

RX Family

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Rev.1.12

Ethernet Module Using Firmware Integration Technology

Nov 11, 2016

Introduction

This application note describes an Ethernet module that uses Firmware Integration Technology (FIT). This module performs Ethernet frame transmission and reception using an Ethernet controller and an Ethernet controller DMA controller. In the remainder of this document, this module is called the Ethernet FIT module.

Pin setting in the Ethernet FIT module has been removed from Rev.1.11. In order to use the Ethernet FIT module, assign input and output signals for Ethernet Controller to I/O Ports. Refer to section 4.3 “Ethernet FIT Module Pin Settings” in detail.

Target Devices

This API supports the following devices.

- RX64M
- RX71M
- RX63N
- RX65N

When using this application note with other Renesas MCUs, careful evaluation is recommended after making modifications to comply with the alternate MCU.

Related Documents

- Firmware Integration Technology User’s Manual (R01AN1833)
- Board Support Package Module Using Firmware Integration Technology (R01AN1685)
- Adding Firmware Integration Technology Modules to Projects (R01AN1723)
- Adding Firmware Integration Technology Modules to CS+ Projects (R01AN1826)

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1. Overview

The Ethernet FIT module uses an Ethernet controller (ETHERC) and an Ethernet controller DMA controller (EDMAC) to implement Ethernet frame transmission and reception. The Ethernet FIT module supports the following functions.

- MII (Media Independent Interface) and RMII (Reduced Media Independent Interface)
- An automatic negotiating function is used for the Ethernet PHY-LSI link.
- The link state is detected using the link signals output by the Ethernet PHY-LSI.
- The result of the automatic negotiation is acquired from the Ethernet PHY-LSI and the connection mode (full or half duplex, 10 or 100 Mbps transfer rate) is set in the ETHERC.

1.1 Ethernet FIT Module

The Ethernet FIT module is implemented in a project and used as the API. Refer to 2.11 Adding the FIT Module for details on implementing the module to the project.

1.2 Outline of the API

Table 1.1 lists the API functions included in the Ethernet FIT module.

Table 1.1 API Functions

Function	Contents
R_ETHER_Initial()	Initializes the Ethernet driver.
R_ETHER_Open_ZC2()	Applies a software reset to the ETHERC, EDMAC, and PHY-LSI, after which it starts PHY-LSI auto-negotiation and enables the link signal change interrupt.
R_ETHER_Close_ZC2()	Disables transmit and receive functionality on the ETHERC. Does not put the ETHERC and EDMAC into the module stop state.
R_ETHER_Read()	Receives data in the specified receive buffer.
R_ETHER_Read_ZC2()	Returns a pointer to the start address of the buffer that holds the receive data.
R_ETHER_Read_ZC2_BufRelease()	Releases the buffer read with the R_ETHER_Read_ZC2() function.
R_ETHER_Write()	Transmits data from the specified transmit buffer.
R_ETHER_Write_ZC2_GetBuf()	Returns a pointer to the start address of the write destination for transmit data.
R_ETHER_Write_ZC2_SetBuf()	Enables transmission of the transmit buffer data to the EDMAC.
R_ETHER_CheckLink_ZC()	Checks the link state of a physical Ethernet using the PHY management interface. If the PHY is connected to an appropriately initialized remote device with a cable, the Ethernet link state becomes link-up.
R_ETHER_LinkProcess()	Performs link signal change detected and magic packet detected interrupt handling.
R_ETHER_WakeOnLAN()	Switches the ETHERC setting from normal transmission and reception to magic packet detected operation.
R_ETHER_CheckWrite()	Verifies that data transmission has completed.
R_ETHER_Control()	Performs the processing that corresponds to a specified control code.
R_ETHER_GetVersion()	Returns the Ethernet FIT module version.

2. API Information

The API functions of the Ethernet FIT module adhere to the Renesas API naming standards.

2.1 Hardware Requirements

This driver requires your MCU supports the following feature:

- ETHERC
- EDMAC

2.2 Software Requirements

This driver is dependent upon the following packages:

- Renesas Board Support Package (r_bsp) v3.40

2.3 Operating Condition

Table 2-1 shows operating confirmation environment of Ethernet FIT module.

Table 2-1 Operation Confirmation Environment

Item	Contents
C compiler	Renesas Electronics C/C++ compiler for RX Family V.2.05.00
Endian order	Big-endian/Little-endian
Board used	Renesas Starter Kit for RX63N (product number.R0K50563NSxxxBE) Renesas Starter Kit for RX64M (product number.R0K50564MSxxxBE) Renesas Starter Kit for RX71M (product number.R0K50571MSxxxBE) Renesas Starter Kit for RX65N (product number.RTK500565NSxxxxxBE)

2.4 Supported Toolchains

The operation of the Ethernet FIT module has been confirmed with the toolchain listed as C compiler in Table 2-1.

2.5 Usage of Interrupt Vector

EINT interrupt, EINT0 interrupt, or EINT1 interrupt corresponding to the channel number is enabled after specified argument to channel number and calling R_ETHER_Control function. Table 2-2 shows each interrupt vector that Ethernet FIT module uses.

Table 2-2 List of Usage of Interrupt Vectors

Device	Contents
RX63N	EINT interrupt [channel number 0] (Vector number. 32)
RX64M	GROUPAL1 interrupt (Vector number. 113)
RX71M	<ul style="list-style-type: none"> EINT0 interrupt [channel number 0] (group interrupt source number. 4) *1 EINT1 interrupt [channel number 1] (group interrupt source number. 5) *1
RX65N	GROUPAL1 interrupt (Vector number. 113) <ul style="list-style-type: none"> EINT0 interrupt [channel number 0] (group interrupt source number. 4)

Note 1. If values of ETHER_CFG_CH0_PHY_ACCESS/ETHER_CFG_CH1_PHY_ACCESS is different from the channel number specified in argument, both EINT0 interrupt and EINT1 interrupt are enabled.

2.6 Header Files

All API calls and their supporting interface definitions are located in r_ether_rx_if.h.

2.7 Integer Types

This project uses ANSI C99. These types are defined in stdint.h.

2.8 Configuration Overview

The configuration options in the Ethernet FIT module are specified in `r_ether_rx_config.h`. The option names and setting values are listed in the table below.

Configuration options in `r_ether_rx_config.h`

<code>#define ETHER_CFG_MODE_SEL</code> Note: Default value = 0	Sets the interface between ETHERC and the Ethernet PHY-LSI. If set to 0, MII (Media Independent Interface) is selected. If set to 1, RMII (Reduced Media Independent Interface) is selected.
<code>#define ETHER_CFG_CH0_PHY_ADDRESS</code> Note: Default value = 0* ⁷	Specify the PHY-LSI address used by ETHERC channel 0. Specify a value between 0 and 15.
<code>#define ETHER_CFG_CH1_PHY_ADDRESS</code> Note: Default value = 1	Specify the PHY-LSI address used by ETHERC channel 1. Specify a value between 0 and 15.
<code>#define ETHER_CFG_EMAC_RX_DESCRIPTOR</code> Note: Default value = 1	Sets the number of receive descriptors. This must be set to a value 1 or greater
<code>#define ETHER_CFG_EMAC_TX_DESCRIPTOR</code> Note: Default value = 1	Sets the number of transmit descriptors. This must be set to a value 1 or greater
<code>#define ETHER_CFG_BUFSIZE</code> Note: Default value = 1,536	Specify the size of the transmit buffer or receive buffer. The buffer is aligned with 32-byte boundaries, so specify a value that is a multiple of 32 bytes.
<code>#define ETHER_CFG_EINT_INT_PRIORITY</code> Note: Default value = 2	Sets the priority level of the group EINT interrupt. This must be set to a value in the range 1 to 15.* ⁴
<code>#define ETHER_CFG_AL1_INT_PRIORITY</code> Note: Default value = 2	Sets the priority level of the group AL1 interrupt. This must be set to a value in the range 1 to 15.* ⁵
<code>#define ETHER_CFG_CH0_PHY_ACCESS</code> Note: Default value = 1* ¹ * ⁸	Specify the PHY access channel used by ETHERC channel 0. When 0 is specified, ETHERC0 is used for PHY register access.* ² When 1 is specified, ETHERC1 is used for PHY register access.* ³
<code>#define ETHER_CFG_CH1_PHY_ACCESS</code> Note: Default value = 1* ¹	Specify the PHY access channel used by ETHERC channel 1. When 0 is specified, ETHERC0 is used for PHY register access.* ² When 1 is specified, ETHERC1 is used for PHY register access.* ³
<code>#define ETHER_CFG_PHY_MII_WAIT</code> Note: Default value = 8	Specify the access timing for the MII or RMII register. Specify a value of 8 or greater.
<code>#define ETHER_CFG_PHY_DELAY_RESET</code> Note: Default value = 0x00020000	Specify the wait time for PHY-LSI reset completion.
<code>#define ETHER_CFG_LINK_PRESENT</code> Note: Default value = 0	Specify the polarity of the link signal output by the PHY-LSI. When 0 is specified, link-up and link-down correspond respectively to the fall and rise of the LINKSTA signal. When 1 is specified, link-up and link-down correspond respectively to the rise and fall of the LINKSTA signal.

Configuration options in *r_ether_rx_config.h*

#define ETHER_CFG_USE_LINKSTA Note: Default value = 1	Specify whether or not to use the PHY-LSI status register instead of the LINKSTA signal when a change in the link status is detected.*6 When 0 is specified, the PHY-LSI status register is used. When 1 is specified, the LINKSTA signal is used.
#define ETHER_CFG_USE_PHY_KSZ8041NL Note: Default value = 0	Specify whether or not the KSZ8041NL PHY-LSI from Micrel is used. When 0 is specified, the KSZ8041 is not used. When 1 is specified, the KSZ8041 is used.

Notes: 1. Refer to Table 2-3 regarding settings for operating the Ethernet FIT module on the Renesas Starter Kit+ for RX64M (product number: R0K50564MSxxxBE). Or refer to Table 2-4 regarding settings for operating the Ethernet FIT module on the Renesas Starter Kit+ for RX71M (product number: R0K50571MSxxxBE)

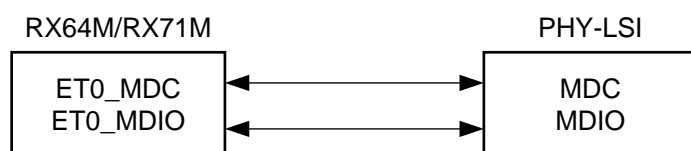
Table 2-3 ETHER_CFG_CH0_PHY_ACCESS/ETHER_CFG_CH1_PHY_ACCESS Settings 1

Short Pin J3	Short Pin J4	ETHER_CFG_CH0_PHY_ACCESS and ETHER_CFG_CH1_PHY_ACCESS Setting Values
1 and 2 shorted	1 and 2 shorted	0 0
2 and 3 shorted	2 and 3 shorted	1 1

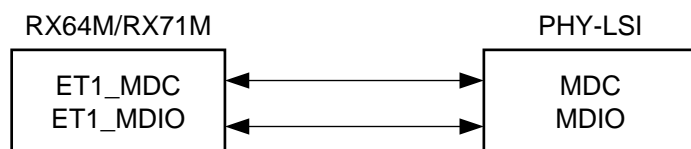
Table 2-4 ETHER_CFG_CH0_PHY_ACCESS/ETHER_CFG_CH1_PHY_ACCESS Settings 2

Short Pin J13	Short Pin J9	ETHER_CFG_CH0_PHY_ACCESS and ETHER_CFG_CH1_PHY_ACCESS Setting Values
1 and 2 shorted	1 and 2 shorted	0 0
2 and 3 shorted	2 and 3 shorted	1 1

2. Setting when ETHERC and PHY-LSI are connected as shown below.



3. Setting when ETHERC and PHY-LSI are connected as shown below.



4. This setting is valid only when the target microcontroller is the RX63N.
 5. This setting is valid only when the target microcontroller is the RX64M, RX71M, or RX65N.
 6. This setting is valid for all channels when the target microcontroller is the RX64M or RX71M.

7. The default value is a numeric value based on the initial setting of Renesas Starter Kit+ for RX64M or Renesas Starter Kit+ for RX71M. When using Renesas Starter Kit+ for RX63N (product number: R0K50563NSxxxBE), set the value to 31. When using Renesas Starter Kit+ for RX65N (product number: RTK500565NSxxxxxBE), set the value to 30.
8. The default value is a numeric value based on the initial setting of Renesas Starter Kit+ for RX64M or Renesas Starter Kit+ for RX71M. When using Renesas Starter Kit+ for RX63N or Renesas Starter Kit+ for RX65N set the value to 0.

2.9 Code Size

The code size when using the supported toolchain (see section 2.4) is assumed to be that when optimization level 2 and optimization for code size are used. The sizes of ROM (code and constants) and RAM (global data) are set in the configuration header file of the Ethernet FIT module and determined at build time by configuration options.

ROM and RAM Code Size		
RX64	With the following settings: ETHER_CFG_EMAC_RX_DESCRIPTOR = 1, ETHER_CFG_EMAC_TX_DESCRIPTOR = 1, ETHER_CFG_BUFSIZE = 1536	ROM: 4,202 bytes
		RAM: 6,273 bytes
RX65	With the following settings: ETHER_CFG_EMAC_RX_DESCRIPTOR = 1, ETHER_CFG_EMAC_TX_DESCRIPTOR = 1, ETHER_CFG_BUFSIZE = 1536	ROM: 3,917 bytes
		RAM: 3,140 bytes

2.10 Arguments

This section documents the enumerations, unions, and structures used as arguments to API functions. These are included in the `r_ether_rx_if.h` header file along with the API function prototype declarations.

```
typedef enum
{
    CONTROL_SET_CALLBACK,          /* Callback function registration */
    CONTROL_SET_PROMISCUOUS_MODE,  /* Promiscuous mode setting */
    CONTROL_SET_INT_HANDLER,       /* Interrupt handler function registration */
    CONTROL_POWER_ON,              /* Cancel ETHERC/EDMAC module stop */
    CONTROL_POWER_OFF,             /* Transition to ETHERC/EDMAC module stop */
    CONTROL_MULTICASTFRAME_FILTER, /* Multicast frame filter setting */
    CONTROL_BROADCASTFRAME_FILTER /* Broadcast frame filter continuous receive count setting */
} ether_cmd_t;

typedef union
{
    ether_cb_t          ether_callback; /* Callback function pointer */
    ether_promiscuous_t * p_ether_promiscuous; /* Promiscuous mode setting */
    ether_cb_t          ether_int_hnd; /* Interrupt handler function pointer */
    uint32_t            channel; /* ETHERC channel number */
    ether_multicast_t   * p_ether_multicast; /* Multicast frame filter setting */
    ether_broadcast_t   * p_ether_broadcast; /* Broadcast frame filter setting */
} ether_param_t;

typedef struct
{
    void (*pcb_func)(void *); /* Callback function pointer */
    void (*pcb_int_hnd)(void *); /* Interrupt handler function pointer */
} ether_cb_t;

typedef enum
{
    ETHER_PROMISCUOUS_OFF, /* ETHERC operates in standard mode */
    ETHER_PROMISCUOUS_ON  /* ETHERC operates in promiscuous mode */
} ether_promiscuous_bit_t;

typedef enum
{
    ETHER_MC_FILTER_OFF, /* Disable multicast frame filter */
    ETHER_MC_FILTER_ON  /* Enable multicast frame filter */
} ether_mc_filter_t;

typedef struct
{
    uint32_t            channel; /* ETHERC channel */
    ether_promiscuous_bit_t bit; /* Promiscuous mode */
} ether_promiscuous_t;

typedef struct
{
    uint32_t            channel; /* ETHERC channel */

```

```
    ether_mc_filter_t    flag;          /* Multicast frame filter setting */
} ether_multicast_t;

typedef struct
{
    uint32_t             channel;        /* ETHERC channel */
    uint32_t             counter;        /* Broadcast frame continuous receive count */
} ether_broadcast_t;

typedef enum
{
    ETHER_CB_EVENT_ID_WAKEON_LAN,        /* Magic packet detection */
    ETHER_CB_EVENT_ID_LINK_ON,          /* Link up detection */
    ETHER_CB_EVENT_ID_LINK_OFF         /* Link down detection */
} ether_cb_event_t;

typedef struct
{
    uint32_t             channel;        /* ETHERC channel */
    ether_cb_event_t     event_id;       /* Event code for callback function */
    uint32_t             status_ecsr;    /* ETHERC status register for interrupt handler */
    uint32_t             status_eesr;    /* ETHERC/EDMAC status register for interrupt handler */
} ether_cb_arg_t;
```

2.11 Return Values

This section describes return values of API functions. This enumeration is located in `r_ether_rx_if.h` as are the prototype declarations of API functions.

```
typedef enum                                /* Error code of Ether API */
{
    ETHER_SUCCESS,                          /* Processing completed successfully */
    ETHER_ERR_INVALID_PTR,                  /* Value of the pointer is NULL or FIT_NO_PTR */
    ETHER_ERR_INVALID_DATA,                 /* Value of the argument is out of range */
    ETHER_ERR_INVALID_CHAN,                 /* Nonexistent channel number */
    ETHER_ERR_INVALID_ARG,                  /* Invalid argument */
    ETHER_ERR_LINK,                         /* Auto-negotiation is not completed, and transmission/reception is not enabled. */
    ETHER_ERR_MPDE,                         /* As a Magic Packet is being detected, and transmission/reception is not enabled. */
    ETHER_ERR_TACT,                         /* Transmit buffer is not empty. */
    ETHER_ERR_CHAN_OPEN,                    /* Indicates the Ethernet cannot be opened because it is being used by another application */
    ETHER_ERR_MC_FRAME,                     /* Multicast frame detected when multicast frame filtering is enabled. */
    ETHER_ERR_RECV_ENABLE,                  /* Could not change setting because receive function is enabled. */
    ETHER_ERR_OTHER                         /* Other error */
} ether_return_t;
```

2.12 Callback Function

(1) Callback Function Called by API Function R_ETHER_LinkProcess

In the Ethernet FIT module, a callback function is called when either a magic packet or a link signal change is detected.

To set up the callback function, use the function R_ETHER_Control(), which is described later in this document, and set the control code CONTROL_SET_CALLBACK as the enumeration (the first argument) described in 2.10 Arguments, and set the address of the function to be registered as the callback function in the structure (the second argument).

When the callback function is called, a variable in which the channel number for which the detection occurred and a constant shown in Table 2-5 are stored is passed as an argument. If the value of this argument is to be used outside the callback function, its value should be copied into, for example, a global variable.

Table 2-5 Argument List of the callback Function

Constant Definition	Description
ETHER_CB_EVENT_ID_WAKEON_LAN	Detect magic packet
ETHER_CB_EVENT_ID_LINK_ON	Detect link signal change (link-up)
ETHER_CB_EVENT_ID_LINK_OFF	Detect link signal change (link-down)

(2) Callback Function Called by EINT0/EINT1 Status Interrupts

The Ethernet FIT module calls an interrupt handler when an interrupt indicating a condition other than the following occurs.

- Magic Packet detection operation by the Ethernet FIT module
 - Link signal change detection*¹
 - Magic packet detection
- Normal operation by the Ethernet FIT module
 - Link signal change detection*¹
 - Frame receive detection or frame transmit end detection

To specify the interrupt handler, use the R_ETHER_Control function described below to set the control code “CONTROL_SET_INT_HANDLER” in the enumeration (first argument) shown in 2.8 Arguments, and set the function address of the interrupt handler to be registered in the structure (second argument).

When the interrupt handler function is called, variables in which are stored the number of the channel on which the interrupt occurred, the ETHERC status register value, and the ETHERC/EDMAC status register value are passed as arguments. To use the argument values in functions other than the callback function, copy them to global variables or the like.

Note 1. If the setting of #define ETHER_CFG_USE_LINKSTA is 0, the interrupt handler function is not called when a link signal change is detected.

2.13 Adding the FIT Module

The FIT module must be added to each project in the e² studio.

You can use the FIT plug-in to add the FIT module to your project, or the module can be added manually.

It is recommended to use the FIT plug-in as you can add the module to your project easily and also it will automatically update the include file paths for you.

To add the FIT module using the plug-in, refer to chapter 3, “Adding FIT Modules to e² studio Projects Using FIT Plug-In” in the “Adding Firmware Integration Technology Modules to Projects” application note (R01AN1723).

To add the FIT module manually, without using the plug-in, refer to chapter 4, “Adding FIT Modules to Projects Manually.”

When using the FIT module, the board support package FIT module (BSP module) needs to be added to the project as well. For instructions for adding the BSP module, refer to the “Board Support Package Module Using Firmware Integration Technology” application note (R01AN1685).

2.14 Ethernet Frame Format

The Ethernet FIT module supports the Ethernet II/IEEE 802.3 frame format.

2.14.1 Frame Format for Data Transmission and Reception

Figure 2.1 shows the Ethernet II/IEEE 802.3 frame format.

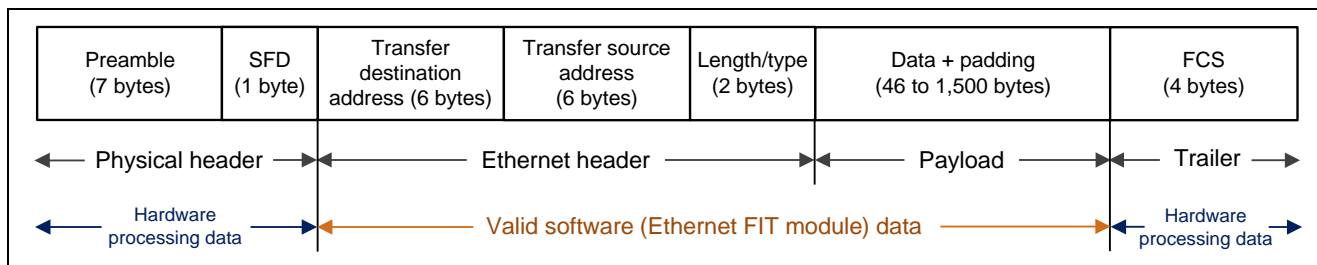


Figure 2.1 Ethernet II/IEEE 802.3 Frame Format

The preamble and SFD signal the start of an Ethernet frame. The FCS contains the CRC of the Ethernet frame and is calculated on the transmitting side. When data is received the CRC value of the frame is calculated in hardware, and the Ethernet frame is discarded if the values do not match.

When the hardware determines that the data is normal, the valid range of receive data is: (transmission destination address) + (transmission source address) + (length/type) + (data).

2.14.2 PAUSE Frame Format

Table 2.2 shows the PAUSE frame format.

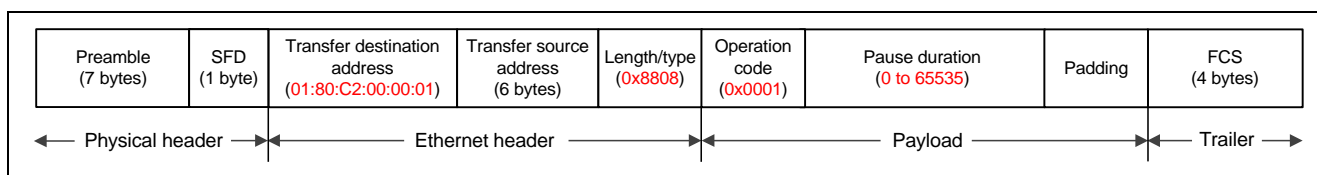


Figure 2.2 PAUSE Frame Format

The transmission destination address is specified as 01:80:C2:00:00:01 (a multicast address reserved for PAUSE frames). At the start of the payload the length/type is specified as 0x8808 and the operation code as 0x0001.

The pause duration in the payload is specified by the value of the automatic PAUSE (AP) bits in the automatic PAUSE frame setting register (APR), or the manual PAUSE time setting (MP) bits in the manual PAUSE frame setting register (MPR).

2.14.3 Magic Packet Frame Format

Table 2.3 shows the Magic Packet frame format.

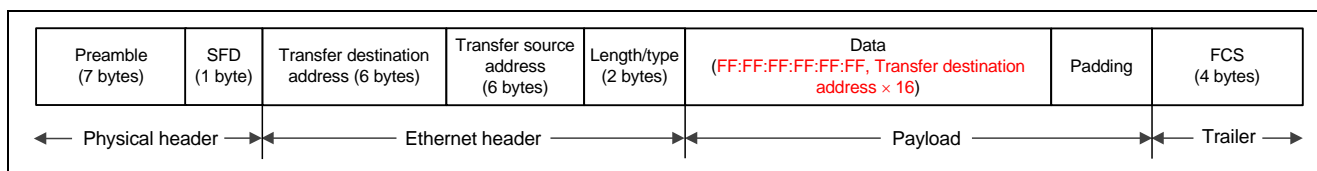


Figure 2.3 Magic Packet Frame Format

In a Magic Packet, the value FF:FF:FF:FF:FF:FF followed by the transmission destination address repeated 16 times is inserted somewhere in the Ethernet frame data.

3. API Functions

3.1 R_ETHER_Initial()

This function makes initial settings to the Ethernet FIT module.

Format

void R_ETHER_Initial(void);

Parameters

None

Return Values

None

Properties

Prototyped in r_ether_rx_if.h.

Description

Initializes the memory to be used in order to start Ethernet communication.

Reentrant

Function is not reentrant.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"

void callback_sample(void*);
void int_handler_sample(void*);

ether_return          ret;
ether_param_t         param;
ether_cb_t            cb_func;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t              channel;

/* Initialize memory which ETHERC/EDMAC is used */
R_ETHER_Initial();

channel               = ETHER_CHANNEL_0
param.channel         = channel;

/* Set the callback function */
cb_func.pcb_func      = &callback_sample;
param.ether_callback  = cb_func;
```



```
ret = R_ETHER_Control(CONTROL_SET_CALLBACK, param);

/* Set the interrupt handler */
cb_func.pcb_int_hnd = &int_handler_sample;
param.ether_int_hnd = cb_func;
ret = R_ETHER_Control(CONTROL_SET_INT_HANDLER, param);

/* Release ETHERC and EDMAC module stop, port settings using ETHERC */
ret = R_ETHER_Control(CONTROL_POWER_ON, param);
if(ETHER_SUCCESS == ret)
{
    /* Initialized successfully completed without ETHERC, EDMAC */
}
```

Special Notes:

This function must be called before calling the R_ETHER_Open_ZC2() function.

3.2 R_ETHER_Open_ZC2()

When using the ETHER API, this function is used first.

Format

```
ether_return_t R_ETHER_Open_ZC2(  
    uint32_t      channel    /* ETHERC channel number */  
    const uint8_t mac_addr[] /* The MAC address of ETHERC */  
    uint8_t      pause      /* Specifies whether flow control functionality is enabled or disabled. */  
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

mac_addr

Specifies the MAC address of ETHERC.

pause

Specifies the value set in bit 10 (Pause) in register 4 (auto-negotiation advertisement) of the PHY-LSI. The setting ETHER_FLAG_ON is possible only when the user's PHY-LSI supports the pause function. This value is passed to the other PHY-LSI during auto-negotiation. Flow control is enabled if the auto-negotiation result indicates that both the local PHY-LSI and the other PHY-LSI support the pause function.

Specify ETHER_FLAG_ON to convey that the pause function is supported to the other PHY-LSI during auto-negotiation, and specify ETHER_FLAG_OFF if the pause function is not supported or will not be used even though it is supported.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_INVALID_PTR</i>	<i>/* Value of the pointer is NULL or FIT_NO_PTR */</i>
<i>ETHER_ERR_INVALID_DATA</i>	<i>/* Value of the argument is out of range */</i>
<i>ETHER_ERR_OTHER</i>	<i>/* PHY-LSI initialization failed */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_Open_ZC2() function resets the ETHERC, EDMAC and PHY-LSI by software, and starts PHY-LSI auto-negotiation to enable the link signal change interrupt.

The MAC address is used to initialize the ETHERC MAC address register.

Reentrant

Function is reentrant for different channels.

Example

The MAC address used in the sample code is assigned based on the vendor ID of Renesas Electronics Corporation. Customers developing products must use a MAC address obtained by submitting an application to the IEEE.

```
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return      ret;

/* Source MAC Address */
static uint8_t    mac_addr_src[6] = {0x74,0x90,0x50,0x00,0x79,0x01};

/* Flow control function
 * ETHER_FLAG_ON = Use flow control function
 * ETHER_FLAG_OFF = No use flow control function
 */
static volatile uint8_t  pause_enable = ETHER_FLAG_OFF;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

/* Initialize ETHERC, EDMAC */
ret = R_ETHER_Open_ZC2(channel, mac_addr_src, pause_enable);
if(ETHER_SUCCESS == ret)
{
    while(1)
    {
        /* Check Link status when Initialized successfully completed */
        R_ETHER_LinkProcess(channel);
    }
}
```

Special Notes:

Either after the R_ETHER_initial() function is called immediately following a power-on reset, or after the R_ETHER_Close_ZC2() function was called, applications should only use the other API functions after first calling this function and verifying that the return value is ETHER_SUCCESS.

3.3 R_ETHER_Close_ZC2()

The R_ETHER_Close_ZC2() function disables transmit and receive functionality on the ETHERC. This function does not put the ETHERC and EDMAC into the module stop state.

Format

```
ether_return_t R_ETHER_Close_ZC2 (
    uint32_t channel    /* ETHERC channel number */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

```
ETHER_SUCCESS           /* Processing completed successfully */
ETHER_ERR_INVALID_CHAN /* Nonexistent channel number */
```

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_Close_ZC2() function disables transmit and receive functionality on the ETHERC and disables Ethernet interrupts. It does not put the ETHERC and EDMAC into the module stop state.

Execute this function to end the Ethernet communication.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return_t ret;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t channel;

channel = ETHER_CHANNEL_0;

/* Disable transmission and receive function */
ret = R_ETHER_Close_ZC2(channel);
if(ETHER_SUCCESS == ret)
{
    goto end;
}
```

Special Notes:

None

3.4 R_ETHER_Read_ZC2()

The R_ETHER_Read_ZC2() function returns a pointer to the starting address of the buffer storing the receive data.

Format

```
int32_t R_ETHER_Read_ZC2(
    uint32_t channel /* ETHERC channel number */
    void ** pbuf /* Pointer to buffer that holds the receive data */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

*** pbuf*

Returns a pointer to the starting address of the buffer storing the receive data.

Return Values

<i>A value of 1 or greater</i>	<i>/* Returns the number of bytes received. */</i>
<i>ETHER_NO_DATA</i>	<i>/* A zero value indicates no data is received. */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_INVALID_PTR</i>	<i>/* Value of the pointer is NULL or FIT_NO_PTR */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_MPDE</i>	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>
<i>ETHER_ERR_MC_FRAME</i>	<i>/* Multicast frame detected when multicast frame filtering is enabled. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

The driver's buffer pointer to the starting address of the buffer storing the receive data is returned in the parameter pbuf. Returning the pointer allows the operation to be performed with zero-copy. Return value shows the number of received bytes. If there is no data available at the time of the call, ETHER_NO_DATA is returned. When auto-negotiation is not completed, and reception is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_MPDE is returned when a Magic Packet is being detected.

The EDMAC hardware operates independent of the R_ETHER_Read_ZC2() function and reads data into a buffer pointed by the EDMAC receive descriptor. The buffer pointed by the EDMAC receive descriptor is statically allocated by the driver.

When multicast frame filtering on the specified channel is enabled by the R_ETHER_Control function, the buffer is released immediately when a multicast frame is detected. Also, the value ETHER_ERR_MC_FRAME is returned. Note that when hardware-based multicast frame filtering is enabled on the RX64M or RX71M, multicast frames are discarded by the hardware and detection is not possible. For details, see section 5.1 EPTPC Light FIT Module.

Frames that generate a receive FIFO overflow, residual-bit frame receive error, long frame receive error, short frame receive error, PHY-LSI receive error, or receive frame CRC error are treated as receive frame errors. When a receive frame error occurs, the descriptor data is discarded, the status is cleared, and reading of data continues.

Reentrant

Function is reentrant for different channels.

Example

```
#include <string.h>
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return      ret;
uint8_t          * pread_buffer_address;
uint8_t          * pbuf;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Read_ZC2(channel, (void **)&pread_buffer_address);
/* When there is data to receive */
if(ETHER_NO_DATA < ret)
{
    memcpy(pbuf, pread_buffer_address, (uint32_t)ret);

    /* Release the receive buffer after reading the receive data. */
    R_ETHER_Read_ZC2_BufRelease(channel);
}
```

Special Notes:

This function is used in combination with the R_ETHER_Read_ZC2_BufRelease function. Always call the R_ETHER_Read_ZC2 function and then the R_ETHER_Read_ZC2_BufRelease function in sequence. If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.5 R_ETHER_Read_ZC2_BufRelease()

The R_ETHER_Read_ZC2_BufRelease() function releases the buffer read by the R_ETHER_Read_ZC2() function.

Format

```
int32_t R_ETHER_Read_ZC2_BufRelease(
    uint32_t channel    /* Specifies the ETHERC channel number. */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_MPDE</i>	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_Read_ZC2_BufRelease() function releases the buffer read by the R_ETHER_Read_ZC2() function.

Reentrant

Function is reentrant for different channels.

Example

```
#include <string.h>
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return    ret;
uint8_t        * pread_buffer_address;
uint8_t        * pbuf;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t        channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Read_ZC2(channel, (void **) &pread_buffer_address);
/* When there is data to receive */
if(ETHER_NO_DATA < ret)
{
```



```
memcpy(pbuf, pread_buffer_address, (uint32_t)ret);  
/* Release the receive buffer after reading the receive data. */  
R_ETHER_Read_ZC2_BufRelease(channel);  
}
```

Special Notes:

Before calling this function, use the R_ETHER_Read_ZC2 function to read data. Call this function after a value of 1 or greater is returned.

This function is used in combination with the R_ETHER_Read_ZC2_BufRelease function. Always call the R_ETHER_Read_ZC2 function and then the R_ETHER_Read_ZC2_BufRelease function in sequence. If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.6 R_ETHER_Write_ZC2_GetBuf()

The R_ETHER_Write_ZC2_GetBuf() function returns a pointer to the starting address of the transmit data destination.

Format

```
ether_return_t R_ETHER_Write_ZC2_GetBuf(
    uint32_t      channel    /* ETHERC channel number */
    void          ** pbuf     /* Pointer to the starting address of the transmit data destination */
    uint16_t      *  pbuf_size /* The Maximum size to write to the buffer */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

*** pbuf*

Returns a pointer to the starting address of the transmit data destination.

** pbuf_size*

Returns the maximum size to write to the buffer.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_INVALID_PTR</i>	<i>/* Value of the pointer is NULL or FIT_NO_PTR */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_MPDE</i>	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>
<i>ETHER_ERR_TACT</i>	<i>/* Transmit buffer is not empty. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_Write_ZC2_GetBuf() function returns the parameter pbuf containing a pointer to the starting address of the transmit data destination. The function also returns the maximum size to write to the buffer to the parameter pbuf_size. Returning the pointer allows the operation to be performed with zero-copy.

Return values indicate if the transmit buffer (pbuf) is writable or not. ETHER_SUCCESS is returned when the buffer is writable at the time of the call. When auto-negotiation is not completed, and transmission is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_MPDE is returned when a Magic Packet is being detected. ETHER_ERR_TACT is returned when the transmit buffer is not empty.

The EDMAC hardware operates independent of the R_ETHER_Write_ZC2_GetBuf() function and writes data stored in a buffer pointed by the EDMAC transmit descriptor. The buffer pointed by the EDMAC transmit descriptor is statically allocated by the driver.

Reentrant

Function is reentrant for different channels.

Example

The MAC address used in the sample code is assigned based on the vendor ID of Renesas Electronics Corporation. Customers developing products must use a MAC address obtained by submitting an application to the IEEE.

```
#include <string.h>
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return      ret;
uint8_t          * pwrite_buffer_address;
uint8_t          * pbuf;
uint16_t         buf_size;

/* Transmit data */
static uint8_t send_data[60] =
{
    0x74,0x90,0x50,0x00,0x79,0x02,          /* Destination MAC address */
    0x74,0x90,0x50,0x00,0x79,0x01,          /* Source MAC address      */
    0x00,0x00,                                /* The type field is not used */
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, /* Data field */
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00
};

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Write_ZC2_GetBuf(channel, (void **)& pwrite_buffer_address,
&buf_size);
/* When transmission buffer is empty */
if(ETHER_SUCCESS == ret)
{
    /* Write the transmit data to the transmission buffer. */
    memcpy(pwrite_buffer_address, send_data, sizeof(send_data));

    R_ETHER_Write_ZC2_SetBuf(channel, sizeof(send_data));

    /* Verifying that the transmission is completed */
    ret = R_ETHER_CheckWrite(channel);
    if(ETHER_SUCCESS == ret)
    {
        /* Transmission is completed */
    }
}
}
```

Special Notes:

This function is used in combination with the R_ETHER_Write_ZC2_SetBuf function. Always call the R_ETHER_Write_ZC2_GetBuf function and then the R_ETHER_Write_ZC2_SetBuf function in sequence. If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.7 R_ETHER_Write_ZC2_SetBuf()

The R_ETHER_Write_ZC2_SetBuf() function enables the EDMAC to transmit the data in the transmit buffer.

Format

```
ether_return_t R_ETHER_Write_ZC2_SetBuf(
    uint32_t channel    /* ETHERC channel number */
    const uint32_t len   /* The size (60 to 1,514 bytes) which is the Ethernet frame length */
                        /* minus 4 bytes of CRC */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

len

Specifies the size (60 to 1,514 bytes) which is the Ethernet frame length minus 4 bytes of CRC.

Return Values

ETHER_SUCCESS	<i>/* Processing completed successfully */</i>
ETHER_ERR_INVALID_CHAN	<i>/* Nonexistent channel number */</i>
ETHER_ERR_INVALID_DATA	<i>/* Value of the argument is out of range */</i>
ETHER_ERR_LINK	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
ETHER_ERR_MPDE	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

Call this function after writing one frame of transmit data is completed.

Set the buffer length to be not less than 60 bytes (64 bytes of the minimum Ethernet frame minus 4 bytes of CRC) and not more than 1,514 bytes (1,518 bytes of the maximum Ethernet frame minus 4 bytes of CRC).

To transmit data less than 60 bytes, make sure to pad the data with zero to be 60 bytes.

Return values indicate that the data written in the transmit buffer is enabled to be transmitted. ETHER_SUCCESS is returned when the data in the transmit buffer is enabled to be transmitted at the time of the call. When auto-negotiation is not completed, and transmission is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_MPDE is returned when a Magic Packet is being detected.

Reentrant

Function is reentrant for different channels.

Example

The MAC address used in the sample code is assigned based on the vendor ID of Renesas Electronics Corporation. Customers developing products must use a MAC address obtained by submitting an application to the IEEE.

```
#include <string.h>
#include "platform.h"
#include "r_ether_rx_if.h"
```

```

ether_return      ret;
uint8_t           * pwrite_buffer_address;
uint8_t           * pbuf;
uint16_t          buf_size;

/* Transmit data */
static uint8_t send_data[60] =
{
    0x74, 0x90, 0x50, 0x00, 0x79, 0x02,          /* Destination MAC address */
    0x74, 0x90, 0x50, 0x00, 0x79, 0x01,          /* Source MAC address */
    0x00, 0x00,                                  /* The type field is not used */
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, /* Data field */
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00
};

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Write_ZC2_GetBuf(channel, (void **)&pwrite_buffer_address,
&buf_size);
/* When transmission buffer is empty */
if(ETHER_SUCCESS == ret)
{
    /* Write the transmit data to the transmission buffer. */
    memcpy(pwrite_buffer_address, send_data, sizeof(send_data));

    R_ETHER_Write_ZC2_SetBuf(channel, sizeof(send_data));

    /* Verifying that the transmission is completed */
    ret = R_ETHER_CheckWrite(channel);
    if(ETHER_SUCCESS == ret)
    {
        /* Transmission is completed */
    }
}
}

```

Special Notes:

- Call this function after writing one frame of transmit data is completed.
- To transmit data less than 60 bytes, make sure to pad the data with zero to be 60 bytes.
- Before calling this function, use the R_ETHER_Write_ZC2_GetBuf function to read data. Call this function after ETHER_SUCCESS is returned.
- This function is used in combination with the R_ETHER_Write_ZC2_GetBuf function. Always call the R_ETHER_Write_ZC2_GetBuf function and then the R_ETHER_Write_ZC2_SetBuf function in sequence. If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.8 R_ETHER_CheckLink_ZC()

The R_ETHER_CheckLink_ZC() function checks the status of the physical Ethernet link using PHY management interface. Ethernet link is up when the cable is connected to a peer device whose PHY is properly initialized.

Format

```
ether_return_t R_ETHER_CheckLink_ZC(
    uint32_t channel    /* ETHERC channel number */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

```
ETHER_SUCCESS          /* Link is up */
ETHER_ERR_OTHER        /* Link is down */
ETHER_ERR_INVALID_CHAN /* Nonexistent channel number */
```

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_CheckLink_ZC() function checks the status of the physical Ethernet link using PHY management interface. This information (status of Ethernet link) is read from the basic status register (register 1) of the PHY-LSI device. ETHER_SUCCESS is returned when the link is up, and ETHER_ERR_OTHER when the link is down.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return_t ret;

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_CheckLink_ZC(channel);
if(ETHER_SUCCESS == ret)
{
    /* Link is up */
    LED1 = LED_ON;
```

```
}  
else  
{  
    /* Link is down */  
    LED1 = LED_OFF;  
}
```

Special Notes:

None

3.9 R_ETHER_LinkProcess()

The R_ETHER_LinkProcess() function performs link signal change interrupt processing and Magic Packet detection interrupt processing.

Format

```
void R_ETHER_LinkProcess(  
    uint32_t channel    /* ETHERC channel number */  
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

None

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_LinkProcess() function performs link signal change interrupt processing and Magic Packet detection interrupt processing. Note that link status change detection processing takes place but link signal change interrupt processing does not occur when ETHER_CFG_USE_LINKSTA is set to a value of 0.

- When a Magic Packet detection interrupt occurs:
 - The callback function registered by the function R_ETHER_Control() reports that a magic packet was detected.
- When a link signal change (link is up) interrupt occurs:
 - The descriptors and the contents of the transmit and receive buffers are erased.
 - After ETHERC and EDMAC are initialized, decide the appropriate configuration to support full-duplex/half-duplex, link speed, and flow control based on the auto-negotiation result, and then enable transmission and reception functionality.
 - EDMAC descriptor is set up to its initial status.
 - The callback function registered by the function R_ETHER_Control() reports that a link signal change (link is up) was detected.
- When a link signal change (link is down) interrupt occurs:
 - After the transmission and reception functions are disabled, the callback function registered by the function R_ETHER_Control() reports that a link signal change (link is down) was detected.
- When ETHER_CFG_USE_LINKSTA is set to a value of 0:
 - The PHY-LSI basic status register (register 1) is read to confirm the Ethernet link status. If a change in the link status is detected, the processing described below occurs.
 - If the link status has changed (link status is link up):
 - The descriptors and the contents of the transmit and receive buffers are erased.
 - After the ETHERC and EDMAC are initialized, the appropriate configuration of full-duplex/half-duplex, link speed, and flow control are determined based on the auto-negotiation result, and transmission and reception functionality are enabled.
 - The EDMAC descriptors are set to their initial status.
 - The callback function registered by the R_ETHER_Control function reports that a link status change (link up) was detected.

— If the link status has changed (link status is link down):

- After the transmission and reception functions are disabled, the callback function registered by the R_ETHER_Control function reports that a link status change (link down) was detected.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

while(1)
{
    /* Perform link signal change interrupt processing and
     * Magic Packet detection interrupt processing
     */
    R_ETHER_LinkProcess(channel);
}
```

Special Notes:

- If ETHER_CFG_USE_LINKSTA is set to a value of 1, either call this function periodically within the normal processing routine, or register the address of this function as the interrupt handler function called by the EINT0/EINT1 status interrupt. Note that Ethernet transmission and reception may not operate correctly, and the Ethernet driver may not enter Magic Packet detection mode correctly, if this function is not called.
- If ETHER_CFG_USE_LINKSTA is set to a value of 0, either call this function periodically within the normal processing routine, or call it from an interrupt function that is processed when a periodically occurring interrupt source occurs. Note that Ethernet transmission and reception may not operate correctly, and the Ethernet driver may not enter Magic Packet detection mode correctly, if this function is not called.
- If no callback function was registered with the function R_ETHER_Control(), there will be no notification by a callback function.

3.10 R_ETHER_WakeOnLAN()

The R_ETHER_WakeOnLAN() function switches the ETHERC setting from normal transmission/reception to Magic Packet detection.

Format

```
ether_return_t R_ETHER_WakeOnLAN(  
    uint32_t channel    /* ETHERC channel number */  
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_OTHER</i>	<i>/* A switch to magic packet detection was performed when the link state */ /* was link is down. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_WakeOnLAN() function initializes the ETHERC and EDMAC, and then switches the ETHERC to Magic Packet detection.

Return values indicate whether the ETHERC has been switched to Magic Packet detection or not. When auto-negotiation is not completed, and transmission/reception is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_OTHER is returned if the link is down after ETHERC is set to Magic Packet detection.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"  
#include "r_ether_rx_if.h"  
  
ether_return_t    ret;  
  
/* Ethernet channel number  
 * ETHER_CHANNEL_0 = Ethernet channel number is 0  
 * ETHER_CHANNEL_1 = Ethernet channel number is 1  
 */  
uint32_t          channel;  
  
channel = ETHER_CHANNEL_0;  
  
while(1)
```

```
{
    /* Perform link signal change interrupt processing and
     * Magic Packet detection interrupt processing
     */
    R_ETHER_LinkProcess(channel);

    /* Enter Magic Packet detection mode. */
    ret = R_ETHER_WakeOnLAN(channel);
    if(ETHER_SUCCESS == ret)
    {
        R_BSP_RegisterProtectDisable(BSP_REG_PROTECT_LPC_CGC_SWR);
        /*
         * Set the MCU in sleep mode as low power consumption mode when the MCU is
         * awaiting a Magic Packet detection.
         */
        SYSTEM.SBYCR.BIT.SSBY = 0;
        R_BSP_RegisterProtectEnable(BSP_REG_PROTECT_LPC_CGC_SWR);

        wait();
    }
}
```

Special Notes:

None

3.11 R_ETHER_CheckWrite()

The R_ETHER_CheckWrite() function verifies that data transmission has completed.

Format

```
ether_return_t R_ETHER_CheckWrite(
    uint32_t channel /* ETHERC channel number */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

Return Values

ETHER_SUCCESS /* Processing completed successfully */
ETHER_ERR_INVALID_CHAN /* Nonexistent channel number */

Properties

Prototyped in r_ether_rx_if.h.

Description

The R_ETHER_CheckWrite() function verifies that data was transmitted.

If the transmission completed, ETHER_SUCCESS is returned.

Reentrant

Function is reentrant for different channels.

Example

The MAC address used in the sample code is assigned based on the vendor ID of Renesas Electronics Corporation. Customers developing products must use a MAC address obtained by submitting an application to the IEEE.

```
#include <string.h>
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return_t ret;
uint8_t * pwrite_buffer_address;
uint8_t * pbuf;
uint16_t buf_size;

/* Transmit data */
static uint8_t send_data[60] =
{
    0x74, 0x90, 0x50, 0x00, 0x79, 0x02, /* Destination MAC address */
    0x74, 0x90, 0x50, 0x00, 0x79, 0x01, /* Source MAC address */
    0x00, 0x00, /* The type field is not used */
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, /* Data field */
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
}
```

```

    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00,
    0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00, 0x00
};

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Write_ZC2_GetBuf(channel, (void **)&pwrite_buffer_address,
&buf_size);
/* When transmission buffer is empty */
if(ETHER_SUCCESS == ret)
{
    /* Write the transmit data to the transmission buffer. */
    memcpy(pwrite_buffer_address, send_data, sizeof(send_data));

    R_ETHER_Write_ZC2_SetBuf(channel, sizeof(send_data));

    /* Verifying that the transmission is completed */
    ret = R_ETHER_CheckWrite(channel);
    if(ETHER_SUCCESS == ret)
    {
        /* Transmission is completed */
    }
}
}

```

Special Notes:

- This function should be called after transmit data has been written with the R_ETHER_Write_ZC2_Setbuf() function.
- Note that it takes several tens of microseconds for data transmission to actually complete after the R_ETHER_Write_ZC2_Setbuf() function is called. Therefore, when using the R_ETHER_Close_ZC2() function to shut down the Ethernet module following data transmission, call the R_ETHER_CheckWrite() function after calling the R_ETHER_Write_ZC2_Setbuf() function and, after waiting for data transmission to finish, call the R_ETHER_Close_ZC2() function. Calling the R_ETHER_Close_ZC2() function without calling the R_ETHER_CheckWrite() function can cause data transmission to be cut off before it completes.

3.12 R_ETHER_Read()

The R_ETHER_Read() function receives data into the specified receive buffer.

Format

```
int32_t R_ETHER_Read(
    uint32_t channel /* ETHERC channel number */
    void * pbuf /* The receive buffer (to store the receive data) */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

** pbuf*

Specifies the receive buffer (to store the receive data).

The maximum write size is 1,514 bytes. When calling this function, specify the start address of a array with a capacity of 1,514 bytes.

Return Values

<i>A value of 1 or greater</i>	<i>/* Returns the number of bytes received. */</i>
<i>ETHER_NO_DATA</i>	<i>/* A zero value indicates no data is received. */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_INVALID_PTR</i>	<i>/* Value of the pointer is NULL or FIT_NO_PTR */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_MPDE</i>	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>
<i>ETHER_ERR_MC_FRAME</i>	<i>/* Multicast frame detected when multicast frame filtering is enabled. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

This function stores the receive data in the specified receive buffer.

Return values indicate the number of bytes received. If there is no data available at the time of the call, ETHER_NO_DATA is returned. When auto-negotiation is not completed, and reception is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_MPDE is returned when a Magic Packet is being detected.

When multicast frame filtering on the specified channel is enabled by the R_ETHER_Control function, the buffer is released immediately when a multicast frame is detected. Also, the value ETHER_ERR_MC_FRAME is returned. Note that when hardware-based multicast frame filtering is enabled on the RX64M or RX71M, multicast frames are discarded by the hardware and detection is not possible. For details, see section 5.1 EPTPC Light FIT Module.

Frames that generate a receive FIFO overflow, residual-bit frame receive error, long frame receive error, short frame receive error, PHY-LSI receive error, or receive frame CRC error are treated as receive frame errors. When a receive frame error occurs, the descriptor data is discarded, the status is cleared, and reading of data continues.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"
#include "r_ether_rx_config.h"

ether_return      ret;
uint8_t          read_buffer[ETHER_BUFSIZE];

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t          channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Read(channel, (void *)read_buffer);
if(ETHER_NO_DATA < ret)
{
    /* Reading the receive data is completed */
}
```

Special Notes:

- As this function calls the R_ETHER_Read_ZC2() function and the R_ETHER_Read_ZC2_BufRelease() function internally, data is copied between the buffer pointed by the EDMAC receive descriptor and the receive buffer specified by the R_ETHER_Read() function. (The maximum write size is 1,514 bytes, so set aside a space of 1,514 bytes for the specified receive buffer.)
- Make sure not to use the R_ETHER_Read_ZC2() function and R_ETHER_Read_ZC2_BufRelease() function when using the R_ETHER_Read() function.
- This function uses the standard function memcpy, so string.h is included.
- If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.13 R_ETHER_Write()

The R_ETHER_Write() function transmits the data from the specified transmit buffer.

Format

```
ether_return_t R_ETHER_Write(
    uint32_t      channel /* ETHERC channel number */
    void          * pbuf  /* Transmit buffer pointer */
    const uint32_t len    /* The size (60 to 1,514 bytes) which is the Ethernet frame length */
                    /* minus 4 bytes of CRC */
);
```

Parameters

channel

Specifies the ETHERC and EDMAC channel number (0 or 1). This value must be specified as 0 on products with only one ETHERC and EDMAC channel.

**pbuf*

Specifies the transmit data (the destination for the transmit data to be written).

len

Specifies the size (60 to 1,514 bytes) which is the Ethernet frame length minus 4 bytes of CRC.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_INVALID_DATA</i>	<i>/* Value of the argument is out of range */</i>
<i>ETHER_ERR_INVALID_PTR</i>	<i>/* Value of the pointer is NULL or FIT_NO_PTR */</i>
<i>ETHER_ERR_LINK</i>	<i>/* Auto-negotiation is not completed, and reception is not enabled. */</i>
<i>ETHER_ERR_MPDE</i>	<i>/* As a Magic Packet is being detected, transmission and reception is not enabled. */</i>
<i>ETHER_ERR_TACT</i>	<i>/* Transmit buffer is not empty. */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

This function transmits data from the specified transmit buffer.

Set the buffer length to be not less than 60 bytes (64 bytes of the minimum Ethernet frame minus 4 bytes of CRC) and not more than 1,514 bytes (1,518 bytes of the maximum Ethernet frame minus 4 bytes of CRC).

To transmit data less than 60 bytes, make sure to pad the data with zero to be 60 bytes.

Return values indicate that the data written in the transmit buffer is enabled to be transmitted. ETHER_SUCCESS is returned when the data in the transmit buffer is enabled to transmit at the time of the call. When auto-negotiation is not completed, and transmission is not enabled, ETHER_ERR_LINK is returned. ETHER_ERR_MPDE is returned when a Magic Packet is being detected. The value ETHER_ERR_TACT is returned if there is no free space in the transmit buffer.

Reentrant

Function is reentrant for different channels.

Example

The MAC address used in the sample code is assigned based on the vendor ID of Renesas Electronics Corporation. Customers developing products must use a MAC address obtained by submitting an application to the IEEE.

```
#include "platform.h"
#include "r_ether_rx_if.h"

ether_return    ret;

/* Transmit data */
static uint8_t send_data[60] =
{
    0x74,0x90,0x50,0x00,0x79,0x02,          /* Destination MAC address */
    0x74,0x90,0x50,0x00,0x79,0x01,          /* Source MAC address */
    0x00,0x00,                                /* The type field is not used */
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00, /* Data field */
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,
    0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00,0x00
};

/* Ethernet channel number
 * ETHER_CHANNEL_0 = Ethernet channel number is 0
 * ETHER_CHANNEL_1 = Ethernet channel number is 1
 */
uint32_t        channel;

channel = ETHER_CHANNEL_0;

ret = R_ETHER_Write(channel, (void *)send_data, sizeof(send_data));
if (ETHER_SUCCESS == ret)
{
    /* Transmission is completed */
}
```

Special Notes:

- To transmit data less than 60 bytes, make sure to pad the data with zero to be 60 bytes.
- As this function calls the R_ETHER_Write_ZC2_GetBuf() function and the R_ETHER_Write_ZC2_SetBuf() function internally, data is copied between the buffer pointed by the EDMAC transmit descriptor and the transmit buffer specified by the R_ETHER_Write() function.
- Make sure not to use the R_ETHER_Write_ZC2_GetBuf() function and R_ETHER_Write_ZC2_SetBuf() function when using the R_ETHER_Write() function.
- This function uses the standard functions memset and memcpy, so string.h is included.
- If the value ETHER_ERR_LINK is returned when this function is called, initialize the Ethernet FIT module.

3.14 R_ETHER_Control()

The R_ETHER_Control() function performs the processing that corresponds to the control code.

Format

```
ether_return_t R_ETHER_Control(  
    ether_cmd_t const    cmd        /* Control code */  
    ether_param_t const  control    /* Parameters according to the control code */  
);
```

Parameters

cmd

Specifies the control code.

control

Specify the parameters according to the control code.

Return Values

<i>ETHER_SUCCESS</i>	<i>/* Processing completed successfully */</i>
<i>ETHER_ERR_INVALID_CHAN</i>	<i>/* Nonexistent channel number */</i>
<i>ETHER_ERR_CHAN_OPEN</i>	<i>/* Indicates the Ethernet cannot be opened because it is being used by another application */</i>
<i>ETHER_ERR_INVALID_ARG</i>	<i>/* Invalid argument */</i>
<i>ETHER_ERR_RECV_ENABLE</i>	<i>/* ETHERC receive function enabled */</i>

Properties

Prototyped in r_ether_rx_if.h.

Description

Performs the processing that corresponds to the control code. The value ETHER_ERR_INVALID_ARG is returned if the control code is not supported.

The table below lists the corresponding control codes.

Control Code	Description
CONTROL_SET_CALLBACK	Registers a function to be called by callback when a link signal change interrupt occurs or a magic packet is detected. Registers the function specified with the second argument.
CONTROL_SET_PROMISCUOUS_MODE	Set the promiscuous mode bit (PRM) in the ETHERC mode register (ECMR). The second argument specifies the ETHERC channel number of the side on which PRM is to be set and the address of the variable storing the PRM value.
CONTROL_SET_INT_HANDLER	Registers the function that is called when an EINT0 or EINT1 status interrupt occurs. Registers the function specified with the second argument.
CONTROL_POWER_ON	Cancels module stop for the ETHERC and EDMAC. The second argument specifies the ETHERC channel for the cancel module stop.
CONTROL_POWER_OFF	Transitions the ETHERC and EDMAC to the module stop state. The second argument specifies the ETHERC channel for the transition to module stop.
CONTROL_MULTICASTFRAME_FILTER	Enables functionality that reads descriptor information, detects multicast frames, and discards those frames (multicast frame filtering). Specify the setting value for multicast frame filtering functionality with the second argument.
CONTROL_BROADCASTFRAME_FILTER	Specifies the number of broadcast frames that can be received continuously by the ETHERC. When more than the specified number of broadcast frames are received by the ETHERC, the additional broadcast frames are discarded. Specify the ETHERC channel number and the number of broadcast frames that can be received continuously by the ETHERC with the second argument. This function is disabled when the number of broadcast frames is specified as 0.

Reentrant

Function is reentrant.

Example

To register a callback function.)

```
void callback(void*);

ether_return_t    ret;
ether_param_t    param;
ether_cb_t       cb_func;

cb_func.pcb_func    = &callback;
param.ether_callback = cb_func;

ret = R_ETHER_Control(CONTROL_SET_CALLBACK, param);
```

To set up promiscuous mode)

```
ether_return_t    ret;
ether_param_t     param;
ether_promiscuous_t promiscuous;

promiscuous.channel      = ETHER_CHANNEL_0;
promiscuous.bit          = ETHER_PROMISCUOUS_ON;
param.p_ether_promiscuous = &promiscuous;

ret = R_ETHER_Control(CONTROL_SET_PROMISCUOUS_MODE, param);
```

Registering an interrupt handler function)

```
void int_handler(void*);

ether_return_t    ret;
ether_param_t     param;
ether_cb_t        cb_func;

cb_func.pcb_int_hnd = &int_handler;
param.ether_callback = cb_func;

ret = R_ETHER_Control(CONTROL_SET_INT_HANDLER, param);
```

Interrupt handler function)

```
static uint32_t    status_ecsr[2];
static uint32_t    status_eesr[2];

void int_handler(void * p_param)
{
    ether_cb_arg_t  *p_arg;

    p_arg = (ether_cb_arg_t *)p_param;

    if (ETHER_CHANNEL_MAX > p_arg->channel)
    {
        status_ecsr[p_arg->channel] = p_arg->status_ecsr;
        status_eesr[p_arg->channel] = p_arg->status_eesr;
    }
}
```

Canceling ETHERC/EDMAC module stop)

```
ether_return_t    ret;
ether_param_t     param;

param.channel = channel;
ret = R_ETHER_Control(CONTROL_POWER_ON, param);
```

Transitioning ETHERC/EDMAC to module stop)

```
ether_return_t    ret;
ether_param_t     param;

param.channel = channel;
ret = R_ETHER_Control(CONTROL_POWER_OFF, param);
```

To enable or disable multicast frame filtering)

```
ether_return_t      ret;
ether_param_t      param;
ether_multicast_t   multicast;

multicast.channel    = channel;
multicast.flag       = ETHER_MC_FILTER_ON;
param.p_ether_multicast = &multicast;

ret = R_ETHER_Control(CONTROL_MULTICASTFRAME_FILTER, param);
```

To set the continuous receive count for broadcast frame filtering)

```
ether_return_t      ret;
ether_param_t      param;
ether_broadcast_t   broadcast;

broadcast.channel    = channel;
broadcast.counter    = 10;
param.p_ether_broadcast = &broadcast;

ret = R_ETHER_Control(CONTROL_BROADCASTFRAME_FILTER, param);
```

Special Notes:

Register callback functions and interrupt handlers before calling the R_ETHER_Open_ZC2() function. It may not be possible to detect the first interrupt if the preceding are registered after the R_ETHER_Open_ZC2() function is called.

Specify promiscuous mode after setting the control code to CONTROL_POWER_ON and calling this function. The intended value will not be stored in the ETHERC mode register if the promiscuous mode setting is specified without first setting the control code to CONTROL_POWER_ON and calling this function.

Multicast frame filtering and broadcast frame filtering settings cannot be made while the receive functionality of the ETHERC is enabled. Make these settings before calling the R_ETHER_LinkProcess function. After the R_ETHER_LinkProcess function is called, the receive functionality is enabled when the Ethernet FIT module enters link up status, so calling this function with CONTROL_MULTICASTFRAME_FILTER or CONTROL_BROADCASTFRAME_FILTER set as the control code causes ETHER_ERR_RECV_ENABLE to be returned, and the settings have no effect.

3.15 R_ETHER_GetVersion()

This function returns the API version.

Format

```
uint32_t R_ETHER_GetVersion(void);
```

Parameters

None

Return Values

Version number

Properties

Prototyped in r_ether_rx_if.h.

Description

Returns the API version number.

Reentrant

Function is reentrant for different channels.

Example

```
#include "platform.h"
#include "r_ether_rx_if.h"

uint32_t    version;

version = R_ETHER_GetVersion();
```

Special Notes:

This function is inlined using ‘#pragma inline’.

4. How to use

4.1 Section Allocation

Table 4-1 shows a sample section allocation for the Ethernet FIT module.

Table 4-1 Program Section Allocation

Address	Device	Section	Description
0x00000000	Internal RAM	B_ETHERNET_BUFFERS_1	Transmit buffer and receive buffer area
		B_RX_DESC_1	Receive descriptor area
		B_TX_DESC_1	Transmit descriptor area
		SI	Interrupt stack area
		SU	User stack area
		B_1	Uninitialized data area of 1byte boundary
		R_1	Initialized data area of 1byte boundary (variable)
		B_2	Uninitialized data area of 2byte boundary
		R_2	Initialized data area of 2byte boundary (variable)
		B	Uninitialized data area of 4byte boundary
		R	Initialized data area of 4byte boundary (variable)
0xFFFF8000	Internal ROM	C_1	Constant area of 1byte boundary
		C_2	Constant area of 2byte boundary
		C	Constant area of 4byte boundary
		C\$*	Constant region (C\$DEC, C\$BSEC, C\$VECT) of C\$* section
		D*	Initialization data area
		P*	Program area
		W*	Branch table area for switch statements
		L	String literal area
0xFFFFFFFF80		EXCEPTVECT	Interrupt vector area
0xFFFFFFFFFC		RESETVECT	Reset vector area

4.1.1 Notes on Section Allocation

- Since the EDMAC mode register (EDMR) transmit/receive descriptor length bits (DL) are set to specify 16 bytes, sections must be allocated on 16-byte boundaries.
- Transmit buffer and receive buffer areas must be allocated on 32-byte boundaries.

4.2 Ethernet FIT Module Initial Settings

Figure 4.1 is a flowchart of the routine for making initial settings to the Ethernet FIT module.

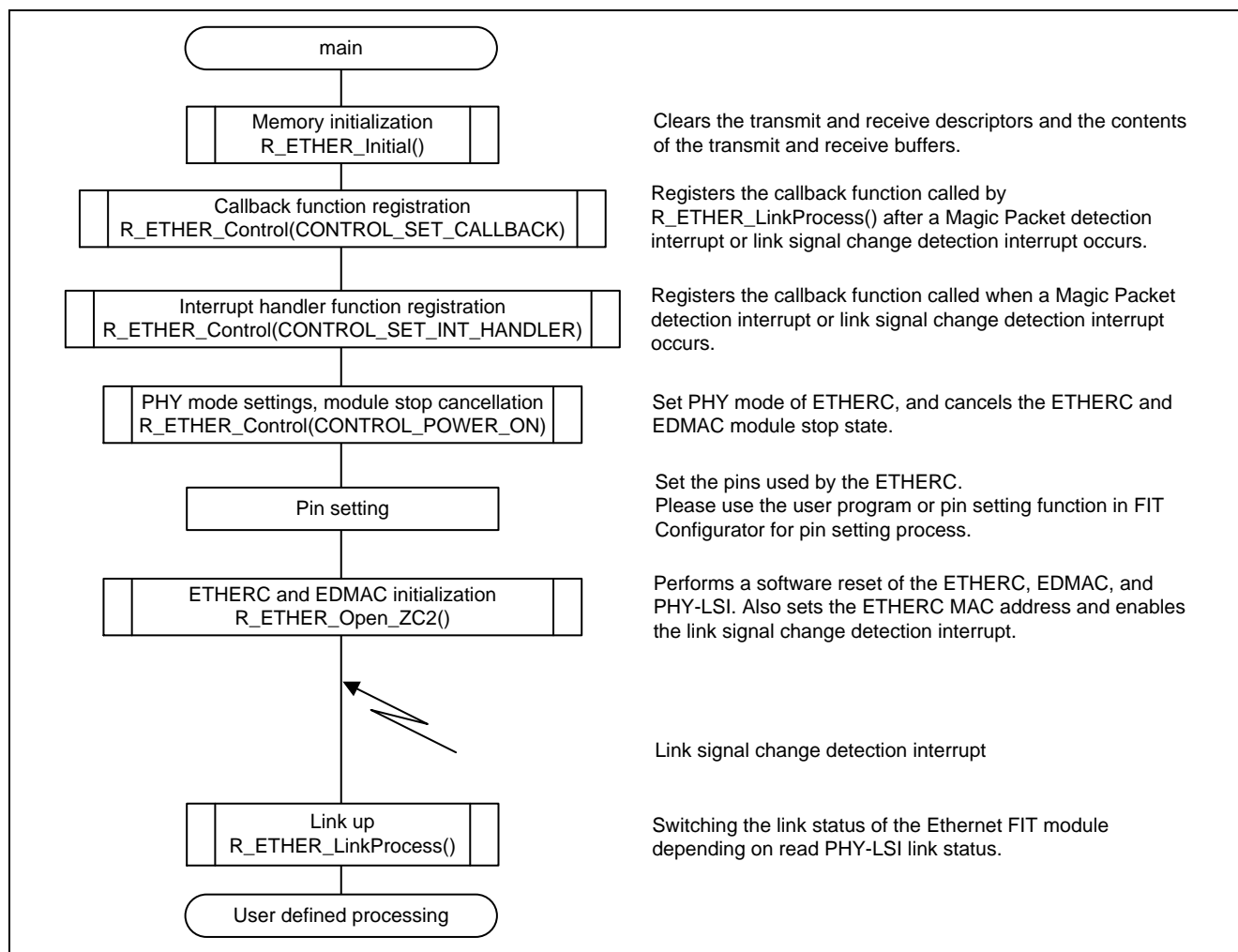


Figure 4.1 Flowchart of Ethernet FIT Module Initial Settings

4.2.1 Notes on Ethernet FIT Module Initial Settings

Calling the R_ETHER_Initial function clears the memory contents for all channels.

4.3 Ethernet FIT Module Pin Settings

In order to use the Ethernet FIT module, user program must assign input and output signals of ETHERC to the I/O Ports. Refer to section 4.2 “Ethernet FIT Module Initial Settings” for timing pin setting processing is executed. In addition, you use can pin setting function in “FIT Configurator” in case of e2 studio.

4.3.1 Pin setting example for using RSK+RX64M/RSK+RX71M

Assign input and output signals of ETHERC to the I/O Ports if using RSK+RX64M or RSK+RX71M. Note that channel number in need of pin setting are determined by use channel and configuration option specified in Table 4-2. Don't set the parameters other than Table 4-2. Table 4-3 and Table 4-4 show the details of each channel's Pins.

Table 4-2 Channel number in need of pin setting by use channel and configuration option

Use Channel	Setting of Configuration Option	Channel Number in Need of Pin Setting
Channel 0	ETHER_CFG_CH0_PHY_ACCESS (0)	Channel 0
	ETHER_CFG_CH1_PHY_ACCESS (0)	
	ETHER_CFG_CH0_PHY_ACCESS (1)	Channel 0
	ETHER_CFG_CH1_PHY_ACCESS (1)	Channel 1
Channel 1	ETHER_CFG_CH0_PHY_ACCESS (0)	Channel 0
	ETHER_CFG_CH1_PHY_ACCESS (0)	Channel 1
	ETHER_CFG_CH0_PHY_ACCESS (1)	Channel 1
	ETHER_CFG_CH1_PHY_ACCESS (1)	
Channel 0	ETHER_CFG_CH0_PHY_ACCESS (0)	Channel 0
Channel 1	ETHER_CFG_CH1_PHY_ACCESS (0)	Channel 1
	ETHER_CFG_CH0_PHY_ACCESS (1)	Channel 0
	ETHER_CFG_CH1_PHY_ACCESS (1)	Channel 1

Table 4-3 Pin setting example for channel 0

Case of Using MII Mode	Case of Using RMII Mode
ET0_TX_CLK	
ET0_RX_CLK	REF50CK0
ET0_TX_EN	RMII0_TXD_EN
ET0_ETXD3	
ET0_ETXD2	
ET0_ETXD1	RMII0_TXD1
ET0_ETXD0	RMII0_TXD0
ET0_TX_ER	
ET0_RX_DV	
ET0_ERXD3	
ET0_ERXD2	
ET0_ERXD1	RMII0_RXD1
ET0_ERXD0	RMII0_RXD0
ET0_RX_ER	RMII0_RX_ER
ET0_CRS	RMII0_CRS_DV
ET0_COL	
ET0_MDC	
ET0_MDIO	
ET0_LINKSTA *1	
ET0_EXOUT *2	
ET0_WOL *2	

Notes: 1. Setting is not required if the setting of #define ETHER_CFG_USE_LINKSTA is 0.

Notes: 2. Setting is not required because these pin are not used in Ethernet FIT module.

Table 4-4 Pin setting example for channel 1

Case of Using MII Mode	Case of Using RMII Mode
ET1_TX_CLK	
ET1_RX_CLK	REF50CK1
ET1_TX_EN	RMII1_TXD_EN
ET1_ETXD3	
ET1_ETXD2	
ET1_ETXD1	RMII1_TXD1
ET1_ETXD0	RMII1_TXD0
ET1_TX_ER	
ET1_RX_DV	
ET1_ERXD3	
ET1_ERXD2	
ET1_ERXD1	RMII1_RXD1
ET1_ERXD0	RMII1_RXD0
ET1_RX_ER	RMII1_RX_ER
ET1_CRS	RMII1_CRS_DV
ET1_COL	
ET1_MDC	
ET1_MDIO	
ET1_LINKSTA *1	
ET1_EXOUT *2	
ET1_WOL *2	

Notes: 1. Setting is not required if the setting of #define ETHER_CFG_USE_LINKSTA is 0.

Notes: 2. Setting is not required because these pin are not used in Ethernet FIT module.

4.4 Magic Packet Detection Operation

Figure 4.2 is a flowchart showing the processing whereby the ETHERC and EDMAC are initialized when a Magic Packet is detected, following the transition to Magic Packet detection operation mode.

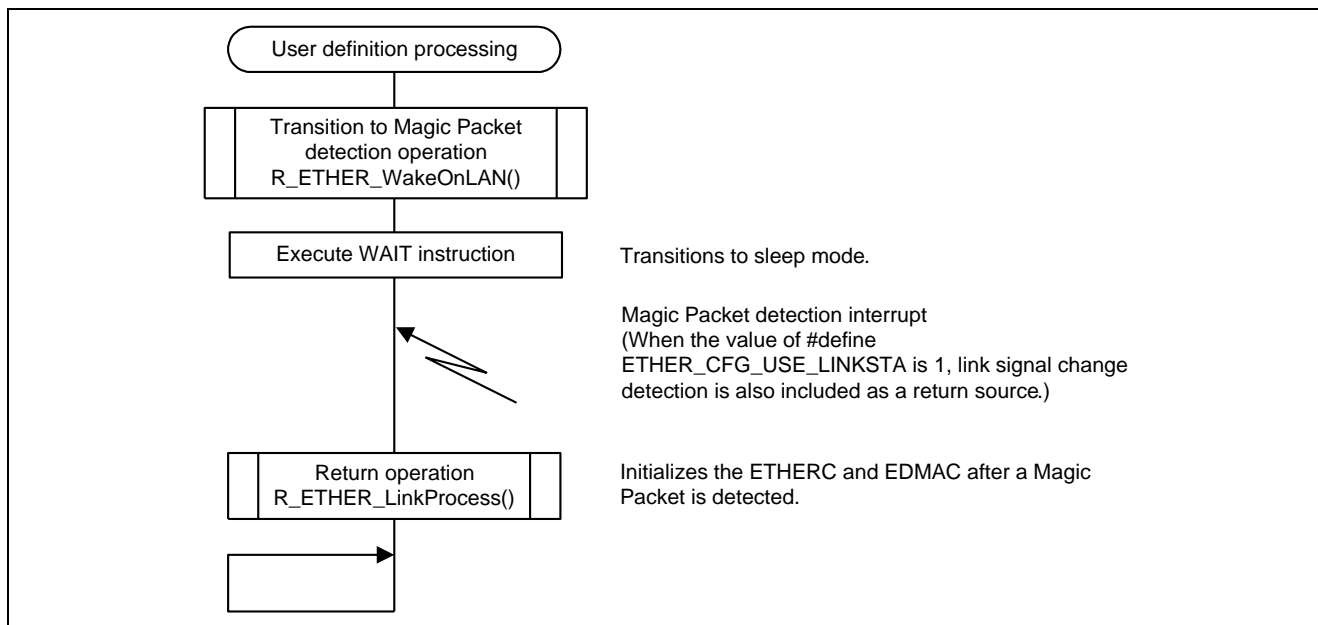


Figure 4.2 Flowchart of Magic Packet Detection Operation

4.4.1 Notes on Magic Packet Detection Operation

- Do not transition the ETHERC or EDMAC to the module stop state after switching to Magic Packet detection operation. Doing so will make it impossible to the CPU to recover from sleep mode following a WAIT instruction, because the ETHERC will be unable to detect Magic Packets.
- When a Magic Packet is detected, there will be data from the previously received broadcast frame, etc., in the receive FIFO, and the ETHERC will receive notifications of receive status, etc. Therefore, call the `R_ETHER_LinkProcess` function to initialize the ETHERC and EDMAC.
- When the value of #define `ETHER_CFG_USE_LINKSTA` is set to 1, the interrupt handler function is called when a change in the link signal is detected. Therefore, if the CPU was in sleep mode when the link signal change was detected, it will return to normal operation regardless of whether or not a Magic Packet is detected.

5. Appendices

5.1 EPTPC Light FIT Module

Simple switching functionality and multicast frame filtering functionality can be implemented on the RX64M and RX71M by combining the Ethernet FIT module with the EPTPC Light FIT module.

(1) Simple Switching

When using a two-channel ETHERC, frame transfers between channels take place in hardware.

Channel 0 to channel 1, channel 1 to channel 0, or bidirectional can be selected as the transfer direction. Store and forward or cut through can be selected as the transfer method.

(2) Multicast Frame Filtering

Processing to receive or discard multicast frames received by the ETHERC is performed in hardware.

It is possible to receive all multicast frames, to receive no multicast frames, or to receive only multicast frames with a designated destination address (up to two addresses can be registered).

For details, refer to the EPTPC Light FIT module application note “RX Family: EPTPC Light Module Using Firmware Integration Technology Modules,” document No. R01AN3035

5.1.1 Usage Notes

When using the Ethernet FIT module and EPTPC Light FIT module together in combination, it is not possible at the same time to use the EPTPC FIT module (full version),*¹ which provides time synchronization based on the IEEE 1588 specification.

When using simple switching or multicast frame filtering on the RX64M or RX71M, select one of the following.

- When not using the IEEE 1588 time synchronization functionality:
Select the EPTPC Light FIT module (module name: r_ptp_light_rx).
- When using the IEEE 1588 time synchronization functionality:
Select EPTPC FIT module (full version) (module name: r_ptp_rx).

Note 1. RX Family: EPTPC Module Using Firmware Integration Technology, document No. R01AN1943

6. Provided Modules

The module provided can be downloaded from the Renesas Electronics website.

7. Ethernet FIT Module Usage Notes

Keep the following points in mind when using the Ethernet FIT module.

- If broken frames or noise on an external line cause detection of a frame error during reception by the ETHERC and EPTPC on the RX64M or RX71M, proper reception may not be possible even if subsequent received frames are normal. For details, refer to the technical updates and application notes listed below.
- Notes on Using Ethernet Controller (Technical Notification No. TN-RX*-A125A/E)
- RX Family Retrieve Recommend Operation of INFABT Occurrence in The Ethernet Controller (Doc No. R01AN2604)

8. Reference Documents

User's Manual: Hardware

RX64M Group User's Manual: Hardware (Doc No. R01UH0377)

RX71M Group User's Manual: Hardware (Doc No. R01UH0493)

RX63N Group, RX631 Group User's Manual: Hardware (Doc No. R01UH0041)

(The latest version can be downloaded from the Renesas Electronics website.)

Technical Update/Technical News

(The latest information can be downloaded from the Renesas Electronics website.)

User's Manual: Development Tools

RX Family C/C++ Compiler, Assembler, Optimizing Linkage Editor Compiler Package (R20UT0570)

(The latest version can be downloaded from the Renesas Electronics website.)

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Revision History

Rev.	Date	Description	
		Page	Summary
1.00	Jul 29, 2014	—	First edition issued
1.01	Jan 28, 2015	1	RX71M added to Target Devices
		5	Notes 1 to 3 of 2.6, Configuration Overview, amended Table 2.2 added
		9	Steps 7 and 8 of 2.10.1, Adding the Ethernet FIT Module, amended
		10	Special Notes of 3.1, R_ETHER_Initial(), amended
		23	Special Notes of 3.11, R_ETHER_CheckWrite(), amended
		30	Special Notes of 3.14, R_ETHER_Control(), amended
		32	Address 0x00120064 deleted from table 4.1, Program Section Allocation
		53	RX71M Group User's Manual: Hardware added to 6, Reference Documents Information regarding development environment user's manual amended
1.02	Mar 27, 2015	—	R_ETHER_LinkProcess() in r_ether_rx.c amended
1.10	Mar 15, 2016	1	RX63N added to Target Devices
		3	Limitations deleted under Overview
		5	#define ETHER_CFG_EINT_INT_PRIORITY added to 2.6, Configuration Overview
		6, 7	Notes 4 to 8 on #define ETHER_CFG_USE_LINKSTA added to 2.6, Configuration Overview
		7	2.7 Code Size added
		8	Description of ether_cmd_t in 2.8, Arguments, amended
		10	Description of ether_return_t in 2.9, Return Values, amended
		11	Description of (2) Callback Function Called by EINT0/EINT1 Status Interrupts in 2.10, Callback Function, amended. Note 1. added Description of 2.11, Adding the FIT Module, amended
		12	2.12, Ethernet Frame Format, added
		13 to 43	Description of API functions in 3., API Functions, amended
		45	4.2, Ethernet FIT Module Initial Settings, added
		46	4.3, EPTPC Light FIT Module, added
		47	4.4, Magic Packet Detection Operation, added
		—	4.2, Sample Code, deleted
		48	6., Ethernet FIT Module Usage Notes, added
1.11	Oct 1, 2016	—	Pin setting in the Ethernet FIT module has been removed for support pin setting function of e2 studio.
		1	RX65N added to Target Devices
		8, 9	Notes 5, 7 and 8 amended
		43	Description in 3.14, R_ETHER_Control(), amended
		48	Description of Figure 4.1 in 4.2, Ethernet FIT Module Initial Settings, amended
		49	4.3, Ethernet FIT Module Pin Settings, added
		52	5, Appendices, added

1.12	Nov 11, 2016	Program	<p>The module is updated to fix the software issue.</p> <p><u>Description:</u></p> <p>When R_ETHER_LinkProcess function is called, there are cases when link up/link down are not processed successfully.</p> <p><u>Conditions:</u></p> <p>ETHER_CFG_USE_LINKSTA is set to a value of 0.</p> <p><u>Corrective action:</u></p> <p>Please use the Ethernet FIT module Rev1.12.</p>
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General Precautions in the Handling of Microprocessing Unit and Microcontroller Unit Products

The following usage notes are applicable to all Microprocessing unit and Microcontroller unit products from Renesas. For detailed usage notes on the products covered by this document, refer to the relevant sections of the document as well as any technical updates that have been issued for the products.

1. Handling of Unused Pins

Handle unused pins in accordance with the directions given under Handling of Unused Pins in the manual.

- The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

- The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed. In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

- The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

- When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

5. Differences between Products

Before changing from one product to another, i.e. to a product with a different part number, confirm that the change will not lead to problems.

- The characteristics of Microprocessing unit or Microcontroller unit products in the same group but having a different part number may differ in terms of the internal memory capacity, layout pattern, and other factors, which can affect the ranges of electrical characteristics, such as characteristic values, operating margins, immunity to noise, and amount of radiated noise. When changing to a product with a different part number, implement a system-evaluation test for the given product.

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