Scenario 3: Position vs Time
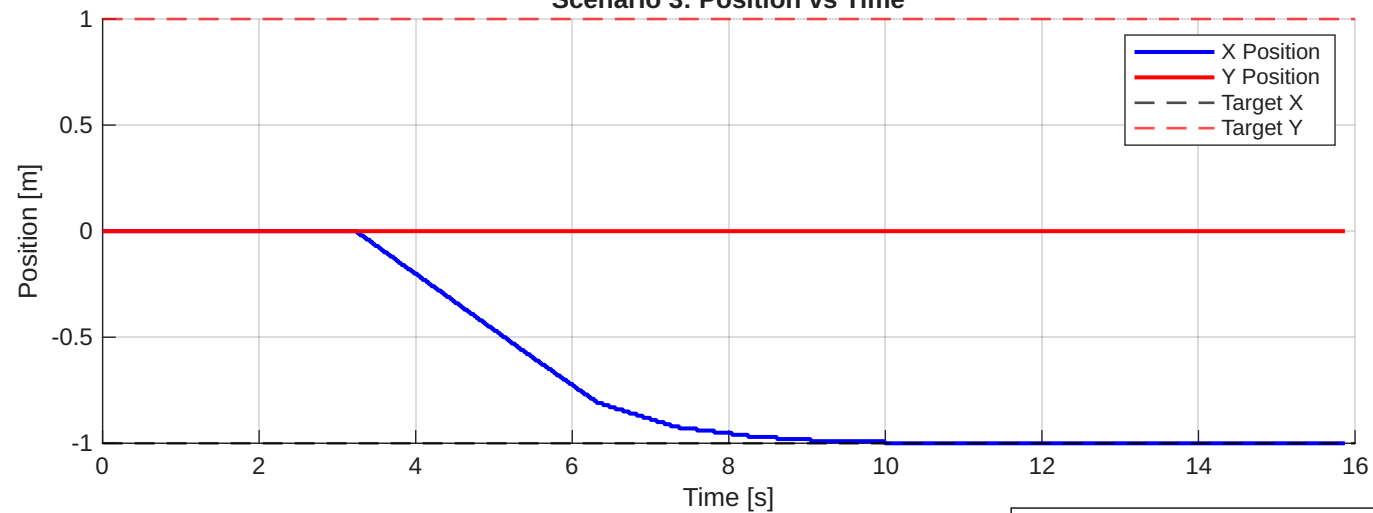
Steady-State Error: 0.000 m

Steady-State Error (Position)