Computational Mechanics by Isogeometric Analysis

Dr. L. Dedè. A.Y. 2015/16

Exercises April 19, 2016

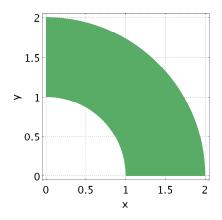
NURBS-based Isogeometric Analysis: Galerkin method. II

Let us consider the following Poisson problem:

$$\mbox{find } u \ : \Omega \to \mathbb{R} \quad : \quad \left\{ \begin{array}{ll} -\nabla \cdot (\mu \nabla u) = f & \ \ \mbox{in } \Omega, \\ \\ u = g & \ \ \mbox{on } \Gamma, \end{array} \right.$$

being $\Omega \subset \mathbb{R}^d$, for d=2,3, a bounded open computational domain with regular boundary $\Gamma = \partial \Omega$. The diffusion coefficient $\mu \in L^{\infty}(\Omega)$ and the source term $f \in L^2(\Omega)$ are assigned functions such that $\mu \geq \mu_0 > 0$ a.e. in Ω ; we assume that $g \in H^{1/2}(\Gamma)$. We solve the problem by means of the Galerkin method with NURBS-based Isogeometric Analysis; use the MATLAB functions test_iga2D.m and test_iga3D.m as templates (the functions are based on the GeoPDEs software).

- 1. Numerically and graphically determine the convergence orders (rates) of the errors in norms L^2 and H^1 under h-refinement for the Poisson problems defined by the following data. Consider different polynomial degrees p and regularities of the basis functions. Also, graphically compare the errors obtained with basis functions of the same degree p but different regularity; plot the errors vs. the characteristic mesh size h and the number of degrees of freedom.
 - a) Let us consider the domain Ω reported in the following figure $(\Omega = (1,2) \times (0,\pi/2)$ in polar coordinates (r,θ)) for which $\mu = 1$, and f and g are such that the exact solution reads $u = xy \sin\left(\frac{\pi}{3}\left(x^2 + y^2 1\right)\right)$.



- b) Set $\Omega = (0,1)^3$, $\mu = 1$, g = 0, and f such that the exact solution is $u = \sin(\pi x) \sin(\pi y) \sin(\pi z)$.
- 2. Let us consider the Poisson problem with the following data: $\Omega = (0,1)^2$, $\mu = 1$, and f = 0. Solve the problem for different mesh sizes h and polynomial degrees p by approximating the Dirichlet data g with the least squares and the "interpolation at the control points" techniques. Compare the results obtained with the two techniques for the following choices of the data g:

a)
$$g = \begin{cases} \sin(\pi y^2) & \text{on } \Gamma_1, \\ 0 & \text{on } \Gamma \setminus \Gamma_1, \end{cases}$$

b) $g = \begin{cases} 1 & \text{on } \Gamma_2, \\ 0 & \text{on } \Gamma \setminus \Gamma_2, \end{cases}$

b)
$$g = \begin{cases} 1 & \text{on } \Gamma_2, \\ 0 & \text{on } \Gamma \setminus \Gamma_2. \end{cases}$$

$$\text{where } \Gamma_1:=\left\{\mathbf{x}\in\Gamma\ :\ x=0\right\} \text{ and } \Gamma_2:=\left\{\mathbf{x}\in\Gamma\ :\ x=0 \text{ and } y>\frac{2}{3}\right\}.$$