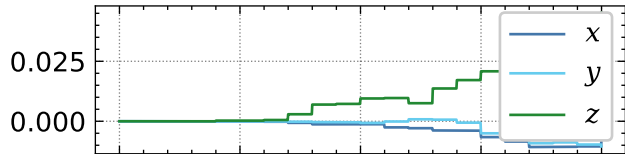


Acc [m/s²]



Gyro [deg/h]

