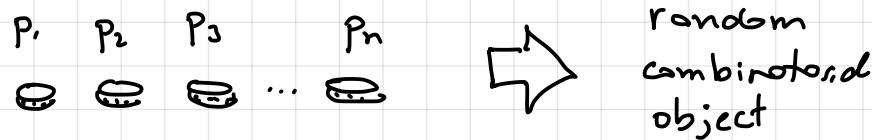
rational.

Polya's Thm: If  $g(x_1 \dots x_m)$  is a real homogeneous polynomial such that  
 $g(x_1 \dots x_m) > 0$  for  $x_i > 0$  then in s.t. all coefficients of  
 $(x_1 + \dots + x_m)^n g(x_1 \dots x_m)$  are positive.

Part II :

## Combinatorial Factories

(Nizadeh, PL, Schneider 2021)



# Random Combinatorial Objects

(1)  $k$ -Subset

(2) Matchings

# Random Combinatorial Objects

(3) Spanning-trees

(4) s-t-flows

# Random Combinatorial Objects

(\*) Vertices of a polytope

Polytope  $P$  contained in  $[0,1]^n$

$V = \text{vertices of } P$

Given coins  s.t.  $p = (p_1 \dots p_n) \in P \cap (0,1)^n$   
output a vertex  $v \in V$  s.t.  $E[v] = p$ .

# General Bernoulli Factory

Output set :  $V$

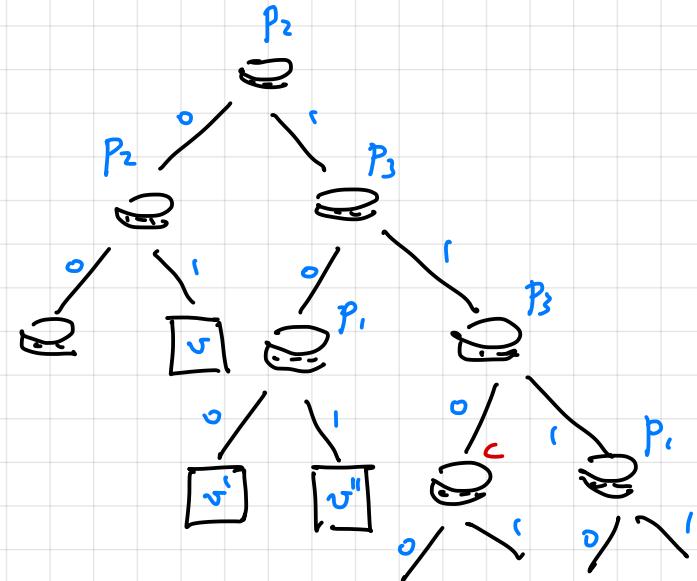
Input coins:  $\text{P}_1 \quad \text{P}_2 \quad \dots \quad \text{P}_j$

Nodes:

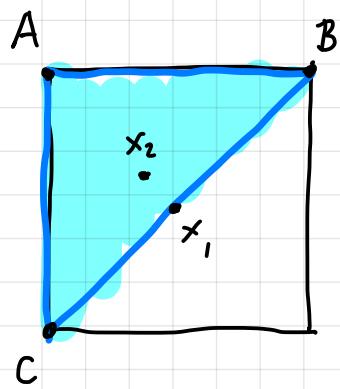
$P_i$ -coin

helper coin (constant  $c$ )

output node ( $v \in V$ )



# Necessary Conditions



Output at  $x_1$ :

Output at  $x_2$ :

# Factory for k-Subset

Natural Algorithms:



# Factory for k-Subset

Sampford Sampling

$$P[\text{sample } S] = \prod_{i \in S} p_i \prod_{i \notin S} (1-p_i)$$



Algorithm

Flip each coin  $X_i$ :

$$S = \{i; X_i = 1\}$$

if  $|S| \neq k$  restart



output  $S$

## A Guess

For every polytope  $P = \{x \in [0,1]^n; Wx = b\}$  we can

find polynomials  $f_{v,r}(p_1, \dots, p_n)$  such that:

$$(1) \sum_{v \in V} f_{v,r}(p_1, \dots, p_n) \cdot (p - v) = 0 \quad \forall p \in P.$$

(2)  $f_{v,r}(p_1, \dots, p_n)$  are implementable by a Bernoulli factory

$$f_{v,r}(p) =$$

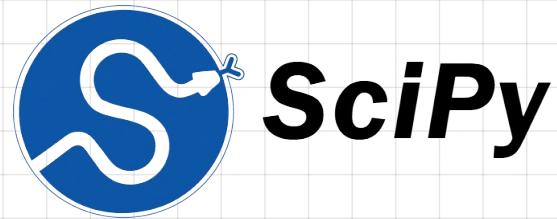
Solve a Program

$$f_v(p) =$$

$$\sum_v f_v(p) \cdot (p - v) = 0 \quad \forall p \text{ s.t. } Wp = b$$



(Manipulate polynomials)



(Solve linear programs)

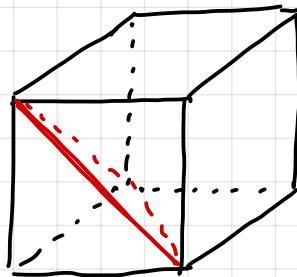
## Next Simplest Example

Towards co-dimension 1:  $P = \{x \in [0,1]^n; w^T x = b\}$ .

Simplest case we didn't understand:  $\sum_i x_i = \alpha \quad \alpha \notin \mathbb{Z}$ .

Example:  $n=3 \quad \alpha = 1.5$

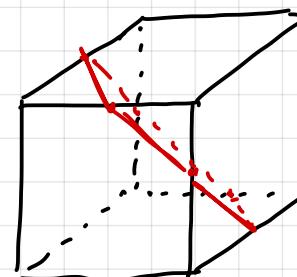
What are the vertices?



$$\alpha = 1$$

$$|V|=3$$

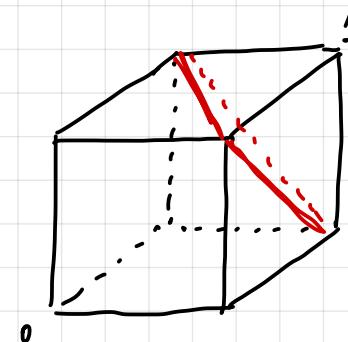
permutations  
of  $(1,0,0)$



$$\alpha = 1.5$$

$$|V|=6$$

permutations  
of  $(1, \frac{1}{2}, 0)$



$$\alpha = 2$$

$$|V|=3$$

permutations  
of  $(1,1,0)$

## Next Simplest Example

Towards co-dimension 1:  $P = \{x \in [0,1]^n; w^T x = b\}$ .

Simplest case we didn't understand:  $\sum_i x_i = \alpha \quad \alpha \notin \mathbb{Z}$ .

In general:  $n, \alpha = k - \varepsilon \quad 0 < \varepsilon < 1$

$V$  = permutations of  $(\underbrace{1, 1, \dots, 1}_{k-1}, \underbrace{1-\varepsilon, 0, \dots, 0}_{n-k})$

Start with  $n=3 \quad k=1+\varepsilon$  (simplest unknown example).

If polynomials exist we should be able to find it. After stems of the solutions for very long:

$$f_v(P) =$$

## Co-dimension One

$$P = \{x \in [0,1]^n; w^T x = b\}.$$

Generic hyperplane  $\Rightarrow$  Each vertex has one special index.  
avoiding  $\{0,1\}^n$

$$w_i \in (0,1)$$

$$f_v(p) = |w_i| \cdot p_i (1-p_i) \prod_{j: w_j=1} p_j \prod_{j: w_j=0} (1-p_j)$$

Non-generic hyperplanes:

## Co-dimension One

$$P = \{x \in [0,1]^n; w^T x = b\}. \quad f_v(x) = |w_i| x_i (1-x_i) \prod_{j:v_j=1} x_j \prod_{j:v_j=0} (1-x_j)$$

Proof idea:  $\sum_v (v - x) f_v(x) = 0$

Vertices  $v \in V \iff$  pairs  $(A, i)$  s.t.

$$\frac{b - w(A)}{w_i} \in \{0, 1\}$$

$$w(A) = \sum_{j \in A} w_j$$

$$v \in (A, i)$$

Define  $P_A(x) = \prod_{i \in A} x_i \prod_{i \notin A} (1-x_i)$  s.t.  $f_{(A,i)}(x) = |w_i| \cdot x_i P_A(x)$

Look at coordinate  $i$  of  $\sum_{(A,i)} (v_i - x_i) f_v(x) = 0$

$$\sum_{\substack{(A,i) \\ 1 \notin A \\ i \neq i}} (0 - x_i) f_{(A,i)}(x) + \sum_{\substack{(A,i) \\ i \in A}} (1 - x_i) f_{(A,i)}(x) + \sum_{\substack{(A,i) \\ i = i}} \left( \frac{b - w(A)}{w_i} - x_i \right) f_{(A,i)}(x) = 0$$

# Any dimension

$$P(x) = \{ x \in \mathbb{R}^n ; Wx = b \} \quad W: k \times n \text{ matrix of rank } k.$$

Vertex  $v$  of  $P$  corresponds to a partition:  $(A, S, B)$

$$A = \{ i ; v_i = 0 \}$$

$$B = \{ i ; v_i = 1 \}$$

$$S = \{ i ; 0 < v_i < 1 \}$$

$$W = \begin{array}{c|c|c} A & S & B \\ \hline w_A & w_S & w_B \end{array}$$

$$v_A = 0_A \quad v_B = 1\mathbb{1}_B$$

$$v_S = w_S^{-1} (b - w_B 1\mathbb{1})$$

Generic subspace  $Ax = b$ :

$$f_v(p) = \boxed{\prod_{i \in A} p_i \prod_{i \in B} (1-p_i) \prod_{i \in S} p_i (1-p_i)}$$

# Factory for Matching

Matching is a bijection  $\pi: [n] \rightarrow [n]$ .

$$f_\pi(p) = \prod_{i=1}^n p_{\pi(i)} \sum_{T \in \text{Arb}_1} \prod_{(u,v) \in T} x_{u,\pi(v)}$$

Algorithm:

Choose a random matching  $\pi$ .

Sample  $\mathbb{P}_{\pi, T(G)}$   $\forall i$ . If any 0, restart.

Pick random spanning tree on  $K_n$ .

Orient edges of  $T$  towards 1.

For each  $(i,j) \in T$ , sample  $\mathbb{P}_{\pi, T(i)}$

If any 0, restart.

Output matching  $\pi$ .

# Application to Mechanism Design

Mechanism Design Setup:  $n$  agents + space of outcomes  $X$ .

- allocations of items to agents
- flows/paths in a graph
- scheduling

Preference/type is a mapping:  $v_i: X \rightarrow \mathbb{R}$ . (private to agents).

Designer wants to optimize welfare  $\sum_{i=1}^n v_i(x)$ .

Two problems: (1) How to compute optimal allocation?

(2) How to incentivize agents to report truthfully?

Is there any reduction from (1) to (2)? Assume  $A(v_1, \dots, v_n)$

- Yes! If  $A$  is the optimal algorithm (Vickrey-Clarke-Groves 60s-70s)
- No, otherwise, without any prior about the valuations.

## Application to Mechanism Design

However if  $v_i \sim F_i$  iid. it is possible to come up with "BIC"-reductions:

- Yes! If types are single-parameter (Hartline - Lucier 2010)
- Yes\*, in general (Hartline - Kleinberg - Malekian 2011)

Algorithm  $A \Rightarrow$  Mechanism  $M$  that is  $\varepsilon$ -BIC and

$$E[\text{welfare}(M)] \geq E[\text{welfare}(A)] - \varepsilon.$$

Technique: Replica-Surrogate Matching

- Yes, in general (Dughmi - Hartline - Kleinberg - Nicaeekh 2017)

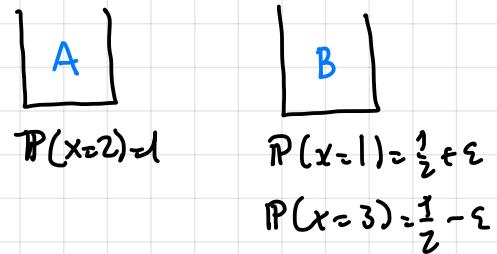
Extra Ingredient is a Bernoulli Factory

# Simple Mechanism Design Problem

- One agent with valuation  $v: X \rightarrow \mathbb{R}$
- $k$  urns, each with a distribution  $F_1, \dots, F_k$  on  $X$ .
- Designer has only sample access wants to maximize  $\mathbb{E}_{x \sim F_i} [v(x)]$ .

- Example:  $X = \{1, 2, 3\}$   $v(1) = 1$   $v(2) = 2$   $v(3) = 3$ .

Two urns ( $k=2$ ).



- Alternative: Choose an urn with probability proportional to  $\mathbb{E}_{x \sim F_j} \exp(\lambda(v(x)-1))$   
+ implicit payment computation (Babaioff, Kleinberg, Slivkins 2013)

## Some Open Problems

(1) What are the conditions for  $f: (0,1)^n \rightarrow (0,1)$  to admit a factory?

- how does the notion of poly-bounded generalize?

$$f(p) \geq \min(p_1, 1-p_1, p_2, 1-p_2, \dots, p_n, 1-p_n)^n \text{ for some } n ?$$

- Nach-Perez proof probably works for  $f: (0,1)^n \rightarrow (\varepsilon, 1-\varepsilon)$ .

(2) Remove "bounded-variation" from Keene-O'Brien proof.

## Some Open Problems

(3) Dealing with  $\{0,1\}$ -values. E.g. extend results to  $f: [0,1] \rightarrow [0,1]$ .

E.s. Can we extend Sampford sampling to the boundary?

Not with an exponential tail.

## Some Open Problems

(4) Sample complexity : how many samples to obtain a matching or a  $k$ -subset ? How optimized are the current factors with respect to  $\mathbb{E}[N]$  ?

For combinatorial factors  $\mathbb{E}[N] \sim \frac{n|V|}{\sum_v P_v(p)}$

(5) Explicit factories for other polytopes : e.g. flows / circulations.  
Non-limit construction for generic polytopes.

(6) Other applications to Game Theory / Mechanism Design  
(e.g. Cai et al on revenue-preserving reductions)

Slides, Lecture Notes, References:

[www.renatoppl.com/bernoulli](http://www.renatoppl.com/bernoulli)

Thanks!