

Öving 12

4.2

$$1) \quad \begin{cases} v = y' \\ v' + 2v - 3y = 0 \end{cases} \Leftrightarrow \begin{cases} y' = v \\ v' = -2v + 3y \end{cases}$$

$$2) \quad \begin{cases} v = y' \\ v' + 4v + y = 0 \end{cases} \Leftrightarrow \begin{cases} y' = v \\ v' = -4v - y \end{cases}$$

5.7

$$1) \quad \vec{x}' = A\vec{x}, \quad \vec{v}_1 = \begin{pmatrix} -3 \\ 1 \end{pmatrix} \text{ with } \lambda_1 = 4$$

$$\vec{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix} \text{ with } \lambda_2 = 2$$

The general solution is

$$\vec{x}(t) = C_1 \begin{pmatrix} -3 \\ 1 \end{pmatrix} e^{4t} + C_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{2t}$$

$$\text{We want } \vec{x}(0) = \begin{pmatrix} -6 \\ 1 \end{pmatrix}$$

$$\begin{aligned} \vec{x}(0) &= C_1 \begin{pmatrix} -3 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 1 \end{pmatrix} \\ &= \begin{pmatrix} -3 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} -6 \\ 1 \end{pmatrix} \end{aligned}$$

$$\Rightarrow \left(\begin{array}{cc|c} -3 & -1 & -6 \\ 1 & 1 & 1 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1/3 & 2 \\ 1 & 1 & 1 \end{array} \right)$$

$$\sim \left(\begin{array}{cc|c} 1 & 1/3 & 2 \\ 0 & 2/3 & -1 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1/3 & 2 \\ 0 & 1/3 & -1/2 \end{array} \right)$$

$$\sim \left(\begin{array}{cc|c} 1 & 0 & 5/2 \\ 0 & 1/3 & -1/2 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 0 & 5/2 \\ 0 & 1 & -3/2 \end{array} \right)$$

$$\Rightarrow \vec{x}(t) = \frac{5}{2} \begin{pmatrix} -3 \\ 1 \end{pmatrix} e^{4t} - \frac{3}{2} \begin{pmatrix} -1 \\ 1 \end{pmatrix} e^{2t}$$

3) We want to solve $\vec{x}'(t) = A\vec{x}(t)$
with $A = \begin{pmatrix} 2 & 3 \\ -1 & -2 \end{pmatrix}$

Eigenvalues:

$$\det(A - \lambda I) = 0$$

$$(2 - \lambda)(-2 - \lambda) + 3 = 0$$

$$2(-2) - 2\lambda - \lambda(-2) + \lambda^2 + 3 = 0$$

$$\lambda^2 - 2\lambda + 2\lambda - 4 + 3 = 0$$

$$\lambda^2 - 1$$

$$|\lambda| = 1$$

$$\lambda_1 = 1, \lambda_2 = -1$$

Eigenvectors:

1) $(A - I)\vec{v}_1 = \vec{0}$, solving for \vec{v}_1

$$\begin{pmatrix} 2-1 & 3 \\ -1 & -2-1 \end{pmatrix} = \begin{pmatrix} 1 & 3 \\ -1 & -3 \end{pmatrix} \sim \begin{pmatrix} 1 & 3 \\ 0 & 0 \end{pmatrix}$$

$$x_1 = -3x_2, x_2 \text{ free}$$

$$\vec{v}_1 = \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

2) $(A + I)\vec{v}_2 = \vec{0}$, solving for \vec{v}_2

$$\begin{pmatrix} 2+1 & 3 \\ -1 & -2+1 \end{pmatrix} = \begin{pmatrix} 3 & 3 \\ -1 & -1 \end{pmatrix} \sim \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$$

$$x_1 = -x_2, x_2 \text{ free}$$

$$\vec{v}_2 = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

So the general solution to $\vec{x}' = A\vec{x}$ is

$$\vec{x}(t) = c_1 \begin{pmatrix} -3 \\ 1 \end{pmatrix} e^t + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t}$$

We want $\vec{x}(0) = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$

$$\vec{x}(0) = \begin{pmatrix} 3 \\ 2 \end{pmatrix} = c_1 \begin{pmatrix} -3 \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow \left(\begin{array}{cc|c} -3 & -1 & 3 \\ 1 & 1 & 2 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1/3 & -1 \\ 1 & 1 & 2 \end{array} \right)$$

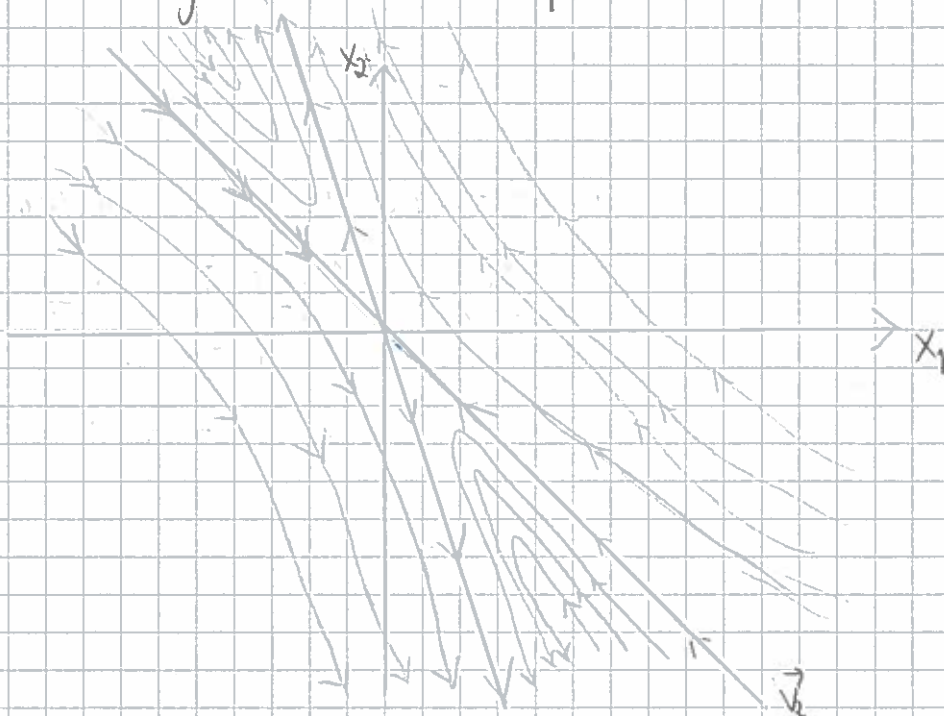
$$\sim \left(\begin{array}{cc|c} 1 & 1/3 & -1 \\ 0 & 2/3 & 3 \end{array} \right) \sim \left(\begin{array}{cc|c} 1 & 1/3 & -1 \\ 0 & 1/3 & 3/2 \end{array} \right)$$

$$\sim \left(\begin{array}{cc|c} 1 & 0 & -5/2 \\ 0 & 1 & 9/2 \end{array} \right)$$

So we get:

$$\vec{x}(t) = -\frac{5}{2} \begin{pmatrix} -3 \\ 1 \end{pmatrix} e^t + \frac{9}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{-t}$$

The origin is a saddle point.



9) Want to solve $\vec{x}' = A\vec{x}$ for $A = \begin{pmatrix} -3 & 2 \\ -1 & -1 \end{pmatrix}$.

Eigenvalues: $\det(A - \lambda I) = 0$

$$(-3-\lambda)(-1-\lambda) + 2 = 0$$

$$\cancel{(-1)}(3-\lambda)\cancel{(-1)}(1+\lambda) + 2 = 0$$

$$3 + 4\lambda + \lambda^2 + 2 = 0$$

$$\lambda^2 + 4\lambda + 5 = 0$$

$$\Rightarrow \lambda_{1,2} = \frac{-4 \pm \sqrt{4^2 - 4 \cdot 5}}{2}$$

$$= \frac{-2 \pm \sqrt{-4}}{2}$$

$$= -2 \pm \frac{2i}{2}$$

$$= -2 \pm i$$

$$\lambda_1 = -2 + i, \lambda_2 = \overline{\lambda_1} = -2 - i$$

Eigenvectors: solve $(A - (-2+i)I)\vec{v}_1 = \vec{0}$ for \vec{v}_1 .

$$\begin{pmatrix} -3+2-i & 2 \\ -1 & -1+2-i \end{pmatrix} \Leftrightarrow \begin{pmatrix} -1-i & 2 \\ -1 & 1-i \end{pmatrix}$$

Since this matrix acts on \mathbb{C}^2 and its rows are linearly dependent we get $\vec{v}_1 = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$, $(-1-i)v_1 + 2v_2 = 0$

v_2 free

$$\Rightarrow v_1 = -\frac{2}{-1-i} v_2$$

$$= \frac{2}{1+i} \frac{(1-i)}{(1-i)} v_2$$

$$= \left(\frac{2}{1+i} - \frac{2i}{1+i} \right) v_2$$

$$= (1-i) v_2$$

$$\vec{v}_1 = \begin{pmatrix} 1-i \\ 1 \end{pmatrix} \text{ corresponds to } \lambda_1 = -2+i$$

$$\vec{v}_2 = \overline{\vec{v}_1} = \begin{pmatrix} 1+i \\ 1 \end{pmatrix} \quad \lambda_2 = -2-i$$

So the general solution to $\vec{x}' = A\vec{x}$ is:

$$\vec{x}(t) = z_1 \underbrace{\begin{pmatrix} 1-i \\ 1 \end{pmatrix} e^{(-2+i)t}}_{\vec{x}_1(t)} + z_2 \underbrace{\begin{pmatrix} 1+i \\ 1 \end{pmatrix} e^{(-2-i)t}}_{\vec{x}_2(t)}$$

$z_1, z_2 \in \mathbb{C}$

To get the real solution we look at the real and imaginary part of \vec{x}_1 .

$$\begin{aligned} \vec{x}_1 &= e^{-2t} \begin{pmatrix} 1-i \\ 1 \end{pmatrix} (\cos t + i \sin t) \\ &= e^{-2t} \begin{pmatrix} \cos t + i \sin t - i \cos t + \sin t \\ \cos t + i \sin t \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{y}_1 &= \operatorname{Re} \vec{x}_1(t) \\ &= e^{-2t} \begin{pmatrix} \cos t + \sin t \\ \cos t \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{y}_2 &= \operatorname{Im} \vec{x}_1(t) \\ &= e^{-2t} \begin{pmatrix} \sin t - \cos t \\ \sin t \end{pmatrix} \end{aligned}$$

So the general real solution is

$$\vec{y} = c_1 \begin{pmatrix} \cos t + \sin t \\ \cos t \end{pmatrix} e^{-2t} + c_2 \begin{pmatrix} \sin t - \cos t \\ \sin t \end{pmatrix} e^{-2t}$$

All trajectories tend to the origin and they will oscillate in some way, often like a spiral, toward the origin.

6.1

$$6) \vec{x} = \begin{pmatrix} 6 \\ -2 \\ 3 \end{pmatrix}, \quad \vec{w} = \begin{pmatrix} 3 \\ -1 \\ -5 \end{pmatrix}$$

$$\frac{\vec{x} \cdot \vec{w}}{\vec{x} \cdot \vec{x}} \vec{x} = \frac{18 + 2 - 15}{36 + 4 + 9} \vec{x}$$

$$= \frac{5}{49} \vec{x}$$

$$= \begin{pmatrix} \frac{30}{49} \\ -\frac{10}{49} \\ \frac{15}{49} \end{pmatrix}$$

$$9) \text{ Normalize the vector: } \vec{x} = \begin{pmatrix} -30 \\ 40 \end{pmatrix}$$

$$\|\vec{x}\| = \sqrt{(-30)^2 + 40^2}$$

$$= \sqrt{900 + 1600}$$

$$= 50$$

The unit vector in the same direction

$$\text{is then } \frac{\vec{x}}{\|\vec{x}\|} = \begin{pmatrix} -3/5 \\ 4/5 \end{pmatrix}$$

$$10) \vec{x} = \begin{pmatrix} -6 \\ 4 \\ -3 \end{pmatrix}, \quad \|\vec{x}\| = \sqrt{6^2 + 4^2 + 3^2}$$

$$= \sqrt{36 + 16 + 9}$$

$$= \sqrt{61}$$

The unit vector with the same direction

$$\text{is then } \frac{\vec{x}}{\|\vec{x}\|} = \begin{pmatrix} -6/\sqrt{61} \\ 4/\sqrt{61} \\ -3/\sqrt{61} \end{pmatrix}$$

$$15) \quad \vec{a} = \begin{pmatrix} 8 \\ -5 \end{pmatrix}, \quad \vec{b} = \begin{pmatrix} -2 \\ -3 \end{pmatrix}$$

$$\vec{a} \cdot \vec{b} = -16 + 15 = -1 \neq 0$$

So \vec{a} and \vec{b} are not orthogonal

$$16) \quad \vec{u} = \begin{pmatrix} 12 \\ 3 \\ -5 \end{pmatrix}, \quad \vec{v} = \begin{pmatrix} 2 \\ -3 \\ 3 \end{pmatrix}$$

$$\vec{u} \cdot \vec{v} = 24 - 9 - 15 = 0$$

So \vec{u} and \vec{v} are orthogonal

$$26) \quad \vec{u} = \begin{pmatrix} 5 \\ -6 \\ 7 \end{pmatrix}$$

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

$$\vec{u} \cdot \vec{x} = 5x_1 - 6x_2 + 7x_3 = 0$$

This is a plane.

We also know that

$$\vec{u} \cdot \vec{x} = \vec{u}^T \vec{x} = 0$$

Now the set of all \vec{x} is $\text{Nul}(\vec{u}^T)$.

• The nullspace of an $m \times n$ matrix is a subspace of \mathbb{R}^n . (Theorem 2, pg. 217)

$\vec{u}^T = \begin{pmatrix} 5 & -6 & 7 \end{pmatrix}$ is a 1×3 matrix so by theorem 2 it is a subspace of \mathbb{R}^3 .

29) All vectors in W can be written as a linear combination of $\vec{v}_1, \dots, \vec{v}_p$.
So any vector $\vec{u} \in W$ is of the form

$$\vec{u} = c_1 \vec{v}_1 + \dots + c_p \vec{v}_p$$

$$\begin{aligned} \Rightarrow \vec{u} \cdot \vec{x} &= (c_1 \vec{v}_1 + \dots + c_p \vec{v}_p) \cdot \vec{x} \\ &= c_1 \vec{v}_1 \cdot \vec{x} + \dots + c_p \vec{v}_p \cdot \vec{x} \\ &= 0 + \dots + 0 \quad \text{since } \vec{x} \cdot \vec{v}_j = 0 \\ &= 0 \end{aligned}$$

$\vec{u} \cdot \vec{x} = 0$ for any vector $\vec{u} \in W$ so \vec{x} is orthogonal to every vector in W .

Extra: def $\vec{u} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \vec{v} = \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$

$$\vec{w} = \begin{pmatrix} 4 \\ -1 \\ -1 \end{pmatrix}$$

So we want $\vec{w} \cdot (c_1 \vec{u} + c_2 \vec{v}) = 0$

$$\Leftrightarrow \vec{w}^T (c_1 \vec{u} + c_2 \vec{v}) = 0$$

So we have to find a vector $c_1 \vec{u} + c_2 \vec{v} = \vec{x}$ in $\text{Nul}(\vec{w}^T)$

$$\vec{w}^T = (4 \quad -1 \quad -1)$$

$$x_1 = \frac{1}{4}x_2 + \frac{1}{4}x_3$$

x_2, x_3 free

$$\text{Nul}(\vec{W}^T) = \text{span} \left\{ \begin{pmatrix} 1 \\ 4 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 4 \end{pmatrix} \right\}$$

Have to find a vector in $\text{Nul}(\vec{W}^T)$, \vec{x} ,
such that $\vec{x} = c_1 \begin{pmatrix} 1 \\ 4 \\ 0 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ 0 \\ 4 \end{pmatrix}$

$$\frac{1}{2} \begin{pmatrix} 1 \\ 4 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 0 \\ 4 \end{pmatrix} = \begin{pmatrix} 3/2 \\ 2 \\ 4 \end{pmatrix} \in \text{Nul}(\vec{W}^T)$$

$$\text{If } c_1 = \frac{1}{2} \text{ and } c_2 = 1, \vec{x} = \begin{pmatrix} 1/2 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 3/2 \\ 2 \\ 4 \end{pmatrix} \in \text{Nul}(\vec{W}^T)$$

So $\frac{1}{2} \vec{u} + \vec{v}$ is a linear combination
of \vec{u} and \vec{v} , which when dotted with
 \vec{w} gives 0.

6.2

$$\Rightarrow \vec{u}_1 = \begin{pmatrix} 2 \\ 3 \end{pmatrix}, \vec{u}_2 = \begin{pmatrix} 6 \\ 4 \end{pmatrix}, \vec{x} = \begin{pmatrix} 9 \\ -7 \end{pmatrix}$$

$$\vec{u}_1 \cdot \vec{u}_2 = 12 - 12 = 0$$

\vec{u}_1, \vec{u}_2 are linearly dependent vectors in \mathbb{R}^2 so
they form a basis for \mathbb{R}^2 .

$$\vec{x} = c_1 \vec{u}_1 + c_2 \vec{u}_2$$

$$\text{where } c_1 = \frac{\vec{u}_1 \cdot \vec{x}}{\vec{u}_1 \cdot \vec{u}_1} = \frac{18 + 21}{4 + 9} = \frac{39}{13} = 3$$

$$c_2 = \frac{\vec{u}_2 \cdot \vec{x}}{\vec{u}_2 \cdot \vec{u}_2} = \frac{54 - 28}{36 + 16} = \frac{26}{52} = \frac{1}{2}$$

$$\text{So } \vec{x} = 3\vec{u}_1 + \frac{1}{2}\vec{u}_2$$

$$\begin{aligned}
 11) \quad \text{proj}_{\begin{pmatrix} 4 \\ 2 \end{pmatrix}} \begin{pmatrix} 1 \\ 7 \end{pmatrix} &= \frac{\begin{pmatrix} -4 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 7 \end{pmatrix}}{\begin{pmatrix} -4 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} -4 \\ 2 \end{pmatrix}} \begin{pmatrix} -4 \\ 2 \end{pmatrix} \\
 &= \frac{-4+14}{16+4} \begin{pmatrix} -4 \\ 2 \end{pmatrix} \\
 &= \frac{1}{2} \begin{pmatrix} -4 \\ 2 \end{pmatrix} \\
 &= \underline{\underline{\begin{pmatrix} -2 \\ 1 \end{pmatrix}}}
 \end{aligned}$$

$$14) \quad \vec{y} = \begin{pmatrix} 2 \\ 6 \end{pmatrix}, \quad \vec{u} = \begin{pmatrix} 7 \\ 1 \end{pmatrix}$$

\vec{u}^\perp denotes a vector orthogonal to \vec{u} .

$$\vec{y} = c_1 \vec{u} + c_2 \vec{u}^\perp$$

$$c_1 = \frac{\vec{u} \cdot \vec{y}}{\vec{u} \cdot \vec{u}} = \frac{14+6}{49+1} = \frac{20}{50} = \frac{2}{5}$$

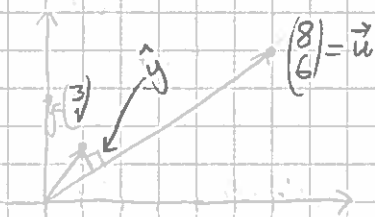
$$c_2 \vec{u}^\perp = \vec{y} - c_1 \vec{u}$$

$$c_2 \vec{u}^\perp = -\frac{2}{5} \begin{pmatrix} 7 \\ 1 \end{pmatrix} + \begin{pmatrix} 2 \\ 6 \end{pmatrix} = \begin{pmatrix} 14/5 - 2 \\ 2/5 - 6 \end{pmatrix}$$

$$c_2 \vec{u}^\perp = \begin{pmatrix} 4/5 \\ -28/5 \end{pmatrix} = \underbrace{-\frac{4}{5}}_{c_2} \underbrace{\begin{pmatrix} 1 \\ -7 \end{pmatrix}}_{\vec{u}^\perp}$$

$$\text{so } \vec{y} = \frac{2}{5} \begin{pmatrix} 7 \\ 1 \end{pmatrix} - \frac{4}{5} \begin{pmatrix} 1 \\ -7 \end{pmatrix}$$

15) let $\vec{y} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ and $\vec{u} = \begin{pmatrix} 8 \\ 6 \end{pmatrix}$



$$\hat{y} = \vec{y} - \text{proj}_{\vec{u}}(\vec{y})$$

$$\text{proj}_{\vec{u}}(\vec{y}) = \frac{\vec{y} \cdot \vec{u}}{\vec{u} \cdot \vec{u}} \vec{u}$$

$$= \frac{24+6}{64+36} \vec{u} = \frac{3}{10} \vec{u} = \begin{pmatrix} \frac{24}{10} \\ \frac{18}{10} \end{pmatrix} = \begin{pmatrix} \frac{12}{5} \\ \frac{9}{5} \end{pmatrix}$$

$$\Rightarrow \hat{y} = \begin{pmatrix} 3 \\ 1 \end{pmatrix} - \begin{pmatrix} 12/5 \\ 9/5 \end{pmatrix} = \begin{pmatrix} 3/5 \\ -4/5 \end{pmatrix}$$

The distance from \vec{y} to \vec{u} is $\|\hat{y}\|$

$$\|\hat{y}\| = \frac{1}{5} \sqrt{3^2 + 4^2} = 1$$

So the distance is 1.

26) W is spanned by a set $\{\vec{v}_1, \dots, \vec{v}_n\}$ of n orthogonal non-zero vectors. Since

all the vectors are non-zero the set

is linearly independent. A linearly independent set of n vectors spans \mathbb{R}^n . So

$$W = \text{span}\{\vec{v}_1, \dots, \vec{v}_n\} = \mathbb{R}^n$$

$$\Rightarrow W = \mathbb{R}^n$$

$$27) U = (\vec{v}_1 | \dots | \vec{v}_n), \quad \vec{v}_i \in \mathbb{R}^n, \quad \{\vec{v}_i\}_{i=1}^n \text{ orthogonal}$$

From (26) we know that the column vectors of U form a basis of \mathbb{R}^n ,

by the invertible matrix theorem (m, pg. 253),

U is then invertible. ■