## Computational Mechanics by Isogeometric Analysis Dr. L. Dedè. A.Y. 2015/16

## Exercises April 26, 2016: Solutions

NURBS-based Isogeometric Analysis: Galerkin method. III

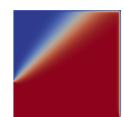
1. a) We start by solving an advection–diffusion problem for which we set the following data:  $\mathbf{b} = 10^2 (1,1)^T$ ,  $\sigma = 0$ , and g = 1 on  $\Gamma_{D1}$ , where  $\Gamma_{D1} := \{\mathbf{x} = (\mathbf{x}, \mathbf{y})^T \in \Gamma_D : \mathbf{x} = 0 \text{ and } y < 1/3, \text{ or } \mathbf{y} = 0\}$ , and g = 0 on  $\Gamma_D \setminus \Gamma_{D1}$ . The problem is advection dominated since the global Péclet number is larger than one, i.e.  $\mathbb{P}e_g := \frac{\|\mathbf{b}\|_{L^{\infty}(\Omega)}L}{2\mu} = 50$ , where L = 1 is the characteristic length size.

We solve the problem by considering p=1 globally  $C^0$ -continuous and p=2 globally  $C^1$ -continuous B-splines basis functions for different mesh sizes h ( $h=h_e$  for all the mesh elements  $\Omega_e$ ). In particular, we firstly consider the case for which the local Péclet number in each mesh element, say  $\mathbb{P}e_e:=\frac{\|\mathbf{b}\|_{L^{\infty}(\Omega_e)}h_e}{2\mu}$ , is larger than 1 ( $\mathbb{P}e_e>1$ ), possibly leading to numerical instabilities; then we consider the case  $\mathbb{P}e_e<1$ , yielding numerically stable results. The Dirichlet boundary conditions are strongly imposed and the "interpolation at the control points" technique is used. The examples are illustrated in the following figures.

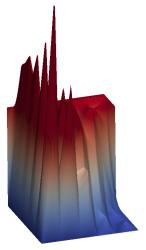
B-splines basis p = 1 ( $C^0$ -continuous),  $\mathbf{b} = 10^2 (1,1)^T$ ,  $\sigma = 0$ 



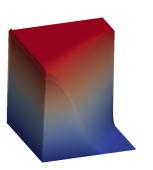
0.75 0.5 0.25



0.75 0.5 0.25

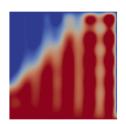


 $h = 1/10, \mathbb{P}e_e = 5 > 1$ 



 $h = 1/60, \mathbb{P}e_e = 5/6 < 1$ 

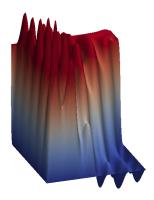
B-splines basis p = 2 (C<sup>1</sup>-continuous),  $\mathbf{b} = 10^2 (1,1)^T$ ,  $\sigma = 0$ 



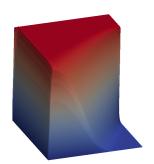








$$h = 1/10, \mathbb{P}e_e = 5 > 1$$



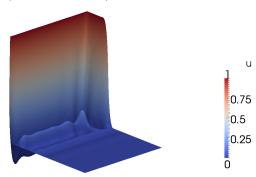
$$h = 1/60, \mathbb{P}e_e = 5/6 < 1$$

We observe for the case p=1 limited "overshooting" effects on the numerical solution appear even if  $\mathbb{P}e_e=5/6<1$ , while for p=2 the "overshooting" effects are negligible.

See the MATLAB file ex8\_1a.m for reference.

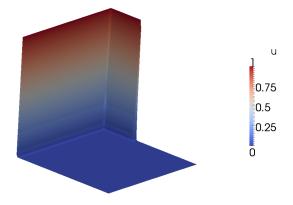
b) We solve a diffusion–reaction problem by setting  $\mathbf{b} = \mathbf{0}$ ,  $\sigma = 2 \cdot 10^4$ , and g as at point 1a). The problem is reaction dominated with the global Péclet number  $\mathbb{P}e_g := \frac{\|\sigma\|_{L^2(\Omega)}L^2}{6\,\mu} = 1/3\cdot 10^4$ . We solve the problem with B–splines basis functions of degree p=2 and globally  $C^1$ –continuous. Firstly, we set h=1/10 yielding the local Péclet number  $\mathbb{P}e_e := \frac{\|\sigma\|_{L^\infty(\Omega_e)}h_e^2}{6\,\mu} = 1/3\cdot 10^4 \gg 1$  for which we obtain the numerical solution reported in the following and exhibiting numerical instabilities.

B-splines basis p=2 (C<sup>1</sup>-continuous),  $\mathbf{b}=\mathbf{0}$ ,  $\sigma=2\cdot 10^4$ , h=1/10



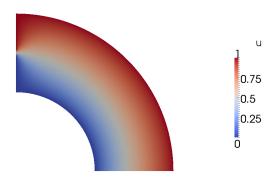
We then set h=1/80 yielding a numerical solution without numerical instabilities since the local Péclet number is  $\mathbb{P}e \simeq 0.5208 < 1$ .

B-splines basis p=2 (C<sup>1</sup>-continuous),  $\mathbf{b}=\mathbf{0}$ ,  $\sigma=2\cdot 10^4$ , h=1/80



See the MATLAB file ex8\_1b.m for reference.

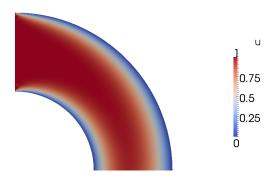
- 2. We consider two different choices of the Dirichlet data g (the "interpolation at the control points" technique is used). For both the cases we consider NURBS basis functions of degree p=2 and globally  $C^1$ -continuous with a meshes comprised of  $20\times 50$  elements.
  - a) We set g=1 on  $\Gamma_{D1}$  and g=0 on  $\Gamma_D\backslash\Gamma_{D1}$ , where the subset  $\Gamma_{D1}:=\left\{\mathbf{x}=(\mathbf{x},\mathbf{y})^T\in\Gamma_D: \mathbf{x}=0 \text{ and } y>3/2, \text{ or } \sqrt{\mathbf{x}^2+\mathbf{y}^2}=2\right\}$ . We obtain the result reported in the following for which we remark that the problem is diffusion dominated since the global Péclet number is  $\mathbb{P}e_g=0.5<1$ .



b) We set g = 1 on  $\Gamma_{D1}$  and g = 0 on  $\Gamma_D \setminus \Gamma_{D1}$ , where  $\Gamma_{D1} := \{ \mathbf{x} = (\mathbf{x}, \mathbf{y})^T \in \Gamma_D : \mathbf{x} = 0 \}$ . We obtain the following result, which highlights that the problem is diffusion dominated since  $\mathbb{P}e_g = 0.5 < 1$ .



If we set  $\mu = 10^{-2}$  we obtain an advection dominated problem with  $\mathbb{P}e_g = 50 \gg 1$ . The corresponding numerical solution is reported in the following.



See the MATLAB file ex8\_2.m for reference