

Øving 5

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Oppgave 1

- a) A - 03 D - 01
B - 02 E - 05
C - 04 F - 06

- b) Siden t_1 og t_2 skjer ved topper kan vi si at

$$\frac{|h(t_1)|}{|h(t_2)|} = \frac{|0,8|}{|-0,25|} = \frac{0,8}{0,25}$$
$$= \frac{e^{-\alpha t_1}}{e^{-\alpha t_2}} = e^{\alpha(t_2 - t_1)} = e^{\frac{\alpha \pi}{\beta}} \quad (*)$$

Ønsker å finne $\zeta = \sin \varphi = \sin(\tan^{-1}(\frac{\alpha}{\beta}))$

$$(*) \Rightarrow \frac{\alpha}{\beta} \pi = \ln\left(\frac{0,8}{0,25}\right)$$

$$\Rightarrow \zeta = \sin\left(\tan^{-1}\left(\frac{\ln(0,8)/\ln(0,25)}{\pi}\right)\right)$$

$$= 0,35$$

B

Oppgave 2

$$\begin{aligned} a) \quad \dot{x}_1 &= \frac{1}{m_1 c_1} (u_1 - g_1(x_1 - x_2)) \\ \dot{x}_2 &= \frac{1}{m_2 c_2} (g_1(x_1 - x_2) + q p c_2 v_1 - q p c_2 x_2 - g_2(x_2 - v_2)) \end{aligned}$$

Hvis vi ser bort fra dynamikken i varmebeholder
betyr det at $\dot{x}_1 = 0$

$$\Rightarrow u_1 = g_1(x_1 - x_2)$$

$$\Leftrightarrow x_1 = x_2 + \frac{u_1}{g_1}$$

Det gir

$$\begin{aligned} \dot{x}_2 &= \frac{1}{m_2 c_2} (u_1 + q p c_2 (v_1 - x_2) - g_2(x_2 - v_2)) \\ &= \underbrace{-\frac{1}{m_2 c_2} (q p c_2 + g_2)}_{= -\frac{1}{T}} x_2 + \frac{1}{m_2 c_2} u_1 + \frac{1}{m_2 c_2} q p c_2 v_1 + \frac{g_2}{m_2 c_2} v_2 \end{aligned}$$

$$\Rightarrow T = \frac{m_2 c_2}{q p c_2 + g_2}$$

b) Finner K ved å ignorere forstyrrelser og se på steady state:

$$\Rightarrow 0 = -\frac{1}{\cancel{m_2 c_2}} (q p c_2 + q_2) + \frac{1}{\cancel{m_2 c_2}} u_1$$

$$\Leftrightarrow x_2 = \frac{1}{q p c_2 + q_2} u_1 = K u_1$$

$$\Rightarrow K = \frac{1}{\underline{\underline{q p c_2 + q_2}}}$$

c) Forstyrrelsesleddene fra forrige side er $\frac{1}{\cancel{m_2 c_2}} \vec{z}_1$

$$V = \cancel{m_2 c_2} \cdot \left(\frac{q p c_2}{\cancel{m_2 c_2}} V_1 + \frac{q_2}{\cancel{m_2 c_2}} V_2 \right)$$

$$= q p c_2 V_1 + q_2 V_2$$

Oppgave 3

$$\begin{aligned} a) \quad k_1(t) &= \mathcal{L}^{-1} \left\{ \frac{1}{s} \cdot h_1(s) \right\} \\ &= \mathcal{L}^{-1} \left\{ \frac{e^{-\tau s}}{s} \right\} \\ &= \mu_1(t - \tau) \end{aligned}$$

$$b) \quad k_2(t) = \mathcal{L}^{-1} \left\{ \frac{1}{s} h_2(s) \right\}$$

$$\frac{1 - \frac{\tau}{2}s + \frac{\tau^2}{8}s^2}{s(1 + \frac{\tau}{2}s + \frac{\tau^2}{8}s^2)} = \frac{A}{s} + \frac{Bs + C}{1 + \frac{\tau}{2}s + \frac{\tau^2}{8}s^2}$$

$$\Rightarrow 1 - \frac{\tau}{2}s + \frac{\tau^2}{8}s^2 = A(1 + \frac{\tau}{2}s + \frac{\tau^2}{8}s^2) + Bs^2 + Cs$$

$$\Rightarrow s^2: \quad \frac{\tau^2}{8} = \frac{\tau^2}{8}A + B$$

$$s^1: \quad -\frac{\tau}{2} = A\frac{\tau}{2} + C$$

$$s^0: \quad 1 = A$$

$$\Rightarrow A=1, B=0, C=-\tau$$

$$\Rightarrow \frac{1}{s} h_2(s) = \frac{1}{s} - \frac{\tau}{1 + \frac{\tau}{2}s + \frac{\tau^2}{8}s^2}$$

$$= \frac{1}{s} - \frac{\frac{8}{\tau}}{\underbrace{\frac{8}{\tau^2}s^2 + \frac{4}{\tau}s + 1}_{s^2 + 2\zeta\omega_0 s + \omega_0^2}}$$

$$\Rightarrow \omega_0 = \sqrt{\frac{8}{\tau^2}} = \frac{2\sqrt{2}}{\tau}$$

$$\zeta = \frac{4}{\tau} \cdot \frac{1}{2 \cdot \omega_0} = \frac{2}{2\sqrt{2}} = \frac{\sqrt{2}}{2}$$

Bruger formell 11 i app. B.

$$\begin{aligned} \mathcal{L}^{-1} \left\{ \frac{1}{s^2 + 2\zeta\omega_0 s + \omega_0^2} \right\} &= \frac{1}{\omega_0 \sqrt{1-\zeta^2}} e^{-\zeta\omega_0 t} \sin(\sqrt{1-\zeta^2}\omega_0 t) \\ &= \frac{\tau}{2} e^{-\frac{2}{\tau}t} \sin\left(\frac{2}{\tau}t\right) \end{aligned}$$

Siden $\mathcal{L}^{-1}\left\{\frac{1}{s}\right\} = \mu_1(t)$ får vi

$$\begin{aligned} k_2(t) &= \mu_1(t) - \frac{8}{\tau} \cdot \frac{\tau}{2} e^{-\frac{2}{\tau}t} \sin\left(\frac{2}{\tau}t\right) \\ &= \mu_1(t) - 4e^{-\frac{2}{\tau}t} \sin\left(\frac{2}{\tau}t\right) \end{aligned}$$

