图像算法工程师笔试题

1 . You are building a 3-class object classification and localization algorithm. The classes are: pedestrian (c=1), car (c=2), motorcycle (c=3). What would be the label for the following image? Recall $y=[p_c,b_x,b_y,b_h,b_w,c_1,c_2,c_3]$



- y = [1, 0.3, 0.7, 0.3, 0.3, 0, 1, 0]
- y = [1, 0.7, 0.5, 0.3, 0.3, 0, 1, 0]
- y = [1, 0.3, 0.7, 0.5, 0.5, 0, 1, 0]
- y = [1, 0.3, 0.7, 0.5, 0.5, 1, 0, 0]
- y = [0, 0.2, 0.4, 0.5, 0.5, 0, 1, 0]
- 2. Continuing from the previous problem, what should y be for the image below? Remember that "?" means "don't care", which means that the neural network loss function won't care what the neural network gives for that component of the output. As before, $y=[p_c,b_x,b_y,b_h,b_w,c_1,c_2,c_3]$.



- y = [0, ?, ?, ?, ?, ?, ?]
- y = [1, ?, ?, ?, ?, 0, 0, 0]
- y = [0, ?, ?, ?, ?, 0, 0, 0]
- y = [?,?,?,?,?,?,?]
- y = [1, ?, ?, ?, ?, ?, ?, ?]



3. You are working on a factory automation task. Your system will see a can of soft-drink coming down a conveyor belt, and you want it to take a picture and decide whether (i) there is a soft-drink can in the image, and if so (ii) its bounding box. Since the soft-drink can is round, the bounding box is always square, and the soft drink can always appears as the same size in the image. There is at most one soft drink can in each image. Here're some typical images in your training set:



	What is the most appropriate set of output units for your neural network?		
	\bigcirc	Logistic unit (for classifying if there is a soft-drink can in the image)	
	\bigcirc	Logistic unit, b_x and b_y	
	\bigcirc	Logistic unit, b_x , b_y , b_h (since b_w = b_h)	
	\bigcirc	Logistic unit, b_x , b_y , b_h , b_w	
4.	If you build a neural network that inputs a picture of a person's face and outputs landmarks on the face (assume the input image always contains exactly one face many output units will the network have?		
	\bigcirc	N	
	\bigcirc	2N	
	\bigcirc	3N	
	\bigcirc	N^2	
5.	trainir bound	n training one of the object detection systems described in lecture, you need a ing set that contains many pictures of the object(s) you wish to detect. However, adding boxes do not need to be provided in the training set, since the algorithm can a to detect the objects by itself.	
	\bigcirc	True	
	\bigcirc	False	
6.	imple	ose you are applying a sliding windows classifier (non-convolutional mentation). Increasing the stride would tend to increase accuracy, but decrease utational cost.	
	\bigcirc	True	
		False	



- 7. In the YOLO algorithm, at training time, only one cell --- the one containing the center/midpoint of an object--- is responsible for detecting this object.

 \[\text{True} \]

 \[\text{False} \]

 8. What is the IoU between these two boxes? The upper-left box is 2x2, and the lower-right box is 2x3. The overlapping region is 1x1.

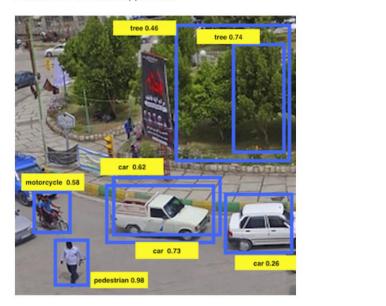
 \[\text{1/6} \]

 \[\text{1/6} \]

 \[\text{1/9} \]

 \[\text{1/10} \]
- 9. Suppose you run non-max suppression on the predicted boxes above. The parameters you use for non-max suppression are that boxes with probability \leq 0.4 are discarded, and the IoU threshold for deciding if two boxes overlap is 0.5. How many boxes will remain after non-max suppression?

None of the above



10. Suppose you are using YOLO on a 19x19 grid, on a detection problem with 20 classes, and with 5 anchor boxes. During training, for each image you will need to construct an output volume y as the target value for the neural network; this corresponds to the last layer of the neural network. (y may include some "?", or "don't cares"). What is the dimension of this output volume?
19x19x(20x25)
19x19x(5x25)
19x19x(5x20)
19x19x(25x20)
11. 请选择正确的梯度下降算法的步骤:
a.计算预测值和真实值之间的误差
b.重复迭代,直至得到网络权重的最佳值
c.把输入传入网络,得到输出值
d.用随机值初始化权重和偏差
e.对每一个产生误差的神经元,调整相应的(权重)值以减小误差
A. abcde B. edcba C. cbaed D. dcaeb
12. 下列哪一项在神经网络中引入了非线性?
A.随机梯度下降
B.修正线性单元(ReLU)
C.卷积函数
D.以上都不正确
13. 已知 Ax = B,其中 A 为 m x n (m>>n) 的矩阵, x 为 n x 1 的矩阵, B 为 m x 1 的矩阵, 求 的最优解。

14. 简述交叉熵损失函数的含义;并求当激活函数为 sigmoid 或者 softmax(任选其一)时,其交叉熵损失函数的导数。