

**CMPE-110****Intro to CE****Fall 2019****Laboratory Nine Worksheet**

Section: \_\_\_\_\_

Day/Time: \_\_\_\_\_

Date: \_\_\_\_\_

Names: \_\_\_\_\_

Lab Instructor/TA Initials:  
(on completion)

\_\_\_\_\_

**Robot**

Robot number: \_\_\_\_\_

**Line Sensing**

Object	Left	Center	Right
Plain white paper			
Desk surface			
Floor (the carpet)			
Robot held in mid air			

Threshold value for detecting white paper: \_\_\_\_\_

**Collision Avoidance**

'Collision Detection' program (instructor/TA initials): \_\_\_\_\_

**Submission**One per team—*make sure team member names are written on each item:*

- \_\_\_ Completed laboratory worksheet.
- \_\_\_ A printed copy of portion of the 'Collision Detection' Arduino sketch that you changed (e.g. the file comment block and driveUntilBump() function; no need to print the code that was provided to you); also, do not forget to comment your code.
- \_\_\_ Make sure the robot is turned off
- \_\_\_ Robot was put away.