

Alejandro Ramirez

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Skills

- **Languages:** C, C++, Assembly, Python
- Embedded Technologies: UART, SPI, I2C, I2S, ADC, PWM, MQTT, FreeRTOS, ROS2
- **Tools:** GDB, QEMU, Serial Debuggers, Firmware Utilities

Experience

Embedded Software Developer , IEEE Region 5 Robotics Competition	Brownsville, Tx
Python C++ PWM	Dec 2024 – April 2025
<ul style="list-style-type: none">• Designed 5+ optimized algorithms improving robotics efficiency by 20%, enabling faster sensor response, smoother actuator control, and more reliable autonomous behavior.• Engineered bare-metal motor control routines that synchronized PWM generation with sensor feedback, reducing latency by 30% while ensuring stable real-time response.• Integrated ROS2 subsystems with a 7-person team, enabling seamless hardware-software communication and improving real-time robotics performance by 15%.• Validated hardware modules against subsystems, reducing errors by 40% and ensuring reliable performance.	
Projects	

Raminox , Personal Project Team Lead	Aug 2025 – Present
C C++ FreeRTOS I2C I2S ADC	
<ul style="list-style-type: none">• Lead a 4-person team in developing a custom embedded device with integrated wireless transceivers, enabling text-like messaging and interactive applications in connectivity dead zones.• Architect modular software architecture supporting real-time user interaction, multiplayer gaming, and resilient peer-to-peer data exchange using direct radio protocols.• Interpret component schematics and reference manuals to design low-power system architecture and power regulation, reducing signal errors by 25% and extending battery life by 35%.	
RetePulse Connect , Embedded Systems Project	
Python C++ MQTT OTA Linux	July 2025 – Aug 2025
<ul style="list-style-type: none">• Developed embedded firmware enabling full MQTT control of up to 10 devices, with continuous bidirectional messaging that monitored connectivity, state changes, and fault conditions.• Built subsystem-safe routines for sensors, hardware control, and error detection, delivering deterministic performance with reliable feedback.• Integrated over-the-air update workflows and automated state-reporting, reducing manual intervention by 40% and improving long-term maintainability.	
MicroUSC , UART 4-byte Command System	Mar 2025 – July 2025
C Assembly FreeRTOS UART	
<ul style="list-style-type: none">• Developed a modular UART framework with fixed-size binary commands, reducing parsing cycles by 25% and lowering packet loss across subsystems.• Reduced host CPU load by 30% and boosted throughput by 20% by offloading 32-bit data packets to external processing.	

Organizations

Institute of Electrical and Electronics Engineers (IEEE) , Member	Aug 2024 – Present
<ul style="list-style-type: none">• Organized and contributed to collaborative engineering projects, fostering cross-disciplinary teamwork and technical problem-solving.	

Education

The University of Texas Rio Grande Valley	Edinburg, Tx
BS in Computer Engineering	Anticipated Grad. Date: May 2027